

# ILD6150/ILD6070 – 60 V buck LED driver IC with high accuracy and efficiency

# Operation, design guide and performance

#### About this document

#### Scope and purpose

This application note introduces Infineon's hysteretic buck DC-DC LED driver ILD6150/ILD6070 for general lighting applications. It describes the operation of the device, its features and how to select values of the passive components. As an example an available reference design and its performance is presented, as well as design ideas for various applications. The ILD6150/ILD6070 offers high efficiency, various protection features, flexible dimming options and reliability for high-performance lighting systems.

#### **Intended audience**

This document is intended for users who wish to design high-efficiency, high-reliability lighting systems with Infineon's ILD6150 (up to 1.5 A)/ILD6070 (up to 700 mA) DC-DC LED driver.

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# ILD6150/ILD6070 – 60 V buck LED driver IC with high accuracy and efficiency



### Introduction

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# 1 Introduction

This application note introduces Infineon's buck LED driver IC ILD6150/ILD6070. ILD6150 and ILD6070 are identical except for maximum current allowed, and hereafter ILD6150 means ILD6070 as well. ILD6150 offers high efficiency, multiple protection features, flexible dimming options and reliability for high-performance lighting systems.

ILD6150 is a hysteretic buck driver IC for use in general LED lighting applications with average currents up to 1.5 A. The hysteretic concept of current control is extremely fast and always stable without the need for any loop compensation. It is suitable for applications with a wide range of supply voltages from 4.5 V to 60 V, allowing input operation up to the maximum Safety Electrical Low Voltage (SELV) of 60 V.

A multifunctional dimming input allows dimming of the LEDs with a DC voltage or a PWM signal.

A maximum contrast ratio of 3000:1 can be achieved depending on the external components. The efficiency of the LED driver is remarkably high, reaching up to 98 percent efficiency over a wide range. The output current variation from device to device and under all load conditions and over-temperature is limited to a minimum. The ILD6150 reference design can also be used as a constant current output second-stage DC-DC converter with a constant input voltage from a front stage AC-DC converter (XDPL8218), making ILD6150 the perfect fit for LED drivers.

### 1.1 Features

- Wide-input voltage range from 4.5 V to 60 V
- Capable of providing up to 1.5 A output current
- Up to 1 MHz switching frequency
- Soft-start capability
- Analog and PWM dimming input signal possible
- Typical 3 percent output current accuracy
- Very low LED current drift over-temperature
- Under Voltage Lockout (UVLO)
- Over Current Protection (OCP)
- Thermally optimized package: PG-DSO-8-27
- Adjustable Over Temperature Protection (OTP)

## 1.2 Application

- LED drivers for general lighting
  - with single output channel
  - with two output channels for tunable white light
- LED drivers for horticultural lighting
  - with multiple output channels



# 2 Circuit description

## 2.1 Operation

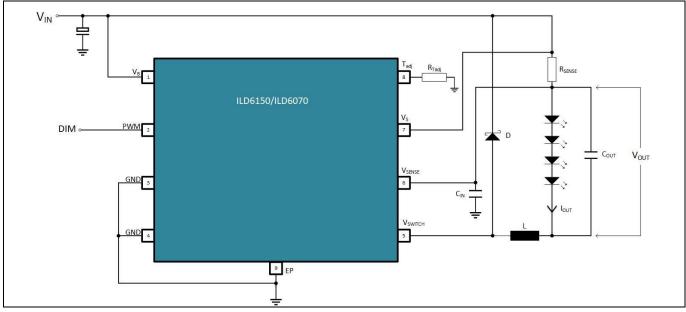


Figure 1 Application schematic

### 2.1.1 Current regulation

Under normal operating conditions the LED current  $I_{OUT}$  is controlled by means of the voltage difference between pins V<sub>s</sub> and V<sub>SENSE</sub>, which is proportional to the current through R<sub>SENSE</sub>. This voltage is compared to two threshold levels, and the internal switch is turned on and off accordingly.

As long as the difference is above the lower internal threshold  $V_{THL}$ , the MOSFET is in the on-state and the current through  $R_{SENSE}$  and load is rising linearly with the slope:

$$\frac{dI_{OUT}}{dt} = \frac{V_{IN} - V_{OUT}}{L}$$

As soon as the threshold is crossed the MOSFET is turned off and current through  $R_{\text{SENSE}}$  is now decreasing with the slope:

$$\frac{dI_{OUT}}{dt} = -\frac{V_D + V_{OUT}}{L}$$

until the higher threshold voltage  $V_{\text{THH}}$  is hit. Now the MOSFET is turned on again and the above described cycle is repeated.

