

# EN6347QI 4A PowerSoC

## Step-Down DC-DC Switching Converter with Integrated Inductor

### DESCRIPTION

The EN6347QI is an Intel® Enpirion® Power System on a Chip (PowerSoC) DC-DC converter. It integrates the inductor, MOSFET switches, small-signal circuits and compensation in an advanced 4mm x 7mm x 1.85mm 38-pin QFN package.

The EN6347QI is specifically designed to meet the precise voltage and fast transient requirements of present and future high-performance, low-power processor, DSP, FPGA, memory boards and system level applications in distributed power architectures. The device's advanced circuit techniques, high switching frequency, and proprietary integrated inductor technology deliver high-quality, ultra compact, non-isolated DC-DC conversion.

Intel Enpirion Power Solutions significantly help in system design and productivity by offering greatly simplified board design, layout and manufacturing requirements. In addition, a reduction in the number of components required for the complete power solution helps to enable an overall system cost saving.

All Enpirion products are RoHS compliant and lead-free manufacturing environment compatible.

### FEATURES

- Integrated Inductor, MOSFETs, Controller
- 1.5%  $V_{OUT}$  Accuracy (Over Load and Temperature)
- Up to 4A Continuous Operating Current
- 3 MHz Operating Frequency with Ext Clock Sync
- High Efficiency (Up to 95%)
- Frequency Synchronization to External Clock
- Input Voltage Range (2.5V to 6.6V)
- Programmable Light Load Mode
- Output Enable Pin and Power OK
- Programmable Soft-Start
- Thermal Shutdown, Over-Current, Short Circuit, and Under-Voltage Protection
- RoHS Compliant, MSL Level 3, 260°C Reflow

### APPLICATIONS

- Point of Load Regulation for Low-Power, ASICs Multi-Core and Communication Processors, DSPs, FPGAs and Distributed Power Architectures
- Low Voltage, Distributed Power Architectures
- High Efficiency 12V Intermediate Bus Architectures
- Blade Servers, RAID Storage, Industrial Automation, Embedded Computing, Wireless Communications
- Beat Frequency/Noise Sensitive Applications

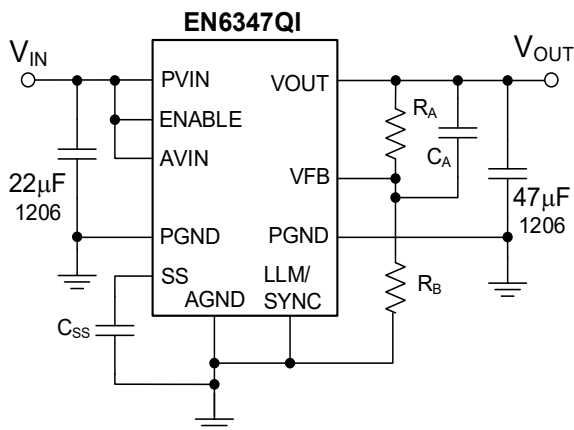


Figure 1. Simplified Applications Circuit

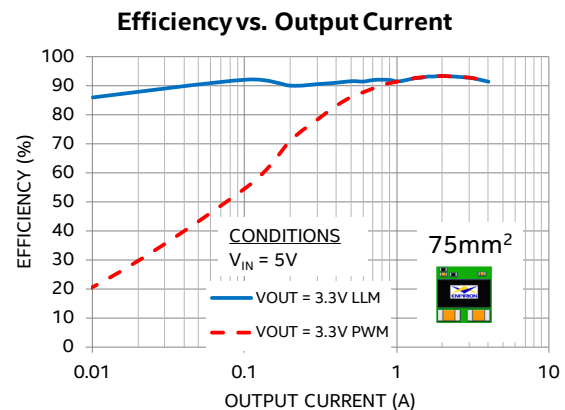


Figure 2. Highest Efficiency in Smallest Solution Size

## ORDERING INFORMATION

Part Number	Package Markings	T <sub>J</sub> Rating	Package Description
EN6347QI	EN6347	-40°C to +125°C	38-pin (4mm x 7mm x 1.85mm) QFN
EVB-EN6347QI	EN6347	QFN Evaluation Board	

Packing and Marking Information: <https://www.intel.com/support/quality-and-reliability/packing.html>

## PIN FUNCTIONS

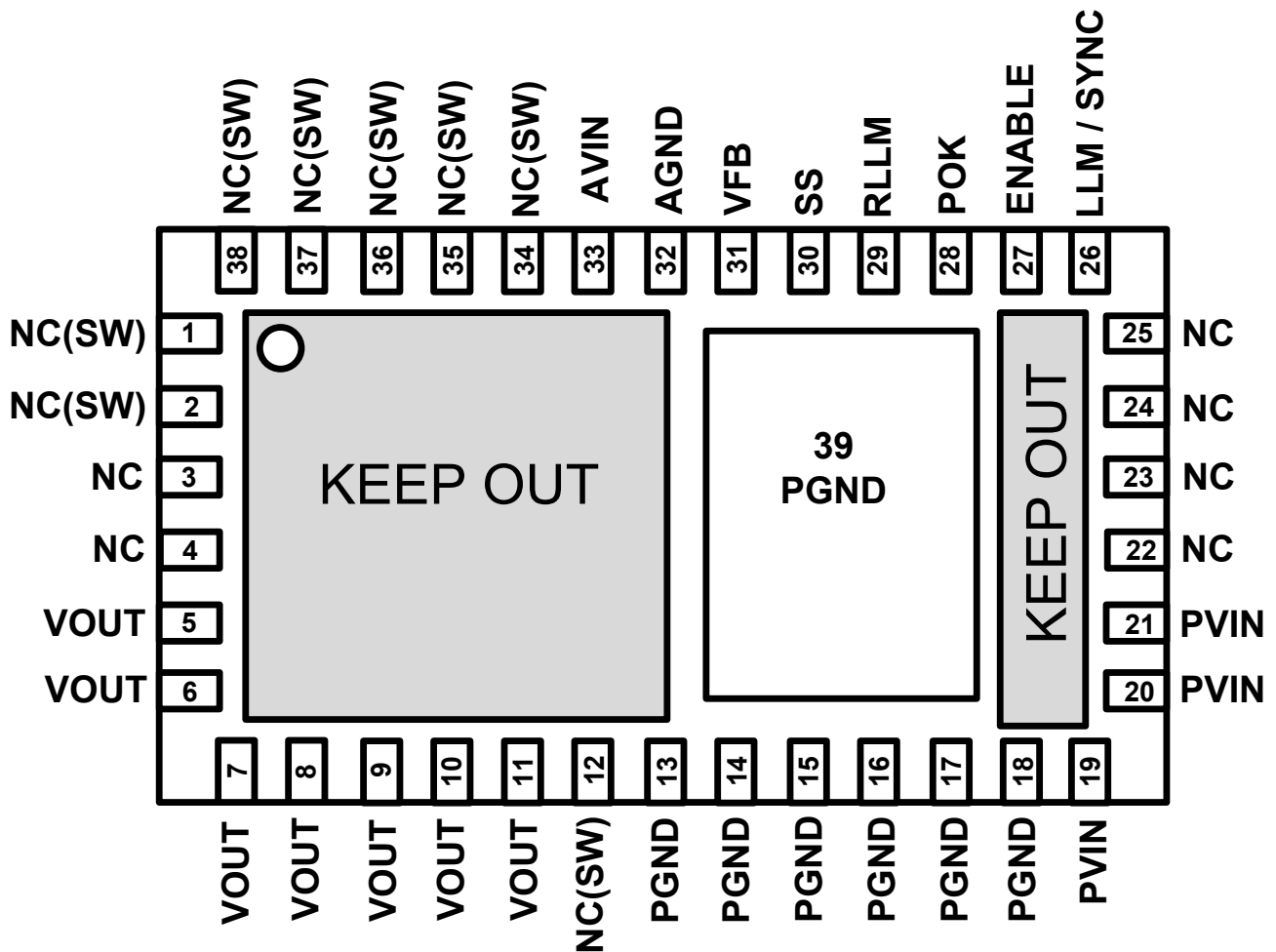


Figure 3. Pin Diagram (Top View)

**NOTE A:** NC pins are not to be electrically connected to each other or to any external signal, ground or voltage. However, they must be soldered to the PCB. Failure to follow this guideline may result in part malfunction or damage.

**NOTE B:** Shaded area highlights exposed metal below the package that is not to be mechanically or electrically connected to the PCB. Refer to Figure 11 for details.

**NOTE C:** White 'dot' on top left is pin 1 indicator on top of the device package.

## PIN DESCRIPTIONS

PIN	NAME	TYPE	FUNCTION
1,2, 12, 34-38	NC(SW)	-	NO CONNECT – These pins are internally connected to the common switching node of the internal MOSFETs. They are not to be electrically connected to any external signal, ground, or voltage. Failure to follow this guideline may result in damage to the device.
3,4, 22-25	NC	-	NO CONNECT – These pins may be internally connected. Do not connect to each other or to any other electrical signal. Failure to follow this guideline may result in device damage.
5- 11	VOUT	Power	Regulated converter output. Connect to the load and place output filter capacitor(s) between these pins and PGND pins. Refer to the <a href="#">Layout Recommendation</a> section.
13-18	PGND	Ground	Input/Output power ground. Connect to the ground electrode of the input and output filter capacitors. See VOUT and PVIN pin descriptions for more details.
19-21	PVIN	Power	Input power supply. Connect to input power supply. Decouple with input capacitor to PGND pin. Refer to the <a href="#">Layout Recommendation</a> section.
26	LLM/SYNC	Analog	Dual function pin providing LLM Enable and External Clock Synchronization (see Application Section). At static Logic HIGH, device will allow automatic engagement of light load mode. At static logic LOW, the device is forced into PWM only. A clocked input to this pin will synchronize the internal switching frequency to the external signal. If this pin is left floating, it will pull to a static logic high, enabling LLM.
27	ENABLE	Analog	Input Enable. Applying logic high enables the output and initiates a soft-start. Applying logic low discharges the output through a soft-shutdown.
28	POK	Digital	Power OK is an open drain transistor used for power system state indication. POK is logic high when VOUT is within -10% of VOUT nominal.
29	RLLM	Analog	Programmable LLM engage resistor to AGND allows for adjustment of load current at which Light-Load Mode engages. Can be left open for PWM only operation.
30	SS	Analog	A soft-start capacitor is connected between this pin and AGND. The value of the capacitor controls the soft-start interval. Refer to <a href="#">Soft-Start Operation</a> in the Functional Description section for more details.
31	VFB	Analog	External Feedback Input. The feedback loop is closed through this pin. A voltage divider at VOUT is used to set the output voltage. The midpoint of the divider is connected to VFB. A phase lead capacitor from this pin to VOUT is also required to stabilize the loop.
32	AGND	Power	Ground for internal control circuits. Connect to the power ground plane with a via right next to the pin.
33	AVIN	Power	Input power supply for the controller. Connect to input voltage at a quiet point. Refer to the <a href="#">Layout Recommendation</a> section.

PIN	NAME	TYPE	FUNCTION
39	PGND	Ground	Power ground thermal pad. Not a perimeter pin. Connect thermal pad to the system GND plane for heat-sinking purposes. Refer to the <a href="#">Layout Recommendation</a> section.

## ABSOLUTE MAXIMUM RATINGS

**CAUTION:** Absolute Maximum ratings are stress ratings only. Functional operation beyond the recommended operating conditions is not implied. Stress beyond the absolute maximum ratings may impair device life. Exposure to absolute maximum rated conditions for extended periods may affect device reliability.

### Absolute Maximum Pin Ratings

PARAMETER	SYMBOL	MIN	MAX	UNITS
PVIN, AVIN, VOUT		-0.3	7.0	V
ENABLE, POK, LLM/SYNC, PG		-0.3	V <sub>IN</sub> +0.3	V
VFB, SS, RLLM, VDDB		-0.3	2.5	V

### Absolute Maximum Thermal Ratings

PARAMETER	CONDITION	MIN	MAX	UNITS
Maximum Operating Junction Temperature			+150	°C
Storage Temperature Range		-65	+150	°C
Reflow Peak Body Temperature	(10 Sec) MSL3 JEDEC J-STD-020A		+260	°C

### Absolute Maximum ESD Ratings

PARAMETER	CONDITION	MIN	MAX	UNITS
HBM (Human Body Model)		±2000		V
CDM (Charged Device Model)		±500		V

## RECOMMENDED OPERATING CONDITIONS

PARAMETER	SYMBOL	MIN	MAX	UNITS
Input Voltage Range	$V_{IN}$	2.5	6.6	V
Output Voltage Range	$V_{OUT}$	0.75	$V_{IN} - V_{DO}^{(1)}$	V
Output Current Range	$I_{OUT}$		4	A
Operating Ambient Temperature Range	$T_A$	-40	+85	°C
Operating Junction Temperature	$T_J$	-40	+125	°C

## THERMAL CHARACTERISTICS

PARAMETER	SYMBOL	TYPICAL	UNITS
Thermal Shutdown	$T_{SD}$	160	°C
Thermal Shutdown Hysteresis	$T_{SDHYS}$	35	°C
Thermal Resistance: Junction to Ambient (0 LFM) <sup>(2)</sup>	$\theta_{JA}$	30	°C/W
Thermal Resistance: Junction to Case (0 LFM)	$\theta_{JC}$	3	°C/W

(1)  $V_{DO}$  (dropout voltage) is defined as  $(I_{LOAD} \times \text{Dropout Resistance})$ . Please refer to Electrical Characteristics Table.

