

High ESD-Protected, Fail-Safe, Slew-Rate-Limited

RS-485 Transceivers

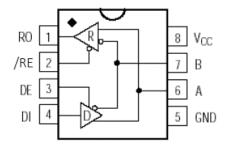
General Description

The BL3085B is a half-duplex RS-485 transceiver with ± 18 kV IEC 61000-4-2 contact discharge protection. The BL3085B contains one driver and one receiver. The device features fail-safe circuitry, which guarantees a logic-high receiver output when the receiver inputs are open or shorted. This means that the receiver output will be logic high even if all transmitters on a terminated bus are disabled. The BL3085B features reduced slew-rate driver that minimizes EMI and reduces reflections caused by improperly terminated cables, allowing error-free data transmission up to 250kbps. The BL3085B has a 1/8 unit load receiver input impedance that allows up to 256 transceivers on the bus.

Features

- +5V Operation
- True Fail-Safe Receiver
- > Data transmission up to 250kbps
- > Allow Up to 256 Transceivers on the Bus
- ±18kV IEC 61000-4-2 ESD Protection on I/O Bus Pins
- Available in SOP8 Package

Functional Block



Applications

- RS-485 Communications
- Level Translators
- Transceivers for EMI-Sensitive Applications
- Industrial Control Local Area Networks
- Energy Meter Networks
- Lighting Systems



Pin Function Description

| Pin Number | Name | Function | | | |
|---------------|-----------------|---|--|--|--|
| 1 | RO | Receiver Output. | | | |
| 2 | /RE | Receiver Output Enable. /RE is low to enable the Receiver; RE is high to disable the Receiver. | | | |
| 3 | DE | Driver Output Enable: DE is high to enable the Driver; DE is low to disable the Driver. | | | |
| 4 | DI | Driver Input | | | |
| 5 | GND | Ground. | | | |
| 6 | A | Non-inverting Receiver Input and Non-inverting Driver Output. | | | |
| 7 | В | Inverting Receiver Input and Inverting Driver Output. | | | |
| 8 | V _{CC} | Power Supply. | | | |

Function Table (Transmitting)

| Inputs | | | Οι | ıtputs | |
|--------|----|----|-------------------|--------|--|
| /RE | DE | DI | A | В | |
| Х | 1 | 1 | 1 | 0 | |
| Х | 1 | 0 | 0 | 1 | |
| 0 | 0 | Х | High-Z | High-Z | |
| 1 | 0 | Х | Shutdown (High-Z) | | |

Function Table (Receiving)

| | Inputs | Outputs | |
|-----|--------|--------------|-------------------|
| /RE | DE | A-B | RO |
| 0 | X | ≥-50mV | 1 |
| 0 | X | ≤-200mV | 0 |
| 0 | X | Open/shorted | 1 |
| 1 | 1 | Х | High-Z |
| 1 | 0 | Х | Shutdown (High-Z) |



Absolute Maximum Ratings

| Parameter | Symbol | Rating | Units |
|----------------------------|-----------------|------------------------------|-------|
| Power Supply | V _{CC} | +7 | V |
| Control Input Voltage | /RE, DE | -0.3 to V _{CC} +0.3 | V |
| Transmitter Input Voltage | DI | -0.3 to V _{CC} +0.3 | V |
| Transmitter Output Voltage | A, B | -8 to +13 | V |
| Receiver Input Voltage | A, B | -8 to +13 | V |
| Receiver Output Voltage | RO | -0.3 to V _{CC} +0.3 | V |
| Operating Temperature | | -40 to +85 | °C |

DC Electrical Characteristics

 $(VCC=+5V\pm5\%, TA=-40\,^\circ\!\!C \sim +85\,^\circ\!\!C$, Typical Values are VCC=+5V and TA=25 $^\circ\!\!C$) (Note1)

| Parameter | Symbol | condi | tions | MIN | TYP | МАХ | UNITS |
|---|------------------|--------------------------------|----------------------|------|------|-----|-------|
| Power Supply | Vcc | | | 4.5 | | 5.5 | V |
| Driver | | | I | | | 1 | I |
| Differential Driver Output(no load) | V _{OD1} | Figure 1 | | | | 5 | V |
| Differential Driver Output | V _{OD2} | Figure 1, F | R=27Ω | 1.5 | | | V |
| Change in Magnitude of Differential Output Voltage (Note 2) | ΔV_{OD} | Figure 1, F | R=27Ω | | | 0.2 | V |
| Driver Common-mode Output Voltage | Voc | Figure 1, F | R=27Ω | 1.0 | | 3.0 | V |
| Change in Magnitude of Common-Mode Voltage (Note 2) | ΔV_{OC} | Figure 1, F | R=27Ω | | | 0.2 | V |
| Input High Voltage | VIH | DE,DI,/RE | | 2.0 | | | V |
| Input Low Voltage | VIL | DE,DI,/RE | | | | 0.8 | V |
| DI Input Hysteresis | V _{HYS} | | | | 100 | | mV |
| Input Current(A and B) | I _{IN4} | DE=GND V _{CC} =GND | V _{IN} =12V | | | 125 | μA |
| | | or 5.25V | V _{IN} =-7V | -75 | | | |
| Driver Short-Circuit Output Current | I _{OSD} | A Pin Short | to B Pin | -100 | | 100 | mA |
| Receiver | | | <u>.</u> | | | | |
| Receiver Differential Threshold Voltage | V _{TH} | -7V≪V _{CM} ≪ | 512V | -200 | -125 | -50 | mV |