Obviously the converter operates in Continuous Conduction Mode (CCM) and the average output current  $I_{OUT}$  can be determined by means of the average threshold  $V_{SENSE} = (V_{THH} + V_{THL})/2 = 152$  mV in the case of ILD6150.

The peak-to-peak ripple amplitude of  $I_{OUT}$  only depends on the hysteresis  $V_{SENSEHYS}$ , which in the case of ILD6150 is 44 percent of  $V_{SENSE}$  or 67 mV.



## 2.1.2 Over Current Protection (OCP)

ILD6150 has two OCP techniques. First, the output current is within limitation even if the output gets shorted as long as R<sub>SENSE</sub> is not damaged. Second, ILD6150 has OCP, which is triggered when the MOSFET current is higher than 2.5 A typically. This can happen when R<sub>SENSE</sub> is shorted or damaged. Although the IC will not be damaged in this case the OCP feature does not guarantee the protection of the LEDs.

## 2.1.3 Over Temperature Protection (OTP)

ILD6150 has an integrated OTP based on the junction temperature on chip. OTP is required to prevent the IC from operating at a potentially destructive temperature. The threshold of the OTP can be set by resistor  $R_{Tadj}$  connected from pin  $T_{adj}$  to GND. The OTP is based on modulation of the LED current with an internal PWM generator. Once the junction temperature exceeds the OTP threshold the PWM duty cycle as well as the average LED current will be reduced. Once junction temperature reaches threshold  $T_{OTP,off}$  the PWM duty cycle and LED current will be reduced to zero.

## 2.1.4 Under Voltage Lockout (UVLO)

UVLO is implemented to protect the IC from operating at insufficient supply voltage. ILD6150 incorporates an UVLO that will shut down the IC when the minimum supply voltage falls below the internal threshold of typically 4.25 V.

## 2.1.5 Dimming

A multifunctional input allows dimming of the LED current either by means of a DC voltage or a PWM signal applied to this pin. To minimize color-shift of the LEDs, independent of the type of input, an internal 1.6 kHz PWM signal is generated that modulates the LED current.

Depending on which type of signal is applied, the duty cycle of this internal PWM signal is either proportional to the DC voltage or to the duty cycle of the signal at the dimming pin.

## 2.1.6 Soft-start

Soft-start helps to reduce component stress when the application starts and can also be used to effect a slow increase of light output, if desired. This can be achieved by adding a capacitor at the PWM pin. ILD6150 having an internal current source of 18  $\mu$ A will charge up the capacitor at the PWM pin from 0 V to 4.7 V linearly.

Refer to the specification of the analog dimming; the linear range of the output current from 0 percent to 100 percent is within the range from 0.67 V to 2.43 V. Hence the value of  $\Delta V$  is equal to 1.76 V and the current *i* is equal to 18  $\mu$ A. The soft-start timing can be calculated using below equation:

$$C = \frac{\Delta t \cdot i}{\Delta V} = \frac{\Delta t \cdot 18 \ \mu A}{1.76 \ V} = \Delta t \cdot 10.2 \ \mu$$

If a capacitor of more than a few hundred pF is attached to the PWM pin, dimming with a PWM input may be difficult due to high displacement currents flowing.



### 2.2 Component selection

#### 2.2.1 Sense resistor

The average LED current is determined by the value of the external current sense resistor ( $R_{SENSE}$ ). As mentioned above, the mean current sense threshold voltage is  $V_{SENSE}$  = 152 mV. Therefore the proper value of  $R_{SENSE}$  is given by:

$$R_{sense} = \frac{152mV}{I_{OUT}}$$

### 2.2.2 Selection of inductor and operating frequency

The inductor shall supply a constant current to the LED. In CCM the inductor value L is related to the switching frequency  $f_{sw}$ , as shown below:

$$L = \frac{1}{\Delta i \cdot f_{SW} \cdot \left(\frac{1}{V_{IN} - V_{OUT}} + \frac{1}{V_{OUT}}\right)}$$

where V<sub>IN</sub> is the input voltage, V<sub>OUT</sub> is the output voltage and  $\Delta i$  is current ripple, which is given by:

 $\Delta i = V_{SENSEHYS} \cdot I_{OUT} = 0.44 \cdot I_{OUT}$ 

where  $V_{\mbox{\tiny SENSEHYS}}$  is sense threshold hysteresis.

For a given inductor value  $f_{SW}$  will vary with varying input and output voltage. Selection of operating frequency is a trade-off between system efficiency and switching noise on the one hand, and inductor and board size and cost on the other. As the frequency increases so do switching noise and losses, while the size and cost of the inductor and capacitor decrease. The switching losses become the major driving factor as  $V_{IN}$  increases to higher voltages.

