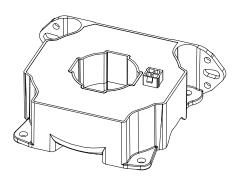


# **Current transducer LF 1010-S/SPA2**

 $I_{PN} = 1000 A$ 

For the electronic measurement of current: DC, AC, pulsed..., with galvanic separation between the primary and the secondary circuit.





#### **Features**

- · Bipolar and insulated current measurement
- Current output
- · Closed loop (compensated) current transducer
- Panel mounting.

#### **Special features**

- Connection to secondary circuit on Molex Mini-Fit Jr 5566 with gold plated pin
- $\bullet~$  Shield between primary and secondary connected on  $\ensuremath{^-} U_{\rm C}$
- Different case long feet.

#### **Advantages**

- High accuracy
- Very low offset drift over temperature.

## **Applications**

- · Windmill inverters
- Single or three phase inverters
- Propulsion and braking choppers
- Propulsion converters
- Auxiliary converters
- · High power drives
- Substations.

## **Standards**

- EN 50155: 2021
- EN 50124-1: 2017
- EN 50121-3-2: 2016
- UL 508: 2013
- IEC 61010-1:2010.

### **Application Domain**

• Railway (fixed installations and onboard).

N°97.J9.60.0A2.0

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### LF 1010-S/SPA2

## **Absolute maximum ratings**

Parameter	Symbol	Unit	Value
Maximum supply voltage (working) (−40 85 °C)	$\pm U_{\rm C\; max}$	V	±25.2
Primary conductor temperature	$T_{B}$	°C	100
Maximum steady state primary current (-40 85 °C)	$I_{ m P\ N\ max}$	A DC	1000

Stresses above these ratings may cause permanent damage.

Exposure to absolute maximum ratings for extended periods may degrade reliability.

#### **UL 508: Ratings and assumptions of certification**

File # E189713 Volume: 2 Section: 7

#### **Standards**

- USR indicated investigation to the Standard for Industrial Control Equipment UL 508.
- CNR Indicated investigation to the Canadian standard for Industrial Control Equipment CSA C22.2 No. 14-13

#### **Conditions of acceptability**

When installed in the end-use equipment, with primary feedthrough potential involved of 600 V AC/DC, consideration shall be given to the following:

- 1 These devices must be mounted in a suitable end-use enclosure.
- 2 The terminals have not been evaluated for field wiring.
- 3 Low voltage circuits are intended to be powered by a circuit derived from an isolating source (such as transformer, optical isolator, limiting impedance or electro-mechanical relay) and having no direct connection back to the primary circuit (other than through the grounding means).

#### Marking

Only those products bearing the UL or UR Mark should be considered to be Listed or Recognized and covered under UL's Follow-Up Service. Always look for the Mark on the product.





## **Insulation coordination**

Parameter	Symbol	Unit	Value	Comment
RMS voltage for AC insulation test, 50 Hz, 1 min	$U_{d}$	kV	6	
Impulse withstand voltage 1.2/50 μs	$U_{\mathrm{Ni}}$	kV	16	
Insulation resistance	$R_{INS}$	МΩ	200	measured at 500 V DC
Application example Rated insulation RMS voltage	$U_{\rm Nm}$	V	600	Reinforced insulation according IEC 62497-1, CAT III, PD2
Application example Rated insulation RMS voltage	$U_{\rm Nm}$	V	1800	Basic insulation according IEC 62497-1, CAT III, PD2
Clearance (pri sec.)	$d_{\text{CI}}$	mm	11.3	Shortest distance through air
Creepage distance (pri sec.)	$d_{Cp}$	mm	24.6	Shortest path along device body
Comparative tracking index	CTI		600	
Case material	-	-	V0	According to UL 94

## **Environmental and mechanical characteristics**

Parameter	Symbol	Unit	Min	Тур	Max	Comment
Ambient operating temperature	$T_{A}$	°C	-40		85	
Ambient storage temperature	$T_{Ast}$	°C	-50		90	
Equipment operating temperature class						EN 50155: OT6
Switch-on extended operating temperature class						EN 50155: ST0
Rapid temperature variation class						EN 50155: H2
Conformal coating type						EN 50155: NA
Mass	m	g		435		