(2) Based on 2oz. external copper layers and proper thermal design in line with EIJ/JEDEC JESD51-7 standard for high thermal conductivity boards.

## ELECTRICAL CHARACTERISTICS

NOTE:  $V_{IN} = 6.6V$ , Minimum and Maximum values are over operating ambient temperature range unless otherwise noted. Typical values are at  $T_A = 25^\circ C$ .

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Operating Input Voltage	$V_{IN}$		2.5		6.6	V
Under Voltage Lock-Out – $V_{IN}$ Rising	$V_{UVLOR}$	Voltage above which UVLO is not asserted		2.3		V
Under Voltage Lock-Out – $V_{IN}$ Falling	$V_{UVLOF}$	Voltage below which UVLO is asserted		2.075		V
Shut-Down Supply Current	$I_S$	ENABLE = 0V		100		$\mu A$
Operating Quiescent Current	$I_Q$	LLM/SYNC = High		650		$\mu A$
Feedback Pin Voltage <sup>(3)</sup>	$V_{FB}$	$V_{IN} = 5V, I_{LOAD} = 0, T_A = 25^\circ C$	0.7425	0.75	0.7575	V
Feedback Pin Voltage (Load, Temp.)	$V_{FB}$	$0A \leq I_{LOAD} \leq 4A$ Starting Date Code: X501 or greater	0.739	0.75	0.761	V
Feedback Pin Voltage (Line, Load, Temp.)	$V_{FB}$	$3.0V \leq V_{IN} \leq 6.0V$ $0A \leq I_{LOAD} \leq 4A$	0.735	0.75	0.765	V
Feedback pin Input Leakage Current <sup>(4)</sup>	$I_{FB}$	VFB pin input leakage current	-5		5	nA
$V_{OUT}$ Rise Time Range <sup>(4)</sup>	$t_{RISE}$	Measured from when $V_{IN} > V_{UVLOR}$ & ENABLE pin voltage crosses its logic high threshold to when $V_{OUT}$ reaches its final value. $C_{SS} = 15\text{ nF}$	0.9	1.2	1.5	ms
Soft Start Capacitance Range	$C_{SS\_RANGE}$		10	47	68	nF
Drop-Out Voltage <sup>(4)</sup>	$V_{DO}$	$V_{INMIN} - V_{OUT}$ at full load		240	360	mV
Drop-Out Resistance <sup>(4)</sup>	$R_{DO}$	Input to output resistance		60	90	$m\Omega$
Continuous Output Current	$I_{OUT}$	PMW mode LLM mode <sup>(5)</sup>	0 0.002		4 4	A
Over Current Trip Level	$I_{OCP}$	$V_{IN} = 5V, V_{OUT} = 1.2V$		5		A

PARAMETER	SYMBOL	TEST CONDITIONS	MIN	TYP	MAX	UNITS
Disable Threshold	$V_{\text{DISABLE}}$	ENABLE pin logic low	0		0.6	V
Enable Threshold	$V_{\text{EN}}$	ENABLE pin logic high $2.5\text{V} \leq V_{\text{IN}} \leq 6.6\text{V}$	1.8		$V_{\text{IN}}$	V
ENABLE Lockout Time	$T_{\text{ENLOCKOUT}}$			3.2		ms
ENABLE Pin Input Current <sup>(4)</sup>	$I_{\text{EN}}$	ENABLE pin has ~180kΩ pull down		40		μA
Switching Frequency (Free Running)	$F_{\text{SW}}$	Free running frequency of oscillator		3		MHz
External SYNC Clock Frequency Lock Range	$F_{\text{PLL\_LOCK}}$	Range of SYNC clock frequency	2.5		3.5	MHz
SYNC Input Threshold – Low (LLM/SYNC PIN)	$V_{\text{SYNC\_LO}}$	SYNC Clock Logic Level			0.8	V
SYNC Input Threshold – High (LLM/SYNC PIN) <sup>(6)</sup>	$V_{\text{SYNC\_HI}}$	SYNC Clock Logic Level	1.8		2.5	V
POK Lower Threshold	$\text{POK}_{\text{LT}}$	Output voltage as a fraction of expected output voltage		90		%
POK Low Voltage	$V_{\text{POKL}}$	With 4mA current sink into POK			0.4	V
POK High Voltage	$V_{\text{POKH}}$	$2.5\text{V} \leq V_{\text{IN}} \leq 6.6\text{V}$			$V_{\text{IN}}$	V
POK Pin Leakage Current <sup>(4)</sup>	$I_{\text{POKH}}$	POK is high			1	μA
LLM Engage Headroom		Minimum $V_{\text{IN}}-V_{\text{OUT}}$ to ensure proper LLM operation		800		mV
LLM Logic Low (LLM/SYNC PIN)	$V_{\text{LLM\_LO}}$	LLM Static Logic Level			0.3	V
LLM Logic High (LLM/SYNC PIN)	$V_{\text{LLM\_HI}}$	LLM Static Logic Level	1.5			V
LLM/SYNC Pin Current		LLM/SYNC Pin is <2.5V		<100		nA

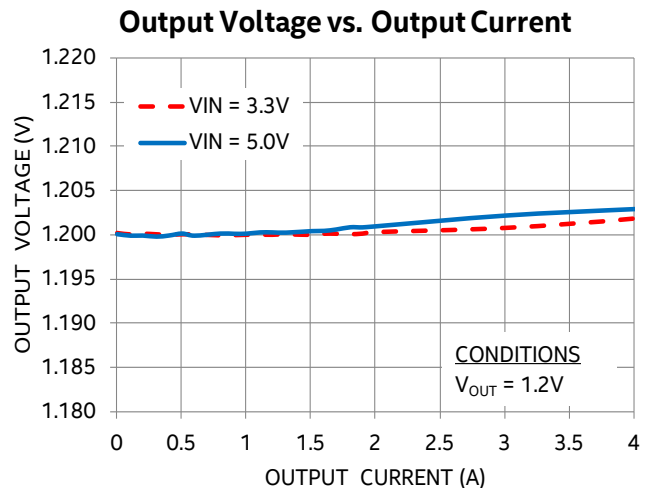
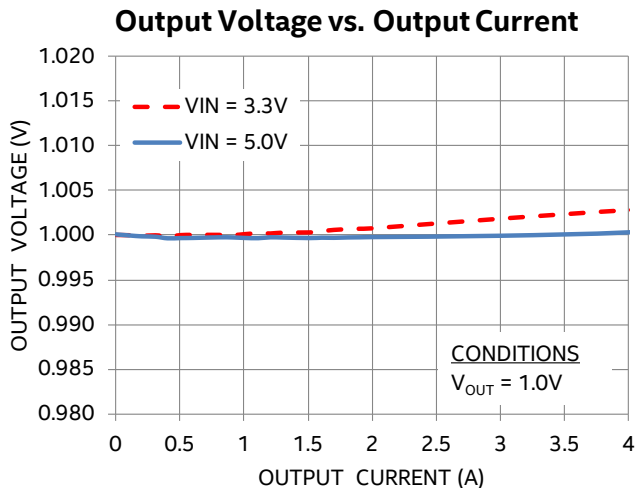
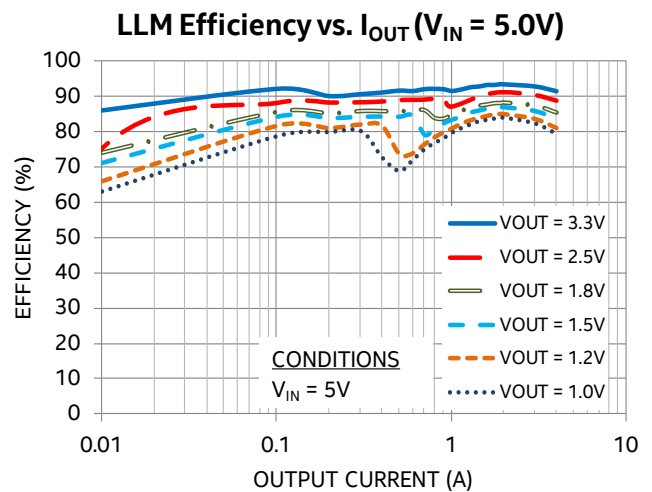
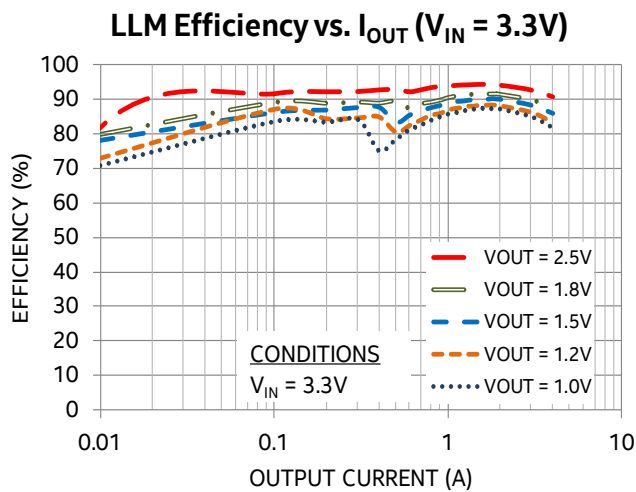
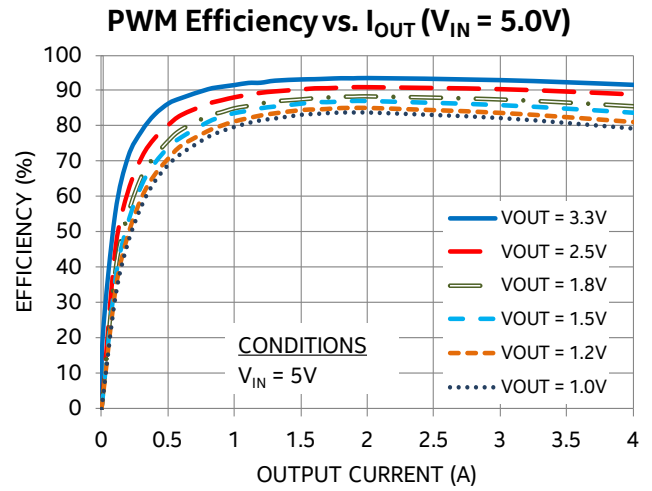
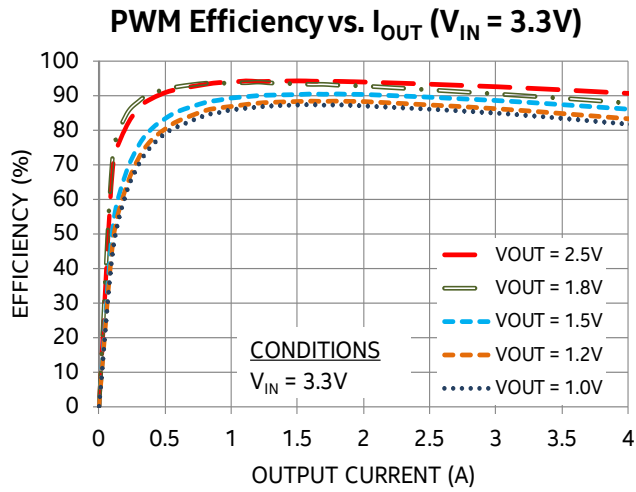
(3) The VFB pin is a sensitive node. Do not touch VFB while the device is in regulation.

(4) Parameter not production tested but is guaranteed by design.

(5) LLM operation is normally only guaranteed above the minimum specified output current.

