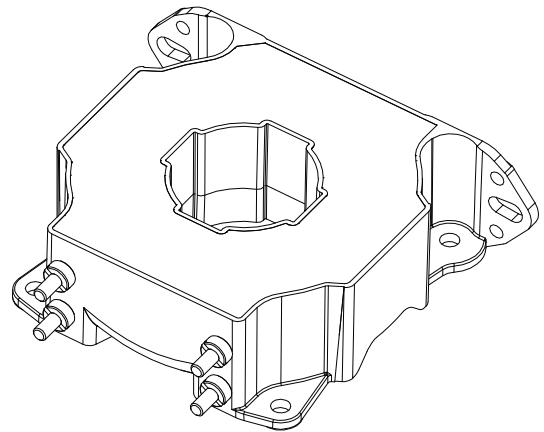


Current transducer LF 1010-S/SP33

$I_{PN} = 1000 \text{ A}$

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.



Features

- Bipolar and insulated current measurement
- Current output
- Closed loop (compensated) current transducer
- Panel mounting.

Special features

- $U_c = \pm 24 \text{ V} (\pm 7 \%)$
- Shield between primary and secondary
- Connection to secondary circuit on M4 threaded studs.

Advantages

- High accuracy
- Very low offset drift over temperature.

Applications

- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- Battery chargers
- Substations.

Standards

- EN 50121-3-2: 2016
- EN 50124-1: 2017
- EN 50155: 2021
- IEC 62497-1: 2010
- UL 508: 2013.

Application Domain

- Railway (fixed installations and onboard).

Absolute maximum ratings

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (-40 ... 85 °C)	$\pm U_C$	V	± 25.7
Primary conductor temperature	T_B	°C	100
Maximum steady state primary current (-40 ... 85 °C)	I_{PN}	A	1000

Stresses above these ratings may cause permanent damage.
Exposure to absolute maximum ratings for extended periods may degrade reliability.

UL 508: Ratings and assumptions of certification

File # E189713 Volume: 2 Section: 9

Standards

- USR indicates investigation to the Standard for Industrial Control Equipment UL 508.
- CNR indicates investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13

Conditions of acceptability

When installed in the end-use equipment, with primary feedthrough potential involved of 600 V AC/DC, consideration shall be given to the following:

- 1 - *These products must be mounted in a suitable end-use enclosure.*
- 2 - *The secondary pin terminals have not been evaluated for field wiring.*
- 3 - *Low voltage control circuit shall be supplied by an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay).*
- 4 - *Based on the temperature test performed on all Series, the primary bar or conductor shall not exceed 100 °C in the end use application.*

Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.

Insulation coordination

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	U_d	kV	6	Between primary and secondary + shield
			1	Between shield and secondary
Impulse withstand voltage 1.2/50 μ s	U_{Ni}	kV	16.5	
Insulation resistance	R_{INS}	M Ω	200	measured at 500 V DC
Comparative tracking index	CTI		600	
Clearance (pri. - sec.)	d_{Cl}	mm	34.5	Shortest distance through air
Creepage distance (pri. - sec.)	d_{Cp}	mm	34.8	Shortest path along device body
Application example Rated insulation RMS voltage	U_{Nm}	kV	3	Reinforced insulation according to IEC 62497-1, CAT III , PD2
Application example Rated insulation RMS voltage	U_{Nm}	kV	4.8	Basic insulation according to IEC 62497-1, CAT III, PD2

Environmental and mechanical characteristics

Parameter	Symbol	Unit	Min	Typ	Max	Comment
Ambient operating temperature	T_A	$^{\circ}$ C	-40		85	
Ambient storage temperature	T_{Ast}	$^{\circ}$ C	-50		90	
Equipment operating temperature class						EN 50155: OT6
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: NA
Mass	m	g		435		

RAMS data

Parameter	Symbol	Unit	Min	Typ	Max
Useful life class					EN 50155: L4
Mean failure rate	$\bar{\lambda}$	h^{-1}		1/3680795	According to IEC 62380: 2004 $T_A = 45^{\circ}$ C ON: 20 hrs/day ON/OFF: 320 cycles/year $U_C = \pm 24$ V, $I_P = 1000$ A DC

Electrical data

At $T_A = 25\text{ °C}$, $\pm U_C = \pm 24\text{ V}$, $R_M = 1\ \Omega$, unless otherwise noted.

Lines with a * in the conditions column apply over the $-40 \dots 85\text{ °C}$ ambient temperature range.

