

PIC24FJ256DA210 Family Data Sheet

64/100-Pin, 16-Bit Flash Microcontrollers with Graphics Controller and USB On-The-Go (OTG)

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64/100-Pin, 16-Bit Flash Microcontrollers with Graphics Controller and USB On-The-Go (OTG)

Graphics Controller Features:

- Three Graphics Hardware Accelerators to Facilitate Rendering of Block Copying, Text and Unpacking of Compressed Data
- Color Look-up Table (CLUT) with Maximum of 256 Entries
- 1/2/4/8/16 bits-per-pixel (bpp) Color Depth Set at
- Run Time
 Display Resolution Programmable According to
 Frame Buffer:
 - Supports direct access to external memory on devices with EPMP
 - Resolution supported is up to 480x272 @ 60 Hz, 16 bpp; 640x480 @ 30 Hz, 16 bpp or 640x480 @ 60 Hz, 8 bpp
- Supports Various Display Interfaces:
- 4/8/16-bit Monochrome STN
- 4/8/16-bit Color STN
- 9/12/18/24-bit Color TFT (18 and 24-bit displays are connected as 16-bit, 5-6-5 RGB color format)

Universal Serial Bus Features:

- USB v2.0 On-The-Go (OTG) Compliant
- Dual Role Capable Can act as either Host or Peripheral
- Low-Speed (1.5 Mbps) and Full-Speed (12 Mbps) USB Operation in Host mode
- Full-Speed USB Operation in Device mode
- High-Precision PLL for USB
- Supports up to 32 Endpoints (16 bidirectional):
- USB module can use the internal RAM location from 0x800 to 0xFFFF as USB endpoint buffers
- On-Chip USB Transceiver with Interface for Off-Chip Transceiver
- Supports Control, Interrupt, Isochronous and Bulk
 Transfers
- On-Chip Pull-up and Pull-Down Resistors

Peripheral Features:

- Enhanced Parallel Master Port/Parallel Slave Port (EPMP/PSP), 100-pin devices only:
 - Direct access from CPU with an Extended Data Space (EDS) interface
 - 4, 8 and 16-bit wide data bus
 - Up to 23 programmable address lines
 - Up to 2 chip select lines
 - Up to 2 Acknowledgement lines (one per chip select)
 - Programmable address/data multiplexing
 - Programmable address and data Wait states
 - Programmable polarity on control signals
- · Peripheral Pin Select:
 - Up to 44 available pins (100-pin devices)
- Three 3-Wire/4-Wire SPI modules (supports 4 Frame modes)
- Three I²C[™] modules Supporting Multi-Master/Slave modes and 7-Bit/10-Bit Addressing
- Four UART modules:
 - Supports RS-485, RS-232, LIN/J2602 protocols and $\text{IrDA}^{\textcircled{R}}$
- Five 16-Bit Timers/Counters with Programmable Prescaler
- Nine 16-Bit Capture Inputs, each with a Dedicated Time Base
- Nine 16-Bit Compare/PWM Outputs, each with a Dedicated Time Base
- Hardware Real-Time Clock and Calendar (RTCC)
- Enhanced Programmable Cyclic Redundancy Check (CRC) Generator
- Up to 5 External Interrupt Sources

				Re	emappa	ble Per	iphera	s							ŗ	
PIC24FJ Device	Pins	Program Memory (bytes)	SRAM (bytes)	Remappable Pins	16-Bit Timers	IC/OC PWM	UART w/IrDA [®]	IdS	I²C™	10-Bit A/D (ch)	Comparators	CTMU	EPMP/PSP	RTCC	Graphics Controller	USB OTG
PIC24FJ128DA106	64	128K	24K	29	5	9/9	4	3	3	16	3	Y	Ν	Y	Y	Y
PIC24FJ256DA106	64	256K	24K	29	5	9/9	4	3	3	16	3	Y	Ν	Y	Y	Y
PIC24FJ128DA110	100/121	128K	24K	44	5	9/9	4	3	3	24	3	Y	Y	Y	Y	Y
PIC24FJ256DA110	100/121	256K	24K	44	5	9/9	4	3	3	24	3	Y	Y	Y	Y	Y
PIC24FJ128DA206	64	128K	96K	29	5	9/9	4	3	3	16	3	Y	Ν	Y	Y	Y
PIC24FJ256DA206	64	256K	96K	29	5	9/9	4	3	3	16	3	Y	Ν	Y	Y	Y
PIC24FJ128DA210	100/121	128K	96K	44	5	9/9	4	3	3	24	3	Y	Y	Y	Y	Y
PIC24FJ256DA210	100/121	256K	96K	44	5	9/9	4	3	3	24	3	Y	Y	Y	Y	Y

High-Performance CPU

- Modified Harvard Architecture
- Up to 16 MIPS Operation at 32 MHz
- 8 MHz Internal Oscillator
- 17-Bit x 17-Bit Single-Cycle Hardware Multiplier
- 32-Bit by 16-Bit Hardware Divider
- 16 x 16-Bit Working Register Array
- C Compiler Optimized Instruction Set Architecture with Flexible Addressing modes
- Linear Program Memory Addressing, up to 12 Mbytes
- Data Memory Addressing, up to 16 Mbytes:
 - 2K SFR space
 - 30K linear data memory
 - 66K extended data memory
 - Remaining (from 16 Mbytes) memory (external) can be accessed using extended data Memory (EDS) and EPMP (EDS is divided into 32-Kbyte pages)
- Two Address Generation Units for Separate Read and Write Addressing of Data Memory

Power Management:

- On-Chip Voltage Regulator of 1.8V
- Switch between Clock Sources in Real Time
- Idle, Sleep and Doze modes with Fast Wake-up and Two-Speed Start-up
- + Run Mode: 800 $\mu\text{A/MIPS},$ 3.3V Typical
- + Sleep mode Current Down to 20 $\mu\text{A},$ 3.3V Typical
- Standby Current with 32 kHz Oscillator: 22 $\mu\text{A},$ 3.3V Typical

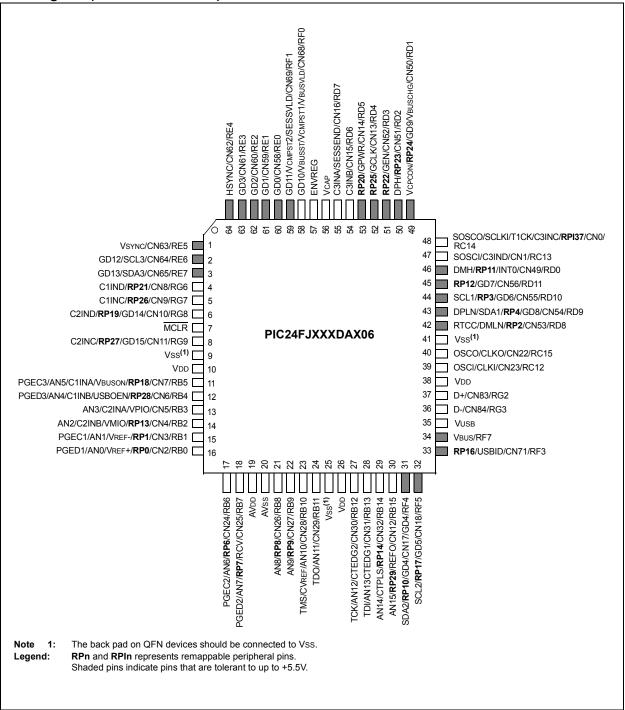
Analog Features:

- 10-Bit, up to 24-Channel Analog-to-Digital (A/D) Converter at 500 ksps:
 - Operation is possible in Sleep mode
 - Band gap reference input feature
- Three Analog Comparators with Programmable Input/Output Configuration
- Charge Time Measurement Unit (CTMU):
 - Supports capacitive touch sensing for touch screens and capacitive switches
 - Minimum time measurement setting at 100 ps
- Available LVD Interrupt VLVD Level

Special Microcontroller Features:

- Operating Voltage Range of 2.2V to 3.6V
- 5.5V Tolerant Input (digital pins only)
- Configurable Open-Drain Outputs on Digital I/O
 Ports
- High-Current Sink/Source (18 mA/18 mA) on all I/O Ports
- Selectable Power Management modes:
 Sleep, Idle and Doze modes with fast wake-up
- Fail-Safe Clock Monitor (FSCM) Operation:
- Detects clock failure and switches to on-chip, FRC oscillator
- On-Chip LDO Regulator
- Power-on Reset (POR) and Oscillator Start-up Timer (OST)
- Brown-out Reset (BOR)
- Flexible Watchdog Timer (WDT) with On-Chip Low-Power RC Oscillator for Reliable Operation
- In-Circuit Serial Programming[™] (ICSP[™]) and In-Circuit Debug (ICD) via 2 Pins
- JTAG Boundary Scan Support
- Flash Program Memory:
 - 10,000 erase/write cycle endurance (minimum)
 - 20-year data retention minimum
 - Selectable write protection boundary
 - Self-reprogrammable under software control
 - Write protection option for Configuration Words

Pin Diagram (64-Pin TQFP/QFN)

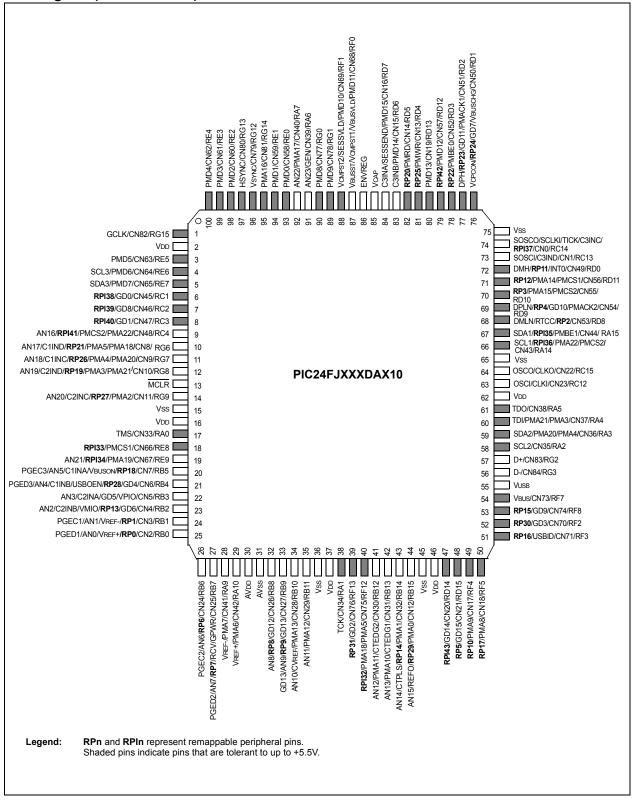


Pin	Function	Pin	Function
1	Vsync/CN63/RE5	33	RP16/USBID/CN71/RF3
2	GD12/SCL3/CN64/RE6	34	VBUS/RF7
3	GD13/SDA3/CN65/RE7	35	Vusb
4	C1IND/ RP21 /CN8/RG6	36	D-/CN84/RG3
5	C1INC/ RP26 /CN9/RG7	37	D+/CN83/RG2
6	C2IND/ RP19 /GD14/CN10/RG8	38	Vdd
7	MCLR	39	OSCI/CLKI/CN23/RC12
8	C2INC/ RP27 /GD15/CN11/RG9	40	OSCO/CLKO/CN22/RC15
9	Vss	41	Vss
10	VDD	42	RTCC/DMLN/ RP2 /CN53/RD8
11	PGEC3/AN5/C1INA/VBUSON/RP18/CN7/RB5	43	DPLN/SDA1/ RP4 /GD8/CN54/RD9
12	PGED3/AN4/C1INB/USBOEN/RP28/CN6/RB4	44	SCL1/ RP3 /GD6/CN55/RD10
13	AN3/C2INA/VPIO/CN5/RB3	45	RP12/GD7/CN56/RD11
14	AN2/C2INB/VMIO/ RP13 /CN4/RB2	46	DMH/ RP11 /INT0/CN49/RD0
15	PGEC1/AN1/VREF-/ RP1 /CN3/RB1	47	SOSCI/C3IND/CN1/RC13
16	PGED1/AN0/VREF+/ RP0 /CN2/RB0	48	SOSCO/SCLKI/T1CK/C3INC/RPI37/CN0/RC14
17	PGEC2/AN6/ RP6 /CN24/RB6	49	VCPCON/RP24/GD9/VBUSCHG/CN50/RD1
18	PGED2/AN7/ RP7 /RCV/CN25/RB7	50	DPH/ RP23 /CN51/RD2
19	AVDD	51	RP22/GEN/CN52/RD3
20	AVss	52	RP25/GCLK/CN13/RD4
21	AN8/ RP8 /CN26/RB8	53	RP20/GPWR/CN14/RD5
22	AN9/ RP9 /CN27/RB9	54	C3INB/CN15/RD6
23	TMS/CVREF/AN10/CN28/RB10	55	C3INA/SESSEND/CN16/RD7
24	TDO/AN11/CN29/RB11	56	VCAP
25	Vss	57	ENVREG
26	VDD	58	GD10/VBUSST/VCMPST1/VBUSVLD/CN68/RF0
27	TCK/AN12/CTEDG2/CN30/RB12	59	GD11/Vcmpst2/SESSVLD/CN69/RF1
28	TDI/AN13/CTEDG1/CN31/RB13	60	GD0/CN58/RE0
29	AN14/CTPLS/ RP14 /CN32/RB14	61	GD1/CN59/RE1
30	AN15/ RP29 /REFO/CN12/RB15	62	GD2/CN60/RE2
31	SDA2/ RP10 /GD4/CN17/RF4	63	GD3/CN61/RE3
32	SCL2/RP17/GD5/CN18/RF5	64	HSYNC/CN62/RE4
l egend.	RPn and RPIn represent remannable nins for Perinheral Pin	<u> </u>	

TABLE 1: COMPLETE PIN FUNCTION DESCRIPTIONS FOR 64-PIN DEVICES

Legend: RPn and RPIn represent remappable pins for Peripheral Pin Select functions.

Pin Diagram (100-Pin TQFP)



Pin	Function	Pin	Function
1	GCLK/CN82/RG15	41	AN12/PMA11/CTEDG2/CN30/RB12
2	VDD	42	AN13/PMA10/CTEDG1/CN31/RB13
3	PMD5/CN63/RE5	43	AN14/CTPLS/RP14/PMA1/CN32/RB14
4	SCL3/PMD6/CN64/RE6	44	AN15/REFO/ RP29 /PMA0/CN12/RB15
5	SDA3/PMD7/CN65/RE7	45	Vss
6	RPI38/GD0/CN45/RC1	46	VDD
7	RPI39/GD8/CN46/RC2	47	RPI43/GD14/CN20/RD14
8	RPI40/GD1/CN47/RC3	48	RP5/GD15/CN21/RD15
9	AN16/RPI41/PMCS2/PMA22 ⁽²⁾ /CN48/RC4	49	RP10/PMA9/CN17/RF4
10	AN17/C1IND/RP21/PMA5/PMA18 ⁽²⁾ /CN8/RG6	50	RP17/PMA8/CN18/RF5
11	AN18/C1INC/RP26/PMA4/PMA20 ⁽²⁾ /CN9/RG7	51	RP16/USBID/CN71/RF3
12	AN19/C2IND/RP19/PMA3/PMA21 ⁽²⁾ /CN10/RG8	52	RP30/GD3/CN70/RF2
13	MCLR	53	RP15/GD9/CN74/RF8
14	AN20/C2INC/RP27/PMA2/CN11/RG9	54	VBUS/CN73/RF7
15	Vss	55	VUSB
16	VDD	56	D-/CN84/RG3
17	TMS/CN33/RA0	57	D+/CN83/RG2
18	RPI33/PMCS1/CN66/RE8	58	SCL2/CN35/RA2
19	AN21/RPI34/PMA19/CN67/RE9	59	SDA2/PMA20/PMA4 ⁽²⁾ /CN36/RA3
20	PGEC3/AN5/C1INA/VBUSON/RP18/CN7/RB5	60	TDI/PMA21/PMA3 ⁽²⁾ /CN37/RA4
21	PGED3/AN4/C1INB/USBOEN/RP28/GD4/CN6/RB4	61	TDO/CN38/RA5
22	AN3/C2INA/GD5/VPIO/CN5/RB3	62	VDD
23	AN2/C2INB/VMIO/RP13/GD6/CN4/RB2	63	OSCI/CLKI/CN23/RC12
24	PGEC1/AN1/VREF- ⁽¹⁾ / RP1 /CN3/RB1	64	OSCO/CLKO/CN22/RC15
25	PGED1/AN0/VREF+ ⁽¹⁾ / RP0 /CN2/RB0	65	Vss
26	PGEC2/AN6/ RP6 /CN24/RB6	66	SCL1/ RPI36 /PMA22/PMCS2 ⁽²⁾ /CN43/RA14
27	PGED2/AN7/ RP7 /RCV/GPWR/CN25/RB7	67	SDA1/ RPI35 /PMBE1/CN44/RA15
28	VREF-/PMA7/CN41/RA9	68	DMLN/RTCC/RP2/CN53/RD8
29	VREF+/PMA6/CN42/RA10	69	DPLN/RP4/GD10/PMACK2/CN54/RD9
30	AVDD	70	RP3/PMA15/PMCS2 ⁽³⁾ /CN55/RD10
31	AVss	71	RP12/PMA14/PMCS1 ⁽³⁾ /CN56/RD11
32	AN8/RP8/GD12/CN26/RB8	72	DMH/RP11/INT0/CN49/RD0
33	AN9/ RP9 /GD13/CN27/RB9	73	SOSCI/C3IND/CN1/RC13
34	AN10/CVREF/PMA13/CN28/RB10	74	SOSCO/SCLKI/T1CK/C3INC/RPI37/CN0/RC14
35	AN11/PMA12/CN29/RB11	75	Vss
36	Vss	76	VCPCON/RP24/GD7/VBUSCHG/CN50/RD1
37	VDD	77	DPH/RP23/GD11/PMACK1/CN51/RD2
38	TCK/CN34/RA1	78	RP22/PMBE0/CN52/RD3
39	RP31/GD2/CN76/RF13	79	RPI42/PMD12/CN57/RD12
40	RPI32/PMA18/PMA5 ⁽²⁾ /CN75/RF12	80	PMD13/CN19/RD13

COMPLETE PIN FUNCTION DESCRIPTIONS FOR 100-PIN DEVICES TABLE 2:

Legend:

RPn and RPIn represent remappable pins for Peripheral Pin Select (PPS) functions.

Alternate pin assignments for VREF+ and VREF- when the ALTVREF Configuration bit is programmed. Alternate pin assignments for EPMP when the ALTPMP Configuration bit is programmed. Note 1:

2:

3: Pin assignment for PMCSx when CSF<1:0> is not equal to '00'.

TABLE 2: COMPLETE PIN FUNCTION DESCRIPTIONS FOR 100-PIN DEVICES

Pin	Function	Pin	Function
81	RP25/PMWR/CN13/RD4	91	AN23/GEN/CN39/RA6
82	RP20/PMRD/CN14/RD5	92	AN22/PMA17/CN40/RA7
83	C3INB/PMD14/CN15/RD6	93	PMD0/CN58/RE0
84	C3INA/SESSEND/PMD15/CN16/RD7	94	PMD1/CN59/RE1
85	VCAP	95	PMA16/CN81/RG14
86	ENVREG	96	Vsync/CN79/RG12
87	VBUSST/VCMPST1/VBUSVLD/PMD11/CN68/RF0	97	HSYNC/CN80/RG13
88	VCMPST2/SESSVLD/PMD10/CN69/RF1	98	PMD2/CN60/RE2
89	PMD9/CN78/RG1	99	PMD3/CN61/RE3
90	PMD8/CN77/RG0	100	PMD4/CN62/RE4

Legend:

end: **RPn** and **RPIn** represent remappable pins for Peripheral <u>Pin Select</u> (PPS) functions.

Note 1: Alternate pin assignments for VREF+ and VREF- when the ALTVREF Configuration bit is programmed.

2: Alternate pin assignments for EPMP when the ALTPMP Configuration bit is programmed.

3: Pin assignment for PMCSx when CSF<1:0> is not equal to '00'.

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Pin Diagram – Top View (121-Pin BGA)⁽¹⁾

	1	2	3	4	5	6	7	8	9	10	11
	•	•	•	•	•	•	0	0	•	•	•
Α	RE4	RE3	HSYNC/ RG13	RE0	RG0	RF1	ENVREG	N/C	RD12	GD11/ RD2	GD7/ RD1
в	O N/C	GCLK/ RG15	RE2	O RE1	O RA7	O RF0	O VCAP	RD5	RD3	O Vss	O RC14
с	RE6	O Vdd	Vsync/ RG12	ORG14	O GEN/ RA6	O N/C	O RD7	RD4	O Vdd	O RC13	O RD11
D	GD0/ RC1	RE7	RE5	O Vss	O Vss	O N/C	O RD6	RD13	RD0	O n/c	RD10
Е	O RC4	GD1/ RC3	O RG6	OD8/ RC2	O Vdd	ORG1	O N/C	RA15	RD8	GD10/ RD9	RA14
F		O RG8	O RG9	O RG7	O Vss	O n/c	O N/C	O Vdd	O OSCI/ RC12	O Vss	OSCO/ RC15
G	RE8	O RE9	RA0	O N/C	O Vdd	O Vss	O Vss	O N/C	O RA5	RA3	O RA4
н	O PGEC3/ RB5	O PGED3/ GD4/RB4	O Vss	O Vdd	O N/C	O Vdd	O n/c	O VBUS/ RF7	О Vusb	O D+/RG2	RA2
J	O GD5/ RB3	O GD6/ RB2	O PGED2/RB7 GPWR	O AVdd	O RB11	RA1	O RB12	O N/C	O N/C	GD9/RF8	O D-/RG3
к	O PGEC1/ RB1	O PGED1/ RB0	O RA10	O GD12/ RB8	O N/C	RF12	O RB14	O Vdd	OD15/ RD15	USBID/ RF3	GD3/ RF2
L	O PGEC2/ RB6	O RA9	O AVss	O GD13/ RB9	O RB10	GD2/ RF13	O RB13	O RB15	GD14/ RD14	ORF4	O RF5

Note 1: See Table 3 for complete functional pinout descriptions.

Legend: RPn and RPIn represent remappable pins for Peripheral Pin Select functions. Shaded pins indicate pins tolerant to up to +5.5V.

Pin	Function	Pin	Function
A1	PMD4/CN62/RE4	E5	VDD
A2	PMD3/CN61/RE3	E6	PMD9/CN78/RG1
A3	HSYNC/CN80/RG13	E7	N/C
A4	PMD0/CN58/RE0	E8	SDA1/ RPI35 /PMBE1/CN44/RA15
A5	PMD8/CN77/RG0	E9	DMLN/RTCC/RP2/CN53/RD8
A6	VCMPST2/SESSVLD/PMD10/CN69/RF1	E10	DPLN/ RP4 /GD10/PMACK2/CN54/RD9
A7	ENVREG	E11	SCL1/ RPI36 /PMA22/PMCS2 ⁽²⁾ /CN43/RA14
A8	N/C	F1	MCLR
A9	RPI42/PMD12/CN57/RD12	F2	AN19/C2IND/RP19/PMA3/PMA21 ⁽²⁾ /CN10/RG8
A10	DPH/RP23/GD11/PMACK1/CN51/RD2	F3	AN20/C2INC/RP27/PMA2/CN11/RG9
A11	VCPCON/RP24/GD7/VBUSCHG/CN50/RD1	F4	AN18/C1INC/ RP26 /PMA4/PMA20 ⁽²⁾ /CN9/RG7
B1	N/C	F5	Vss
B2	GCLK/CN82/RG15	F6	N/C
B3	PMD2/CN60/RE2	F7	N/C
B4	PMD1/CN59/RE1	F8	VDD
B5	AN22/PMA17/CN40/RA7	F9	OSCI/CLKI/CN23/RC12
B6	VBUSST/VCMPST1/VBUSVLD/PMD11/CN68/RF0	F10	Vss
B7	VCAP	F11	OSCO/CLKO/CN22/RC15
B8	RP20/PMRD/CN14/RD5	G1	RPI33/PMCS1/CN66/RE8
B9	RP22/PMBE0/CN52/RD3	G2	AN21/RPI34/PMA19/CN67/RE9
B10	Vss	G3	TMS/CN33/RA0
B11	SOSCO/SCLKI/T1CK/C3INC/RPI37/CN0/RC14	G4	N/C
C1	SCL3/PMD6/CN64/RE6	G5	VDD
C2	VDD	G6	Vss
C3	VSYNC/CN79/RG12	G7	Vss
C4	PMA16/CN81/RG14	G8	N/C
C5	AN23/GEN/CN39/RA6	G9	TDO/CN38/RA5
C6	N/C	G10	SDA2/PMA20/PMA4 ⁽²⁾ /CN36/RA3
C7	C3INA/SESSEND/PMD15/CN16/RD7	G11	TDI/PMA21/PMA3 ⁽²⁾ /CN37/RA4
C8	RP25/PMWR/CN13/RD4	H1	PGEC3/AN5/C1INA/VBUSON/RP18/CN7/RB5
C9	VDD	H2	PGED3/AN4/C1INB/USBOEN/RP28/GD4/CN6/RB4
C10	SOSCI/C3IND/CN1/RC13	H3	Vss
C11	RP12/PMA14/PMCS1 ⁽³⁾ /CN56/RD11	H4	VDD
D1	RPI38/GD0/CN45/RC1	H5	N/C
D2	SDA3/PMD7/CN65/RE7	H6	VDD
D3	PMD5/CN63/RE5	H7	N/C
D4	Vss	H8	VBUS/CN73/RF7
D5	Vss	H9	Vusb
D6	N/C	H10	D+/CN83/RG2
D7	C3INB/PMD14/CN15/RD6	H11	SCL2/CN35/RA2
D8	PMD13/CN19/RD13	J1	AN3/C2INA/GD5/VPIO/CN5/RB3
D9	DMH/RP11/INT0/CN49/RD0	J2	AN2/C2INB/VMIO/RP13/GD6/CN4/RB2
D10	N/C	J3	PGED2/AN7/RP7/RCV/GPWR/CN25/RB7
D11	RP3/PMA15/PMCS2 ⁽³⁾ /CN55/RD10	J4	AVDD
E1	AN16/ RPI41 /PMCS2/PMA22 ⁽²⁾ /CN48/RC4	J5	AN11/PMA12/CN29/RB11
E2	RPI40/GD1/CN47/RC3	J6	TCK/CN34/RA1
E3	AN17/C1IND/ RP21 /PMA5/PMA18 ⁽²⁾ /CN8/RG6	J7	AN12/PMA11/CTEDG2/CN30/RB12

TABLE 3: **COMPLETE PIN FUNCTION DESCRIPTIONS FOR 121-PIN (BGA) DEVICES**

Note

RPn and **RPIn** represent remappable pins for Peripheral Pin Select functions. Alternate pin assignments for VREF+ and VREF- when the ALTVREF Configuration bit is programmed. Alternate pin assignments for EPMP when the ALTPMP Configuration bit is programmed. 1:

2:

3: Pin assignment for PMCSx when CSF<1:0> is not equal to '00'.

TABLE 3: **COMPLETE PIN FUNCTION DESCRIPTIONS FOR 121-PIN (BGA) DEVICES**

Pin	Function	Pin	Function
J9	N/C	L1	PGEC2/AN6/ RP6 /CN24/RB6
J10	RP15/GD9/CN74/RF8	L2	VREF- ⁽¹⁾ /PMA7/CN41/RA9
J11	D-/CN84/RG3	L3	AVSS
K1	PGEC1/AN1/VREF- ⁽¹⁾ /RP1/CN3/RB1	L4	AN9/ RP9 /GD13/CN27/RB9
K2	PGED1/AN0/VREF+ ⁽¹⁾ / RP0 /CN2/RB0	L5	AN10/CVREF/PMA13/CN28/RB10
K3	VREF+ ⁽¹⁾ /PMA6/CN42/RA10	L6	RP31/GD2/CN76/RF13
K4	AN8/ RP8 /GD12/CN26/RB8	L7	AN13/PMA10/CTEDG1/CN31/RB13
K5	N/C	L8	AN15/REFO/RP29/PMA0/CN12/RB15
K6	RPI32/PMA18/PMA5 ⁽²⁾ /CN75/RF12	L9	RPI43/GD14/CN20/RD14
K7	AN14/CTPLS/RP14/PMA1/CN32/RB14	L10	RP10/PMA9/CN17/RF4
K8	VDD	L11	RP17/GD5/PMA8/SCL2/CN18/RF5
K9	RP5/GD15/CN21/RD15	_	_
K10	RP16/USBID/CN71/RF3	_	-
K11	RP30/GD3/CN70/RF2	—	—

Legend: Note 1

RPn and **RPIn** represent remappable pins for Peripheral Pin Select functions. Alternate pin assignments for VREF+ and VREF- when the ALTVREF Configuration bit is programmed. Alternate pin assignments for EPMP when the ALTPMP Configuration bit is programmed. 1:

2:

3: Pin assignment for PMCSx when CSF<1:0> is not equal to '00'.

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1.0 DEVICE OVERVIEW

This document contains device-specific information for the following devices:

- PIC24FJ128DA106 PIC24FJ128DA206
- PIC24FJ256DA106
 - A106 PIC24FJ256DA206 A110 • PIC24FJ128DA210
- PIC24FJ128DA110
 PIC24
 PIC24FJ256DA110
 PIC24
 - PIC24FJ256DA210

The PIC24FJ256DA210 family enhances on the existing line of Microchip's 16-bit microcontrollers, adding a new Graphics Controller (GFX) module to interface with a graphical LCD display and also adds large data RAM, up to 96 Kbytes. The PIC24FJ256DA210 family allows the CPU to fetch data directly from an external memory device using the EPMP module.

1.1 Core Features

1.1.1 16-BIT ARCHITECTURE

Central to all PIC24F devices is the 16-bit modified Harvard architecture, first introduced with Microchip's dsPIC[®] Digital Signal Controllers (DSCs). The PIC24F CPU core offers a wide range of enhancements, such as:

- 16-bit data and 24-bit address paths with the ability to move information between data and memory spaces
- Linear addressing of up to 12 Mbytes (program space) and 32 Kbytes (data)
- A 16-element working register array with built-in software stack support
- A 17 x 17 hardware multiplier with support for integer math
- Hardware support for 32 by 16-bit division
- An instruction set that supports multiple addressing modes and is optimized for high-level languages, such as 'C'
- Operational performance up to 16 MIPS

1.1.2 POWER-SAVING TECHNOLOGY

All of the devices in the PIC24FJ256DA210 family incorporate a range of features that can significantly reduce power consumption during operation. Key items include:

• **On-the-Fly Clock Switching:** The device clock can be changed under software control to the Timer1 source or the internal, low-power RC oscillator during operation, allowing the user to incorporate power-saving ideas into their software designs.

- **Doze Mode Operation:** When timing-sensitive applications, such as serial communications, require the uninterrupted operation of peripherals, the CPU clock speed can be selectively reduced, allowing incremental power savings without missing a beat.
- Instruction-Based Power-Saving Modes: The microcontroller can suspend all operations, or selectively shut down its core while leaving its peripherals active with a single instruction in software.

1.1.3 OSCILLATOR OPTIONS AND FEATURES

All of the devices in the PIC24FJ256DA210 family offer five different oscillator options, allowing users a range of choices in developing application hardware. These include:

- Two Crystal modes using crystals or ceramic resonators.
- Two External Clock modes offering the option of a divide-by-2 clock output.
- A Fast Internal Oscillator (FRC) with a nominal 8 MHz output, which can also be divided under software control to provide clock speeds as low as 31 kHz.
- A Phase Lock Loop (PLL) frequency multiplier, available to the external oscillator modes and the FRC oscillator, which allows clock speeds of up to 32 MHz.
- A separate Low-Power Internal RC Oscillator (LPRC) with a fixed 31 kHz output, which provides a low-power option for timing-insensitive applications.

The internal oscillator block also provides a stable reference source for the Fail-Safe Clock Monitor (FSCM). This option constantly monitors the main clock source against a reference signal provided by the internal oscillator and enables the controller to switch to the internal oscillator, allowing for continued low-speed operation or a safe application shutdown.

1.1.4 EASY MIGRATION

Regardless of the memory size, all devices share the same rich set of peripherals, allowing for a smooth migration path as applications grow and evolve. The consistent pinout scheme used throughout the entire family also aids in migrating from one device to the next larger, or even in jumping from 64-pin to 100-pin devices.

The PIC24F family is pin compatible with devices in the dsPIC33 family, and shares some compatibility with the pinout schema for PIC18 and dsPIC30. This extends the ability of applications to grow from the relatively simple, to the powerful and complex, yet still selecting a Microchip device.

1.2 Graphics Controller

With the PIC24FJ256DA210 family of devices, Microchip introduces the Graphics Controller module, which acts as an interface between the CPU (mainly through SFRs) and a display. On-board RAM is provided for display buffer, scratch areas, images and fonts. In some cases, the RAM requirements for the display used exceeds the on-board RAM; external memory connected through EPMP can be used.

This module provides acceleration for drawing points, vertical and horizontal lines, rectangles, copying rectangles between different locations on screen, drawing text and decompressing compressed data.

1.3 USB On-The-Go

The USB On-The-Go (USB OTG) module provides on-chip functionality as a target device compatible with the USB 2.0 standard, as well as limited stand-alone functionality as a USB embedded host. By implementing USB Host Negotiation Protocol (HNP), the module can also dynamically switch between device and host operation, allowing for a much wider range of versatile USB enabled applications on a microcontroller platform.

In addition to USB host functionality, PIC24FJ256DA210 family devices provide a true single chip USB solution, including an on-chip transceiver and voltage regulator, and a voltage boost generator for sourcing bus power during host operations.

1.4 Other Special Features

- Peripheral Pin Select: The Peripheral Pin Select (PPS) feature allows most digital peripherals to be mapped over a fixed set of digital I/O pins. Users may independently map the input and/or output of any one of the many digital peripherals to any one of the I/O pins.
- Communications: The PIC24FJ256DA210 family incorporates a range of serial communication peripherals to handle a range of application requirements. There are three independent I²C[™] modules that support both Master and Slave modes of operation. Devices also have, through the PPS feature, four independent UARTs with built-in IrDA[®] encoders/decoders and three SPI modules.
- Analog Features: All members of the PIC24FJ256DA210 family include a 10-bit A/D Converter (ADC) module and a triple comparator module. The ADC module incorporates programmable acquisition time, allowing for a channel to be selected and a conversion to be initiated without waiting for a sampling period, and faster sampling speeds. The comparator module includes three analog comparators that are configurable for a wide range of operations.
- **CTMU Interface:** In addition to their other analog features, members of the PIC24FJ256DA210 family include the CTMU interface module. This provides a convenient method for precision time measurement and pulse generation, and can serve as an interface for capacitive sensors.
- Enhanced Parallel Master/Parallel Slave Port: There are general purpose I/O ports, which can be configured for parallel data communications. In this mode, the device can be master or slave on the communication bus. 4-bit, 8-bit and 16-bit data transfers, with up to 23 external address lines are supported in Master modes.
- Real-Time Clock and Calendar: (RTCC) This module implements a full-featured clock and calendar with alarm functions in hardware, freeing up timer resources and program memory space for use of the core application.

1.5 Details on Individual Family Members

Devices in the PIC24FJ256DA210 family are available in 64-pin and 100-pin packages. The general block diagram for all devices is shown in Figure 1-1.

The devices are differentiated from each other in seven ways:

- 1. Flash program memory (128 Kbytes for PIC24FJ128DAXXX devices and 256 Kbytes for PIC24FJ256DAXXX devices).
- 2. Data memory (24 Kbytes for PIC24FJXXXDA1XX devices, and 96 Kbytes for PIC24FJXXXDA2XX devices).
- Available I/O pins and ports (52 pins on 6 ports for PIC24FJXXXDAX06 devices and 84 pins on 7 ports for PIC24FJXXXDAX10 devices).
- Available Interrupt-on-Change Notification (ICN) inputs (52 on PIC24FJXXXDAx06 devices and 84 on PIC24FJXXXDAX10 devices).

- Available remappable pins (29 pins on PIC24FJXXXDAX06 devices and 44 pins on PIC24FJXXXDAX10 devices).
- Analog channels for ADC (16 channels for PIC24FJXXXDAX06 devices and 24 channels for PIC24FJxxxDAx10 devices).
- 7. EPMP module (available in PIC24FJXXXDAX10 devices and not in PIC24FJXXXDAX06 devices).

All other features for devices in this family are identical. These are summarized in Table 1-1 and Table 1-2.

A list of the pin features available on the PIC24FJ256DA210 family devices, sorted by function, is shown in Table 1-1. Note that this table shows the pin location of individual peripheral features and not how they are multiplexed on the same pin. This information is provided in the pinout diagrams in the beginning of the data sheet. Multiplexed features are sorted by the priority given to a feature, with the highest priority peripheral being listed first.

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TABLE 1-1: DEVICE FEATURES FOR THE PIC24FJ256DA210 FAMILY: 64-PIN

Features	PIC24FJ128DA106	PIC24FJ256DA106	PIC24FJ128DA206	PIC24FJ256DA206		
Operating Frequency		DC – 3	2 MHz	•		
Program Memory (bytes)	128K	256K	128K	256K		
Program Memory (instructions)	44,032	87,552	44,032	87,552		
Data Memory (bytes)	24	1K	96	δK		
Interrupt Sources (soft vectors/ NMI traps)		65 (6	51/4)			
I/O Ports		Ports B, C	, D, E, F, G			
Total I/O Pins		5	2			
Remappable Pins		29 (28 I/O, 1	1 Input only)			
Timers:						
Total Number (16-bit)		5	1)			
32-Bit (from paired 16-bit timers)		2	2			
Input Capture Channels		91	1)			
Output Compare/PWM Channels		91	1)			
Input Change Notification Interrupt		5	2			
Serial Communications:						
UART		40	1)			
SPI (3-wire/4-wire)		3	[1]			
I ² C™		3	3			
Parallel Communications (EPMP/PSP)		Ν	0			
JTAG Boundary Scan		Ye	es			
10-Bit Analog-to-Digital Converter (ADC) Module (input channels)		1	6			
Analog Comparators		3	3			
CTMU Interface		Ye	es			
USB OTG		Ye	es			
Graphics Controller	Yes					
Resets (and Delays)	POR, BOR, RESET Instruction, MCLR, WDT; Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (OST, PLL Lock)					
Instruction Set	76 Base	e Instructions, Multiple	Addressing Mode Va	ariations		
Packages		64-Pin TQF	P and QFN			

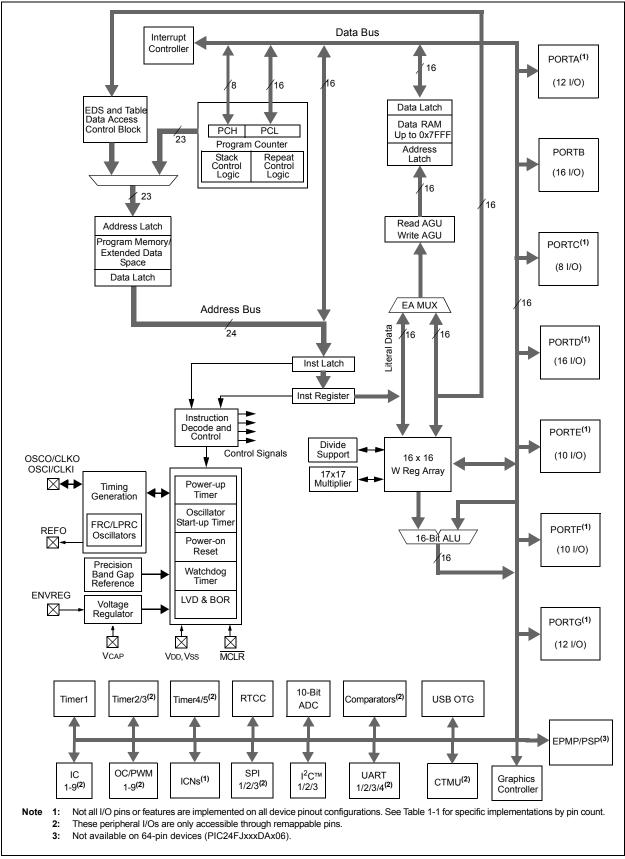
Note 1: Peripherals are accessible through remappable pins.

Features	PIC24FJ128DA110	PIC24FJ256DA110	PIC24FJ128DA210	PIC24FJ256DA210		
Operating Frequency		DC – 3	2 MHz			
Program Memory (bytes)	128K	256K	128K	256K		
Program Memory (instructions)	44,032	87,552	44,032	87,552		
Data Memory (bytes)	24	iκ	96	δK		
Interrupt Sources (soft vectors/NMI traps)		66 (6	52/4)			
I/O Ports		Ports A, B, (C, D, E, F, G			
Total I/O Pins		8	4			
Remappable Pins		44 (32 I/O, 1	2 input only)			
Timers:						
Total Number (16-bit)		5	(1)			
32-Bit (from paired 16-bit timers)			2			
Input Capture Channels		9	(1)			
Output Compare/PWM Channels		9	(1)			
Input Change Notification Interrupt		8	4			
Serial Communications:						
UART		4	(1)			
SPI (3-wire/4-wire)		3	(1)			
I ² C™		÷	3			
Parallel Communications (EPMP/PSP)		Ye	es			
JTAG Boundary Scan		Ye	es			
10-Bit Analog-to-Digital Converter (ADC) Module (input channels)		2	4			
Analog Comparators		:	3			
CTMU Interface		Ye	es			
USB OTG		Ye	es			
Graphics Controller	Yes					
Resets (and delays)	POR, BOR, RESET Instruction, MCLR, WDT; Illegal Opcode, REPEAT Instruction, Hardware Traps, Configuration Word Mismatch (OST, PLL Lock)					
Instruction Set	76 Base	Instructions, Multiple	Addressing Mode V	ariations		
Packages		100-Pin TQFP a	nd 121-Pin BGA			

TABLE 1-2: DEVICE FEATURES FOR THE PIC24FJ256DA210 FAMILY: 100-PIN DEVICES

Note 1: Peripherals are accessible through remappable pins.