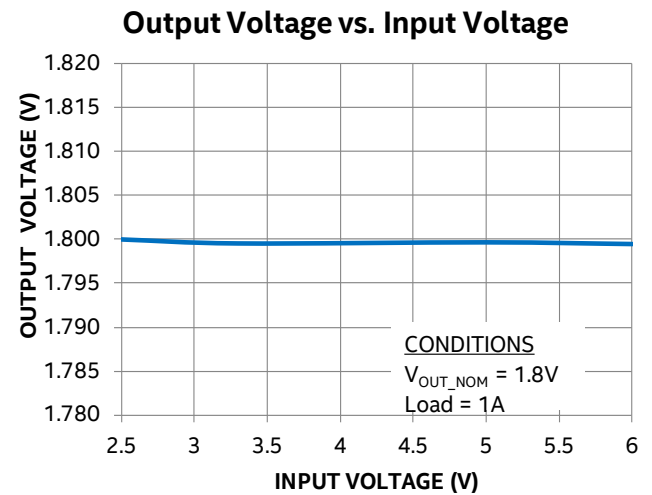
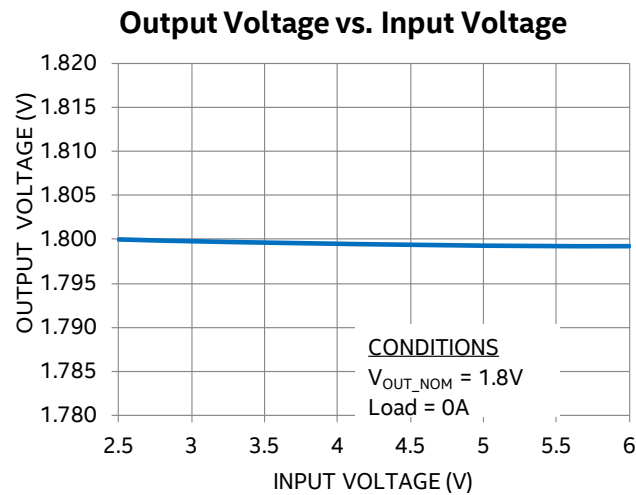
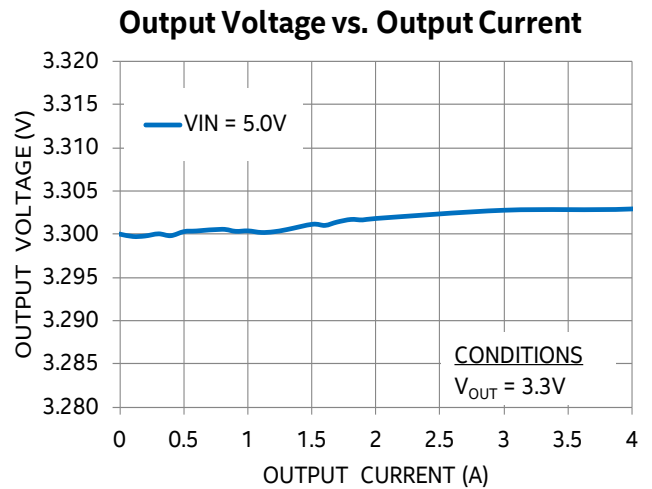
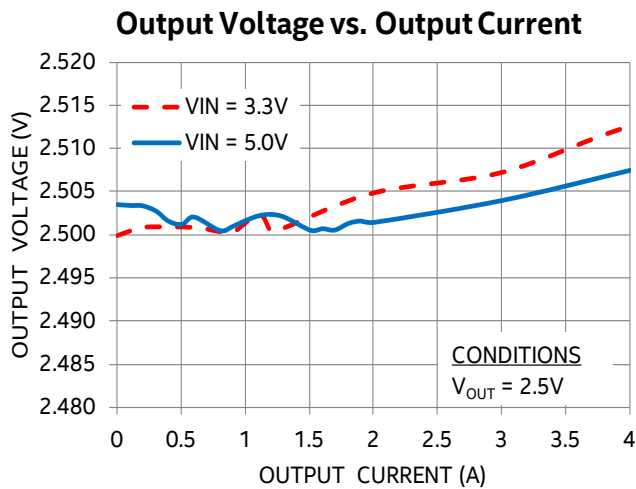
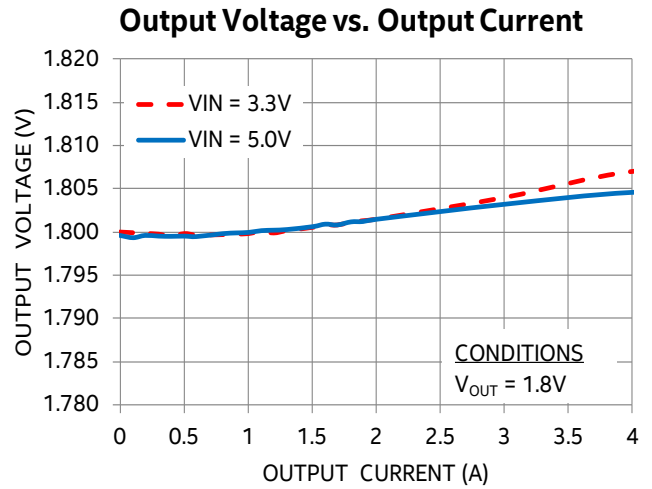
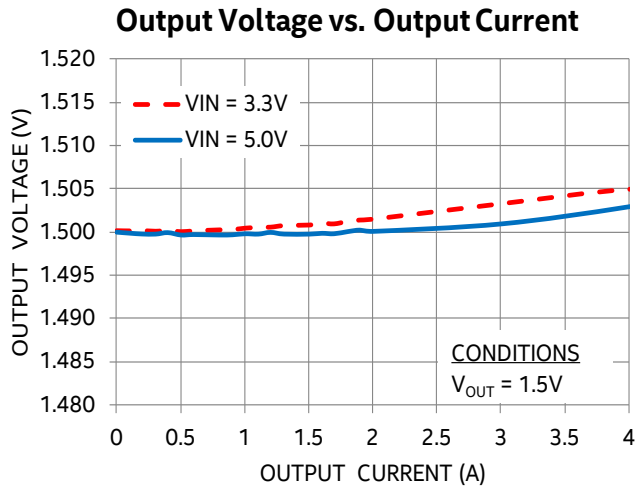
(6) For proper operation of the synchronization circuit, the high-level amplitude of the SYNC signal should not be above 2.5V.

