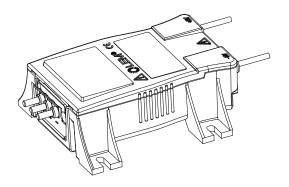


Voltage transducer DV 1500

$U_{\rm PN}$ = 1500 V

For the electronic measurement of voltage: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





Features

- Bipolar and isolated measurement up to 2250 V
- Current output
- Input cables for increased isolation, output on faston and M5 studs
- Footprint compatible with OV, CV 4 and LV 200-AW/2 families.

Advantages

- Low consumption and losses
- Compact design
- Good behavior under common mode variations
- Excellent accuracy (offset, sensitivity, linearity)
- Response time 60 µs
- Low temperature drift
- High immunity to external interferences.

Applications

- Single or three phase inverters
- Propulsion and braking chopper
- Propulsion converter
- Auxiliary converter
- High power drives
- Substations
- On-board energy meters.

Standards

- EN 50155: 2017
- EN 50124-1: 2017
- EN 50121-3-2: 2016.

Application Domain

• Railway (fixed installations and onboard).

N°97.F2.65.000.0

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Absolute maximum ratings

Parameter	Symbol	Value
Maximum supply voltage ($U_{\rm P}$ = 0 V, 0.1 s)	$\pm \hat{U}_{ m Cmax}$	±34 V
Maximum supply voltage (working) (-40 85 °C)	$\pm U_{ m C\ max}$	±26.4 V
Maximum primary voltage (-40 85 °C)	U _{P max}	2.25 kV
Maximum steady state primary voltage (-40 85 °C)	U _{PN max}	1500 V see derating on figure 2

Absolute maximum ratings apply at 25 °C unless otherwise noted. Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T _A	°C	-40		85	
Ambient storage temperature	T _{Ast}	°C	-50		90	
Equipment operating temperature class						EN 50155: OT6
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: PC2
Relative humidity	RH	%			95	
Shock & vibration categorie and class						EN 50155: 1B, (EN 61373)
Mass	m	g		640		
Ingress protection rating				IP40		IEC 60529 by constructrion (Indoor use)
Pollution degree					PD4	Insulation voltage accordingly
Altitude		m			2000 1)	

Note: ¹⁾ Insulation coordination at 2000 m.

RAMS data

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Useful life class						EN 50155: L4
Mean failure rate	λ	h-1		1/1883371		According to IEC 62380 $T_{\rm A}$ = 45 °C ON: 20 hrs/day ON/OFF: 320 cycles/year $U_{\rm c}$ = ±24 V, $U_{\rm P}$ = 1500 V

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DV 1500



Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_{d}	kV	18.5	100 % tested in production
Impulse withstand voltage 1.2/50 µs	\hat{U}_{W}	kV	30	
Partial discharge extinction RMS voltage @ 10 pC	U_{e}	V	5000	
Insulation resistance	R _{INS}	MΩ	200	Measured at 500 V DC
Clearance (pri sec.)	d _{CI}	mm	see dimensions	Shortest distance through air
Creepage distance (pri sec.)	$d_{\rm Cp}$	mm	drawing on page 10	Shortest path along device body
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	

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Electrical data

At $T_A = 25 \text{ °C}$, $U_C = \pm 24 \text{ V}$, $R_M = 100 \Omega$, unless otherwise noted. Lines with a * in the conditions column apply over the -40 … 85 °C ambient temperature range.