		Pin Number				
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description
AN0	16	25	K2	I	ANA	
AN1	15	24	K1	I	ANA	
AN2	14	23	J2	I	ANA	
AN3	13	22	J1	I	ANA	
AN4	12	21	H2	I	ANA	
AN5	11	20	H1	I	ANA	
AN6	17	26	L1	I	ANA	
AN7	18	27	J3	I	ANA	
AN8	21	32	K4	I	ANA	
AN9	22	33	L4	I	ANA	
AN10	23	34	L5	I	ANA	
AN11	24	35	J5	I	ANA	
AN12	27	41	J7	I	ANA	A/D Analog Inputs.
AN13	28	42	L7	I	ANA	
AN14	29	43	K7	I	ANA	
AN15	30	44	L8	I	ANA	
AN16	—	9	E1	I	ANA	
AN17	—	10	E3	I	ANA	
AN18	—	11	F4	I	ANA	
AN19	—	12	F2	I	ANA	
AN20	—	14	F3	I	ANA	
AN21	—	19	G2	I	ANA	
AN22	—	92	B5	I	ANA	
AN23	—	91	C5	I	ANA	
AVdd	19	30	J4	Р		Positive Supply for Analog modules.
AVss	20	31	L3	Р		Ground Reference for Analog modules.
C1INA	11	20	H1	I	ANA	Comparator 1 Input A.
C1INB	12	21	H2	I	ANA	Comparator 1 Input B.
C1INC	5	11	F4	I	ANA	Comparator 1 Input C.
C1IND	4	10	E3	I	ANA	Comparator 1 Input D.
C2INA	13	22	J1	I	ANA	Comparator 2 Input A.
C2INB	14	23	J2	I	ANA	Comparator 2 Input B.
C2INC	8	14	F3	Ι	ANA	Comparator 2 Input C.
C2IND	6	12	F2	I	ANA	Comparator 2 Input D.
C3INA	55	84	C7	I	ANA	Comparator 3 Input A.
C3INB	54	83	D7	Ι	ANA	Comparator 3 Input B.
C3INC	48	74	B11	I	ANA	Comparator 3 Input C.
C3IND	47	73	C10	I	ANA	Comparator 3 Input D.
CLKI	39	63	F9	I	ST	Main Clock Input Connection.
CLKO	40	64	F11	0	—	System Clock Output.
	TTL = TTL inpu ANA = Analog		nut		ST = I ² C™	Schmitt Trigger input buffer = I ² C/SMBus input buffer

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS

ANA = Analog level input/output

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number			Input	
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Buffer	Description
CN0	48	74	B11	I	ST	
CN1	47	73	C10	Ι	ST	
CN2	16	25	K2	I	ST	
CN3	15	24	K1	Ι	ST	
CN4	14	23	J2	Ι	ST	
CN5	13	22	J1	I	ST	
CN6	12	21	H2	Ι	ST	
CN7	11	20	H1	Ι	ST	
CN8	4	10	E3	Ι	ST	
CN9	5	11	F4	Ι	ST	
CN10	6	12	F2	Ι	ST	
CN11	8	14	F3	I	ST	
CN12	30	44	L8	Ι	ST	
CN13	52	81	C8	Ι	ST	
CN14	53	82	B8	ļ	ST	
CN15	54	83	D7	I	ST	
CN16	55	84	C7	Ι	ST	
CN17	31	49	L10	I	ST	
CN18	32	50	L11	I	ST	
CN19	—	80	D8	I	ST	Interrupt-on-Change Inputs.
CN20	—	47	L9	I	ST	
CN21	—	48	K9	I	ST	
CN22	40	64	F11	I	ST	
CN23	39	63	F9	Ι	ST	
CN24	17	26	L1	I	ST	
CN25	18	27	J3	I	ST	
CN26	21	32	K4	I	ST	
CN27	22	33	L4	Ι	ST	
CN28	23	34	L5	I	ST	
CN29	24	35	J5	Ι	ST	
CN30	27	41	J7	I	ST	
CN31	28	42	L7	I	ST	
CN32	29	43	K7	Ι	ST	
CN33	—	17	G3	Ι	ST	
CN34	—	38	J6	I	ST	
CN35	—	58	H11	ļ	ST	
CN36	—	59	G10	I	ST	
CN37	—	60	G11	I	ST	
CN38	—	61	G9	Ι	ST	
CN39	—	91	C5	I	ST	

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number			Incret			
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description		
CN40	—	92	B5	I	ST			
CN41	_	28	L2	I	ST			
CN42		29	K3	I	ST			
CN43	_	66	E11	Ι	ST			
CN44	_	67	E8	Ι	ST			
CN45	_	6	D1	Ι	ST			
CN46	—	7	E4	Ι	ST			
CN47	—	8	E2	Ι	ST			
CN48	_	9	E1	Ι	ST			
CN49	46	72	D9	Ι	ST			
CN50	49	76	A11	Ι	ST			
CN51	50	77	A10	Ι	ST			
CN52	51	78	B9	Ι	ST			
CN53	42	68	E9	I	ST			
CN54	43	69	E10	Ι	ST			
CN55	44	70	D11	Ι	ST			
CN56	45	71	C11	Ι	ST			
CN57	—	79	A9	Ι	ST			
CN58	60	93	A4	Ι	ST			
CN59	61	94	B4	I	ST			
CN60	62	98	B3	Ι	ST	Interrupt-on-Change Inputs.		
CN61	63	99	A2	I	ST			
CN62	64	100	A1	I	ST			
CN63	1	3	D3	Ι	ST			
CN64	2	4	C1	I	ST			
CN65	3	5	D2	I	ST			
CN66		18	G1	I	ST			
CN67	_	19	G2	I	ST			
CN68	58	87	B6	I	ST			
CN69	59	88	A6	I	ST			
CN70	—	52	K11	I	ST			
CN71	33	51	K10	I	ST			
CN73	—	54	H8	I	ST			
CN74	—	53	J10	I	ST			
CN75	—	40	K6	I	ST			
CN76	—	39	L6	Ι	ST	1		
CN77	_	90	A5	Ι	ST	1		
CN78	_	89	E6	Ι	ST	1		
CN79	_	96	C3	I	ST	1		
CN80	_	97	A3	I	ST	1		
	TTL = TTL inp ANA = Analog		put		ST = I ² C™	Schmitt Trigger input buffer = I ² C/SMBus input buffer		

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.
4: The alternate VREF pins selected when the ALTVREF (CW1<5>) bit is programmed to '0'.

Pin Number Input I/O Function Description 64-Pin 100-Pin 121-Pin Buffer **TQFP/QFN** TQFP BGA **CN81** 95 C4 ST Т **CN82** ____ 1 B2 T ST Interrupt-on-Change Inputs. **CN83** 37 57 H10 I ST **CN84** 56 36 J11 ST I CTEDG1 42 L7 I 28 ANA CTMU External Edge Input 1. CTEDG2 27 41 J7 CTMU External Edge Input 2. I ANA CTPLS 29 43 K7 0 CTMU Pulse Output **CVREF** 23 34 15 0 Comparator Voltage Reference Output. ____ D+ 37 57 H10 I/O USB Differential Plus Line (internal transceiver). _____ D-36 56 J11 I/O USB Differential Minus Line (internal transceiver) ____ DMH 46 72 D9 0 D- External Pull-up Control Output. DMLN D- External Pull-down Control Output. 42 68 E9 0 DPH 50 77 A10 0 _ D+ External Pull-up Control Output DPLN 43 69 E10 0 D+ External Pull-down Control Output. **ENVREG** 57 86 J7 T ST Voltage Regulator Enable. GCLK B2 0 Graphics Display Pixel Clock. 52 1 GD0 60 6 D1 0 ____ GD1 0 61 8 E2 GD2 62 39 L6 0 _ GD3 63 52 K11 0 GD4 21 H2 0 31 ____ GD5 32 22 J1 0 GD6 44 23 J2 0 _ GD7 45 76 A11 0 ____ Graphics Controller Data Output. GD8 43 7 E4 0 GD9 49 53 J10 0 _ GD10 58 69 E10 0 GD11 59 77 A10 0 _ 2 GD12 32 K4 0 GD13 3 33 L4 0 ____ GD14 6 47 L9 0 ____ GD15 8 48 K9 0 _ GEN 51 91 C5 0 _____ Graphics Display Enable Output. GPWR 53 27 J3 0 Graphics Display Power System Enable. ____ HSYNC 64 97 A3 0 Graphics Display Horizontal Sync Pulse. _ INT0 46 72 D9 Т ST External Interrupt Input. MCLR 7 F1 T ST 13 Master Clear (device Reset) Input. This line is brought low to cause a Reset. OSCI 39 63 F9 ANA Main Oscillator Input Connection. I OSCO 40 64 F11 0 ANA Main Oscillator Output Connection. Legend: TTL = TTL input buffer ST = Schmitt Trigger input buffer ANA = Analog level input/output I²C[™] = I²C/SMBus input buffer

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the $\overline{\text{ALTPMP}}$ (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

_		Pin Number		I/O	Input	Description			
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA		Buffer				
PGEC1	15	24	K1	I/O	ST	In-Circuit Debugger/Emulator/ICSP™ Programming Clock			
PGED1	16	25	K2	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data 1			
PGEC2	17	26	L1	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Clock 2			
PGED2	18	27	J3	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data 2			
PGEC3	11	20	H1	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Clock			
PGED3	12	21	H2	I/O	ST	In-Circuit Debugger/Emulator/ICSP Programming Data 3			
PMA0	—	44	L8	I/O	ST	Parallel Master Port Address bit 0 Input (Buffered Slave modes) and Output (Master modes).			
PMA1	—	43	K7	I/O	ST	Parallel Master Port Address Bit 1 Input (Buffered Slave modes) and Output (Master modes).			
PMA2	_	14	F3	0	_				
PMA3	_	12, 60 ⁽¹⁾	F2, G11 ⁽¹⁾	0	_				
PMA4	_	11,59 ⁽¹⁾	F4,G10 ⁽¹⁾	0	_				
PMA5	—	10,40 ⁽¹⁾	E3,K6 ⁽¹⁾	0	_				
PMA6	_	29	K3	0	_				
PMA7	_	28	L2	0	_				
PMA8	—	50	L11	0	_				
PMA9	_	49	L10	0	_				
PMA10	_	42	L7	0	_				
PMA11	—	41	J7	0	_				
PMA12	_	35	J5	0	_	Parallel Master Port Address bits<22:2>.			
PMA13	—	34	L5	0	—				
PMA14	—	71	C11	0	_				
PMA15	_	70	D11	0	_				
PMA16	—	95	C4	0	—				
PMA17	—	92	B5	0	_				
PMA18	_	40,10 ⁽¹⁾	K6,E3 ⁽¹⁾	0	—				
PMA19	—	19	G2	0	_				
PMA20	—	59, 11 ⁽¹⁾	G10, F4 ⁽¹⁾	0	_				
PMA21	—	60,12 ⁽¹⁾	G11,F2 ⁽¹⁾	0	_				
PMA22	—	66,9 ⁽¹⁾	E11,E1 ⁽¹⁾	0	_				
PMACK1	—	77	A10	I	ST/TTL	Parallel Master Port Acknowledge Input 1.			
PMACK2	_	69	E10	Ι	ST/TTL	Parallel Master Port Acknowledge Input 2.			
PMALL	_	44	L8	0		Parallel Master Port Lower Address Latch Strobe.			
PMALH	—	43	K7	0	—	Parallel Master Port Higher Address Latch Strobe.			
PMALU	—	14	F3	0	—	Parallel Master Port Upper Address Latch Strobe.			
PMBE0	—	78	B9	0	—	Parallel Master Port Byte Enable Strobe 0.			
PMBE1	—	67	E8	0	—	Parallel Master Port Byte Enable Strobe 1.			
PMCS1	_	71 ⁽³⁾ ,18	C11 ⁽³⁾ ,G1	I/O	ST/TTL	Parallel Master Port Chip Select Strobe 1.			
PMCS2	—	70 ⁽²⁾ ,9, 66 ⁽¹⁾	D11 ⁽²⁾ ,E1, E11 ⁽¹⁾	0	_	Parallel Master Port Chip Select Strobe 2.			
Note 1:		level input/out EPMP pins are	selected whe		I ² C™ ALTPMP (Schmitt Trigger input buffer = I ² C/SMBus input buffer CW3<12>) bit is programmed to '0'. i-pin PMA when CSF<1:0> = 01 or 10.			

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

4: The alternate VREF pins selected when the ALTVREF (CW1<5>) bit is programmed to '0'.

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		Pin Number			Innut					
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description				
PMD0	—	93	A4	I/O	ST/TTL					
PMD1	—	94	B4	I/O	ST/TTL					
PMD2	—	98	B3	I/O	ST/TTL					
PMD3	—	99	A2	I/O	ST/TTL					
PMD4	_	100	A1	I/O	ST/TTL					
PMD5	—	3	D3	I/O	ST/TTL					
PMD6	—	4	C1	I/O	ST/TTL					
PMD7	_	5	D2	I/O	ST/TTL	Devellet Meeter Deve bits (15:0)				
PMD8	—	90	A5	I/O	ST/TTL	Parallel Master Port Data bits<15:0>.				
PMD9	—	89	E6	I/O	ST/TTL					
PMD10	_	88	A6	I/O	ST/TTL					
PMD11	—	87	B6	I/O	ST/TTL					
PMD12	—	79	A9	I/O	ST/TTL					
PMD13	_	80	D8	I/O	ST/TTL					
PMD14	_	83	D7	I/O	ST/TTL					
PMD15	_	84	C7	I/O	ST/TTL					
PMRD	_	82	B8	I/O	ST/TTL	Parallel Master Port Read Strobe.				
PMWR	_	81	C8	I/O	ST/TTL	Parallel Master Port Write Strobe.				
RA0	_	17	G3	I/O	ST					
RA1	—	38	J6	I/O	ST					
RA2	—	58	H11	I/O	ST					
RA3	—	59	G10	I/O	ST					
RA4	—	60	G11	I/O	ST					
RA5	—	61	G9	I/O	ST					
RA6	—	91	C5	I/O	ST	PORTA Digital I/O.				
RA7	_	92	B5	I/O	ST					
RA9	—	28	L2	I/O	ST					
RA10	—	29	K3	I/O	ST					
RA14	—	66	E11	I/O	ST					
RA15	_	67	E8	I/O	ST					
	TTL = TTL inp ANA = Analog		put		ST = I ² C™	Schmitt Trigger input buffer = I ² C/SMBus input buffer				

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number			Innut				
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description			
RB0	16	25	K2	I/O	ST				
RB1	15	24	K1	I/O	ST				
RB2	14	23	J2	I/O	ST				
RB3	13	22	J1	I/O	ST				
RB4	12	21	H2	I/O	ST				
RB5	11	20	H1	I/O	ST				
RB6	17	26	L1	I/O	ST				
RB7	18	27	J3	I/O	ST				
RB8	21	32	K4	I/O	ST	PORTB Digital I/O.			
RB9	22	33	L4	I/O	ST				
RB10	23	34	L5	I/O	ST				
RB11	24	35	J5	I/O	ST				
RB12	27	41	J7	I/O	ST				
RB13	28	42	L7	I/O	ST				
RB14	29	43	K7	I/O	ST				
RB15	30	44	L8	I/O	ST				
RC1	—	6	D1	I/O	ST				
RC2	—	7	E4	I/O	ST				
RC3	—	8	E2	I/O	ST				
RC4	—	9	E1	I/O	ST				
RC12	39	63	F9	I/O	ST	PORTC Digital I/O.			
RC13	47	73	C10	I/O	ST				
RC14	48	74	B11	I/O	ST				
RC15	40	64	F11	I/O	ST				
RCV	18	27	J3	I	ST	USB Receive Input (from external transceiver).			
-	TTL = TTL inpu ANA = Analog		put		ST = I ² C™	Schmitt Trigger input buffer = I ² C/SMBus input buffer			

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number			Incost					
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description				
RD0	46	72	D9	I/O	ST					
RD1	49	76	A11	I/O	ST					
RD2	50	77	A10	I/O	ST					
RD3	51	78	B9	I/O	ST					
RD4	52	81	C8	I/O	ST					
RD5	53	82	B8	I/O	ST					
RD6	54	83	D7	I/O	ST					
RD7	55	84	C7	I/O	ST					
RD8	42	68	E9	I/O	ST	PORTD Digital I/O.				
RD9	43	69	E10	I/O	ST					
RD10	44	70	D11	I/O	ST					
RD11	45	71	C11	I/O	ST					
RD12		79	A9	I/O	ST					
RD13	_	80	D8	I/O	ST					
RD14		47	L9	I/O	ST					
RD15		48	K9	I/O	ST					
RE0	60	93	A4	I/O	ST					
RE1	61	94	B4	I/O	ST					
RE2	62	98	B3	I/O	ST					
RE3	63	99	A2	I/O	ST					
RE4	64	100	A1	I/O	ST					
RE5	1	3	D3	I/O	ST	PORTE Digital I/O.				
RE6	2	4	C1	I/O	ST					
RE7	3	5	D2	I/O	ST					
RE8	_	18	G1	I/O	ST					
RE9	_	19	G2	I/O	ST					
REFO	30	44	L8	0		Reference Clock Output.				
RF0	58	87	B6	I/O	ST					
RF1	59	88	A6	I/O	ST					
RF2	_	52	K11	I/O	ST					
RF3	33	51	K10	I/O	ST					
RF4	31	49	L10	I/O	ST					
RF5	32	50	L11	I/O	ST	PORTF Digital I/O.				
RF7	34	54	H8	I/O	ST					
RF8	_	53	J10	I/O	ST					
RF12	_	40	K6	I/O	ST					
RF13	_	39	L6	I/O	ST					
Legend:	TTL = TTL inp ANA = Analog		put			Schmitt Trigger input buffer = I ² C/SMBus input buffer				

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number								
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA	I/O	Input Buffer	Description				
RG0	—	90	A5	I/O	ST					
RG1	—	89	E6	I/O	ST					
RG2	37	57	H10	I/O	ST					
RG3	36	56	J11	I/O	ST					
RG6	4	10	E3	I/O	ST					
RG7	5	11	F4	I/O	ST					
RG8	6	12	F2	I/O	ST	PORTG Digital I/O.				
RG9	8	14	F3	I/O	ST					
RG12	—	96	C3	I/O	ST					
RG13	—	97	A3	I/O	ST					
RG14	_	95	C4	I/O	ST					
RG15	—	1	B2	I/O	ST					
RP0	16	25	K2	I/O	ST					
RP1	15	24	K1	I/O	ST					
RP2	42	68	E9	I/O	ST					
RP3	44	70	D11	I/O	ST					
RP4	43	69	E10	I/O	ST					
RP5	—	48	K9	I/O	ST					
RP6	17	26	L1	I/O	ST					
RP7	18	27	J3	I/O	ST					
RP8	21	32	K4	I/O	ST					
RP9	22	33	L4	I/O	ST					
RP10	31	49	L10	I/O	ST	Remappable Peripheral (input or output).				
RP11	46	72	D9	I/O	ST					
RP12	45	71	C11	I/O	ST					
RP13	14	23	J2	I/O	ST					
RP14	29	43	K7	I/O	ST					
RP15	—	53	J10	I/O	ST					
RP16	33	51	K10	I/O	ST					
RP17	32	50	L11	I/O	ST					
RP18	11	20	H1	I/O	ST					
RP19	6	12	F2	I/O	ST					
Legend:	TTL = TTL inpu	ut buffer			ST =	Schmitt Trigger input buffer				

TABLE 1-3: PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED)

ANA = Analog level input/output

I²C[™] = I²C/SMBus input buffer

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number		I/O	Incut	Description				
Function	64-Pin TQFP/QFN	100-Pin TQFP	121-Pin BGA		Input Buffer					
RP20	53	82	B8	I/O	ST					
RP21	4	10	E3	I/O	ST					
RP22	51	78	B9	I/O	ST					
RP23	50	77	A10	I/O	ST					
RP24	49	76	A11	I/O	ST					
RP25	52	81	C8	I/O	ST					
RP26	5	11	F4	I/O	ST	Remappable Peripheral (input or output).				
RP27	8	14	F3	I/O	ST					
RP28	12	21	H2	I/O	ST	-				
RP29	30	44	L8	I/O	ST					
RP30	_	52	K11	I/O	ST					
RP31	_	39	L6	I/O	ST					
RPI32	_	40	K6	I	ST					
RPI33	_	18	G1	I	ST					
RPI34	_	19	G2	Ι	ST					
RPI35	_	67	E8	Ι	ST					
RPI36	_	66	E11	I	ST					
RPI37	48	74	B11	I	ST	Remappable Peripheral (input only).				
RPI38	_	6	D1	Ι	ST					
RPI39	_	7	E4	I	ST					
RPI40	_	8	E2	I	ST					
RPI41	_	9	E1	I	ST	-				
RPI42	_	79	A9	I	ST					
RPI43	_	47	L9	I	ST					
RTCC	42	68	E9	0	_	Real-Time Clock Alarm/Seconds Pulse Output.				
SCL1	44	66	E11	I/O	I ² C™	I2C1 Synchronous Serial Clock Input/Output.				
SCL2	32	58	H11	I/O	l ² C	I2C2 Synchronous Serial Clock Input/Output.				
SCL3	2	4	C1	I/O	l ² C	I2C3 Synchronous Serial Clock Input/Output.				
SCLKI	48	74	B11	0	ANA	Secondary Clock Input.				
SDA1	43	67	E8	I/O	l ² C	I2C1 Data Input/Output.				
SDA2	31	59	G10	I/O	l ² C	I2C2 Data Input/Output.				
SDA3	3	5	D2	I/O	l ² C	I2C3 Data Input/Output.				
SESSEND	55	84	C7	I	ST	USB VBUS Boost Generator, Comparator Input 3.				
SESSVLD	59	88	A6	I	ST	USB VBUS Boost Generator, Comparator Input 2.				
SOSCI	47	73	C10	I	ANA	Secondary Oscillator/Timer1 Clock Input.				
	48	74	B11	0	ANA	Secondary Oscillator/Timer1 Clock Output.				
SOSCO				1						

PIC24FJ256DA210 FAMILY PINOUT DESCRIPTIONS (CONTINUED) **TABLE 1-3**:

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

		Pin Number			Immut			
Function	64-Pin 100-Pin TQFP/QFN TQFP		121-Pin BGA	I/O	Input Buffer	Description		
ТСК	27	38	J6	I	ST	JTAG Test Clock Input.		
TDI	28	60	G11	I	ST	JTAG Test Data Input.		
TDO	24	61	G9	0	_	JTAG Test Data Output.		
TMS	23	17	G3	I	ST	JTAG Test Mode Select Input.		
USBID	33	51	K10	Ι	ST	USB OTG ID (OTG mode only).		
USBOEN	12	21	H2	0	_	USB Output Enable Control (for external transceiver).		
VBUS	34	54	H8	I	ANA	USB Voltage, Host mode (5V).		
VBUSCHG	49	76	A11	0	—	External USB VBUS Charge Output.		
VBUSON	11	20	H1	0	_	USB OTG External Charge Pump Control.		
VBUSST	58	87	B6	Ι	ANA	USB OTG Internal Charge Pump Feedback Control.		
VBUSVLD	58	87	B6	I	ST	USB VBUS Boost Generator, Comparator Input 1.		
VCAP	56	85	B7	Р	_	External Filter Capacitor Connection (regulator enabled		
VCMPST1	58	87	B6	I	ST	USB VBUS Boost Generator, Comparator Input 1.		
VCMPST2	59	88	A6	Ι	ST	USB VBUS Boost Generator, Comparator Input 2.		
VCPCON	49	76	A11	0	_	USB OTG VBUS PWM/Charge Output.		
Vdd	10, 26, 38	2, 16, 37, 46, 62	C2, C9, F8, G5, H6, K8, H4, E5	Ρ	—	Positive Supply for Peripheral Digital Logic and I/O Pins.		
VMIO	14	23	J2	I	ST	USB Differential Minus Input/Output (external transceiver).		
VPIO	13	22	J1	I	ST	USB Differential Plus Input/Output (external transceiver).		
VREF-	15	28, 24 ⁽⁴⁾	L2, K1 ⁽⁴⁾	I	ANA	A/D and Comparator Reference Voltage (low) Input.		
VREF+	16	29, 25 ⁽⁴⁾	K3, K2 ⁽⁴⁾	Ι	ANA	A/D and Comparator Reference Voltage (high) Input.		
Vss	9, 25, 41	15, 36, 45, 65, 75	B10, F5, F10, G6, G7, H3, D4, D5	Ρ	—	Ground Reference for Logic and I/O Pins.		
VSYNC	1	96	C3	0		Graphics Display Vertical Sync Pulse.		
VUSB	35	55	H9	Р	—	USB Voltage (3.3V).		

ANA = Analog level input/output $l^2C^{TM} =$

 $I^2C^{TM} = I^2C/SMBus$ input buffer

Note 1: The alternate EPMP pins are selected when the ALTPMP (CW3<12>) bit is programmed to '0'.

2: The PMSC2 signal will replace the PMA15 signal on the 15-pin PMA when CSF<1:0> = 01 or 10.

3: The PMCS1 signal will replace the PMA14 signal on the 14-pin PMA when CSF<1:0> = 10.

NOTES:

2.0 GUIDELINES FOR GETTING STARTED WITH 16-BIT MICROCONTROLLERS

2.1 Basic Connection Requirements

Getting started with the PIC24FJ256DA210 family of 16-bit microcontrollers requires attention to a minimal set of device pin connections before proceeding with development.

The following pins must always be connected:

- All VDD and VSS pins (see Section 2.2 "Power Supply Pins")
- All AVDD and AVss pins, regardless of whether or not the analog device features are used (see Section 2.2 "Power Supply Pins")
- MCLR pin (see Section 2.3 "Master Clear (MCLR) Pin")
- ENVREG/DISVREG and VCAP/VDDCORE pins (PIC24FJ devices only) (see Section 2.4 "Voltage Regulator Pins (ENVREG/DISVREG and VCAP/VDDCORE)")

These pins must also be connected if they are being used in the end application:

- PGECx/PGEDx pins used for In-Circuit Serial Programming[™] (ICSP[™]) and debugging purposes (see **Section 2.5 "ICSP Pins**")
- OSCI and OSCO pins when an external oscillator source is used

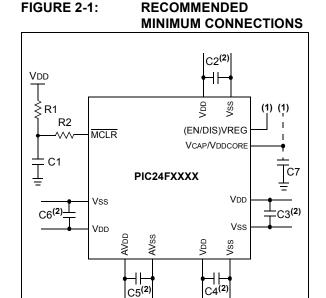
(see Section 2.6 "External Oscillator Pins")

Additionally, the following pins may be required:

• VREF+/VREF- pins used when external voltage reference for analog modules is implemented

Note: The AVDD and AVss pins must always be connected, regardless of whether any of the analog modules are being used.

The minimum mandatory connections are shown in Figure 2-1.



Key (all values are recommendations):

C1 through C6: 0.1 µF, 20V ceramic

C7: 10 $\mu\text{F},$ 6.3V or greater, tantalum or ceramic

R1: 10 kΩ

R2: 100Ω to 470Ω

- Note 1: See Section 2.4 "Voltage Regulator Pins (ENVREG/DISVREG and VCAP/VDDCORE)" for explanation of ENVREG/DISVREG pin connections.
 - 2: The example shown is for a PIC24F device with five VDD/VSs and AVDD/AVSs pairs. Other devices may have more or less pairs; adjust the number of decoupling capacitors appropriately.

2.2 Power Supply Pins

2.2.1 DECOUPLING CAPACITORS

The use of decoupling capacitors on every pair of power supply pins, such as VDD, VSS, AVDD and AVSS is required.

Consider the following criteria when using decoupling capacitors:

- Value and type of capacitor: A 0.1 μ F (100 nF), 10-20V capacitor is recommended. The capacitor should be a low-ESR device with a resonance frequency in the range of 200 MHz and higher. Ceramic capacitors are recommended.
- Placement on the printed circuit board: The decoupling capacitors should be placed as close to the pins as possible. It is recommended to place the capacitors on the same side of the board as the device. If space is constricted, the capacitor can be placed on another layer on the PCB using a via; however, ensure that the trace length from the pin to the capacitor is no greater than 0.25 inch (6 mm).
- Handling high-frequency noise: If the board is experiencing high-frequency noise (upward of tens of MHz), add a second ceramic type capacitor in parallel to the above described decoupling capacitor. The value of the second capacitor can be in the range of 0.01 μ F to 0.001 μ F. Place this second capacitor next to each primary decoupling capacitor. In high-speed circuit designs, consider implementing a decade pair of capacitances as close to the power and ground pins as possible (e.g., 0.1 μ F in parallel with 0.001 μ F).
- Maximizing performance: On the board layout from the power supply circuit, run the power and return traces to the decoupling capacitors first, and then to the device pins. This ensures that the decoupling capacitors are first in the power chain. Equally important is to keep the trace length between the capacitor and the power pins to a minimum, thereby reducing PCB trace inductance.

2.2.2 TANK CAPACITORS

On boards with power traces running longer than six inches in length, it is suggested to use a tank capacitor for integrated circuits including microcontrollers to supply a local power source. The value of the tank capacitor should be determined based on the trace resistance that connects the power supply source to the device, and the maximum current drawn by the device in the application. In other words, select the tank capacitor so that it meets the acceptable voltage sag at the device. Typical values range from 4.7 μ F to 47 μ F.

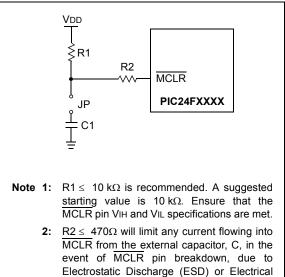
2.3 Master Clear (MCLR) Pin

The MCLR pin provides two specific device functions: device Reset, and device programming and debugging. If programming and debugging are not required in the end application, a direct connection to VDD may be all that is required. The addition of other components, to help increase the application's resistance to spurious Resets from voltage sags, may be beneficial. A typical configuration is shown in Figure 2-1. Other circuit designs may be implemented, depending on the application's requirements.

During programming and debugging, the resistance and capacitance that can be added to the pin must be considered. Device programmers and debuggers drive the MCLR pin. Consequently, specific voltage levels (VIH and VIL) and fast signal transitions must not be adversely affected. Therefore, specific values of R1 and C1 will need to be adjusted based on the application and PCB requirements. For example, it is recommended that the capacitor, C1, be isolated from the MCLR pin during programming and debugging operations by using a jumper (Figure 2-2). The jumper is replaced for normal run-time operations.

Any components associated with the $\overline{\text{MCLR}}$ pin should be placed within 0.25 inch (6 mm) of the pin.

FIGURE 2-2: EXAMPLE OF MCLR PIN CONNECTIONS



Overstress (EOS). Ensure that the MCLR pin

VIH and VIL specifications are met.

2.4 Voltage Regulator Pins (ENVREG/DISVREG and VCAP/VDDCORE)

Note:	This section	n applies	only	to	PIC24FJ
	devices with	regulator.			

The on-chip voltage regulator enable/disable pin (ENVREG or DISVREG, depending on the device family) must always be connected directly to either a supply voltage or to ground. The particular connection is determined by whether or not the regulator is to be used:

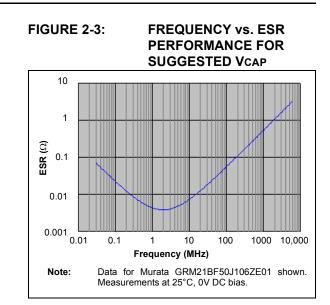
- For ENVREG, tie to VDD to enable the regulator, or to ground to disable the regulator
- For DISVREG, tie to ground to enable the regulator or to VDD to disable the regulator

Refer to **Section 27.2** "**On-Chip Voltage Regulator**" for details on connecting and using the on-chip regulator.

When the regulator is enabled, a low-ESR (<5 Ω) capacitor is required on the VCAP/VDDCORE pin to stabilize the voltage regulator output voltage. The VCAP/VDDCORE pin must not be connected to VDD, and must use a capacitor of 10 μ F connected to ground. The type can be ceramic or tantalum. A suitable example is the Murata GRM21BF50J106ZE01 (10 μ F, 6.3V) or equivalent. Designers may use Figure 2-3 to evaluate ESR equivalence of candidate devices.

The placement of this capacitor should be close to VCAP/VDDCORE. It is recommended that the trace length not exceed 0.25 inch (6 mm). Refer to **Section 30.0 "Electrical Characteristics"** for additional information.

When the regulator is disabled, the VCAP/VDDCORE pin must be tied to a voltage supply at the VDDCORE level. Refer to **Section 30.0 "Electrical Characteristics"** for information on VDD and VDDCORE.



2.5 ICSP Pins

The PGECx and PGEDx pins are used for In-Circuit Serial Programming (ICSP) and debugging purposes. It is recommended to keep the trace length between the ICSP connector and the ICSP pins on the device as short as possible. If the ICSP connector is expected to experience an ESD event, a series resistor is recommended, with the value in the range of a few tens of ohms, not to exceed 100Ω .

Pull-up resistors, series diodes and capacitors on the PGECx and PGEDx pins are not recommended as they will interfere with the programmer/debugger communications to the device. If such discrete components are an application requirement, they should be removed from the circuit during programming and debugging. Alternatively, refer to the AC/DC characteristics and timing requirements information in the respective device Flash programming specification for information on capacitive loading limits and pin input voltage high (VIH) and input low (VIL) requirements.

For device emulation, ensure that the "Communication Channel Select" (i.e., PGECx/PGEDx pins) programmed into the device matches the physical connections for the ICSP to the Microchip debugger/emulator tool.

For more information on available Microchip development tools connection requirements, refer to **Section 28.0 "Development Support"**.

2.6 External Oscillator Pins

Many microcontrollers have options for at least two oscillators: a high-frequency primary oscillator and a low-frequency secondary oscillator (refer to **Section 8.0 "Oscillator Configuration**" for details).

The oscillator circuit should be placed on the same side of the board as the device. Place the oscillator circuit close to the respective oscillator pins with no more than 0.5 inch (12 mm) between the circuit components and the pins. The load capacitors should be placed next to the oscillator itself, on the same side of the board.

Use a grounded copper pour around the oscillator circuit to isolate it from surrounding circuits. The grounded copper pour should be routed directly to the MCU ground. Do not run any signal traces or power traces inside the ground pour. Also, if using a two-sided board, avoid any traces on the other side of the board where the crystal is placed.

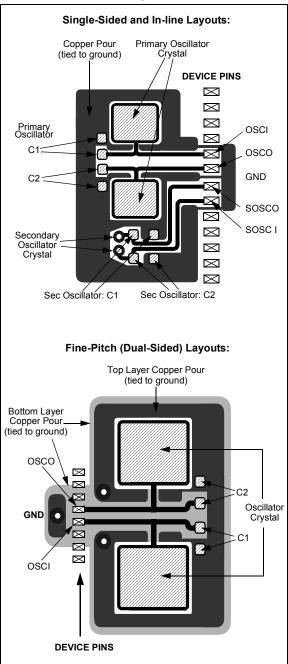
Layout suggestions are shown in Figure 2-4. In-line packages may be handled with a single-sided layout that completely encompasses the oscillator pins. With fine-pitch packages, it is not always possible to completely surround the pins and components. A suitable solution is to tie the broken guard sections to a mirrored ground layer. In all cases, the guard trace(s) must be returned to ground.

In planning the application's routing and I/O assignments, ensure that adjacent port pins and other signals in close proximity to the oscillator are benign (i.e., free of high frequencies, short rise and fall times and other similar noise).

For additional information and design guidance on oscillator circuits, please refer to these Microchip Application Notes, available at the corporate web site (www.microchip.com):

- AN826, "Crystal Oscillator Basics and Crystal Selection for rfPIC™ and PICmicro[®] Devices"
- AN849, "Basic PICmicro[®] Oscillator Design"
- AN943, "Practical PICmicro[®] Oscillator Analysis and Design"
- AN949, "Making Your Oscillator Work"

FIGURE 2-4: SUGGESTED PLACEMENT OF THE OSCILLATOR CIRCUIT



2.7 Configuration of Analog and Digital Pins During ICSP Operations

If an ICSP compliant emulator is selected as a debugger, it automatically initializes all of the A/D input pins (ANx) as "digital" pins. Depending on the particular device, this is done by setting all bits in the ADnPCFG register(s), or clearing all bit in the ANSx registers.

All PIC24F devices will have either one or more ADnPCFG registers or several ANSx registers (one for each port); no device will have both. Refer to (Section 23.0 "10-Bit High-Speed A/D Converter") for more specific information.

The bits in these registers that correspond to the A/D pins that initialized the emulator must not be changed by the user application firmware; otherwise, communication errors will result between the debugger and the device.

If your application needs to use certain A/D pins as analog input pins during the debug session, the user application must modify the appropriate bits during initialization of the ADC module, as follows:

- For devices with an ADnPCFG register, clear the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.
- For devices with ANSx registers, set the bits corresponding to the pin(s) to be configured as analog. Do not change any other bits, particularly those corresponding to the PGECx/PGEDx pair, at any time.

When a Microchip debugger/emulator is used as a programmer, the user application firmware must correctly configure the ADnPCFG or ANSx registers. Automatic initialization of this register is only done during debugger operation. Failure to correctly configure the register(s) will result in all A/D pins being recognized as analog input pins, resulting in the port value being read as a logic '0', which may affect user application functionality.

2.8 Unused I/Os

Unused I/O pins should be configured as outputs and driven to a logic low state. Alternatively, connect a 1 k Ω to 10 k Ω resistor to Vss on unused pins and drive the output to logic low.

 $[\]ensuremath{\textcircled{}^{\odot}}$ 2010 Microchip Technology Inc.

NOTES:

3.0 CPU

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 44. "CPU with Extended Data Space (EDS)" (DS39732). The information in this data sheet supersedes the information in the FRM.

The PIC24F CPU has a 16-bit (data) modified Harvard architecture with an enhanced instruction set and a 24-bit instruction word with a variable length opcode field. The Program Counter (PC) is 23 bits wide and addresses up to 4M instructions of user program memory space. A single-cycle instruction prefetch mechanism is used to help maintain throughput and provides predictable execution. All instructions execute in a single cycle, with the exception of instructions that change the program flow, the double-word move (MOV.D) instruction and the table instructions. Overhead-free program loop constructs are supported using the REPEAT instructions, which are interruptible at any point.

PIC24F devices have sixteen, 16-bit working registers in the programmer's model. Each of the working registers can act as a data, address or address offset register. The 16th working register (W15) operates as a Software Stack Pointer for interrupts and calls.

The lower 32 Kbytes of the data space can be accessed linearly. The upper 32 Kbytes of the data space are referred to as extended data space to which the extended data RAM, EPMP memory space or program memory can be mapped.

The Instruction Set Architecture (ISA) has been significantly enhanced beyond that of the PIC18, but maintains an acceptable level of backward compatibility. All PIC18 instructions and addressing modes are supported, either directly, or through simple macros. Many of the ISA enhancements have been driven by compiler efficiency needs. The core supports Inherent (no operand), Relative, Literal, Memory Direct Addressing modes along with three groups of addressing modes. All modes support Register Direct and various Register Indirect modes. Each group offers up to seven addressing modes. Instructions are associated with predefined addressing modes depending upon their functional requirements.

For most instructions, the core is capable of executing a data (or program data) memory read, a working register (data) read, a data memory write and a program (instruction) memory read per instruction cycle. As a result, three parameter instructions can be supported, allowing trinary operations (that is, A + B = C) to be executed in a single cycle.

A high-speed, 17-bit x 17-bit multiplier has been included to significantly enhance the core arithmetic capability and throughput. The multiplier supports Signed, Unsigned and Mixed mode, 16-bit x 16-bit or 8-bit x 8-bit, integer multiplication. All multiply instructions execute in a single cycle.

The 16-bit ALU has been enhanced with integer divide assist hardware that supports an iterative non-restoring divide algorithm. It operates in conjunction with the REPEAT instruction looping mechanism and a selection of iterative divide instructions to support 32-bit (or 16-bit), divided by 16-bit, integer signed and unsigned division. All divide operations require 19 cycles to complete but are interruptible at any cycle boundary.

The PIC24F has a vectored exception scheme with up to 8 sources of non-maskable traps and up to 118 interrupt sources. Each interrupt source can be assigned to one of seven priority levels.

A block diagram of the CPU is shown in Figure 3-1.

3.1 Programmer's Model

The programmer's model for the PIC24F is shown in Figure 3-2. All registers in the programmer's model are memory mapped and can be manipulated directly by instructions. A description of each register is provided in Table 3-1. All registers associated with the programmer's model are memory mapped.

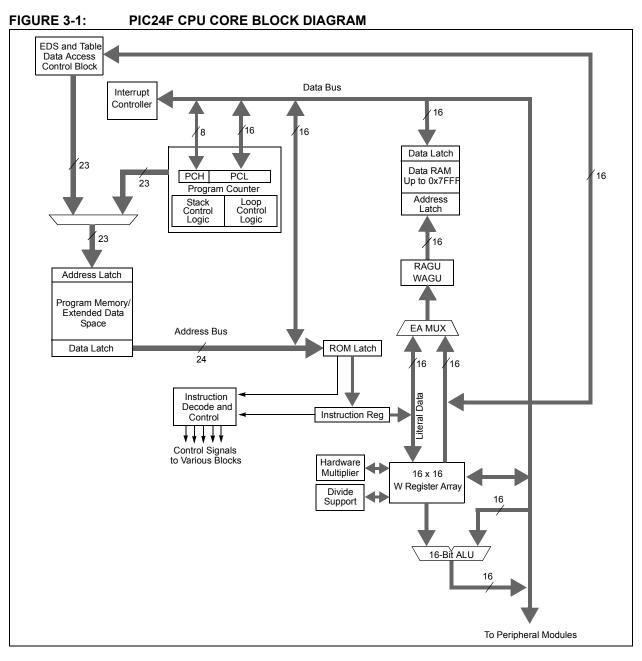


TABLE 3-1:	CPU CORE	REGISTERS
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Register(s) Name	Description		
W0 through W15	Working Register Array		
PC	23-Bit Program Counter		
SR	ALU STATUS Register		
SPLIM	Stack Pointer Limit Value Register		
TBLPAG	Table Memory Page Address Register		
RCOUNT	Repeat Loop Counter Register		
CORCON	CPU Control Register		
DISICNT	Disable Interrupt Count Register		
DSRPAG	Data Space Read Page Register		
DSWPAG	Data Space Write Page Register		

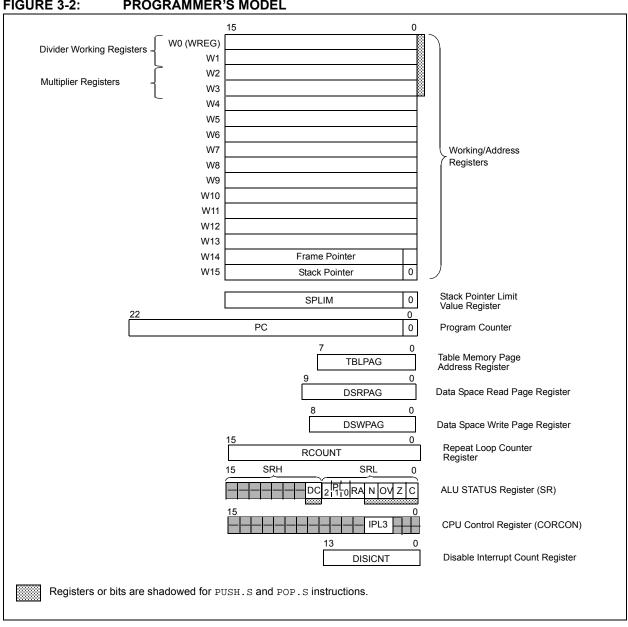


FIGURE 3-2: **PROGRAMMER'S MODEL**

3.2 CPU Control Registers

REGISTER 3-1: SR: ALU STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0, HSC
—	—	—	—	—	_	_	DC
bit 15							bit 8

R/W-0, HSC ⁽¹⁾	R/W-0, HSC ⁽¹⁾	R/W-0, HSC ⁽¹⁾	R-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC
IPL2 ⁽²⁾	IPL1 ⁽²⁾	IPL0 ⁽²⁾	RA	N	OV	Z	С
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ad as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-9	Unimplemented: Read as '0'
bit 8	DC: ALU Half Carry/Borrow bit
	1 = A carry out from the 4 th low-order bit (for byte-sized data) or 8 th low-order bit (for word-sized data) of the result occurred
	0 = No carry out from the 4 th or 8 th low-order bit of the result has occurred
bit 7-5	IPL<2:0>: CPU Interrupt Priority Level Status bits ^(1,2)
	111 = CPU interrupt priority level is 7 (15); user interrupts are disabled
	110 = CPU interrupt priority level is 6 (14)
	101 = CPU interrupt priority level is 5 (13) 100 = CPU interrupt priority level is 4 (12)
	011 = CPU interrupt priority level is 3 (11)
	010 = CPU interrupt priority level is 2 (10)
	001 = CPU interrupt priority level is 1 (9)
	000 = CPU interrupt priority level is 0 (8)
bit 4	RA: REPEAT Loop Active bit
	1 = REPEAT loop in progress
1.11.0	0 = REPEAT loop not in progress
bit 3	N: ALU Negative bit
	 1 = Result was negative 0 = Result was not negative (zero or positive)
bit 2	OV: ALU Overflow bit
DILZ	1 = Overflow occurred for signed (2's complement) arithmetic in this arithmetic operation
	0 = No overflow has occurred
bit 1	Z: ALU Zero bit
	1 = An operation, which affects the Z bit, has set it at some time in the past
	0 = The most recent operation, which affects the Z bit, has cleared it (i.e., a non-zero result)
bit 0	C: ALU Carry/Borrow bit
	1 = A carry out from the Most Significant bit of the result occurred
	0 = No carry out from the Most Significant bit of the result occurred
Note 1:	The IPL Status bits are read-only when NSTDIS (INTCON1<15>) = 1.
2:	The IPL Status bits are concatenated with the IPL3 (CORCON<3>) bit to form the CPU Interrupt Priority

Level (IPL). The value in parentheses indicates the IPL when IPL3 = 1.

REGISTER 3-2: CORCON: CPU CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/C-0, HSC	R-1	U-0	U-0
—	_	—	—	IPL3 ⁽¹⁾	r	—	—
bit 7							bit 0

Legend:	C = Clearable bit	r = Reserved bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4 Unimplemented: Read as '0'

- bit 3 IPL3: CPU Interrupt Priority Level Status bit⁽¹⁾ 1 = CPU interrupt priority level is greater than 7 0 = CPU interrupt priority level is 7 or less
- bit 2 Reserved: Read as '1'
- bit 1-0 Unimplemented: Read as '0'
- **Note 1:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU interrupt priority level; see Register 3-1 for bit description.