### **RAMS** data

Parameter	Symbol	Unit	Min	Тур	Max
Useful life class					EN 50155: L4
Mean failure rate	Σ	h <sup>-1</sup>		1/3680795	According to IEC 62380: 2004 $T_{\rm A}$ = 45 °C ON: 20 hrs/day ON/OFF: 320 cycles/year $U_{\rm C}$ = ±24 V, $I_{\rm P}$ = 1000 A DC



# Electrical data LF 1010-S/SPA2

At  $T_{\rm A}$  = 25 °C,  $\pm U_{\rm C}$  =  $\pm 24$  V,  $R_{\rm M}$  = 1  $\Omega$ , unless otherwise noted.

Lines with a \* in the conditions column apply over the -40 ... 85 °C ambient temperature range.

Parameter	Symbol	Unit	Min	Тур	Max		Conditions
Primary nominal DC current	$I_{PN}$	Α			1000	*	
Primary nominal AC <sup>1)</sup> RMS current	$I_{PN}$	Α			1200	*	
Primary current, measuring range	$I_{PM}$	А	-2720		2720	*	With $\pm U_{\rm C}$ = $\pm 22.8$ V; $T_{\rm A}$ = $+85$ °C; $R_{\rm M}$ = 1 $\Omega$ For other conditions, see <u>figure 1</u>
Measuring resistance	$R_{M}$	Ω	0			*	Max value of $R_{\rm M}$ is given in figure 1
Secondary nominal DC current	$I_{\mathrm{SN}}$	Α			0.2	*	
Resistance of secondary winding	$R_{\mathbb{S}}$	Ω			29.9		$R_{\rm S}(T_{\rm A}) = R_{\rm S} \times (1 + 0.004 \times (T_{\rm A} + \Delta {\rm temp} - 25))$ Estimated temperature increase @ $I_{\rm P N}$ is $\Delta {\rm temp} = 15  ^{\circ}{\rm C}$
Secondary current	$I_{\rm S}$	А	-0.544		0.544	*	
Number of secondary turns	$N_{\mathtt{S}}$			5000			
Nominal sensitivity	$S_{N}$	mA/A		0.2			
Supply voltage	$\pm U_{\mathrm{c}}$	V	±14.25		±25.2	*	
Current consumption	$I_{\mathtt{C}}$	mA		44 + I <sub>S</sub> 49 + I <sub>S</sub>			$\pm U_{\rm C} = \pm 15 \text{ V}$ $\pm U_{\rm C} = \pm 24 \text{ V}$
Inrush current							NA (EN 50155)
Interruptions on power supply voltage class							NA (EN 50155)
Supply change-over class							NA (EN 50155)
Offset current, referred to primary	$I_{O}$	Α	-1		1		
Temperature variation of $I_{\rm O}$ , referred to primary	$I_{\rm OT}$	А	-0.6		0.6	*	
Magnetic offset current, referred to primary	$I_{OM}$	Α		±1			After 3 × I <sub>PN</sub>
Sensitivity error	$arepsilon_{ extsf{S}}$	%	-0.15		0.15	*	
Linearity error	$arepsilon_{L}$	% of $I_{PN}$	-0.15		0.15	*	
Total error	$arepsilon_{ ext{tot}}$	% of $I_{PN}$	-0.2 -0.4		0.2 0.4	*	25 70 85 °C -40 85 °C
RMS noise current referred to primary	$I_{no}$	mA		50			1 Hz to 20 kHz (see figure 4)
Delay time to 10 % of the final output value $I_{\rm PN}$ step	t <sub>D 10</sub>	μs		< 0.5			0 to 1 kA, 200 A/μs
Delay time to 90 % of the final output value $I_{\rm PN}$ step	t <sub>D 90</sub>	μs		< 0.5			0 to 1 kA, 200 A/μs
Frequency bandwidth	BW	kHz		200			-3 dB, small signal bandwidth (see figure 5)

Note: 1) Low frequency.

## Definition of typical, minimum and maximum values

Minimum and maximum values for specified limiting and safety conditions have to be understood as such as well as values shown in "typical" graphs.

On the other hand, measured values are part of a statistical distribution that can be specified by an interval with upper and lower limits and a probability for measured values to lie within this interval.

