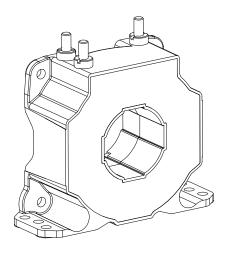


# **Current transducer LF 510-S/SP22**



For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





#### **Features**

- Bipolar and insulated current measurement up to 1.2 kA
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

#### **Special features**

- I<sub>PM</sub> = 0 ... ±1200 A
- N<sub>s</sub> = 3500
- T<sub>A</sub> = -40 °C ... 70°C
- · Connection to secondary circuit on M4 threaded studs.

### **Advantages**

- High accuracy
- Very low offset drift over temperature.

#### **Applications**

- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- Battery chargers
- Substations.

#### **Standards**

- EN 50155: 2021
- EN 50124-1: 2017
- EN 50121-3-2: 2016
- UL 508: 2010.

#### **Application Domain**

• Railway (fixed installations and onboard).

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### Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (-40 85 °C)	$\pm U_{\rm c}$	V	±25.2
Primary conductor temperature	T <sub>B</sub>	°C	100
Maximum steady state primary current (-40 85 °C)	I <sub>PN</sub>	A	500

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

#### UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

#### Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13

#### Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 600 V AC/DC, consideration shall be given to the following:

- 1 These products must be mounted in a suitable end-use enclosure.
- 2 The secondary pin terminals have not been evaluated for field wiring.
- 3 Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).
- 4 Based on the temperature test performed on all Series, the primary bar or conductor shall not exceed 100 °C in the end use application.

#### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

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## Insulation coordination

Parameter	Symbol	Unit	Value	Comment			
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_{\rm d}$	kV	4				
Impulse withstand voltage 1.2/50 μs	$U_{\rm Ni}$	kV	10.8				
Insulation resistance	R <sub>INS</sub>	MΩ	200	measured at 500 V DC			
Comparative tracking index	CTI		600				
Application example Rated insulation RMS voltage		V	2300	Reinforced insulation according to IEC 62497-1, CAT III, PD2			
Application example Rated insulation RMS voltage		V	3700	Basic insulation according to IEC 62497-1, CAT III, PD2			
Case material	-	-	V0	According to UL 94			
Clearance and creepage	See dimensions drawing on page 7						

### **Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	T <sub>A</sub>	°C	-40		70	
Ambient storage temperature	T <sub>Ast</sub>	°C	-45		90	
Equipment operating temperature class						EN 50155: OT4
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: NA
Mass	т	g		240		

#### **RAMS** data

Parameter	Symbol	Unit	Min	Тур	Comment
Useful life class					EN 50155: L4
Mean failure rate	Σ	h-1		1/4189558	According to IEC 62380: 2004 $T_A = 45 \degree C$ ON: 20 hrs/day ON/OFF: 320 cycles/year $U_C = \pm 24 \lor$ , $I_P = 500 \land DC$





### **Electrical data**

At  $T_A = 25 \text{ °C}$ ,  $\pm U_C = \pm 15 \text{ V}$ ,  $R_M = 1 \Omega$ , unless otherwise noted. Lines with a \* in the conditions column apply over the -40 … 70 °C ambient temperature range.

