

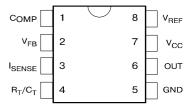
CURRENT MODE PWM CONTROLLER

DESCRIPTION

The UC3842/UC3844/UC3845 are fixed frequency current mode PWM controller. They are specially designed for OFF-Line and DC to DC converter applications with a minimal external components. Internally implemented circuits include a trimmed oscillator for precise duty cycle control, a temperature compensated reference, high gain error amplifier, current sensing comparator, and a high current totem pole output ideally suited for driving a power MOSFET. Protection circuitry includes built under voltage lockout and current limiting.

The UC3842, UC3844 have UVLO thresholds of 16 V (on) and 10 V (off). The corresponding thresholds for the UC3843, UC3845 are 8.4V (on) and 7.6V (off). The UC3842, UC3843 can operate within 100% duty cycle. The UC3844, UC3845 can operate within 50% duty cycle.

PIN CONNECTION (TOP VIEW)

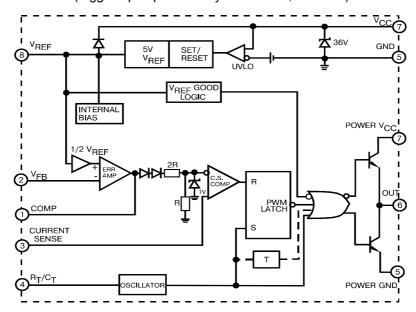


FEATURES

- Low Start-Up and Operating Current
- High Current Totem Pole Output
- Under voltage Lockout With Hysteresis
- Operating Frequency Up To 500KHz

BLOCK DIAGRAM

(toggle flip flop used only in UC3844, UC3845)



Absolute Maximum Ratings

Characteristic	Symbol	Value	Unit	
Supply Voltage (low impedance source)	V _{CC}	30	V	
Output Current	Io	±1	Α	
Input Voltage (Analog Inputs pins 2,3)	Vı	-0.3 to 5.5	V	
Error Amp Output Sink Current	I _{SINK (E.A)}	10	mA	
Power Dissipation (T _A =25 ^o C)	Po	1	W	
Storage Temperature Range	Tstg	-65 to150	°C	
Lead Temperature (soldering 5 sec.)	T∟	260	°C	



Electrical characteristics (* V_{CC} =15V, R_T =10 $k\Omega$, C_T =3.3nF, T_A =0 0C to +70 0C , unless otherwise specified)