To maintain best regulation capability of the LED driver IC it is reasonable to keep a margin to the minimum switch-on and switch-off times defined by internal propagation delay times. Disregard of this recommendation by choosing inductor values that are too small might result in an increased LED current ripple and loss of LED current regulation accuracy. Minimum 350 ns on- and off-times are recommended as a reasonable design target for the inductor selection.

The saturation current  $I_{sat}$  of the chosen inductor has to be higher than the peak LED current  $I_{Pk} = I_{OUT} + \Delta t/2$ , and its continuous current needs to exceed the average LED current  $I_{OUT}$ .

### 2.2.3 Selection of diode D

Once the switch turns off, the residual energy of the inductor is discharged through the diode into the output capacitor and the LED load. Typically a Schottky diode is used to reduce losses caused by the diode forward voltage and reverse recovery times.

The first parameter to consider when selecting a diode is its maximum reverse voltage  $V_{BR}$ . This voltage rating must be higher than the maximum input voltage  $V_S$  of the circuit:  $V_{BR}$  greater than  $V_S$ .

The other two parameters defining the diode are average and RMS forward currents  $I_{D,AVG}$  and  $I_{D,RMS}$ , which are given by:

$$I_{D,AVG} = I_{OUT} \cdot (1 - d)$$
$$I_{D,RMS} = I_{OUT} \cdot \sqrt{1 - d} \cdot \sqrt{1 + \frac{1}{12} \cdot \left(\frac{\Delta i}{I_{OUT}}\right)^2}$$

where d is the duty cycle of the switching waveform and is given by:

$$d = \frac{V_{OUT}}{V_{IN}}$$

The diode must be chosen so that its respective current ratings are higher than these values. Reverse blocking capability should be higher than V<sub>IN</sub>, with a meaningful margin of 25 percent or so.



### 2.2.4 Selection of input capacitor $C_{IN}$

The input current of the buck controller is identical to the current through the MOSFET – i.e. it is pulsating and thus causes a ripple voltage at the input. A capacitor close to pin V<sub>s</sub> reduces this ripple voltage by providing current when the switch is conducting. The RMS current through the input capacitor I<sub>C,RMS</sub> is purely AC and can be calculated from average and RMS inputs currents I<sub>IN,AVG</sub> and I<sub>IN,RMS</sub> as:

$$I_{C,RMS}^2 = I_{IN,RMS}^2 - I_{IN,AVG}^2$$

Hence,

$$I_{C,RMS} = I_{OUT} \cdot \sqrt{d \cdot \left(1 - d + \frac{1}{12} \cdot \left(\frac{\Delta i}{I_{OUT}}\right)^2\right)}$$

Use low-ESR capacitors, especially under high switching frequency applications. With low-ESR capacitors, the input voltage ripple can be estimated by:

$$\Delta V_S = \frac{I_{OUT}}{f_{SW} \cdot C_{in}} \cdot d \cdot (1 - d)$$
$$C_{IN} \ge \frac{I_{OUT}}{f_{SW} \cdot \Delta V_S} \cdot d \cdot (1 - d)$$

The input capacitor must be chosen so that it is capable of withstanding the calculated RMS current rating and reducing input voltage ripples to an acceptable level.

### 2.2.5 Selection of output capacitor COUT

Due to the relatively low ripple current of a buck with ILD6150 a capacitor in parallel to the LED that reduces ripple even further is not needed in many applications.

Due to the non-linear I-V characteristic of LED it is very difficult to estimate the ripple voltage with and without output capacitor. A generally accepted model is the approximation of LED V-I characteristic by a voltage source  $V_{FD}$ , which models the forward voltage of the LED with a series resistor  $R_D$  to model differential resistance. Both parameters need to be determined from the LED datasheet. As a rule of thumb a  $V_{FD}$  of 2.8 V and a differential resistance  $R_D$  of 0.4  $\Omega$  are very reasonable values for typical white, high-power LED. Consequently, for 12 LEDs in series this would lead to a  $V_{FD}$  of 33.6 V and a total  $R_D$  of 4.8  $\Omega$ . The ripple voltage without capacitor is then approximated as:

$$\Delta V_{OUT} \cong \Delta i \cdot R_D$$

A meaningful output capacitor should therefore have an impedance at  $f_{SW}$  which is at least five to ten times lower than  $R_D$ :