Parameter	Symbol	Unit	Min	Тур	Max		Conditions
Primary nominal RMS voltage	U _{pn}	V		1500		*	
Primary voltage, measuring range	U _{PM}	V	-2250		2250	*	
Measuring resistance	R _M	Ω	0		133.3	*	See derating on figure 2. For $ U_{PM} < 2250$ V, max value of R_{M} is given on figure 1
Secondary nominal RMS current	I _{s n}	mA		50		*	
Secondary current	Is	mA	-75		75	*	
Supply voltage	$\pm U_{\rm c}$	V	±13.5	±24	±26.4	*	
Rise time of $U_{ m c}$ (10-90 %)	t _{rise}	ms			100		
Current consumption	I _c	mA		20 + I _s	25 + I _s		
nrush current							NA (EN 50155)
nterruptions on power supply /oltage class							NA (EN 50155)
Supply change-over class							NA (EN 50155)
Offset current	Ι _ο	μΑ	-50	0	50		100 % tested in production
Temperature variation of <i>I_o</i>	I _{o T}	μA	-210	170	210		 −40 … 85 °C, 100 % tested in production
Sensitivity	G	μA/V		33.33			50 mA for 1500 V
Sensitivity error	$\varepsilon_{_G}$	%	-0.2	0	0.2		
Thermal drift of sensitivity	\mathcal{E}_{GT}	%	-0.5 -0.8 -0.8		0.5 0.8 0.8	*	−25 70 °C −25 85 °C −40 85 °C
_inearity error	ε _L	% of $U_{\rm PM}$	-0.1		0.1	*	±2250 V range
Overall accuracy	X _G	% of $U_{\rm PN}$	-0.3 -0.8 -1.1 -1.1		0.3 0.8 1.1 1.1	*	25 °C; 100 % tested in production -25 70 °C -25 85 °C -40 85 °C
Output RMS current noise	I _{no}	μΑ		10		1	1 Hz to 100 kHz
Reaction time @ 10 % of $U_{_{PN}}$	t _{ra}	μs		21		\square	
Response time @ 90 % of $U_{\rm PN}$	t _r	μs		48	60	1	0 to 1500 V step, 6 kV/µs
Frequency bandwidth	BW	kHz		12 6.5 1.6			3 dB 1 dB 0.1 dB
Start-up time	t _{start}	ms		190	250	*	
Resistance of primary (winding)	R _P	MΩ		23		*	
Total primary power loss @ U_{PN}	P _P	W		0.10		*	

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Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs. On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %. For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution. Typical, maximal and minimal values are determined during the initial characterization of a product.

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Typical performance characteristics

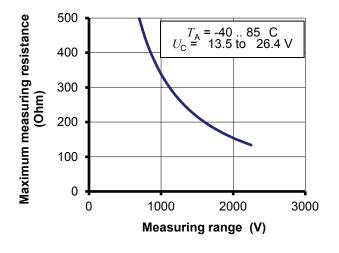


Figure 1: Maximum measuring resistance

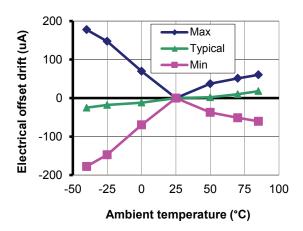


Figure 3: Electrical offset thermal drift

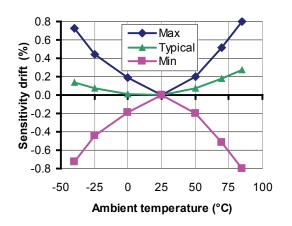


Figure 5: Sensitivity thermal drift

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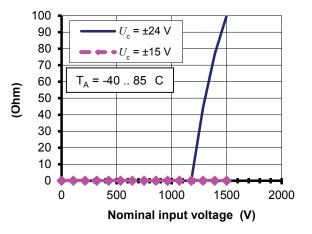


Figure 2: Minimum measuring resistance; For T_A under 80°C, the minimum measuring resistance is 0 Ω whatever U_c

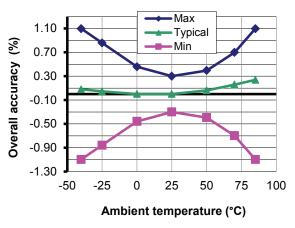
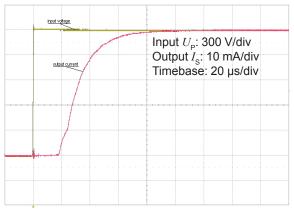
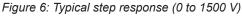


Figure 4: Overall accuracy in temperature





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Typical performance characteristics

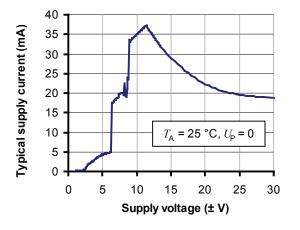
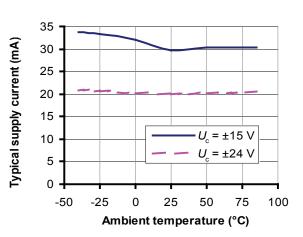
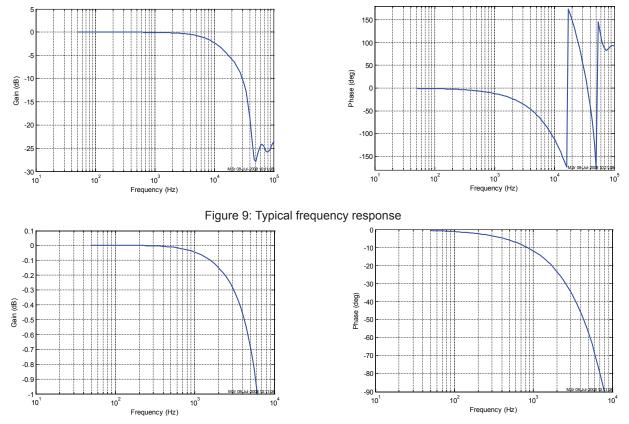