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| Receiver Input Hysteresis | △V _{TH} | | | | 40 | | mV |
|---|------------------|---------------------------|------------------------|----------------------|-----|-----|----|
| Receiver Output High Voltage | V _{OH} | l ₀ =-4mA,∖ | / _{ID} =-50mV | V _{CC} -1.5 | | | V |
| Receiver Output Low Voltage | V _{OL} | I _O =4mA,V | _{iD} =-200mV | | | 0.4 | V |
| Three-State Output Current at Receiver | I _{OZR} | | | | | ±1 | μΑ |
| Receiver Input Resistance | R _{IN} | -7V≪V _{CM} i | ≪12V | 96 | | | ΚΩ |
| Receiver Output Short-Circuit Current | I _{OSR} | 0V≪V _{RO} ≪ | ≦V _{CC} | ±7 | | ±95 | mA |
| Supply Current | | | | | | | |
| Current Current | Icc | No load , /RE=DI= | DE=V _{CC} | | 150 | 600 | μA |
| Supply Current | | GND or V _{CC} | DE=GND | | 185 | 600 | μA |
| Supply Current in Shutdown Mode | Ishdn | DE=GND, /RE=VCC GND | ,DI=V _{CC} or | | | 10 | μΑ |

Note 1: All currents into the device are positive. All currents out of the device are negative. All voltages are referred to device ground unless otherwise noted.

Note 2: $\triangle V_{OD}$ and $\triangle V_{OC}$ are the changes in V_{OD} and V_{OC} , respectively, when the DI input changes state.

Switching Characteristics

| Parameter | Symbol | Conditions | MIN | ТҮР | МАХ | UNITS |
|---|-----------------------------------|---|-----|-----|-----|-------|
| Driver Input to | t _{DPLH} | Figure 3 and 5, | | 450 | 800 | |
| Output | t _{DPHL} | R _{DIFF} =54Ω C _{L1} =C _{L2} =100pF | | 450 | 800 | - ns |
| Driver Output Skew Т _{DPLH} – Т _{DPHL} | t _{DSKEW} | Figure 3 and 5, R_{DIFF} =54 Ω C_{L1} = C_{L2} =100pF | | | 100 | ns |
| Driver Rise or Fall Time | t _{DR} , t _{DF} | Figure 3 and 5, R_{DIFF} =54 Ω C_{L1} = C_{L2} =100pF | | 150 | 500 | ns |

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| Maximum Data Rate | F MAX | | 250 | | | kbps |
|--|--|---|-----|-----|-----|------|
| Driver Enable to Output High | t _{DZH} | Figure 4 and 6, C _L =100pF S2 Closed | | | 200 | ns |
| Driver Enable to Output Low | t _{DZL} | Figure 4 and 6, C _L =100pF S1 Closed | | | 200 | ns |
| Driver Disable Time from Low | t _{DLZ} | Figure 4 and 6, C _L =15pF S1 Closed | | | 300 | ns |
| Driver Disable Time from High | t _{DHZ} | Figure 4 and 6, C _L =15pF S2 Closed | | | 300 | ns |
| Receiver Input to Output | t _{RPLH} t _{RPHL} | Figure 7 and 9, $ V_{ID} \ge 2.0V$; ; rise and fall time of VID \le 15ns | | 450 | 800 | ns |
| T _{RPLH} – T _{RPHL} Differential Receiver Skew | t _{RSKD} | Figure 7 and 9, $ V_{ID} \ge 2.0V$; ; rise and fall time of VID \le 15ns | | 30 | | ns |
| Receiver Enable to Output Low | t _{RZL} | Figure 2 and 8, C _{RL} =15pF S1 Closed | | 20 | 50 | ns |
| Receiver Enable to Output High | t _{RZH} | Figure 2 and 8, C _{RL} =15pF S2 Closed | | 20 | 50 | ns |
| Receiver Disable Time from Low | t _{RLZ} | Figure 2 and 8, C _{RL} =15pF S1 Closed | | 80 | 150 | ns |
| Receiver Disable Time from High | t _{RHZ} | Figure 2 and 8, C _{RL} =15pF S2 Closed | | 80 | 150 | ns |
| Time to Shutdown | t _{SHDN} | | | 50 | 300 | ns |
| Driver Enable from Shutdown to Output High | t dzh(shdn) | Figure 4 and6, C _L =100pF S2 Closed | | | 200 | ns |
| Driver Enable from Shutdown to Output Low | t dzl(shdn) | Figure 4 and 6, C _L =100pF S1 Closed | | | 200 | ns |



