

Current Transducer LXS series

*I*_{PN} **= 6, 15, 25 A**

Ref: LXS 6-NPS, LXS 15-NPS, LXS 25-NPS

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





Features

- Closed loop multi-range current transducer
- Voltage output
- Unipolar supply voltage
- Compact design for PCB mounting.

Advantages

- · Very low offset drift
- Very good dv/dt immunity
- LTS footprint compatible
- Extended measuring range for unipolar measurement.

Applications

- AC variable speed and servo motor drives
- Static converters for DC motor drives
- Battery supplied applications
- Uninterruptible Power Supplies (UPS)
- Switched Mode Power Supplies (SMPS)
- Power supplies for welding applications
- Solar inverters.

Standards

- IEC 61800-1: 1997
- IEC 61800-2: 2015
- IEC 61800-3: 2004
- IEC 61800-5-1: 2007
- IEC 62109-1: 2010
- IEC 62477-1: 2012
- UL 508:2013.

Application Domain

• Industrial.

2June2022/Version 3

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N°97.O9.09.000.0, N°97.O9.15.000.0, N°97.O9.19.000.0



Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage	$U_{\rm C\;max}$	V	7
Maximum primary conductor temperature	$T_{\rm B\ max}$	°C	110
Maximum primary current	$I_{\rm P\;max}$	A	20 × <i>I</i> _{PN}
Maximum electrostatic discharge voltage	$U_{\rm ESD\;max}$	kV	4

Stresses above these ratings may cause permanent damage. Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 11

Standards

- CSA C22.2 NO. 14-10 INDUSTRIAL CONTROL EQUIPMENT Date 2011/08/01
- UL 508 STANDARD FOR INDUSTRIAL CONTROL EQUIPMENT Date 2013

Ratings

Parameter	Symbol	Unit	Value
Primary involved potential		V AC/DC	600
Max surrounding air temperature	T_{A}	°C	105
Primary current	I _P	А	According to series primary currents
Secondary supply voltage	U _c	V DC	7
Output voltage	U_{out}	V	0 5

Conditions of acceptability

When installed in the end-use equipment, consideration shall be given to the following:

- 1 These devices must be mounted in a suitable end-use enclosure.
- 2 The terminals have not been evaluated for field wiring.
- 3 The LES, LESR, LKSR, LPSR, LXS and LXSR Series shall be used in a pollution degree 2 environment or better.
- 4 Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as a transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).
- 5 These devices are intended to be mounted on the printed wiring board of the end-use equipment (with a minimum CTI of 100).
- 6 LES, LESR, LKSR and LPSR Series: based on results of temperature tests, in the end-use application, a maximum of 110°C cannot be exceeded on the primary jumper.

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Page 2/16



Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_{\rm d}$	kV	4.3	
Impulse withstand voltage 1.2/50 μs	$U_{ m Ni}$	kV	8	
Insulation resistance	R _{INS}	GΩ	18	measured at 500 V DC
Partial discharge RMS test voltage (q_m < 10 pC)	$U_{\rm t}$	kV	1.65	
Clearance (pri sec.)	d _{ci}	mm	7.7	Shortest distance through air
Creepage distance (pri sec.)	$d_{\rm Cp}$	mm	7.7	Shortest path along device body
Case material	-	-	V0	According to UL 94
Comparative tracking index	CTI		600	
Application example		V	300	Reinforced insulation according to IEC 61800-5-1 CAT III, PD2
Application example		V	600	Basic insulation according to IEC 61800-5-1 CAT III, PD2

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Тур	Мах	Comment
Ambient operating temperature	T_{A}	°C	-40		105	
Ambient storage temperature	$T_{\rm Ast}$	°C	-55		125	
Mass	т	g		10		

Page 3/16



Electrical data LXS 6-NPS

At $T_A = 25 \text{ °C}$, $U_C = +5 \text{ V}$, $N_P = 1 \text{ turn}$, $R_L = 10 \text{ k}\Omega$ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 14).

