

# **High-Voltage Input Integrated Switch Step-Down Regulator**

#### <span id="page-0-0"></span>**Features**

- Up to 96% Typical Efficiency
- Input Voltage Range:
	- 4.0V to 30V (**MCP16301**)
	- 4.7V to 36V (**MCP16301H**)
- Output Voltage Range: 2.0V to 15V
- 2% Output Voltage Accuracy
- Passes Automotive AEC-Q100 Reliability Testing
- Integrated N-Channel Buck Switch: 460 m $\Omega$
- Minimum 600 mA Output Current Over All Input Voltage Range (See [Figure 2-6](#page-4-0) for Maximum Output Current vs.  $V_{IN}$ :
	- Up to 1A output current at 3.3V, 5V and 12V  $V_{\text{OUT}}$ , SOT-23 package at +25°C ambient temperature
- 500 kHz Fixed Frequency
- Adjustable Output Voltage
- Low Device Shutdown Current
- Peak Current Mode Control
- Internal Soft-Start
- Internal Compensation
- Stable with Ceramic Capacitors
- Cycle-by-Cycle Peak Current Limit
- Undervoltage Lockout (UVLO): 3.5V
- Overtemperature Protection
- Available Package: SOT-23-6

#### **Applications**

- $\text{PIC}^{\circledR}$  Microcontroller and dsPIC $^{\circledR}$  Digital Signal Controller Bias Supply
- 24V Industrial Input DC-DC Conversion
- Set-Top Boxes
- DSL Cable Modems
- Automotive
- Wall Cube Regulation
- SLA Battery-Powered Devices
- AC-DC Digital Control Power Source
- Power Meters
- $D^2$  Package Linear Regulator Replacement
- See [Figure 5-2](#page-21-0)
- Consumer
- Medical and Health Care
- Distributed Power Supplies

#### <span id="page-0-1"></span>**General Description**

The MCP16301/H devices are highly integrated, high-efficiency, fixed-frequency, step-down DC-DC converters in a popular 6-pin SOT-23 package, that operate from input voltage sources up to 36V. Integrated features include a high-side switch, fixed-frequency peak current mode control, internal compensation, peak current limit and overtemperature protection. Only a few external components are necessary to develop a complete step-down DC-DC converter power supply.

High converter efficiency is achieved by integrating the current-limited, low-resistance, high-speed N-Channel MOSFET and associated drive circuitry. High switching frequency minimizes the size of external filtering components, resulting in a small solution size.

The MCP16301/H devices can supply 600 mA of continuous current while regulating the output voltage from 2.0V to 15V. An integrated, high-performance peak current mode architecture keeps the output voltage tightly regulated, even during input voltage steps and output current transient conditions that are common in power systems.

The EN input is used to turn the device on and off. While turned off, only a few micro amps of current are consumed from the input for power shedding and load distribution applications.

Output voltage is set with an external resistor divider. The MCP16301/H devices are offered in a space-saving SOT-23-6 surface mount package.

### **Package Type**



# <span id="page-1-0"></span>**Typical Applications**



# **1.0 ELECTRICAL CHARACTERISTICS**

# **Absolute Maximum Ratings †**



**† Notice:** Stresses above those listed under "Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operational sections of this specification is not intended. Exposure to maximum rating conditions for extended periods may affect device reliability.

# **DC CHARACTERISTICS**

**Electrical Characteristics:** Unless otherwise indicated,  $T_A = +25^{\circ}C$ ,  $V_{IN} = V_{EN} = 12V$ ,  $V_{BOOST} - V_{SW} = 3.3V$ ,  $V_{\text{OUT}} = 3.3V$ ,  $I_{\text{OUT}} = 100 \text{ mA}$ , L = 15 µH,  $C_{\text{OUT}} = C_{\text{IN}} = 2 \times 10 \text{ pF}$  X7R ceramic capacitors. **Boldface** specifications apply over the  $T_A$  range of -40<sup>o</sup>C to +125<sup>o</sup>C.



<span id="page-2-0"></span>**Note 1:** The input voltage should be > output voltage + headroom voltage; higher load currents increase the input voltage necessary for regulation. See characterization graphs for typical input to output operating voltage range and UVLO<sub>START</sub> and UVLO<sub>STOP</sub> limits.

<span id="page-2-1"></span>**2:** For  $V_{IN} < V_{OUT}$ ,  $V_{OUT}$  will not remain in regulation.

<span id="page-2-2"></span>**3:**  $V_{\text{BOOST}}$  supply is derived from  $V_{\text{OUT}}$ .