Parameter	Symbol	Unit	Min	Тур	Max		Conditions
Primary nominal RMS current	I <sub>pn</sub>	А			500	*	
Primary current, measuring range	I <sub>PM</sub>	A	-1200		1200	*	
Measuring resistance	R <sub>M</sub>	Ω	0			*	Max value of $R_{\rm M}$ is given in figure 1
Secondary nominal RMS current	I <sub>s n</sub>	A	İ		0.1429	*	
Resistance of secondary winding	R <sub>s</sub>	Ω			27.7		$R_{\rm s}(T_{\rm A}) = R_{\rm s} \times (1 + 0.004 \times (T_{\rm A} + \Delta \text{temp}-25))$ Estimated temperature increase @ $I_{\rm PN}$ is $\Delta \text{temp} = 15 ^{\circ}\text{C}$
Secondary current	Is	Α	-0.343		0.343	*	
Number of secondary turns	$N_{\sf S}$			3500			
Nominal sensitivity	$S_{N}$	mA/A		0.285			
Supply voltage	$\pm U_{\rm C}$	V	±14.25		±25.2	*	
Current consumption	I <sub>c</sub>	mA		$44 + I_{s}$ $49 + I_{s}$			$\begin{array}{l} \pm U_{\rm c} = \pm 15 \text{ V} \\ \pm U_{\rm c} = \pm 24 \text{ V} \end{array}$
Inrush current							NA (EN 50155)
Interruptions on power supply voltage class							NA (EN 50155)
Supply change-over class							NA (EN 50155)
Offset current, referred to primary	Io	A	-1		1		
Temperature variation of $I_{\rm o}$ , referred to primary	I <sub>o T</sub>	A	-0.6		0.6	*	
Magnetic offset current, referred to primary	I <sub>om</sub>	A		±0.7			After 3 × $I_{PN}$
Sensitivity error	€ <sub>G</sub>	%	-0.5		0.5	*	
Linearity error	ε <sub>L</sub>	% of $I_{\rm PN}$	-0.1		0.1	*	
Total error at I <sub>PN</sub>	$\varepsilon_{\mathrm{tot}}$	% of $I_{\rm PN}$	_0 5		0.5 0.6	*	25 … 70 °C −40 … 70 °C
Output RMS current noise referred to primary	$I_{\rm no}$	mA		50			1 Hz to 20 kHz (see figure 4)
Delay time @ 10 % of the final output value $U_{\rm PN}$ step	t <sub>D 10</sub>	μs		< 0.5			0 to 500 A, 200 A/µs
Delay time @ 90 % of the final output value $U_{\rm PN}$ step	t <sub>D 90</sub>	μs		< 0.5			0 to 500 A, 200 A/µs
Frequency bandwidth	BW	kHz		200			−3 dB, small signal bandwidth (see figure 5)

#### Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

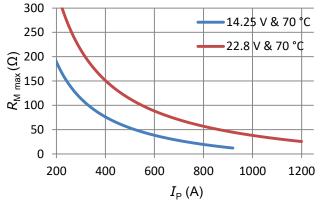
For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

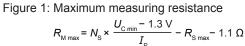
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## **Typical performance characteristics**



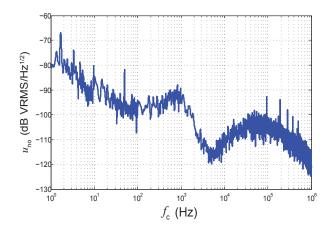


Figure 3: Typical noise voltage density  $u_{no}$  with  $R_{\rm M}$  = 100  $\Omega$ 

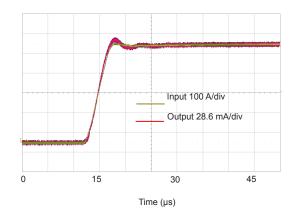


Figure 2: Typical step response (0 to 500 A, 100 A/ $\mu$ s  $R_{M}$  = 1  $\Omega$ )

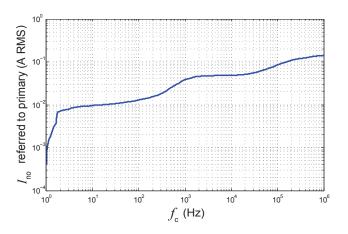


Figure 4: Typical total output current noise with  $R_{\rm M}$  = 100  $\Omega$  (primary referred, RMS)

To calculate the noise in a frequency band  $f_1$  to  $f_2$ , the formula is:

$$I_{\rm no} (f_1 \dots f_2) = \sqrt{I_{\rm no} (f_2)^2 - I_{\rm no} (f_2)^2}$$

with  $I_{no}(f)$  read from figure 4 (typical, RMS value).