Parameter	Symbol	Unit	Min	Тур	Мах	Comment
Primary nominal RMS current	I _{pn}	A		6		Apply derating according to <u>figure 16</u>
Primary current, measuring range	I _{PM}	Α	-20		20	
Number of primary turns	N_{P}			1, 2, 3		
Supply voltage	U_{c}	V	4.75	5	5.25	
Current consumption	I _c	mA		$18 + \frac{I_{p}(mA)}{N_{s}}$	$20.5 + \frac{I_{\rm p}({\rm mA})}{N_{\rm S}}$	$N_{\rm s}$ = 2000 turns
Output voltage	U_{out}	V	0.25		4.75	with U_c = +5 V
Output voltage @ $I_P = 0 A$	$U_{\rm out}$	V		2.5		
Electrical offset voltage	U _{oe}	mV	-19.8		19.8	100 % tested U_{out} – 2.5 V
Electrical offset current referred to primary	I _{oe}	mA	-190		190	100 % tested
Temperature coefficient of U_{out} @ $I_{p} = 0 \text{ A}$	$TCU_{\rm out}$	ppm/K			±70	ppm/K of 2.5 V −40 °C … 105 °C
Nominal sensitivity	S_{N}	mV/A		104.2		625 mV/ I _{PN}
Sensitivity error	$\varepsilon_{_S}$	%	-0.2		0.2	100 % tested
Temperature coefficient of S	TCS	ppm/K			±45	-40 °C 105 °C
Linearity error	εL	% of $I_{\rm PN}$	-0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	$I_{\rm OM}$	mA	-25		25	
Noise voltage spectral density 100 Hz 100 kHz referred to primary	u _{no}	µV/Hz½		7		
RMS noise voltage referred to primary DC 10 kHz DC 100 kHz DC 1 MHz	$U_{\sf no}$	mVpp		11.5 13.6 13.8		
Delay time to 10 % of the final output value for $I_{\rm PN}$ step	t _{D 10}	μs			0.3	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Delay time to 90 % of the final output value for $I_{\rm PN}$ step	t _{D 90}	μs			0.4	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			$R_{\rm L} = 1 \ \rm k\Omega$
Total error	$\varepsilon_{ m tot}$	% of $I_{\rm PN}$			3.2	
Total error @ T_A = 85 °C (105 °C)	$\mathcal{E}_{\mathrm{tot}}$	% of <i>I</i> _{PN}			3.5 (4.2)	
Sum of sensitivity and linearity	$\varepsilon_{_{SL}}$	% of $I_{\rm PN}$			0.45	
Sum of sensitivity and linearity @ $T_A = 85 \text{ °C} (105 \text{ °C})$	e _{sl}	% of $I_{\rm PN}$			0.8 (1)	

Page 4/16



Electrical data LXS 15-NPS

At $T_A = 25 \text{ °C}$, $U_C = +5 \text{ V}$, $N_P = 1 \text{ turn}$, $R_L = 10 \text{ k}\Omega$ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 14).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal RMS current	$I_{\rm PN}$	А		15		Apply derating according to <u>figure 17</u>
Primary current, measuring range	I _{PM}	A	-51		51	
Number of primary turns	N_{P}			1, 2, 3		
Supply voltage	U_{C}	V	4.75	5	5.25	
Current consumption	I _c	mA		$18 + \frac{I_{\rm P}({\rm mA})}{N_{\rm S}}$	$20.5 + \frac{I_{\rm P}({\rm mA})}{N_{\rm S}}$	$N_{\rm S}$ = 2000 turns
Output voltage	U_{out}	V	0.25		4.75	with $U_{\rm c}$ = +5 V
Output voltage @ $I_{\rm P}$ = 0 A	$U_{\rm out}$	V		2.5		
Electrical offset voltage reffered to primary	$U_{\rm OE}$	mV	-15.42		15.42	100 % tested $U_{\rm out}$ – 2.5 V
Electrical offset current referred to primary	I _{oe}	mA	-370		370	100 % tested
Temperature coefficient of U_{out} @ $I_{p} = 0 A$	$TCU_{\rm out}$	ppm/K			±80	ppm/K of 2.5 V −40 °C … 105 °C
Nominal sensitivity	S_{N}	mV/A		41.67		625 mV\
Sensitivity error	ε_s	%	-0.2		0.2	100 % tested
Temperature coefficient of S	TCS	ppm/K			±45	−40 °C 105 °C
Linearity error	ε_{L}	% of $I_{\rm PN}$	-0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	$I_{\rm O\;M}$	mA	-45		45	
Noise voltage spectral density 100 Hz 100 kHz referred to primary	u _{no}	µV/Hz½		4		
RMS noise voltage referred to primary DC 10 kHz DC 100 kHz DC 1 MHz	$U_{\sf no}$	mVpp		5.7 6.3 7.6		
Delay time to 10 % of the final output value for I_{PN} step	t _{D 10}	μs			0.3	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Delay time to 90 % of the final output value for $I_{\rm PN}$ step	t _{D 90}	μs			0.4	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			$R_{\rm L} = 1 \ \rm k\Omega$
Total error	$\varepsilon_{\rm tot}$	% of $I_{\rm PN}$			2.5	
Total error @ $T_A = 85 \degree C (105 \degree C)$	$\varepsilon_{\rm tot}$	% of I _{PN}			3 (3.9)	
Sum of sensitivity and linearity	€ _{S1}	% of <i>I</i> _{PN}			0.45	
Sum of sensitivity and linearity @ $T_A = 85 \degree C (105 \degree C)$	e _{s L}	% of I _{PN}			0.7 (0.75)	