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# **DC CHARACTERISTICS (CONTINUED)**

**Electrical Characteristics:** Unless otherwise indicated,  $T_A = +25^{\circ}C$ ,  $V_{IN} = V_{EN} = 12V$ ,  $V_{BOOST} - V_{SW} = 3.3V$ ,  $V_{\text{OUT}} = 3.3V$ ,  $I_{\text{OUT}} = 100 \text{ mA}$ , L = 15 µH,  $C_{\text{OUT}} = C_{\text{IN}} = 2 \times 10 \text{ pF}$  X7R ceramic capacitors. **Boldface** specifications apply over the  $T_A$  range of -40<sup>o</sup>C to +125<sup>o</sup>C.



Note 1: The input voltage should be > output voltage + headroom voltage; higher load currents increase the input voltage necessary for regulation. See characterization graphs for typical input to output operating voltage range and UVLO<sub>START</sub> and UVLO<sub>STOP</sub> limits.

**2:** For  $V_{IN} < V_{OUT}$ ,  $V_{OUT}$  will not remain in regulation.

**3:** V<sub>BOOST</sub> supply is derived from V<sub>OUT</sub>.

# **TEMPERATURE SPECIFICATIONS**

**Electrical Specifications:** Unless otherwise indicated,  $T_A = +25^{\circ}C$ ,  $V_{IN} = V_{EN} = 12V$ ,  $V_{BOOST} - V_{SW} = 3.3V$ ,  $V_{OUT}$  = 3.3V



# **2.0 TYPICAL PERFORMANCE CURVES**

**Note:** The graphs and tables provided following this note are a statistical summary based on a limited number of samples and are provided for informational purposes only. The performance characteristics listed herein are not tested or guaranteed. In some graphs or tables, the data presented may be outside the specified operating range (e.g., outside specified power supply range) and therefore outside the warranted range.

**Note:** Unless otherwise indicated,  $V_{IN} = EN = 12V$ ,  $C_{OUT} = C_{IN} = 2 \times 10 \mu F$ , L = 15  $\mu H$ ,  $V_{OUT} = 3.3V$ ,  $I_{LOAD} = 200 \mu F$ ,  $T_A = +25$ °C.

<span id="page-4-1"></span><span id="page-4-0"></span>

**Note:** Unless otherwise indicated,  $V_{IN} = EN = 12V$ ,  $C_{OUT} = C_{IN} = 2 \times 10 \mu F$ , L = 15  $\mu H$ ,  $V_{OUT} = 3.3V$ ,  $I_{LOAD} = 200 \mu F$ ,  $T_A = +25$ °C.





<span id="page-5-0"></span>





<span id="page-5-1"></span>*FIGURE 2-8: Switching Frequency vs. Temperature;*  $V_{OUT} = 3.3V$ .



<span id="page-5-2"></span>*FIGURE 2-9: Maximum Duty Cycle vs. Ambient Temperature; V<sub>OUT</sub> = 5.0V.* 



<span id="page-5-3"></span>*FIGURE 2-10: Peak Current Limit vs. Temperature;*  $V_{OUT} = 3.3V$ .



*FIGURE 2-11: Switch R<sub>DSON</sub> vs. V<sub>BOOST.</sub>* 



<span id="page-5-4"></span>**FIGURE 2-12:** *V<sub>FB</sub> vs. Temperature;*  $V_{OUT} = 3.3V$ .

**Note:** Unless otherwise indicated,  $V_{IN}$  = EN = 12V,  $C_{OUT}$  =  $C_{IN}$  = 2 X 10  $\mu$ F, L = 15  $\mu$ H,  $V_{OUT}$  = 3.3V,  $I_{LOAD}$  = 200 mA,  $T_A = +25$ °C.



<span id="page-6-1"></span>*Temperature.*



<span id="page-6-2"></span>*FIGURE 2-14: EN Threshold Voltage vs. Temperature.*



*Waveforms.*

*FIGURE 2-15: Light Load Switching* 



*FIGURE 2-16: Heavy Load Switching Waveforms.*



<span id="page-6-0"></span>*FIGURE 2-17: Typical Minimum Input Voltage vs. Output Current.*



*FIGURE 2-18: Start-Up From Enable.*

**Note:** Unless otherwise indicated,  $V_{IN} = EN = 12V$ ,  $C_{OUT} = C_{IN} = 2 \times 10 \mu F$ , L = 15  $\mu H$ ,  $V_{OUT} = 3.3V$ ,  $I_{LOAD} = 200 \mu F$ ,  $T_A = +25$ °C.



*FIGURE 2-19: Start-Up from V<sub>IN.</sub>* 



*FIGURE 2-20: Load Transient Response.*



*FIGURE 2-21: Line Transient Response.*

# <span id="page-8-1"></span>**3.0 PIN DESCRIPTIONS**

The descriptions of the pins are listed in [Table 3-1.](#page-8-0)



#### <span id="page-8-0"></span>**TABLE 3-1: PIN FUNCTION TABLE**

# **3.1 Boost Pin (BOOST)**

The high side of the floating supply, used to turn the integrated N-Channel MOSFET on and off, is connected to the boost pin.