$$C_{OUT} \gg \frac{5}{2\pi \cdot f_{SW} \cdot R_D}$$

### 2.2.6 Selection of R<sub>Tadj</sub>

ILD6150 has an integrated OTP based on the junction temperature on chip. The threshold of the OTP circuit is tunable by resistor  $R_{Tadj}$  connected from pin  $T_{adj}$  to GND.  $R_{Tadj}$  resistor values within 0 to 35 k $\Omega$  define the OTP behavior.  $R_{Tadj}$  values greater than or equal to 150 k $\Omega$  set the OTP threshold to  $T_{OTP,Open}$ . OTP is based on modulation of the LED current with an internal PWM generator. Once the junction temperature exceeds the OTP threshold the PWM duty cycle as well as the average LED current will get reduced. Once the junction temperature reaches  $T_{OTP,Off}$  the PWM duty cycle and LED current will be reduced to zero. Adjustable OTP offers great flexibility with the starting point of the current reduction at high temperature, and can be designed according to the LED lamp requirement.



#### 2.3 Layout consideration

An optimized PCB layout leads to better performance, reliability and lower cost. Certain layout guidelines must be kept in mind while routing the PCB.

The power components include the internal switch, Schottky diode, input capacitor, output capacitor and inductor. Route the input capacitor close to the IC, as parasitic inductance can be minimized by minimizing trace lengths and using short and wide traces. Extra parasitic inductance between the input capacitor's terminals and the IC's V<sub>B</sub> and GND terminals creates high dv/dt due to the switching process. This can lead to IC failure. Also, place the inductor as close as possible to the IC to reduce radiated EMI.

The output capacitor completes the routing of all the power components. It is the final component connected to the power ground terminal in the system. An improper output capacitor placement typically causes poor output voltage regulation. To ensure optimum operation, take care to minimize the area of the power-current loop.

The small-signal control components consists of all analog and digital components indirectly related to the power conversion like the sense voltage pin, soft-start capacitor, etc., and are sensitive to noise. To reduce the noise coupling from the power stage to the control circuitry, it is necessary to keep the noisy switching traces far from the sensitive small-signal traces. To minimize noise and ensure good output voltage regulation, it is critical to keep the V<sub>SENSE</sub> path as small as possible, and it is desirable to return the ground of the small signal component to a "clean" point. Poor routing of small-signal components may lead to poor output voltage regulation.

Keep separate grounds for power components, which are noisy, and for the small-signal components, which are quiet. Then join these two grounds at one point, possibly the exposed pad under the IC, which is also the IC ground. A grid of thermal vias can be created to improve the thermal conduction under the exposed pad. The above guidelines ensure a well laid-out power supply design.

#### 2.4 **Design example**

As an example an LED driver with the following specification shall be designed:

V<sub>s</sub> = 48 V

I<sub>OUT</sub> = **1 A** 

V<sub>LED</sub> = **36.3 V** (12 pieces LED)

#### 2.4.1 **Determine R**SENSE

$$R_{SENSE} = \frac{0.152 \, V}{1 \, A} = \mathbf{0}. \, \mathbf{152} \, \Omega$$

Next closest standard value of 0.15  $\Omega$  will be used, increasing the nominal output current to I<sub>OUT</sub> = 1.013 A

#### 2.4.2 Select switching frequency

90 kHz may be a reasonable compromise between switching loss and inductor size. This needs to be verified by measurement on the finished design.

#### Calculation of inductor value and currents 2.4.3

$$L = \frac{1}{1.013A \cdot 0.44 \cdot 90 \ kHz \cdot \left(\frac{1}{48 \ V - 36.3 \ V} + \frac{1}{36.3 \ V}\right)} = 220.5 \ \mu H$$

**Application Note** 



The next closest standard value is **220**  $\mu$ **H** leading to a slightly higher f<sub>sw</sub>.

The inductor average current is 1.013 A, while the peak current will be  $I_{Pk} = I_{OUT} + \Delta t/2 = I_{OUT} * 1.22 = 1.24$  A. Saturation current  $I_{SAT}$  of the inductor must be higher than the latter value.

#### 2.4.4 Diode selection

To calculate diode currents the duty-cycle **d** is needed:

$$d = \frac{V_{OUT}}{V_{IN}} = \frac{36.3}{48} = 0.756$$
$$1 - d = 0.243$$

RMS diode current:  $I_{D,RMS} = 1.013 \cdot \sqrt{0.243 \cdot \left(1 + \frac{1}{12} \cdot \left(\frac{0.44}{1.013}\right)^2\right)} = 0.503 A$ 

Average diode current:  $I_{D,AVG} = 1.013 \cdot 0.243 = 0.246 A$ 

For a design with variable number of LEDs the highest diode currents will occur at the lowest output voltage. "1-d" is close to one under such conditions, and diode currents are close to output current. In general a 1 A diode is recommended as long as output current is below 1 A and a 2 A diode otherwise.