## TYPICAL PERFORMANCE CURVES



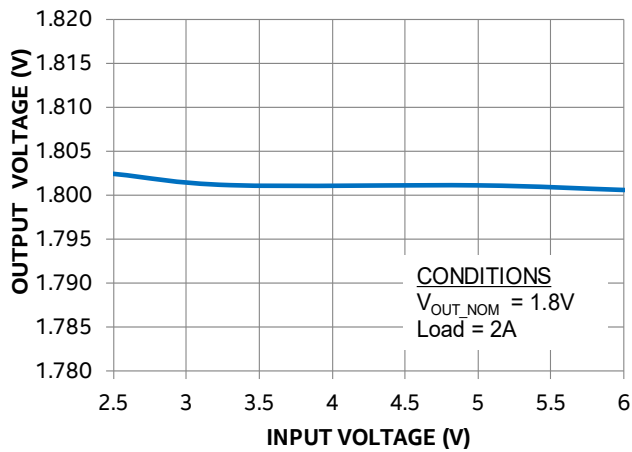


## TYPICAL PERFORMANCE CURVES (CONTINUED)

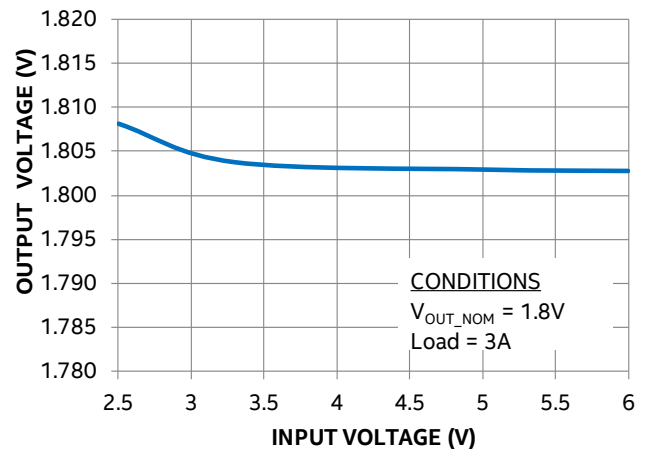


## TYPICAL PERFORMANCE CURVES (CONTINUED)

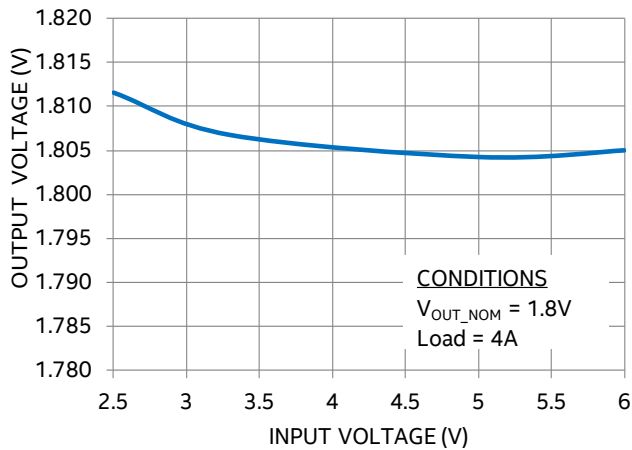
**Output Voltage vs. Input Voltage**



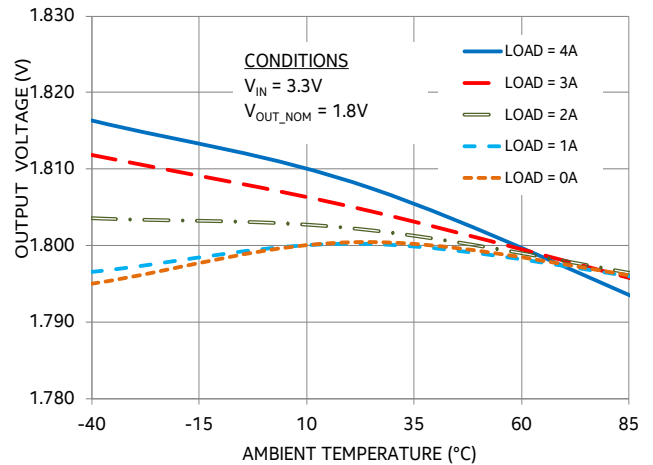
**Output Voltage vs. Input Voltage**



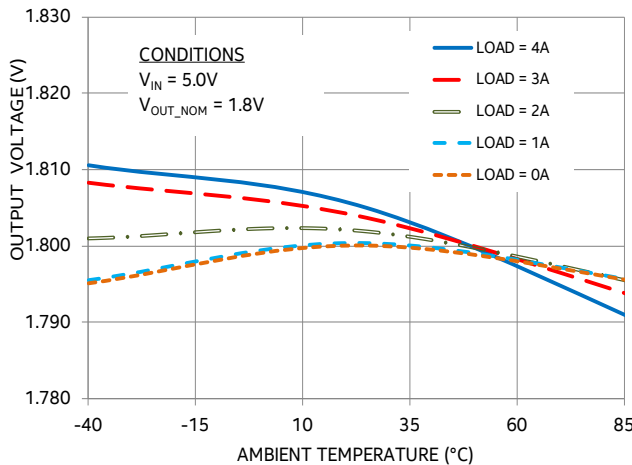
**Output Voltage vs. Input Voltage**



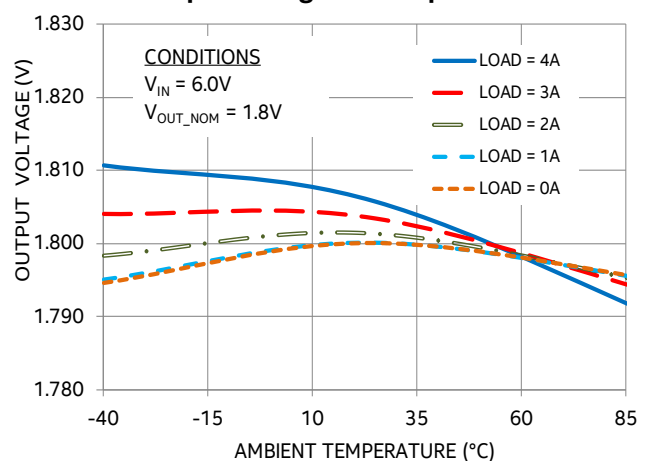
**Output Voltage vs. Temperature**



**Output Voltage vs. Temperature**

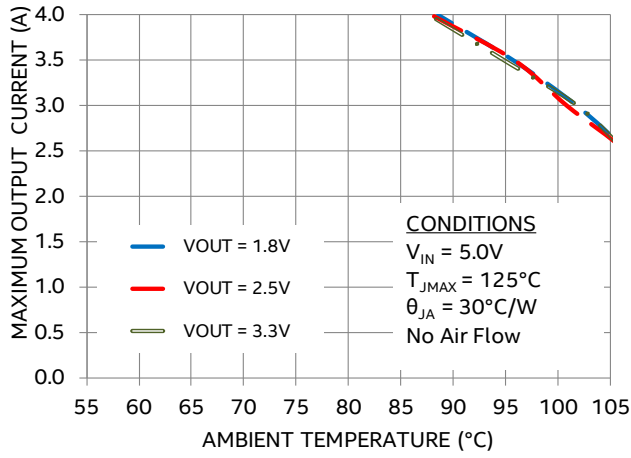


**Output Voltage vs. Temperature**

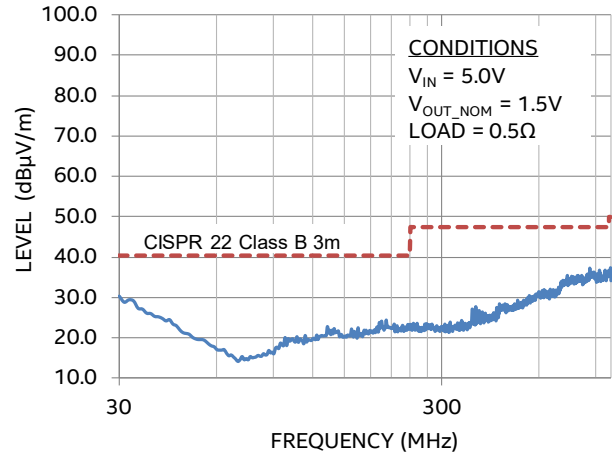


## TYPICAL PERFORMANCE CHARACTERISTICS

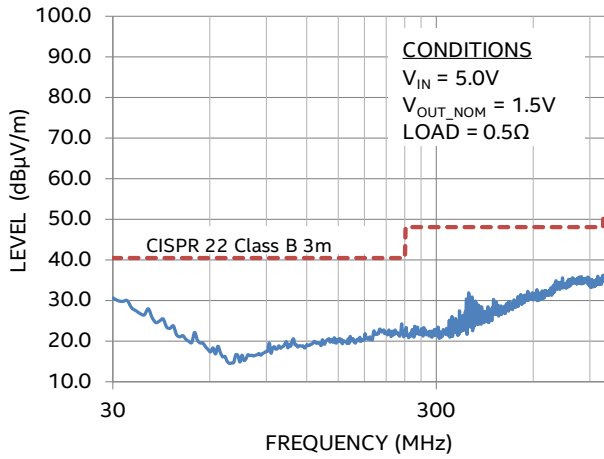
### Output Current De-rating



### EMI Performance (Horizontal Scan)

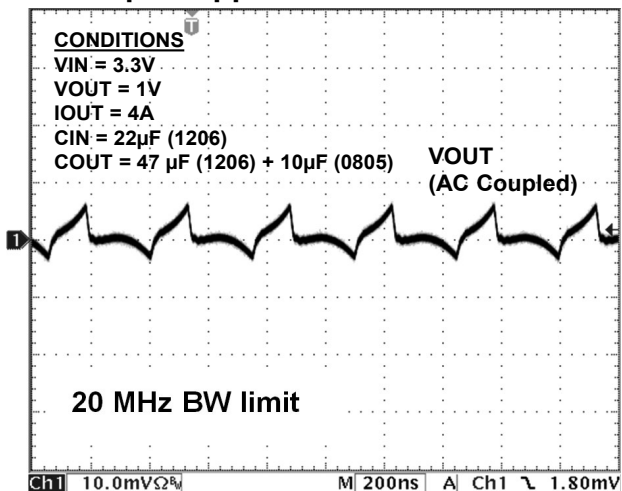


### EMI Performance (Vertical Scan)

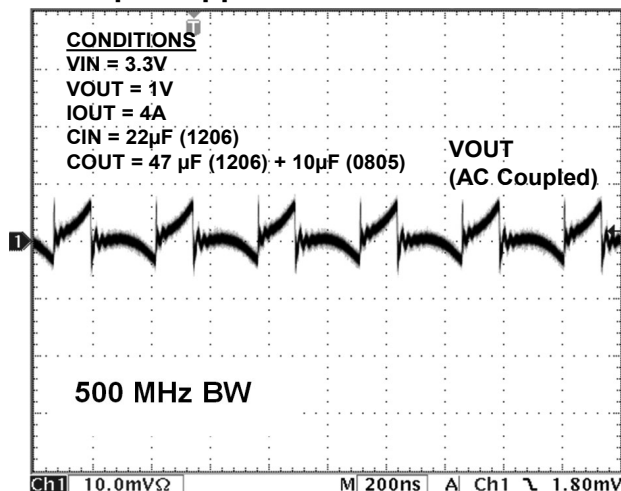


## TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

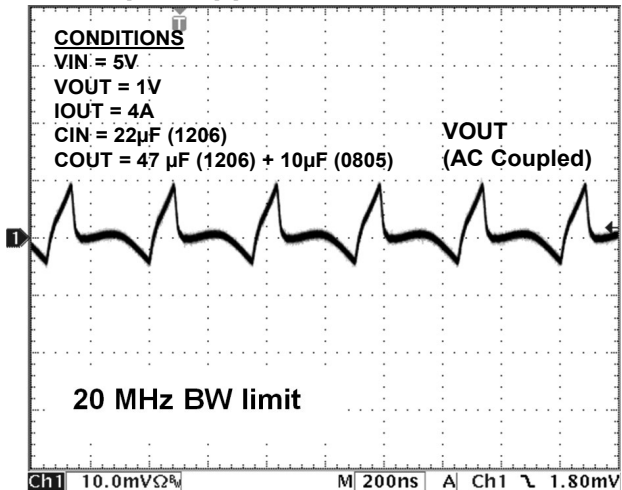
Output Ripple at 20MHz Bandwidth



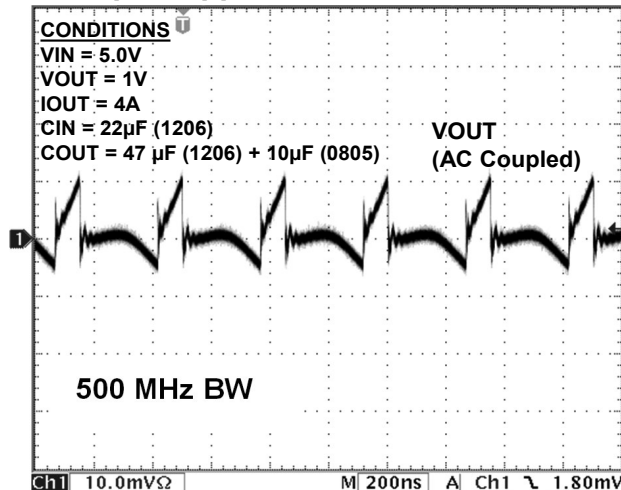
Output Ripple at 500MHz Bandwidth



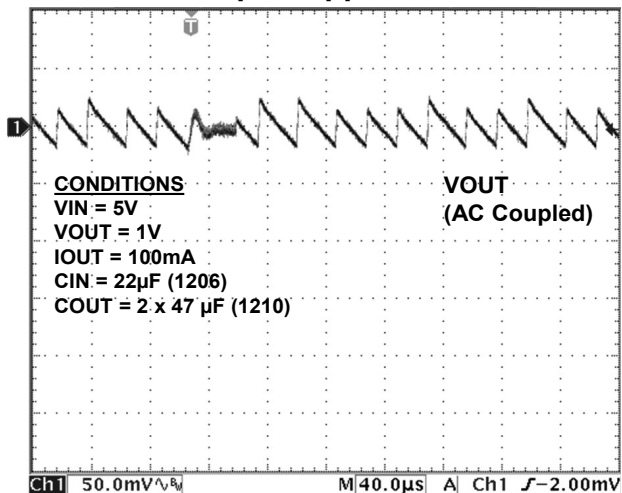
Output Ripple at 20MHz Bandwidth



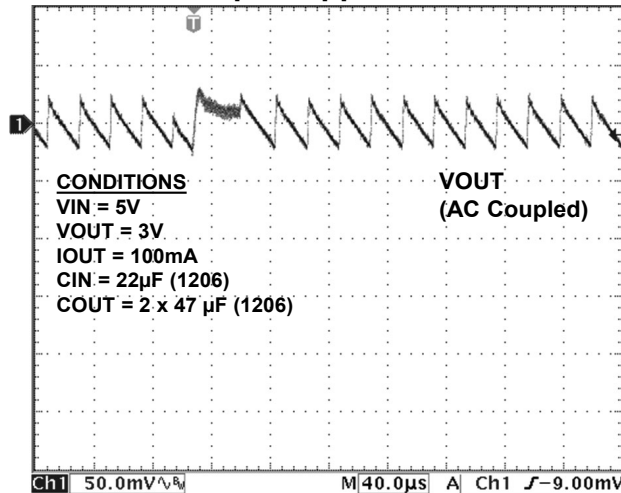
Output Ripple at 500MHz Bandwidth



LLM Output Ripple at 100mA

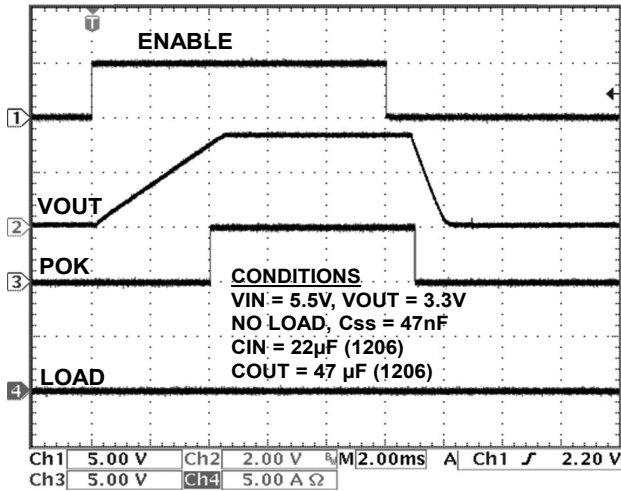


LLM Output Ripple at 100mA

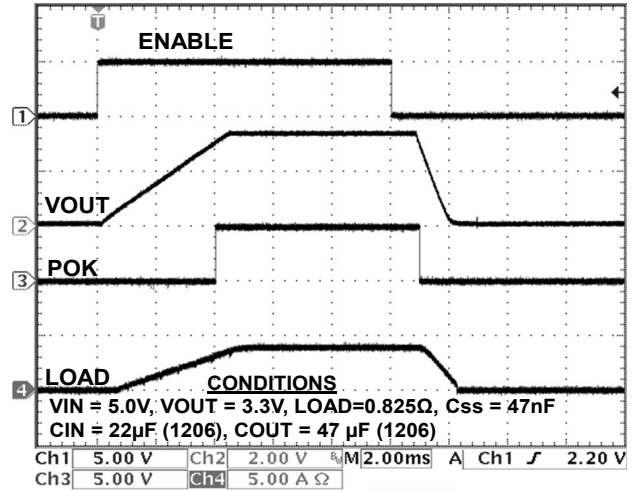


## TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

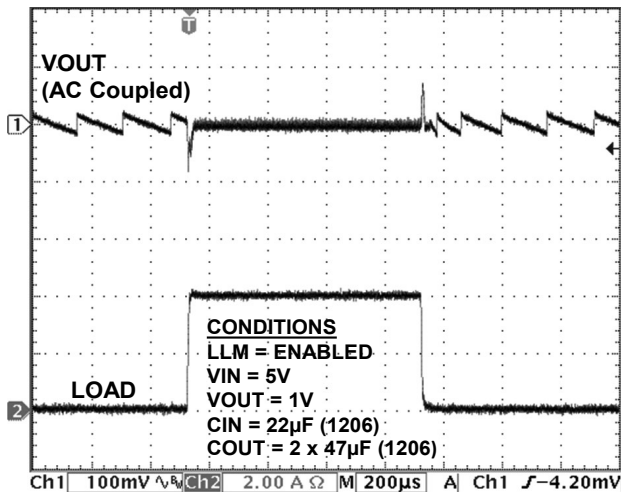
Enable Power Up/Down



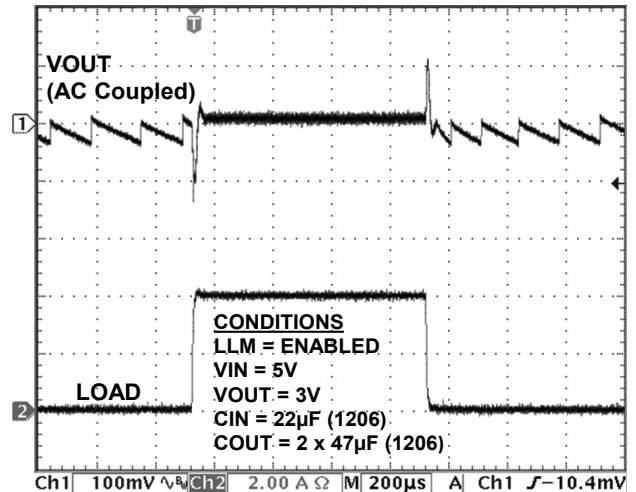
Enable Power Up/Down



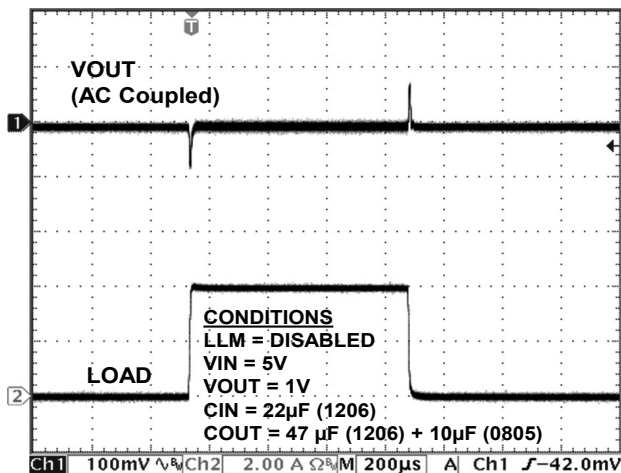
LLM Load Transient from 0.01 to 4A



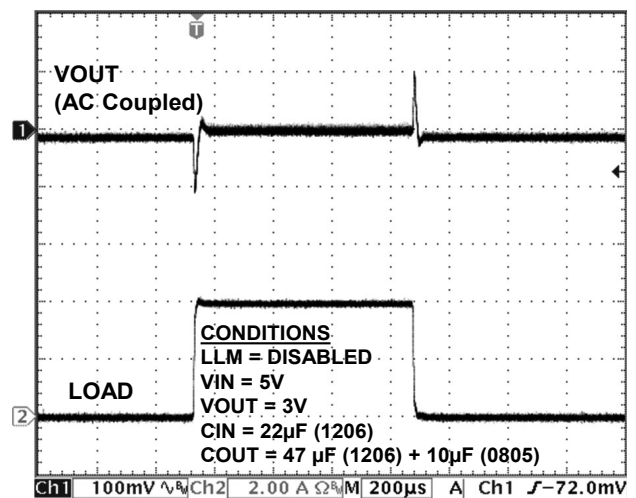
LLM Load Transient from 0.01 to 4A



PWM Load Transient from 0 to 4A



PWM Load Transient from 0 to 4A





### Protection Features:

The power supply has the following protection features:

