

Features

- 3.3 and 5 VDC voltage supply option
- PWM Absolute Position
- Bushing or servo mount

CMOS and TTL compatible

- Non-contacting magnetic technology
- Small size

- Resolution: 1024 states
- Long life
- High operating speed
- Highly repeatable
- Sealed option
- Magnetic technology

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EMS22P - Non-Contacting PWM Encoder

Electrical Characteristics

Resolution	
Insulation Resistance (500 VDC)	
Electrical Travel	Continuous
Supply Voltage	
Supply Current	
Output Voltage	
Low Output Level	
High Output Level	
Output Current	
With 4.5 VDC Supply Voltage	
With 3.0 VDC Supply Voltage	
Rise/Fall Time (Incremental Output)	
Shaft RPM (Ball Bearing)	
Linearity	
Accuracy	
Nominal	±0.7 ° or better
Worst Case	±1.4 °
Output Transition Noise	0.12 ° BMS max.
Environmental Characteristics	
Operating Temperature Range	-40 °C to +125 °C (-40 °F to +257 °F)
Storage Temperature Range	
Humidity	MIL-STD-202. Method 103B. Condition B
Vibration	
Shock	
Rotational Life	
S Bushing (@1.000 rpm)	100.000 revolutions
T & W Bushings (@1 000 rpm with 250 g side load)	50 000 revolutions
IP Rating	IP 65
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Mechanical Characteristics	
Mechanical Angle	
Torque	
Starting	
Running	
Mounting Torque	
Shaft End Play	
Shaft Radial Play	0.12 mm (0.005 ") T.I.R. maximum
Weight	
Terminals	Axial, radial or ribbon cable
Soldering Condition	

Manual Soldering	
	370 °C (700 °F) max. for 3 seconds
Wave Soldering	
	260 °C (500 °F) max. for 10 seconds
Wash processes	
Marking	
Hardware	

Pin Configuration

Output Type	Pin 1	Pin 2	Pin 3	Pin 4	Pin 5	Pin 6	1α	\neg			┓
PWM	PWM Signal	GND	GND	GND	VCC*	CS**]				
* Can be 5 or 3.3 VDC depending on the version. ** Active low chip select pin; if not used connect pin 6 to GND. WARNING Cancer and Reproductive Harm - www.P65Warnings.ca.gov										RIN	
*RoHS Directive 2015/86 Specifications are subject	3, Mar 31, 2015 and	d Annex. notice		Ŭ] 1 :	23	45	e

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Applications

- Material handling equipment
- Brushless DC motor commutation
- Robotics
- Automotive
- Industrial automation
- Petroleum refinery

EMS22P - Non-Contacting PWM Encoder

Medical (low/medium risk)*

Audio and broadcast equipment

Office equipment

Output Type Waveform and Variant Table

PWM Output

Parameter		Symbol Type		Unit	Note
PWM frequer	ncy	fPWM	0.9756	KHz	Signal period: 1025 µs
MIN pulse wit	h	PWMIN	1 µS Position 0 Angle		Position 0 Angle 0 °
MAX pulse w	ith	PWMAX	1024	μs	Position 1023 Angle 359.65 °





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Position = t on * 1025/(t on + t off) - 1



Recommended Filter

R1, R2 \ge 4.7K Ohms C1, C2 \ge 1 μ F / 6 V

R1 should be \ge 4.7K ohms to avoid loading of the PWM output. Larger values of Rx and Cx will provide better filtering and less ripple, but will also slow down the response time.

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Consult factory for options not shown, including:

- . Special shaft/bushing sizes and features
- Connectors

.

- .
- Non-standard resolutions •

Wire lead or cable options

- Special performance characteristics
- PCB mounting bracket ٠

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Product Dimensions





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13.21

(0.52) 2 PLCS

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CIRCUIT #1

MM

(INCHES)

PIN 1 IDENTIFICATION STRIPE $^{>}$

DIMENSIONS:

Product Dimensions (Continued)

Shaft Style D (Bushing W)



Shaft Style C (Bushing S)





CIRCUIT #1

匝

18.0 (0.709) 2 PLCS.

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FLAT CABLE -2.0 MM PITCH ROUND CONDUCTOR 24 AWG (7X32) STRANDED, TOP COAT 6 CIRCUITS, P.V.C. INSULATION

EMS22P - Non-Contacting PWM Encoder

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How To Order



OUTPUT TYPE					
Code	Description	Notes			
Р	CW PWM	See Note 1			
R	CCW PWM	See Note 2			

* Shaft length measured from mounting surface.

** Standard ribbon cable is 10 inches long. Consult factory for other lengths. Note 1: (P) t on increases from 1 to 1025 with CW rotation of the shaft. Note 2: (R) t on increases from 1 to 1025 with CCW rotation of the shaft.

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