Parameter	Symbol	Unit	Min	Typ	Max	Conditions
Primary nominal RMS current	I_{PN}	A			1000	*
Primary current, measuring range	I_{PM}	A	-2580		2580	* With $\pm U_C = \pm 22.3\text{ V}$; $T_A = +85\text{ °C}$; $R_M = 1\ \Omega$ For other conditions, see figure 1
Measuring resistance	R_M	Ω	0			* Max value of R_M is given in figure 1
Secondary nominal RMS current	I_{SN}	A	-0.2		0.2	*
Resistance of secondary winding	R_S	Ω			29.9	$R_S(T_A) = R_S \times (1 + 0.004 \times (T_A + \Delta\text{temp} - 25))$ Estimated temperature increase @ I_{PN} is $\Delta\text{temp} = 15\text{ °C}$
Secondary current	I_S	A	-0.516		0.516	
Number of secondary turns	N_S			5000		
Nominal sensitivity	S_N	mA/A		0.2		
Supply voltage	$\pm U_C$	V	± 22.3		± 25.7	*
Current consumption	I_C	mA		$49 + I_S$		$\pm U_C = \pm 24\text{ V}$
Inrush current						NA (EN 50155)
Interruptions on power supply voltage class						NA (EN 50155)
Supply change-over class						NA (EN 50155)
Offset current, referred to primary	I_O	A	-1		1	
Temperature variation of I_O , referred to primary	I_{OT}	A	-0.6		0.6	*
Magnetic offset current, referred to primary	I_{OM}	A		± 1		After $3 \times I_{PN}$
Sensitivity error	ε_S	%	-0.15		0.15	*
Linearity error	ε_L	% of I_{PN}	-0.15		0.15	*
Total error at I_{PN}	ε_{tot}	% of I_{PN}	-0.2 -0.4		0.2 0.4	25 ... 70 ... 85 °C -40 ... 85 °C *
RMS noise current referred to primary	I_{no}	mA		50		1 Hz to 20 kHz (see figure 4)
Delay time to 10 % of the final output value I_{PN} step	t_{D10}	μs		< 0.5		0 to 1 kA, 200 A/ μs
Delay time to 90 % of the final output value I_{PN} step	t_{D90}	μs		< 0.5		0 to 1 kA, 200 A/ μs
Frequency bandwidth	BW	kHz		200		-3 dB, small signal bandwidth (see figures 5, 6)

Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

Typical performance characteristics

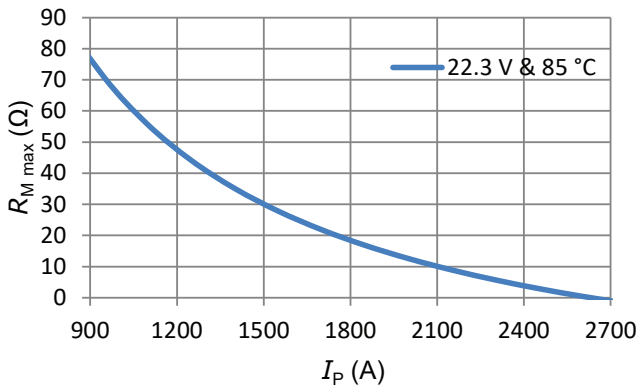


Figure 1: Maximum measuring resistance

$$R_{M \max} = N_S \times \frac{U_{C \min} - 1.3 \text{ V}}{I_P} - R_{S \max} - 0.93 \Omega$$

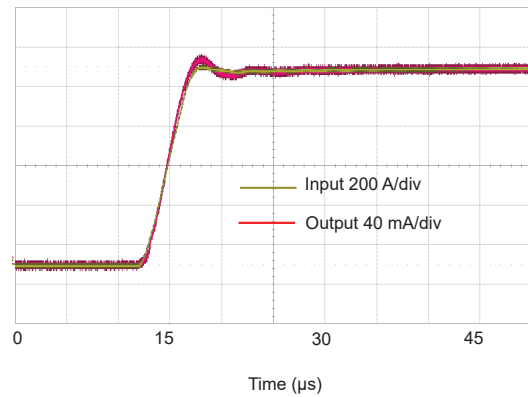


Figure 2: Typical step response (0 to 1 kA, 200 A/μs)