# **3.2 Ground Pin (GND)**

The ground or return pin is used for circuit ground connection. The length of the trace from the input capacitor return, output capacitor return and GND pin should be made as short as possible, in order to minimize the noise on the GND pin.

# **3.3** Feedback Voltage Pin (V<sub>FB</sub>)

The  $V_{FB}$  pin is used to provide output voltage regulation by using a resistor divider. The  $V_{FB}$  voltage will be 0.800V typical, with the output voltage in regulation.

# **3.4 Enable Pin (EN)**

The EN pin is a logic-level input used to enable or disable device switching and to lower the quiescent current while disabled. A logic high (> 1.4V) will enable the regulator's output; a logic low (< 0.4V) will ensure that the regulator is disabled.

# **3.5 Power Supply Input Voltage Pin (VIN)**

Connect the input voltage source to  $V_{IN}$ . The input source should be decoupled to GND with a 4.7 µF (up to 20 µF) capacitor, depending on the impedance of the source and the output current. The input capacitor provides AC current for the power switch and a stable voltage source for the internal device power. This capacitor should be connected as close as possible to the  $V_{IN}$  and GND pins. For light load applications, a 1 µF X7R (or X5R, for limited temperature range, -40 to +85°C) ceramic capacitor can be used.

# **3.6 Switch Pin (SW)**

The Switch Node pin is connected internally to the N-Channel switch and externally to the SW node consisting of the inductor and Schottky diode. The SW node can rise very fast, as a result of the internal switch turning on. The external Schottky diode should be connected close to the SW node and GND.

**NOTES:**

# <span id="page-10-0"></span>**4.0 DETAILED DESCRIPTION**

### **4.1 Device Overview**

The MCP16301/H devices are high-input voltage step-down regulators, capable of supplying 600 mA to a regulated output voltage from 2.0V to 15V. Internally, the trimmed 500 kHz oscillator provides a fixed frequency, while the peak current mode control architecture varies the duty cycle for output voltage regulation. An internal floating driver is used to turn the high-side integrated N-Channel MOSFET on and off. The power for this driver is derived from an external boost capacitor whose energy is supplied from a fixed voltage ranging from 3.0V to 5.5V, typically the input or output voltage of the converter. For applications with an output voltage outside of this range, such as 12V, the boost capacitor bias can be derived from the output, using a simple Zener diode regulator.

#### 4.1.1 INTERNAL REFERENCE VOLTAGE  $(V_{RFF})$

An integrated precise 0.8V reference combined with an external resistor divider sets the desired converter's output voltage. The resistor divider range can vary without affecting the control system gain. High-value resistors consume less current, but are more susceptible to noise.

#### 4.1.2 INTERNAL COMPENSATION

All control system components necessary for stable operation over the entire device operating range are integrated, including the error amplifier and inductor current slope compensation. To add the proper amount of slope compensation, the inductor value changes along with the output voltage (see [Table 5-1\)](#page-16-0).

### 4.1.3 EXTERNAL COMPONENTS

External components consist of:

- input capacitor
- output filter (inductor and capacitor)
- freewheeling diode
- boost capacitor
- boost blocking diode
- resistor divider

The selection of the external inductor, output capacitor, input capacitor and freewheeling diode is dependent upon the output voltage and the maximum output current.

#### 4.1.4 ENABLE INPUT

Enable input (EN), is used to enable and disable the device. If disabled, the MCP16301/H devices consume a minimal amount of current from the input. Once enabled, the internal soft start controls the output voltage rate of rise, preventing high-inrush current and output voltage overshoot.

### 4.1.5 SOFT START

The internal reference voltage rate of rise is controlled during start-up, minimizing the output voltage overshoot and the inrush current.

### 4.1.6 UNDERVOLTAGE LOCKOUT

An integrated Undervoltage Lockout (UVLO) prevents the converter from starting until the input voltage is high enough for normal operation. The converter will typically start at 3.5V and operate down to 3.0V. Hysteresis is added to prevent starting and stopping during start-up, as a result of loading the input voltage source.

#### 4.1.7 OVERTEMPERATURE **PROTECTION**

Overtemperature protection limits the silicon die temperature to +150°C by turning the converter off. The normal switching resumes at +120°C.

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<span id="page-11-0"></span>*FIGURE 4-1: MCP16301/H Block Diagram.*

# **4.2 Functional Description**

#### 4.2.1 STEP-DOWN OR BUCK **CONVERTER**

The MCP16301/H devices are non-synchronous step-down or buck converters, capable of stepping input voltages ranging from 4V to 30V (MCP16301) or 36V (MCP16301H) down to 2.0V to 15V, for  $V_{IN}$  >  $V_{OUT}$ .