Characteristics	Symbol	Test Condition	Min	Тур	Max	Unit	
Reference Section	Reference Section						
Reference Output Voltage	V_{REF}	T _J = 25°C, I _{REF} = 1 mA	4.9	5.0	5.1	V	
Line Regulation	ΔV_{REF}	12V ≤ V _{CC} ≤ 25 V		6.0	20	mV	
Load Regulation	ΔV_{REF}	$1 \text{ mA} \le I_{REF} \le 20 \text{mA}$		6.0	25		
Short Circuit Output Current	I _{SC}	T _A = 25°C		-100	-180	mA	
Oscillator Section							
Oscillation Frequency	f	T _J = 25°C	47	52	57	KHz	
Frequency Change with Voltage	$\Delta f/\Delta V_{CC}$	12V ≤ V _{CC} ≤ 25 V		0.05	1.0	%	
Oscillator Amplitude	V _(OSC)	(peak to peak)		1.6		V	
Error Amplifier Section							
Input Bias Current	I _{BIAS}	V _{FB} =3V		-0.1	-2	μΑ	
Input Voltage	V _{I(E.A)}	V _{pin1} = 2.5V	2.42	2.5	2.58	V	
Open Loop Voltage Gain	A _{VOL}	$2V \le V_0 \le 4V$	65	90		dB	
Unity Gain Bandwidth	UGBW	T _j =25 ⁰ C, Note 3	0.5	0.6		MHz	
Power Supply Rejection Ratio	PSRR	12V ≤ V _{CC} ≤ 25 V	60	70		dB	
Output Sink Current	I _{SINK}	$V_{pin2} = 2.7V, V_{pin1} = 1.1V$	2	7		mA	
Output Source Current	I _{SOURCE}	V _{pin2} = 2.3V, V _{pin1} = 5V	-0.5	-1.0		mA	
High Output Voltage	V _{OH}	V_{pin2} = 2.3V, R_L = 15K Ω to GND	5.0	6.0		V	
Low Output Voltage	V _{OL}	V_{pin2} = 2.7V, R_L = 15K Ω to PIN 8		0.8	1.1	T V	
Current Sense Section							
Gain	G _V	(Note 1 & 2)	2.85	3.0	3.15	V/V	
Maximum Input Signal	$V_{I(MAX)}$	V _{pin1} = 5V (Note1)	0.9	1.0	1.1	V	
Supply Voltage Rejection	SVR	12V ≤ V _{CC} ≤ 25 V (Note 1)		70		dB	
Input Bias Current	I _{BIAS}	V _{pin3} = 3V		-3.0	-10	μА	
Output Section		•					
Low Output Voltage	V _{OL}	I _{SINK} = 20 mA		0.08	0.4		
		I _{SINK} = 200 mA		1.4	2.2	V	
High Output Voltage	V_{OH}	I _{SINK} = 20 mA	13	13.5		V	
		I _{SINK} = 200 mA	12	13.0			
Rise Time	t_{R}	$T_J = 25^{\circ}C, C_L = 1nF \text{ (Note 3)}$		45	150	nS	
Fall Time	t _F	$T_J = 25^{\circ}C, C_L = 1nF \text{ (Note 3)}$		35	150	110	
Undervoltage Lockout Section							
Start Theshold	$V_{TH(ST)}$	UC3842,UC3844	14.5	16.0	17.5	V	
		UC3843,UC3845	7.8	8.4	9.0	V	
Min. Operating Voltage	$V_{OPR(min)}$	UC3842,UC3844	8.5	10	11.5	V	
(After Turn On)		UC3843,UC3845	7.0	7.6	8.2	•	
PWM Section							
Max. Duty Cycle	$D_{(MAX)}$	UC3842,UC3843	95	97	100		
	1	UC3844,UC3845	47	48	50	%	
Min. Duty Cycle	$D_{(MAX)}$				0		
Total Standby Current							
Start-Up Current	I _{ST}	UC3842/43/44/45		0.17	0.3	mA	
Operating Supply Current	I _{CC (OPR)}	$V_{pin3} = V_{pin2} = 0V$		13	17		
Zener Voltage	V_Z	I _{CC} =25 mA	30	38		V	

^{*} Adjust V_{CC} above the start threshold before setting it to 15V.

Note 1: Parameter measured at trip point of latch with V_{pin2} =0.

Note 2: Gain defined as $A=\Delta V_{pin1}/\Delta V_{pin3}$; $0 \le V_{pin3} \le 0.8V$. Note 3: These parameters, although guaranteed, are not 100% tested in production.



PIN FUNCTION

N	FUNCTION	DESCRIPTION
1	COMP	This pin is the Error Amplifier output and is made for loop compensation.
2	V_{FB}	This is the inverting input of the Error Amplifier. It is normally connected to the switching power supply output through a resistor divider.
3	I _{SENSE}	A voltage proportional to inductor current is connected to this input. The PWM uses this information to terminate the output switch conduction.
4	R _T /C _T	The oscillator frequency and maximum Output duty cycle are programmed by connecting resistor R_T to V_{ref} and capacitor C_T to ground.
5	GROUND	This pin is the combined control circuitry and power ground.
6	OUTPUT	This output directly drives the gate of a power MOSFET. Peak currents up to 1A are sourced and sink by this pin.
7	V _{CC}	This pin is the positive supply of the integrated circuit.
8	V _{ref}	This is the reference output. It provides charging current for capacitor C_T through resistor R_T .