3.3 Arithmetic Logic Unit (ALU)

The PIC24F ALU is 16 bits wide and is capable of addition, subtraction, bit shifts and logic operations. Unless otherwise mentioned, arithmetic operations are 2's complement in nature. Depending on the operation, the ALU may affect the values of the Carry (C), Zero (Z), Negative (N), Overflow (OV) and Digit Carry (DC) Status bits in the SR register. The C and DC Status bits operate as Borrow and Digit Borrow bits, respectively, for subtraction operations.

The ALU can perform 8-bit or 16-bit operations, depending on the mode of the instruction that is used. Data for the ALU operation can come from the W register array, or data memory, depending on the addressing mode of the instruction. Likewise, output data from the ALU can be written to the W register array or a data memory location.

The PIC24F CPU incorporates hardware support for both multiplication and division. This includes a dedicated hardware multiplier and support hardware for 16-bit divisor division.

3.3.1 MULTIPLIER

The ALU contains a high-speed, 17-bit x 17-bit multiplier. It supports unsigned, signed or mixed sign operation in several multiplication modes:

- 1. 16-bit x 16-bit signed
- 2. 16-bit x 16-bit unsigned
- 3. 16-bit signed x 5-bit (literal) unsigned
- 4. 16-bit unsigned x 16-bit unsigned
- 5. 16-bit unsigned x 5-bit (literal) unsigned
- 6. 16-bit unsigned x 16-bit signed
- 7. 8-bit unsigned x 8-bit unsigned

3.3.2 DIVIDER

The divide block supports signed and unsigned integer divide operations with the following data sizes:

- 1. 32-bit signed/16-bit signed divide
- 2. 32-bit unsigned/16-bit unsigned divide
- 3. 16-bit signed/16-bit signed divide
- 4. 16-bit unsigned/16-bit unsigned divide

The quotient for all divide instructions ends up in W0 and the remainder in W1. 16-bit signed and unsigned DIV instructions can specify any W register for both the 16-bit divisor (Wn), and any W register (aligned) pair (W(m + 1):Wm) for the 32-bit dividend. The divide algorithm takes one cycle per bit of divisor, so both 32-bit/16-bit and 16-bit/16-bit instructions take the same number of cycles to execute.

3.3.3 MULTI-BIT SHIFT SUPPORT

The PIC24F ALU supports both single bit and single-cycle, multi-bit arithmetic and logic shifts. Multi-bit shifts are implemented using a shifter block, capable of performing up to a 15-bit arithmetic right shift, or up to a 15-bit left shift, in a single cycle. All multi-bit shift instructions only support Register Direct Addressing for both the operand source and result destination.

A full summary of instructions that use the shift operation is provided in Table 3-2.

TABLE 3-2: INSTRUCTIONS THAT USE THE SINGLE BIT AND MULTI-BIT SHIFT OPERATION

Instruction	Description			
ASR	Arithmetic shift right source register by one or more bits.			
SL	Shift left source register by one or more bits.			
LSR	Logical shift right source register by one or more bits.			

4.0 MEMORY ORGANIZATION

As Harvard architecture devices, PIC24F microcontrollers feature separate program and data memory spaces and busses. This architecture also allows direct access of program memory from the data space during code execution.

4.1 **Program Memory Space**

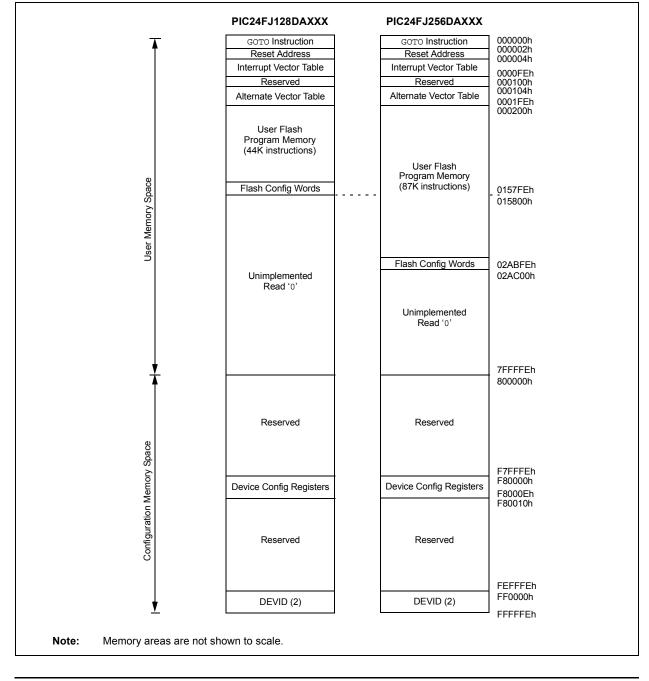
The program address memory space of the PIC24FJ256DA210 family devices is 4M instructions. The space is addressable by a 24-bit value derived

from either the 23-bit Program Counter (PC) during program execution, or from table operation or data space remapping, as described in **Section 4.3 "Interfacing Program and Data Memory Spaces"**.

User access to the program memory space is restricted to the lower half of the address range (000000h to 7FFFFFh). The exception is the use of TBLRD/TBLWT operations, which use TBLPAG<7> to permit access to the Configuration bits and Device ID sections of the configuration memory space.

Memory maps for the PIC24FJ256DA210 family of devices are shown in Figure 4-1.

FIGURE 4-1: PROGRAM SPACE MEMORY MAP FOR PIC24FJ256DA210 FAMILY DEVICES



4.1.1 PROGRAM MEMORY ORGANIZATION

The program memory space is organized in word-addressable blocks. Although it is treated as 24 bits wide, it is more appropriate to think of each address of the program memory as a lower and upper word, with the upper byte of the upper word being unimplemented. The lower word always has an even address, while the upper word has an odd address (Figure 4-2).

Program memory addresses are always word-aligned on the lower word and addresses are incremented or decremented by two during code execution. This arrangement also provides compatibility with data memory space addressing and makes it possible to access data in the program memory space.

4.1.2 HARD MEMORY VECTORS

All PIC24F devices reserve the addresses between 0x00000 and 0x000200 for hard coded program execution vectors. A hardware Reset vector is provided to redirect code execution from the default value of the PC on device Reset to the actual start of code. A GOTO instruction is programmed by the user at 0x000000 with the actual address for the start of code at 0x000002.

PIC24F devices also have two interrupt vector tables, located from 0x000004 to 0x0000FF and 0x000100 to 0x0001FF. These vector tables allow each of the many device interrupt sources to be handled by separate ISRs. A more detailed discussion of the interrupt vector tables is provided in **Section 7.1 "Interrupt Vector Table"**.

4.1.3 FLASH CONFIGURATION WORDS

In PIC24FJ256DA210 family devices, the top four words of on-chip program memory are reserved for configuration information. On device Reset, the configuration information is copied into the appropriate Configuration register. The addresses of the Flash Configuration Word for devices in the PIC24FJ256DA210 family are shown in Table 4-1. Their location in the memory map is shown with the other memory vectors in Figure 4-1.

The Configuration Words in program memory are a compact format. The actual Configuration bits are mapped in several different registers in the configuration memory space. Their order in the Flash Configuration Words does not reflect a corresponding arrangement in the configuration space. Additional details on the device Configuration Words are provided in **Section 27.1** "Configuration Bits".

TABLE 4-1:	FLASH CONFIGURATION
	WORDS FOR
	PIC24FJ256DA210 FAMILY
	DEVICES

Device	Program Memory (Words)	Configuration Word Addresses
PIC24FJ128DAXXX	44,032	0x0157F8:0x0157FE
PIC24FJ256DAXXX	87,552	0x02ABF8:0x02ABFE

msw Address		ificant word		least significant wo		PC Address (Isw Address
	'	23	16	8	0	
0x000001	00000000					0x000000
0x000003	00000000					0x000002
0x000005	00000000					0x000004
0x000007	00000000					0x000006
	<u> </u>	\land		~		
	Program Memory 'Phantom' Byte (read as '0')	1	Instru	ction Width		

4.2 Data Memory Space

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 45. "Data Memory with Extended Data Space" (DS39733). The information in this data sheet supersedes the information in the FRM.

The PIC24F core has a 16-bit wide data memory space, addressable as a single linear range.

The data space is accessed using two Address Generation Units (AGUs), one each for read and write operations. The data space memory map is shown in Figure 4-3.

The 16-bit wide data addresses in the data memory space point to bytes within the Data Space (DS). This gives a DS address range of 64 Kbytes or 32K words. The lower 32 Kbytes (0x0000 to 0x7FFF) of DS is compatible with the PIC24F microcontrollers without EDS.

The upper 32 Kbytes of data memory address space (0x8000 - 0xFFFF) are used as an EDS window.

The EDS window is used to access all memory region implemented in EDS, as shown in Figure 4-4.

The EDS includes any additional internal data memory not accessible by the lower 32-Kbyte data address space and any external memory through EPMP. For more details on accessing internal extended data memory, refer to the "*PIC24F Family Reference Manual*", Section 45. "Data Memory with Extended Data Space (EDS)" (DS39733). For more details on accessing external memory using EPMP, refer to the "*PIC24F Family Reference Manual*", Section 42. "Enhanced Parallel Master Port (EPMP)" (DS39730). In PIC24F microcontrollers with EDS, the program memory can also be read from EDS. This is called Program Space Visibility (PSV). Table 4-2 lists the total memory accessible by each of the devices in this family.

The EDS is organized as pages, with a single page called an EDS page that equals the EDS window (32 Kbytes). A particular EDS page is selected through the Data Space Read register (DSRPAG) or Data Space Write register (DSWPAG). For PSV, only the DSRPAG register is used. The combination of the DSRPAG register value and the 16-bit wide data address forms a 24-bit Effective Address (EA). For more information on EDS, refer to **Section 4.3.3 "Reading Data from Program Memory Using EDS"**.

Devices	Internal RAM	External RAM Access Using EPMP	Program Memory Access Using EDS
PIC24FJXXXDA210	96 Kbytes (30K + 66K ⁽¹⁾)	Yes (up to 16 MB)	Yes
PIC24FJXXXDA206	96 Kbytes (30K + 66K ⁽¹⁾)	No	Yes
PIC24FJXXXDA110	24 Kbytes	Yes (up to 16 MB)	Yes
PIC24FJXXXDA106	24 Kbytes	No	Yes

TABLE 4-2:TOTAL MEMORY ACCESSIBLE BY THE DEVICE

Note 1: The internal RAM above 30 Kbytes can be accessed through EDS window.

4.2.1 DATA SPACE WIDTH

The data memory space is organized in byte-addressable, 16-bit wide blocks. Data is aligned in data memory and registers as 16-bit words, but all data space EAs resolve to bytes. The Least Significant Bytes (LSBs) of each word have even addresses, while the Most Significant Bytes (MSBs) have odd addresses.

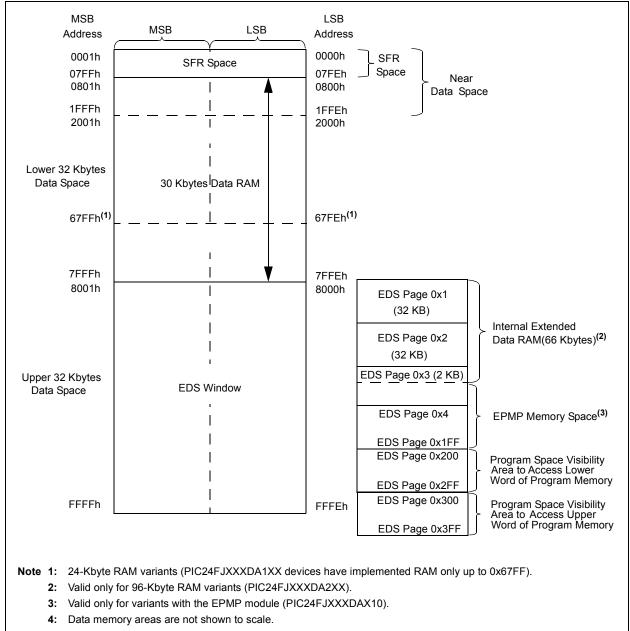


FIGURE 4-3: DATA SPACE MEMORY MAP FOR PIC24FJ256DA210 FAMILY DEVICES⁽⁴⁾

4.2.2 DATA MEMORY ORGANIZATION AND ALIGNMENT

To maintain backward compatibility with PIC^{\otimes} MCUs and improve data space memory usage efficiency, the PIC24F instruction set supports both word and byte operations. As a consequence of byte accessibility, all EA calculations are internally scaled to step through word-aligned memory. For example, the core recognizes that Post-Modified Register Indirect Addressing mode [Ws++] will result in a value of Ws + 1 for byte operations and Ws + 2 for word operations.

Data byte reads will read the complete word, which contains the byte, using the LSB of any EA to determine which byte to select. The selected byte is placed onto the LSB of the data path. That is, data memory and registers are organized as two parallel, byte-wide entities with shared (word) address decode but separate write lines. Data byte writes only write to the corresponding side of the array or register which matches the byte address.

All word accesses must be aligned to an even address. Misaligned word data fetches are not supported, so care must be taken when mixing byte and word operations or translating from 8-bit MCU code. If a misaligned read or write is attempted, an address error trap will be generated. If the error occurred on a read, the instruction underway is completed; if it occurred on a write, the instruction will be executed but the write will not occur. In either case, a trap is then executed, allowing the system and/or user to examine the machine state prior to execution of the address Fault.

All byte loads into any W register are loaded into the LSB. The Most Significant Byte (MSB) is not modified.

A sign-extend instruction (SE) is provided to allow users to translate 8-bit signed data to 16-bit signed values. Alternatively, for 16-bit unsigned data, users can clear the MSB of any W register by executing a zero-extend (\mathbb{ZE}) instruction on the appropriate address.

Although most instructions are capable of operating on word or byte data sizes, it should be noted that some instructions operate only on words.

4.2.3 NEAR DATA SPACE

The 8-Kbyte area between 0000h and 1FFFh is referred to as the near data space. Locations in this space are directly addressable via a 13-bit absolute address field within all memory direct instructions. The remainder of the data space is addressable indirectly. Additionally, the whole data space is addressable using MOV instructions, which support Memory Direct Addressing with a 16-bit address field.

4.2.4 SPECIAL FUNCTION REGISTER (SFR) SPACE

The first 2 Kbytes of the near data space, from 0000h to 07FFh, are primarily occupied with Special Function Registers (SFRs). These are used by the PIC24F core and peripheral modules for controlling the operation of the device.

SFRs are distributed among the modules that they control and are generally grouped together by module. Much of the SFR space contains unused addresses; these are read as '0'. A diagram of the SFR space, showing where the SFRs are actually implemented, is shown in Table 4-3. Each implemented area indicates a 32-byte region where at least one address is implemented as an SFR. A complete list of implemented SFRs, including their addresses, is shown in Tables 4-4 throughTable 4-34.

			SFR	Space Add	ess					
	xx00	xx20	xx40	xx60	хх	80	xxA0	xxC0	xxE0	
000h		Core		ICN			Inter	rupts		
100h	Oh Timers Capture Compare Oh I²C™ UART SPI/UART SPI/I²C SPI UART I/O									
200h	I ² C™	UART	SPI/UART	SPI/I ² C	S	PI	UART	I/	0	
300h		ADC/CTMU		—	_	_	—	_	—	
400h	—	_	_	—			USB		ANSEL	
500h	—	—		—	_	_	_	_	_	
600h	EPMP	RTC/Comp	CRC	_			PPS		_	
700h	GFX C	ontroller	System	NVM/PMD	_	_	_	_	—	

TABLE 4-3:IMPLEMENTED REGIONS OF SFR DATA SPACE

Legend: — = No implemented SFRs in this block

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IABLE 4-	4. U		RE REG									_	_	_		_		_
File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
WREG0	0000								Working R	egister 0								0000
WREG1	0002								Working R	egister 1								0000
WREG2	0004								Working R	egister 2								0000
WREG3	0006								Working R	egister 3								0000
WREG4	0008								Working R	egister 4								0000
WREG5	000A								Working R	egister 5								0000
WREG6	000C								Working R	egister 6								0000
WREG7	000E								Working R	egister 7								0000
WREG8	0010								Working R	egister 8								0000
WREG9	0012								Working R	egister 9								0000
WREG10	0014								Working Re	egister 10								0000
WREG11	0016								Working Re	egister 11								0000
WREG12	0018								Working Re	egister 12								0000
WREG13	001A								Working Re	egister 13								0000
WREG14	001C								Working Re	egister 14								0000
WREG15	001E								Working Re	egister 15								0800
SPLIM	0020							Stack	Pointer Limi	t Value Reg	gister							xxxx
PCL	002E			-	_			Program	n Counter L	ow Word Re	egister							0000
PCH	0030		—	—	—	-	_		—			Progran	n Counter R	Register Hig	h Byte			0000
DSRPAG	0032		—	—	—	-	_			Exte	ended Data	Space Rea	d Page Ado	dress Regis	ter			0001
DSWPAG ⁽¹⁾	0034		—	—	—	-	_				Extende	d Data Spac	e Write Pag	e Address F	Register			0001
RCOUNT	0036							Repe	eat Loop Co	unter Regis	ster			_			-	xxxx
SR	0042	-	—	—	—	—	_	-	DC	IPL2	IPL1	IPL0	RA	N	OV	Z	С	0000
CORCON	0044	-	—	—	—	—	_		—	—	—	—	—	IPL3	r	—	-	0004
DISICNT	0052	-	—						Disable	Interrupts	Counter Re	gister						xxxx
TBLPAG	0054	-	—	—	_	_	_	_	_			Table M	emory Page	Address R	egister			0000

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TABLE 4-4. CPU CORE REGISTERS MAP

 Legend:
 — = unimplemented, read as '0'; r = Reserved bit. Reset values are shown in hexadecimal.

 Note
 1:
 Reserved in PIC24FJXXXDA106 devices; do not use.



TABLE 4-5: **ICN REGISTER MAP**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CNPD1	0056	CN15PDE	CN14PDE	CN13PDE	CN12PDE	CN11PDE	CN10PDE	CN9PDE	CN8PDE	CN7PDE	CN6PDE	CN5PDE	CN4PDE	CN3PDE	CN2PDE	CN1PDE	CN0PDE	0000
CNPD2	0058	CN31PDE	CN30PDE	CN29PDE	CN28PDE	CN27PDE	CN26PDE	CN25PDE	CN24PDE	CN23PDE	CN22PDE	CN21PDE ⁽¹⁾	CN20PDE ⁽¹⁾	CN19PDE ⁽¹⁾	CN18PDE	CN17PDE	CN16PDE	0000
CNPD3	005A	CN47PDE ⁽¹⁾	CN46PDE ⁽¹⁾	CN45PDE ⁽¹⁾	CN44PDE ⁽¹⁾	CN43PDE ⁽¹⁾	CN42PDE ⁽¹⁾	CN41PDE ⁽¹⁾	CN40PDE ⁽¹⁾	CN39PDE ⁽¹⁾	CN38PDE ⁽¹⁾	CN37PDE ⁽¹⁾	CN36PDE ⁽¹⁾	CN35PDE ⁽¹⁾	CN34PDE ⁽¹⁾	CN33PDE ⁽¹⁾	CN32PDE	0000
CNPD4	005C	CN63PDE	CN62PDE	CN61PDE	CN60PDE	CN59PDE	CN58PDE	CN57PDE ⁽¹⁾	CN56PDE	CN55PDE	CN54PDE	CN53PDE	CN52PDE	CN51PDE	CN50PDE	CN49PDE	CN48PDE ⁽¹⁾	0000
CNPD5	005E	CN79PDE ⁽¹⁾	CN78PDE ⁽¹⁾	CN77PDE ⁽¹⁾	CN76PDE ⁽¹⁾	CN75PDE ⁽¹⁾	CN74PDE ⁽¹⁾	CN73PDE ⁽¹⁾	_	CN71PDE	CN70PDE ⁽¹⁾	CN69PDE	CN68PDE	CN67PDE ⁽¹⁾	CN66PDE ⁽¹⁾	CN65PDE	CN64PDE	0000
CNPD6	0060	—	_	_	_	_	_	_	_	_	_	_	CN84PDE	CN83PDE	CN82PDE ⁽¹⁾	CN81PDE ⁽¹⁾	CN80PDE ⁽¹⁾	0000
CNEN1	0062	CN15IE	CN14IE	CN13IE	CN12IE	CN11IE	CN10IE	CN9IE	CN8IE	CN7IE	CN6IE	CN5IE	CN4IE	CN3IE	CN2IE	CN1IE	CN0IE	0000
CNEN2	0064	CN31IE	CN30IE	CN29IE	CN28IE	CN27IE	CN26IE	CN25IE	CN24IE	CN23IE	CN22IE	CN21IE ⁽¹⁾	CN20IE ⁽¹⁾	CN19IE ⁽¹⁾	CN18IE	CN17IE	CN16IE	0000
CNEN3	0066	CN47IE ⁽¹⁾	CN46IE ⁽¹⁾	CN45IE ⁽¹⁾	CN44IE ⁽¹⁾	CN43IE ⁽¹⁾	CN42IE ⁽¹⁾	CN41IE ⁽¹⁾	CN40IE ⁽¹⁾	CN39IE ⁽¹⁾	CN38IE ⁽¹⁾	CN37IE ⁽¹⁾	CN36IE ⁽¹⁾	CN35IE ⁽¹⁾	CN34IE ⁽¹⁾	CN33IE ⁽¹⁾	CN32IE	0000
CNEN4	0068	CN63IE	CN62IE	CN61IE	CN60IE	CN59IE	CN58IE	CN57IE ⁽¹⁾	CN56IE	CN55IE	CN54IE	CN53IE	CN52IE	CN51IE	CN50IE	CN49IE	CN48IE ⁽¹⁾	0000
CNEN5	006A	CN79IE ⁽¹⁾	CN78IE ⁽¹⁾	CN77IE ⁽¹⁾	CN76IE ⁽¹⁾	CN75IE ⁽¹⁾	CN74IE ⁽¹⁾	CN73IE ⁽¹⁾	_	CN71IE	CN70IE ⁽¹⁾	CN69IE	CN68IE	CN67IE ⁽¹⁾	CN66IE ⁽¹⁾	CN65IE	CN64IE	0000
CNEN6	006C	—	_	_	_	_	_	_	_	_	_	_	CN84IE	CN83IE	CN82IE ⁽¹⁾	CN81IE ⁽¹⁾	CN80IE ⁽¹⁾	0000
CNPU1	006E	CN15PUE	CN14PUE	CN13PUE	CN12PUE	CN11PUE	CN10PUE	CN9PUE	CN8PUE	CN7PUE	CN6PUE	CN5PUE	CN4PUE	CN3PUE	CN2PUE	CN1PUE	CN0PUE	0000
CNPU2	0070	CN31PUE	CN30PUE	CN29PUE	CN28PUE	CN27PUE	CN26PUE	CN25PUE	CN24PUE	CN23PUE	CN22PUE	CN21PUE ⁽¹⁾	CN20PUE ⁽¹⁾	CN19PUE ⁽¹⁾	CN18PUE	CN17PUE	CN16PUE	0000
CNPU3	0072	CN47PUE ⁽¹⁾	CN46PUE ⁽¹⁾	CN45PUE ⁽¹⁾	CN44PUE ⁽¹⁾	CN43PUE ⁽¹⁾	CN42PUE ⁽¹⁾	CN41PUE ⁽¹⁾	CN40PUE ⁽¹⁾	CN39PUE ⁽¹⁾	CN38PUE ⁽¹⁾	CN37PUE ⁽¹⁾	CN36PUE ⁽¹⁾	CN35PUE ⁽¹⁾	CN34PUE ⁽¹⁾	CN33PUE ⁽¹⁾	CN32PUE	0000
CNPU4	0074	CN63PUE	CN62PUE	CN61PUE	CN60PUE	CN59PUE	CN58PUE	CN57PUE ⁽¹⁾	CN56PUE	CN55PUE	CN54PUE	CN53PUE	CN52PUE	CN51PUE	CN50PUE	CN49PUE	CN48PUE ⁽¹⁾	0000
CNPU5	0076	CN79PUE ⁽¹⁾	CN78PUE ⁽¹⁾	CN77PUE ⁽¹⁾	CN76PUE ⁽¹⁾	CN75PUE ⁽¹⁾	CN74PUE ⁽¹⁾	CN73PUE ⁽¹⁾	_	CN71PUE	CN70PUE(1)	CN69PUE	CN68PUE	CN67PUE ⁽¹⁾	CN66PUE ⁽¹⁾	CN65PUE	CN64PUE	0000
CNPU6	0078	—	_	_	_	_	_			_	_		CN84PUE	CN83PUE	CN82PUE ⁽¹⁾	CN81PUE ⁽¹⁾	CN80PUE ⁽¹⁾	0000

 Legend:
 — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Unimplemented in 64-pin devices; read as '0'.

TABLE	4-6:	INT	ERRUP	т солт	ROLLE	R REG		IAP										
File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
INTCON1	0080	NSTDIS	—	—	—	—	—	_	—	_	_	—	MATHERR	ADDRERR	STKERR	OSCFAIL	—	0000
INTCON2	0082	ALTIVT	DISI	_	_	_	_	_	_	_	_	_	INT4EP	INT3EP	INT2EP	INT1EP	INT0EP	0000
IFS0	0084	_	_	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPF1IF	T3IF	T2IF	OC2IF	IC2IF	_	T1IF	OC1IF	IC1IF	INTOIF	0000
IFS1	0086	U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF	_	IC8IF	IC7IF	_	INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF	0000
IFS2	0088		_	PMPIF ⁽¹⁾	OC8IF	OC7IF	OC6IF	OC5IF	IC6IF	IC5IF	IC4IF	IC3IF	_	_	_	SPI2IF	SPF2IF	0000
IFS3	008A	-	RTCIF	_	_	_	—	_	_	_	INT4IF	INT3IF	_	_	MI2C2IF	SI2C2IF	_	0000
IFS4	008C	-	_	CTMUIF	_	—	_	_	LVDIF	_	_	-	_	CRCIF	U2ERIF	U1ERIF	_	0000
IFS5	008E	-	_	IC9IF	OC9IF	SPI3IF	SPF3IF	U4TXIF	U4RXIF	U4ERIF	USB1IF	MI2C3IF	SI2C3IF	U3TXIF	U3RXIF	U3ERIF	_	0000
IFS6	0090	_	_	_	—	—	—	_	_	_	_	—	GFX1IF	_	_	_	_	0000
IEC0	0094	-	_	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPF1IE	T3IE	T2IE	OC2IE	IC2IE	_	T1IE	OC1IE	IC1IE	INTOIE	0000
IEC1	0096	U2TXIE	U2RXIE	INT2IE	T5IE	T4IE	OC4IE	OC3IE	—	IC8IE	IC7IE	—	INT1IE	CNIE	CMIE	MI2C1IE	SI2C1IE	0000
IEC2	0098	_	_	PMPIE ⁽¹⁾	OC8IE	OC7IE	OC6IE	OC5IE	IC6IE	IC5IE	IC4IE	IC3IE	_	_	_	SPI2IE	SPF2IE	0000
IEC3	009A	_	RTCIE	_	—	—	_	_	_	_	INT4IE	INT3IE	—	_	MI2C2IE	SI2C2IE	_	0000
IEC4	009C	_	_	CTMUIE	—	—	—	_	LVDIE	_	_	—	_	CRCIE	U2ERIE	U1ERIE	_	0000
IEC5	009E	_	_	IC9IE	OC9IE	SPI3IE	SPF3IE	U4TXIE	U4RXIE	U4ERIE	USB1IE	MI2C3IE	SI2C3IE	U3TXIE	U3RXIE	U3ERIE	_	0000
IEC6	00A0	-	_	_	_	—	_	_	_	_	_	-	GFX1IE	_	_	_	_	0000
IPC0	00A4	-	T1IP2	T1IP1	T1IP0	_	OC1IP2	OC1IP1	OC1IP0	_	IC1IP2	IC1IP1	IC1IP0	_	INT0IP2	INT0IP1	INT0IP0	4444
IPC1	00A6	-	T2IP2	T2IP1	T2IP0	_	OC2IP2	OC2IP1	OC2IP0	_	IC2IP2	IC2IP1	IC2IP0	_	_	_	_	4440
IPC2	00A8	-	U1RXIP2	U1RXIP1	U1RXIP0	_	SPI1IP2	SPI1IP1	SPI1IP0	_	SPF1IP2	SPF1IP1	SPF1IP0	_	T3IP2	T3IP1	T3IP0	4444
IPC3	00AA	-	_	_	—	_	—	_	—	_	AD1IP2	AD1IP1	AD1IP0	_	U1TXIP2	U1TXIP1	U1TXIP0	0044
IPC4	00AC	_	CNIP2	CNIP1	CNIP0	—	CMIP2	CMIP1	CMIP0	_	MI2C1IP2	MI2C1IP1	MI2C1IP0	_	SI2C1IP2	SI2C1IP1	SI2C1IP0	4444
IPC5	00AE	-	IC8IP2	IC8IP1	IC8IP0	_	IC7IP2	IC7IP1	IC7IP0	_	_	_	_	_	INT1IP2	INT1IP1	INT1IP0	4404
IPC6	00B0		T4IP2	T4IP1	T4IP0	_	OC4IP2	OC4IP1	OC4IP0	_	OC3IP2	OC3IP1	OC3IP0	_	_	_	_	4440
IPC7	00B2	-	U2TXIP2	U2TXIP1	U2TXIP0	_	U2RXIP2	U2RXIP1	U2RXIP0	_	INT2IP2	INT2IP1	INT2IP0	_	T5IP2	T5IP1	T5IP0	4444
IPC8	00B4	_	_	_	—	—	_	_	_	_	SPI2IP2	SPI2IP1	SPI2IP0	_	SPF2IP2	SPF2IP1	SPF2IP0	0044
IPC9	00B6	_	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0	—	IC3IP2	IC3IP1	IC3IP0	_	_	_	_	4440
IPC10	00B8	_	OC7IP2	OC7IP1	OC7IP0	—	OC6IP2	OC6IP1	OC6IP0	_	OC5IP2	OC5IP1	OC5IP0	_	IC6IP2	IC6IP1	IC6IP0	4444
IPC11	00BA	_	_	_	_	_	_	_	—	_	PMPIP2 ⁽¹⁾	PMPIP1 ⁽¹⁾	PMPIP0 ⁽¹⁾	_	OC8IP2	OC8IP1	OC8IP0	₀₀₄₄ (2)
IPC12	00BC	_					MI2C2IP2	MI2C2IP1	MI2C2IP0	_	SI2C2IP2	SI2C2IP1	SI2C2IP0	_	—	_		0440
IPC13	00BE	_					INT4IP2	INT4IP1	INT4IP0		INT3IP2	INT3IP1	INT3IP0	_	—		—	0440
IPC15	00C2	_	_	_	—	_	RTCIP2	RTCIP1	RTCIP0	_	_	_	_	_	—	_	_	0400

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 Legend:
 -- = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Unimplemented in 64-pin devices, read as '0'.

 2:
 The Reset value in 64-pin devices are '0004'.

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TABLE 4-6: **INTERRUPT CONTROLLER REGISTER MAP (CONTINUED)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IPC16	00C4		CRCIP2	CRCIP1	CRCIP0	-	U2ERIP2	U2ERIP1	U2ERIP0		U1ERIP2	U1ERIP1	U1ERIP0	_	_		_	4440
IPC18	00C8	_	_	_	_	-	_	_	_	_	_	_	_	_	LVDIP2	LVDIP1	LVDIP0	0004
IPC19	00CA	_	_	_	_		_	_	_	_	CTMUIP2	CTMUIP1	CTMUIP0	_	_	_	_	0040
IPC20	00CC	_	U3TXIP2	U3TXIP1	U3TXIP0	_	U3RXIP2	U3RXIP1	U3RXIP0	_	U3ERIP2	U3ERIP1	U3ERIP0	_	_	_	_	4440
IPC21	00CE	_	U4ERIP2	U4ERIP1	U4ERIP0	-	USB1IP2	USB1IP1	USB1IP0	_	MI2C3IP2	MI2C3IP1	MI2C3IP0	_	SI2C3IP2	SI2C3IP1	SI2C3IP0	4444
IPC22	00D0	_	SPI3IP2	SPI3IP1	SPI3IP0		SPF3IP2	SPF3IP1	SPF3IP0	_	U4TXIP2	U4TXIP1	U4TXIP0	_	U4RXIP2	U4RXIP1	U4RXIP0	4444
IPC23	00D2	_	_	_	_	-	_	_	_	_	IC9IP2	IC9IP1	IC9IP0	_	OC9IP2	OC9IP1	OC9IP0	0044
IPC25	00D6	_	_	_	_	-	_	_	_	_	_	-	_	_	GFX1IP2	GFX1IP1	GFX1IP0	0004
INTTREG	00E0	CPUIRQ	_	VHOLD	_	ILR3	ILR2	ILR1	ILR0		VECNUM6	VECNUM5	VECNUM4	VECNUM3	VECNUM2	VECNUM1	VECNUM0	0000

 – = unimplemented, read as '0'. Reset values are shown in hexadecimal.
 Unimplemented in 64-pin devices, read as '0'.
 The Reset value in 64-pin devices are '0004'. Legend:

Note 1:

2:

TABLE 4-7: TIMER REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TMR1	0100								Timer1 I	Register								0000
PR1	0102								Timer1 Peri	od Register								FFFF
T1CON	0104	TON	_	TSIDL	_	_	_	_	_	—	TGATE	TCKPS1	TCKPS0	_	TSYNC	TCS	_	0000
TMR2	0106								Timer2	Register								0000
TMR3HLD	0108						Time	er3 Holding	Register (for	32-bit timer	operations o	nly)						0000
TMR3	010A								Timer3 I	Register								0000
PR2	010C								Timer2 Peri	od Register								FFFF
PR3	010E																FFFF	
T2CON	0110	TON	_	TSIDL	_	_	_	_	_	_	TGATE	TCKPS1	TCKPS0	T32	_	TCS	_	0000
T3CON	0112	TON	_	TSIDL	_	_	_		—	_	TGATE	TCKPS1	TCKPS0	_		TCS	_	0000
TMR4	0114								Timer4 I	Register								0000
TMR5HLD	0116						Т	imer5 Holdir	ng Register (for 32-bit op	erations only	')						0000
TMR5	0118								Timer5 I	Register								0000
PR4	011A								Timer4 Peri	od Register								FFFF
PR5	011C								Timer5 Peri	od Register								FFFF
T4CON	011E	TON	_	TSIDL	_	_	_		—	_	TGATE	TCKPS1	TCKPS0	T45		TCS	—	0000
T5CON	0120	TON	_	TSIDL	_	_	—	_	_	—	TGATE	TCKPS1	TCKPS0		_	TCS	_	0000

- = unimplemented, read as '0'. Reset values are shown in hexadecimal. Legend:

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File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
IC1CON1	0140	_	_	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	—	_	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC1CON2	0142	—	_	—	—	—	—	_	IC32	ICTRIG	TRIGSTAT		SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC1BUF	0144								Input Cap	oture 1 Buffe	er Register							0000
IC1TMR	0146			-					Input Captur	e 1 Timer Va	alue Register							xxxx
IC2CON1	0148	—	_	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	—	_	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC2CON2	014A	—	_	—	—	—	—	_	IC32	ICTRIG	TRIGSTAT		SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC2BUF	014C								Input Cap	oture 2 Buffe	er Register							0000
IC2TMR	014E								Input Captur	e 2 Timer Va	alue Register							xxxx
IC3CON1	0150	—	_	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	—	-	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC3CON2	0152	_	—	—	—		_	—	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC3BUF	0154								Input Cap	oture 3 Buffe	er Register							0000
IC3TMR	0156								Input Captur	e 3 Timer Va	alue Register							xxxx
IC4CON1	0158		_	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	-	_	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC4CON2	015A	-	_	_	_	_	—	_	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC4BUF	015C								Input Cap	oture 4 Buffe	er Register							0000
IC4TMR	015E								Input Captur	e 4 Timer Va	alue Register							xxxx
IC5CON1	0160		—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	-	-	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC5CON2	0162	_	_	_	_		_	_	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC5BUF	0164								Input Cap	oture 5 Buffe	er Register							0000
IC5TMR	0166								Input Captur	e 5 Timer Va	alue Register							xxxx
IC6CON1	0168		—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	-	-	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC6CON2	016A		_	_	_	_	—	_	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC6BUF	016C								Input Cap	oture 6 Buffe	er Register							0000
IC6TMR	016E								Input Captur	e 6 Timer Va	alue Register							xxxx
IC7CON1	0170	_	—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	—	-	—	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC7CON2	0172	_	_	_	_	_	_	_	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC7BUF	0174								Input Cap	oture 7 Buffe	er Register							0000
IC7TMR	0176								Input Captur	e 7 Timer Va	alue Register							xxxx
IC8CON1	0178		—	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	-	-	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC8CON2	017A	_	_	—		_	_	_	IC32	ICTRIG	TRIGSTAT	—	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC8BUF	017C								Input Cap	oture 8 Buffe	er Register						-	0000
IC8TMR	017E								Input Captur	e 8 Timer Va	alue Register							xxxx
IC9CON1	0180	_	_	ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0	_	—	_	ICI1	ICI0	ICOV	ICBNE	ICM2	ICM1	ICM0	0000
IC9CON2	0182	_	_	—	—	—	—	_	IC32	ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000D
IC9BUF	0184								Input Cap	oture 9 Buffe	er Register			•	•	•	•	0000
IC9TMR	0186								Input Captur	a 0 Timor \/	alua Pagistor							xxxx

TABLE	4-9:	OUT	ГРИТ С	OMPA	RE REG	ISTER I	MAP							r		n		
File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC1CON1	0190		—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC1CON2	0192	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC1RS	0194								Output Comp	are 1 Seconda	ny Register							0000
OC1R	0196								Output	Compare 1 Re	gister							0000
OC1TMR	0198								Output Compa	are 1 Timer Va	ue Register							XXXX
OC2CON1	019A		_	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC2CON2	019C	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC2RS	019E								Output Comp	are 2 Seconda	ry Register							0000
OC2R	01A0								Output	Compare 2 Re	gister							0000
OC2TMR	01A2								Output Compa	are 2 Timer Va	ue Register							xxxx
OC3CON1	01A4	_	_	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC3CON2	01A6	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC3RS	01A8								Output Comp	are 3 Seconda	ry Register							0000
OC3R	01AA								Output	Compare 3 Re	gister							0000
OC3TMR	01AC		Output Compare 3 Timer Value Register														xxxx	
OC4CON1	01AE			OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC4CON2	01B0	FLTMD	FLTOUT	FLTTRIEN	OCINV	—	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC4RS	01B2								Output Comp	are 4 Seconda	ry Register							0000
OC4R	01B4								Output	Compare 4 Re	gister							0000
OC4TMR	01B6								Output Compa	are 4 Timer Va	ue Register							xxxx
OC5CON1	01B8	_	_	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT1	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC5CON2	01BA	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC5RS	01BC			•	•	•			Output Comp	are 5 Seconda	ry Register		•	•		•		0000
OC5R	01BE								Output	Compare 5 Re	gister							0000
OC5TMR	01C0								Output Compa	are 5 Timer Va	ue Register							xxxx
OC6CON1	01C2	-	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC6CON2	01C4	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC6RS	01C6								Output Comp	are 6 Seconda	ry Register							0000
OC6R	01C8								Output	Compare 6 Re	gister							0000
OC6TMR	01CA								Output Compa	are 6 Timer Va	ue Register							xxxx
OC7CON1	01CC	—	—	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC7CON2	01CE	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC7RS	01D0		•	•	•		•	•	Output Comp	are 7 Seconda	ry Register	•			•	•	•	0000
OC7R	01D2								Output	Compare 7 Re	gister							0000
OC7TMR	01D4								Output Compa	are 7 Timer Va	ue Register							xxxx

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Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-9: **OUTPUT COMPARE REGISTER MAP (CONTINUED)**

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
OC8CON1	01D6	_	_	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC8CON2	01D8	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC8RS	01DA								Output Comp	are 8 Seconda	ry Register							0000
OC8R	01DC								Output (Compare 8 Re	gister							0000
OC8TMR	01DE								Output Compa	are 8 Timer Val	ue Register							xxxx
OC9CON1	01E0	_	_	OCSIDL	OCTSEL2	OCTSEL1	OCTSEL0	ENFLT2	ENFLT1	ENFLT0	OCFLT2	OCFLT1	OCFLT0	TRIGMODE	OCM2	OCM1	OCM0	0000
OC9CON2	01E2	FLTMD	FLTOUT	FLTTRIEN	OCINV	_	DCB1	DCB0	OC32	OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0	000C
OC9RS	01E4								Output Comp	are 9 Seconda	ry Register							0000
OC9R	01E6								Output (Compare 9 Re	gister							0000
OC9TMR	01E8								Output Compa	are 9 Timer Val	ue Register							xxxx
Legend:		·	,	as '0'. Resel	t values are	shown in he	xadecimal.											

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
I2C1RCV	0200	_	—	_	_	—	—	—	—				I2C1 Receiv	/e Register				0000
I2C1TRN	0202	—	_	_	_	_	_	_	_				I2C1 Transm	nit Register				OOFF
I2C1BRG	0204	_		_	_	_	_	_				I2C1 Baud I	Rate Generat	or Register				0000
I2C1CON	0206	I2CEN		I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C1STAT	0208	ACKSTAT	TRSTAT	_	_	_	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	Р	S	R/W	RBF	TBF	0000
I2C1ADD	020A	_	_	_	_	_	_					I2C1 Addre	ss Register					0000
I2C1MSK	020C	_	_	_	_	_	_				12	C1 Address	Mask Registe	er				0000
I2C2RCV	0210	_	_	—	_	_	_		_				I2C2 Receiv	/e Register				0000
I2C2TRN	0212	_	_	—	_	_	_		_									00FF
I2C2BRG	0214	_	_	—	—	_	_	_		I2C2 Baud Rate Generator Register								
I2C2CON	0216	I2CEN	_	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C2STAT	0218	ACKSTAT	TRSTAT	_	_	_	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	Р	S	R/W	RBF	TBF	0000
I2C2ADD	021A	_	_	_	_	_	—				•	I2C2 Addre	ss Register				•	0000
I2C2MSK	021C	_	_	_	_	_	_				12	C2 Address	Mask Registe	er				0000
I2C3RCV	0270	_	_	_	_	_	_	_	_				I2C3 Receiv	/e Register				0000
I2C3TRN	0272	_	_	—	_	_	_		_				I2C3 Transn	nit Register				00FF
I2C3BRG	0274	_	_	—	_	_	_					I2C3 Baud I	Rate Generat	or Register				0000
I2C3CON	0276	I2CEN	_	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN	GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN	1000
I2C3STAT	0278	ACKSTAT	TRSTAT	_	_	_	BCL	GCSTAT	ADD10	IWCOL	I2COV	D/A	Р	S	R/W	RBF	TBF	0000
I2C3ADD	027A	_	_	—	—		_		I2C3 Address Register									0000
I2C3MSK	027C	_		_	_	—	—		I2C3 Address Mask Register									0000

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Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-11: UART REGISTER MAPS

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets			
U1MODE	0220	UARTEN	_	USIDL	IREN	RTSMD	_	UEN1	UEN0	WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000			
U1STA	0222	UTXISEL1	UTXINV	UTXISEL0	_	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110			
U1TXREG	0224	_	_	_	_	_	_	—				UART1	Transmit Re	gister				xxxx			
U1RXREG	0226	_	_	_		_	_	—				UART1	Receive Re	gister				0000			
U1BRG	0228							UART1 Bau	id Rate Gene	erator Prescale	er Register							0000			
U2MODE	0230	UARTEN	_	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000			
U2STA	0232	UTXISEL1	UTXINV	UTXISEL0		UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110			
U2TXREG	0234	_		_		_	—	—				UART2	Transmit Re	gister				xxxx			
U2RXREG	0236	_		_		-	—	—	UART2 Receive Register												
U2BRG	0238							UART2 Bau	T2 Baud Rate Generator Prescaler Register												
U3MODE	0250	UARTEN	_	USIDL	IREN	RTSMD	—	UEN1	UEN0	WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000			
U3STA	0252	UTXISEL1	UTXINV	UTXISEL0	-	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110			
U3TXREG	0254	_		—		_	—	_				UART3	Transmit Re	gister				xxxx			
U3RXREG	0256	_	_	—	-	—	_	—				UART3	Receive Re	gister				0000			
U3BRG	0258							UART3 Bau	id Rate Gene	erator Prescale	er Register							0000			
U4MODE	02B0	UARTEN	_	USIDL	IREN	RTSMD	_	UEN1	UEN0	WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL	0000			
U4STA	02B2	UTXISEL1	UTXINV	UTXISEL0	-	UTXBRK	UTXEN	UTXBF	TRMT	URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA	0110			
U4TXREG	02B4	_		—		_	—	—				UART4	Transmit Re	gister				xxxx			
U4RXREG	02B6	—		—		—	_	—	UART4 Receive Register												
U4BRG	02B8							UART4 Bau	ART4 Baud Rate Generator Prescaler Register 00												
Legend:	= uni	mplemented.	read as '0'	Recet values	are chown	in hovadooi	mal														

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.