The reverse blocking voltage  $V_{BR}$  of the diode must be higher than the maximum input voltage  $V_{IN}$ . A 60 V diode is sufficient in this example, but a  $V_{BR}$  of 80 V will increase robustness and reliability of the design.

#### 2.4.5 Selection of capacitor C<sub>IN</sub>

$$C_{IN} \ge \frac{1.013}{90.2 \cdot 10^3 \cdot 0.01 \cdot 48} \cdot 0.756 \cdot 0.243 = 4.30 \,\mu F$$

The  $C_{IN}$  value depends on parameters "d,"  $I_{out}$  and  $f_{SW}$ , which are variables and can result in higher values of input capacitor. Therefore, a 47  $\mu$ F electrolytic capacitor with a rated voltage of 100 V would be recommended in this case.

#### 2.4.6 Selection of capacitor Cout

The value of  $C_{OUT}$  can be estimated as:

$$C_{OUT} \gg \frac{5}{2\pi \cdot 90.2 \ kHz \cdot 4.8 \ \Omega} = \mathbf{1.84} \ \mu \mathbf{F}$$

For lower output voltage ripple a bigger output capacitor can be used. Since the value of this capacitor is relatively low even for low ripple demands an MLCC capacitor will be the best choice in terms of cost, lifetime and ESR. A 4.7  $\mu$ F MLCC capacitor would be recommended in this case. If an electrolytic capacitor is used for any reason, attention needs to be payed to the ripple current capability and ESR. Rated voltage needs to be higher than the highest possible output voltage in any case.



**Application circuit** 

#### 3 **Application circuit**

This section provides more information about the reference design available for evaluation. The reference design is configured to have an output current of 1 A. The operating voltage range for the reference design can be from 4.5 V up to 60 V. The schematic, PCB layout and PCB photo are shown in Figure 2, Figure 3 and Figure 4 respectively. The bill of materials can be found in Appendix A.

#### 3.1 Schematic layout

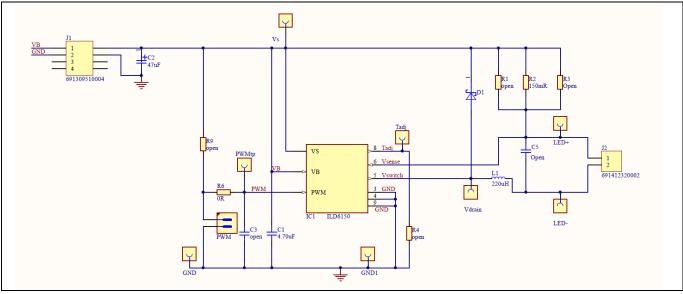
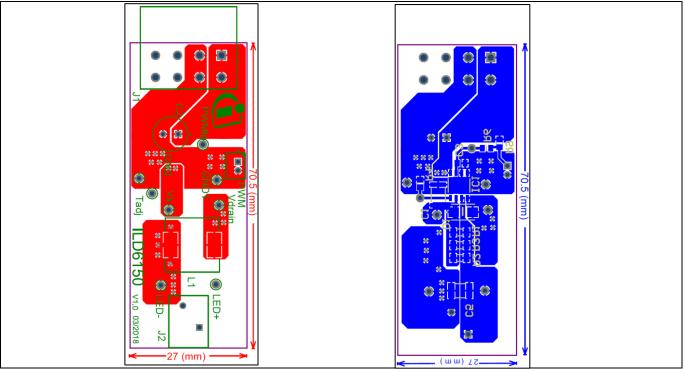


Figure 2 Schematic of the reference design

#### 3.2 **PCB** layout



PCB layout of the reference design Figure 3

# ILD6150/ILD6070 - 60 V buck LED driver IC with high accuracy and efficiency



Application circuit

#### 3.3 PCB photo



Figure 4 Photo of the reference design



Measurement results with reference design

# 4 Measurement results with reference design

Table 1	Typical condition for measurement
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Vs	R <sub>sense</sub>	Inductance	LED load
48 V	0.15 Ω	220 µH	12 pieces

Figure 5 shows the actual operating waveforms. The actual measured LED current is 1 A. The switching frequency is 92.4 kHz and the internal DMOS transistor on duty cycle is 78.9 percent.