- Over-current protection (to protect the IC from excessive load current)
- Thermal shutdown with hysteresis.
- Under-voltage lockout circuit to keep the converter output off while the input voltage is less than 2.3V.

### Additional Features:

- The switching frequency can be phase-locked to an external clock to eliminate or move beat frequency tones out of band.
- Soft-start circuit allowing controlled startup when the converter is initially powered up. The soft start time is programmable with an appropriate choice of soft start capacitor.
- Power good circuit indicating the output voltage is greater than 90% of programmed value as long as feedback loop is closed.
- To maintain high efficiency at low output current, the device incorporates automatic light load mode operation.

### Precision Enable Operation

The ENABLE pin provides a means to enable normal operation or to shut down the device. When the ENABLE pin is asserted (high) the device will undergo a normal soft-start. A logic low on this pin will power the device down in a controlled manner. From the moment ENABLE goes low, there is a fixed lock out time before the output will respond to the ENABLE pin re-asserted (high). This lock out is activated for even very short logic low pulses on the ENABLE pin. The ENABLE signal must be pulled high at a slew rate faster than  $1V/5\mu s$  in order to meet startup time specifications; otherwise, the device may experience a delay of 4.2ms (lock-out time) before startup occurs. See the [Electrical Characteristics Table](#) for technical specifications for this pin. See the [Electrical Characteristics Table](#) for technical specifications for the ENABLE pin.

### LLM/SYNC Pin

This is a dual function pin providing LLM Enable and External Clock Synchronization. At static Logic HIGH, device will allow automatic engagement of light load mode. At static logic LOW, the device is forced into PWM only. A clocked input to this pin will synchronize the internal switching frequency – LLM mode is not available if this input is clocked. If this pin is left floating, it will pull to a static logic high, enabling LLM.

### Frequency Synchronization

The switching frequency of the DC-DC converter can be phase-locked to an external clock source to move unwanted beat frequencies out of band. To avail this feature, the clock source should be connected to the LLM/SYNC pin. An activity detector recognizes the presence of an external clock signal and automatically phase-locks the internal oscillator to this external clock. Phase-lock will occur as long as the clock frequency is in the range specified in the Electrical Characteristics Table. For proper operation of the synchronization circuit, the high-level amplitude of the SYNC signal should not be above 2.5V. Please note LLM is not available when synchronizing to an external frequency.

## Spread Spectrum Mode

The external clock frequency may be swept between the limits specified in the Electrical Characteristics Table at repetition rates of up to 10kHz in order to reduce EMI frequency components.

## Soft-Start Operation

During Soft-start, the output voltage is ramped up gradually upon start-up. The output rise time is controlled by the choice of soft-start capacitor, which is placed between the SS pin (30) and the AGND pin (32).

$$\text{Rise Time: } T_R \approx (C_{SS} * 80k\Omega) \pm 25\%$$

During start-up of the converter, the reference voltage to the error amplifier is linearly increased to its final level by an internal current source of approximately 10 $\mu$ A. Typical soft-start rise time is ~3.8ms with SS capacitor value of 47nF. The rise time is measured from when  $V_{IN} > V_{UVLOR}$  and ENABLE pin voltage crosses its logic high threshold to when  $V_{OUT}$  reaches its programmed value. Please note LLM function is disabled during the soft-start ramp-up time.

## POK Operation

The POK signal is an open drain signal (requires a pull up resistor to  $V_{IN}$  or similar voltage) from the converter indicating the output voltage is within the specified range. The POK signal will be logic high ( $V_{IN}$ ) when the output voltage is above 90% of programmed  $V_{OUT}$ . If the output voltage goes below this threshold, the POK signal will be logic low.

## Light Load Mode (LLM) Operation

The EN6347QI uses a proprietary light load mode to provide high efficiency at low output currents. When the LLM/SYNC pin is high, the device is in automatic LLM “Detection” mode. When the LLM/SYNC pin is low, the device is forced into PWM mode. In automatic LLM “Detection” mode (LLM connected to AVIN with 50k $\Omega$ ), when a light load condition is detected, the device will:

- (1) Step  $V_{OUT}$  up by approximately 1.0% above the nominal operating output voltage setting,  $V_{NOM}$  and as low as -0.5% below  $V_{NOM}$ , and then
- (2) Shut down unnecessary circuitry, and then
- (3) Monitor  $V_{OUT}$ .

When  $V_{OUT}$  falls below  $V_{NOM}$ , the device will repeat (1), (2), and (3). The voltage step up, or pre-positioning, improves transient droop when a load transient causes a transition from LLM mode to PWM mode. If a load transient occurs, causing  $V_{OUT}$  to fall below the threshold  $V_{MIN}$ , the device will exit LLM operation and begin normal PWM operation. Figure 5 demonstrates  $V_{OUT}$  behavior during transition into and out of LLM operation. Many multi-mode DC-DC converters suffer from a condition that occurs when the load current increases only slowly so that there is no load transient driving  $V_{OUT}$  below the  $V_{MIN}$  threshold. In this condition, the device would never exit LLM operation. This could adversely affect efficiency and cause unwanted ripple. To prevent this from occurring, the EN6347QI periodically exits LLM mode into PWM mode and measures the load current. If the load current is above the LLM threshold current, the device will remain in PWM mode. If the load current is below the LLM threshold, the device will re-enter LLM operation. There may be a small overshoot or undershoot in  $V_{OUT}$  when the device exits and re-enters LLM.



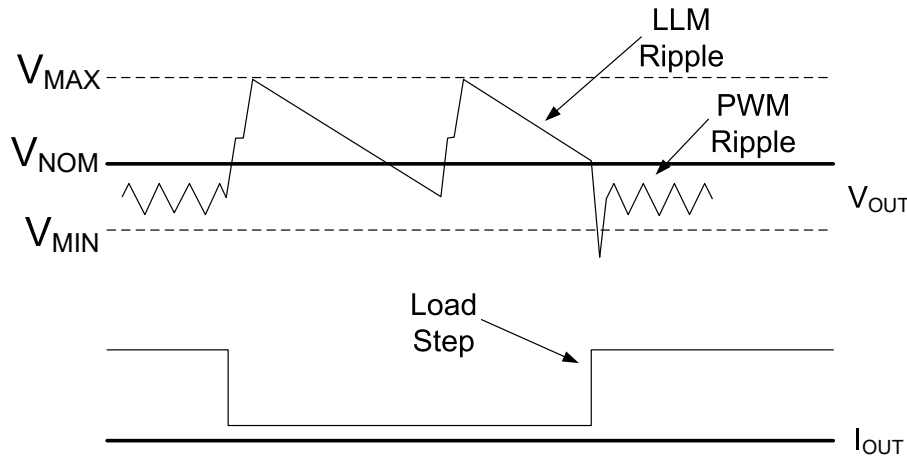


Figure 5. VOUT behavior in LLM operation

The load current at which the device will enter LLM mode is a function of input and output voltage, inductance variation and the RLLM pin resistor. The lower the RLLM resistor value, the lower the current when the device transitions from LLM into PWM mode. A 60kΩ resistor from RLLM to ground is recommended for most applications. For PWM only operation, the RLLM pin can be left open.

### LLM to PWM Current vs. RLLM

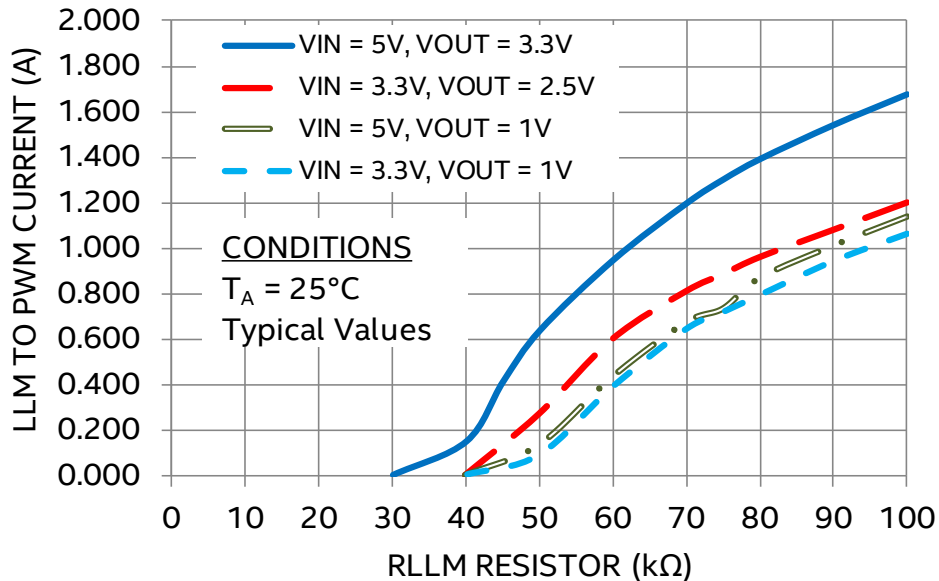


Figure 6. Typical LLM to PWM Current vs. RLLM

To ensure normal LLM operation, LLM mode should be enabled and disabled with specific sequencing. For applications with explicit LLM pin control, enable LLM after  $V_{IN}$  ramp up is complete. For applications with only ENABLE controlled, tie LLM to ENABLE. Enable the device after  $V_{IN}$  ramps up into regulation and disable the device before  $V_{IN}$  ramps. For designs with ENABLE and LLM tied to  $V_{IN}$ , make sure the device soft-start time is longer than the  $V_{IN}$  ramp-up time. LLM will start operating after the soft-start time is completed.

**NOTE:** For proper LLM operation the EN6347QI requires a minimum difference between  $V_{IN}$  and  $V_{OUT}$ , and a minimum LLM load requirement as specified in the [Electrical Characteristics Table](#).

## Over-Current Protection (OCP)

The current limit function is achieved by sensing the current flowing through the Power PFET. When the sensed current exceeds the over current trip point, both power FETs are turned off for the remainder of the switching cycle. If the over-current condition is removed, the over-current protection circuit will enable normal PWM operation. If the over-current condition persists, the soft start capacitor will gradually discharge causing the output voltage to fall. When the OCP fault is removed, the output voltage will ramp back up to the desired voltage. This circuit is designed to provide high noise immunity.

## Thermal Protection

Thermal shutdown circuit will disable device operation when the Junction temperature exceeds the thermal shutdown temperature. After a thermal shutdown event, when the junction temperature drops to a safe operating level, the converter will re-start with a normal soft-start. The specific thermal shutdown junction temperature and hysteresis can be found in the [Thermal Characteristics Table](#).