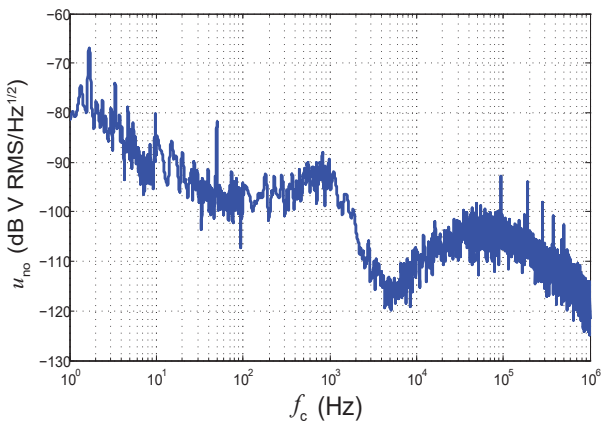


Figure 3: Typical noise voltage density u_{no} with $R_M = 100 \Omega$

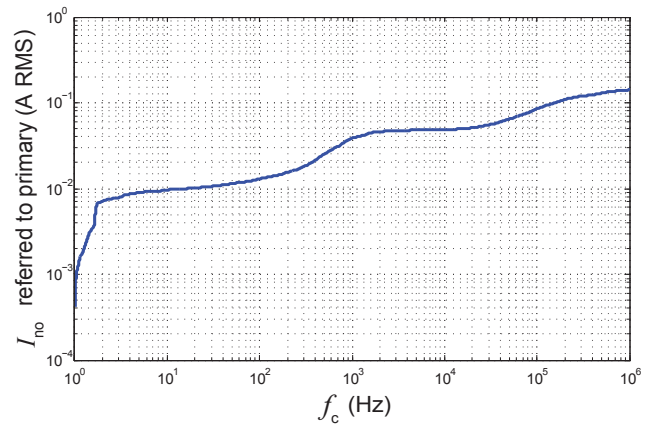


Figure 4: Typical total RMS noise current with $R_M = 100 \Omega$ (primary referred, RMS)

To calculate the noise in a frequency band f_1 to f_2 , the formula is:

$$I_{no}(f_1 \dots f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

with $I_{no}(f)$ read from figure 4 (typical, RMS value).

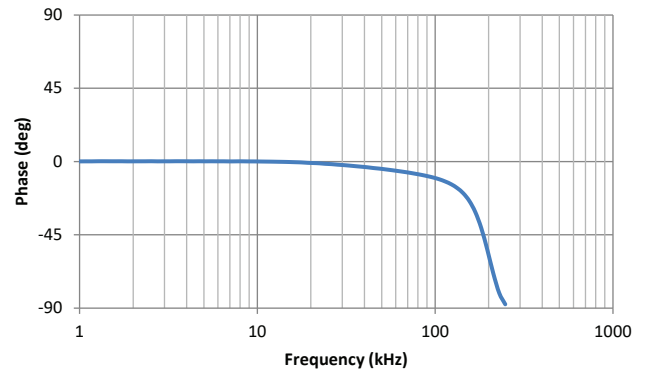
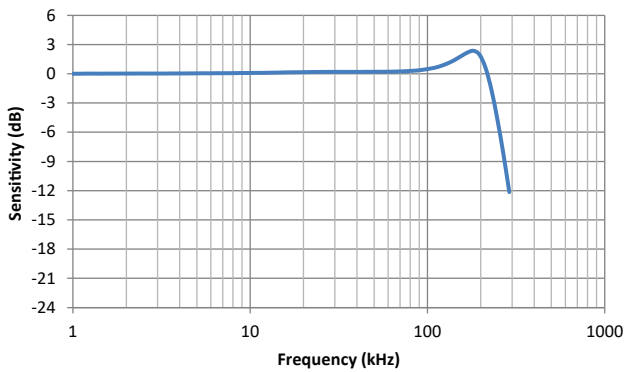
Example:

What is the noise from 1 to 10^6 Hz?

Figure 4 gives $I_{no}(1 \text{ Hz}) = 0.5 \text{ mA}$ and $I_{no}(10^6 \text{ Hz}) = 199 \text{ mA}$. The output current noise (RMS) is therefore:

$$\sqrt{(199 \times 10^{-3})^2 - (0.5 \times 10^{-3})^2} = 199 \text{ mA referred to primary}$$

Typical performance characteristics



Figures 5, 6: Typical frequency response, small signal bandwidth

Performance parameters definition

Sensitivity and linearity

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to I_{PM} , then to $-I_{PM}$ and back to 0 (equally spaced $I_{PM}/10$ steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between $\pm I_{PM}$.

The linearity error ϵ_L is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

Magnetic offset

The magnetic offset I_{OM} is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

Electrical offset

The electrical offset current I_{OE} is the residual output current when the input current is zero.

Total error

The total error ϵ_{tot} is the error at $\pm I_{PN}$, relative to the rated value I_{PN} . It includes all errors mentioned above.

Delay times

The delay time $t_{D,10}$ @ 10 % and the delay time $t_{D,90}$ @ 90 % with respect to the primary are shown in the next figure. Both slightly depend on the primary current di/dt . They are measured at nominal current.

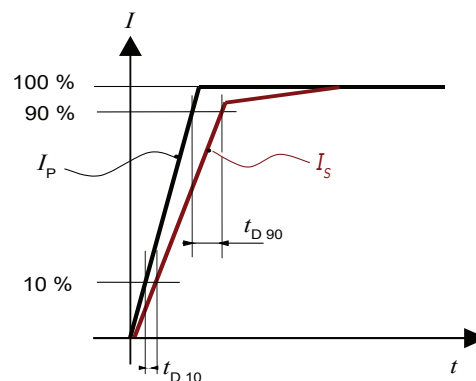


Figure 7: $t_{D,10}$ (delay time @ 10 %) and $t_{D,90}$ (delay time @ 90 %)

单击下面可查看定价，库存，交付和生命周期等信息

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