APPLICATION INFORMATION

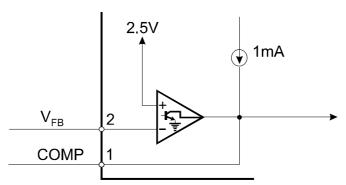


Figure 1. Error Amp Configuration

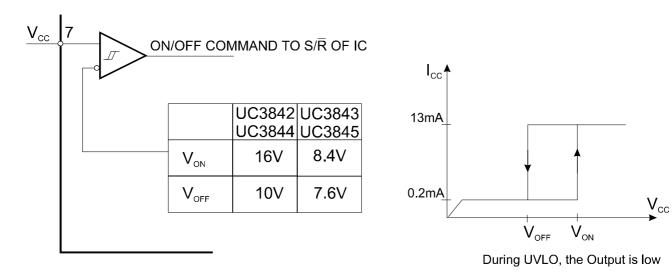


Figure 2. Under voltage Lockout



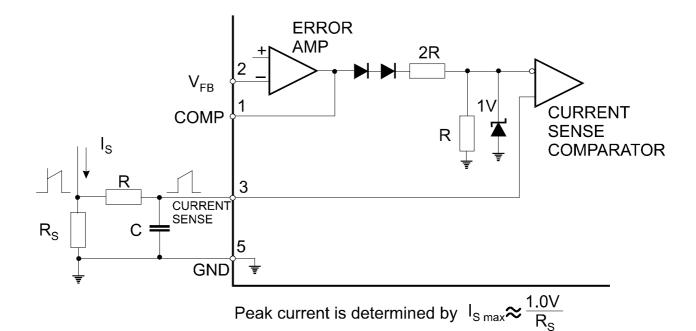


Figure 3. Current Sense Circuit

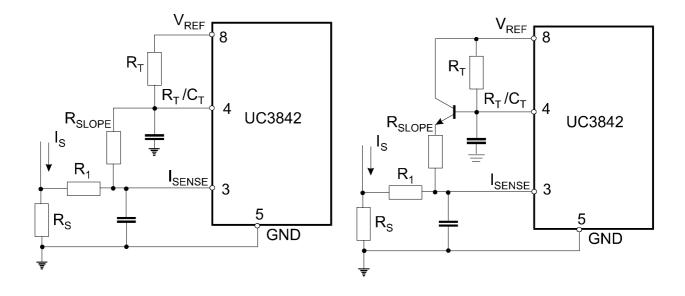
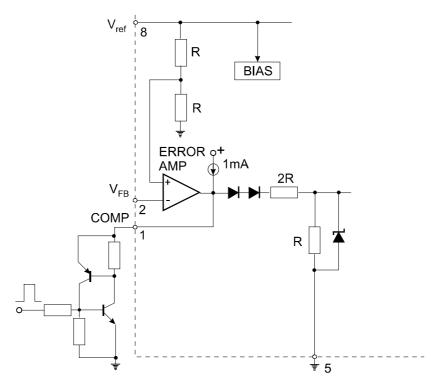


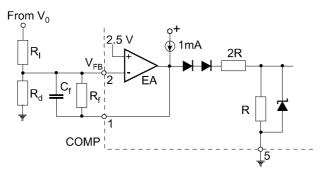
Figure 4. Slope Compensation Techniques



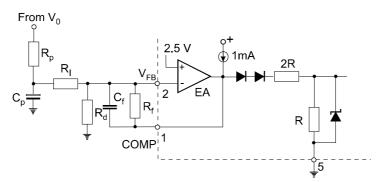


SCR must be selected for a holding current of less than 0.5mA. The simple two transistor circuit can be used in place of the SCR as shown.

Figure 5. Latched Shutdown



Error Amp compensation circuit for stabilizing any current-mode topology except for boost and flyback converters operating with continuous inductor current.



Error Amp compensation circuit for stabilizing current-mode boost and flyback topologies operating with continuous inductor current.