TABLE 4-12: SPI REGISTER MAPS

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
SPI1STAT	0240	SPIEN	—	SPISIDL	-	-	SPIBEC2	SPIBEC1	SPIBEC0	SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF	0000
SPI1CON1	0242	-	—	—	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0	0000
SPI1CON2	0244	FRMEN	SPIFSD	SPIFPOL	_	_	_	_	_	_	—	_	_	_	_	SPIFE	SPIBEN	0000
SPI1BUF	0248		SPI1 Transmit and Receive Buffer															0000
SPI2STAT	0260	SPIEN	_	SPISIDL	_	_	SPIBEC2	SPIBEC1	SPIBEC0	SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF	0000
SPI2CON1	0262	_	—	_	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0	0000
SPI2CON2	0264	FRMEN	SPIFSD	SPIFPOL	_	_	_	—	_	_	_	_	_	_	_	SPIFE	SPIBEN	0000
SPI2BUF	0268							SPI	2 Transmit an	d Receive B	uffer							0000
SPI3STAT	0280	SPIEN	—	SPISIDL	_	_	SPIBEC2	SPIBEC1	SPIBEC0	SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF	0000
SPI3CON1	0282	_	_	_	DISSCK	DISSDO	MODE16	SMP	CKE	SSEN	CKP	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0	0000
SPI3CON2	0284	FRMEN	SPIFSD	SPIFPOL	_	_	_	_	_	_	_	_	_	_	_	SPIFE	SPIBEN	0000
SPI3BUF	0288							SPI	3 Transmit an	d Receive B	uffer							0000

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Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-13: PORTA REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit2	Bit 1	Bit 0	All Resets
TRISA	02C0	TRISA15	TRISA14		—		TRISA10	TRISA9		TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	C6FF
PORTA	02C2	RA15	RA14	_	_	_	RA10	RA9	_	RA7	RA6	RA5	RA4	RA3	RA2	RA1	RA0	xxxx
LATA	02C4	LATA15	LATA14	_	_	_	LATA10	LATA9	_	LATA7	LATA6	LATA5	LATA4	LATA3	LATA2	LATA1	LATA0	xxxx
ODCA	02C6	ODA15	ODA14	_	_	_	ODA10	ODA9	_	ODA7	ODA6	ODA5	ODA4	ODA3	ODA2	ODA1	ODA0	0000

 Legend:
 -- = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

 Note
 1:
 PORTA and all associated bits are unimplemented on 64-pin devices and read as '0'. Bits are available on 100-pin devices only, unless otherwise noted.

TABLE 4-14: PORTB REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISB	02C8	TRISB15	TRISB14	TRISB13	TRISB12	TRISB11	TRISB10	TRISB9	TRISB8	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	FFFF
PORTB	02CA	RB15	RB14	RB13	RB12	RB11	RB10	RB9	RB8	RB7	RB6	RB5	RB4	RB3	RB2	RB1	RB0	xxxx
LATB	02CC	LATB15	LATB14	LATB13	LATB12	LATB11	LATB10	LATB9	LATB8	LATB7	LATB6	LATB5	LATB4	LATB3	LATB2	LATB1	LATB0	xxxx
ODCB	02CE	ODB15	ODB14	ODB13	ODB12	ODB11	ODB10	ODB9	ODB8	ODB7	ODB6	ODB5	ODB4	ODB3	ODB2	ODB1	ODB0	0000

Legend: Reset values are shown in hexadecimal.

TABLE 4-15: PORTC REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4 ⁽¹⁾	Bit 3 ⁽¹⁾	Bit 2 ⁽¹⁾	Bit 1 ⁽¹⁾	Bit 0	All Resets
TRISC	02D0	TRISC15	TRISC14	TRISC13	TRISC12	_	_	_	_	_	_	_	TRISC4	TRISC3	TRISC2	TRISC1	_	F01E
PORTC	02D2	RC15 ^(2,3)	RC14	RC13	RC12 ⁽²⁾	_	_	-	_	_	_	_	RC4	RC3	RC2	RC1	_	xxxx
LATC	02D4	LATC15	LATC14	LATC13	LATC12	_	_	-	_	_	_	_	LATC4	LATC3	LATC2	LATC1	_	xxxx
ODCC	02D6	ODC15	ODC14	ODC13	ODC12	_	_		_	_	_	_	ODC4	ODC3	ODC2	ODC1	_	0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Bits are unimplemented in 64-pin devices; read as '0'. Note 1:

RC12 and RC15 are only available when the primary oscillator is disabled or when EC mode is selected (POSCMD<1:0> Configuration bits = 11 or 00); otherwise read as '0'. RC15 is only available when the POSCMD<1:0> Configuration bits = 11 or 00 and the OSCIOFN Configuration bit = 1. 2:

3:

TABLE 4-16: PORTD REGISTER MAP

File Name	Addr	Bit 15 ⁽¹⁾	Bit 14 ⁽¹⁾	Bit 13 ⁽¹⁾	Bit 12 ⁽¹⁾	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISD	02D8	TRISD15	TRISD14	TRISD13	TRISD12	TRISD11	TRISD10	TRISD9	TRISD8	TRISD7	TRISD6	TRISD5	TRISD4	TRISD3	TRISD2	TRISD1	TRISD0	FFFF
PORTD	02DA	RD15	RD14	RD13	RD12	RD11	RD10	RD9	RD8	RD7	RD6	RD5	RD4	RD3	RD2	RD1	RD0	xxxx
LATD	02DC	LATD15	LATD14	LATD13	LATD12	LATD11	LATD10	LATD9	LATD8	LATD7	LATD6	LATD5	LATD4	LATD3	LATD2	LATD1	LATD0	xxxx
ODCD	02DE	ODD15	ODD14	ODD13	ODD12	ODD11	ODD10	ODD9	ODD8	ODD7	ODD6	ODD5	ODD4	ODD3	ODD2	ODD1	ODD0	0000

- = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices. Legend:

Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-17: PORTE REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9 ⁽¹⁾	Bit 8 ⁽¹⁾	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
TRISE	02E0	_	—	—	_	—	—	TRISE9	TRISE8	TRISE7	TRISE6	TRISE5	TRISE4	TRISE3	TRISE2	TRISE1	TRISE0	03FF
PORTE	02E2	_	_	_	_	_	_	RE9	RE8	RE7	RE6	RE5	RE4	RE3	RE2	RE1	RE0	xxxx
LATE	02E4	_	_	_	_	_	_	LATE9	LATE8	LATE7	LATE6	LATE5	LATE4	LATE3	LATE2	LATE1	LATE0	xxxx
ODCE	02E6		_	_	_	_	_	ODE9	ODE8	ODE7	ODE6	ODE5	ODE4	ODE3	ODE2	ODE1	ODE0	0000

- = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices. Legend:

Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-18: PORTF REGISTER MAP

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File Name	Addr	Bit 15	Bit 14	Bit 13 ⁽¹⁾	Bit 12 ⁽¹⁾	Bit 11	Bit 10	Bit 9	Bit 8 ⁽¹⁾	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2 ⁽¹⁾	Bit 1	Bit 0	All Resets
TRISF	02E8		_	TRISF13	TRISF12		_	_	TRISF8	TRISF7	_	TRISF5	TRISF4	TRISF3	TRISF2	TRISF1	TRISF0	31BF
PORTF	02EA	_		RF13	RF12	_	_	_	RF8	RF7		RF5	RF4	RF3	RF2	RF1	RF0	xxxx
LATF	02EC		-	LATF13	LATF12		_	_	LATF8	LATF7	-	LATF5	LATF4	LATF3	LATF2	LATF1	LATF0	xxxx
ODCF	02EE	_		ODF13	ODF12	_	_	—	ODF8	ODF7		ODF5	ODF4	ODF3	ODF2	ODF1	ODF0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-19: PORTG REGISTER MAP

File Name	Addr	Bit 15 ⁽¹⁾	Bit 14 ⁽¹⁾	Bit 13 ⁽¹⁾	Bit 12 ⁽¹⁾	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1 ⁽¹⁾	Bit 0 ⁽¹⁾	All Resets
TRISG	02F0	TRISG15	TRISG14	TRISG13	TRISG12	_	—	TRISG9	TRISG8	TRISG7	TRISG6	—		TRISG3	TRISG2	TRISG1	TRISG0	F3CF
PORTG	02F2	RG15	RG14	RG13	RG12		_	RG9	RG8	RG7	RG6	_	_	RG3	RG2	RG1	RG0	xxxx
LATG	02F4	LATG15	LATG14	LATG13	LATG12		_	LATG9	LATG8	LATG7	LATG6	_	_	LATG3	LATG2	LATG1	LATG0	xxxx
ODCG	02F6	ODG15	ODG14	ODG13	ODG12	_	_	ODG9	ODG8	ODG7	ODG6	—	_	ODG3	ODG2	ODG1	ODG0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal. Reset values shown are for 100-pin devices.

Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-20: PAD CONFIGURATION REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PADCFG1	02FC	_	_		—	_	_	_	_	_		—		_	_	RTSECSEL	PMPTTL ⁽¹⁾	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-21: ADC REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ADC1BUF0	0300								ADC Dat	ta Buffer 0								xxxx
ADC1BUF1	0302								ADC Dat	ta Buffer 1								xxxx
ADC1BUF2	0304								ADC Dat	ta Buffer 2								xxxx
ADC1BUF3	0306								ADC Dat	ta Buffer 3								xxxx
ADC1BUF4	0308								ADC Dat	ta Buffer 4								xxxx
ADC1BUF5	030A								ADC Dat	ta Buffer 5								xxxx
ADC1BUF6	030C								ADC Dat	ta Buffer 6								xxxx
ADC1BUF7	030E								ADC Dat	ta Buffer 7								xxxx
ADC1BUF8	0310								ADC Dat	ta Buffer 8								xxxx
ADC1BUF9	0312								ADC Dat	ta Buffer 9								xxxx
ADC1BUFA	0314								ADC Data	a Buffer 10								xxxx
ADC1BUFB	0316								ADC Dat	a Buffer 11								xxxx
ADC1BUFC	0318								ADC Data	a Buffer 12								xxxx
ADC1BUFD	031A								ADC Data	a Buffer 13								xxxx
ADC1BUFE	031C								ADC Data	a Buffer 14								xxxx
ADC1BUFF	031E								ADC Data	a Buffer 15								xxxx
ADC1BUF10	0340								ADC Data	a Buffer 16								xxxx
ADC1BUF11	0342								ADC Data	a Buffer 17								xxxx
ADC1BUF12	0344								ADC Data	a Buffer 18								xxxx
ADC1BUF13	0346								ADC Data	a Buffer 19								xxxx
ADC1BUF14	0348								ADC Data	a Buffer 20								xxxx
ADC1BUF15	034A								ADC Dat	a Buffer21								xxxx
ADC1BUF16	034C								ADC Data	a Buffer 22								xxxx
ADC1BUF17	034E								ADC Data	a Buffer 23								xxxx
ADC1BUF18	0350								ADC Data	a Buffer 24								xxxx
ADC1BUF19	0352								ADC Data	a Buffer 25								xxxx
ADC1BUF1A	0354								ADC Data	a Buffer 26								xxxx
ADC1BUF1B	0356								ADC Data	a Buffer 27								xxxx
ADC1BUF1C	0358								ADC Dat	a Buffer 28								xxxx
ADC1BUF1D	035A								ADC Data	a Buffer 29								xxxx
ADC1BUF1E	035C								ADC Data	a Buffer 30								xxxx
ADC1BUF1F	035E								ADC Data	a Buffer 31								xxxx

 Legend:
 -- = unimplemented, read as '0', r = reserved, maintain as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Unimplemented in 64-pin devices, read as '0'

TABLE 4-21: ADC REGISTER MAP (CONTINUED)

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
AD1CON1	0320	ADON		ADSIDL		_		FORM1	FORM0	SSRC2	SSRC1	SSRC0	_		ASAM	SAMP	DONE	0000
AD1CON2	0322	VCFG2	VCFG1	VCFG0	r	_	CSCNA			BUFS	SMPI4	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS	0000
AD1CON3	0324	ADRC	r	r	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0	ADCS7	ADCS6	ADCS5	ADCS4	ADCS3	ADCS2	ADCS1	ADCS0	0000
AD1CHS	0328	CH0NB	_	_	CH0SB4	CH0SB3	CH0SB2	CH0SB1	CH0SB0	CH0NA	_	_	CH0SA4	CH0SA3	CH0SA2	CH0SA1	CH0SA0	0000
AD1CSSH	032E	_	_	_		CSSL27	CSSL26	CSSL25	CSSL24	CSSL23 ⁽¹⁾	CSSL22 ⁽¹⁾	CSSL21 ⁽¹⁾	CSSL20 ⁽¹⁾	CSSL19 ⁽¹⁾	CSSL18 ⁽¹⁾	CSSL17 ⁽¹⁾	CSSL16 ⁽¹⁾	0000
AD1CSSL	0330	CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8	CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0	0000

Legend: — = unimplemented, read as '0', r = reserved, maintain as '0'. Reset values are shown in hexadecimal Note 1: Unimplemented in 64-pin devices, read as '0'

TABLE 4-22: CTMU REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CTMUCON	033C	CTMUEN		CTMUSIDL	TGEN	EDGEN	EDGSEQEN	IDISSEN	CTTRIG	EDG2POL	EDG2SEL1	EDG2SEL0	EDG1POL	EDG1SEL1	EDG1SEL0	EDG2STAT	EDG1STAT	0000
CTMUICON	033E	ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0	_	-	-	_	_	_	_	_	0000

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Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-23: USB OTG REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
U1OTGIR ⁽²⁾	0480	_	_	—	_	_	—	—	—	IDIF	T1MSECIF	LSTATEIF	ACTVIF	SESVDIF	SESENDIF	—	VBUSVDIF	0000
U1OTGIE ⁽²⁾	0482	_	_	_	_	_	_	_	_	IDIE	T1MSECIE	LSTATEIE	ACTVIE	SESVDIE	SESENDIE	_	VBUSVDIE	0000
U1OTGSTAT ²⁾	0484	-	_	_	-	-	_	_	_	ID	_	LSTATE	_	SESVD	SESEND	_	VBUSVD	0000
U1OTGCON ⁽²⁾	0486		-	_			_	_	_	DPPULUP	DMPULUP	DPPULDWN	DMPULDWN	VBUSON	OTGEN	VBUSCHG	VBUSDIS	0000
U1PWRC	0488	_	_	_	-	_	_	_		UACTPND	_	_	USLPGRD	_	_	USUSPND	USBPWR	0000
U1IR	048A ⁽¹⁾	_	_	_	-	-	_	_		STALLIF		RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	URSTIF	0000
		_	_	—	_	_	-	—		STALLIF	ATTACHIF ⁽¹⁾	RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	DETACHIF ⁽¹⁾	0000
U1IE	048C ⁽¹⁾	_	_	_	-	_	_	_		STALLIE	_	RESUMEIE	IDLEIE	TRNIE	SOFIE	UERRIE	URSTIE	0000
		_	_	_	-	-	_	_		STALLIE	ATTACHIE ⁽¹⁾	RESUMEIE	IDLEIE	TRNIE	SOFIE	UERRIE	DETACHIE ⁽¹⁾	0000
U1EIR	048E ⁽¹⁾	_	_	—	_	_	-	—		BTSEF		DMAEF	BTOEF	DFN8EF	CRC16EF	CRC5EF	PIDEF	0000
		_	_	_	-	_	_	_		BTSEF	_	DMAEF	BTOEF	DFN8EF	CRC16EF	EOFEF ⁽¹⁾	PIDEF	0000
U1EIE	0490 ⁽¹⁾	_	_	_	-	-	_	_		BTSEE		DMAEE	BTOEE	DFN8EE	CRC16EE	CRC5EE	PIDEE	0000
		_	_	—	_	_	-	—		BTSEE	DMAEE BTOEE DFN8EE CRC16EE EOFEE ⁽¹⁾ PIDEE ENDPT2 ENDPT1 ENDPT0 DIR PPBI							
U1STAT	0492	_	_	_	-	_	_	_		ENDPT3	ENDPT2	ENDPT1	ENDPT0	DIR	PPBI	_	_	0000
U1CON	0494 ⁽¹⁾	-	_	_	-	-	_	_	_	_	SE0	PKTDIS	_	HOSTEN	RESUME	PPBRST	USBEN	0000
			-	_			_	_	_	JSTATE ⁽¹⁾	SE0	TOKBUSY	USBRST	HOSTEN	RESUME	PPBRST	SOFEN ⁽¹⁾	0000
U1ADDR	0496	_	_	_	-	_	_	_		LSPDEN ⁽¹⁾			USB Device Ad	dress (DEVA	DDR) Register			0000
U1BDTP1	0498	_	_	_	-	-	_	_			E	Buffer Descripto	r Table Base Ad	dress Registe	er			0000
U1FRML	049A	_	_	—	_	_	-	—				F	Frame Count Re	gister Low By	rte			0000
U1FRMH	049C	_	_	—	_	_	-	_		—			_		Frame (Count Register	High Byte	0000
U1TOK ⁽²⁾	049E	_	_	_	-	-	_	_		PID3	PID2	PID1	PID0	EP3	EP2	EP1	EP0	0000
U1SOF ⁽²⁾	04A0		-	_			_	_	_				Start-Of-Frame	Count Registe	er			0000
U1CNFG1	04A6	-	—	_	_	-	_	_	_	UTEYE	UOEMON	_	USBSIDL	_	_	PPB1	PPB0	0000
U1CNFG2	04A8			_	_	-	-	_	-	—		UVCMPSEL	PUVBUS	EXTI2CEN	UVBUSDIS	UVCMPDIS	UTRDIS	0000
U1EP0	04AA		-	_			_	_	_	LSPD ⁽¹⁾	RETRYDIS ⁽¹⁾	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP1	04AC	_	_	_	-	_	_	_		_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP2	04AE			_	_	-	-	_	-	—		-	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP3	04B0	_	_	_	_	_	_	_	—	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP4	04B2	_	_	_	_	_	_		—			_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP5	04B4	_	_	_	_	_	_	_	_	_		_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP6	04B6	_	—	_	_	_	_	_	_		_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP7	04B8	_	_	_	_	_	—	—	_	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP8	04BA	_	_	_	_	_	_	_	_	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP9	04BC	_	_	_	_	_	_	_	_	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000

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Legend: Note 1 met: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.
 Alternate register or bit definitions when the module is operating in Host mode.
 This register is available in Host mode only.

TABLE 4-23: USB OTG REGISTER MAP (CONTINUED)

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
U1EP10	04BE		_		—	ļ	_		_	_		_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP11	04C0	—			_			_		_	_		EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP12	04C2	—	_	_	_	_	_	_	_	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP13	04C4	_		_	_	_		_	_	_	_		EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP14	04C6	_	_	_	_		-	_	-	_	-	-	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1EP15	04C8	—	_	_	_	_	_	_	_	_	_	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK	0000
U1PWMRRS	04CC			USB Pow	ver Supply F	WM Duty C	ycle Registe	r				USB F	ower Supply P	WM Period I	Register			0000
U1PWMCON	04CE	PWMEN		_	_	-	_	PWMPOL	CNTEN	_	_	_	_	_	_	_	_	0000

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Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Atternate register or bit definitions when the module is operating in Host mode. This register is available in Host mode only. Note 1:

2:

TABLE 4-24: ANCFG REGISTER MAP

	File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
,	ANCFG	04DE	_	_	_	_	_	_	_	_		_	_	_	_	VBG6EN	VBG2EN	VBGEN	0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-25: ANSEL REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets ⁽²⁾
ANSA ⁽¹⁾	04E0	_	_	_	—	—	ANSA10 ⁽¹⁾	ANSA9 ⁽¹⁾		ANSA7(1)	ANSA6 ⁽¹⁾	—	_	_	_	_	_	0600
ANSB	04E2	ANSB15	ANSB14	ANSB13	ANSB12	ANSB11	ANSB10	ANSB9	ANSB8	ANSB7	ANSB6	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0	FFFF
ANSC	04E4	_	ANSC14	ANSC13	_	_	_	_	_	_	_	_	ANSC4 ⁽¹⁾	_	_	_	_	6010
ANSD	04E6	_	_	_	_	_	_	_	_	ANSD7	ANSD6	_	—	-	_	_	_	00C0
ANSE ⁽¹⁾	04E8	_	_	_	_	_	_	ANSE9 ⁽¹⁾	_	_		_	—	_	_	_	_	0200
ANSF	04EA	_	_	_	_	_	_	_	_	_	_	_	—	_	_	_	ANSF0	0001
ANSG	04EC	_	_	_	_	_	_	ANSG9	ANSG8	ANSG7	ANSG6	_	—		-	_	_	03C0

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Unimplemented in 64-pin devices, read as '0'. Note 1:

2: Reset values are valid for 100-pin devices only.

TABLE 4-26: ENHANCED PARALLEL MASTER/SLAVE PORT REGISTER MAP⁽¹⁾

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMCON1	0600	PMPEN	_	PSIDL	ADRMUX1	ADRMUX0	_	MODE1	MODE0	CSF1	CSF0	ALP	ALMODE	—	BUSKEEP	IRQM1	IRQM0	0000
PMCON2	0602	BUSY	_	ERROR	TIMEOUT	AMREQ	CURMST	MSTSEL1	MSTSEL0	RADDR23	RADDR22	RADDR21	RADDR20	RADDR19	RADDR18	RADDR17	RADDR16	0000
PMCON3	0604	PTWREN	PTRDEN	PTBE1EN	PTBE0EN	_	AWAITM1	AWAITM0	AWAITE	_	PTEN22	PTEN21	PTEN20	PTEN19	PTEN18	PTEN17	PTEN16	0000
PMCON4	0606	PTEN15	PTEN14	PTEN13	PTEN12	PTEN11	PTEN10	PTEN9	PTEN8	PTEN7	PTEN6	PTEN5	PTEN4	PTEN3	PTEN2	PTEN1	PTEN0	0000
PMCS1CF	0608	CSDIS	CSP	CSPTEN	BEP	_	WRSP	RDSP	SM	ACKP	PTSZ1	PTSZ0	_	_	—	_	_	0000
PMCS1BS	060A	BASE23	BASE22	BASE21	BASE20	BASE19	BASE18	BASE17	BASE16	BASE15	_	_	_	BASE11	_	_	_	0200
PMCS1MD	060C	ACKM1	ACKM0	AMWAIT2	AMWAIT1	AMWAIT0	_	_	_	DWAITB1	DWAITB0	DWAITM3	DWAITM2	DWAITM1	DWAITM0	DWAITE1	DWAITE0	0000
PMCS2CF	060E	CSDIS	CSP	CSPTEN	BEP	_	WRSP	RDSP	SM	ACKP	PTSZ1	PTSZ0	_	_	—	_	_	0000
PMCS2BS	0610	BASE23	BASE22	BASE21	BASE20	BASE19	BASE18	BASE17	BASE16	BASE15	_	_	_	BASE11	_	_	_	0600
PMCS2MD	0612	ACKM1	ACKM0	AMWAIT2	AMWAIT1	AMWAIT0	_	_	_	DWAITB1	DWAITB0	DWAITM3	DWAITM2	DWAITM1	DWAITM0	DWAITE1	DWAITE0	0000
PMDOUT1	0614			EF	MP Data Out	Register 1<15:	8>					EP	MP Data Out	Register 1<	7:0>			xxxx
PMDOUT2	0616			EF	MP Data Out	Register 2<15:	8>					EP	MP Data Out	Register 2<	7:0>			xxxx
PMDIN1	0618			E	PMP Data In F	Register 1<15:8	>					EF	PMP Data In I	Register 1<7	:0>			xxxx
PMDIN2	061A			E	PMP Data In F	Register 2<15:8	>					EF	PMP Data In I	Register 2<7	:0>			xxxx
PMSTAT	061C	IBF	IBOV	_	—	IB3F	IB2F	IB1F	IB0F	OBE	OBUF	_	_	OB3E	OB2E	OB1E	OB0E	008F

 Legend:
 — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Unimplemented in 64-pin devices, read as '0'.

TABLE 4-27: REAL-TIME CLOCK AND CALENDAR REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
ALRMVAL	0620						Alarm	Value Registe	r Window Bas	ed on ALRN	/IPTR<1:0>							xxxx
ALCFGRPT	0622	ALRMEN	CHIME	AMASK3	AMASK2	AMASK1	AMASK0	ALRMPTR1	ALRMPTR0	ARPT7	ARPT6	ARPT5	ARPT4	ARPT3	ARPT2	ARPT1	ARPT0	0000
RTCVAL	0624						RTCO	C Value Regist	er Window Ba	sed on RTC	PTR<1:0>							xxxx
RCFGCAL	0626	RTCEN		RTCWREN	RTCSYNC	HALFSEC	RTCOE	RTCPTR1	RTCPTR0	CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	(Note 1)

 Legend:
 - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 The status of the RCFGCAL register on POR is '0000' and on other Resets is unchanged.

TABLE 4-28: COMPARATORS REGISTER MAP

	File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
С	MSTAT	0630	CMIDL	_	_	_		C3EVT	C2EVT	C1EVT		_	_	_	_	C3OUT	C2OUT	C10UT	0000
С	VRCON	0632	_	_	_	_	_	CVREFP	CVREFM1	CVREFM0	CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0	0000
С	M1CON	0634	CON	COE	CPOL	_	_	_	CEVT	COUT	EVPOL1	EVPOL0		CREF	_	_	CCH1	CCH0	0000
С	M2CON	0636	CON	COE	CPOL	_	_	_	CEVT	COUT	EVPOL1	EVPOL0	_	CREF	_	_	CCH1	CCH0	0000
С	M3CON	0638	CON	COE	CPOL	—		_	CEVT	COUT	EVPOL1	EVPOL0	_	CREF	—	_	CCH1	CCH0	0000

Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

TABLE 4-29: CRC REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
CRCCON1	0640	CRCEN	_	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0	CRCFUL	CRCMPT	CRCISEL	CRCGO	LENDIAN	_	_		0040
CRCCON2	0642	_	_	_	DWIDTH4	DWIDTH3	DWIDTH2	DWIDTH1	DWIDTH0			_	PLEN4	PLEN3	PLEN2	PLEN1	PLEN0	0000
CRCXORL	0644	X15	X14	X13	X12	X11	X10	X9	X8	X7	X6	X5	X4	X3	X2	X1	_	0000
CRCXORH	0646	X31	X30	X29	X28	X27	X26	X25	X24	X23	X22	X21	X20	X19	X18	X17	X16	0000
CRCDATL	0648								CRC Data Inp	out Register	Low							0000
CRCDATH	064A							(CRC Data Inp	ut Register I	High							0000
CRCWDATL	064C								CRC Result	t Register Lo	w							0000
CRCWDATH	064E								CRC Result	Register Hi	gh							0000

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Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

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TABLE 4-30: PERIPHERAL PIN SELECT REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPINR0	0680	_	—	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0	_	—	_	—	—	_	—	_	3F00
RPINR1	0682			INT3R5	INT3R4	INT3R3	INT3R2	INT3R1	INT3R0	_		INT2R5	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0	3F3F
RPINR2	0684			_		_		_	_	_		INT4R5	INT4R4	INT4R3	INT4R2	INT4R1	INT4R0	003F
RPINR3	0686			T3CKR5	T3CKR4	T3CKR3	T3CKR2	T3CKR1	T3CKR0	_		T2CKR5	T2CKR4	T2CKR3	T2CKR2	T2CKR1	T2CKR0	3F3F
RPINR4	0688			T5CKR5	T5CKR4	T5CKR3	T5CKR2	T5CKR1	T5CKR0	_		T4CKR5	T4CKR4	T4CKR3	T4CKR2	T4CKR1	T4CKR0	3F3F
RPINR7	068E	_	_	IC2R5	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0	—	_	IC1R5	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0	3F3F
RPINR8	0690	_	_	IC4R5	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0	_		IC3R5	IC3R4	IC3R3	IC3R2	IC3R1	IC3R0	3F3F
RPINR9	0692	_	_	IC6R5	IC6R4	IC6R3	IC6R2	IC6R1	IC6R0	_		IC5R5	IC5R4	IC5R3	IC5R2	IC5R1	IC5R0	3F3F
RPINR10	0694	_	_	IC8R5	IC8R4	IC8R3	IC8R2	IC8R1	IC8R0	_		IC7R5	IC7R4	IC7R3	IC7R2	IC7R1	IC7R0	3F3F
RPINR11	0696	_	_	OCFBR5	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0	_		OCFAR5	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0	3F3F
RPINR15	069E	_	—	IC9R5	IC9R4	IC9R3	IC9R2	IC9R1	IC9R0	—	_	—	_	—	—	—	_	3F00
RPINR17	06A2	_	—	U3RXR5	U3RXR4	U3RXR3	U3RXR2	U3RXR1	U3RXR0	—	_	—	—	—	—	—	—	3F00
RPINR18	06A4	_	_	U1CTSR5	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0	_		U1RXR5	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0	3F3F
RPINR19	06A6	_	—	U2CTSR5	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0	—	_	U2RXR5	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0	3F3F
RPINR20	06A8	_	—	SCK1R5	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0	—	_	SDI1R5	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0	3F3F
RPINR21	06AA	—	_	U3CTSR5	U3CTSR4	U3CTSR3	U3CTSR2	U3CTSR1	U3CTSR0	_	_	SS1R5	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0	3F3F
RPINR22	06AC	_	_	SCK2R5	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0	_	_	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0	3F3F
RPINR23	06AE	_	—	—	_	—	—	—	—	_	_	SS2R5	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0	003F
RPINR27	06B6	_	—	U4CTSR5	U4CTSR4	U4CTSR3	U4CTSR2	U4CTSR1	U4CTSR0	—	_	U4RXR5	U4RXR4	U4RXR3	U4RXR2	U4RXR1	U4RXR0	3F3F
RPINR28	06B8	_	—	SCK3R5	SCK3R4	SCK3R3	SCK3R2	SCK3R1	SCK3R0	_	_	SDI3R5	SDI3R4	SDI3R3	SDI3R2	SDI3R1	SDI3R0	3F3F
RPINR29	06BA	_	_	_	_	_	_	_	_	_	_	SS3R5	SS3R4	SS3R3	SS3R2	SS3R1	SS3R0	003F

 Legend:
 — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-30: PERIPHERAL PIN SELECT REGISTER MAP (CONTINUED)

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RPOR0	06C0	_	—	RP1R5	RP1R4	RP1R3	RP1R2	RP1R1	RP1R0	_	—	RP0R5	RP0R4	RP0R3	RP0R2	RP0R1	RP0R0	0000
RPOR1	06C2		_	RP3R5	RP3R4	RP3R3	RP3R2	RP3R1	RP3R0		_	RP2R5	RP2R4	RP2R3	RP2R2	RP2R1	RP2R0	0000
RPOR2	06C4	_	_	RP5R5 ⁽¹⁾	RP5R4 ⁽¹⁾	RP5R3 ⁽¹⁾	RP5R2 ⁽¹⁾	RP5R1 ⁽¹⁾	RP5R0 ⁽¹⁾	_	_	RP4R5	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0	0000
RPOR3	06C6	_	_	RP7R5	RP7R4	RP7R3	RP7R2	RP7R1	RP7R0	_	_	RP6R5	RP6R4	RP6R3	RP6R2	RP6R1	RP6R0	0000
RPOR4	06C8		_	RP9R5	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0		_	RP8R5	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0	0000
RPOR5	06CA	_	_	RP11R5	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0	_	_	RP10R5	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0	0000
RPOR6	06CC	_	_	RP13R5	RP13R4	RP13R3	RP13R2	RP13R1	RP13R0	_	_	RP12R5	RP12R4	RP12R3	RP12R2	RP12R1	RP12R0	0000
RPOR7	06CE	-	_	RP15R5 ⁽¹⁾	RP15R4 ⁽¹⁾	RP15R3 ⁽¹⁾	RP15R2 ⁽¹⁾	RP15R1 ⁽¹⁾	RP15R0 ⁽¹⁾		_	RP14R5	RP14R4	RP14R3	RP14R2	RP14R1	RP14R0	0000
RPOR8	06D0		_	RP17R5	RP17R4	RP17R3	RP17R2	RP17R1	RP17R0		_	RP16R5	RP16R4	RP16R3	RP16R2	RP16R1	RP16R0	0000
RPOR9	06D2	_	_	RP19R5	RP19R4	RP19R3	RP19R2	RP19R1	RP19R0	_	_	RP18R5	RP18R4	RP18R3	RP18R2	RP18R1	RP18R0	0000
RPOR10	06D4	-	_	RP21R5	RP21R4	RP21R3	RP21R2	RP21R1	RP21R0		_	RP20R5	RP20R4	RP20R3	RP20R2	RP20R1	RP20R0	0000
RPOR11	06D6		_	RP23R5	RP23R4	RP23R3	RP23R2	RP23R1	RP23R0		_	RP22R5	RP22R4	RP22R3	RP22R2	RP22R1	RP22R0	0000
RPOR12	06D8	-	_	RP25R5	RP25R4	RP25R3	RP25R2	RP25R1	RP25R0	-	_	RP24R5	RP24R4	RP24R3	RP24R2	RP24R1	RP24R0	0000
RPOR13	06DA	_		RP27R5	RP27R4	RP27R3	RP27R2	RP27R1	RP27R0	_		RP26R5	RP26R4	RP26R3	RP26R2	RP26R1	RP26R0	0000
RPOR14	06DC	_	_	RP29R5	RP29R4	RP29R3	RP29R2	RP29R1	RP29R0	_	_	RP28R5	RP28R4	RP28R3	RP28R2	RP28R1	RP28R0	0000
RPOR15 ⁽¹⁾	06DE		_	RP31R5 ⁽¹⁾	RP31R4 ⁽¹⁾	RP31R3 ⁽¹⁾	RP31R2 ⁽¹⁾	RP31R1 ⁽¹⁾	RP31R0 ⁽¹⁾	_	_	RP30R5 ⁽¹⁾	RP30R4 ⁽¹⁾	RP30R3 ⁽¹⁾	RP30R2 ⁽¹⁾	RP30R1 ⁽¹⁾	RP30R0 ⁽¹⁾	0000

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 Legend:
 -- = unimplemented, read as '0'. Reset values are shown in hexadecimal.

 Note
 1:
 Bits are unimplemented in 64-pin devices; read as '0'.

TABLE 4-31: GRAPHICS REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets	
G1CMDL	0700							Graph	ics Command I	Register<15:0>	,							0000	
G1CMDH	0702							Graphi	cs Command F	Register<31:16	>							0000	
G1CON1	0704	G1EN	_	G1SIDL	GCMDWMK4	GCMDWMK3	GCMDWMK2	GCMDWMK2 GCMDWMK1 GCMDWMK0 PUBPP2 PUBPP1 PUBPP0 GCMDCNT4 GCMDCNT3 GCMDCNT2 GCMDCNT1 GCMD										0000	
G1STAT	0706	PUBUSY	_	_	_	_	IPUBUSY RCCBUSY CHRBUSY VMRGN HMRGN CMDLV CMDFUL CMD										CMDMPT	0000	
G1IE	0708	PUIE	_	_	_	_	_	_	_	IPUIE	RCCIE	CHRIE	VMRGNIE	HMRGNIE	CMDLVIE	CMDFULIE	CMDMPTIE	0000	
G1IR	070A	PUIF	_	—	_	—	_	_	_	IPUIF	RCCIF	CHRIF	VMRGNIF	HMRGNIF	CMDLVIF	CMDFULIF	CMDMPTIF	0000	
G1W1ADRL	070C							GPU Work A	Area 1 Start Ado	dress Register	<15:0>							0000	
G1W1ADRH	070E	—	—	—	-	—	—	—	—			GPU Wa	rk Area 1 Star	Address Regi	ster<23:16>			0000	
G1W2ADRL	0710			-			-	GPU Work A	Area 2 Start Ado	dress Register	<15:0>							0000	
G1W2ADRH	0712	—	_	—	—	—	_	-	—			GPU Wa	rk Area 2 Star	Address Regi	ster<23:16>			0000	
G1PUW	0714	—	_	—	—	—					GPU Wor	k Area Width	Register					0000	
G1PUH	0716	_	—	_	_	_					GPU Wor	k Area Heigh	t Register					0000	
G1DPADRL	0718							Display Bu	uffer Start Addre	ess Register<1	5:0>							0000	
G1DPADRH	071A	_	—	_	—	_	_	—	—			Display	/ Buffer Start A	ddress Regist	er<23:16>			0000	
G1DPW	071C	_	_	_	_	_					Display F	rame Width	Register					0000	
G1DPH	071E	—	_	—	_	_					Display F	rame Height	Register					0000	
G1DPWT	0720	—	_	—	_	_					Display	Total Width F	Register					0000	
G1DPHT	0722	—	—	—	—	_					Display	Total Height I	Register		1	1	1	0000	
G1CON2	0724	DPGWDTH1	DPGWDTH0	DPSTGER1	DPSTGER0	—	_	DPTEST1	DPTEST0	DPBPP2	DPBPP1	DPBPP0	—	—	DPMODE2	DPMODE1	DPMODE0	0000	
G1CON3	0726	_	—	_	_	_	—	DPPINOE	DPPOWER	DPCLKPOL	DPENPOL	DPVSPOL	DPHSPOL	DPPWROE	DPENOE	DPVSOE	DPHSOE	0000	
G1ACTDA	0728				Lines Before th		0			Number of Pixels Before the First Active Plxel Register									
G1HSYNC	072A			HSYN	IC Pulse-Width	Configuration F	Register			HSYNC Start Delay Configuration Register									
G1VSYNC	072C			VSYN	IC Pulse-Width	Configuration F	Register					VSYI	NC Start Delay	Configuration	Register			0000	
G1DBLCON	072E		Vert	tical Blanking	Start to First Dis	played Line Co	nfiguration Reg	jsiter			Horizo	ntal Blanking	Start to First D	Displayed Line	Configuration F	Regsiter		0000	
G1CLUT	0730	CLUTEN	CLUTBUSY	—	-	—	—	CLUTTRD	CLUTRWEN			Color Lo	ook-Up Table N	Memory Addres	ss Register			0000	
G1CLUTWR	0732							Color Look-u	p Table Memor	y Write Data R	legister							0000	
G1CLUTRD	0734	Color Look-up Table Memory Read Data Register												0000					
G1MRGN	0736	36 Vertical Blanking Advance Register Horizontal Blanking Advance										ng Advance Re	egister			0000			
G1CHRX	0738	_	_	_	_					Curre	nt Character	X-Coordinate	e Position Reg	ister				0000	
G1CHRY	073A	Current Character Y-Coordinate Position Register											0000						
G1IPU	073C	_	_	_	_	_	_		_	_	_	HUFFERR	BLCKERR	LENERR	WRAPERR	IPUDONE	BFINAL	0000	
G1DBEN	073E	GDBEN15	GDBEN14	GDBEN13	GDBEN12	GDBEN11	GDBEN10	GDBEN9	GDBEN8	GDBEN7	GDBEN6	GDBEN5	GDBEN4	GDBEN3	GDBEN2	GDBEN1	GDBEN0	0000	

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Legend: — = unimplemented, read as '0'. Reset values are shown in hexadecimal.

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
RCON	0740	TRAPR	IOPUWR	-	—		_	CM	VREGS	EXTR	SWR	SWDTEN	WDTO	SLEEP	IDLE	BOR	POR	Note 1
OSCCON	0742	_	COSC2	COSC1	COSC0	_	NOSC2	NOSC1	NOSC0	CLKLOCK	IOLOCK	LOCK	_	CF	POSCEN	SOSCEN	OSWEN	Note 2
CLKDIV	0744	ROI	DOZE2	DOZE1	DOZE0	DOZEN	RCDIV2	RCDIV1	RCDIV0	CPDIV1	CPDIV0	PLLEN	G1CLKSEL	_	_	_	_	0100
CLKDIV2	0746	GCLKDIV6	GCLKDIV5	GCLKDIV4	GCLKDIV3	GCLKDIV2	GCLKDIV1	GCLKDIV0	_	_	_	_	_	_	_	_	—	0000
OSCTUN	0748	_	_	_	_	_	_	_	_	_	_	TUN5	TUN4	TUN3	TUN2	TUN1	TUN0	0000
REFOCON	074E	ROEN	_	ROSSLP	ROSEL	RODIV3	RODIV2	RODIV1	RODIV0	_	_	_	_	_	—	_	_	0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

The Reset value of the RCON register is dependent on the type of Reset event. See Section 6.0 "Resets" for more information. Note 1:

The Reset value of the OSCCON register is dependent on both the type of Reset event and the device configuration. See Section 8.0 "Oscillator Configuration" for more information. 2:

TABLE 4-33: NVM REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
NVMCON	0760	WR	WREN	WRERR	_	_	_	_	_	_	ERASE	_	_	NVMOP3	NVMOP2	NVMOP1	NVMOP0	₀₀₀₀ (1)
NVMKEY	0766	_	_	_	_	_	_	_	_				NVMKEY R	egister<7:0>				0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Reset value shown is for POR only. Value on other Reset states is dependent on the state of memory write or erase operations at the time of Reset. Note 1:

TABLE 4-34: PMD REGISTER MAP

File Name	Addr	Bit 15	Bit 14	Bit 13	Bit 12	Bit 11	Bit 10	Bit 9	Bit 8	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	All Resets
PMD1	0770	T5MD	T4MD	T3MD	T2MD	T1MD	-	_	_	I2C1MD	U2MD	U1MD	SPI2MD	SPI1MD	—	_	ADC1MD	0000
PMD2	0772	IC8MD	IC7MD	IC6MD	IC5MD	IC4MD	IC3MD	IC2MD	IC1MD	OC8MD	OC7MD	OC6MD	OC5MD	OC4MD	OC3MD	OC2MD	OC1MD	0000
PMD3	0774	_		_	_		CMPMD	RTCCMD	PMPMD ⁽¹⁾	CRCMD	_	_	_	U3MD	I2C3MD	I2C2MD		0000
PMD4	0776	_	_	_	_	_	_	—	_	_	UPWMMD	U4MD	_	REFOMD	CTMUMD	LVDMD	USB1MD	0000
PMD5	0778	_	_	_	_	_	_	—	IC9MD	_	_	_	_	_	_	_	OC9MD	0000
PMD6	077A	_	_	_	_	_	_	_	_	_	GFX1MD	_	_	_	—	_	SPI3MD	0000

Legend: - = unimplemented, read as '0'. Reset values are shown in hexadecimal.

Note 1: Unimplemented in 64-pin devices, read as '0'.

4.2.5 EXTENDED DATA SPACE (EDS)

The enhancement of the data space in PIC24FJ256DA210 family devices has been accomplished by a new technique, called the Extended Data Space (EDS).

The EDS includes any additional internal extended data memory not accessible by the lower 32 Kbytes data address space, any external memory through EPMP and the Program Space Visibility (PSV).

The extended data space is always accessed through the EDS window, the upper half of data space. The entire extended data space is organized into EDS pages, each having 32 Kbytes of data. Mapping of the EDS page into the EDS window is done using the Data Space Read register (DSRPAG<9:0>) for read operations and Data Space Write register (DSWPAG<8:0>) for write operations. Figure 4-4 displays the entire EDS space.

Note: Accessing Page 0 in the EDS window will generate an address error trap as Page 0 is the base data memory (data locations, 0x0800 to 0x7FFF, in the lower data space).