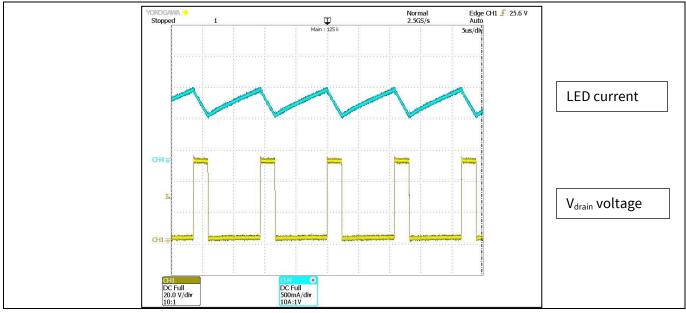
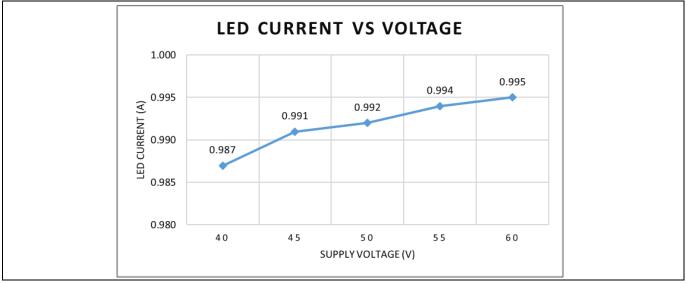


Figure 5 Normal operation waveform

## 4.1 LED current vs supply voltage

ILD6150 offers a high accuracy of output current despite the changes in supply voltage. Figure 6 shows the output current versus the supply voltage over the range of 40 V to 60 V. Over the supply range, the output LED current only deviates by 2 percent.







Measurement results with reference design

## 4.2 **PWM dimming**

The multifunctional PWM input pin allows dimming of the LEDs with a PWM input. The LED current varies linearly with the duty cycle of the PWM pulse, as shown in Figure 7.

#### Table 2 Condition for PWM dimming

V <sub>PWM</sub>	PWM frequency	LED
48 V	1 kHz	12 pieces

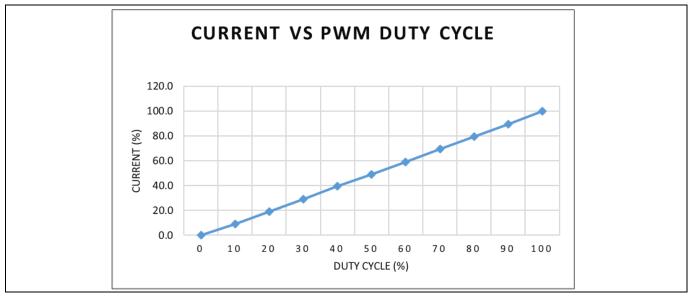


Figure 7 Output current vs duty cycle

## 4.3 Analog dimming

The multifunctional PWM input pin allows dimming of the LEDs with an analog DC voltage. The linear range of the analog dimming is from 0.5 V to 2.5 V. LEDs are fully turned on for voltage above 2.5 V and fully turned off for voltage below 0.5 V, as shown in Figure 8.

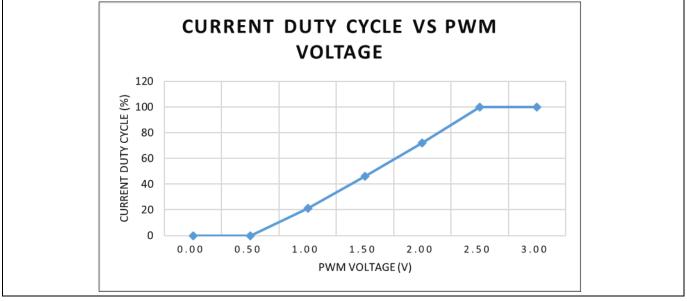


Figure 8 Analog dimming ratio vs PWM pin voltage

# ILD6150/ILD6070 – 60 V buck LED driver IC with high accuracy and efficiency



#### Measurement results with reference design

Figure 9 shows the output waveforms while the PWM pin voltage is equal to 1.5 V. The output current is modulated by the internal PWM signal at 1.6 kHz.