Figure 6. Error Amplifier Compensation



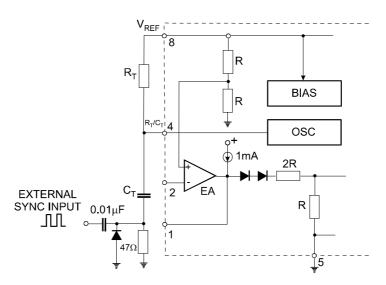


Figure 7. External Clock Synchronization

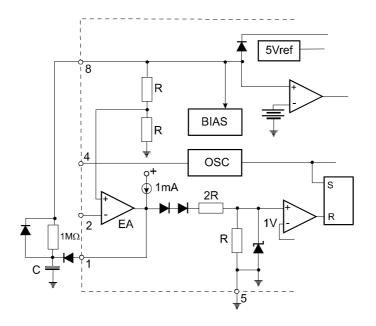


Figure 8. Soft-Start Circuit



TYPICAL PERFORMANCE CHARACTERISTICS

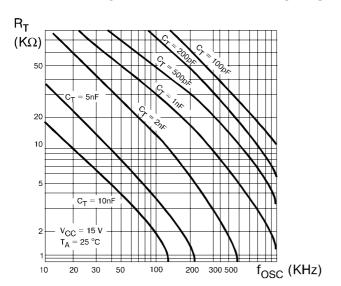


Figure 1. Timing Resistor vs. Oscillator Frequency

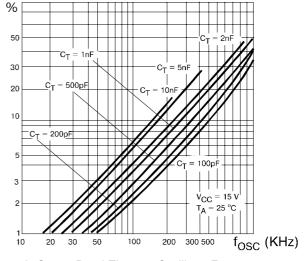


Figure 2. Output Dead-Time vs. Oscillator Frequency

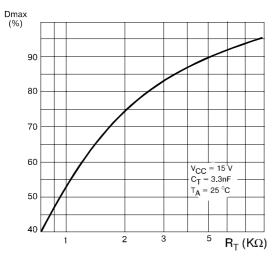


Figure 3. Maximum Output Duty Cycle vs. Timing Resistor (UC3842/43)

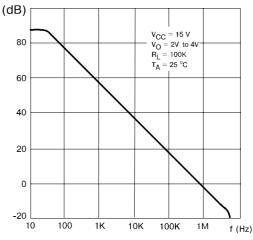


Figure 4. Error Amp Open-Loop Gain vs. Frequency

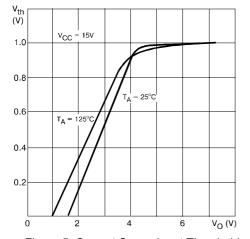


Figure 5. Current Sense Input Threshold vs. Error Amp Output Voltage

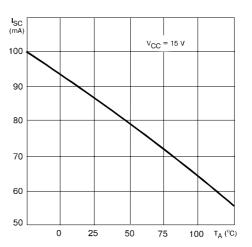
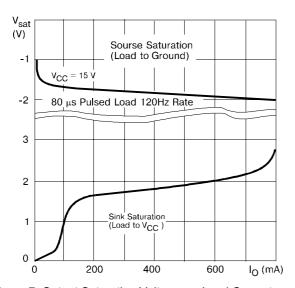
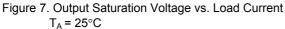


Figure 6. Reference Short Circuit Current vs. Temperature







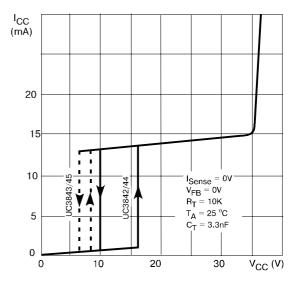


Figure 8. Supply Current vs. Supply Voltage

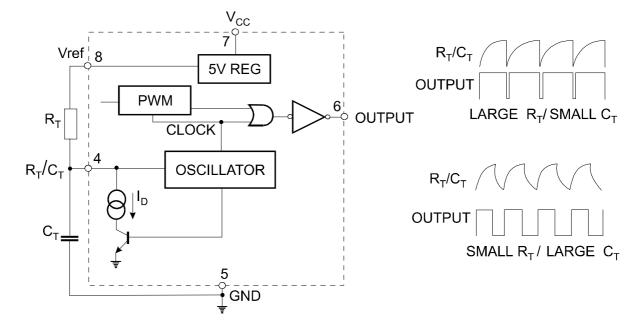


Figure 9. Oscillator and Output Waveforms



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