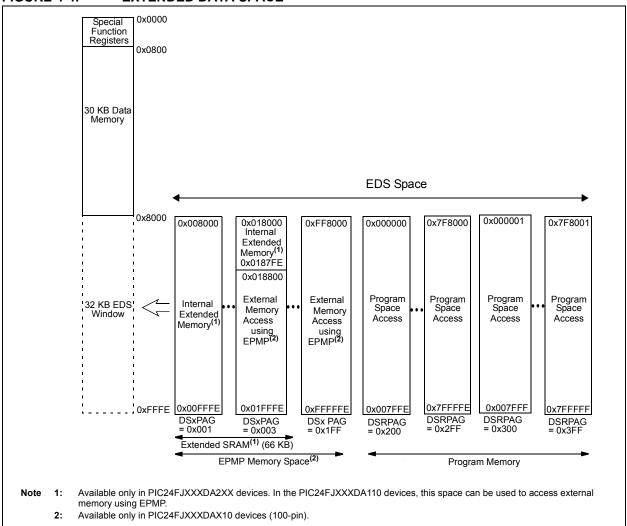


FIGURE 4-4: EXTENDED DATA SPACE

4.2.5.1 Data Read from EDS Space

In order to read the data from the EDS space, first, an Address Pointer is set up by loading the required EDS page number into the DSRPAG register and assigning the offset address to one of the W registers. Once the above assignment is done, the EDS window is enabled by setting bit 15 of the working register, assigned with the offset address; then, the contents of the pointed EDS location can be read.

Figure 4-5 illustrates how the EDS space address is generated for read operations.

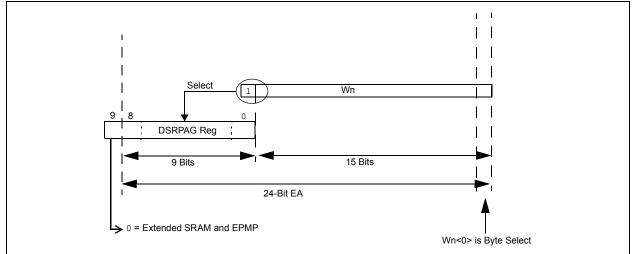


FIGURE 4-5: EDS ADDRESS GENERATION FOR READ OPERATIONS

When the Most Significant bit (MSBs) of EA is '1' and DSRPAG<9> = 0, the lower 9 bits of DSRPAG are concatenated to the lower 15 bits of EA to form a 24-bit EDS space address for read operations.

Example 4-1 shows how to read a byte, word and double-word from EDS.

Note:	All read operations from EDS space have an overhead of one instruction cycle.
	Therefore, a minimum of two instruction
	cycles is required to complete an EDS
	read. EDS reads under the REPEAT
	instruction; the first two accesses take
	three cycles and the subsequent
	accesses take one cycle.

EXAMPLE 4-1: EDS READ CODE IN ASSEMBLY

```
; Set the EDS page from where the data to be read
              #0x0002 , w0
   mov
              w0 , DSRPAG
                             ;page 2 is selected for read
   mov
   mov
              \#0x0800 , w1 ;select the location (0x800) to be read
bset
          wl , #15
                         ;set the MSB of the base address, enable EDS mode
;Read a byte from the selected location
   mov.b
            [w1++] , w2 ;read Low byte
   mov.b
              [w1++] , w3 ;read High byte
;Read a word from the selected location
              [w1] , w2
   mov
                           ;
;Read Double - word from the selected location
   mov.d
              [w1] , w2
                             ;two word read, stored in w2 and w3
```

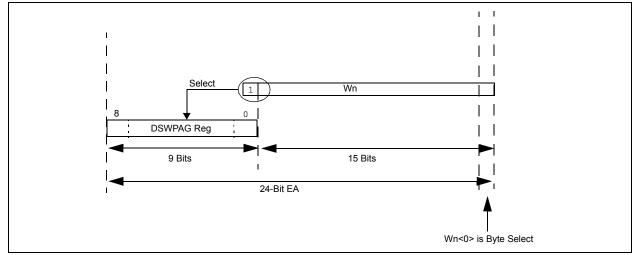
4.2.5.2 Data Write into EDS Space

In order to write data to EDS space, such as in EDS reads, an Address Pointer is set up by loading the required EDS page number into the DSWPAG register, and assigning the offset address to one of the W registers. Once the above assignment is done, then the

EDS window is enabled by setting bit 15 of the working register, assigned with the offset address, and the accessed location can be written.

Figure 4-2 illustrates how the EDS space address is generated for write operations.

FIGURE 4-6: EDS ADDRESS GENERATION FOR WRITE OPERATIONS



When the MSBs of EA is '1', the lower 9 bits of DSWPAG are concatenated to the lower 15 bits of EA to form a 24-bit EDS address for write operations. Example 4-2 shows how to write a byte, word and double-word to EDS.

EXAMPLE 4-2: EDS WRITE CODE IN ASSEMBLY

```
; Set the EDS page where the data to be written
          #0x0002 , w0
   mov
          w0 , DSWPAG
                         ;page 2 is selected for write
   mov
          \#0x0800 , wl ;select the location (0x800) to be written
   mov
   bset
          wl , #15
                         ;set the MSB of the base address, enable EDS mode
;Write a byte to the selected location
   mov
         #0x00A5 , w2
          #0x003C , w3
   mov
   mov.b w2 , [w1++]
                            ;write Low byte
                        ;write High byte
   mov.b w3 , [w1++]
;Write a word to the selected location
   mov
         #0x1234 , w2 ;
          w2 , [w1]
   mov
                         ;
;Write a Double - word to the selected location
   mov #0x1122 , w2
          #0x4455 , w3
   mov
   mov.d w2 , [w1]
                         ;2 EDS writes
```

The page registers (DSRPAG/DSWPAG) do not update automatically while crossing a page boundary, when the rollover happens from 0xFFFF to 0x8000. While developing code in assembly, care must be taken to update the page registers when an Address Pointer crosses the page boundary. The 'C' compiler keeps track of the addressing, and increments or decrements the page registers accordingly while accessing contiguous data memory locations.

- **Note 1:** All write operations to EDS are executed in a single cycle.
 - 2: Use of Read/Modify/Write operation on any EDS location under a REPEAT instruction is not supported. For example, BCLR, BSW, BTG, RLC f, RLNC f, RRC f, RRNC f, ADD f, SUB f, SUBR f, AND f, IOR f, XOR f, ASR f, ASL f.
 - 3: Use the DSRPAG register while performing Read/Modify/Write operation.

DSRPAG (Data Space Read Register)	DSWPAG (Data Space Write Register)	Source/Destination Address while Indirect Addressing	24-Bit EA Pointing to EDS	Comment
x ⁽¹⁾	x ⁽¹⁾	0x0000 to 0x1FFF	0x000000 to 0x001FFF	Near data space ⁽²⁾
		0x2000 to 0x7FFF	0x002000 to 0x007FFF	
0x001	0x001		0x008000 to 0x00FFFE	
0x002	0x002		0x010000 to 0x017FFE	32 Kbytes on each page
0x003	0x003	0x8000 to 0xFFFF	0x018000 to 0x0187FE	Only 2 Kbytes of extended SRAM on this page
0x004	0x004		0x018800 to 0x027FFE	
• • •	• • •		•	EPMP memory space ⁽⁴⁾
0x1FF	0x1FF		0xFF8000 to 0xFFFFFE	
0x000	0x000		Invalid Address	Address error trap ⁽³⁾

TABLE 4-35: EDS MEMORY ADDRESS WITH DIFFERENT PAGES AND ADDRESSES

Note 1: If the source/destination address is below 0x8000, the DSRPAG and DSWPAG registers are not considered.

2: This data space can also be accessed by Direct Addressing.

3: When the source/destination address is above 0x8000 and DSRPAG/DSWPAG is '0', an address error trap will occur.

4: EPMP memory space can start from location, 0x008000, in the parts with 24 Kbytes of data memory (PIC24FJXXXDA1XX)

4.2.6 SOFTWARE STACK

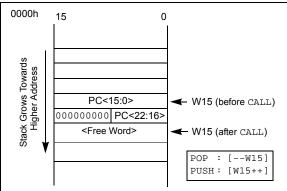
Apart from its use as a working register, the W15 register in PIC24F devices is also used as a Software Stack Pointer (SSP). The pointer always points to the first available free word and grows from lower to higher addresses. It pre-decrements for stack pops and post-increments for stack pushes, as shown in Figure 4-7. Note that for a PC push during any CALL instruction, the MSB of the PC is zero-extended before the push, ensuring that the MSB is always clear.

Note:	A PC push during exception processing	
	will concatenate the SRL register to the	
	MSB of the PC prior to the push.	

The Stack Pointer Limit Value register (SPLIM), associated with the Stack Pointer, sets an upper address boundary for the stack. SPLIM is uninitialized at Reset. As is the case for the Stack Pointer, SPLIM<0> is forced to '0' as all stack operations must be word-aligned. Whenever an EA is generated using W15 as a source or destination pointer, the resulting address is compared with the value in SPLIM. If the contents of the Stack Pointer (W15) and the SPLIM register are equal, and a push operation is performed, a stack error trap will not occur. The stack error trap will occur on a subsequent push operation. Thus, for example, if it is desirable to cause a stack error trap when the stack grows beyond address 2000h in RAM, initialize the SPLIM with the value, 1FFEh.

Similarly, a Stack Pointer underflow (stack error) trap is generated when the Stack Pointer address is found to be less than 0800h. This prevents the stack from interfering with the SFR space.

A write to the SPLIM register should not be immediately followed by an indirect read operation using W15.



4.3 Interfacing Program and Data Memory Spaces

The PIC24F architecture uses a 24-bit wide program space and 16-bit wide data space. The architecture is also a modified Harvard scheme, meaning that data can also be present in the program space. To use this data successfully, it must be accessed in a way that preserves the alignment of information in both spaces.

Aside from normal execution, the PIC24F architecture provides two methods by which program space can be accessed during operation:

- Using table instructions to access individual bytes or words anywhere in the program space
- Remapping a portion of the program space into the data space (program space visibility)

Table instructions allow an application to read or write to small areas of the program memory. This makes the method ideal for accessing data tables that need to be updated from time to time. It also allows access to all bytes of the program word. The remapping method allows an application to access a large block of data on a read-only basis, which is ideal for look ups from a large table of static data. It can only access the least significant word of the program word.

4.3.1 ADDRESSING PROGRAM SPACE

Since the address ranges for the data and program spaces are 16 and 24 bits, respectively, a method is needed to create a 23-bit or 24-bit program address from 16-bit data registers. The solution depends on the interface method to be used.

For table operations, the 8-bit Table Memory Page Address register (TBLPAG) is used to define a 32K word region within the program space. This is concatenated with a 16-bit EA to arrive at a full 24-bit program space address. In this format, the MSBs of TBLPAG is used to determine if the operation occurs in the user memory (TBLPAG<7> = 0) or the configuration memory (TBLPAG<7> = 1).

For remapping operations, the 10-bit Extended Data Space Read register (DSRPAG) is used to define a 16K word page in the program space. When the Most Significant bit (MSb) of the EA is '1', and the MSb (bit 9) of DSRPAG is '1', the lower 8 bits of DSRPAG are concatenated with the lower 15 bits of the EA to form a 23-bit program space address. The DSRPAG<8> bit decides whether the lower word (when bit is '0') or the higher word (when bit is '1') of program memory is mapped. Unlike table operations, this strictly limits remapping operations to the user memory area.

Table 4-36 and Figure 4-8 show how the program EA is created for table operations and remapping accesses from the data EA. Here, P<23:0> refers to a program space word, whereas D<15:0> refers to a data space word.

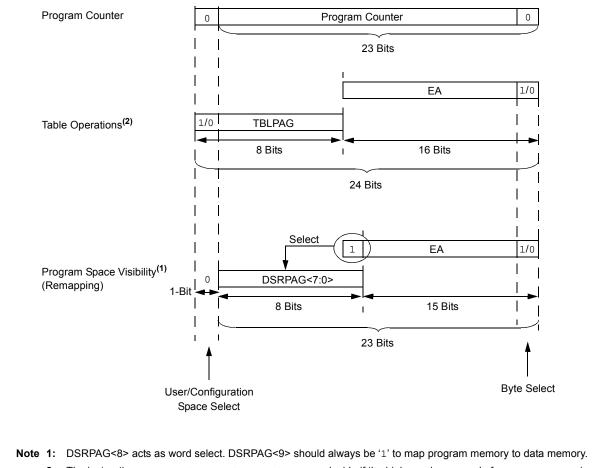
TABLE 4-36: PROGRAM SPACE ADDRESS CONSTRUCTION

	Access	Program Space Address					
Access Type	Space	<23>	<22:16>	<15>	<14:1>	<0>	
Instruction Access	User	0 PC<22:1>				0	
(Code Execution)			0xx xxxx xxxx xxxx xxxx xxx0				
TBLRD/TBLWT (Byte/Word Read/Write)	User	TBLPAG<7:0>		Data EA<15:0>			
		0:	xxx xxxx	xxxx xxxx xxxx xxxx			
	Configuration	TBLPAG<7:0>		Data EA<15:0>			
		1xxx xxxx		xxxx xxxx xxxx xxxx		xxx	
Program Space Visibility	User 0		DSRPAG<7:0> ⁽²⁾		Data EA<14	:0>(1)	
(Block Remap/Read)		0	XXXX XXX	κx	XXX XXXX XXX	x xxxx	

Note 1: Data EA<15> is always '1' in this case, but is not used in calculating the program space address. Bit 15 of the address is DSRPAG<0>.

2: DSRPAG<9> is always '1' in this case. DSRPAG<8> decides whether the lower word or higher word of program memory is read. When DSRPAG<8> is '0', the lower word is read and when it is '1', the higher word is read.

FIGURE 4-8: DATA ACCESS FROM PROGRAM SPACE ADDRESS GENERATION



2: The instructions, TBLRDH/TBLWTH/TBLRDL/TBLWTL, decide if the higher or lower word of program memory is accessed. TBLRDH/TBLWTH instructions access the higher word and TBLRDL/TBLWTL instructions access the lower word. Table read operations are permitted in the configuration memory space.

4.3.2 DATA ACCESS FROM PROGRAM MEMORY USING TABLE INSTRUCTIONS

The TBLRDL and TBLWTL instructions offer a direct method of reading or writing the lower word of any address within the program space without going through data space. The TBLRDH and TBLWTH instructions are the only method to read or write the upper 8 bits of a program space word as data.

The PC is incremented by two for each successive 24-bit program word. This allows program memory addresses to directly map to data space addresses. Program memory can thus be regarded as two, 16-bit word-wide address spaces, residing side by side, each with the same address range. TBLRDL and TBLWTL access the space which contains the least significant data word, and TBLRDH and TBLWTH access the space which contains the upper data byte.

Two table instructions are provided to move byte or word-sized (16-bit) data to and from program space. Both function as either byte or word operations.

 TBLRDL (Table Read Low): In Word mode, it maps the lower word of the program space location (P<15:0>) to a data address (D<15:0>).
 In Byte mode, either the upper or lower byte of the lower program word is mapped to the lower byte of a data address. The upper byte is selected when byte select is '1'; the lower byte is selected when it is '0'. TBLRDH (Table Read High): In Word mode, it maps the entire upper word of a program address (P<23:16>) to a data address. Note that D<15:8>, the 'phantom' byte, will always be '0'. In Byte mode, it maps the upper or lower byte of the program word to D<7:0> of the data address, as above. Note that the data will always be '0' when the upper 'phantom' byte is selected (byte select = 1).

In a similar fashion, two table instructions, TBLWTH and TBLWTL, are used to write individual bytes or words to a program space address. The details of their operation are described in **Section 5.0 "Flash Program Memory"**.

For all table operations, the area of program memory space to be accessed is determined by the Table Memory Page Address register (TBLPAG). TBLPAG covers the entire program memory space of the device, including user and configuration spaces. When TBLPAG<7> = 0, the table page is located in the user memory space. When TBLPAG<7> = 1, the page is located in configuration space.

Note: Only table read operations will execute in the configuration memory space, where Device IDs are located. Table write operations are not allowed.

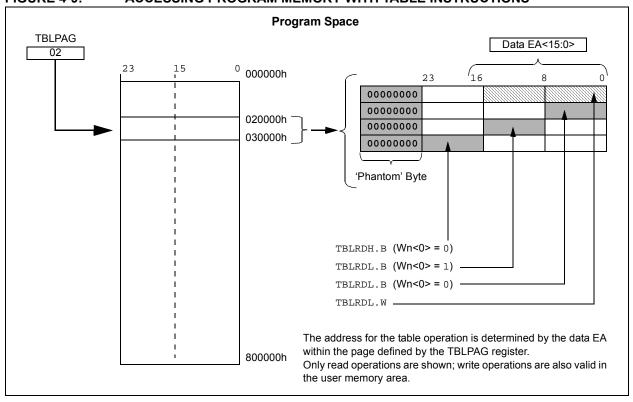


FIGURE 4-9: ACCESSING PROGRAM MEMORY WITH TABLE INSTRUCTIONS

4.3.3 READING DATA FROM PROGRAM MEMORY USING EDS

The upper 32 Kbytes of data space may optionally be mapped into any 16K word page of the program space. This provides transparent access of stored constant data from the data space without the need to use special instructions (i.e., TBLRDL/H).

Program space access through the data space occurs when the MSb of EA is '1' and the DSRPAG<9> is also '1'. The lower 8 bits of DSRPAG are concatenated to the Wn<14:0> bits to form a 23-bit EA to access program memory. The DSRPAG<8> decides which word should be addressed; when the bit is '0', the lower word and when '1', the upper word of the program memory is accessed.

The entire program memory is divided into 512 EDS pages, from 0x200 to 0x3FF, each consisting of 16K words of data. Pages, 0x200 to 0x2FF, correspond to the lower words of the program memory, while 0x300 to 0x3FF correspond to the upper words of the program memory.

Using this EDS technique, the entire program memory can be accessed. Previously, the access to the upper word of the program memory was not supported. Table 4-37 provides the corresponding 23-bit EDS address for program memory with EDS page and source addresses.

For operations that use PSV and are executed outside a REPEAT loop, the MOV and MOV.D instructions will require one instruction cycle in addition to the specified execution time. All other instructions will require two instruction cycles in addition to the specified execution time.

For operations that use PSV, which are executed inside a REPEAT loop, there will be some instances that require two instruction cycles in addition to the specified execution time of the instruction:

- Execution in the first iteration
- · Execution in the last iteration
- Execution prior to exiting the loop due to an interrupt
- Execution upon re-entering the loop after an interrupt is serviced

Any other iteration of the REPEAT loop will allow the instruction accessing data, using PSV, to execute in a single cycle.

DSRPAG (Data Space Read Register)	Source Address while Indirect Addressing	23-Bit EA Pointing to EDS	Comment
0x200		0x000000 to 0x007FFE	
•		•	Lower words of 4M
•		•	program instructions;
•		•	(8 Mbytes) for read operations only.
0x2FF	0x8000 to 0xFFFF	0x7F8000 to 0x7FFFFE	
0x300		0x000001 to 0x007FFF	Upper words of 4M
•		•	program instructions
•		•	(4 Mbytes remaining,
•		•	4 Mbytes are phantom bytes) for read
0x3FF		0x7F8001 to 0x7FFFFF	operations only.
0x000		Invalid Address	Address error trap ⁽¹⁾

TABLE 4-37: EDS PROGRAM ADDRESS WITH DIFFERENT PAGES AND ADDRESSES

Note 1: When the source/destination address is above 0x8000 and DSRPAG/DSWPAG is '0', an address error trap will occur.



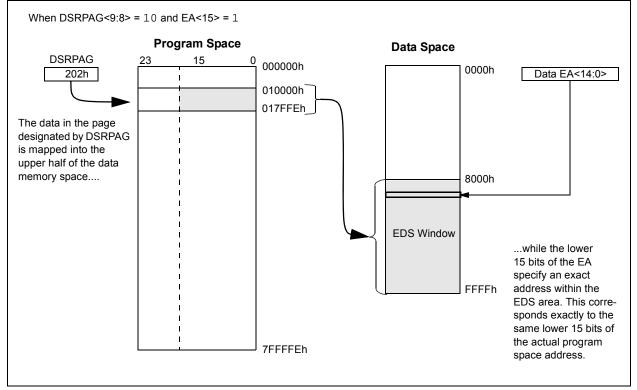
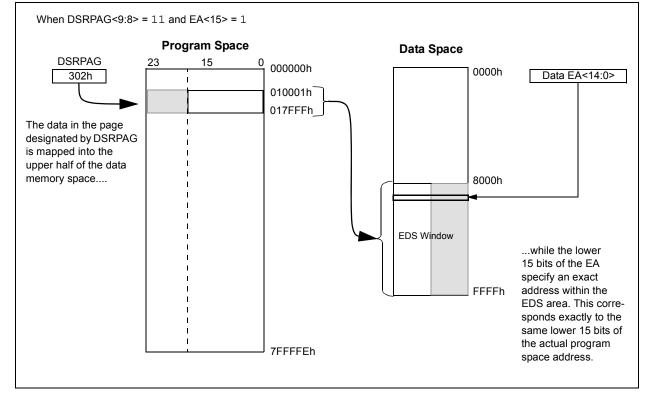


FIGURE 4-11: PROGRAM SPACE VISIBILITY OPERATION TO ACCESS HIGHER WORD



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EXAMPLE 4-3: EDS READ CODE FROM PROGRAM MEMORY IN ASSEMBLY

; Set the EDS page from where the data to be read #0x0202 , w0 mov w0 , DSRPAG ;page 0x202, consisting lower words, is selected for read mov mov #0x000A , w1 ;select the location (0x0A) to be read bset w1 , #15 ;set the MSB of the base address, enable EDS mode ;Read a byte from the selected location mov.b [w1++] , w2 ;read Low byte mov.b [w1++] , w3 ;read High byte ;Read a word from the selected location mov [w1], w2 ; ;Read Double - word from the selected location mov.d [w1] , w2 ;two word read, stored in w2 and w3

5.0 FLASH PROGRAM MEMORY

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 4. "Program Memory" (DS39715). The information in this data sheet supersedes the information in the FRM.

The PIC24FJ256DA210 family of devices contains internal Flash program memory for storing and executing application code. The program memory is readable, writable and erasable. The Flash can be programmed in four ways:

- In-Circuit Serial Programming[™] (ICSP[™])
- Run-Time Self-Programming (RTSP)
- JTAG
- Enhanced In-Circuit Serial Programming (Enhanced ICSP)

ICSP allows a PIC24FJ256DA210 family device to be serially programmed while in the end application circuit. This is simply done with two lines for the programming clock and programming data (named PGECx and PGEDx, respectively), and three other lines for power (VDD), ground (VSS) and Master Clear (MCLR). This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

RTSP is accomplished using TBLRD (table read) and TBLWT (table write) instructions. With RTSP, the user may write program memory data in blocks of 64 instructions (192 bytes) at a time and erase program memory in blocks of 512 instructions (1536 bytes) at a time.

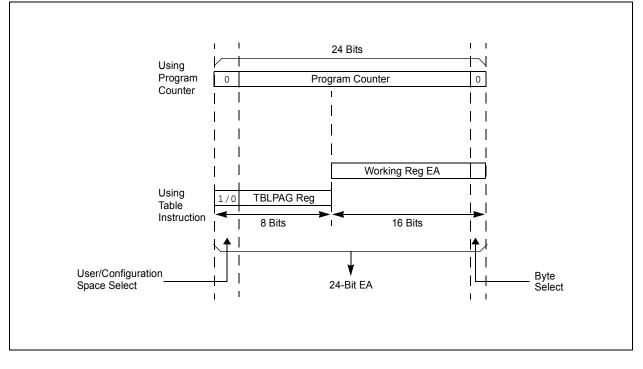
5.1 Table Instructions and Flash Programming

Regardless of the method used, all programming of Flash memory is done with the table read and write instructions. These allow direct read and write access to the program memory space from the data memory while the device is in normal operating mode. The 24-bit target address in the program memory is formed using the TBLPAG<7:0> bits and the Effective Address (EA) from a W register, specified in the table instruction, as shown in Figure 5-1.

The TBLRDL and the TBLWTL instructions are used to read or write to bits<15:0> of program memory. TBLRDL and TBLWTL can access program memory in both Word and Byte modes.

The TBLRDH and TBLWTH instructions are used to read or write to bits<23:16> of program memory. TBLRDH and TBLWTH can also access program memory in Word or Byte mode.

FIGURE 5-1: ADDRESSING FOR TABLE REGISTERS



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5.2 RTSP Operation

The PIC24F Flash program memory array is organized into rows of 64 instructions or 192 bytes. RTSP allows the user to erase blocks of eight rows (512 instructions) at a time and to program one row at a time. It is also possible to program single words.

The 8-row erase blocks and single row write blocks are edge-aligned, from the beginning of program memory, on boundaries of 1536 bytes and 192 bytes, respectively.

When data is written to program memory using TBLWT instructions, the data is not written directly to memory. Instead, data written using table writes is stored in holding latches until the programming sequence is executed.

Any number of TBLWT instructions can be executed and a write will be successfully performed. However, 64 TBLWT instructions are required to write the full row of memory.

To ensure that no data is corrupted during a write, any unused address should be programmed with FFFFFFh. This is because the holding latches reset to an unknown state, so if the addresses are left in the Reset state, they may overwrite the locations on rows which were not rewritten.

The basic sequence for RTSP programming is to set up a Table Pointer, then do a series of TBLWT instructions to load the buffers. Programming is performed by setting the control bits in the NVMCON register.

Data can be loaded in any order and the holding registers can be written to multiple times before performing a write operation. Subsequent writes, however, will wipe out any previous writes.

Note: Writing to a location multiple times without erasing is *not* recommended.

All of the table write operations are single-word writes (2 instruction cycles), because only the buffers are written. A programming cycle is required for programming each row.

5.3 JTAG Operation

The PIC24F family supports JTAG boundary scan. Boundary scan can improve the manufacturing process by verifying pin to PCB connectivity.

5.4 Enhanced In-Circuit Serial Programming

Enhanced In-Circuit Serial Programming uses an on-board bootloader, known as the program executive, to manage the programming process. Using an SPI data frame format, the program executive can erase, program and verify program memory. For more information on Enhanced ICSP, see the device programming specification.

5.5 Control Registers

There are two SFRs used to read and write the program Flash memory: NVMCON and NVMKEY.

The NVMCON register (Register 5-1) controls which blocks are to be erased, which memory type is to be programmed and when the programming cycle starts.

NVMKEY is a write-only register that is used for write protection. To start a programming or erase sequence, the user must consecutively write 55h and AAh to the NVMKEY register. Refer to **Section 5.6 "Programming Operations"** for further details.

5.6 Programming Operations

A complete programming sequence is necessary for programming or erasing the internal Flash in RTSP mode. During a programming or erase operation, the processor stalls (waits) until the operation is finished. Setting the WR bit (NVMCON<15>) starts the operation and the WR bit is automatically cleared when the operation is finished.

REGISTER 5-1:	NVMCON: FLASH MEMORY CONTROL REGISTER

R/S-0, HC ⁽¹⁾	R/W-0 ⁽¹⁾	R-0, HSC ⁽¹⁾	U-0	U-0	U-0	U-0	U-0
WR	WREN	WRERR	—		_		—
bit 15							bit 8
U-0	R/W-0 ⁽¹⁾	U-0	U-0	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾	R/W-0 ⁽¹⁾
_	ERASE	—	_	NVMOP3 ⁽²⁾	NVMOP2 ⁽²⁾	NVMOP1 ⁽²⁾	NVMOP0 ⁽²⁾
bit 7							bit
Legend:		S = Settable b	t	HSC = Hardw	are Settable/C	earable bit	
R = Readabl	e bit	W = Writable b	bit U = Unimplemented bit, read as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown
HC = Hardwa	are Clearable b	oit					
	cleared	a Flash memory by hardware onc o or erase operat	e the operatio	on is complete	n; the operatio	n is self-timed	and the bit i
bit 14	-	e Enable bit ⁽¹⁾					
		- lash program/er					
bit 13		ite Sequence Er	-	-			
	 1 = An improper program or erase sequence attempt or termination has occurred (bit is se automatically on any set attempt of the WR bit) 0 = The program or erase operation completed normally 						
bit 12-7	Unimpleme	nted: Read as '0	,				
bit 6	ERASE: Era	se/Program Ena	ble bit ⁽¹⁾				
		the erase operative the program operation operation of the program operation operatio					nd
bit 5-4	Unimplemer	nted: Read as '0	,				
bit 3-0		>: NVM Operation					
	0011 = Mer 0010 = Mer	mory bulk erase o mory word progra mory page erase mory row prograr	am operation operation (Ef	(ERASE = 0) or RASE = 1) or no	r no operation (o operation (EF	ERASE = 1) RASE = 0)	
	These bits can only be reset on POR. All other combinations of NVMOP<3:0> are unimplemented. Available in ICSP™ mode only: refer to the device programming specification						

3: Available in ICSP[™] mode only; refer to the device programming specification.

5.6.1 PROGRAMMING ALGORITHM FOR FLASH PROGRAM MEMORY

The user can program one row of Flash program memory at a time. To do this, it is necessary to erase the 8-row erase block containing the desired row. The general process is:

- 1. Read eight rows of program memory (512 instructions) and store in data RAM.
- 2. Update the program data in RAM with the desired new data.
- 3. Erase the block (see Example 5-1):
 - a) Set the NVMOP bits (NVMCON<3:0>) to '0010' to configure for block erase. Set the ERASE (NVMCON<6>) and WREN (NVMCON<14>) bits.
 - b) Write the starting address of the block to be erased into the TBLPAG and W registers.
 - c) Write 55h to NVMKEY.
 - d) Write AAh to NVMKEY.
 - e) Set the WR bit (NVMCON<15>). The erase cycle begins and the CPU stalls for the duration of the erase cycle. When the erase is done, the WR bit is cleared automatically.

- 4. Write the first 64 instructions from data RAM into the program memory buffers (see Example 5-3).
- 5. Write the program block to Flash memory:
 - a) Set the NVMOP bits to '0001' to configure for row programming. Clear the ERASE bit and set the WREN bit.
 - b) Write 55h to NVMKEY.
 - c) Write AAh to NVMKEY.
 - d) Set the WR bit. The programming cycle begins and the CPU stalls for the duration of the write cycle. When the write to Flash memory is done, the WR bit is cleared automatically.
- 6. Repeat steps 4 and 5, using the next available 64 instructions from the block in data RAM by incrementing the value in TBLPAG, until all 512 instructions are written back to Flash memory.

For protection against accidental operations, the write initiate sequence for NVMKEY must be used to allow any erase or program operation to proceed. After the programming command has been executed, the user must wait for the programming time until programming is complete. The two instructions following the start of the programming sequence should be NOPS, as shown in Example 5-4.

EXAMPLE 5-1: ERASING A PROGRAM MEMORY BLOCK (ASSEMBLY LANGUAGE CODE)

; Set up NVMCON for block erase oper	Set up NVMCON for block erase operation			
MOV #0x4042, W0 ;				
MOV W0, NVMCON	; Initialize NVMCON			
; Init pointer to row to be ERASED				
MOV #tblpage(PROG_ADDR), W0	i			
MOV W0, TBLPAG	; Initialize Program Memory (PM) Page Boundary SFR			
MOV #tbloffset(PROG_ADDR), W0	; Initialize in-page EA<15:0> pointer			
TBLWTL W0, [W0]	; Set base address of erase block			
DISI #5	; Block all interrupts with priority <7			
	; for next 5 instructions			
MOV.B #0x55, W0				
MOV W0, NVMKEY	; Write the 0x55 key			
MOV.B #0xAA, W1 ;				
MOV W1, NVMKEY	; Write the OxAA key			
BSET NVMCON, #WR	; Start the erase sequence			
NOP	; Insert two NOPs after the erase			
NOP	; command is asserted			

EXAMPLE 5-2: ERASING A PROGRAM MEMORY BLOCK ('C' LANGUAGE CODE)

<pre>// C example using MPLAB C30 unsigned long progAddr = 0xXXXXXX; unsigned int offset;</pre>	// Address of row to write
//Set up pointer to the first memory location t	o be written
TBLPAG = progAddr>>16;	// Initialize PM Page Boundary SFR
offset = progAddr & 0xFFFF;	<pre>// Initialize lower word of address</pre>
<pre>builtin_tblwtl(offset, 0x0000);</pre>	// Set base address of erase block
	// with dummy latch write
NVMCON = 0×4042 ;	// Initialize NVMCON
asm("DISI #5");	<pre>// Block all interrupts with priority <7</pre>
	// for next 5 instructions
builtin_write_NVM();	// check function to perform unlock
	// sequence and set WR

EXAMPLE 5-3: LOADING THE WRITE BUFFERS

; Set up NVMCO	N for row programming operations		
MOV	#0x4001, W0	;	
MOV	W0, NVMCON	;	Initialize NVMCON
; Set up a poir	nter to the first program memory	loc	ation to be written
; program memo	ry selected, and writes enabled		
MOV	#0x0000, W0	;	
MOV	W0, TBLPAG	;	Initialize PM Page Boundary SFR
MOV	#0x6000, W0	;	An example program memory address
; Perform the	TBLWT instructions to write the l	atc	hes
; 0th_program_	word		
MOV	#LOW_WORD_0, W2	;	
MOV	#HIGH_BYTE_0, W3	;	
TBLWTL	W2, [W0]	;	Write PM low word into program latch
TBLWTH	W3, [W0++]	;	Write PM high byte into program latch
; 1st_program_	word		
MOV	#LOW_WORD_1, W2	;	
MOV	#HIGH_BYTE_1, W3	;	
	W2, [W0]		Write PM low word into program latch
	W3, [W0++]	;	Write PM high byte into program latch
; 2nd_program	—		
MOV	#LOW_WORD_2, W2	;	
	#HIGH_BYTE_2, W3	;	
	W2, [W0]		Write PM low word into program latch
TBLWTH	W3, [W0++]	;	Write PM high byte into program latch
•			
•			
•	_		
; 63rd_program	—		
MOV	#LOW_WORD_63, W2	;	
MOV	<pre>#HIGH_BYTE_63, W3</pre>	;	
	W2, [W0]		Write PM low word into program latch
TBLWTH	W3, [W0]	;	Write PM high byte into program latch

EXAMPLE 5-4: INITIATING A PROGRAMMING SEQUENCE

DISI	#5	; Block all interrupts with priority <7 ; for next 5 instructions
MOV.B	#0x55, W0	
MOV	W0, NVMKEY	; Write the 0x55 key
MOV.B	#0xAA, W1	i
MOV	W1, NVMKEY	; Write the OxAA key
BSET	NVMCON, #WR	; Start the programming sequence
NOP		; Required delays
NOP		
BTSC	NVMCON, #15	; and wait for it to be
BRA	\$-2	; completed

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5.6.2 PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY

If a Flash location has been erased, it can be programmed using table write instructions to write an instruction word (24-bit) into the write latch. The TBLPAG register is loaded with the 8 Most Significant Bytes (MSB) of the Flash address. The TBLWTL and TBLWTH instructions write the desired data into the write latches and specify the lower 16 bits of the program memory address to write to. To configure the NVMCON register for a word write, set the NVMOP bits (NVMCON<3:0>) to '0011'. The write is performed by executing the unlock sequence and setting the WR bit (see Example 5-5). An equivalent procedure in 'C' compiler, using the MPLAB C30 compiler and built-in hardware functions is shown in Example 5-6.

EXAMPLE 5-5: PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY

; Setup a MOV MOV MOV		; ;Initialize PM Page Boundary SFR ;Initialize a register with program memory address
MOV	#LOW_WORD_N, W2	;
MOV	#HIGH_BYTE_N, W3	;
TBLWTL	W2, [W0]	; Write PM low word into program latch
TBLWTH	W3, [W0++]	; Write PM high byte into program latch
; Setup NV MOV MOV	MCON for programming one word to #0x4003, W0 W0, NVMCON	o data Program Memory ; ; Set NVMOP bits to 0011
DISI	#5	; Disable interrupts while the KEY sequence is written
MOV.B	#0x55, W0	; Write the key sequence
MOV	W0, NVMKEY	
MOV.B	#0xAA, W0	
MOV	W0, NVMKEY	
BSET	NVMCON, #WR	; Start the write cycle
NOP		; Required delays
NOP		

EXAMPLE 5-6: PROGRAMMING A SINGLE WORD OF FLASH PROGRAM MEMORY ('C' LANGUAGE CODE)

// C example using MPLAB C30	
unsigned int offset;	
unsigned long progAddr = 0xXXXXXX;	// Address of word to program
unsigned int progDataL = 0xXXXX;	// Data to program lower word
unsigned char progDataH = 0xXX;	// Data to program upper byte
//Set up NVMCON for word programming	
NVMCON = 0×4003 ;	// Initialize NVMCON
//Set up pointer to the first memory locatio	n to be written
TBLPAG = progAddr>>16;	// Initialize PM Page Boundary SFR
offset = progAddr & 0xFFFF;	// Initialize lower word of address
//Perform TBLWT instructions to write latche	S
<pre>builtin_tblwtl(offset, progDataL);</pre>	// Write to address low word
<pre>builtin_tblwth(offset, progDataH);</pre>	// Write to upper byte
asm("DISI #5");	// Block interrupts with priority <7
	// for next 5 instructions
builtin_write_NVM();	// C30 function to perform unlock
	// sequence and set WR

6.0 RESETS

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 7. "Reset" (DS39712). The information in this data sheet supersedes the information in the FRM.

The Reset module combines all Reset sources and controls the device Master Reset Signal, SYSRST. The following is a list of device Reset sources:

- POR: Power-on Reset
- MCLR: Pin Reset
- SWR: RESET Instruction
- WDT: Watchdog Timer Reset
- BOR: Brown-out Reset
- CM: Configuration Mismatch Reset
- TRAPR: Trap Conflict Reset
- · IOPUWR: Illegal Opcode Reset
- UWR: Uninitialized W Register Reset

A simplified block diagram of the Reset module is shown in Figure 6-1.

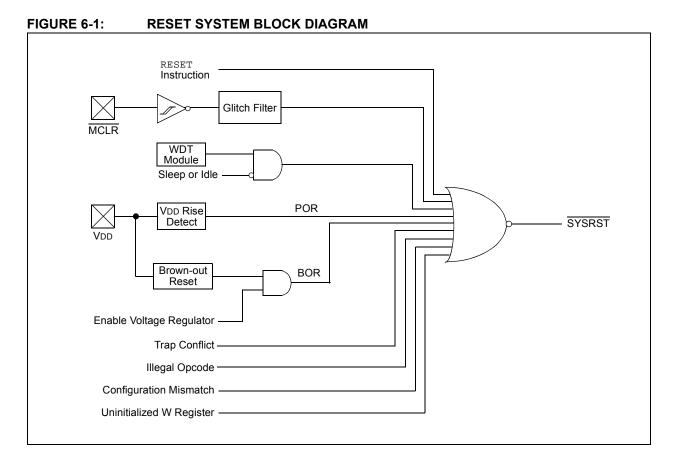
Any active source of Reset will make the SYSRST signal active. Many registers associated with the CPU and peripherals are forced to a known Reset state. Most registers are unaffected by a Reset; their status is unknown on POR and unchanged by all other Resets.

Note: Refer to the specific peripheral or CPU section of this manual for register Reset states.

All types of device Reset will set a corresponding status bit in the RCON register to indicate the type of Reset (see Register 6-1). A POR will clear all bits, except for the BOR and POR (RCON<1:0>) bits, which are set. The user may set or clear any bit at any time during code execution. The RCON bits only serve as status bits. Setting a particular Reset status bit in software will not cause a device Reset to occur.

The RCON register also has other bits associated with the Watchdog Timer and device power-saving states. The function of these bits is discussed in other sections of this data sheet.

Note: The status bits in the RCON register should be cleared after they are read so that the next RCON register value after a device Reset will be meaningful.



REGISTER 6-1:

RCON: RESET CONTROL REGISTER⁽¹⁾

R/W-0. HS R/W-0. HS U-0 U-0 U-0 U-0 R/W-0. HS R/W-0 TRAPR IOPUWR VREGS⁽³⁾ CM bit 15 bit 8 R/W-0, HS R/W-0, HS R/W-0, HS R/W-0, HS R/W-0, HS R/W-0. HS R/W-1, HS R/W-1, HS SWDTEN⁽²⁾ EXTR SWR WDTO SLEEP IDLE BOR POR bit 7 bit 0 Legend: HS = Hardware Settable bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '0' = Bit is cleared '1' = Bit is set x = Bit is unknown bit 15 TRAPR: Trap Reset Flag bit 1 = A Trap Conflict Reset has occurred 0 = A Trap Conflict Reset has not occurred bit 14 IOPUWR: Illegal Opcode or Uninitialized W Access Reset Flag bit 1 = An illegal opcode detection, an illegal address mode or uninitialized W register is used as an Address Pointer and caused a Reset 0 = An illegal opcode or uninitialized W Reset has not occurred bit 13-10 Unimplemented: Read as '0' bit 9 CM: Configuration Word Mismatch Reset Flag bit 1 = A Configuration Word Mismatch Reset has occurred 0 = A Configuration Word Mismatch Reset has not occurred bit 8 VREGS: Voltage Regulator Standby Enable bit⁽³⁾ 1 = Program memory and regulator remain active during Sleep/Idle 0 = Program memory power is removed and regulator goes to standby during Seep/Idle bit 7 EXTR: External Reset (MCLR) Pin bit 1 = A Master Clear (pin) Reset has occurred 0 = A Master Clear (pin) Reset has not occurred bit 6 SWR: Software Reset (Instruction) Flag bit 1 = A RESET instruction has been executed 0 = A RESET instruction has not been executed SWDTEN: Software Enable/Disable of WDT bit⁽²⁾ bit 5 1 = WDT is enabled 0 = WDT is disabled bit 4 WDTO: Watchdog Timer Time-out Flag bit 1 = WDT time-out has occurred 0 = WDT time-out has not occurred bit 3 SLEEP: Wake From Sleep Flag bit 1 = Device has been in Sleep mode 0 = Device has not been in Sleep mode Note 1: All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset. 2: If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting. 3: Re-enabling the regulator after it enters Standby mode will add a delay, TVREG, when waking up from

 Re-enabling the regulator after it enters Standby mode will add a delay, TVREG, when waking up from Sleep. Applications that do not use the voltage regulator should set this bit to prevent this delay from occurring.

REGISTER 6-1: RCON: RESET CONTROL REGISTER⁽¹⁾ (CONTINUED)

- bit 2 **IDLE:** Wake-up From Idle Flag bit
 - 1 = Device has been in Idle mode
 - 0 = Device has not been in Idle mode
- bit 1 BOR: Brown-out Reset Flag bit
 - 1 = A Brown-out Reset has occurred
 Note that BOR is also set after a Power-on Reset.
 0 = A Brown-out Reset has not occurred
- bit 0 **POR:** Power-on Reset Flag bit
 - 1 = A Power-on Reset has occurred
 - 0 = A Power-on Reset has not occurred
- **Note 1:** All of the Reset status bits may be set or cleared in software. Setting one of these bits in software does not cause a device Reset.
 - 2: If the FWDTEN Configuration bit is '1' (unprogrammed), the WDT is always enabled, regardless of the SWDTEN bit setting.
 - **3:** Re-enabling the regulator after it enters Standby mode will add a delay, TVREG, when waking up from Sleep. Applications that do not use the voltage regulator should set this bit to prevent this delay from occurring.

Flag Bit	Setting Event	Clearing Event
TRAPR (RCON<15>)	Trap Conflict Event	POR
IOPUWR (RCON<14>)	Illegal Opcode or Uninitialized W Register Access	POR
CM (RCON<9>)	Configuration Mismatch Reset	POR
EXTR (RCON<7>)	MCLR Reset	POR
SWR (RCON<6>)	RESET Instruction	POR
WDTO (RCON<4>)	WDT Time-out	CLRWDT, PWRSAV Instruction, POR
SLEEP (RCON<3>)	PWRSAV #0 Instruction	POR
IDLE (RCON<2>)	PWRSAV #1 Instruction	POR
BOR (RCON<1>)	POR, BOR	—
POR (RCON<0>)	POR	—

TABLE 6-1: RESET FLAG BIT OPERATION

Note: All Reset flag bits may be set or cleared by the user software.

6.1 Special Function Register Reset States

Most of the Special Function Registers (SFRs) associated with the PIC24F CPU and peripherals are reset to a particular value at a device Reset. The SFRs are grouped by their peripheral or CPU function and their Reset values are specified in each section of this manual.