Page 5/16

LXS series



Electrical data LXS 25-NPS

At $T_A = 25 \text{ °C}$, $U_C = +5 \text{ V}$, $N_P = 1 \text{ turn}$, $R_L = 10 \text{ k}\Omega$ internal reference, unless otherwise noted (see Definition of typical, minimum and maximum values paragraph in page 14).

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Primary nominal RMS current	I _{pn}	А		25		Apply derating according to <u>figure 18</u>
Primary current, measuring range	I _{PM}	A	-85		85	
Number of primary turns	N _P			1, 2, 3		
Supply voltage	Uc	V	4.75	5	5.25	
Current consumption	I _c	mA		$18 + \frac{I_{p}(mA)}{N_{s}}$	20.5 + $\frac{I_{p}(mA)}{N_{s}}$	$N_{\rm s}$ = 2000 turns
Output voltage	$U_{\rm out}$	V	0.25		4.75	with $U_{\rm c}$ = +5 V
Output voltage @ $I_{\rm P}$ = 0 A	$U_{\rm out}$	V		2.5		
Electrical offset voltage reffered to primary	U _{oe}	mV	-14.5		14.5	100 % tested $U_{\rm out}$ – 2.5 V
Electrical offset current referred to primary	I _{oe}	mA	-580		580	100 % tested
Temperature coefficient of U_{out} @ $I_{p} = 0 \text{ A}$	TCU _{out}	ppm/K			±80	ppm/K of 2.5 V −40 °C … 105 °C
Nominal sensitivity	S _N	mV/A		25		625 mV/ I _{P N}
Sensitivity error	$\varepsilon_{_S}$	%	-0.2		0.2	100 % tested
Temperature coefficient of S	TCS	ppm/K			±45	−40 °C 105 °C
Linearity error	ε _L	% of <i>I</i> _{P N}	-0.1		0.1	
Magnetic offset current (10 × I_{PN}) referred to primary	I _{om}	mA	-60		60	
Noise voltage spectral density 100 Hz 100 kHz referred to primary	u _{no}	µV/Hz½		3.5		
RMS noise voltage referred to primary DC 10 kHz DC 100 kHz DC 1 MHz	$U_{\sf no}$	mVpp		2.7 4.5 5.3		
Delay time to 10 % of the final output value for $I_{\rm PN}$ step	t _{D 10}	μs			0.3	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Delay time to 90 % of the final output value for I_{PN} step	t _{D 90}	μs			0.4	$R_{\rm L}$ = 1 k Ω , d <i>i</i> /d <i>t</i> = 50 A/µs
Frequency bandwidth (±3 dB)	BW	kHz	300			$R_{\rm L} = 1 \ \rm k\Omega$
Total error	$\varepsilon_{\rm tot}$	% of $I_{\rm PN}$			2.5	
Total error @ T_A = 85 °C (105 °C)	€ _{tot}	% of $I_{\rm PN}$			3 (3.1)	
Sum of sensitivity and linearity	ε _{sl}	% of I _{PN}			0.45	
Sum of sensitivity and linearity @ $T_A = 85 \text{ °C} (105 \text{ °C})$	e _{sl}	% of $I_{\rm PN}$			0.7 (0.75)	