## Input Under-Voltage Lock-Out (UVLO)

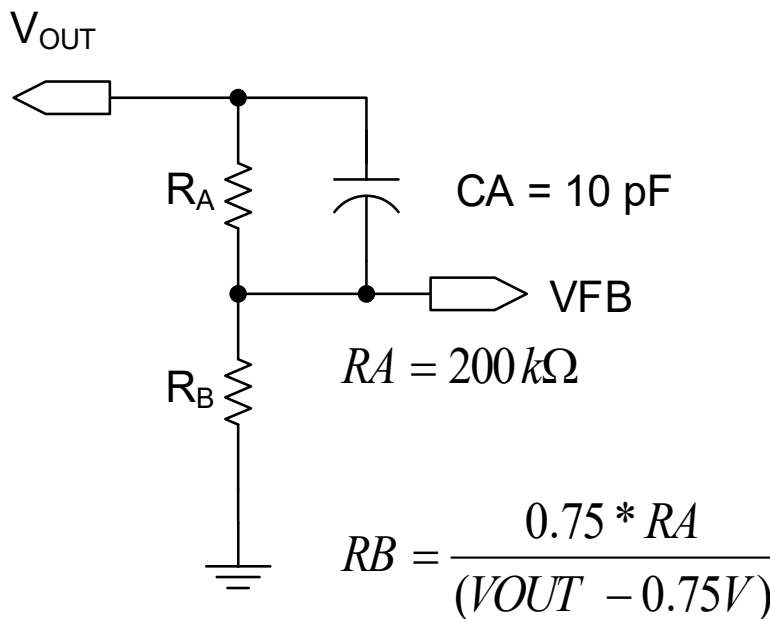
Internal circuits ensure that the converter will not start switching until the input voltage is above the specified minimum voltage. Hysteresis and input de-glitch circuits ensure high noise immunity and prevent false UVLO triggers.

## APPLICATION INFORMATION

### Output Voltage Setting

The EN6347QI uses a Type III voltage mode control compensation network. As noted earlier, a piece of the compensation network is the phase lead capacitor  $C_A$  equal 10pF in Figure 7. This network is optimized for use with about 50-100 $\mu$ F.

The EN6347QI output voltage is programmed using a simple resistor divider network. Since VFB is a sensitive node, do not touch the VFB node while the device is in operation as doing so may introduce parasitic capacitance into the control loop that causes the device to behave abnormally and damage may occur Figure 7 shows the resistor divider configuration. An additional compensation capacitor  $C_A$  is also required in parallel with the upper resistor.



**Figure 7. VOUT Resistor Divider & Compensation Capacitor**

The EN6347QI output voltage is programmed using a simple resistor divider network ( $R_A$  and  $R_B$ ). Figure 7 shows the resistor divider configuration.

The recommended  $R_A$  resistor value is 200k $\Omega$  and the feedback voltage is typically 0.75V. Depending on the output voltage ( $V_{OUT}$ ), the  $R_B$  resistor value may be calculated as shown in Figure 7. Since the accuracy of the output voltage setting is dependent upon the feedback voltage and the external resistors, 1% or better resistors are recommended. The external compensation capacitor ( $C_A$ ) is also required in parallel with  $R_A$ , depending on input voltage and output voltage setting.

**Table 1. Best Performance Solution**

$C_{OUT}= 47\mu\text{F } 1206, C_{IN}= 22\mu\text{F } (10\text{V},1206), R_A= 200\text{k}\Omega$

$V_{OUT}$	$V_{IN}$	$C_A$
3.3V	6.6V	18pF
	$\leq 5.0\text{V}$	22pF
2.5V	6.6V	22pF
	$\leq 5.0\text{V}$	33pF
1.8V	6.6V	27pF
	5.0V	33pF
	3.3V	39pF
	2.5V	47pF
1.5V	6.6V	27pF
	5.0V	33pF
	$\leq 3.3\text{V}$	47pF
$\leq 1.2\text{V}$	6.6V	27pF
	5.0V	39pF
	$\leq 3.3\text{V}$	47pF

**Table 2. Small Footprint Solution**

$C_{OUT}= 47\mu\text{F } (1206), C_{IN}= 22\mu\text{F } (10\text{V},1206), R_A= 200\text{k}\Omega$

$V_{OUT}$	$V_{IN}$	$C_A$
3.3V	ALL $V_{IN}$	10pF
2.5V	$> 5.0\text{V}$	12pF
	$\leq 5.0\text{V}$	15pF
1.8V	6.6V	12pF
	5.0V	15pF
	3.3V	22pF
	2.5V	27pF
1.5V	$> 3.3\text{V}$	15pF
	$\leq 3.3\text{V}$	27pF
$\leq 1.2\text{V}$	6.6V	15pF
	5.0V	18pF
	$\leq 3.3\text{V}$	27pF

### Input Capacitor Selection

The EN6347QI requires at least a 22µF X5R/X7R ceramic input capacitor. Additional input capacitors may be used in parallel to reduce input voltage spikes caused by parasitic line inductance. For applications where the input of the EN6347QI is far from the input power source, be sure to use sufficient bulk capacitors to mitigate the extra line inductance. Low-cost, low-ESR ceramic capacitors should be used as input capacitors for this converter. The dielectric must be X5R/X7R rated. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage. In some applications, lower value capacitors are needed in parallel with the larger, capacitors in order to provide high frequency decoupling.

**Table 3. Recommended Input Capacitors**

Description	MFG	P/N
22µF, 10V, X7R, 1206	Murata	GRM31CR71A226ME15
	Taiyo Yuden	LMK316AB7226KL-TR
	AVX	1206ZC226KAT2A
22µF, 10V, X5R, 1206	Murata	GRM31CR61A226ME19L
	Taiyo Yuden	LMK316BJ226ML-T
22µF, 16V, X5R, 0805	Murata	GRM21BR61C226ME44L
	Taiyo Yuden	EMK212BBJ226MG-T

### Output Capacitor Selection

The EN6347QI requires at least one 22µF 0805 case size ceramic output capacitor. Additional output capacitors may be used in parallel near the load (>4mΩ away) to improve transient response as well as lower output ripple. In some cases modifications to the compensation or output filter capacitance may be required to optimize device performance such as transient response, ripple, or hold-up time. The EN6347QI provides the capability to modify the control loop response to allow for customization for such applications. Note that in Type III Voltage Mode Control, the double pole of the output filter is around  $1/2\pi\sqrt{L_O \cdot C_{out}}$ , where  $C_{out}$  is the equivalent capacitance of all the output capacitors including the minimum required output capacitors that Altera recommended and the extra bulk capacitors customers added based on their design requirement. While the compensation network was designed based on the capacitors that Altera recommended, increasing the output capacitance will shift the double pole to the direction of lower frequency, which will lower the loop bandwidth and phase margin. In most cases, this will not cause the instability due to adequate phase margin already in the design. In order to maintain a higher bandwidth as well as adequate phase margin, a slight modification of the external compensation is necessary. This can be easily implemented by increasing the leading capacitor value,  $C_A$ . In addition the ESR of the output capacitors also helps since the ESR and output capacitance forms a zero which also helps to boost the phase.

**Table 4.  $C_A$  and Minimum ESR for Output Capacitors Ranges**

Total $C_{OUT}$ Range	Recommended $C_A$	Min ESR
100µF to 250µF	27pF	0
250µF to 450µF	33pF	0
450µF to 1000µF	47pF	>4mΩ

**Table 5. Recommended Output Capacitors**

Description	MFG	P/N
47µF, 6.3V, X7R, 1210	Murata	GRM32ER70J476ME20
	Taiyo Yuden	LMK325B7476KM-TR
47µF, 6.3V, X5R, 1206	Murata	GRM31CR60J476ME19L
	Taiyo Yuden	JMK316BJ476ML-T
22µF, 10V, X7R, 1206	Murata	GRM31CR71A226ME15
	Taiyo Yuden	LMK316AB7226KL-TR
	AVX	1206ZC226KAT2A
22 µF, 10V, X5R, 1206	Murata	GRM31CR61A226ME19L
	Taiyo Yuden	LMK316BJ226ML-T
22 µF, 10V, X5R, 0805	Murata	GRM219R61A226MEA0D
	Taiyo Yuden	LMK212BJ226MG-T
10µF, 10V, X7R, 0805	Murata	GRM21BR71A106KE51
	Taiyo Yuden	LMK212AB7106MG-T
	AVX	0805ZC106KAT2A

Low ESR ceramic capacitors are required with X5R/X7R rated dielectric formulation. Y5V or equivalent dielectric formulations must not be used as these lose too much capacitance with frequency, temperature and bias voltage.

Output ripple voltage is determined by the aggregate output capacitor impedance. Output impedance, denoted as Z, is comprised of effective series resistance, ESR, and effective series inductance, ESL:

$$Z = ESR + ESL$$

Placing output capacitors in parallel reduces the impedance and will hence result in lower PWM ripple voltage. In addition, higher output capacitance will improve overall regulation and ripple in light-load mode.

$$\frac{1}{Z_{Total}} = \frac{1}{Z_1} + \frac{1}{Z_2} + \dots + \frac{1}{Z_n}$$

For best LLM performance, we recommend using just 2x47µF capacitors mentioned in the above table, and no 10µF capacitor.

The V<sub>OUT</sub> sense point should be just after the last output filter capacitor right next to the device. Additional bulk output capacitance beyond the above recommendations can be used on the output node of the EN6347QI as long as the bulk capacitors are far enough from the V<sub>OUT</sub> sense point such that they don't interfere with the control loop operation.

**Table 6. Typical PWM Ripple Voltages**

Output Capacitor Configuration	Typical Output Ripple (mVp-p) (as measured on EN6347QI Evaluation Board)*
1 x 47 $\mu$ F	25
47 $\mu$ F + 10 $\mu$ F	14

\* Note: 20 MHz BW limit

### Power-Up Sequencing

During power-up, ENABLE should not be asserted before PVIN, and PVIN should not be asserted before AVIN. AVIN. Tying all three pins together meets these requirements.

## THERMAL CONSIDERATIONS

Thermal considerations are important power supply design facts that cannot be avoided in the real world. Whenever there are power losses in a system, the heat that is generated by the power dissipation needs to be accounted for. The Enpirion PowerSoC helps alleviate some of those concerns.

The Enpirion EN6347QI DC-DC converter is packaged in a 4x7x1.85mm 38-pin QFN package. The QFN package is constructed with copper lead frames that have exposed thermal pads. The exposed thermal pad on the package should be soldered directly on to a copper ground pad on the printed circuit board (PCB) to act as a heat sink. The recommended maximum junction temperature for continuous operation is 125°C. Continuous operation above 125°C may reduce long-term reliability. The device has a thermal overload protection circuit designed to turn off the device at an approximate junction temperature value of 160°C.

The following example and calculations illustrate the thermal performance of the EN6347QI.

Example:

$$V_{IN} = 5V$$

$$V_{OUT} = 3.3V$$

$$I_{OUT} = 4A$$

First calculate the output power.

$$P_{OUT} = 3.3V \times 4A = 13.2W$$

Next, determine the input power based on the efficiency ( $\eta$ ) shown in Figure 8.

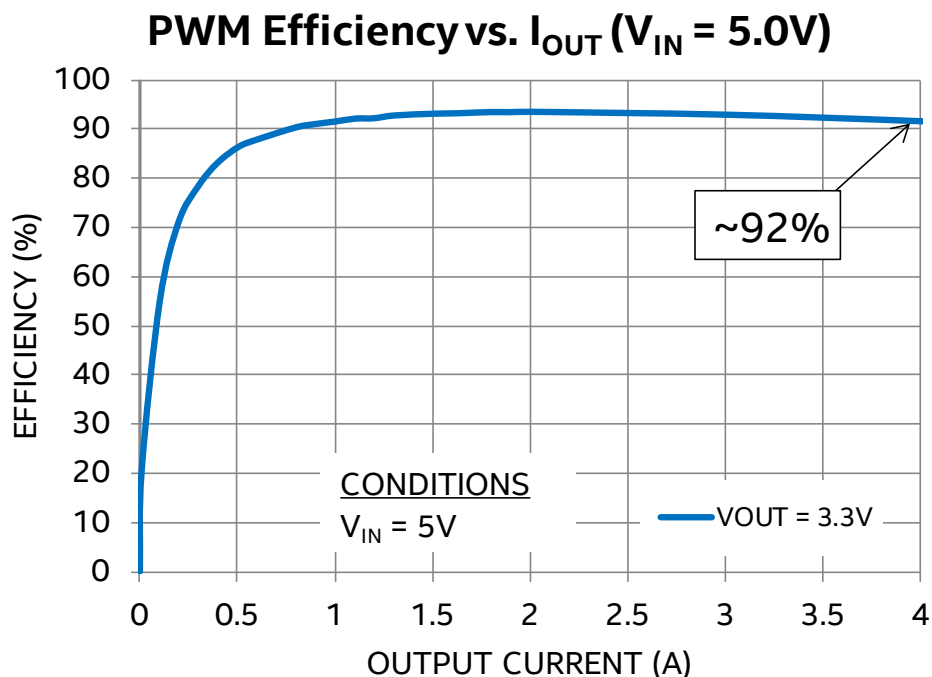


Figure 8. Efficiency vs. Output Current



For  $V_{IN} = 5V$ ,  $V_{OUT} = 3.3V$  at  $4A$ ,  $\eta \approx 92\%$

$$\eta = P_{OUT} / P_{IN} = 92\% = 0.92$$

$$P_{IN} = P_{OUT} / \eta$$

$$P_{IN} \approx 13.2W / 0.92 \approx 14.35W$$

The power dissipation ( $P_D$ ) is the power loss in the system and can be calculated by subtracting the output power from the input power.

$$P_D = P_{IN} - P_{OUT}$$

$$\approx 14.35W - 13.2W \approx 1.148W$$

With the power dissipation known, the temperature rise in the device may be estimated based on the theta JA value ( $\theta_{JA}$ ). The  $\theta_{JA}$  parameter estimates how much the temperature will rise in the device for every watt of power dissipation. The EN6347QI has a  $\theta_{JA}$  value of  $30\text{ }^\circ\text{C/W}$  without airflow.