The integrated high-side switch is used to chop or modulate the input voltage using a controlled duty cycle for output voltage regulation. High efficiency is achieved by using low-resistance integrated switch, low forward drop diode (Schottky rectifier), low equivalent series resistance (ESR) capacitors and low DC impedance (DCR) inductor. When the switch is turned on, a DC voltage is applied to the inductor  $(V_{IN} - V_{OUT})$ , resulting in a positive linear ramp of inductor current. When the switch turns off, the applied inductor voltage is equal to - $V_{\text{OUT}}$ , resulting in a negative linear ramp of inductor current (ignoring the forward drop of the Schottky diode).

For steady-state, continuous inductor current operation, the positive inductor current slope must be identical to the negative current slope. While operating in steady state, the switch duty cycle must be equal to the relationship of  $V_{\text{OUT}}/V_{\text{IN}}$  for constant output voltage regulation, under the condition that the inductor current is continuous or never reaches zero. For discontinuous inductor current operation, the steady-state duty cycle will be less than  $V_{\text{OUT}}/V_{\text{IN}}$  to maintain voltage regulation. The average of the chopped input voltage or SW node voltage is equal to the output voltage, while the average of the inductor current is equal to the output current.



### 4.2.2 PEAK CURRENT MODE CONTROL

The MCP16301/H devices integrate a Peak Current Mode Control architecture, resulting in superior AC regulation while minimizing the number of voltage loop compensation components and their size, for integration. Peak Current Mode Control takes a small portion of the inductor current, replicates it, and compares this replicated current sense signal to the output of the integrated error voltage. In practice, the inductor current and the internal switch current are equal during the switch-on time. By adding this peak current sense to the system control, the step-down power train system is reduced from a 2<sup>nd</sup> order to a 1<sup>st</sup> order. This reduces the system complexity and increases its dynamic performance.

For Pulse-Width Modulation (PWM) duty cycles that exceed 50%, the control system can become bimodal where a wide pulse followed by a short pulse repeats instead of the desired fixed pulse width. To prevent this mode of operation, an internal compensating ramp is added to the current information, as shown in [Figure 4-1.](#page-11-0)

#### 4.2.3 PULSE-WIDTH MODULATION (PWM)

The internal oscillator periodically starts the switching period, which, for MCP16301, occurs every 2 µs (or with a frequency of 500 kHz). With the integrated switch turned on, the inductor current ramps up until the sum of the current sense and slope compensation ramp exceeds the integrated error amplifier output. The error amplifier output slews up or down to increase or decrease the inductor peak current feeding into the output LC filter. If the regulated output voltage is lower than its target, the inverting error amplifier output rises. This results in an increase in the inductor current to correct the errors in the output voltage.

The fixed-frequency duty cycle is terminated when the sensed inductor peak current, summed with the internal slope compensation, exceeds the output voltage of the error amplifier. The PWM latch is reset by turning off the internal switch and prevents it from turning on until the beginning of the next cycle. An overtemperature signal, or boost capacitor undervoltage, can also reset the PWM latch to asynchronously terminate the cycle.

#### 4.2.4 HIGH-SIDE DRIVE

The MCP16301/H devices feature an integrated high-side N-Channel MOSFET for high-efficiency step-down power conversion; an N-Channel MOSFET is preferred for its low resistance and size (instead of a P-Channel MOSFET). The N-Channel MOSFET gate must be driven above its source to fully turn on the transistor. Therefore, a gate-drive voltage above the input is necessary to turn on the high-side N-Channel. The high-side drive voltage should be between 3.0V and 5.5V; the N-Channel source is connected to the inductor and Schottky diode, or switch node.

When the switch is off, the inductor current flows through the Schottky diode, providing a path to recharge the boost capacitor from the boost voltage source: typically, the output voltage for 3.0V to 5.0V output applications. A boost-blocking diode is used to prevent current flow from the boost capacitor back into the output during the internal switch-on time. Prior to start-up, the boost cap has no stored charge to drive the switch; an internal regulator is used to precharge the boost cap.

Once precharged, the switch is turned on and the inductor current flows. When the switch turns off, the inductor current free-wheels through the Schottky diode, providing a path to recharge the boost capacitor. Worst-case conditions for recharge occur when the switch turns on for a very short duty cycle at light load, limiting the inductor current ramp. In this case, there is a small amount of time for the boost capacitor to recharge. For high input voltages there is enough precharge current to replenish the boost capacitor charge. For input voltages above 5.5V typical, the MCP16301/ H devices will regulate the output voltage with no load. After starting, the MCP16301/H devices will regulate the output voltage until the input voltage decreases below 4V. See [Figure 2-17](#page-6-0) for device range of operation over input voltage, output voltage and load.

### 4.2.5 ALTERNATIVE BOOST BIAS

For 3.0V to 5.0V output voltage applications, the boost supply is typically the output voltage. For applications with the output voltage lower than 3V or higher than 5V, an alternative boost supply can be used.

Alternative boost supplies can be directly used from the input, input derived, output derived or an auxiliary system voltage.

For low voltage output applications with unregulated input voltage, a shunt regulator derived from the input can be used to obtain the boost supply. For applications with high output voltage or regulated high input voltage, a series regulator can be used to derive the boost supply.