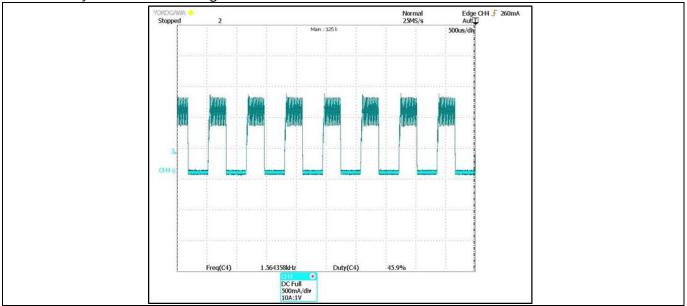


Figure 9 Output waveforms at V<sub>PWM</sub> = 1.5 V

### 4.4 Soft-start

A capacitor with the value of 10  $\mu$ F is connected to the PWM pin, and the soft-start timing for the light output from 0 percent to 100 percent requires 0.978 s. Figure 10 shows the LED current waveform which is modulated by the PWM signal from 0 percent to 100 percent output. The actual measurement result for the soft-start is 0.700 s.

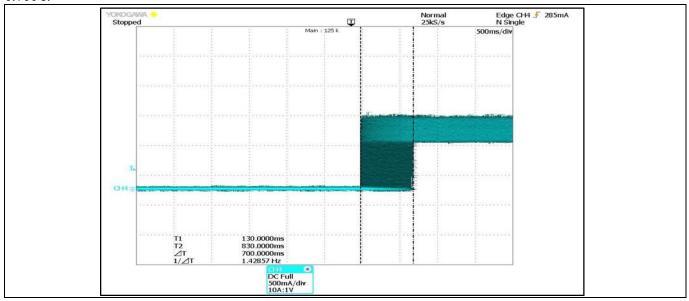


Figure 10 Soft-start with 10 µF at the PWM pin

# ILD6150/ILD6070 - 60 V buck LED driver IC with high accuracy and efficiency



Measurement results with reference design

### 4.5 OCP

Figure 11 shows the waveforms where the ILD6150 is in OCP mode. The  $R_{SENSE}$  is shorted, and the LED's load is replaced by a DC electronic load with constant voltage of 0.01 V and supply voltage of 20 V.

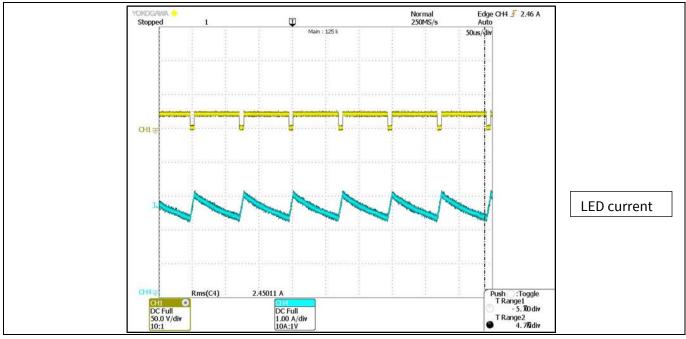


Figure 11 OCP waveforms

## 4.6 Efficiency

The measurement results of efficiency of the system for supply voltage ( $V_s$ ) ranging from 40 V to 60 V can be found in Figure 12. The efficiency ranges from 94 percent to 98 percent for 12 pieces LED as load.

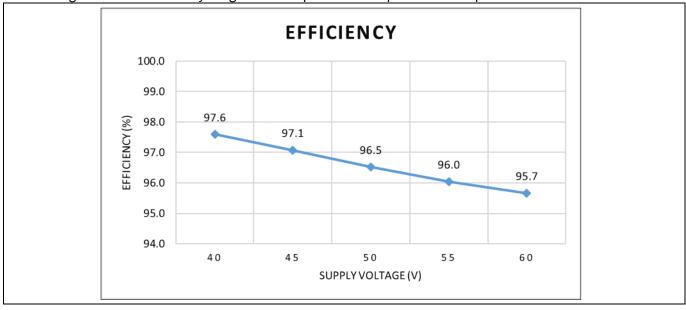


Figure 12 Efficiency vs supply voltage



Measurement results with reference design

#### **Thermal behavior** 4.7

The maximum temperature attained by the reference design is 96.6°C, as shown in Figure 13. The test is conducted with an input voltage of 60 V and with 10 pieces of LEDs as load. This condition results in maximum switching frequency, and therefore results in maximum temperature.