Determine the change in temperature ( $\Delta T$ ) based on  $P_D$  and  $\theta_{JA}$ .

$$\Delta T = P_D \times \theta_{JA}$$

$$\Delta T \approx 1.148W \times 30^\circ\text{C/W} = 34.43^\circ\text{C} \approx 35^\circ\text{C}$$

The junction temperature ( $T_J$ ) of the device is approximately the ambient temperature ( $T_A$ ) plus the change in temperature. We assume the initial ambient temperature to be  $25^\circ\text{C}$ .

$$T_J = T_A + \Delta T$$

$$T_J \approx 25^\circ\text{C} + 35^\circ\text{C} \approx 60^\circ\text{C}$$

The maximum operating junction temperature ( $T_{JMAX}$ ) of the device is  $125^\circ\text{C}$ , so the device can operate at a higher ambient temperature. The maximum ambient temperature ( $T_{AMAX}$ ) allowed can be calculated.

$$T_{AMAX} = T_{JMAX} - P_D \times \theta_{JA}$$

$$\approx 125^\circ\text{C} - 35^\circ\text{C} \approx 90^\circ\text{C}$$

The maximum ambient temperature (before de-rating) the device can reach is  $90^\circ\text{C}$  given the input and output conditions. Note that the efficiency will be slightly lower at higher temperatures and this calculation is an estimate.

## APPLICATION CIRCUITS

A single through-hole test point connects the AGND pin to the GND plane.

For a PWM application RLLM pin can float, and LLM/SYNC has to be tied to GND.

Enable can also be driven with an external logic signal depending on the application

Depending on the output accuracy requirements, these three components' footprints may have to be larger than 0402.

See the datasheet for choosing the proper value for Ra, Rb, and Ca.

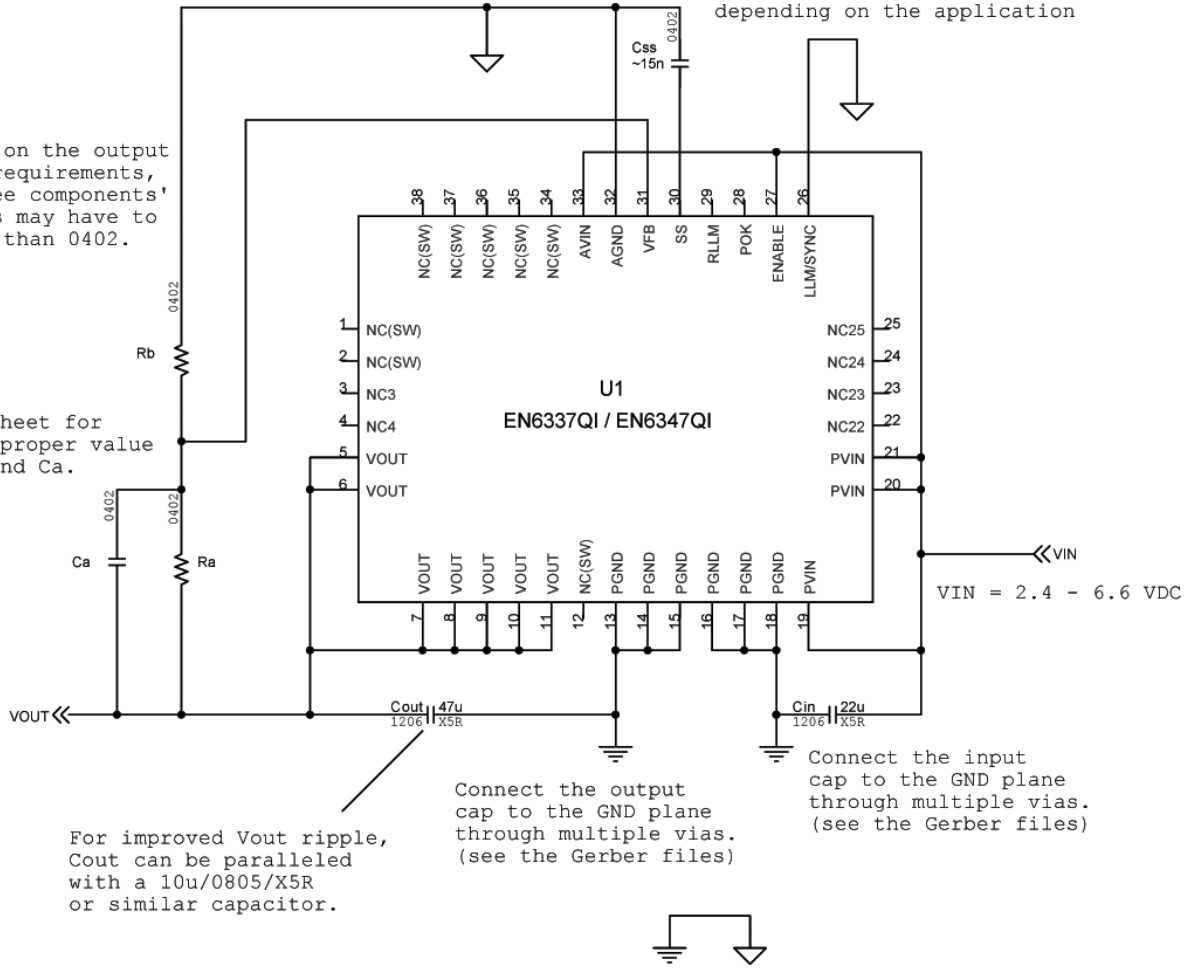


Figure 9. Engineering Schematic with Engineering Notes

## LAYOUT RECOMMENDATIONS

Figure 9 shows critical components and layer 1 traces of a typical EN6347QI layout with ENABLE tied to  $V_{IN}$  in PWM mode. Alternate ENABLE configurations and other small signal pins need to be connected and routed according to specific customer application. Please see the Gerber files on the Altera website <http://www.intel.com/enpirion> for exact dimensions and other layers. Please refer to this Figure while reading the layout recommendations in this section.

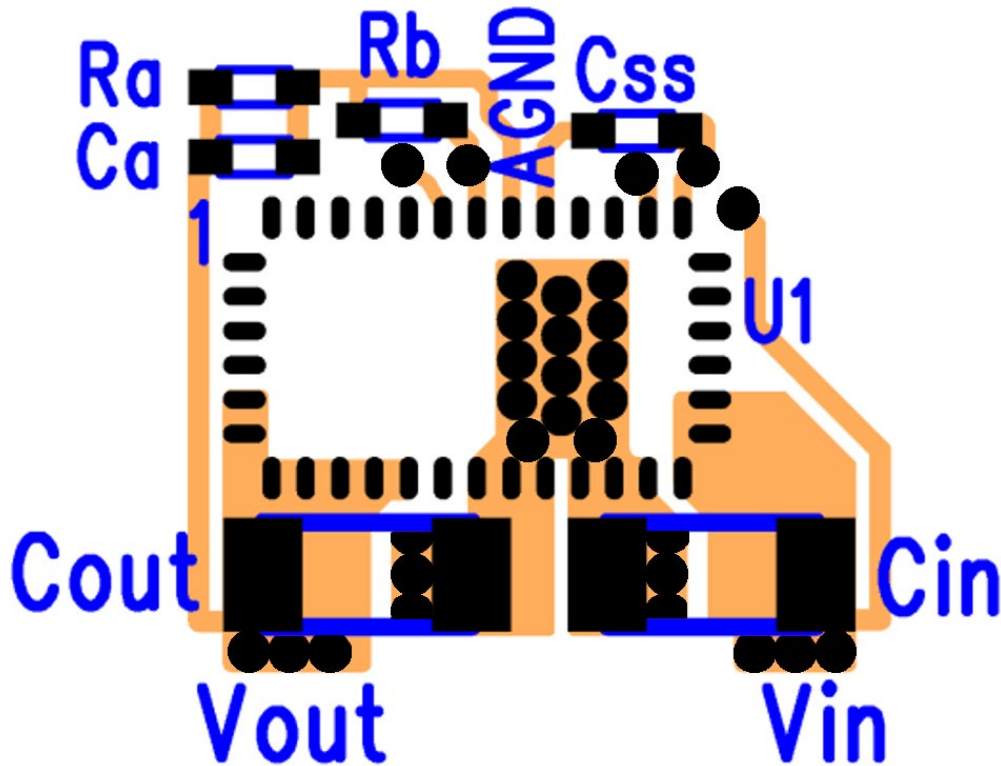


Figure 10. Top PCB Layer Critical Components and Copper for Minimum Footprint (Top View)

**Recommendation 1:** Input and output filter capacitors should be placed on the same side of the PCB, and as close to the EN6347QI package as possible. They should be connected to the device with very short and wide traces. Do not use thermal reliefs or spokes when connecting the capacitor pads to the respective nodes. The +V and GND traces between the capacitors and the EN6347QI should be as close to each other as possible so that the gap between the two nodes is minimized, even under the capacitors.

**Recommendation 2:** Three PGND pins are dedicated to the input circuit, and three to the output circuit. The slit in Figure 10 separating the input and output GND circuits helps minimize noise coupling between the converter input and output switching loops.

**Recommendation 3:** The system ground plane should be the first layer immediately below the surface layer. This ground plane should be continuous and un-interrupted below the converter and the input/output capacitors. Please see the Gerber files on the Altera website <http://www.intel.com/enpirion>.

**Recommendation 4:** The large thermal pad underneath the component must be connected to the system ground plane through as many vias as possible. The drill diameter of the vias should be 0.33mm, and the vias must have at least 1 oz. copper plating on the inside wall, making the finished hole size around 0.20-0.26mm. Do not use thermal reliefs or spokes to connect the vias to the ground plane. This connection provides the path for heat dissipation from the converter.

**Recommendation 5:** Multiple small vias (the same size as the thermal vias discussed in recommendation 4) should be used to connect ground terminal of the input capacitor and output capacitors to the system ground plane. It is preferred to put these vias under the capacitors along the edge of the GND copper closest to the +V copper. Please see Figure 10. These vias connect the input/output filter capacitors to the GND plane, and help reduce parasitic inductances in the input and output current loops. If the vias cannot be placed under  $C_{IN}$  and  $C_{OUT}$ , then put them just outside the capacitors along the GND slit separating the two components. Do not use thermal reliefs or spokes to connect these vias to the ground plane.

**Recommendation 6:** AVIN is the power supply for the internal small-signal control circuits. It should be connected to the input voltage at a quiet point. In Figure 10 this connection is made at the input capacitor close to the  $V_{IN}$  connection.

**Recommendation 7:** The layer 1 metal under the device must not be more than shown in Figure 10. See the section regarding exposed metal on bottom of package. As with any switch-mode DC-DC converter, try not to run sensitive signal or control lines underneath the converter package on other layers.

**Recommendation 8:** The  $V_{OUT}$  sense point should be just after the last output filter capacitor. Keep the sense trace as short as possible in order to avoid noise coupling into the control loop.

**Recommendation 9:** Keep  $R_A$ ,  $C_A$ , and  $R_B$  close to the VFB pin (see Figures 7). The VFB pin is a high-impedance, sensitive node. Keep the trace to this pin as short as possible. Whenever possible, connect  $R_B$  directly to the AGND pin instead of going through the GND plane.