Unless otherwise stated (e.g. "100 % tested"), the LEM definition for such intervals designated with "min" and "max" is that the probability for values of samples to lie in this interval is 99.73 %.

For a normal (Gaussian) distribution, this corresponds to an interval between -3 sigma and +3 sigma. If "typical" values are not obviously mean or average values, those values are defined to delimit intervals with a probability of 68.27 %, corresponding to an interval between -sigma and +sigma for a normal distribution.

Typical, minimum and maximum values are determined during the initial characterization of the product.

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# **Typical performance characteristics**

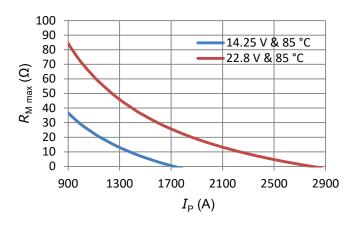


Figure 1: Maximum measuring resistance

$$R_{
m M\,max} = N_{
m S} imes \; rac{U_{
m C\,min} - 0.5 \; 
m V}{I_{
m P}} - R_{
m S\,max} - \; 0.93 \; \Omega$$

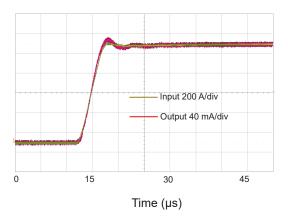


Figure 2: Typical step response (0 to 1 kA, 200 A/µs)

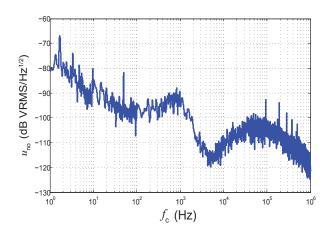


Figure 3: Typical noise voltage density  $u_{\rm no}$  with  $R_{\rm M}$  = 100  $\Omega$ 

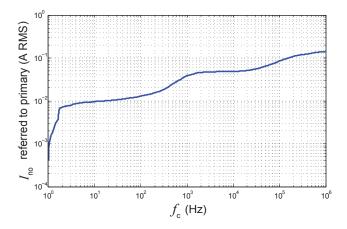


Figure 4: Typical total output current noise with  $R_{\rm M}$  = 100  $\Omega$  (primary referred, RMS)

To calculate the noise in a frequency band  $f_{\rm 1}$  to  $f_{\rm 2}$ , the formula is:

$$I_{no}(f_1 \dots f_2) = \sqrt{I_{no}(f_2)^2 - I_{no}(f_1)^2}$$

with  $I_{no}(f)$  read from figure 4 (typical, RMS value).

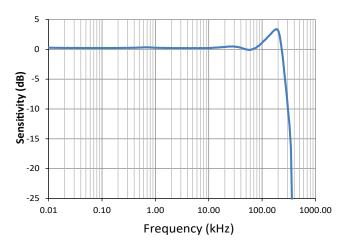
#### Example:

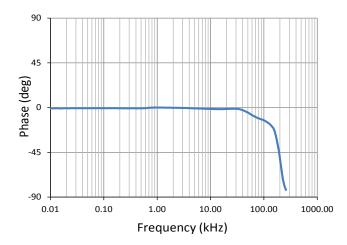
What is the noise from 1 to  $10^6$  Hz? Figure 4 gives  $I_{\rm no}$  (1 Hz) = 0.5 mA and  $I_{\rm no}$  (10 $^6$  Hz) = 199 mA. The output current noise (RMS) is therefore:

$$\sqrt{(199 \times 10^{-3})^2 - (0.5 \times 10^{-3})^2}$$
 = 199 mA referred to primary



# Typical performance characteristics





Figures 5 and 6: Typical frequency response, small signal bandwidth

### Performance parameters definition

## **Sensitivity and linearity**

To measure sensitivity and linearity, the primary current (DC) is cycled from 0 to  $I_{\rm PM}$ , then to  $-I_{\rm PM}$  and back to 0 (equally spaced  $I_{\rm PM}/10$  steps).

The sensitivity S is defined as the slope of the linear regression line for a cycle between  $\pm I_{\rm P\,M}$ .

The linearity error  $\varepsilon_{\rm L}$  is the maximum positive or negative difference between the measured points and the linear regression line, expressed in % of the maximum measured value.