<span id="page-13-0"></span>*FIGURE 4-3: MCP16301/H Shunt and External Boost Supply.*

Shunt Boost Supply Regulation is used for low-output voltage converters operating from a wide ranging input source. A regulated 3.0V to 5.5V supply is needed to provide high-side drive bias. The shunt uses a Zener diode to clamp the voltage within the 3.0V to 5.5V range using the  $R_{SH}$  resistor shown in [Figure 4-3](#page-13-0).

To calculate the  $R_{SH}$  resistor value, the boost drive current needs to be estimated first using [Equation 4-1](#page-13-1).  $I_{\text{BOOST~TYP}}$  for 3.3V Boost Supply = 0.6 mA  $I_{\text{BOOST}}$  Typ for 5.0V Boost Supply = 0.8 mA

### <span id="page-13-1"></span>**EQUATION 4-1: BOOST CURRENT**

 $I_{\text{BOOST}} = I_{\text{BOOST\_TYP}} \times 1.5 \text{ mA}$ 

To calculate the  $R_{SH}$  resistor value, the maximum  $I_{\text{BOOST}}$  and  $I_{\text{Z}}$  currents are used at the minimum input voltage [\(Equation 4-2](#page-14-0)).

<span id="page-14-0"></span>

$$
R_{SH} = \frac{V_{INMIN} - V_Z}{I_{Boost} + I_Z}
$$

 $V_Z$  and  $I_Z$  can be found on the Zener diode manufacturer's data sheet. Typically,  $I_z = 1$  mA.

Series regulator applications use a Zener diode to drop the excess voltage. The series regulator bias source can be input or output voltage derived, as shown in [Figure 4-4.](#page-14-1) For proper circuit operation, the boost supply must remain between 3.0V and 5.5V at all times.



<span id="page-14-1"></span>*FIGURE 4-4: MCP16301/H Series Regulator Boost Supply.*

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**NOTES:**

# <span id="page-16-5"></span>**5.0 APPLICATION INFORMATION**

# **5.1 Typical Applications**

The MCP16301/H step-down converters operate over a wide input voltage range, up to 36V maximum. Typical applications include generating a bias or  $V_{DD}$ voltage for the PIC<sup>®</sup> microcontroller product line, digital control system bias supply for AC-DC converters, 24V industrial input and similar applications.

# **5.2 Adjustable Output Voltage Calculations**

To calculate the resistor divider values for the MCP16301/H devices, [Equation 5-1](#page-16-1) can be used.  $R_{\text{TOP}}$  is connected to  $V_{\text{OUT}}$ ,  $R_{\text{BOT}}$  is connected to GND and both are connected to the  $V_{FB}$  input pin.

#### <span id="page-16-1"></span>**EQUATION 5-1:**

<span id="page-16-3"></span>
$$
R_{TOP} = R_{BOT} \times \left(\frac{V_{OUT}}{V_{FB}} - 1\right)
$$

### **EXAMPLE 5-1:**



### **EXAMPLE 5-2:**

<span id="page-16-4"></span>

The transconductance error amplifier gain is controlled by its internal impedance. The external resistor dividers have no effect on system gain, so a wide range of values can be used. A 10  $k\Omega$  bottom resistor is recommended as a good trade-off for quiescent current and noise immunity.

# **5.3 General Design Equations**

The step-down converter duty cycle can be estimated using [Equation 5-2](#page-16-2) while operating in Continuous Inductor Current mode. This equation also counts the forward drop of the freewheeling diode and internal N-Channel MOSFET switch voltage drop. As the load current increases, the switch voltage drop and diode voltage drop increase, requiring a larger PWM duty cycle to maintain the output voltage regulation. Switch voltage drop is estimated by multiplying the switch current times the switch resistance (or  $R_{DSON}$ ).

#### <span id="page-16-2"></span>**EQUATION 5-2: CONTINUOUS INDUCTOR CURRENT DUTY CYCLE**

$$
D = \frac{(V_{OUT} + V_{Diode})}{(V_{IN} - (I_{SW} \times R_{DSON}))}
$$

The MCP16301/H devices feature an integrated slope compensation to prevent the bimodal operation of the PWM duty cycle. Internally, half of the inductor current down slope is summed with the internal current sense signal. For the proper amount of slope compensation, it is recommended to keep the inductor down-slope current constant by varying the inductance with  $V_{\text{OUT}}$ , where  $K = 0.22V/\mu H$ .

### **EQUATION 5-3:**

$$
K = V_{OUT}/L
$$

For  $V_{\text{OUT}} = 3.3V$ , an inductance of 15 µH is recommended.