The Reset value for each SFR does not depend on the type of Reset, with the exception of four registers. The Reset value for the Reset Control register, RCON, will depend on the type of device Reset. The Reset value for the Oscillator Control register, OSCCON, will depend on the type of Reset and the programmed values of the FNOSC bits in Flash Configuration Word 2 (CW2) (see Table 6-2). The RCFGCAL and NVMCON registers are only affected by a POR.

6.2 Device Reset Times

The Reset times for various types of device Reset are summarized in Table 6-3. Note that the system Reset signal, SYSRST, is released after the POR delay time expires.

The time at which the device actually begins to execute code will also depend on the system oscillator delays, which include the Oscillator Start-up Timer (OST) and the PLL lock time. The OST and PLL lock times occur in parallel with the applicable SYSRST delay times.

The Fail-Safe Clock Monitor (FSCM) delay determines the time at which the FSCM begins to monitor the system clock source after the SYSRST signal is released.

6.3 Clock Source Selection at Reset

If clock switching is enabled, the system clock source at device Reset is chosen, as shown in Table 6-2. If clock switching is disabled, the system clock source is always selected according to the oscillator Configuration bits. Refer to the "*PIC24F Family Reference Manual*", **Section 8.0 "Oscillator Configuration**" for further details.

TABLE 6-2:	OSCILLATOR SELECTION vs.
	TYPE OF RESET (CLOCK
	SWITCHING ENABLED)

Reset Type	Clock Source Determinant	
POR	FNOSC Configuration bits	
BOR	(CW2<10:8>)	
MCLR		
WDTO	COSC Control bits (OSCCON<14:12>)	
SWR	(0300014.122)	

Reset Type	Clock Source	SYSRST Delay	System Clock Delay	Notes
POR ⁽⁷⁾	EC	TPOR + TSTARTUP + TRST		1, 2, 3
	ECPLL	TPOR + TSTARTUP + TRST	TLOCK	1, 2, 3, 5
	XT, HS, SOSC	TPOR + TSTARTUP + TRST	Tost	1, 2, 3, 4
	XTPLL, HSPLL	TPOR + TSTARTUP + TRST	Tost + Tlock	1, 2, 3, 4, 5
	FRC, FRCDIV	TPOR + TSTARTUP + TRST	TFRC	1, 2, 3, 6, 7
	FRCPLL	TPOR + TSTARTUP + TRST	TFRC + TLOCK	1, 2, 3, 5, 6
	LPRC	TPOR + TSTARTUP + TRST	TLPRC	1, 2, 3, 6
BOR	EC	TSTARTUP + TRST	—	2, 3
	ECPLL	TSTARTUP + TRST	TLOCK	2, 3, 5
	XT, HS, SOSC	TSTARTUP + TRST	Tost	2, 3, 4
	XTPLL, HSPLL	TSTARTUP + TRST	Tost + Tlock	2, 3, 4, 5
	FRC, FRCDIV	TSTARTUP + TRST	TFRC	2, 3, 6, 7
	FRCPLL	TSTARTUP + TRST	TFRC + TLOCK	2, 3, 5, 6
	LPRC	TSTARTUP + TRST	TLPRC	2, 3, 6
MCLR	Any Clock	Trst	_	3
WDT	Any Clock	Trst		3
Software	Any clock	Trst	—	3
Illegal Opcode	Any Clock	Trst	—	3
Uninitialized W	Any Clock	Trst		3
Trap Conflict	Any Clock	Trst		3

TABLE 6-3: RESET DELAY TIMES FOR VARIOUS DEVICE RESETS

Note 1: TPOR = Power-on Reset delay (10 μ s nominal).

2: TSTARTUP = TVREG (10 μs nominal when VREGS = 1 and when VREGS = 0; depends upon WUTSEL<1:0> bits setting).

- 3: TRST = Internal State Reset time (32 μs nominal).
- **4:** Tos⊤ = Oscillator Start-up Timer. A 10-bit counter counts 1024 oscillator periods before releasing the oscillator clock to the system.
- **5:** TLOCK = PLL lock time.
- 6: TFRC and TLPRC = RC Oscillator start-up times.
- 7: If Two-speed Start-up is enabled, regardless of the primary oscillator selected, the device starts with FRC so the system clock delay is just TFRC, and in such cases, FRC start-up time is valid. It switches to the primary oscillator after its respective clock delay.

6.3.1 POR AND LONG OSCILLATOR START-UP TIMES

The oscillator start-up circuitry and its associated delay timers are not linked to the device Reset delays that occur at power-up. Some crystal circuits (especially low-frequency crystals) will have a relatively long start-up time. Therefore, one or more of the following conditions is possible after SYSRST is released:

- The oscillator circuit has not begun to oscillate.
- The Oscillator Start-up Timer has not expired (if a crystal oscillator is used).
- The PLL has not achieved a lock (if PLL is used).

The device will not begin to execute code until a valid clock source has been released to the system. Therefore, the oscillator and PLL start-up delays must be considered when the Reset delay time must be known.

6.3.2 FAIL-SAFE CLOCK MONITOR (FSCM) AND DEVICE RESETS

If the FSCM is enabled, it will begin to monitor the system clock source when SYSRST is released. If a valid clock source is not available at this time, the device will automatically switch to the FRC oscillator and the user can switch to the desired crystal oscillator in the Trap Service Routine (TSR).

NOTES:

7.0 INTERRUPT CONTROLLER

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 8. "Interrupts" (DS39707). The information in this data sheet supersedes the information in the FRM.

The PIC24F interrupt controller reduces the numerous peripheral interrupt request signals to a single interrupt request signal to the PIC24F CPU. It has the following features:

- Up to 8 processor exceptions and software traps
- · Seven user-selectable priority levels
- Interrupt Vector Table (IVT) with up to 118 vectors
- Unique vector for each interrupt or exception source
- Fixed priority within a specified user priority level
- Alternate Interrupt Vector Table (AIVT) for debug support
- Fixed interrupt entry and return latencies

7.1 Interrupt Vector Table

The Interrupt Vector Table (IVT) is shown in Figure 7-1. The IVT resides in program memory, starting at location 000004h. The IVT contains 126 vectors, consisting of 8 non-maskable trap vectors, plus up to 118 sources of interrupt. In general, each interrupt source has its own vector. Each interrupt vector contains a 24-bit wide address. The value programmed into each interrupt vector location is the starting address of the associated Interrupt Service Routine (ISR).

Interrupt vectors are prioritized in terms of their natural priority; this is linked to their position in the vector table. All other things being equal, lower addresses have a higher natural priority. For example, the interrupt associated with Vector 0 will take priority over interrupts at any other vector address.

PIC24FJ256DA210 family devices implement non-maskable traps and unique interrupts. These are summarized in Table 7-1 and Table 7-2.

7.1.1 ALTERNATE INTERRUPT VECTOR TABLE

The Alternate Interrupt Vector Table (AIVT) is located after the IVT, as shown in Figure 7-1. The ALTIVT (INTCON2<15>) control bit provides access to the AIVT. If the ALTIVT bit is set, all interrupt and exception processes will use the alternate vectors instead of the default vectors. The alternate vectors are organized in the same manner as the default vectors.

The AIVT supports emulation and debugging efforts by providing a means to switch between an application and a support environment without requiring the interrupt vectors to be reprogrammed. This feature also enables switching between applications for evaluation of different software algorithms at run time. If the AIVT is not needed, the AIVT should be programmed with the same addresses used in the IVT.

7.2 Reset Sequence

A device Reset is not a true exception because the interrupt controller is not involved in the Reset process. The PIC24F devices clear their registers in response to a Reset, which forces the PC to zero. The micro-controller then begins program execution at location, 000000h. The user programs a GOTO instruction at the Reset address, which redirects program execution to the appropriate start-up routine.

Note: Any unimplemented or unused vector locations in the IVT and AIVT should be programmed with the address of a default interrupt handler routine that contains a RESET instruction.

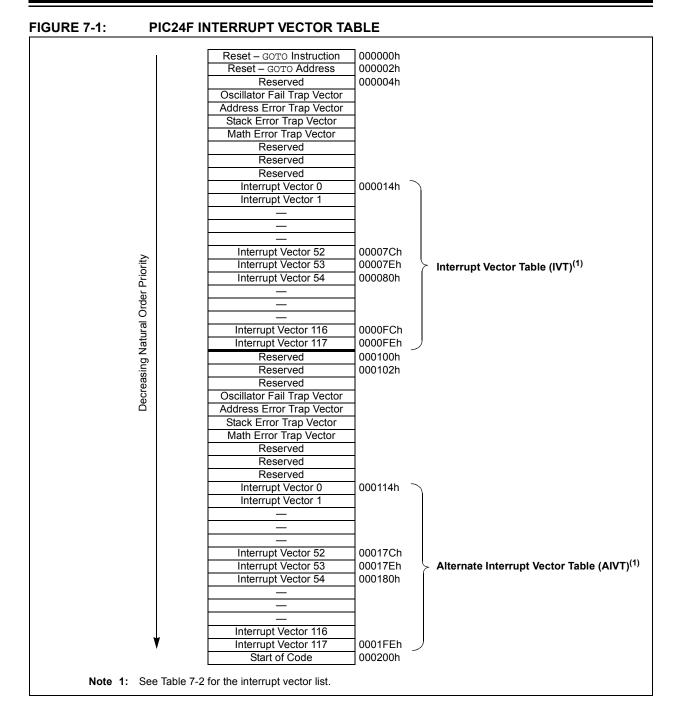


TABLE 7-1: TRAP VECTOR DETAILS

Vector Number	IVT Address	AIVT Address	Trap Source
0	000004h	000104h	Reserved
1	000006h	000106h	Oscillator Failure
2	000008h	000108h	Address Error
3	00000Ah	00010Ah	Stack Error
4	00000Ch	00010Ch	Math Error
5	00000Eh	00010Eh	Reserved
6	000010h	000110h	Reserved
7	000012h	000112h	Reserved

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Interrupt Source	Vector	IVT	ΑΙΥΤ	Inte	errupt Bit Locat	ions
Interrupt Source	Number	Address	Address	Flag	Enable	Priority
ADC1 Conversion Done	13	00002Eh	00012Eh	IFS0<13>	IEC0<13>	IPC3<6:4>
Comparator Event	18	000038h	000138h	IFS1<2>	IEC1<2>	IPC4<10:8>
CRC Generator	67	00009Ah	00019Ah	IFS4<3>	IEC4<3>	IPC16<14:12>
CTMU Event	77	0000AEh	0001AEh	IFS4<13>	IEC4<13>	IPC19<6:4>
External Interrupt 0	0	000014h	000114h	IFS0<0>	IEC0<0>	IPC0<2:0>
External Interrupt 1	20	00003Ch	00013Ch	IFS1<4>	IEC1<4>	IPC5<2:0>
External Interrupt 2	29	00004Eh	00014Eh	IFS1<13>	IEC1<13>	IPC7<6:4>
External Interrupt 3	53	00007Eh	00017Eh	IFS3<5>	IEC3<5>	IPC13<6:4>
External Interrupt 4	54	000080h	000180h	IFS3<6>	IEC3<6>	IPC13<10:8>
Graphics Controller	100	0000DCh	0001DCh	IFS6<4>	IEC6<4>	IPC25<2:0>
I2C1 Master Event	17	000036h	000136h	IFS1<1>	IEC1<1>	IPC4<6:4>
I2C1 Slave Event	16	000034h	000134h	IFS1<0>	IEC1<0>	IPC4<2:0>
I2C2 Master Event	50	000078h	000178h	IFS3<2>	IEC3<2>	IPC12<10:8>
I2C2 Slave Event	49	000076h	000176h	IFS3<1>	IEC3<1>	IPC12<6:4>
I2C3 Master Event	85	0000BEh	0001BEh	IFS5<5>	IEC5<5>	IPC21<6:4>
I2C3 Slave Event	84	0000BCh	0001BCh	IFS5<4>	IEC5<4>	IPC21<2:0>
Input Capture 1	1	000016h	000116h	IFS0<1>	IEC0<1>	IPC0<6:4>
Input Capture 2	5	00001Eh	00011Eh	IFS0<5>	IEC0<5>	IPC1<6:4>
Input Capture 3	37	00005Eh	00015Eh	IFS2<5>	IEC2<5>	IPC9<6:4>
Input Capture 4	38	000060h	000160h	IFS2<6>	IEC2<6>	IPC9<10:8>
Input Capture 5	39	000062h	000162h	IFS2<7>	IEC2<7>	IPC9<14:12>
Input Capture 6	40	000064h	000164h	IFS2<8>	IEC2<8>	IPC10<2:0>
Input Capture 7	22	000040h	000140h	IFS1<6>	IEC1<6>	IPC5<10:8>
Input Capture 8	23	000042h	000142h	IFS1<7>	IEC1<7>	IPC5<14:12>
Input Capture 9	93	0000CEh	0001CEh	IFS5<13>	IEC5<13>	IPC23<6:4>
Input Change Notification (ICN)	19	00003Ah	00013Ah	IFS1<3>	IEC1<3>	IPC4<14:12>
Low-Voltage Detect (LVD)	72	0000A4h	0001A4h	IFS4<8>	IEC4<8>	IPC18<2:0>
Output Compare 1	2	000018h	000118h	IFS0<2>	IEC0<2>	IPC0<10:8>
Output Compare 2	6	000020h	000120h	IFS0<6>	IEC0<6>	IPC1<10:8>
Output Compare 3	25	000046h	000146h	IFS1<9>	IEC1<9>	IPC6<6:4>
Output Compare 4	26	000048h	000148h	IFS1<10>	IEC1<10>	IPC6<10:8>
Output Compare 5	41	000066h	000166h	IFS2<9>	IEC2<9>	IPC10<6:4>
Output Compare 6 Output Compare 7	42	000068h	000168h	IFS2<10> IFS2<11>	IEC2<10>	IPC10<10:8>
Output Compare 8	43	00006Ah	00016Ah		IEC2<11>	IPC10<14:12>
Output Compare 9	44 92	00006Ch 0000CCh	00016Ch 0001CCh	IFS2<12> IFS5<12>	IEC2<12> IEC5<12>	IPC11<2:0> IPC23<2:0>
Enhanced Parallel Master Port (EPMP) ⁽¹⁾	45	0000CCh 00006Eh	0001CCH	IFS3<12>	IEC3<12>	IPC23<2.0>
			00018En	IFS2<13> IFS3<14>		-
Real-Time Clock and Calendar (RTCC)	62 9	000090h 000026h	000190h 000126h	IFS3<14> IFS0<9>	IEC3<14> IEC0<9>	IPC15<10:8> IPC2<6:4>
SPI1 Error SPI1 Event	9 10	000028h	000128h	IFS0<9>	IEC0<9>	IPC2<0.4>
SPI1 Event	32	000028h	000128h	IFS0<10>	IEC0<10>	IPC2<10.8>
SPI2 Error	32	000054h 000056h	000154h 000156h	IFS2<0> IFS2<1>	IEC2<0>	IPC8<2:0>
SPI2 Event	90	000056h	000156h	IFS2<1> IFS5<10>	IEC5<10>	IPC6<6.4>
SPI3 Event	90 91	0000C8h	0001C8h	IFS5<10>	IEC5<10>	IPC22<10.8>
SFIS EVENIL	91		UUUICAN	11-305112		15022514:12>

TABLE 7-2: IMPLEMENTED INTERRUPT VECTORS

Note 1: Not available in 64-pin devices (PIC24FJXXXDAX06).

 $[\]ensuremath{\textcircled{}^{\odot}}$ 2010 Microchip Technology Inc.

	Vector Number	IVT Address	AIVT	Interrupt Bit Locations			
Interrupt Source			Address	Flag	Enable	Priority	
Timer1	3	00001Ah	00011Ah	IFS0<3>	IEC0<3>	IPC0<14:12>	
Timer2	7	000022h	000122h	IFS0<7>	IEC0<7>	IPC1<14:12>	
Timer3	8	000024h	000124h	IFS0<8>	IEC0<8>	IPC2<2:0>	
Timer4	27	00004Ah	00014Ah	IFS1<11>	IEC1<11>	IPC6<14:12>	
Timer5	28	00004Ch	00014Ch	IFS1<12>	IEC1<12>	IPC7<2:0>	
UART1 Error	65	000096h	000196h	IFS4<1>	IEC4<1>	IPC16<6:4>	
UART1 Receiver	11	00002Ah	00012Ah	IFS0<11>	IEC0<11>	IPC2<14:12>	
UART1 Transmitter	12	00002Ch	00012Ch	IFS0<12>	IEC0<12>	IPC3<2:0>	
UART2 Error	66	000098h	000198h	IFS4<2>	IEC4<2>	IPC16<10:8>	
UART2 Receiver	30	000050h	000150h	IFS1<14>	IEC1<14>	IPC7<10:8>	
UART2 Transmitter	31	000052h	000152h	IFS1<15>	IEC1<15>	IPC7<14:12>	
UART3 Error	81	0000B6h	0001B6h	IFS5<1>	IEC5<1>	IPC20<6:4>	
UART3 Receiver	82	0000B8h	0001B8h	IFS5<2>	IEC5<2>	IPC20<10:8>	
UART3 Transmitter	83	0000BAh	0001BAh	IFS5<3>	IEC5<3>	IPC20<14:12>	
UART4 Error	87	0000C2h	0001C2h	IFS5<7>	IEC5<7>	IPC21<14:12>	
UART4 Receiver	88	0000C4h	0001C4h	IFS5<8>	IEC5<8>	IPC22<2:0>	
UART4 Transmitter	89	0000C6h	0001C6h	IFS5<9>	IEC5<9>	IPC22<6:4>	
USB Interrupt	86	0000C0h	0001C0h	IFS5<6>	IEC5<6>	IPC21<10:8>	

TABLE 7-2: IMPLEMENTED INTERRUPT VECTORS (CONTINUED)

Note 1: Not available in 64-pin devices (PIC24FJXXXDAX06).

7.3 Interrupt Control and Status Registers

The PIC24FJ256DA210 family of devices implements a total of 40 registers for the interrupt controller:

- INTCON1
- INTCON2
- IFS0 through IFS6
- IEC0 through IEC6
- IPC0 through IPC25 (except IPC14, IPC17 and IPC24)
- INTTREG

Global interrupt control functions are controlled from INTCON1 and INTCON2. INTCON1 contains the Interrupt Nesting Disable (NSTDIS) bit, as well as the control and status flags for the processor trap sources. The INTCON2 register controls the external interrupt request signal behavior and the use of the Alternate Interrupt Vector Table (AIVT).

The IFSx registers maintain all of the interrupt request flags. Each source of interrupt has a status bit, which is set by the respective peripherals or an external signal and is cleared via software.

The IECx registers maintain all of the interrupt enable bits. These control bits are used to individually enable interrupts from the peripherals or external signals. The IPCx registers are used to set the interrupt priority level for each source of interrupt. Each user interrupt source can be assigned to one of eight priority levels.

The INTTREG register contains the associated interrupt vector number and the new CPU interrupt priority level, which are latched into the Vector Number (VECNUM<6:0>) and the Interrupt Level (ILR<3:0>) bit fields in the INTTREG register. The new interrupt priority level is the priority of the pending interrupt.

The interrupt sources are assigned to the IFSx, IECx and IPCx registers in the order of their vector numbers, as shown in Table 7-2. For example, the INT0 (External Interrupt 0) is shown as having a vector number and a natural order priority of 0. Thus, the INT0IF status bit is found in IFS0<0>, the INT0IE enable bit in IEC0<0> and the INT0IP<2:0> priority bits in the first position of IPC0 (IPC0<2:0>).

Although they are not specifically part of the interrupt control hardware, two of the CPU Control registers contain bits that control interrupt functionality. The ALU STATUS register (SR) contains the IPL<2:0> bits (SR<7:5>). These indicate the current CPU interrupt priority level. The user can change the current CPU priority level by writing to the IPL bits. The CORCON register contains the IPL3 bit, which, together with IPL<2:0>, indicates the current CPU priority level. IPL3 is a read-only bit so that trap events cannot be masked by the user software.

The interrupt controller has the Interrupt Controller Test register, INTTREG, which displays the status of the interrupt controller. When an interrupt request occurs, it's associated vector number and the new interrupt priority level are latched into INTTREG. This information can be used to determine a specific interrupt source if a generic ISR is used for multiple vectors (such as when ISR remapping is used in bootloader applications) or to check if another interrupt is pending while in an ISR.

All interrupt registers are described in Register 7-1 through Register 7-40 in the succeeding pages.

REGISTER 7-1: SR: ALU STATUS REGISTER (IN CPU)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R-0, HSC
—	—	—	—	_	—	—	DC ⁽¹⁾
bit 15							bit 8

R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC
IPL2 ^(2,3)	IPL1 ^(2,3)	IPL0 ^(2,3)	RA ⁽¹⁾	N ⁽¹⁾	0V ⁽¹⁾	Z ⁽¹⁾	C ⁽¹⁾
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-9 Unimplemented: Read as '0'

bit 7-5	IPL<2:0>: CPU Interrupt Priority Level Status bits ^(2,3)
	111 = CPU interrupt priority level is 7 (15); user interrupts are disabled
	110 = CPU interrupt priority level is 6 (14)
	101 = CPU interrupt priority level is 5 (13)
	100 = CPU interrupt priority level is 4 (12)
	011 = CPU interrupt priority level is 3 (11)
	010 = CPU interrupt priority level is 2 (10)
	001 = CPU interrupt priority level is 1 (9)
	000 = CPU interrupt priority level is 0 (8)
Note 1:	See Register 3-1 for the description of the remaining bits (bit 8, 4, 3, 2, 1 and 0)

- **Note 1:** See Register 3-1 for the description of the remaining bits (bit 8, 4, 3, 2, 1 and 0) that are not dedicated to interrupt control functions.
 - **2:** The IPL bits are concatenated with the IPL3 (CORCON<3>) bit to form the CPU interrupt priority level. The value in parentheses indicates the interrupt priority level if IPL3 = 1.
 - **3:** The IPL Status bits are read-only when NSTDIS (INTCON1<15>) = 1.

REGISTER 7-2: CORCON: CPU CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	_	—	_	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R/C-0, HSC	r-1	U-0	U-0
—	—	_	—	IPL3 ⁽¹⁾	r	—	—
bit 7							bit 0

Legend:	r = Reserved bit	C = Clearable bit	HSC = Hardware Settable/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ad as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-4 Unimplemented: Read as '0'

- bit 3 IPL3: CPU Interrupt Priority Level Status bit⁽¹⁾
 - 1 = CPU interrupt priority level is greater than 7
 - 0 = CPU interrupt priority level is 7 or less
- bit 2 Reserved: Read as '1'
- bit 1-0 Unimplemented: Read as '0'
- **Note 1:** The IPL3 bit is concatenated with the IPL<2:0> bits (SR<7:5>) to form the CPU interrupt priority level; see Register 3-2 for bit description.

REGISTER 7-3: INTCON1: INTERRUPT CONTROL REGISTER 1

R/W-0	U-0						
NSTDIS	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0
—	—	—	MATHERR	ADDRERR	STKERR	OSCFAIL	—
bit 7							bit 0

Legend:		HS = Hardware Settabl	e bit	
R = Readable	e bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR		'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown
bit 15	NSTDIS: I	nterrupt Nesting Disable bit		
	1 = Interru	upt nesting is disabled		

	0 = Interrupt nesting is enabled
bit 14-5	Unimplemented: Read as '0'
bit 4	MATHERR: Arithmetic Error Trap Status bit
	1 = Overflow trap has occurred0 = Overflow trap has not occurred
bit 3	ADDRERR: Address Error Trap Status bit
	1 = Address error trap has occurred
	0 = Address error trap has not occurred
bit 2	STKERR: Stack Error Trap Status bit
	1 = Stack error trap has occurred
	0 = Stack error trap has not occurred
bit 1	OSCFAIL: Oscillator Failure Trap Status bit
	1 = Oscillator failure trap has occurred0 = Oscillator failure trap has not occurred
bit 0	Unimplemented: Read as '0'

R/W-0	R-0, HSC	U-0	U-0	U-0	U-0	U-0	U-0
ALTIVT	DISI	_	_	_	_	_	—
bit 15	-			- -		-	bit 8
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	— — INT4EP INT3EP INT2EP INT1EP INT0						
bit 7							bit 0
Legend:		HSC = Hardv	/are Settable/C	learable bit			
R = Readable	e bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	ıown
bit 15			terrupt Vector -	Table bit			
		nate Interrupt					
h:+ 4 4		dard (default)					
bit 14		struction Statu					
		truction is not a	-				
bit 13-5	Unimplemen	ted: Read as '	0'				
bit 4	INT4EP: Exte	ernal Interrupt 4	Edge Detect F	Polarity Select b	bit		
	1 = Interrupt	on negative ec	lge				
	0 = Interrupt	on positive ed	ge				
bit 3		-	-	Polarity Select b	bit		
		on negative ec	0				
L:1 0	•	on positive ed			.:.		
bit 2		•	•	Polarity Select b	DIT		
		on negative ed					
bit 1	 0 = Interrupt on positive edge INT1EP: External Interrupt 1 Edge Detect Polarity Select bit 						
	1 = Interrupt on negative edge						
		on positive ed					
bit 0	INT0EP: Exte	ernal Interrupt () Edge Detect F	Polarity Select b	bit		
		on negative eq	0				
	0 = Interrupt	on positive ed	ge				

REGISTER 7-4: INTCON2: INTERRUPT CONTROL REGISTER 2

REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0

U-0	U-0	R/W-0, HS					
—	—	AD1IF	U1TXIF	U1RXIF	SPI1IF	SPF1IF	T3IF
bit 15							bit 8

R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS
T2IF	OC2IF	IC2IF	—	T1IF	OC1IF	IC1IF	INTOIF
bit 7							bit 0

Legend:		HS = Hardware Settabl	le bit						
R = Readab	ole bit	W = Writable bit	U = Unimplemented bit	, read as '0'					
-n = Value a	at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown					
bit 15-14	-	mented: Read as '0'							
bit 13		/D Conversion Complete Inte	errupt Flag Status bit						
		upt request has occurred upt request has not occurred	4						
bit 12		JART1 Transmitter Interrupt							
		upt request has occurred	T lag Olatus bit						
		upt request has not occurred	d						
bit 11	U1RXIF:	UART1 Receiver Interrupt FI	ag Status bit						
		upt request has occurred							
		upt request has not occurred							
bit 10		PI1 Event Interrupt Flag Stat	tus bit						
		upt request has occurred	4						
bit 9		upt request has not occurred SPI1 Fault Interrupt Flag Stat							
DIL 9		upt request has occurred							
		upt request has not occurred	d						
bit 8	T3IF: Tim	er3 Interrupt Flag Status bit							
	1 = Interru	upt request has occurred							
	0 = Interru	upt request has not occurred							
bit 7		er2 Interrupt Flag Status bit							
		 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 							
bit 6		utput Compare Channel 2 In							
		upt request has occurred	iterrupt riag Status bit						
		upt request has not occurred	l						
bit 5	IC2IF: Inp	out Capture Channel 2 Interro	upt Flag Status bit						
	1 = Interr	upt request has occurred							
	0 = Interr	upt request has not occurred	d						
bit 4	Unimpler	nented: Read as '0'							
bit 3		er1 Interrupt Flag Status bit							
		rupt request has occurred	4						
hit 0		rupt request has not occurred							
bit 2		utput Compare Channel 1 In upt request has occurred	iterrupt Flag Status bit						
		upt request has not occurred	d						

REGISTER 7-5: IFS0: INTERRUPT FLAG STATUS REGISTER 0 (CONTINUED)

bit 1	IC1IF: Input Capture Channel 1 Interrupt Flag Status bit
	 Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 0	INT0IF: External Interrupt 0 Flag Status bit
	1 = Interrupt request has occurred

0 = Interrupt request has not occurred

REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1

R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0			
U2TXIF	U2RXIF	INT2IF	T5IF	T4IF	OC4IF	OC3IF				
bit 15							bit 8			
R/W-0, HS	R/W-0, HS	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS			
IC8IF	IC7IF		INT1IF	CNIF	CMIF	MI2C1IF	SI2C1IF			
bit 7							bit 0			
Legend:		HS = Hardwa	re Settable bit							
R = Readable	bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'				
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown			
bit 15	U2TXIF: UAR	T2 Transmitter	Interrupt Flag	Status bit						
		request has oc								
		request has no								
bit 14		KIF: UART2 Receiver Interrupt Flag Status bit								
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 									
bit 13	-	•								
bit 10	INT2IF: External Interrupt 2 Flag Status bit 1 = Interrupt request has occurred									
	0 = Interrupt request has not occurred									
bit 12	T5IF: Timer5 Interrupt Flag Status bit									
	1 = Interrupt request has occurred									
	0 = Interrupt	request has no	t occurred							
bit 11	T4IF: Timer4 Interrupt Flag Status bit									
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 									
h# 40	-	•			- :4					
bit 10	OC4IF: Output Compare Channel 4 Interrupt Flag Status bit									
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 									
bit 9	OC3IF: Output Compare Channel 3 Interrupt Flag Status bit									
	1 = Interrupt request has occurred									
	0 = Interrupt	request has no	t occurred							
bit 8	Unimplemen	ted: Read as ')'							
bit 7	IC8IF: Input C	Capture Channe	el 8 Interrupt Fl	ag Status bit						
		request has oc								
	-	request has no								
bit 6		Capture Channe	-	ag Status bit						
		request has oc								
		request has no	loccurred							

REGISTER 7-6: IFS1: INTERRUPT FLAG STATUS REGISTER 1 (CONTINUED)

bit 5	Unimplemented: Read as '0'
bit 4	INT1IF: External Interrupt 1 Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 3	CNIF: Input Change Notification Interrupt Flag Status bit
	1 = Interrupt request has occurred0 = Interrupt request has not occurred
bit 2	CMIF: Comparator Interrupt Flag Status bit
	1 = Interrupt request has occurred0 = Interrupt request has not occurred
bit 1	MI2C1IF: Master I2C1 Event Interrupt Flag Status bit
	1 = Interrupt request has occurred0 = Interrupt request has not occurred
bit 0	SI2C1IF: Slave I2C1 Event Interrupt Flag Status bit
	1 = Interrupt request has occurred0 = Interrupt request has not occurred

REGISTER 7-7: IFS2: INTERRUPT FLAG STATUS REGISTER 2

U-0	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS
—	—	PMPIF ⁽¹⁾	OC8IF	OC7IF	OC6IF	OC5IF	IC6IF
bit 15							bit 8

R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0	U-0	U-0	R/W-0, HS	R/W-0, HS
IC5IF	IC4IF	IC3IF	—	—	—	SPI2IF	SPF2IF
bit 7							bit 0

Legend:	HS = Hardware Settable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13	PMPIF: Parallel Master Port Interrupt Flag Status bit ⁽¹⁾
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 12	OC8IF: Output Compare Channel 8 Interrupt Flag Status bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 11	OC7IF: Output Compare Channel 7 Interrupt Flag Status bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 10	OC6IF: Output Compare Channel 6 Interrupt Flag Status bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
bit 9	OC5IF: Output Compare Channel 5 Interrupt Flag Status bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred
Note 1:	Not available in PIC24FJXXXDAX06 devices.

REGISTER 7-7: IFS2: INTERRUPT FLAG STATUS REGISTER 2 (CONTINUED)

bit 8	IC6IF: Input Capture Channel 6 Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 7	IC5IF: Input Capture Channel 5 Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 6	IC4IF: Input Capture Channel 4 Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 5	IC3IF: Input Capture Channel 3 Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 4-2	Unimplemented: Read as '0'
bit 1	 SPI2IF: SPI2 Event Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
bit 0	 SPF2IF: SPI2 Fault Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred

Note 1: Not available in PIC24FJXXXDAX06 devices.

REGISTER 7-8: IFS3: INTERRUPT FLAG STATUS REGISTER 3

U-0	R/W-0, HS	U-0	U-0	U-0	U-0	U-0	U-0
—	RTCIF	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-0, HS	R/W-0, HS	U-0	U-0	R/W-0, HS	R/W-0, HS	U-0
—	INT4IF	INT3IF	—	—	MI2C2IF	SI2C2IF	—
bit 7							bit 0

Legend:	HS = Hardware Settable b	pit	
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 14 RTCIF: Real-Time Clock/Calendar Interrupt Flag Status	hit
	υn
1 = Interrupt request has occurred	
0 = Interrupt request has not occurred	
bit 13-7 Unimplemented: Read as '0'	
bit 6 INT4IF: External Interrupt 4 Flag Status bit	
1 = Interrupt request has occurred	
0 = Interrupt request has not occurred	
bit 5 INT3IF: External Interrupt 3 Flag Status bit	
1 = Interrupt request has occurred	
0 = Interrupt request has not occurred	
bit 4-3 Unimplemented: Read as '0'	
bit 2 MI2C2IF: Master I2C2 Event Interrupt Flag Status bit	
1 = Interrupt request has occurred	
0 = Interrupt request has not occurred	
bit 1 SI2C2IF: Slave I2C2 Event Interrupt Flag Status bit	
1 = Interrupt request has occurred	
0 = Interrupt request has not occurred	
bit 0 Unimplemented: Read as '0'	

U-0	U-0	R/W-0, HS	U-0	U-0	U-0	U-0	R/W-0, HS			
_	—	CTMUIF	_	—	—	—	LVDIF			
bit 15							bit 8			
U-0	U-0	U-0	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0			
—	—	—		CRCIF	U2ERIF	U1ERIF	—			
bit 7							bit C			
Legend:		HS = Hardware								
R = Readat		W = Writable b	it		nented bit, read					
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown			
			,							
bit 15-14	•	nted: Read as '0								
bit 13		MU Interrupt Fla	•							
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 									
bit 12-9	-	nted: Read as '0'								
bit 8	•	Voltage Detect In		Status bit						
		1 = Interrupt request has occurred								
	0 = Interrupt request has not occurred									
bit 7-4	Unimplemer	nted: Read as '0	,							
bit 3	CRCIF: CRC	Generator Inter	rupt Flag Stat	us bit						
1 = Interrupt request has occurred										
	•	t request has not								
bit 2		RT2 Error Interru		s bit						
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 									
bit 1	•	•		, hit						
DILI		RT1 Error Interru t request has occ		S DIL						
		t request has not								
bit 0	•	nted: Read as '0'								

REGISTER 7-9: IFS4: INTERRUPT FLAG STATUS REGISTER 4

REGISTER 7-10: IFS5: INTERRUPT FLAG STATUS REGISTER 5

U-0	U-0	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS		
—	—	IC9IF	OC9IF	SPI3IF	SPF3IF	U4TXIF	U4RXIF		
bit 15							bit 8		
R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	U-0		
U4ERIF	USB1IF	MI2C3IF	SI2C3IF	U3TXIF	U3RXIF	U3ERIF			
bit 7							bit 0		
1									
Legend:	- h:4	HS = Hardwa W = Writable			anted bit was				
R = Readable bit -n = Value at POR		'1' = Bit is set		U = Unimplemented bit, read as '0' '0' = Bit is cleared x = Bit is unknown			0.000		
	FUK				areu		IOWIT		
bit 15-14	Unimplemen	ted: Read as ')'						
bit 13	Unimplemented: Read as '0' IC9IF: Input Capture Channel 9 Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
	0 = Interrupt request has not occurred								
bit 12	•	ut Compare Ch		pt Flag Status b	bit				
	1 = Interrupt request has occurred								
1.11.4.4	0 = Interrupt request has not occurred								
bit 11	SPI3IF: SPI3 Event Interrupt Flag Status bit								
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 								
bit 10	SPF3IF: SPI3 Fault Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
	0 = Interrupt request has not occurred								
bit 9	U4TXIF: UART4 Transmitter Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
bit 8	 Interrupt request has not occurred U4RXIF: UART4 Receiver Interrupt Flag Status bit 								
DIL O	1 = Interrupt request has occurred								
	0 = Interrupt request has occurred								
bit 7	U4ERIF: UART4 Error Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
	0 = Interrupt request has not occurred								
bit 6	USB1IF: USB1 (USB OTG) Interrupt Flag Status bit								
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 								
bit 5	MI2C3IF: Master I2C3 Event Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
	0 = Interrupt request has not occurred								
bit 4	SI2C3IF: Slave I2C3 Event Interrupt Flag Status bit								
	1 = Interrupt request has occurred								
bit 3	0 = Interrupt request has not occurred								
	U3TXIF: UART3 Transmitter Interrupt Flag Status bit								
	 1 = Interrupt request has occurred 0 = Interrupt request has not occurred 								
bit 2	-	RT3 Receiver Ir		atus bit					
–		request has oc							
		request has no							

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REGISTER 7-10: IFS5: INTERRUPT FLAG STATUS REGISTER 5 (CONTINUED)

- bit 1 U3ERIF: UART3 Error Interrupt Flag Status bit 1 = Interrupt request has occurred 0 = Interrupt request has not occurred
- bit 0 Unimplemented: Read as '0'

REGISTER 7-11: IFS6: INTERRUPT FLAG STATUS REGISTER 6

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	R/W-0, HS	U-0	U-0	U-0	U-0
	—	—	GFX1IF		—	—	—
bit 7							bit 0
Legend:	HS = Hardware Settable bit						

Legend:	HS = Hardware Settable bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-5 Unimplemented: Read as '0'

bit 4	GFX1IF: Graphics 1 Interrupt Flag Status bit
	1 = Interrupt request has occurred
	0 = Interrupt request has not occurred

bit 3-0 Unimplemented: Read as '0'

REGISTER 7-12: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
_	_	AD1IE	U1TXIE	U1RXIE	SPI1IE	SPF1IE	T3IE				
oit 15							bit a				
R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0				
T2IE	OC2IE	IC2IE	_	T1IE	OC1IE	IC1IE	INTOIE				
pit 7	002iL	10212			00112	IGHE	bit				
_egend:											
R = Readabl	e bit	W = Writable	bit	U = Unimplen	nented bit, read	d as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkn	own				
bit 15-14	-	nted: Read as '									
bit 13		Conversion Con	•	t Enable bit							
		request is enab request is not e									
bit 12	•	•		ole hit							
		U1TXIE: UART1 Transmitter Interrupt Enable bit 1 = Interrupt request is enabled									
		request is not e									
oit 11	U1RXIE: UART1 Receiver Interrupt Enable bit										
	1 = Interrupt request is enabled										
	0 = Interrupt	request is not e	enabled								
bit 10	SPI1IE: SPI1 Transfer Complete Interrupt Enable bit										
	1 = Interrupt request is enabled										
	•	request is not e									
bit 9		1 Fault Interrup									
		request is enable request is not									
bit 8	•	0 = Interrupt request is not enabled									
	T3IE: Timer3 Interrupt Enable bit 1 = Interrupt request is enabled										
	0 = Interrupt request is enabled										
bit 7		T2IE: Timer2 Interrupt Enable bit									
	1 = Interrupt request is enabled										
	0 = Interrupt request is not enabled										
bit 6	OC2IE: Outp	ut Compare Ch	annel 2 Interru	pt Enable bit							
	1 = Interrupt request is enabled										
	-	0 = Interrupt request is not enabled									
bit 5	IC2IE: Input Capture Channel 2 Interrupt Enable bit										
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled 										
bit 4		nted: Read as '									
oit 3	-	Interrupt Enabl									
		request is enal									
	•	request is not e									
bit 2	OC1IE: Outp	ut Compare Ch	annel 1 Interru	pt Enable bit							
	•	request is enab									
	a 1.1	request is not e									

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REGISTER 7-12: IEC0: INTERRUPT ENABLE CONTROL REGISTER 0 (CONTINUED)

bit

bit 1	IC1IE: Input Capture Channel 1 Interrupt Enable
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 0	INTOIE: External Interrupt 0 Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled

REGISTER 7-13: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0					
U2TXIE	U2RXIE	INT2IE ⁽¹⁾	T5IE	T4IE	OC4IE	OC3IE						
bit 15							bit 8					
R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
IC8IE	IC7IE	—	INT1IE ⁽¹⁾	CNIE	CMIE	MI2C1IE	SI2C1IE					
bit 7							bit 0					
Legend:												
R = Readabl	e hit	W = Writable	hit	II – Unimplen	nented bit, rea	d as 'O'						
-n = Value at		'1' = Bit is set	UIL	'0' = Bit is cle		x = Bit is unkr						
	FOR	I – Dit is set			aleu		IOWIT					
bit 15		RT2 Transmitter	Interrunt Enal	ole hit								
		request is enab	•									
	0 = Interrupt request is not enabled											
bit 14	U2RXIE: UART2 Receiver Interrupt Enable bit											
	1 = Interrupt request is enabled											
	0 = Interrupt request is not enabled											
bit 13	INT2IE: External Interrupt 2 Enable bit ⁽¹⁾											
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled 											
bit 12	•	•										
DILIZ	T5IE: Timer5 Interrupt Enable bit 1 = Interrupt request is enabled											
	 0 = Interrupt request is not enabled 											
bit 11	T4IE: Timer4 Interrupt Enable bit											
	1 = Interrupt request is enabled											
	0 = Interrupt request is not enabled											
bit 10	OC4IE: Output Compare Channel 4 Interrupt Enable bit											
	1 = Interrupt request is enabled											
	0 = Interrupt request is not enabled											
bit 9	OC3IE: Output Compare Channel 3 Interrupt Enable bit											
		request is enable request is not e										
bit 8	-	ited: Read as '										
bit 7	•	Capture Channe		nable bit								
		request is enat										
		request is not e										
		-										

Note 1: If an external interrupt is enabled, the interrupt input must also be configured to an available RPx or RPIx pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

REGISTER 7-13: IEC1: INTERRUPT ENABLE CONTROL REGISTER 1 (CONTINUED)

bit 6	 IC7IE: Input Capture Channel 7 Interrupt Enable bit 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 5	Unimplemented: Read as '0'
bit 4	INT1IE: External Interrupt 1 Enable bit ⁽¹⁾
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 3	CNIE: Input Change Notification Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 2	CMIE: Comparator Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 1	MI2C1IE: Master I2C1 Event Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 0	SI2C1IE: Slave I2C1 Event Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled

Note 1: If an external interrupt is enabled, the interrupt input must also be configured to an available RPx or RPIx pin. See **Section 10.4 "Peripheral Pin Select (PPS)**" for more information.

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U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
		PMPIE ⁽¹⁾	OC8IE	OC7IE	OC6IE	OC5IE	IC6IE				
oit 15							bit				
R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0	R/W-0				
IC5IE	IC4IE	IC3IE	—	<u> </u>	—	SPI2IE	SPF2IE				
pit 7							bit				
egend:											
R = Readable	bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'					
n = Value at I	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	iown				
oit 15-14	Unimplemen	ted: Read as ')'								
bit 13	PMPIE: Para	llel Master Port	Interrupt Enab	ole bit ⁽¹⁾							
	•	request is enabled									
pit 12	•	request is not e		nt Enchlo hit							
JIL 12	OC8IE: Output Compare Channel 8 Interrupt Enable bit										
	 Interrupt request is enabled Interrupt request is not enabled 										
pit 11	OC7IE: Output Compare Channel 7 Interrupt Enable bit										
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled 										
	•	•									
pit 10	OC6IE: Output Compare Channel 6 Interrupt Enable bit										
	 I = Interrupt request is enabled 0 = Interrupt request is not enabled 										
oit 9	O = Interrupt request is not enabled OC5IE: Output Compare Channel 5 Interrupt Enable bit										
	1 = Interrupt request is enabled										
		request is not e									
oit 8	IC6IE: Input Capture Channel 6 Interrupt Enable bit										
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled 										
oit 7	IC5IE: Input Capture Channel 5 Interrupt Enable bit										
	1 = Interrupt request is enabled										
	0 = Interrupt request is not enabled										
pit 6	IC4IE: Input Capture Channel 4 Interrupt Enable bit										
	 I = Interrupt request is enabled 0 = Interrupt request is not enabled 										
oit 5	-	-		nable bit							
	IC3IE: Input Capture Channel 3 Interrupt Enable bit 1 = Interrupt request is enabled										
		request is not e									
oit 4-2	Unimplemen	ted: Read as ')'								
pit 1	SPI2IE: SPI2	Event Interrupt	Enable bit								
		request is enab									
oit O	-	request is not e 2 Fault Interrupt									
JIL U		request is enat									
	0 = Interrupt	i squest is criat	illu illu								

REGISTER 7-14: IEC2: INTERRUPT ENABLE CONTROL REGISTER 2

Note 1: Not available in 64-pin devices (PIC24FJXXXDAX06).