#### **Magnetic offset**

The magnetic offset  $I_{\rm O~M}$  is the change of offset after a given current has been applied to the input. It is included in the linearity error as long as the transducer remains in its measuring range.

#### **Electrical offset**

The electrical offset current  $I_{\rm O\;E}$  is the residual output current when the input current is zero.

#### **Total error**

The total error  $\varepsilon_{\rm tot}$  is the error at  $\pm I_{\rm P\,N}$ , relative to the rated value  $I_{\rm P\,N}$ .

It includes all errors mentioned above.

#### **Delay times**

The delay time  $t_{\rm D\,10}$  @ 10 % and the delay time  $t_{\rm D\,90}$  @ 90 % with respect to the primary are shown in the next figure.

Both slightly depend on the primary current di/dt. They are measured at nominal current.

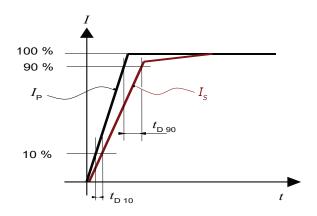
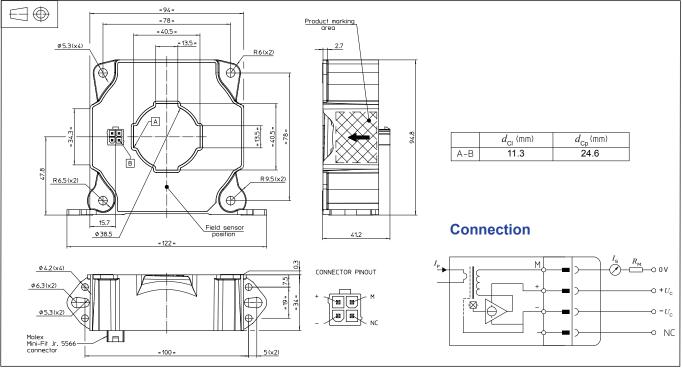


Figure 7:  $t_{\rm D\,10}$  (delay time @ 10 %) and  $t_{\rm D\,90}$  (delay time @ 90 %)



### **Dimensions (in mm)**

# LF 1010-S/SPA2



#### **Mechanical characteristics**

<ul> <li>General tol</li> </ul>	lerance
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 Transducer fastening Vertical position

Recommended fastening torque Or

Recommended fastening torque

Recommended fastening torque

Primary through-hole
 Or

Transducer fastening Horizontal position

Recommended fastening torque

Connection of secondary

#### ±0.5 mm

2 holes  $\varnothing$  5.3 mm 2 M5 steel screws 3.2 N·m ( $\pm$ 10 %) 4 holes  $\varnothing$  4.2 mm 4 M4 steel screws 2.1 N·m ( $\pm$ 10 %) 2 M6 steel screws 4.5 N·m ( $\pm$ 10 %)  $\varnothing$  38 mm 40 mm  $\times$  13 mm

4 holes Ø 5.3 mm 4 M5 steel screws 3.2 N·m (±10 %) Molex Mini-Fit Jr 5566 gold plated pin

## Safety

This transducer must be used in limited-energy secondary circuits according to IEC 61010-1.



This transducer must be used in electric/electronic equipment with respect to applicable standards and safety requirements in accordance with the manufacturer's operating instructions.



Caution, risk of electrical shock

When operating the transducer, certain parts of the module can carry hazardous voltage (eg. primary connection, power supply).

Ignoring this warning can lead to injury and/or cause serious damage.

This transducer is a build-in device, whose conducting parts must be inaccessible after installation.

A protective housing or additional shield could be used. Main supply must be able to be disconnected.

Note: Additional information avaible on request.

#### **Remarks**

- $I_s$  is positive when  $I_p$  flows in the direction of arrow.
- The secondary cables also have to be routed together all the way.
- Installation of the transducer is to be done without primary current or secondary voltage present.
- Maximum temperature of primary conductor: see page 2.
- Installation of the transducer must be done, unless otherwise specified on the datasheet, according to LEM Transducer Generic Mounting Rules. Please refer to LEM document N°ANE120504 available on our Web site: https://www.lem.com/en/file/3137/download/.

# 单击下面可查看定价,库存,交付和生命周期等信息

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