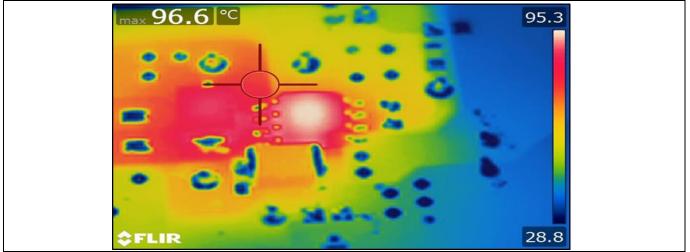
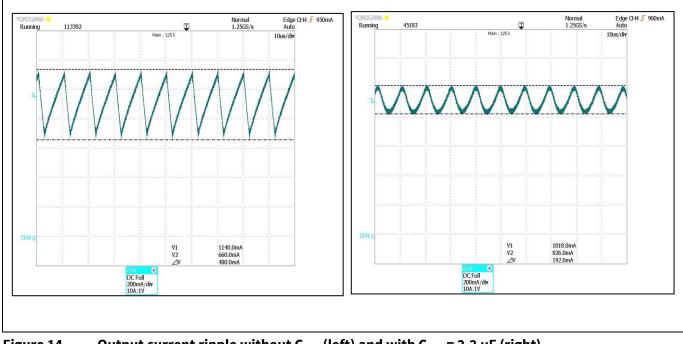


Figure 13 Maximum temperature on the reference design

#### 4.8 **Output current ripple**

Figure 14 shows the waveform of the output current ripple with and without an output capacitor. It is observed that by placing a capacitor with value 2.2 µF the output voltage ripple reduces to 2.74 percent from the earlier value of 6.85 percent.



Output current ripple without Cout (left) and with Cout = 2.2 µF (right) Figure 14



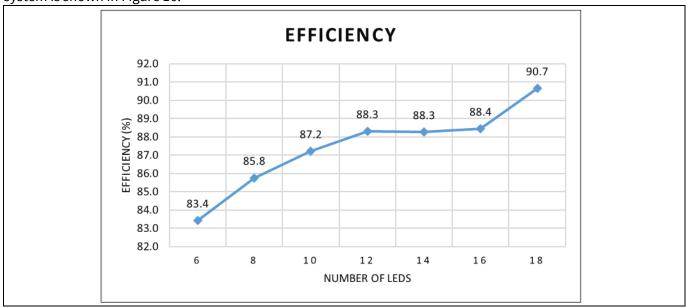
**Application with flyback converter XDPL8218** 

# 5 Application with flyback converter XDPL8218



Figure 15 Modular reference design consisting of AC-DC converter based on XDPL8218 with ILD6150 DC-DC buck

The XDPL8218 40 W reference design is a digitally configurable front-stage High Power Factor (HPF) flyback converter with universal AC input of 90 V<sub>rms</sub> to 305 V<sub>rms</sub> and Secondary Side Regulated (SSR) Constant Voltage (CV) output of 54 V. The CV output cannot be directly used to drive the LEDs. For LED lighting applications, it should be converted to Constant Current (CC) output by a second-stage DC-DC switching or linear regulator. The ILD6150 reference design can be used as the second-stage DC-DC buck converter, as shown in Figure 15. The ILD6150 hysteretic buck converter then operates with a fixed input voltage of 54 V. The efficiency of such a system is shown in Figure 16.







# 6 Appendix A

Table 3 Bill of Materials (BOM)

Qty.	Designator	Value	Parameters	Manufacturer	Manufacturer order number
1	C1	4.70 µF	V DC:100 V	TDK	CGA8N3X7S2A475K230KB
1	C2	47 µF	V DC:100 V	Panasonic	ECA2AM470
			Ur:[100 V]	Diodes	
1	D1		If:[2 A]	Incorporated	B2100-13-F
8	GND, GND1, LED+, LED-, PWMtp, Tadj, Vdrain, Vs	VER_TESTPOINT_PTH		Vero Technologies	20-2137
0			V DC 4.5 V to 60 V;		
1	IC1	ILD6150	Ι <sub>ουτ</sub> 1.5 Α:	Infineon	ILD6150XUMA1
			WR-TBL series 3095 – 5.08 mm reversed		
1	J1	Reversed gender horizontal PCB header, 04 p	gender horizontal PCB header, 04 p	Würth Electronics	691309510004
		Screwless 45-degree	WR-TBL series 4123 – 3.81mm screwless 45-degree	Würth	
1	J2	entry, 2 p	entry, 2 p	Electronics	691412320002
1	L1	220 µH	I DC:1.8 A	Würth Electronics	7447709221
			Conn header PH TOP 2POS 2	JST	
1	PWM	2 p	mm	Corporation	B2B-PH-K-S(LF)(SN)
1	R2	150 mR	P:250 mW	Bourns Inc.	CRL1206-FW-R150ELF
1	R6	0 R	P:125 mW	Multicomp	MCMR08X000 PTL



## References

Please refer to the ILD6150/ILD6070 datasheets for more information:

ILD6150 datasheet ILD6070 datasheet

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