Page 6/16



Typical performance characteristics LXS 6-NPS





Figure 1: Linearity error











2June2022/Version 3



Page 7/16

3.5

3.4

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6

20 kV/µs

5

3

4

t (μs)



Rel. Sensitivity

Phase

10⁵

20

10

10[□] -20

-30

-40

-50

10⁶

Typical performance characteristics LXS 15-NPS







10²

10³10 Frequency [Hz]

10⁴

2

0

-10

10¹

Relative Sensitivity [dB]









2June2022/Version 3

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Page 8/16

Figure 9: Noise voltage spectral density

Figure 10: dv/dt



Typical performance characteristics LXS 25-NPS





Figure 11: Linearity error













Figure 15: dv/dt

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Page 9/16

3.5



Maximum continuous DC primary current



Figure 16: $I_{\rm P}$ vs $T_{\rm A}$ for LXS 6-NPS



LXS series

Figure 17: I_P vs T_A for LXS 15-NPS



Figure 18: $I_{\rm P}$ vs $T_{\rm A}$ for LXS 25-NPS

The maximum continuous DC primary current plot shows the boundary of the area for which all the following conditions are true:

- I_P < I_{PM}
- Junction temperature $T_{\rm J}$ < 125 °C
- Primary conductor temperature < 110 °C
- Max power dissipation of internal resistors < 0.5 × resistors nominal power

Frequency derating



Figure 19: Maximum RMS AC primary current / maximum DC primary current vs frequency

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Page 10/16



Performance parameters definition

Ampere-turns and amperes

The transducer is sensitive to the primary current linkage $\Theta_{\rm P}$ (also called ampere-turns).

 $\Theta_{\mathsf{P}} = N_{\mathsf{P}} \cdot I_{\mathsf{P}} \text{ (At)}$

Where $N_{\rm p}$ is the number of primary turn (depending on the connection of the primary jumpers)

Caution: As most applications will use the transducer with only one single primary turn ($N_p = 1$), much of this datasheet is written in terms of primary current instead of current linkages. However, the ampere-turns (At) unit is used to emphasis that current linkages are intended and applicable.

Simplified transducer model

The static model of the transducer at temperature T_{A} is:

 $U_{\text{out}} = S \cdot \Theta_{\text{P}} + \varepsilon$ In which $\dot{\varepsilon} =$ $U_{\mathsf{OE}} + U_{\mathsf{OT}}(T_{\mathsf{A}}) + \varepsilon_{S} \cdot \mathcal{O}_{\mathsf{P}} \cdot S + \varepsilon_{\mathsf{L}} \left(\mathcal{O}_{\mathsf{P}\max} \right) \cdot \mathcal{O}_{\mathsf{P}\max} \cdot S + TCS \cdot (T_{\mathsf{A}} - 25) \cdot \mathcal{O}_{\mathsf{P}} \cdot S$ $\Theta_{P} = N_{P} \cdot I_{P}$: primary current linkage (At) With: : max primary current linkage applied to $\Theta_{\rm P\,max}$ the transducer : output voltage (V) U_{s} T_{A} : ambient operating temperature (°C) $\stackrel{I_{\mathsf{OE}}}{U_{\mathsf{OT}}}(T_{\mathsf{A}})$: electrical offset voltage (V) : temperature variation of U_0 at temperature T_A (°C) S : sensitivity of the transducer (V/At) TCS : temperature coefficient of S : sensitivity error ε_{s} $\vec{e_{I}}(\Theta_{P_{max}})$: linearity error for $\Theta_{P_{max}}$

This model is valid for primary ampere-turns $\Theta_{\rm P}$ between $-\Theta_{\rm P max}$ and $+\Theta_{\rm P max}$ only.

Total error

The total error at 25 °C ε_{tot} is the error in the $-I_{PN} \dots +I_{PN}$ range, relative to the rated value I_{PN} . It includes:

- the electrical offset U_{OF}
- the sensitivity error ε_{c}
- the linearity error ε_{I} (to I_{PN})

Electrical offset

The electrical offset voltage $U_{\rm OE}$ can either be measured when the ferro-magnetic parts of the transducer are:

LXS series

- · Completely demagnetized, which is difficult to realize,
- or in a known magnetization state, like in the current cycle shown in figure 21.