| Receiver Enable from Shutdown to Output High | t _{RZH(SHDN)} | Figure 2 and 8, C _{RL} =15pF S2 Closed | | 300 | ns |
|--|------------------------|--|--|-----|----|
| Receiver Enable from Shutdown to Output Low | t _{RZL(SHDN)} | Figure 2 and 8, C _{RL} =15pF S1 Closed | | 300 | ns |

Test Circuits and Timing Diagrams

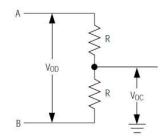


Figure 1: Driver DC Test Load

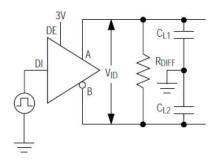


Figure 3: Driver Timing Test Circuit

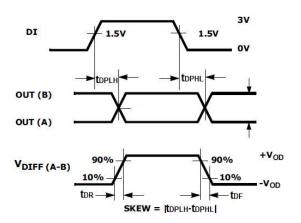


Figure 5: Driver Propagation Delays

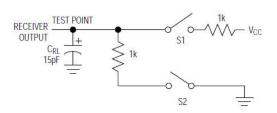


Figure 2: Receiver Enable/Disable Timing Test Load

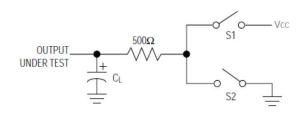
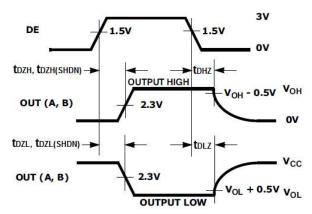
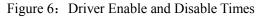


Figure 4: Driver Enable/Disable Timing Test Load







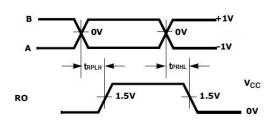


Figure 7: Receiver Propagation Delays

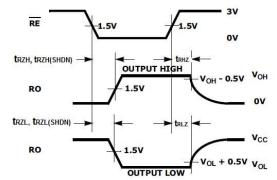


Figure 8: Receiver Enable and Disable Times

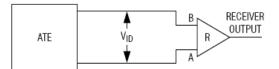
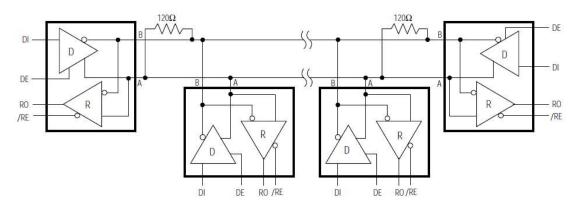
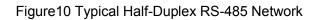


Figure 9: Receiver Propagation Delay Test Circuit

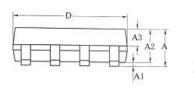
Typical Application

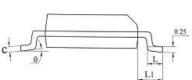


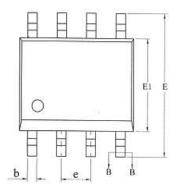


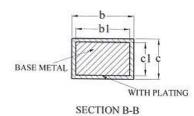


Package Information (SOP8)









| SYMBOL | M | ILLIMET | ER | |
|--------|---------|---------|------|--|
| STMBUL | MIN | NOM | MAX | |
| А | | - | 1.77 | |
| A1 | 0.08 | 0.18 | 0.28 | |
| A2 | 1.20 | 1.40 | 1.60 | |
| A3 | 0.55 | 0.65 | 0.75 | |
| ь | 0.39 | | 0.48 | |
| 61 | 0.38 | 0.41 | 0.43 | |
| c | 0.21 | - | 0.26 | |
| c1 | 0.19 | 0.20 | 0.21 | |
| D | 4.70 | 4.90 | 5.10 | |
| E | 5.80 | 6.00 | 6.20 | |
| E1 | 3.70 | 3.90 | 4.10 | |
| e | 1.27BSC | | | |
| L | 0.50 | 0.65 | 0.80 | |
| LI | 1.05BSC | | | |
| 0 | 0 | | 8° | |

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