<span id="page-16-0"></span>



# **5.4 Input Capacitor Selection**

The input capacitor of the step-down converter must filter the high input ripple current as a result of pulsing or chopping the input voltage. The input voltage pin of the MCP16301/H devices is used to supply voltage for the power train and as a source for internal bias. A low equivalent series resistance (ESR), preferably a ceramic capacitor, is recommended. The necessary capacitance is dependent upon the maximum load current and source impedance. Three capacitor parameters to keep in mind are the voltage rating, equivalent series resistance and the temperature rating. For wide temperature range applications, a multi-layer X7R dielectric is mandatory, while for applications with limited temperature range, a multi-layer X5R dielectric is acceptable. Typically, input capacitance between 4.7 µF and 10 µF is sufficient for most applications. For applications with 100 mA to 200 mA load, a 1 µF X7R capacitor can be used, depending on the input source and its impedance.

The input capacitor voltage rating should be a minimum of  $V_{1N}$  plus margin. [Table 5-2](#page-17-0) contains the recommended range for the input capacitor value.

# **5.5 Output Capacitor Selection**

The output capacitor helps in providing a stable output voltage during sudden load transients, and reduces the output voltage ripple. As with the input capacitor, X5R and X7R ceramic capacitors are well suited for this application.

The output capacitor value, type and equivalent series resistance will have a significant effect on the output ripple voltage and system stability. The range of the output capacitance is limited due to the integrated compensation of the MCP16301/H devices.

The output capacitor voltage rating should be a minimum of  $V_{\text{OUT}}$  plus margin. [Table 5-2](#page-17-0) contains the recommended range for the input and output capacitor value:

<span id="page-17-0"></span>



#### **5.6 Inductor Selection**

The MCP16301/H devices are designed to be used with small surface mount (SMT/SMD) inductors. Several specifications should be considered prior to selecting an inductor. To optimize system performance, the inductance value is determined based on the output voltage [\(Table 5-1](#page-16-0)), so the inductor ripple current is somehow constant over the output voltage range and can be calculated using [Equation 5-4](#page-17-1).

#### <span id="page-17-1"></span>**EQUATION 5-4: INDUCTOR RIPPLE CURRENT**

$$
\varDelta_{I_L} = \frac{V_{IN} - V_{OUT}}{L} \times t_{ON}
$$

**EXAMPLE 5-3:**

 $V_{IN}$  = 12V  $V_{OUT}$  = 3.3V  $I_{\text{OUT}}$  = 600 mA

Based on the inductor ripple current, the inductor peak current can be calculated using [Equation 5-5.](#page-17-2)

<span id="page-17-2"></span>

$$
I_{LPK} = \frac{\varDelta I_L}{2} + I_{OUT}
$$

Inductor ripple current = 319 mA Inductor peak current = 760 mA

In case of the aforementioned example, an inductor saturation rating higher than 760 mA is recommended. Low DCR inductors result in higher system efficiency. A trade-off between size, cost and efficiency should be made to achieve the desired results.

**TABLE 5-3: MCP16301/H RECOMMENDED 3.3V INDUCTORS**

<b>Part Number</b>	Value Ĵ	DCR(Q)	$I_{SAT}(A)$	<b>Size</b> WxLxH (mm)
Coilcraft <sup>®</sup>				
ME3220-153	15	0.52	0.90	3.2x2.5x2.0
LPS4414-153	15	0.440	0.92	4.3x4.3x1.4
LPS6235-153	15	0.125	2.00	6.0x6.0x3.5
MSS6132-153	15	0.135	1.56	6.1x6.1x3.2
MSS7341-153	15	0.057	1.78	7.3x7.3x4.1
ME3220-153	15	0.520	0.8	2.8x3.2x2.0
LPS3015-153	15	0.700	0.61	3.0x3.0x1.4
Würth Elektronik Group®				
74408942150	15	0.245	1.6	4.8x4.8x2.8
74438356150	15	0.230	2.1	4.1x4.1x2.1
74437324150	15	0.375	2.1	4.06x4.45x1.8
744025150	15	0.400	0.900	2.8x2.8x2.8
744031150	15	0.255	0.450	3.8x3.8x1.65
744042150	15	0.175	0.75	4.8x4.8x1.8
<b>TDK-EPCOS®</b>				
VLS3012HBX-150M	15	0.636	1.52	3.0x3.0x1.2
VLS3015CX-150M-H	15	0.428	0.57	3.0x3.0x1.5
VLS5045EX-150M	15	0.143	2.2	5.0x5.0x4.5
B82462G4153M000	15	0.097	1.05	6.0x6.0x2.2
Eaton				
SD12-150-R	15	0.48	0.692	5.2x5.2x1.2
SD18-150-R	15	0.266	0.831	5.2x5.2x1.8
SD20-150-R	15	0.193	0.718	5.2x5.2x2.0
SD3118-150-R	15	0.51	0.75	3.2x3.2x1.8
SD52-150-R	15	0.189	0.88	5.2x5.5.2.0
Sumida <sup>®</sup> Corporation				
CDPH4D19F	15	0.075	0.66	5.2x5.2x2.0
CDRH3D28	15	0.170	0.9	4.0x4.0x3.0