Figure 7: Supply current function of supply voltage



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Typical performance charateristics (continued)

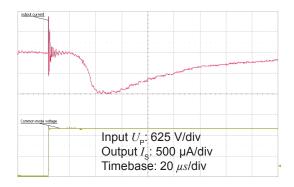
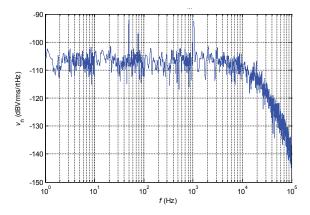
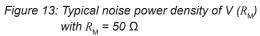


Figure 11: Typical common mode perturbation (1500 V step with 6 kV/ μ s $R_{\rm M}$ = 100 Ω)





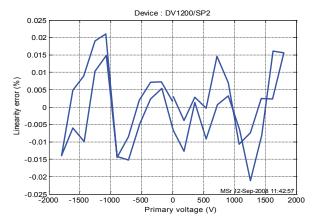


Figure 15: Typical linearity error

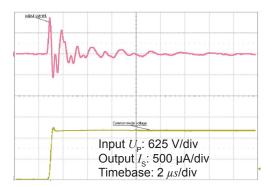


Figure 12: Detail of typical common mode perturbation (1500 V step with 6 kV/ μ s, $R_{\rm M}$ = 100 Ω)

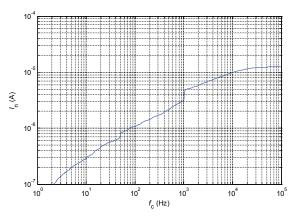


Figure 14: Typical total output RMS noise current with $R_{\rm M}$ = 50 Ω (fc is upper cut off frequency of bandpass, low cut off frequency is 1 Hz)

Figure 13 (output RMS noise voltage) shows that there are no significant discrete frequencies in the output.

Figure 14 confirms that because there are no steps in the total output current noise that would indicate discrete frequencies (there is only a small step around 1.5 kHz). To calculate the noise in a frequency band f1 to f2, the formula is

 $In(f1 to f2) = \sqrt{In(f2)^2 - In(f1)^2}$

with In(f) read from figure 14 (typical, RMS value).

Example:

What is the noise from 10 to 100 Hz? Figure 14 gives In(10 Hz) = 0.3 μ A and In(100 Hz) = 1 μ A. The output current noise (RMS) is therefore

$$\sqrt{(1.10^{-6})^2 - (0.3.10^{-6})^2} = 95 \,\mu V$$

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Performance parameters definition

The schematic used to measure all electrical parameters are:

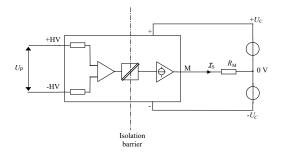


Figure 16: standard characterization schematics for current output transducers ($R_{\rm M}$ = 50 Ω unless otherwise noted)

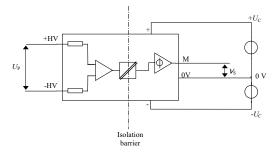


Figure 17: standard characterization schematics for voltage output transducers ($R_{_M} = 100 \text{ k}\Omega$ unless otherwise noted)

For all the following explanations, the output currents I_{s} , I_{o} , $I_{o \tau^{i}}$ etc. should be replaced by voltages for transducers with voltage output: V_{s} , V_{o} , $V_{o \tau}$ etc.