## DESIGN CONSIDERATIONS FOR LEAD-FRAME BASED MODULES

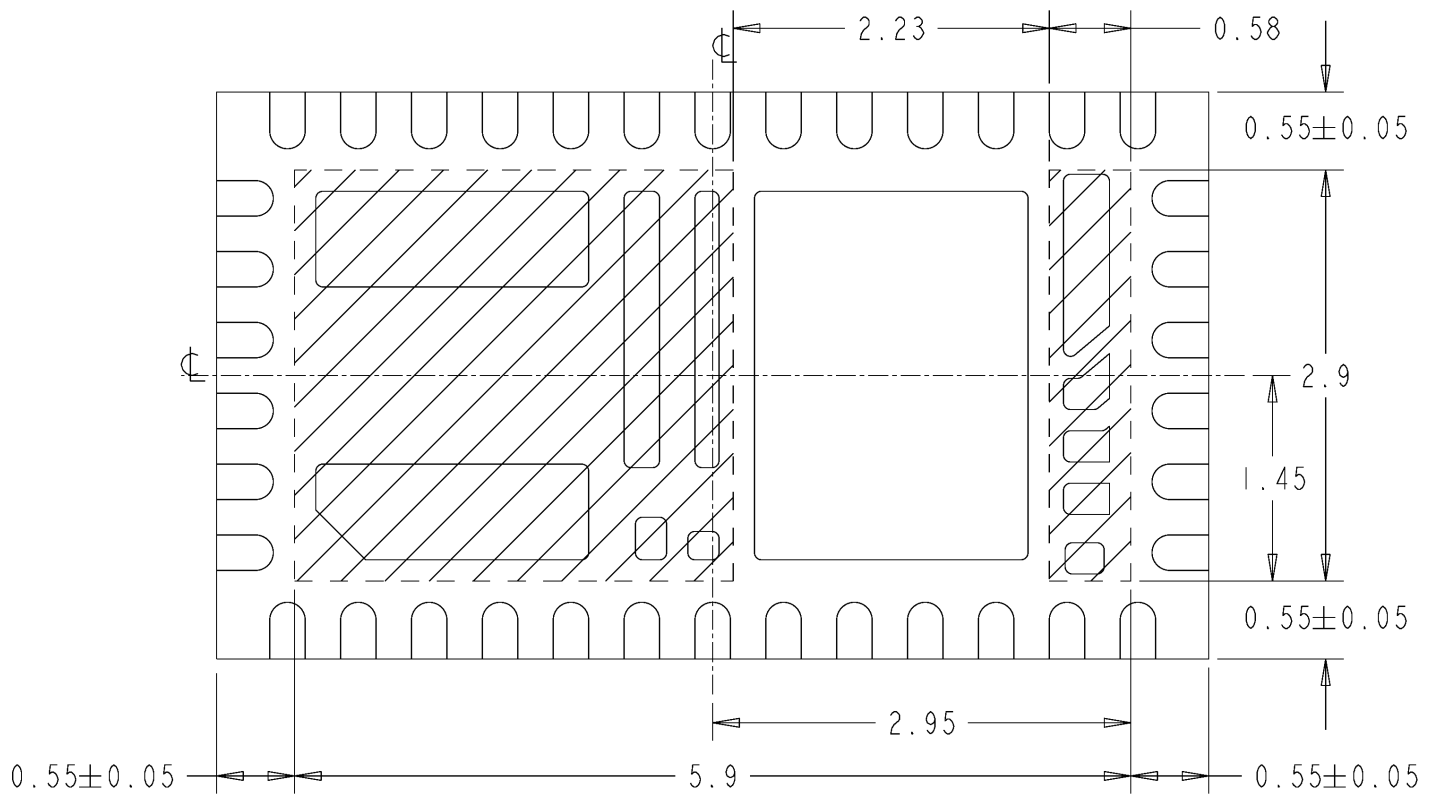
### Exposed Metal on Bottom of Package

Lead-frames offer many advantages in thermal performance, in reduced electrical lead resistance, and in overall foot print. However, they do require some special considerations.

In the assembly process lead frame construction requires that, for mechanical support, some of the lead-frame cantilevers be exposed at the point where wire-bond or internal passives are attached. This results in several small pads being exposed on the bottom of the package, as shown in Figure 11.

Only the thermal pad and the perimeter pads are to be mechanically or electrically connected to the PCB. The PCB top layer under the EN6347QI should be clear of any metal (copper pours, traces, or vias) except for the thermal pad. The “shaded-out” area in Figure 11 represents the area that should be clear of any metal on the top layer of the PCB. Any layer 1 metal under the shaded-out area runs the risk of undesirable shorted connections even if it is covered by soldermask.

The solder stencil aperture should be smaller than the PCB ground pad. This will prevent excess solder from causing bridging between adjacent pins or other exposed metal under the package.



**Figure 11. Lead-Frame exposed metal (Bottom View)**

Shaded area highlights exposed metal that is not to be mechanically or electrically connected to the PCB.

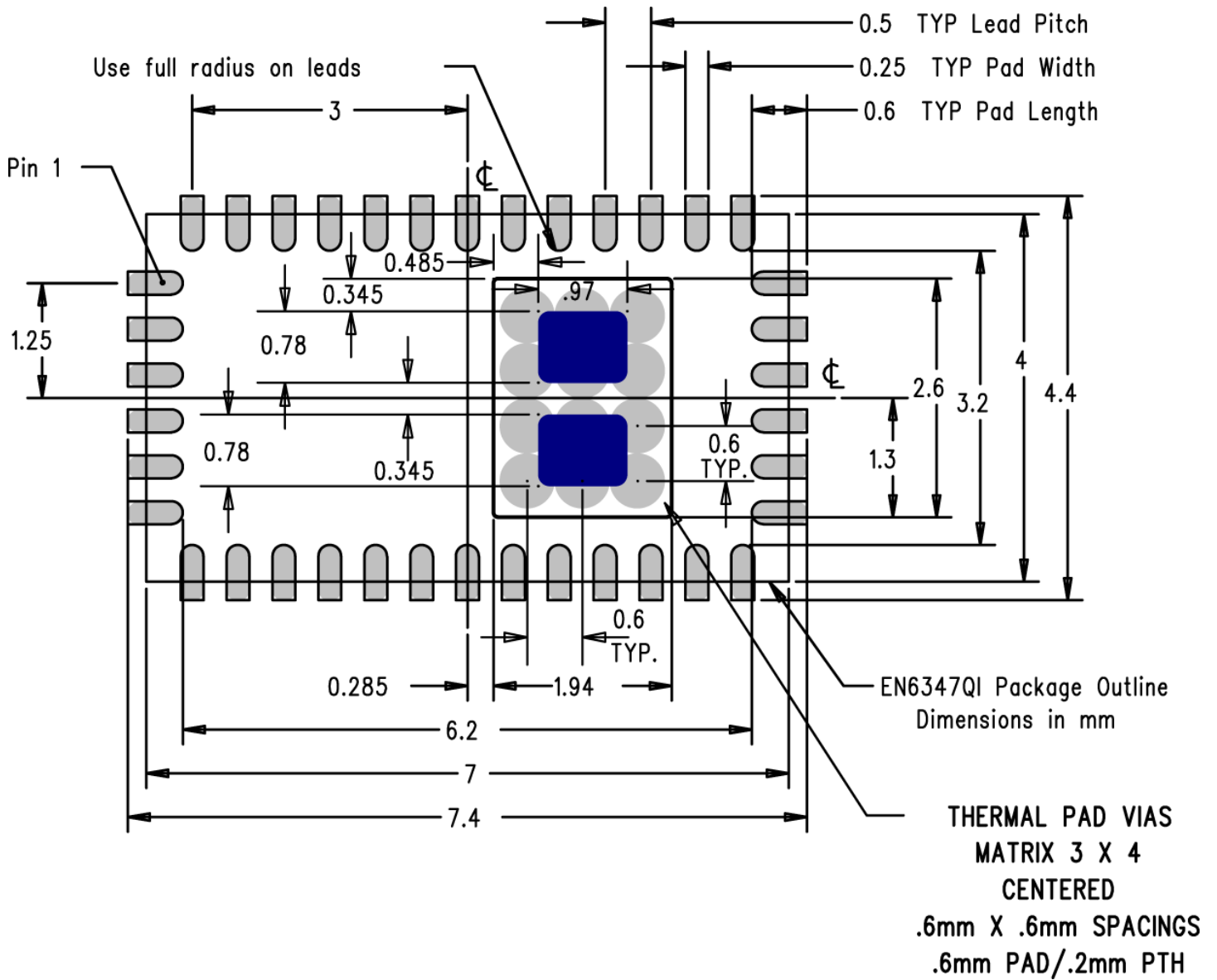


Figure 12. EN6347QI PCB Footprint (Top View)

The solder stencil aperture for the thermal pad is shown in blue and is based on Enpirion power product manufacturing specifications.

## PACKAGE DIMENSIONS

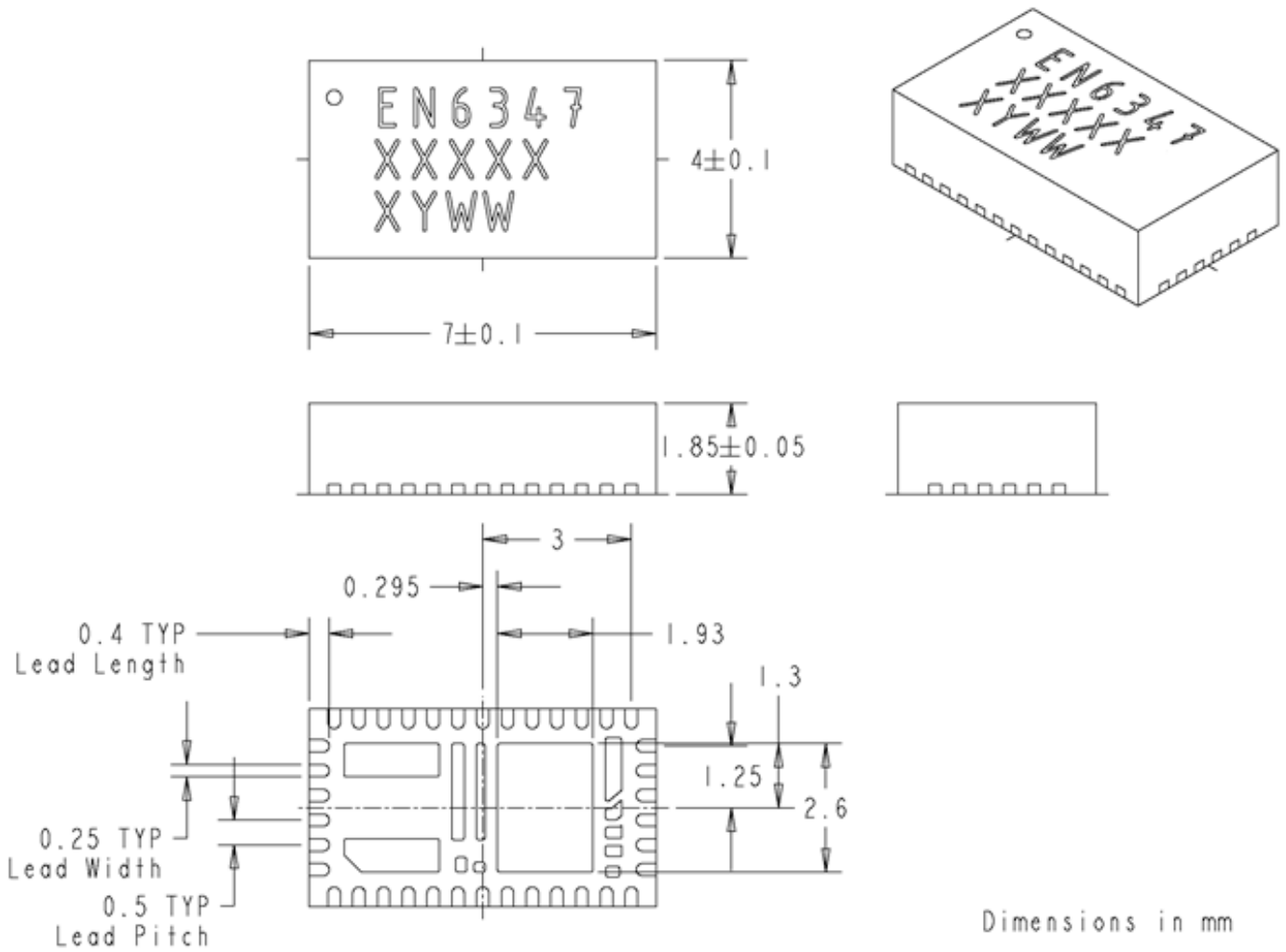


Figure 13. EN6347QI Package Dimensions

Packing and Marking Information: <https://www.intel.com/support/quality-and-reliability/packing.html>

## REVISION HISTORY

Rev	Date	Change(s)
J	April, 2018	Changed datasheet into Intel format.
K	August, 2018	Correct some typos
L	May, 2019	Correct some typos

## WHERE TO GET MORE INFORMATION

For more information about Intel® and Enpirion® PowerSoCs, visit:

[www.altera.com/enpirion](http://www.altera.com/enpirion)

© 2017 Intel Corporation. All rights reserved. Intel, the Intel logo, Altera, ARRIA, CYCLONE, ENPIRION, MAX, MEGACORE, NIOS, QUARTUS, and STRATIX words and logos are trademarks of Intel Corporation or its subsidiaries in the U.S. and/or other countries. Other marks and brands may be claimed as the property of others. Intel reserves the right to make changes to any products and services at any time without notice. Intel assumes no responsibility or liability arising out of the application or use of any information, product, or service described herein except as expressly agreed to in writing by Intel. Intel customers are advised to obtain the latest version of device specifications before relying on any published information and before placing orders for products or services.

\* Other marks and brands may be claimed as the property of others.



单击下面可查看定价，库存，交付和生命周期等信息

[>>Intel\(英特尔\)](#)