REGISTER 7-15: IEC3: INTERRUPT ENABLE CONTROL REGISTER 3

U-0	R/W-0	U-0	U-0	U-0	U-0	U-0	U-0
_	RTCIE	—		—		—	—
bit 15							bit 8
U-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	U-0
_	INT4IE ⁽¹⁾	INT3IE ⁽¹⁾	_	_	MI2C2IE	SI2C2IE	_

Legend:						
R = Readable bit	W = Writable bit	U = Unimplemented bit,	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	Unimplemented: Read as '0'
bit 14	RTCIE: Real-Time Clock/Calendar Interrupt Enable bit 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 13-7	Unimplemented: Read as '0'
bit 6	INT4IE: External Interrupt 4 Enable bit ⁽¹⁾ 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 5	INT3IE: External Interrupt 3 Enable bit ⁽¹⁾ 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 4-3	Unimplemented: Read as '0'
bit 2	MI2C2IE: Master I2C2 Event Interrupt Enable bit
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 1	SI2C2IE: Slave I2C2 Event Interrupt Enable bit
	 1 = Interrupt request is enabled 0 = Interrupt request is not enabled
bit 0	Unimplemented: Read as '0'

Note 1: If an external interrupt is enabled, the interrupt input must also be configured to an available RPx or RPIx pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

bit 7

bit 0

U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	R/W-0			
_		CTMUIE	—	_	—		LVDIE			
bit 15		-					bit 8			
U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	U-0			
_	_	—	_	CRCIE	U2ERIE	U1ERIE	_			
bit 7							bit (
Legend:										
R = Readabl		W = Writable b	It	•	nented bit, read					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own			
bit 15-14										
	-	nted: Read as '0'								
bit 13	CTMUIE: CTMU Interrupt Enable bit									
	 I = Interrupt request is enabled 0 = Interrupt request is not enabled 									
bit 12-9	•	nted: Read as '0'								
bit 8	LVDIE: Low-Voltage Detect Interrupt Enable bit									
	1 = Interrupt request is enabled									
	0 = Interrupt request is not enabled									
bit 7-4	Unimplemen	nted: Read as '0'								
bit 3	CRCIE: CRC Generator Interrupt Enable bit									
	1 = Interrupt request is enabled									
		request is not er								
bit 2	U2ERIE: UART2 Error Interrupt Enable bit									
	1 = Interrupt request is enabled									
	0 = Interrupt request is not enabled									
	•	•								
bit 1	U1ERIE: UAI	RT1 Error Interru	pt Enable bit							
bit 1	U1ERIE: UAI 1 = Interrupt	•	pt Enable bit ed							

REGISTER 7-16: IEC4: INTERRUPT ENABLE CONTROL REGISTER 4

REGISTER 7-17: IEC5: INTERRUPT ENABLE CONTROL REGISTER 5

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
—	_	IC9IE	OC9IE	SPI3IE	SPF3IE	U4TXIE	U4RXIE					
bit 15							bit a					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0					
U4ERIE	USB1IE	MI2C3IE	SI2C3IE	U3TXIE	U3RXIE	U3ERIE	_					
bit 7							bit					
Legend:												
R = Readabl	e bit	W = Writable	bit	U = Unimplen	nented bit, read	d as '0'						
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown					
bit 15-14	Unimplemen	ted: Read as ')'									
bit 13	IC9IE: Input C	Capture Channe	el 9 Interrupt E	nable bit								
		request enable request not enable										
bit 12	•	ut Compare Ch		upt Enable bit								
	1 = Interrupt	request enable	d									
bit 11	 0 = Interrupt request not enabled SPI3IE: SPI3 Event Interrupt Enable bit 											
		 1 = Interrupt request enabled 0 = Interrupt request not enabled 										
bit 10	•	PF3IE: SPI3 Fault Interrupt Enable bit										
	1 = Interrupt	request enable	d									
bit 9	 Interrupt request not enabled U4TXIE: UART4 Transmitter Interrupt Enable bit 											
bit 9	1 = Interrupt request enabled											
	-	request not en										
bit 8	U4RXIE: UART4 Receiver Interrupt Enable bit 1 = Interrupt request enabled											
	0 = Interrupt request not enabled											
bit 7	U4ERIE: UART4 Error Interrupt Enable bit											
	 1 = Interrupt request enabled 0 = Interrupt request not enabled 											
L:1 0	-	-		1- 1-14								
bit 6	USB1IE: USB1 (USB OTG) Interrupt Enable bit 1 = Interrupt request enabled											
	0 = Interrupt request not enabled											
bit 5	MI2C3IE: Master I2C3 Event Interrupt Enable bit											
		request enable										
bit 4	-	 0 = Interrupt request not enabled SI2C3IE: Slave I2C3 Event Interrupt Enable bit 										
	1 = Interrupt	request enable request not ena	d									
bit 3	•	RT3 Transmitter		ble bit								
		request enable	-									
	-	request not en										
bit 2	U3RXIE: UAF	RT3 Receiver Ir	nterrupt Enable	e bit								
		request enable	-									

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REGISTER 7-17: IEC5: INTERRUPT ENABLE CONTROL REGISTER 5 (CONTINUED)

bit 1	U3ERIE: UART3 Error Interrupt Enable bit
	1 = Interrupt request is enabled
	0 = Interrupt request is not enabled
bit 0	Unimplemented: Read as '0'

REGISTER 7-18: IEC6: INTERRUPT ENABLE CONTROL REGISTER 6

U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	•••	00	0-0	0-0	0-0	0-0	
	—	—	—		—	_	
						bit 8	
U-0	U-0	R/W-0	U-0	U-0	U-0	U-0	
	—	GFX1IE	—	_	—	_	
bit 7					- -	bit 0	
R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared		x = Bit is unknown		
	t	t W = Writable t	— — GFX1IE t W = Writable bit	GFX1IE t W = Writable bit U = Unimplem	— — — GFX1IE — — — — — — — — — — — — — — — — — — —	— — GFX1IE — — — t W = Writable bit U = Unimplemented bit, read as '0'	

```
bit 4 GFX1IE: Graphics 1 Interrupt Enable bit
```

- 1 = Interrupt request is enabled
- 0 = Interrupt request is not enabled
- bit 3-0 Unimplemented: Read as '0'

REGISTER 7-19: IPC0: INTERRUPT PRIORITY CONTROL REGISTER 0

	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
—	T1IP2	T1IP1	T1IP0		OC1IP2	OC1IP1	OC1IP0				
pit 15							bit				
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
	IC1IP2	IC1IP1	IC1IP0	—	INT0IP2	INT0IP1	INT0IP0				
bit 7							bit				
Legend:											
R = Readab	le bit	W = Writable b	bit	U = Unimplei	mented bit, read	l as '0'					
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown				
bit 15	Unimpleme	nted: Read as '0	,								
bit 14-12	-										
		T1IP<2:0>: Timer1 Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)									
	•		5 1 7	. /							
	•										
		upt is priority 1 upt source is dis	ablad								
bit 11		-									
•											
hit 10-8	OC11P<2.0>	Output Compa	re Channel 1 I	nterrunt Priorit	ty hits						
bit 10-8		 Output Compa upt is priority 7 (h 		-	ty bits						
bit 10-8		 Output Compa upt is priority 7 (h 		-	ty bits						
bit 10-8				-	ty bits						
bit 10-8	111 = Interru • •	upt is priority 7 (h		-	ty bits						
bit 10-8	111 = Intern • • 001 = Intern		ighest priority	-	ty bits						
	111 = Intern • • 001 = Intern 000 = Intern	upt is priority 7 (h upt is priority 1	iighest priority abled	-	ty bits						
bit 10-8 bit 7 bit 6-4	111 = Intern • • 001 = Intern 000 = Intern Unimpleme	upt is priority 7 (h upt is priority 1 upt source is dis	ighest priority abled	interrupt)							
bit 7	111 = Intern 001 = Intern 000 = Intern Unimplement IC1IP<2:0>:	upt is priority 7 (h upt is priority 1 upt source is disa nted: Read as '0	abled , hannel 1 Inter	interrupt) rupt Priority bit							
bit 7	111 = Intern 001 = Intern 000 = Intern Unimplement IC1IP<2:0>:	upt is priority 7 (h upt is priority 1 upt source is dis nted: Read as '0 Input Capture C	abled , hannel 1 Inter	interrupt) rupt Priority bit							
bit 7	111 = Intern 001 = Intern 000 = Intern Unimplement IC1IP<2:0>:	upt is priority 7 (h upt is priority 1 upt source is dis nted: Read as '0 Input Capture C	abled , hannel 1 Inter	interrupt) rupt Priority bit							
bit 7	111 = Intern 001 = Intern 000 = Intern Unimplemen IC1IP<2:0>: 111 = Intern 001 = Intern	upt is priority 7 (h upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (h upt is priority 1	abled ,' hannel 1 Intern nighest priority	interrupt) rupt Priority bit							
oit 7 oit 6-4	111 = Intern 001 = Intern 000 = Intern Unimplemen IC1IP<2:0>: 111 = Intern 001 = Intern 000 = Intern	upt is priority 7 (h upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (h	abled ,' hannel 1 Inter highest priority	interrupt) rupt Priority bit							
bit 7 bit 6-4 bit 3	111 = Intern 001 = Intern 000 = Intern Unimplement IC1IP<2:0>: 111 = Intern 001 = Intern 000 = Intern Unimplement	upt is priority 7 (h upt is priority 1 upt source is disa nted: Read as 'c Input Capture C upt is priority 7 (h upt is priority 1 upt source is disa	abled ,' hannel 1 Intern highest priority abled	interrupt) rupt Priority bit interrupt)							
bit 7	111 = Intern 001 = Intern 000 = Intern Unimplemen 001 = Intern 001 = Intern Unimplement Unimplement Unimplement	upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0	abled ,' hannel 1 Intern highest priority abled ,'	interrupt) rupt Priority bit rinterrupt)							
bit 7 bit 6-4 bit 3	111 = Intern 001 = Intern 000 = Intern Unimplemen 001 = Intern 001 = Intern Unimplement Unimplement Unimplement	upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 >: External Intern	abled ,' hannel 1 Intern highest priority abled ,'	interrupt) rupt Priority bit rinterrupt)							
bit 7 bit 6-4 bit 3	111 = Intern 001 = Intern 000 = Intern Unimplemen 001 = Intern 001 = Intern Unimplement Unimplement Unimplement	upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 >: External Intern	abled ,' hannel 1 Intern highest priority abled ,'	interrupt) rupt Priority bit rinterrupt)							
bit 7 bit 6-4 bit 3	111 = Intern 001 = Intern 000 = Intern Unimplemen IC1IP<2:0>: 111 = Intern 001 = Intern 000 = Intern Unimplemen INT0IP<2:0> 111 = Intern	upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 Input Capture C upt is priority 7 (f upt is priority 1 upt source is dis nted: Read as '0 >: External Intern	abled ,' hannel 1 Intern highest priority abled ,'	interrupt) rupt Priority bit rinterrupt)							

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	T2IP2	T2IP1	T2IP0	_	OC2IP2	OC2IP1	OC2IP0
bit 15			1				bit
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
_	IC2IP2	IC2IP1	IC2IP0	_	_	_	_
bit 7							bit
Legend:							
R = Readat	ole bit	W = Writable	bit	U = Unimplen	nented bit, read	l as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
bit 14-12 bit 11 bit 10-8	111 = Interru • • • • • • • • • • • • • • • • • •	Timer2 Interrupt upt is priority 7 (upt is priority 1 upt source is dis nted: Read as ' : Output Compa upt is priority 7 (highest priority sabled 0' are Channel 2	Interrupt Priorit	y bits		
bit 7 bit 6-4	• • • 001 = Interru 000 = Interru	upt is priority 1 upt source is dis nted: Read as '	sabled 0'		S		
	111 = Interru •	upt is priority 7 (

REGISTER 7-20: IPC1: INTERRUPT PRIORITY CONTROL REGISTER 1

REGISTER 7-21: IPC2: INTERRUPT PRIORITY CONTROL REGISTER 2

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
_	U1RXIP2	U1RXIP1	U1RXIP0	_	SPI1IP2	SPI1IP1	SPI1IP0				
bit 15							bit				
		D #44 0	D #44.0		D 444 4		D 444 0				
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
	SPF1IP2	SPF1IP1	SPF1IP0	—	T3IP2	T3IP1	T3IP0				
bit 7							bit				
Legend:											
R = Readab	le bit	W = Writable	bit	U = Unimple	mented bit, read	l as '0'					
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown				
bit 15	Unimplemen	ted: Read as ')'								
bit 14-12	U1RXIP<2:0>	>: UART1 Rece	iver Interrupt F	Priority bits							
	111 = Interrupt is priority 7 (highest priority interrupt)										
	•										
	•										
	001 = Interrupt is priority 1 000 = Interrupt source is disabled										
		-									
bit 11	-	ted: Read as '									
bit 10-8	SPI1IP<2:0>: SPI1 Event Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)										
	111 = Interru	ipt is priority 7 (highest priority	interrupt)							
	•										
	•										
	001 = Interru	ipt is priority 1 ipt source is dis	abled								
bit 7		ited: Read as '									
bit 6-4		SPI1 Fault Ini		hite							
DIL 0-4		pt is priority 7 (1 5								
	•		inglieet prienty	interrapt)							
	•										
	• 001 = Interru	• 001 = Interrupt is priority 1									
		pt source is dis	abled								
bit 3	Unimplemen	ted: Read as ')'								
bit 2-0	T3IP<2:0>: ⊤	ïmer3 Interrupt	Priority bits								
	111 = Interru	pt is priority 7 (highest priority	interrupt)							
	•										
	•										
	•										
	• 001 = Interru	pt is priority 1 pt source is dis									

	-	-	-							
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
		—	—	—	—		_			
bit 15							bit 8			
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0			
—	AD1IP2	AD1IP1	AD1IP0	—	U1TXIP2	U1TXIP1	U1TXIP0			
bit 7							bit 0			
Legend:										
R = Readable bit W = Writable bit				U = Unimplemented bit, read as '0'						
-n = Value a	at POR	'1' = Bit is set	t	'0' = Bit is cle	eared	x = Bit is unkr	IOWN			
bit 15-7	-	nted: Read as '								
bit 6-4		AD1IP<2:0>: A/D Conversion Complete Interrupt Priority bits								
	111 = Interru	upt is priority 7	(highest priority	y interrupt)						
	•									
	•									
		upt is priority 1 upt source is di	sabled							
bit 3	Unimplemer	nted: Read as '	0'							
bit 2-0	U1TXIP<2:0	>: UART1 Tran	smitter Interrup	ot Priority bits						
	111 = Interru	upt is priority 7	(highest priority	y interrupt)						
	•									
	•									
		upt is priority 1								
	000 = Interru	upt source is dis	sabled							

REGISTER 7-22: IPC3: INTERRUPT PRIORITY CONTROL REGISTER 3

REGISTER 7-23: IPC4: INTERRUPT PRIORITY CONTROL REGISTER 4

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
—	CNIP2	CNIP1	CNIP0		CMIP2	CMIP1	CMIP0				
bit 15					•		bit				
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0				
_	MI2C1IP2	MI2C1IP1	MI2C1IP0	_	SI2C1IP2	SI2C1IP1	SI2C1IP0				
bit 7							bit				
Legend:											
R = Readab	le bit	W = Writable I	oit	U = Unimplen	nented bit, read	l as '0'					
-n = Value a	It POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown				
bit 15	Unimplemen	ted: Read as 'd)'								
bit 14-12	CNIP<2:0>: II	nput Change N	otification Inter	rrupt Priority bit	s						
	CNIP<2:0>: Input Change Notification Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)										
	•										
	001 = Interrupt is priority 1										
		pt source is dis									
bit 11	Unimplemen	ted: Read as '0)'								
bit 10-8	CMIP<2:0>: Comparator Interrupt Priority bits										
	111 = Interru	pt is priority 7 (nighest priority	interrupt)							
	•										
	•										
	001 = Interru		ablad								
bit 7		pt source is dis									
	Unimplemen	Unimplemented: Read as '0'									
hit C 1	MICCAID			t Driarity bita							
bit 6-4		>: Master I2C1	Event Interrup	•							
bit 6-4			Event Interrup	•							
bit 6-4		>: Master I2C1	Event Interrup	•							
bit 6-4	111 = Interru • •	>: Master I2C1 pt is priority 7 (I	Event Interrup	•							
bit 6-4	111 = Interru • • 001 = Interru	>: Master I2C1 pt is priority 7 (I pt is priority 1	Event Interrup nighest priority	•							
	111 = Interru • • • • • • • • • • • • • • • • • •	>: Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis	Event Interrup highest priority abled	•							
bit 3	111 = Interru • • 001 = Interru 000 = Interru Unimplemen	>: Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as '0	Event Interrup nighest priority abled	r interrupt)							
bit 3	111 = Interru 001 = Interru 000 = Interru Unimplemen SI2C1IP<2:0>	>: Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis	Event Interrup nighest priority abled o' vent Interrupt	r interrupt) Priority bits							
bit 3	111 = Interru 001 = Interru 000 = Interru Unimplemen SI2C1IP<2:0>	>: Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as '(>: Slave I2C1 E	Event Interrup nighest priority abled o' vent Interrupt	r interrupt) Priority bits							
bit 6-4 bit 3 bit 2-0	111 = Interru 001 = Interru 000 = Interru Unimplemen SI2C1IP<2:0>	>: Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as '(>: Slave I2C1 E	Event Interrup nighest priority abled o' vent Interrupt	r interrupt) Priority bits							
bit 3	111 = Interru 001 = Interru 000 = Interru Unimplemen SI2C1IP<2:0>	 Master I2C1 pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as '(Slave I2C1 E pt is priority 7 (I 	Event Interrup nighest priority abled o' vent Interrupt	r interrupt) Priority bits							

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0			
_	IC8IP2	IC8IP1	IC8IP0		IC7IP2	IC7IP1	IC7IP0			
bit 15			•				bit			
U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0			
_			_		INT1IP2	INT1IP1	INT1IP0			
bit 7	•	•	•	·	•		bit			
Legend:										
R = Readat	ole bit	W = Writable	bit	U = Unimpler	mented bit, rea	d as '0'				
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown			
bit 15	-	nted: Read as '								
bit 14-12	IC8IP<2:0>: Input Capture Channel 8 Interrupt Priority bits									
	111 = Interrupt is priority 7 (highest priority interrupt)									
		upt is priority 1 upt source is dis	abled							
bit 11	Unimplemen	ted: Read as '	0'							
bit 10-8	IC7IP<2:0>: Input Capture Channel 7 Interrupt Priority bits									
	111 = Interrupt is priority 7 (highest priority interrupt)									
	•	, ,	0 1	, ,						
	•									
	• $0.01 = 1$ ptorrupt is priority 1									
	001 = Interrupt is priority 1 000 = Interrupt source is disabled									
bit 7-3		nted: Read as '								
bit 2-0	-	: External Interi		hits						
		. External internal internal internal priority 7 (
	•		ingricot priorit	y menupt)						
	•									
	•									
		upt is priority 1 upt source is dis	ablad							
		ipi source is us	aneu							

REGISTER 7-24: IPC5: INTERRUPT PRIORITY CONTROL REGISTER 5

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0			
_	T4IP2	T4IP1	T4IP0	—	OC4IP2	OC4IP1	OC4IP0			
bit 15							bit 8			
	D 44/ 4	DAMA	D 444 0							
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0			
 bit 7	OC3IP2	OC3IP1	OC3IP0	—	_	_	bit (
							Dit C			
Legend:										
R = Readat	ole bit	W = Writable	bit	U = Unimpler	mented bit, read	d as '0'				
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown			
bit 15	Unimplemer	nted: Read as '	0'							
bit 14-12	T4IP<2:0>: Timer4 Interrupt Priority bits									
	111 = Interrupt is priority 7 (highest priority interrupt)									
	•									
	•									
	001 = Interrupt is priority 1									
	000 = Interru	ipt source is dis	abled							
bit 11	Unimplemer	nted: Read as '	0'							
bit 10-8	OC4IP<2:0>: Output Compare Channel 4 Interrupt Priority bits									
	<pre>111 = Interrupt is priority 7 (highest priority interrupt)</pre>									
	•									
	•									
		upt is priority 1								
	000 = Interrupt source is disabled									
	Unimplemented: Read as '0'									
bit 7	-									
bit 7 bit 6-4	OC3IP<2:0>	: Output Compa	are Channel 3 I	•	y bits					
	OC3IP<2:0>		are Channel 3 I	•	y bits					
	OC3IP<2:0>	: Output Compa	are Channel 3 I	•	y bits					
	OC3IP<2:0> 111 = Interru	: Output Compa Ipt is priority 7 (are Channel 3 I	•	y bits					
	OC3IP<2:0> 111 = Interru	: Output Compa upt is priority 7 (upt is priority 1	are Channel 3 I highest priority	•	y bits					
	OC3IP<2:0> 111 = Intern	: Output Compa Ipt is priority 7 (are Channel 3 I highest priority abled	•	y bits					

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0					
_	U2TXIP2	U2TXIP1	U2TXIP0	—	U2RXIP2	U2RXIP1	U2RXIP0					
bit 15							bit					
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0					
	INT2IP2	INT2IP1	INT2IP0	0-0	T5IP2	T5IP1	T5IP0					
bit 7	11112112				10112	1011 1	bit					
Legend:												
R = Readab		W = Writable		-	mented bit, read							
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	iown					
L:1 4 F		tad: Daad as f	. '									
bit 15	-	ted: Read as '		t Dui a uite : la ita								
bit 14-12		 UART2 Trans pt is priority 7 (-	-								
	•	pr is priority 7 (nignest priority	interrupt)								
	•											
	• 001 = Interru	• 001 = Interrupt is priority 1										
		pt source is dis	abled									
bit 11	Unimplemen	ted: Read as '	כי									
bit 10-8	U2RXIP<2:0>: UART2 Receiver Interrupt Priority bits											
	111 = Interru	pt is priority 7 (highest priority	interrupt)								
	•											
	•											
	001 = Interru											
		pt source is dis										
bit 7	-	ted: Read as '		.,								
bit 6-4		External Interr										
	111 = Interru •	pt is priority 7 (nignest priority	interrupt)								
	•											
	• 001 = Interru	nt is priority 1										
		pt source is dis	abled									
bit 3		ted: Read as '(
bit 2-0	-	imer5 Interrupt										
		pt is priority 7 (-	interrupt)								
	•											
	•											
	• •											
		pt is priority 1 pt source is dis										

REGISTER 7-27: IPC8: INTERRUPT PRIORITY CONTROL REGISTER 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	_	—	_	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	SPI2IP2	SPI2IP1	SPI2IP0	—	SPF2IP2	SPF2IP1	SPF2IP0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-7 bit 6-4	Unimplemented: Read as '0' SPI2IP<2:0>: SPI2 Event Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)
	001 = Interrupt is priority 1 000 = Interrupt source is disabled
bit 3	Unimplemented: Read as '0'
bit 2-0	SPF2IP<2:0>: SPI2 Fault Interrupt Priority bits
	<pre>111 = Interrupt is priority 7 (highest priority interrupt)</pre>
	001 = Interrupt is priority 1 000 = Interrupt source is disabled

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U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0		
	IC5IP2	IC5IP1	IC5IP0	—	IC4IP2	IC4IP1	IC4IP0		
bit 15	·				•	·	bit 8		
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0		
_	IC3IP2	IC3IP1	IC3IP0	_		_	_		
bit 7							bit		
Legend:									
R = Readab	ole bit	W = Writable	bit	U = Unimplen	nented bit, read	1 as '0'			
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkn	own		
bit 15	Unimplomen	tod: Dood oo '	o'						
bit 15	Unimplemen	ted: Read as '	0'						
bit 14-12	IC5IP<2:0>:	Input Capture (Channel 5 Inter	rrupt Priority bits	6				
	111 = Interrupt is priority 7 (highest priority interrupt)								
	•								
	•								
	• 001 = Interrupt is priority 1								
		ipt is priority 1 ipt source is dis	ablad						
bit 11		ited: Read as '							
bit 10-8	-			rrupt Priority bits					
DIL TO-O					>				
	<pre>111 = Interrupt is priority 7 (highest priority interrupt)</pre>								
	•								
	•								
	001 = Interru								
	000 = Interru	pt source is dis	sabled						
bit 7	Unimplemen	ted: Read as '	0'						
bit 6-4	IC3IP<2:0>:	Input Capture 0	Channel 3 Inter	rrupt Priority bits	3				
	111 = Interru	pt is priority 7 (highest priority	y interrupt)					
	•								
	•								
	• 001 = Interru	pt is priority 1							
		ipt is priority i ipt source is dis	sabled						
bit 3-0	Unimplemen	-							
			∩'						

REGISTER 7-28: IPC9: INTERRUPT PRIORITY CONTROL REGISTER 9

REGISTER 7-29: IPC10: INTERROPT PRIORITY CONTROL REGISTER 10	REGISTER 7-29:	IPC10: INTERRUPT PRIORITY CONTROL REGISTER 10
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U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0			
—	OC7IP2	OC7IP1	OC7IP0	_	OC6IP2	OC6IP1	OC6IP0			
bit 15						-	bit			
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0			
_	OC5IP2	OC5IP1	OC5IP0		IC6IP2	IC6IP1	IC6IP0			
bit 7							bit			
Legend:										
R = Readab	ole bit	W = Writable I	bit	U = Unimple	mented bit, read	d as '0'				
-n = Value a		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	nown			
bit 15	Unimplemen	ted: Read as 'd	י)							
bit 14-12	OC7IP<2:0>:	Output Compa	re Channel 7	Interrupt Priori	ty bits					
	OC7IP<2:0>: Output Compare Channel 7 Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)									
	•									
	•									
	001 = Interru									
	000 = Interru	pt source is dis								
	000 = Interru Unimplemen	ipt source is dis ited: Read as '()'							
bit 11 bit 10-8	000 = Interru Unimplemen OC6IP<2:0>:	ipt source is dis ited: Read as '(Output Compa	o' ire Channel 6	-	ty bits					
	000 = Interru Unimplemen OC6IP<2:0>:	ipt source is dis ited: Read as '(o' ire Channel 6	-	ty bits					
	000 = Interru Unimplemen OC6IP<2:0>:	ipt source is dis ited: Read as '(Output Compa	o' ire Channel 6	-	ty bits					
	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis Ited: Read as '(Output Compa Ipt is priority 7 (o' ire Channel 6	-	ty bits					
	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru	pt source is dis ted: Read as 'c Output Compa pt is priority 7 (l pt is priority 1	^{∋'} Ire Channel 6 ∣ highest priority	-	ty bits					
bit 10-8	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ited: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis	_o , ire Channel 6 highest priority abled	-	ty bits					
bit 10-8 bit 7	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ited: Read as '(_o , ire Channel 6 highest priority abled	/ interrupt)						
bit 10-8 bit 7	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa	⁾ ire Channel 6 highest priority abled) ['] ire Channel 5 h	/ interrupt)						
bit 10-8 bit 7	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ited: Read as '(⁾ ire Channel 6 highest priority abled) ['] ire Channel 5 h	/ interrupt)						
bit 10-8	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa	⁾ ire Channel 6 highest priority abled) ['] ire Channel 5 h	/ interrupt)						
bit 10-8 bit 7	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen OC5IP<2:0>: 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (⁾ ire Channel 6 highest priority abled) ['] ire Channel 5 h	/ interrupt)						
bit 10-8 bit 7	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru	pt source is dis ted: Read as 'C Output Compa pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as 'C Output Compa pt is priority 7 (I pt is priority 7 (I	^{)'} ire Channel 6 highest priority abled ^{)'} ire Channel 5 highest priority	/ interrupt)						
bit 10-8 bit 7 bit 6-4	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 001 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (^{o'} Ire Channel 6 highest priority abled o' Ire Channel 5 highest priority	/ interrupt)						
bit 10-8 bit 7 bit 6-4 bit 3	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 7 pt source is dis ted: Read as '(pt is priority 1 pt source is dis ted: Read as '(^{o)} Ire Channel 6 highest priority abled bighest priority abled o'	/ interrupt) Interrupt Priorit / interrupt)	ty bits					
bit 10-8 bit 7 bit 6-4 bit 3	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 001 = Interru 001 = Interru Unimplemen IC6IP<2:0>: I	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 7 pt source is dis ted: Read as '(Input Source is dis ted: Read as '(Input Capture C	^{D'} Ire Channel 6 highest priority abled D' Ire Channel 5 highest priority abled D' Channel 6 Inter	/ interrupt) Interrupt Priorit / interrupt)	ty bits					
bit 10-8 bit 7 bit 6-4 bit 3	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 001 = Interru 001 = Interru Unimplemen IC6IP<2:0>: I	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 7 pt source is dis ted: Read as '(pt is priority 1 pt source is dis ted: Read as '(^{D'} Ire Channel 6 highest priority abled D' Ire Channel 5 highest priority abled D' Channel 6 Inter	/ interrupt) Interrupt Priorit / interrupt)	ty bits					
bit 10-8 bit 7 bit 6-4	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 001 = Interru 001 = Interru Unimplemen IC6IP<2:0>: I	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 7 pt source is dis ted: Read as '(Input Source is dis ted: Read as '(Input Capture C	^{D'} Ire Channel 6 highest priority abled D' Ire Channel 5 highest priority abled D' Channel 6 Inter	/ interrupt) Interrupt Priorit / interrupt)	ty bits					
bit 10-8 bit 7 bit 6-4 bit 3	000 = Interru Unimplemen OC6IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen OC5IP<2:0>: 111 = Interru 001 = Interru 000 = Interru Unimplemen IC6IP<2:0>: I 111 = Interru	pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '(Output Compa pt is priority 7 (pt is priority 7 pt source is dis ted: Read as '(Input Source is dis ted: Read as '(Input Capture C	^{D'} Ire Channel 6 highest priority abled D' Ire Channel 5 highest priority abled D' Channel 6 Inter	/ interrupt) Interrupt Priorit / interrupt)	ty bits					

REGISTER 7-30: IPC11: INTERRUPT PRIORITY CONTROL REGISTER 11

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
0-0	0-0	0-0	0-0	0-0	0-0	0-0	0-0
	_	_		_	_	_	<u> </u>
bit 15							bit 8
						-	-
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
	PMPIP2 ⁽¹⁾	PMPIP1 ⁽¹⁾	PMPIP0 ⁽¹⁾	—	OC8IP2	OC8IP1	OC8IP0
bit 7							bit 0
Legend:							
R = Readal	ole bit	W = Writable	bit	U = Unimpler	mented bit, read	d as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unki	nown
bit 15-7	Unimplement	ted: Read as '	כ'				
bit 6-4	PMPIP<2:0>:	Parallel Maste	r Port Interrupt	t Priority bits ⁽¹⁾			
	111 = Interru	pt is priority 7 (highest priority	interrupt)			
	•						
	•						
	001 = Interru						
	000 = Interru	pt source is dis	abled				
bit 3	Unimplement	ted: Read as '	כי				
bit 2-0	OC8IP<2:0>:	Output Compa	ire Channel 8 I	nterrupt Priorit	y bits		
	111 = Interru	pt is priority 7 (highest priority	interrupt)			
	•						
	•						
	001 = Interru	pt is priority 1					
	000 = Interru	pt source is dis	abled				
			abled				

Note 1: Not available in 64-pin devices (PIC24FJXXXDAX06).

REGISTER 7-31: IPC12: INTERRUPT PRIORITY CONTROL REGISTER 12

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	MI2C2IP2	MI2C2IP1	MI2C2IP0
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	SI2C2IP2	SI2C2IP1	SI2C2IP0	—	—	—	—
bit 7							bit 0

-									
Legend:									
R = Readal	ole bit	W = Writable bit	U = Unimplemented bit,	, read as '0'					
-n = Value a	at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown					
bit 15-11	Unimplem	ented: Read as '0'							
bit 10-8	MI2C2IP<2	::0>: Master I2C2 Event In	terrupt Priority bits						
	111 = Interrupt is priority 7 (highest priority interrupt)								
	•								
	•								
	• 001 = Inter	rrupt is priority 1							
		rrupt source is disabled							
bit 7	Unimplem	ented: Read as '0'							
bit 6-4	SI2C2IP<2	:0>: Slave I2C2 Event Inte	errupt Priority bits						
	111 = Inter	rrupt is priority 7 (highest p	priority interrupt)						
	•								
	•								
	• 001 - Into	rrupt is priority 1							
		rrupt source is disabled							
bit 3-0		ented: Read as '0'							
	p.e								

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	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0		
	_		—	_	INT4IP2	INT4IP1	INT4IP0		
bit 15	·						bit 8		
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0		
—	INT3IP2	INT3IP1	INT3IP0	—	—	_	—		
bit 7							bit 0		
Legend:									
R = Readab	ole bit	W = Writable	bit	•	mented bit, read	d as '0'			
-n = Value at POR '1' = Bit is set				'0' = Bit is cle	eared	x = Bit is unkr	nown		
bit 15-11	•	ted: Read as '	0'						
		INT4IP<2:0>: External Interrupt 4 Priority bits							
bit 10-8	INT4IP<2:0>:	External Inter	rupt 4 Priority b	oits					
dit 10-8		External Interi pt is priority 7 (
dit 10-8									
dit 10-8									
dit 10-8	111 = Interru • • 001 = Interru	pt is priority 7 (pt is priority 1	highest priority						
dit 10-8	111 = Interru • • 001 = Interru	pt is priority 7 (highest priority						
bit 10-8 bit 7	111 = Interru • • 001 = Interru 000 = Interru	pt is priority 7 (pt is priority 1	highest priority						
	111 = Interru 001 = Interru 000 = Interru Unimplemen	pt is priority 7 (pt is priority 1 pt source is dis	highest priority sabled 0'	/ interrupt)					
bit 7	111 = Interru 001 = Interru 000 = Interru Unimplemen INT3IP<2:0>:	pt is priority 7 (pt is priority 1 pt source is dis ted: Read as '	highest priority sabled 0' rupt 3 Priority I	y interrupt) bits					
bit 7	111 = Interru 001 = Interru 000 = Interru Unimplemen INT3IP<2:0>:	pt is priority 7 (pt is priority 1 pt source is dis ted: Read as ' External Intern	highest priority sabled 0' rupt 3 Priority I	y interrupt) bits					
bit 7	111 = Interru 001 = Interru 000 = Interru Unimplemen INT3IP<2:0>:	pt is priority 7 (pt is priority 1 pt source is dis ted: Read as ' External Intern	highest priority sabled 0' rupt 3 Priority I	y interrupt) bits					
bit 7	111 = Interru 001 = Interru 000 = Interru Unimplemen INT3IP<2:0>:	pt is priority 7 (pt is priority 1 pt source is dis ted: Read as ' External Intern pt is priority 7 (highest priority sabled 0' rupt 3 Priority I	y interrupt) bits					
bit 7	111 = Interru 001 = Interru 000 = Interru Unimplemen INT3IP<2:0>: 111 = Interru 001 = Interru	pt is priority 7 (pt is priority 1 pt source is dis ted: Read as ' External Intern pt is priority 7 (highest priority abled o' rupt 3 Priority t	y interrupt) bits					

REGISTER 7-32: IPC13: INTERRUPT PRIORITY CONTROL REGISTER 13

REGISTER 7-33: IPC15: INTERRUPT PRIORITY CONTROL REGISTER 15

U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0		
_	—	—	—	—	RTCIP2	RTCIP1	RTCIP0		
bit 15							bit 8		
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
	—	—	_	—	—	—	—		
bit 7							bit 0		
Legend:									
R = Readabl	le bit	W = Writable	bit	U = Unimplem	nented bit, read	l as '0'	bit 0		
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr			
bit 15-11	Unimplemen	ted: Read as '0)'						
bit 10-8	RTCIP<2:0>:	Real-Time Clo	ck and Calenda	ar Interrupt Pric	ority bits				
	111 = Interru	pt is priority 7 (highest priority	interrupt)					
	•								
	•								
	• 001 = Interru	nt is priority 1							
		pt is priority i pt source is dis	abled						
bit 7-0		ted: Read as 'd							
	•								

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U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0		
—	CRCIP2	CRCIP1	CRCIP0		U2ERIP2	U2ERIP1	U2ERIP0		
bit 15							bit 8		
	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	11.0		
U-0	U1ERIP2	U1ERIP1	U1ERIP0	0-0	0-0	0-0	U-0		
bit 7	UTERIFZ	UIERIFI	UTERIFU				bit (
Legend: R = Readable	o hit	M = Mritabla	hit		optod bit roop				
		W = Writable		-	nented bit, read		0.00		
-n = Value at	PUR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	IOWN		
bit 15	Unimplemen	ted: Read as '	ז'						
bit 14-12	-	CRC Generate		nt Priority hite					
DIL 14-12									
	 111 = Interrupt is priority 7 (highest priority interrupt) • 								
	•								
	• 001 = Interrupt is priority 1								
		pt is priority 1 pt source is dis	abled						
bit 11		ted: Read as '							
bit 10-8	-	: UART2 Error		ity hite					
		pt is priority 7 (I	•						
	•		ingricor priority	interrupt)					
	•								
	• 001 = Interru	nt in priority 1							
			abled						
000 = Interrupt source is disabled									
hit 7	Unimplemen	ted: Read as '	ר'						
	•	ted: Read as '(ity bite					
	U1ERIP<2:0>	>: UART1 Error	Interrupt Prior	-					
	U1ERIP<2:0>		Interrupt Prior	-					
	U1ERIP<2:0>	>: UART1 Error	Interrupt Prior	-					
bit 7 bit 6-4	U1ERIP<2:0> 111 = Interru •	: UART1 Error pt is priority 7 (I	Interrupt Prior	-					
	U1ERIP<2:0> 111 = Interru	: UART1 Error pt is priority 7 (I	Interrupt Prior nighest priority	-					

REGISTER 7-34: IPC16: INTERRUPT PRIORITY CONTROL REGISTER 16

REGISTER 7-35: IPC18: INTERRUPT PRIORITY CONTROL REGISTER 18

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	_		—	—
bit 15							bit 8
11-0	11-0	11-0	11_0	11_0	R/M_1	R/W_0	R/W_0

0-0	0-0	0-0	0-0	0-0	R/W-1	R/W-0	R/W-0
—	—	—	—	—	LVDIP2	LVDIP1	LVDIP0
bit 7							bit 0

Legend:

Legenu.			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3 Unimplemented: Read as '0'

- bit 2-0 LVDIP<2:0>: Low-Voltage Detect Interrupt Priority bits 111 = Interrupt is priority 7 (highest priority interrupt)
 - •
 - 001 = Interrupt is priority 1 000 = Interrupt source is disabled

REGISTER 7-36: IPC19: INTERRUPT PRIORITY CONTROL REGISTER 19

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
—	CTMUIP2	CTMUIP1	CTMUIP0	_	—	—	—
bit 7	•						bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-7 Unimplemented: Read as	'0'
---------------------------------	-----

bit 6-4	CTMUIP<2:0>: CTMU Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is priority 1
	000 = Interrupt source is disabled
bit 3-0	Unimplemented: Read as '0'

	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
_	U3TXIP2	U3TXIP1	U3TXIP0		U3RXIP2	U3RXIP1	U3RXIP0
bit 15	·		•			•	bit
U-0	R/W-1	R/W-0	R/W-0	U-0	U-0	U-0	U-0
_	U3ERIP2	U3ERIP1	U3ERIP0	_	_	—	
bit 7					L		bit
Legend:							
R = Readab	ole bit	W = Writable	bit	U = Unimpler	mented bit, read	l as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown
	•						
	• 001 = Interru	nt is priority 1					
	• 001 = Interruj 000 = Interruj	pt is priority 1 pt source is dis	abled				
bit 11	000 = Interru Unimplemen	pt source is dis ted: Read as '(כ'				
	000 = Interru Unimplemen U3RXIP<2:0> 111 = Interru	pt source is dis ted: Read as ' >: UART3 Rece pt is priority 7 (I	_D ' biver Interrupt l highest priority	•			
bit 11 bit 10-8 bit 7	000 = Interrup Unimplemen U3RXIP<2:0> 111 = Interrup	pt source is dis ted: Read as '(>: UART3 Rece pt is priority 7 (I pt is priority 1	_o , iver Interrupt l highest priority abled	•			
bit 10-8	000 = Interrup Unimplemen U3RXIP<2:0> 111 = Interrup	pt source is dis ted: Read as '(>: UART3 Rece pt is priority 7 (I pt is priority 1 pt source is dis ted: Read as '(>: UART3 Error pt is priority 7 (I	^{D'} highest priority abled D' Interrupt Prior highest priority	rity bits			

REGISTER 7-37: IPC20: INTERRUPT PRIORITY CONTROL REGISTER 20

REGISTER 7-38: IPC21: INTERRUPT PRIORITY CONTROL REGISTER 21

	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
_	U4ERIP2	U4ERIP1	U4ERIP0		USB1IP2	USB1IP1	USB1IP0
bit 15					1		bit
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
	MI2C3IP2	MI2C3IP1	MI2C3IP0		SI2C3IP2	SI2C3IP1	SI2C3IP0
bit 7							bit
Legend:							
R = Readabl	le bit	W = Writable I	oit	U = Unimplem	nented bit, read	l as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	iown
bit 15	Unimplemen	ted: Read as 'd)'				
bit 14-12	U4ERIP<2:0>	UART4 Error	Interrupt Prior	ity bits			
	111 = Interrup	ot is priority 7 (h	nighest priority	interrupt)			
	•						
	•						
	001 = Interrup	ot is priority 1					
	000 = Interrup	ot source is disa	abled				
bit 11	Unimplemen	ted: Read as '0)'				
bit 10-8	USB1IP<2:0>	•: USB1 (USB (DTG) Interrupt	Priority bits			
	111 = Interrup	ot is priority 7 (h	nighest priority	interrupt)			
	•						
	•						
	• 001 = Interrup	• •					
	000 = Interrup	ot source is disa					
	000 = Interrup Unimplemen	ot source is disa ted: Read as 'o)'				
	000 = Interru Unimplemen MI2C3IP<2:0	ot source is disa ted: Read as 'o >: Master I2C3)' Event Interrup	-			
	000 = Interru Unimplemen MI2C3IP<2:0	ot source is disa ted: Read as 'o)' Event Interrup	-			
	000 = Interru Unimplemen MI2C3IP<2:0	ot source is disa ted: Read as 'o >: Master I2C3)' Event Interrup	-			
bit 7 bit 6-4	000 = Interru Unimplemen MI2C3IP<2:0 111 = Interru •	ot source is disa ted: Read as 'c >: Master I2C3 ot is priority 7 (h)' Event Interrup	-			
	000 = Interrup Unimplement MI2C3IP<2:0 111 = Interrup	ot source is disa ted: Read as 'co >: Master I2C3 ot is priority 7 (h	,' Event Interrup highest priority	-			
bit 6-4	000 = Interrup Unimplement MI2C3IP<2:0 111 = Interrup	ot source is disa ted: Read as 'o >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa	, [,] Event Interrup nighest priority abled	-			
bit 6-4 bit 3	000 = Interrup Unimplemen MI2C3IP<2:0 111 = Interrup	ot source is disa ted: Read as '0 >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa ted: Read as '0	, [,] Event Interrup nighest priority abled ,	interrupt)			
	000 = Interrup Unimplemen MI2C3IP<2:03 111 = Interrup	ot source is disa ted: Read as '0 >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa ted: Read as '0 >: Slave I2C3 E)' Event Interrup highest priority abled)' vent Interrupt	interrupt) Priority bits			
bit 6-4 bit 3	000 = Interrup Unimplemen MI2C3IP<2:03 111 = Interrup	ot source is disa ted: Read as '0 >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa ted: Read as '0)' Event Interrup highest priority abled)' vent Interrupt	interrupt) Priority bits			
bit 6-4 bit 3	000 = Interrup Unimplemen MI2C3IP<2:03 111 = Interrup	ot source is disa ted: Read as '0 >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa ted: Read as '0 >: Slave I2C3 E)' Event Interrup highest priority abled)' vent Interrupt	interrupt) Priority bits			
bit 6-4 bit 3	000 = Interrup Unimplemen MI2C3IP<2:03 111 = Interrup	ot source is disa ted: Read as '0 >: Master I2C3 ot is priority 7 (h ot is priority 1 ot source is disa ted: Read as '0 >: Slave I2C3 E ot is priority 7 (h)' Event Interrup highest priority abled)' vent Interrupt	interrupt) Priority bits			

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
	SPI3IP2	SPI3IP1	SPI3IP0		SPF3IP2	SPF3IP1	SPF3IP0
bit 15			1				bit 8
U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
0-0	U4TXIP2	U4TXIP1	U4TXIP0	0-0	U4RXIP2	U4RXIP1	U4RXIP0
bit 7	0417/112	0417/111	0417110		0410/11 2	0410/11 1	bit (
Legend:							
R = Readat	ole bit	W = Writable	bit	U = Unimple	mented bit, read	d as '0'	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is cle	eared	x = Bit is unkr	nown
bit 15	-	ited: Read as '					
bit 14-12		: SPI3 Event In					
	111 = Interru	pt is priority 7 (highest priority	interrupt)			
	•						
	•	nt in mainaite d					
	001 = Interru	pt is priority i pt source is dis	abled				
bit 11		ited: Read as '					
bit 10-8	-	SPI3 Fault In		bits			
		pt is priority 7 (
	•						
	•						
	001 = Interru						
		pt source is dis					
bit 7	-	ted: Read as '					
bit 6-4		: UART4 Trans					
	111 = Interru	pt is priority 7 (highest priority	interrupt)			
	•						
	•						
	001 = Interru 000 = Interru	pt is priority i pt source is dis	abled				
bit 3		ited: Read as '					
bit 2-0	-	>: UART4 Rece		Priority bits			
		pt is priority 7 (-			
	•			• •			
	•						
	•						
	• 001 = Interru	pt is priority 1 pt source is dis					

REGISTER 7-39: IPC22: INTERRUPT PRIORITY CONTROL REGISTER 22

REGISTER 7-40: IPC23: INTERRUPT PRIORITY CONTROL REGISTER 23

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—		—	—	—	—	—
bit 15							bit 8

U-0	R/W-1	R/W-0	R/W-0	U-0	R/W-1	R/W-0	R/W-0
—	IC9IP2	IC9IP1	IC9IP0	—	OC9IP2	OC9IP1	OC9IP0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-7	Unimplemented: Read as '0'
bit 6-4	IC9IP<2:0>: Input Capture Channel 9 Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is priority 1
	000 = Interrupt source is disabled
bit 3	Unimplemented: Read as '0'
bit 2-0	OC9IP<2:0>: Output Compare Channel 9 Interrupt Priority bits
	111 = Interrupt is priority 7 (highest priority interrupt)
	•
	•
	•
	001 = Interrupt is priority 1
	000 = Interrupt source is disabled
	•

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REGISTER 7-41: IPC25: INTERRUPT PRIORITY CONTROL REGISTER 25

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—		—	—	—	—
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-0	R/W-0
_	—	—	—	—	GFX1IP2	GFX1IP1	GFX1IP0
bit 7		-		•		•	bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 15-3 Unimplemented: Read as '0'

bit 2-0 **GFX1IP<2:0>:** Graphics 1 Interrupt Priority bits

- 111 = Interrupt is priority 7 (highest priority interrupt)
- .