# **5.7 Freewheeling Diode**

The freewheeling diode creates a path for inductor current flow after the internal switch is turned off. The average diode current is dependent upon output load current at duty cycle (D). The efficiency of the converter is a function of the forward drop and speed of the freewheeling diode. A low forward drop Schottky diode is recommended. The current rating and voltage rating of the diode are application dependent. The diode voltage rating should be a higher than  $V_{IN}$  plus margin. For example, a diode rating of 40V should be used for an application with a maximum input of 30V. The average diode current can be calculated using [Equation 5-6.](#page-18-0)

### <span id="page-18-0"></span>**EQUATION 5-6: DIODE AVERAGE CURRENT**



#### **EXAMPLE 5-4:**



A 0.5A to 1A diode is recommended and a list of recommended freewheeling diodes is shown is [Table 5-4,](#page-18-1) below.

<span id="page-18-1"></span>



### **5.8 Boost Diode**

The boost diode is used to provide a charging path from the low-voltage gate drive source, while the switch node is low. The boost diode blocks the high voltage of the switch node from feeding back into the output voltage when the switch is turned on, forcing the switch node high.

A standard 1N4148 ultra-fast diode is recommended for its recovery speed, high voltage blocking capability, availability and cost. The voltage rating required for the boost diode is  $V_{IN}$ .

For low boost voltage applications, a small Schottky diode with the appropriately rated voltage can be used to lower the forward drop, while increasing the boost supply for gate drive.

# **5.9 Boost Capacitor**

The boost capacitor is used to supply current for the internal high-side drive circuitry that is above the input voltage. The boost capacitor must store enough energy to completely drive the high-side switch on and off. A 0.1 µF X5R or X7R capacitor is recommended for all applications. The boost capacitor maximum voltage is 5.5V, so a 6.3V or 10V rated capacitor is recommended. In case of a noise-sensitive application, an additional resistor, connected in series with the boost capacitor, that will reduce the high-frequency noise associated with switching power supplies, can be added. A typical value for the resistor is  $82\Omega$ .

# **5.10 Thermal Calculations**

The MCP16301/H devices are available in a SOT-23-6 package. By calculating the power dissipation and applying the package thermal resistance  $(\theta_{JA})$ , the junction temperature is estimated. The maximum continuous junction temperature rating for the MCP16301/H devices is +125°C.

To quickly estimate the internal power dissipation for the step-down switching regulator, an empirical calculation using measured efficiency can be used. Given the measured efficiency, the internal power dissipation is estimated by [Equation 5-7](#page-19-0). This power dissipation includes all internal and external component losses. For a quick internal estimate, subtract the estimated Schottky diode loss and inductor DCR loss from the  $P_{DIS}$  calculation in [Equation 5-7.](#page-19-0)

#### <span id="page-19-0"></span>**EQUATION 5-7: TOTAL POWER DISSIPATION ESTIMATE**



The difference between the first term, input power, and the second term, power delivered, is the total system power dissipation. The freewheeling Schottky diode losses are determined by calculating the average diode current and multiplying it by the diode forward drop. The inductor losses are estimated by  $P_L = I_{OUT}^2 \times L_{DCR}$ .

# **EQUATION 5-8: DIODE POWER DISSIPATION ESTIMATE**

$$
P_{Diode} = V_F \times ((1 - D) \times I_{OUT})
$$

### **EXAMPLE 5-5:**



# **5.11 PCB Layout Information**

Good printed circuit board layout techniques are important to any switching circuitry, and switching power supplies are no different. When wiring the switching high-current paths, short and wide traces should be used. Therefore, it is important that the input and output capacitors should be placed as close as possible to the MCP16301/H devices, to minimize the loop area.

The feedback resistors and feedback signal should be routed away from the switching node and the switching current loop. When possible, ground planes and traces should be used to help shield the feedback signal and minimize noise and magnetic interference.

A good MCP16301/H layout starts with  $C_{1N}$  placement.  $C_{1N}$  supplies current to the input of the circuit when the switch is turned on. In addition to supplying high-frequency switch current,  $C_{IN}$  also provides a stable voltage source for the internal MCP16301/H circuitry. Unstable PWM operation can result if there are excessive transients or ringing on the  $V_{1N}$  pin of the MCP16301/H devices. In [Figure 5-1](#page-20-0),  $C_{IN}$  is placed close to pin 5. A ground plane on the bottom of the board provides a low resistive and inductive path for the return current. The next priority in placement is the freewheeling current loop formed by D1,  $C<sub>OUT</sub>$  and L, while strategically placing  $C_{OUT}$  return close to  $C_{IN}$ return. Next,  $C_B$  and  $D_B$  should be placed between the boost pin and the switch node pin, SW. This leaves space close to the  $V_{FB}$  pin of the MCP16301/H devices to place  $R_{\text{TOP}}$  and  $R_{\text{BOT}}$ .  $R_{\text{TOP}}$  and  $R_{\text{BOT}}$  are routed away from the switch node, so noise is not coupled into the high-impedance  $V_{FB}$  input.