Transducer simplified model

The static model of the transducer at temperature T_A is:

 $I_{\rm S}$ = $G U_{\rm P}$ + error In which

$$\operatorname{error} = I_{OE} + I_{OT}(T_{A}) + \varepsilon_{G} G U_{P} + \varepsilon_{GT}(T_{A}) G U_{P} + \varepsilon_{L} G U_{PM}$$

$$\begin{array}{ll} I_{\rm S} & : {\rm the \ secondary \ current \ (A)} \\ G & : {\rm the \ sensitivity \ of \ the \ transducer \ (A/V)} \\ U_{\rm P} & : {\rm the \ voltage \ to \ measure \ (V)} \\ U_{\rm PM} & : {\rm the \ measuring \ range \ (V)} \\ T_{\rm A} & : {\rm the \ ambient \ temperature \ (^{\circ}{\rm C})} \\ I_{\rm O \ E} & : {\rm the \ ambient \ temperature \ variation \ of \ I_{\rm O}} \\ I_{\rm O \ T}(T_{\rm A}) & : {\rm the \ temperature \ variation \ of \ I_{\rm O}} \\ \epsilon_{\rm G} & : {\rm the \ sensitivity \ error \ at \ 25^{\circ}{\rm C} \ at \ temperature \ T_{\rm A}} \\ \epsilon_{\rm G \ T}(T_{\rm A}) & : {\rm the \ the \ measuring \ the \ temperature \ T_{\rm A}} \\ \end{array}$$

 ϵ_{L} :the linearity error

This is the absolute maximum error. As all errors are independent, a more realistic way to calculate the error would be to use the following formula:

$$\varepsilon = \sqrt{\sum_{i=1}^{N} \varepsilon_i^2}$$

Sensitivity and linearity

To measure sensitivity and linearity, the primary voltage (DC) is cycled from $U_{\rm PM}$, then to $-U_{\rm PM}$ and back to 0 (equally spaced $U_{\rm PM}$ /10 steps).

The sensitivity *G* is defined as the slope of the linear regression line for a cycle between $\pm U_{\rm PM}$.

The linearity error $\epsilon_{\rm L}$ is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Electrical offset

The electrical offset current $I_{\rm O\,E}$ is the residual output current when the input voltage is zero.

The temperature variation $I_{o \tau}$ of the electrical offset current $I_{o E}$ is the variation of the electrical offset from 25°C to the considered temperature.

Overall accuracy

The overall accuracy $X_{\rm G}$ is the error at $\pm U_{\rm PN}$, relative to the rated value $U_{\rm PN}$.

It includes all errors mentionned above.

Response and reaction times

The response time t_r and the reaction time t_{ra} are shown in the next figure.

Both slightly depend on the primary voltage dv/dt. They are measured at nominal voltage.

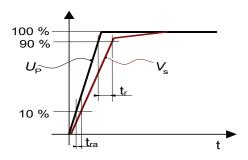
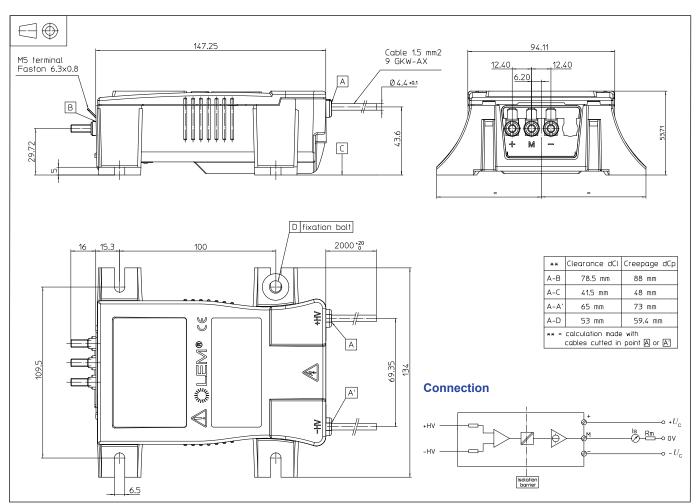


Figure 18: response time t_r and reaction time t_{ra}

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Dimensions (in mm)



Mechanical characteristics

- General tolerance
- Transducer fastening
- ±1 mm 4 M6 steel screws

2 × 1.5 mm² cables

M5 threaded studs

6.3 × 0.8 mm fastons and

- 4 washers ext. \varnothing 18 mm Recommended fastening torque 5 N·m
- Connection of primary
- Connection of secondary

Recommended fastening torque 2.2 N·m

Remarks

- I_s is positive when a positive voltage is applied on +HV.
- The transducer is directly connected to the primary voltage.
- The primary cables have to be routed together all the way.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary or secondary voltage present
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site:
 Products/Product Documentation.

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Note: Additional information available on request.

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary connections, power supply). Ignoring this warning can lead to injury and/ or cause serious damage. This transducer is a build-in device, whose conducting parts must be inaccessible after installation. A protective housing or additional shield could be used. Main supply must be able to be disconnected.

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