Using the current cycle shown in figure 21, the electrical offset is:

$$U_{\text{o}\,\text{E}} = \frac{U_{\text{out}}\left(t_{1}\right) + U_{\text{out}}\left(t_{2}\right)}{2}$$

The temperature variation $U_{0\ T}$ of the electrical offset voltage $U_{0\ E}$ is the variation of the electrical offset from 25 °C to the considered temperature:

$$U_{0\tau}(T) = U_{0E}(T) - U_{0E}(25^{\circ} \text{ C})$$

Note: the transducer has to be demagnetized prior to the application of the current cycle (for example with a demagnetization tunnel).



Figure 20: Test connection

Magnetic offset

The magnetic offset current I_{OM} is the consequence of a current on the primary side ("memory effect" of the transducer's ferromagnetic parts). It is measured using the following primary current cycle. I_{OM} depends on the current value $I_{P1}(I_{P1} > I_{PM})$.



Figure 21: Current cycle used to measure magnetic and electrical offset (transducer supplied)

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Page 11/16

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to $I_{\rm p}$, then to $-I_{\rm p}$ and back to 0 (equally spaced $I_{\rm p}/10$ steps). The sensitivity *S* is defined as the slope of the linear regression line for a cycle between $\pm I_{\rm PN}$.

The linearity error $\varepsilon_{\rm L}$ is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of $I_{\rm PN}$.

Delay times

The delay time t_{D10} @ 10 % and the delay time t_{D90} @ 90 % are shown in figure 22.

Both depend on the primary current di/dt. They are measured at nominal ampere-turns.



Figure 22: $t_{D 10}$ (delay time @ 10 %) and $t_{D 90}$ (delay time @ 90 %).

Page 12/16

LXS series

Application information

Filtering and decoupling

Supply voltage U_c

The transducer has internal decoupling capacitors, but in the case of a power supply with high impedance, it is highly recommended to provide local decoupling (100 nF or more, located close to the transducer) as it may reduce disturbance on transducer output $U_{\rm out}$ and reference $U_{\rm ref}$ due to high varying primary current. The transducer power supply rejection ratio is low at high frequency.

Output U_{out}

The output U_{out} has a very low output impedance of typically 1 Ohm; it can drive capacitive loads of up to 100 nF directly. Adding series resistance R*f* of several tenths of Ohms allows much larger capacitive loads Cf (higher than 1 µF). Empirical evaluation may be necessary to obtain optimum results. The minimum load resistance on U_{out} is 1 kOhm.



Figure 23: filtered $U_{\rm out}$ connection

Total Primary Resistance

The primary resistance is $0.72 \text{ m}\Omega$ per conductor.

In the following table, examples of primary resistance according to the number of primary turns.

Number of primary turns	Primary Nominal RMS current	Output voltage $U_{\rm out}$	Primary resistance R _P [mΩ]		Recommended connections	
1	±I _{PN}	2.5 ±0.625	0.24	IN	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	OUT
2	±I _{PN} /2	2.5±0.625	1.08	IN	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	OUT
3	±I _{PN} /3	2.5 ±0.625	2.16	IN	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$	OUT

Page 13/16

LXS series



PCB footprint



Assembly on PCB

- Recommended PCB hole diameter
- Maximum PCB thickness
- Wave soldering profile No clean process only

Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.

1.3 mm for primary pin0.8 mm for secondary pin

maximum 260 °C for 10 s

2.4 mm



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (e.g. primary busbar, power supply). Ignoring this warning can lead to injury and/or cause serious damage. This transducer is a build-in device, whose conducting parts must be inaccessible after installation. A protective housing or additional shield could be used. Main supply must be able to be disconnected.

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, maximal and minimal values are determined during the initial characterization of the product.

Page 14/16



Dimensions (in mm)





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Page 15/16





Packaging information

Standard delivery in cardboard: $L \times W \times H$: 315 × 200 × 120 mm Each carboard contains 150 parts, placed into 3 Polystyrene-made trays of 50 parts each one. Both trays and carboard are ESD-compliant. The typical weight of the cardboard is 2.5 Kg.



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Page 16/16

单击下面可查看定价,库存,交付和生命周期等信息

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