<span id="page-20-1"></span><span id="page-20-0"></span>*FIGURE 5-1: MCP16301/H SOT-23-6 Recommended Layout, 600 mA Design.*

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<span id="page-21-1"></span><span id="page-21-0"></span>*FIGURE 5-2: MCP16301/H SOT-23-6 Recommended Layout, 200 mA Design.*

# <span id="page-22-1"></span>**6.0 TYPICAL APPLICATION CIRCUITS**



<span id="page-22-0"></span>

**FIGURE 6-1:** *Typical Application 6V – 30V V<sub>IN</sub> to 3.3V V<sub>OUT</sub>.* 

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*FIGURE 6-2: Typical Application 15V – 30V Input; 12V Output.*



*FIGURE 6-3: Typical Application 12V Input; 2V Output at 600 mA.*



**FIGURE 6-4:** *Typical Application 10V to 16V V<sub>IN</sub> to 2.5V V<sub>OUT</sub>.* 



<span id="page-26-0"></span>

**FIGURE 6-5:** *Typical Application 4V to 30V V<sub>IN</sub> to 3.3V V<sub>OUT</sub> at 150 mA.* 

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**NOTES:**

# <span id="page-28-0"></span>**7.0 PACKAGING INFORMATION**

# **7.1 Package Marking Information**









# **6-Lead Plastic Small Outline Transistor (CH, CHY) [SOT-23]**

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging **Note:**



Microchip Technology Drawing C04-028C (CH) Sheet 1 of 2

# **6-Lead Plastic Small Outline Transistor (CH, CHY) [SOT-23]**

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging **Note:**





Notes:

protrusions shall not exceed 0.25mm per side. 1. Dimensions D and E1 do not include mold flash or protrusions. Mold flash or

2. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-028C (CH) Sheet 2 of 2

# **6-Lead Plastic Small Outline Transistor (CH, CHY) [SOT-23]**

For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging **Note:**



### RECOMMENDED LAND PATTERN



#### Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2028B (CH)

# **APPENDIX A: REVISION HISTORY**

# **Revision E (January 2021)**

The following is the list of modifications:

- 1. Added AEC-Q100 Qualification.
- 2. Updated the **[Features](#page-0-0)** section.
- 3. Updated the **[General Description](#page-0-1)** section.
- 4. Updated **[Section 3.0, Pin Descriptions](#page-8-1)**.
- 5. Updated **[Section 4.0, Detailed Description.](#page-10-0)**
- 6. Updated **[Section 5.0, Application Informa](#page-16-5)[tion](#page-16-5)**.
- 7. Updated **[Section 6.0, Typical Application Cir](#page-22-1)[cuits.](#page-22-1)**
- 8. Updated the **[Product Identification System](#page-34-0)** section.

# **Revision D (April 2015)**

The following is the list of modifications:

- 1. Updated the **[Features](#page-0-0)** section.
- 2. Updated the input voltage and resistor values in the **[Typical Applications](#page-1-0)** section.
- 3. Added **[Figure 2-6](#page-4-1)**.
- 4. Updated **[Example 5-1](#page-16-3)** and **[Example 5-2](#page-16-4)**.
- 5. Updated the  $R_{\text{TOP}}$  value in **Figures [5-1](#page-20-1), [5-2](#page-21-1), [6-1](#page-22-0)** and **[6-5](#page-26-0)**.

# **Revision C (November 2013)**

The following is the list of modifications:

- 1. Added new device to the family (MCP16301H) and related information throughout the document.
- 2. Added package markings and drawings for the MCP16301H device.
- 3. Updated the **[Product Identification System](#page-34-0)** section.

### **Revision B (November 2012)**

The following is the list of modifications:

- 1. Added Extended Temperature characteristic.
- 2. Added 6-lead SOT-23 package version (CH code).
- 3. Updated the following characterization charts: **Figure[s 2-7](#page-5-0)[, 2-8](#page-5-1)[, 2-9](#page-5-2)[, 2-10](#page-5-3)[, 2-12](#page-5-4)[, 2-13](#page-6-1)** and **[2-14](#page-6-2)**.
- 4. Updated **[Section 7.0, Packaging Information](#page-28-0)**.
- 5. Updated the **[Product Identification System](#page-34-0)** section.

# **Revision A (May 2011)**

• Original Release of this Document.

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**NOTES:**

# <span id="page-34-0"></span>**PRODUCT IDENTIFICATION SYSTEM**

To order or obtain information, e.g., on pricing or delivery, refer to the factory or the listed sales office.



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**NOTES:**

#### **Note the following details of the code protection feature on Microchip devices:**

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