Example: What is the noise from 1 to  $10^6$  Hz? Figure 4 gives  $I_{no}$  (1 Hz) = 0.4 mA and  $I_{no}$  ( $10^6$  Hz) = 145 mA. The output current noise (RMS) is therefore:

 $\sqrt{(145 \times 10^{-3})^2 - (0.4 \times 10^{-3})^2} = 145$  mA referred to primary

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## **Typical performance characteristics**

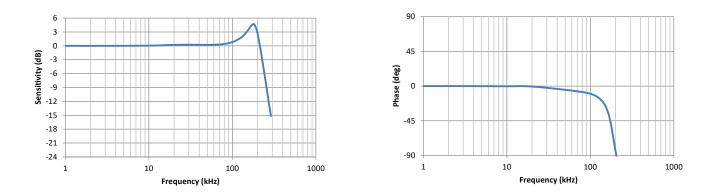


Figure 5, 6: Typical frequency response, small signal bandwidth

#### Performance parameters definition

#### Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to  $I_{\rm PM}$ , then to  $-I_{\rm PM}$  and back to 0 (equally spaced I<sub>Р М</sub>/10 steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between  $\pm I_{PM}$ .

The linearity error  $\varepsilon_{\rm L}$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

#### **Magnetic offset**

The magnetic offset  $I_{\rm O\,M}$  is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range

#### **Electrical offset**

The electrical offset current  $I_{\rm O\ E}$  is the residual output current when the input current is zero.

#### **Total error**

The total error  $\varepsilon_{tot}$  is the error at  $\pm I_{PN}$ , relative to the rated value  $I_{\rm PN}$ . It includes all errors mentioned above.

#### **Delay times**

The delay time  $t_{\rm D\,10}$  @ 10 % and the delay time  $t_{\rm D\,90}$  @ 90 % with respect to the primary are shown in the next figure. Both slightly depend on the primary voltage di/dt. They are measured at nominal voltage.

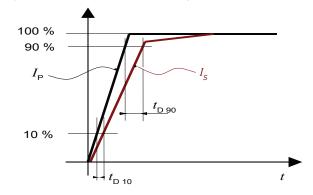
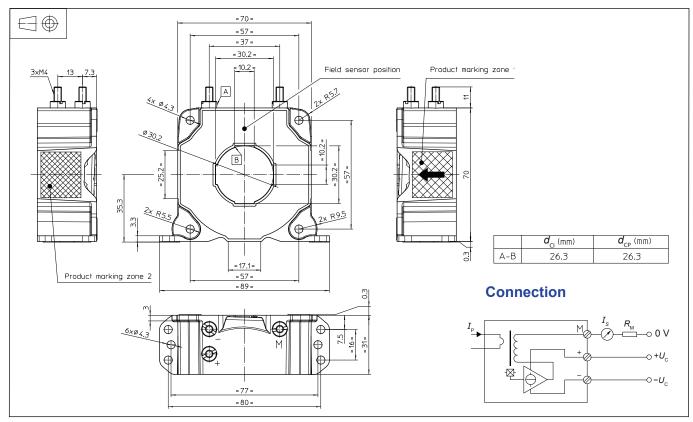


Figure 7: delay time  $t_{D10}$  @ 10 % and delay time  $t_{D90}$  @ 90 %

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## Dimensions (in mm)



#### **Mechanical characteristics**

- General tolerance
  - Transducer fastening Vertical position

±0.5 mm

ø 30 mm

6 holes ø 4.3 mm 6 M4 steel screws

2.1 N·m (±10 %)

30 mm × 10 mm

4 holes ø 4.3 mm 4 M4 steel screws

2.1 N·m (±10 %)

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary connection, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used. Main supply must be able to be disconnected.

- Recommended fastening torque
- Primary through-hole Or
  Transducer fastening
  - Transducer fastening Horizontal position
  - Recommended fastening torque
- Connection of secondary M4 threaded studs Recommended fastening torque 1.2 N·m (±10 %)

#### Remarks

- $I_{\rm s}$  is positive when  $I_{\rm p}$  flows in the direction of arrow.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary current or secondary voltage present.
- Maximum temperature of primary conductor: see page 2.
- Installation of the transducer must be done unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: <u>https://www.lem.com/en/file/3137/download/</u>.

Note: Additional information avaible on request.

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单击下面可查看定价,库存,交付和生命周期等信息

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