• 001 = Interrupt is priority 1

000 = Interrupt source is disabled

REGISTER 7-42: INTTREG: INTERRUPT CONTROLLER TEST REGISTER

R-0, HSC	U-0	R/W-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
CPUIRQ	—	VHOLD	—	ILR3	ILR2	ILR1	ILR0
bit 15			•				bit 8

U-0	R-0, HSC						
—	VECNUM6	VECNUM5	VECNUM4	VECNUM3	VECNUM2	VECNUM1	VECNUM0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	CPUIRQ: Interrupt Request from Interrupt Controller CPU bit
	1 = An interrupt request has occurred but has not yet been Acknowledged by the CPU; this happens when the CPU priority is higher than the interrupt priority
	0 = No interrupt request is unacknowledged
bit 14	Unimplemented: Read as '0'
bit 13	VHOLD: Vector Number Capture Configuration bit
	 1 = The VECNUM bits contain the value of the highest priority pending interrupt 0 = The VECNUM bits contain the value of the last Acknowledged interrupt (i.e., the last interrupt that has occurred with higher priority than the CPU, even if other interrupts are pending)
bit 12	Unimplemented: Read as '0'
bit 11-8	ILR<3:0>: New CPU Interrupt Priority Level bits
	1111 = CPU Interrupt Priority Level is 15
	0001 = CPU Interrupt Priority Level is 1 0000 = CPU Interrupt Priority Level is 0
bit 7	Unimplemented: Read as '0'
bit 6-0	VECNUM<5:0>: Vector Number of Pending Interrupt or Last Acknowledged Interrupt bits
	 VHOLD = 1: The VECNUM bits indicate the vector number (from 0 to 118) of the last interrupt to occur VHOLD = 0: The VECNUM bits indicate the vector number (from 0 to 118) of the interrupt request currently being handled

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7.4 Interrupt Setup Procedures

7.4.1 INITIALIZATION

To configure an interrupt source:

- Set the NSTDIS (INTCON1<15>) control bit if nested interrupts are not desired.
- Select the user-assigned priority level for the interrupt source by writing the control bits in the appropriate IPCx register. The priority level will depend on the specific application and type of interrupt source. If multiple priority levels are not desired, the IPCx register control bits for all enabled interrupt sources may be programmed to the same non-zero value.

Note: At a device Reset, the IPCx registers are initialized, such that all user interrupt sources are assigned to priority level 4.

- 3. Clear the interrupt flag status bit associated with the peripheral in the associated IFSx register.
- 4. Enable the interrupt source by setting the interrupt enable control bit associated with the source in the appropriate IECx register.

7.4.2 INTERRUPT SERVICE ROUTINE (ISR)

The method that is used to declare an Interrupt Service Routine (ISR) and initialize the IVT with the correct vector address will depend on the programming language (i.e., 'C' or assembler) and the language development toolsuite that is used to develop the application. In general, the user must clear the interrupt flag in the appropriate IFSx register for the source of the interrupt that the ISR handles. Otherwise, the ISR will be re-entered immediately after exiting the routine. If the ISR is coded in assembly language, it must be terminated using a RETFIE instruction to unstack the saved PC value, SRL value and old CPU priority level.

7.4.3 TRAP SERVICE ROUTINE (TSR)

A Trap Service Routine (TSR) is coded like an ISR, except that the appropriate trap status flag in the INTCON1 register must be cleared to avoid re-entry into the TSR.

7.4.4 INTERRUPT DISABLE

All user interrupts can be disabled using the following procedure:

- 1. Push the current SR value onto the software stack using the PUSH instruction.
- 2. Force the CPU to priority level 7 by inclusive ORing the value 0Eh with SRL.

To enable user interrupts, the POP instruction may be used to restore the previous SR value.

Note that only user interrupts with a priority level of 7 or less can be disabled. Trap sources (Level 8-15) cannot be disabled.

The DISI instruction provides a convenient way to disable interrupts of priority levels, 1-6, for a fixed period of time. Level 7 interrupt sources are not disabled by the DISI instruction.

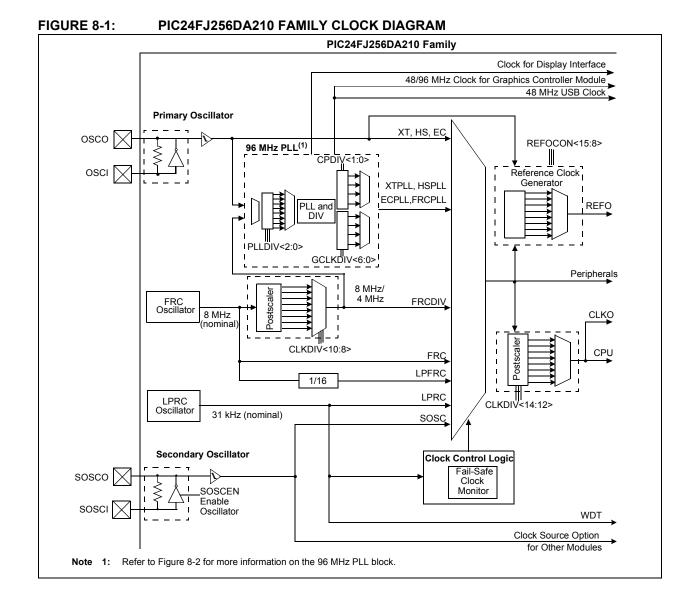
8.0 OSCILLATOR CONFIGURATION

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 6. "Oscillator" (DS39700). The information in this data sheet supersedes the information in the FRM.

The oscillator system for PIC24FJ256DA210 family devices has the following features:

 A total of four external and internal oscillator options as clock sources, providing 11 different clock modes

- An on-chip PLL block to boost internal operating frequency on select internal and external oscillator sources, and to provide a precise clock source for peripherals, such as USB and graphics
- Software controllable switching between various clock sources
- Software controllable postscaler for selective clocking of CPU for system power savings
- A Fail-Safe Clock Monitor (FSCM) that detects clock failure and permits safe application recovery or shutdown
- A separate and independently configurable system clock output for synchronizing external hardware
- A simplified diagram of the oscillator system is shown in Figure 8-1.



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8.1 CPU Clocking Scheme

The system clock source can be provided by one of four sources:

- Primary Oscillator (POSC) on the OSCI and OSCO pins
- Secondary Oscillator (SOSC) on the SOSCI and SOSCO pins
- · Fast Internal RC (FRC) Oscillator
- · Low-Power Internal RC (LPRC) Oscillator

The primary oscillator and FRC sources have the option of using the internal 24x PLL block, which generates the USB module clock, the Graphics module clock and a separate system clock through the 96 MHZ PLL. Refer to **Section 8.5 "96 MHz PLL Block"** for additional information.

The internal FRC provides an 8 MHz clock source. It can optionally be reduced by the programmable clock divider to provide a range of system clock frequencies.

The selected clock source generates the processor and peripheral clock sources. The processor clock source is divided by two to produce the internal instruction cycle clock, FcY. In this document, the instruction cycle clock is also denoted by Fosc/2. The internal instruction cycle clock, Fosc/2, can be provided on the OSCO I/O pin for some operating modes of the primary oscillator.

8.2 Initial Configuration on POR

The oscillator source (and operating mode) that is used at a device Power-on Reset (POR) event is selected using Configuration bit settings. The oscillator Configuration bit settings are located in the Configuration registers in the program memory (refer to **Section 27.1 "Configuration Bits"** for further details). The Primary Oscillator Configuration bits, POSCMD<1:0> (Configuration Word 2<1:0>) and the Initial Oscillator Select Configuration bits, FNOSC<2:0> (Configuration Word 2<10:8>), select the oscillator source that is used at a POR. The FRC primary oscillator with postscaler (FRCDIV) is the default (unprogrammed) selection. The secondary oscillator, or one of the internal oscillators, may be chosen by programming these bit locations.

The Configuration bits allow users to choose between the various clock modes, shown in Table 8-1.

8.2.1 CLOCK SWITCHING MODE CONFIGURATION BITS

The FCKSM Configuration bits (Configuration Word 2<7:6>) are used to jointly configure device clock switching and the Fail-Safe Clock Monitor (FSCM). Clock switching is enabled only when FCKSM1 is programmed ('0'). The FSCM is enabled only when FCKSM<1:0> are both programmed ('00').

Oscillator Mode	Oscillator Source	POSCMD<1:0>	FNOSC<2:0>	Notes
Fast RC Oscillator with Postscaler (FRCDIV)	Internal	11	111	1, 2
FRC Oscillator/16 (500 KHz)	Internal	11	110	1
Low-Power RC Oscillator (LPRC)	Internal	11	101	1
Secondary (Timer1) Oscillator (SOSC)	Secondary	11	100	1
Primary Oscillator (XT) with PLL Module (XTPLL)	Primary	01	011	-
Primary Oscillator (EC) with PLL Module (ECPLL)	Primary	00	011	1
Primary Oscillator (HS)	Primary	10	010	_
Primary Oscillator (XT)	Primary	01	010	_
Primary Oscillator (EC)	Primary	00	010	1
Fast RC Oscillator with PLL Module (FRCPLL)	Internal	11	001	1
Fast RC Oscillator (FRC)	Internal	11	000	1

TABLE 8-1: CONFIGURATION BIT VALUES FOR CLOCK SELECTION

Note 1: OSCO pin function is determined by the OSCIOFCN Configuration bit.

2: This is the default oscillator mode for an unprogrammed (erased) device.

8.3 Control Registers

The following five Special Function Registers control the operation of the oscillator:

- OSCCON
- CLKDIV
- OSCTUN
- CLKDIV2
- REFOCON

The OSCCON register (Register 8-1) is the main control register for the oscillator. It controls clock source switching and allows the monitoring of clock sources.

The CLKDIV register (Register 8-2) controls the features associated with Doze mode, as well as the postscaler for the FRC oscillator.

The OSCTUN register (Register 8-3) allows the user to fine tune the FRC oscillator over a range of approximately $\pm 1.5\%$.

The CLKDIV2 register (Register 8-4) controls the clock to the display glass, with the frequency ranging from 750 kHz to 96 MHz.

The REFOCON register (Register 8-5) controls the frequency of the reference clock out.

REGISTER 8-1: OSCCON: OSCILLATOR CONTROL REGISTER

U-0	R-x, HSC ⁽¹⁾	R-x, HSC ⁽¹⁾	R-x, HSC ⁽¹⁾	U-0	R/W-x ⁽¹⁾	R/W-x ⁽¹⁾	R/W-x ⁽¹⁾
_	COSC2	COSC1	COSC0	_	NOSC2	NOSC1	NOSC0
bit 15							bit 8

R/S-0	R/W-0	R-0, HSC ⁽³⁾	U-0	R/C-0, HS	R/W-0	R/W-0	R/W-0
CLKLOCK	IOLOCK ⁽²⁾	LOCK	_	CF	POSCEN	SOSCEN	OSWEN
bit 7							bit 0

Legend:	C = Clearable bit	S = Settable bit	HSC = Hardware Settable/Clearable bit			
R = Readable bit	W = Writable bit	U = Unimplemented bi	t, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			
HS = Hardware Settable bit						

bit 15 Unimplemented: Read as '0'

bit 14-12 COSC<2:0>: Current Oscillator Selection bits⁽¹⁾

- 111 = Fast RC Oscillator with Postscaler (FRCDIV)
- 110 = Fast RC/16 Oscillator
- 101 = Low-Power RC Oscillator (LPRC)
- 100 = Secondary Oscillator (SOSC)
- 011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL)
- 010 = Primary Oscillator (XT, HS, EC)
- 001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL)
- 000 = Fast RC Oscillator (FRC)
- bit 11 Unimplemented: Read as '0'
- Note 1: Reset values for these bits are determined by the FNOSC Configuration bits.
 - 2: The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1', once the IOLOCK bit is set, it cannot be cleared.
 - 3: Also resets to '0' during any valid clock switch or whenever a non PLL Clock mode is selected.

REGISTE	R 8-1: OSCCON: OSCILLATOR CONTROL REGISTER (CONTINUED)
bit 10-8	NOSC<2:0>: New Oscillator Selection bits ⁽¹⁾ 111 = Fast RC Oscillator with Postscaler (FRCDIV) 110 = Fast RC/16 Oscillator 101 = Low-Power RC Oscillator (LPRC) 100 = Secondary Oscillator (SOSC) 011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL) 010 = Primary Oscillator (XT, HS, EC) 001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL) 000 = Fast RC Oscillator (FRC)
bit 7	CLKLOCK: Clock Selection Lock Enabled bit
	If FSCM is enabled (FCKSM1 = 1): 1 = Clock and PLL selections are locked 0 = Clock and PLL selections are not locked and may be modified by setting the OSWEN bit If FSCM is disabled (FCKSM1 = 0): Clock and PLL selections are never locked and may be modified by setting the OSWEN bit.
bit 6	IOLOCK: I/O Lock Enable bit ⁽²⁾
	1 = I/O lock is active 0 = I/O lock is not active
bit 5	LOCK: PLL Lock Status bit ⁽³⁾
	 1 = PLL module is in lock or PLL module start-up timer is satisfied 0 = PLL module is out of lock, PLL start-up timer is running or PLL is disabled
bit 4	Unimplemented: Read as '0'
bit 3	CF: Clock Fail Detect bit
	 1 = FSCM has detected a clock failure 0 = No clock failure has been detected
bit 2	POSCEN: Primary Oscillator Sleep Enable bit
	 1 = Primary Oscillator continues to operate during Sleep mode 0 = Primary Oscillator is disabled during Sleep mode
bit 1	SOSCEN: 32 kHz Secondary Oscillator (SOSC) Enable bit
	1 = Enable the Secondary Oscillator0 = Disable the Secondary Oscillator
bit 0	OSWEN: Oscillator Switch Enable bit
	 1 = Initiate an oscillator switch to the clock source specified by the NOSC<2:0> bits 0 = Oscillator switch is complete
Note 1:	Reset values for these bits are determined by the FNOSC Configuration bits.
2:	The state of the IOLOCK bit can only be changed once an unlocking sequence has been executed. In addition, if the IOL1WAY Configuration bit is '1', once the IOLOCK bit is set, it cannot be cleared.

3: Also resets to '0' during any valid clock switch or whenever a non PLL Clock mode is selected.

	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-1
ROI	DOZE2	DOZE1	DOZE0	DOZEN ⁽¹⁾	RCDIV2	RCDIV1	RCDIV0
oit 15		•				•	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0
CPDIV1	CPDIV0	PLLEN	G1CLKSEL	<u> </u>			
oit 7							bit (
Legend:							
R = Readabl	e bit	W = Writable	bit	U = Unimplem	ented bit, read	d as '0'	
n = Value at	POR	'1' = Bit is set	t	'0' = Bit is clea	ired	x = Bit is unkr	nown
oit 15		r on Interrupt b					
			ZEN bit and res t on the DOZEI	et the CPU peri	pheral clock r	atio to 1:1	
oit 14-12	•		al Clock Ratio S				
51(14 12	111 = 1:128	or or enprior					
	110 = 1:64						
	101 = 1:32						
	100 = 1:16						
	011 = 1:8 010 = 1:4						
	010 = 1.4 001 = 1.2						
	000 = 1:1						
oit 11	DOZEN: DOZ	ZE Enable bit ⁽¹)				
	1 = DOZE<2	:0> bits specify	/ the CPU perip	heral clock ratio)		
	•	•	atio is set to 1:1				
oit 10-8		FRC Postsca					
		kHz (divide by					
		Hz (divide by 64					
		Hz (divide by 32 Hz (divide by 10					
	011 = 1 MHz		0)				
	010 = 2 MHz						
	001 = 4 MHz	· · · ·					
	000 = 8 MHz	(divide by 1)					
oit 7-6		•		stscaler select f	rom 32 MHz o	clock branch)	
	11 = 4 MHz	: (divide by 8) ⁽²	2)				
		(divide by 4) ⁽²					
		Iz (divide by 2)					

2: This setting is not allowed while the USB module is enabled.

REGISTER 8-2: CLKDIV: CLOCK DIVIDER REGISTER (CONTINUED)

bit 5	PLLEN: 96 MHz PLL Enable bit
	The 96 MHz PLL must be enabled when the USB or graphics controller module is enabled. This control bit can be overridden by the PLL96MHZ (Configuration Word 2 <11>) Configuration bit. 1 = Enable the 96 MHz PLL for USB, graphics controller or HSPLL/ECPLL/FRCPLL operation 0 = Disable the 96 MHz PLL
bit 4	G1CLKSEL: Display Controller Module Clock Select bit
	 1 = Use the 96 MHz clock as a graphics controller module clock 0 = Use the 48 MHz clock as a graphics controller module clock
	0 - Ose the 40 Minz clock as a graphics controller module clock

- bit 3-0 Unimplemented: Read as '0'
- **Note 1:** This bit is automatically cleared when the ROI bit is set and an interrupt occurs.
 - 2: This setting is not allowed while the USB module is enabled.

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
_	—			_	_	—	—	
bit 15					- -		bit 8	
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_	_	TUN5 ⁽¹⁾	TUN4 ⁽¹⁾	TUN3 ⁽¹⁾	TUN2 ⁽¹⁾	TUN1 ⁽¹⁾	TUN0 ⁽¹⁾	
bit 7	L					·	bit 0	
Legend:								
R = Readab	le bit	W = Writable	bit	U = Unimplen	nented bit, read	l as '0'		
-n = Value a	t POR	'1' = Bit is set	set '0' = Bit is cleared			x = Bit is unknown		
bit 15-6	Unimplemen	ted: Read as '	0'					
bit 5-0	TUN<5:0>: F	RC Oscillator T	uning bits ⁽¹⁾					
		aximum freque	ncy deviation					
	011110 =							
	000001 =							
		enter frequency	/, oscillator is ru	unning at factor	ry calibrated fre	quency		
	111111 =							
	•							
	100001 =							
	100000 = M	inimum frequer	ncy deviation					

REGISTER 8-3: OSCTUN: FRC OSCILLATOR TUNE REGISTER

Note 1: Increments or decrements of TUN<5:0> may not change the FRC frequency in equal steps over the FRC tuning range and may not be monotonic.

REGISTER 8-4: CLKDIV2: CLOCK DIVIDER REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
GCLKDIV6(1)	GCLKDIV5 ⁽¹⁾	GCLKDIV4 ⁽¹⁾	GCLKDIV3 ⁽¹⁾	GCLKDIV2 ⁽¹⁾	GCLKDIV1 ⁽¹⁾	GCLKDIV0 ⁽¹⁾	_
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	
bit 7							bit C
Legend:							
R = Readable	bit	W = Writable b	bit	U = Unimplem	ented bit, read	as '0'	
-n = Value at a	II Resets	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkno	wn
	1100000 = (9	97) 2.82 MHz (c 96) 2.91 MHz (c 95) 2.95 MHz (c	livide by 33); fro		nent the divisor	by 1.00	
	1000000 = (6	65) 5.49 MHz (c 64) 5.65 MHz (c 63) 5.73 MHz (c	livide by 17.00)	; from here, inc	rement the divi	sor by 0.50	
bit 8-0	$\begin{array}{l} 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 $	8) 54.86 MHz (c 2) 64.00 MHz (c 1) 76.80 MHz (c 0) 96.00 MHz (c ed: Read as '0	livide by 1.5) livide by 1.25); livide by 1)	from here, incre	ement the divis	or by 0.25	

Note 1: These bits take effect only when the 96 MHz PLL is enabled.

8.4 Clock Switching Operation

With few limitations, applications are free to switch between any of the four clock sources (POSC, SOSC, FRC and LPRC) under software control and at any time. To limit the possible side effects that could result from this flexibility, PIC24F devices have a safeguard lock built into the switching process.

Note: The Primary Oscillator mode has three different submodes (XT, HS and EC) which are determined by the POSCMDx Configuration bits. While an application can switch to and from Primary Oscillator mode in software, it cannot switch between the different primary submodes without reprogramming the device.

8.4.1 ENABLING CLOCK SWITCHING

To enable clock switching, the FCKSM1 Configuration bit in CW2 must be programmed to '0'. (Refer to **Section 27.1 "Configuration Bits"** for further details.) If the FCKSM1 Configuration bit is unprogrammed ('1'), the clock switching function and Fail-Safe Clock Monitor function are disabled. This is the default setting.

The NOSCx (OSCCON<10:8>) control bits do not control the clock selection when clock switching is disabled. However, the COSCx (OSCCON<14:12>) control bits will reflect the clock source selected by the FNOSCx Configuration bits.

The OSWEN (OSCCON<0>) control bit has no effect when clock switching is disabled; It is held at '0' at all times.

8.4.2 OSCILLATOR SWITCHING SEQUENCE

At a minimum, performing a clock switch requires this basic sequence:

- If desired, read the COSCx (OSCCON<14:12>) control bits to determine the current oscillator source.
- 2. Perform the unlock sequence to allow a write to the OSCCON register high byte.
- Write the appropriate value to the NOSCx (OSCCON<10:8>) control bits for the new oscillator source.
- 4. Perform the unlock sequence to allow a write to the OSCCON register low byte.
- 5. Set the OSWEN bit to initiate the oscillator switch.

Once the basic sequence is completed, the system clock hardware responds automatically as follows:

- 1. The clock switching hardware compares the COSCx bits with the new value of the NOSCx bits. If they are the same, then the clock switch is a redundant operation. In this case, the OSWEN bit is cleared automatically and the clock switch is aborted.
- If a valid clock switch has been initiated, the LOCK (OSCCON<5>) and CF (OSCCON<3>) bits are cleared.
- The new oscillator is turned on by the hardware if it is not currently running. If a crystal oscillator must be turned on, the hardware will wait until the OST expires. If the new source is using the PLL, then the hardware waits until a PLL lock is detected (LOCK = 1).
- 4. The hardware waits for 10 clock cycles from the new clock source and then performs the clock switch.
- 5. The hardware clears the OSWEN bit to indicate a successful clock transition. In addition, the NOSCx bit values are transferred to the COSCx bits.
- The old clock source is turned off at this time, with the exception of LPRC (if WDT or FSCM are enabled) or SOSC (if SOSCEN remains set).
 - Note 1: The processor will continue to execute code throughout the clock switching sequence. Timing-sensitive code should not be executed during this time.
 - 2: Direct clock switches between any Primary Oscillator mode with PLL and FRCPLL modes are not permitted. This applies to clock switches in either direction. In these instances, the application must switch to FRC mode as a transition clock source between the two PLL modes.

A recommended code sequence for a clock switch includes the following:

- 1. Disable interrupts during the OSCCON register unlock and write sequence.
- Execute the unlock sequence for the OSCCON high byte by writing 78h and 9Ah to OSCCON<15:8> in two back-to-back instructions.
- 3. Write new oscillator source to the NOSCx bits in the instruction immediately following the unlock sequence.
- Execute the unlock sequence for the OSCCON low byte by writing 46h and 57h to OSCCON<7:0> in two back-to-back instructions.
- 5. Set the OSWEN bit in the instruction immediately following the unlock sequence.
- 6. Continue to execute code that is not clock-sensitive (optional).
- 7. Invoke an appropriate amount of software delay (cycle counting) to allow the selected oscillator and/or PLL to start and stabilize.
- Check to see if OSWEN is '0'. If it is, the switch was successful. If OSWEN is still set, then check the LOCK bit to determine the cause of failure.

The core sequence for unlocking the OSCCON register and initiating a clock switch is shown in Example 8-1.

EXAMPLE 8-1: BASIC CODE SEQUENCE FOR CLOCK SWITCHING IN ASSEMBLY

;Place the new oscillator selection in WO
;OSCCONH (high byte) Unlock Sequence
MOV #OSCCONH, w1
MOV #0x9A, w3
MOV.b w2, [w1]
MOV.b w3, [w1]
;Set new oscillator selection
MOV.b WREG, OSCCONH
;OSCCONL (low byte) unlock sequence
MOV #OSCCONL, w1
MOV #0x46, w2
MOV #0x57, w3
MOV.b w2, [w1]
MOV.b w3, [w1]
;Start oscillator switch operation
BSET OSCCON, #0

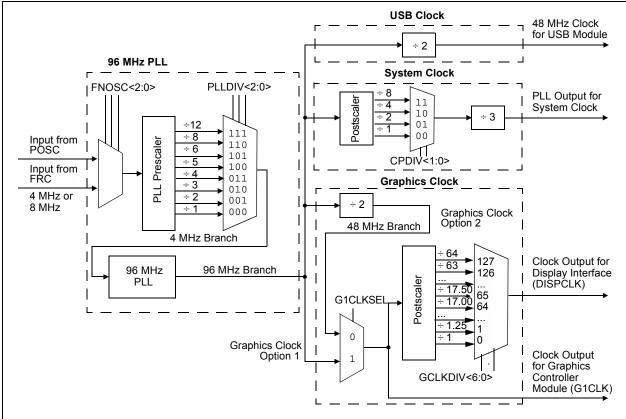
8.5 96 MHz PLL Block

The 96 MHz PLL block is implemented to generate the stable 48 MHz clock required for full-speed USB operation, a programmable clock output for the graphics controller module and the system clock from the same oscillator source. The 96 MHz PLL block is shown in Figure 8-2.

The 96 MHz PLL block requires a 4 MHz input signal; it uses this to generate a 96 MHz signal from a fixed, 24x PLL. This is, in turn, divided into three branches. The first branch generates the USB clock, the second branch generates the system clock and the third branch generates the graphics clock. The 96 MHz PLL block can be enabled and disabled using the PLL96MHZ Configuration bit (Configuration Word<11>) or through the PLLEN (CLKDIV<5>) control bit when the PLL96MHZ Configuration bit is not set. Note that the PLL96MHZ Configuration bit and PLLEN register bit are available only for PIC24F devices with USB and graphics controller modules.

The 96 MHz PLL prescaler does not automatically sense the incoming oscillator frequency. The user must manually configure the PLL divider to generate the required 4 MHz output, using the PLLDIV<2:0> Configuration bits (Configuration Word 2<14:12> in most devices).

FIGURE 8-2: 96 MHz PLL BLOCK



8.5.1 SYSTEM CLOCK GENERATION

The system clock is generated from the 96 MHz branch using a configurable postscaler/divider to generate a range of frequencies for the system clock multiplexer. The output of the multiplexer is further passed through a fixed divide-by-3 divider and the final output is used as the system clock. Figure 8-2 shows this logic in the system clock sub-block. Since the source is a 96 MHz signal, the possible system clock frequencies are listed in Table 8-2. The available system clock options are always the same, regardless of the setting of the PLLDIV Configuration bits.

TABLE 8-2: SYSTEM CLOCK OPTIONS FOR 96 MHz PLL BLOCK

MCU Clock Division (CPDIV<1:0>)	System Clock Frequency (Instruction Rate in MIPS)
None (00)	32 MHz (16)
÷2 (01)	16 MHz (8)
÷4 (10)	8 MHz (4) ⁽¹⁾
÷8 (11)	4 MHz (2) ⁽¹⁾

Note 1: These options are not compatible with USB operation. They may be used whenever the PLL branch is selected and the USB module is disabled.

8.5.2 USB CLOCK GENERATION

In the USB-On-The-Go module in PIC24FJ256DA210 family of devices, the primary oscillator with the PLL block can be used as a valid clock source for USB operation. The FRC oscillator (implemented with $\pm 0.25\%$ accuracy) can be combined with a PLL block, providing another option for a valid USB clock source. There is no provision to provide a separate external 48 MHz clock to the USB module. The USB module sources its

clock signal from 96 MHz PLL. Due to the requirement that a 4 MHz input must be provided to generate the 96 MHz signal, the oscillator operation is limited to a range of possible values. Table 8-3 shows the valid oscillator configurations (i.e., ECPLL, HSPLL, XTPLL and FRCPLL) for USB operation. This sets the correct PLLDIV configuration for the specified oscillator frequency and the output frequency of the USB clock branch is always 48 MHz.

TABLE 8-3:	VALID OSCILLATOR CONFIGURATIONS FOR USB OPERATIONS

Input Oscillator Frequency	Clock Mode	PLL Division (PLLDIV<2:0>)
48 MHz	ECPLL	÷12 (111)
32 MHz	HSPLL, ECPLL	÷8(110)
24 MHz	HSPLL, ECPLL	÷6 (101)
20 MHz	HSPLL, ECPLL	÷5 (100)
16 MHz	HSPLL, ECPLL	÷4 (011)
12 MHz	HSPLL, ECPLL	÷3 (010)
8 MHz	ECPLL, HSPLL, XTPLL, FRCPLL	÷2 (001)
4 MHz	ECPLL, HSPLL, XTPLL, FRCPLL	÷1 (000)

Note: For USB devices, the use of a primary oscillator or external clock source, with a frequency above 32 MHz, does not imply that the device's system clock can be run at the same speed when the USB module is not used. The maximum system clock for all PIC24F devices is 32 MHz.

8.5.3 CONSIDERATIONS FOR USB OPERATION

When using the USB On-The-Go module in PIC24FJ256DA210 family devices, users must always observe these rules in configuring the system clock:

- For USB operation, the selected clock source (EC, HS or XT) must meet the USB clock tolerance requirements.
- The Primary Oscillator/PLL modes are the only oscillator configurations that permit USB operation. There is no provision to provide a separate external clock source to the USB module.
- While the FRCPLL Oscillator mode is used for USB applications, users must always ensure that the FRC source is configured to provide a frequency of 4 MHz or 8 MHz (RCDIV<2:0> = 001 or 000) and that the USB PLL prescaler is configured appropriately.

All other oscillator modes are available; however, USB operation is not possible when these modes are selected. They may still be useful in cases where other power levels of operation are desirable and the USB module is not needed (e.g., the application is sleeping and waiting for a bus attachment).

8.5.4 GRAPHICS CLOCK GENERATION

Two stable clock signals are generated for the graphics controller in the PIC24FJ256DA210 family of devices. The first clock is for the graphics controller module logic and the second clock is for the display module interface logic that generates the signals for the display glass. Figure 8-2 shows this logic in the graphics clock sub-block. Both clock signals are generated either from the Graphics Clock Option 1 (96 MHz branch) or the Graphics Clock Option 2 (48 MHz branch). Selection is set in the multiplexer using the G1CLKSEL (CLKDIV<4>) control bit. Graphics controller module logic directly uses the output of that multiplexer while the display module interface clock is further conditioned through a postscaler to generate 128 possible frequencies. The final clock output signal is selected through a multiplexer using the GCLKDIV<6:0> (CLKDIV2<15:9>) control bits. The 128 selections vary in increments of 0.25, 0.5, and 1.0. Refer to Table 8-4 for details. Note that for applications that use the graphics controller (GFX) module, the 96 MHz PLL must be enabled.

GCLKDIV<6:0>	Frequency Divisor	Display Module Clock Frequency 96 MHz Input (48 MHz Input)		
000000	1	96 MHz (48 MHz)		
0000001	1.25 (start incrementing by 0.25)	76.80 MHz (38.4 MHz)		
0000010	1.5	64 MHz (32 MHz)		
0111111	16.75	5.73 MHz (2.86 MHz)		
1000000	17	5.65 MHz (2.82 MHz)		
1000001	17.5 (start incrementing by 0.5)	5.49 MHz (2.74 MHz)		
1000010	18	5.33 MHz (2.66 MHz)		
1011111	32.5	2.95 MHz (1.47 MHz)		
1100000	33	2.91 MHz (1.45 MHz)		
1100001	34 (start incrementing by 1)	2.82 MHz (1.41 MHz)		
1100010	35	2.74 MHz (1.37 MHz)		
1111110	63	1.52 MHz (762 kHz)		
1111111	64	1.50 MHz (750 kHz)		

TABLE 8-4: DISPLAY MODULE CLOCK FREQUENCY DIVISION

8.6 Reference Clock Output

In addition to the CLKO output (Fosc/2) available in certain oscillator modes, the device clock in the PIC24FJ256DA210 family devices can also be configured to provide a reference clock output signal to a port pin. This feature is available in all oscillator configurations and allows the user to select a greater range of clock submultiples to drive external devices in the application.

This reference clock output is controlled by the REFOCON register (Register 8-5). Setting the ROEN bit (REFOCON<15>) makes the clock signal available on the REFO pin. The RODIV bits (REFOCON<11:8>) enable the selection of 16 different clock divider options.

The ROSSLP and ROSEL bits (REFOCON<13:12>) control the availability of the reference output during Sleep mode. The ROSEL bit determines if the oscillator on OSCI and OSCO, or the current system clock source, is used for the reference clock output. The ROSSLP bit determines if the reference source is available on REFO when the device is in Sleep mode.

To use the reference clock output in Sleep mode, both the ROSSLP and ROSEL bits must be set. The device clock must also be configured for one of the primary modes (EC, HS or XT); otherwise, if the POSCEN bit is not also set, the oscillator on OSCI and OSCO will be powered down when the device enters Sleep mode. Clearing the ROSEL bit allows the reference output frequency to change as the system clock changes during any clock switches.

REGISTER 8-5: REFOCON: REFERENCE OSCILLATOR CONTROL REGISTER

		DALO		D 44/ 0	D /// 0	DAALO	D AAL O
R/W-0	U-0	R/W-0	R/W-0 ROSEL ⁽¹⁾	R/W-0	R/W-0	R/W-0	R/W-0
ROEN bit 15	_	ROSSLP	RUSEL	RODIV3	RODIV2	RODIV1	RODIV0
							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_			—		—	_	—
bit 7							bit (
Legend:							
R = Readabl	le bit	W = Writable	bit	U = Unimplen	nented bit, rea	d as '0'	
-n = Value at	t POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkn	iown
bit 15	ROEN: Refer	ence Oscillator	Output Enable	e bit			
	1 = Reference	e oscillator ena	bled on REFO	pin			
	0 = Reference	e oscillator disa	abled				
bit 14	Unimplemen	ted: Read as '0)'				
bit 13	3 ROSSLP: Reference Oscillator Output Stop in Sleep bit						
		e oscillator con					
	0 = Reference	e oscillator is d	isabled in Slee	ep			
bit 12	ROSEL: Refe	erence Oscillato	or Source Seleo	ct bit ⁽¹⁾			
		oscillator used a					
					ects any clock	switching of the	device
bit 11-8	RODIV<3:0>:	Reference Os	cillator Divisor				
		e clock value di	vided by 32,76	8			
	1110 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38	8 4			
	1110 = Base 1101 = Base	e clock value di e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192	8 4			
	1110 = Base 1101 = Base 1100 = Base	e clock value di e clock value di e clock value di e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base	e clock value di e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 1000 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 256	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 1000 = Base 0111 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 256 vided by 128	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 1000 = Base 0111 = Base 0110 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 256 vided by 128 vided by 64	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 0111 = Base 0111 = Base 0110 = Base 0110 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 512 vided by 256 vided by 128 vided by 64 vided by 32	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 0111 = Base 0111 = Base 0110 = Base 0110 = Base 0101 = Base 0101 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 512 vided by 256 vided by 128 vided by 32 vided by 16	8 4			
	1110 = Base 1101 = Base 1001 = Base 1011 = Base 1001 = Base 1000 = Base 0111 = Base 0110 = Base 0110 = Base 0101 = Base 0100 = Base 0101 = Base 0011 = Base 0011 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 512 vided by 256 vided by 128 vided by 64 vided by 32 vided by 16 vided by 8 vided by 4	8 4			
	1110 = Base 1101 = Base 1100 = Base 1011 = Base 1010 = Base 1001 = Base 0111 = Base 0110 = Base 0110 = Base 0100 = Base 0011 = Base 0011 = Base 0011 = Base 0011 = Base 0011 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 512 vided by 256 vided by 128 vided by 64 vided by 32 vided by 16 vided by 8 vided by 4	8 4			
bit 7-0	1110 = Base 1101 = Base 100 = Base 1011 = Base 1010 = Base 1001 = Base 0111 = Base 0110 = Base 0101 = Base 0100 = Base 0011 = Base 0011 = Base 0011 = Base 0011 = Base 0011 = Base 0001 = Base	e clock value di e clock value di	vided by 32,76 vided by 16,38 vided by 8,192 vided by 4,096 vided by 2,048 vided by 1,024 vided by 512 vided by 512 vided by 256 vided by 128 vided by 4 vided by 8 vided by 4 vided by 2	8 4			

Note 1: Note that the crystal oscillator must be enabled using the FOSC<2:0> bits; the crystal maintains the operation in Sleep mode.

NOTES:

9.0 POWER-SAVING FEATURES

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 10. "Power-Saving Features" (DS39698). The information in this data sheet supersedes the information in the FRM.

The PIC24FJ256DA210 family of devices provides the ability to manage power consumption by selectively managing clocking to the CPU and the peripherals. In general, a lower clock frequency and a reduction in the number of circuits being clocked constitutes lower consumed power. All PIC24F devices manage power consumption in four different ways:

- Clock Frequency
- Instruction-Based Sleep and Idle modes
- Software Controlled Doze mode
- · Selective Peripheral Control in Software

Combinations of these methods can be used to selectively tailor an application's power consumption, while still maintaining critical application features, such as timing-sensitive communications.

9.1 Clock Frequency and Clock Switching

PIC24F devices allow for a wide range of clock frequencies to be selected under application control. If the system clock configuration is not locked, users can choose low-power or high-precision oscillators by simply changing the NOSC bits. The process of changing a system clock during operation, as well as limitations to the process, are discussed in more detail in **Section 8.0** "Oscillator Configuration".

9.2 Instruction-Based Power-Saving Modes

PIC24F devices have two special power-saving modes that are entered through the execution of a special PWRSAV instruction. Sleep mode stops clock operation and halts all code execution; Idle mode halts the CPU and code execution, but allows peripheral modules to continue operation. The assembly syntax of the PWRSAV instruction is shown in Example 9-1.

Sleep and Idle modes can be exited as a result of an enabled interrupt, WDT time-out or a device Reset. When the device exits these modes, it is said to "wake-up".

9.2.1 SLEEP MODE

Sleep mode has these features:

- The system clock source is shut down. If an on-chip oscillator is used, it is turned off.
- The device current consumption will be reduced to a minimum, provided that no I/O pin is sourcing current.
- The Fail-Safe Clock Monitor (FSCM) does not operate during Sleep mode since the system clock source is disabled.
- The LPRC clock will continue to run in Sleep mode if the WDT is enabled.
- The WDT, if enabled, is automatically cleared prior to entering Sleep mode.
- Some device features or peripherals may continue to operate in Sleep mode. This includes items such as the input change notification on the I/O ports or peripherals that use an external clock input. Any peripheral that requires the system clock source for its operation will be disabled in Sleep mode. Users can opt to make the voltage regulator enter standby mode on entering Sleep mode by clearing the VREGS bit (RCON<8>). This will decrease current consumption but will add a delay, TVREG, to the wake-up time. For this reason, applications that do not use the voltage regulator should set this bit.

The device will wake-up from Sleep mode on any of the these events:

- On any interrupt source that is individually enabled
- · On any form of device Reset
- On a WDT time-out

On wake-up from sleep, the processor will restart with the same clock source that was active when Sleep mode was entered.

EXAMPLE 9-1:	PWRSAV INSTRUCTION
	SYNTAX

PWRSAV	#0	;	Put	the	device	into	SLEEP mode
PWRSAV	#1						IDLE mode

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9.2.2 IDLE MODE

Idle mode has these features:

- The CPU will stop executing instructions.
- The WDT is automatically cleared.
- The system clock source remains active. By default, all peripheral modules continue to operate normally from the system clock source, but can also be selectively disabled (see Section 9.4 "Selective Peripheral Module Control").
- If the WDT or FSCM is enabled, the LPRC will also remain active.

The device will wake from Idle mode on any of these events:

- Any interrupt that is individually enabled.
- · Any device Reset.
- · A WDT time-out.

On wake-up from Idle, the clock is reapplied to the CPU and instruction execution begins immediately, starting with the instruction following the PWRSAV instruction or the first instruction in the ISR.

9.2.3 INTERRUPTS COINCIDENT WITH POWER SAVE INSTRUCTIONS

Any interrupt that coincides with the execution of a PWRSAV instruction will be held off until entry into Sleep or Idle mode has completed. The device will then wake-up from Sleep or Idle mode.

9.3 Doze Mode

Generally, changing clock speed and invoking one of the power-saving modes are the preferred strategies for reducing power consumption. There may be circumstances, however, where this is not practical. For example, it may be necessary for an application to maintain uninterrupted synchronous communication, even while it is doing nothing else. Reducing system clock speed may introduce communication errors, while using a power-saving mode may stop communications completely.

Doze mode is a simple and effective alternative method to reduce power consumption while the device is still executing code. In this mode, the system clock continues to operate from the same source and at the same speed. Peripheral modules continue to be clocked at the same speed while the CPU clock speed is reduced. Synchronization between the two clock domains is maintained, allowing the peripherals to access the SFRs while the CPU executes code at a slower rate.

Doze mode is enabled by setting the DOZEN bit (CLKDIV<11>). The ratio between peripheral and core clock speed is determined by the DOZE<2:0> bits (CLKDIV<14:12>). There are eight possible configurations, from 1:1 to 1:128, with 1:1 being the default.

It is also possible to use Doze mode to selectively reduce power consumption in event driven applications. This allows clock-sensitive functions, such as synchronous communications, to continue without interruption while the CPU idles, waiting for something to invoke an interrupt routine. Enabling the automatic return to full-speed CPU operation on interrupts is enabled by setting the ROI bit (CLKDIV<15>). By default, interrupt events have no effect on Doze mode operation.

9.4 Selective Peripheral Module Control

Idle and Doze modes allow users to substantially reduce power consumption by slowing or stopping the CPU clock. Even so, peripheral modules still remain clocked, and thus, consume power. There may be cases where the application needs what these modes do not provide: the allocation of power resources to CPU processing with minimal power consumption from the peripherals.

PIC24F devices address this requirement by allowing peripheral modules to be selectively disabled, reducing or eliminating their power consumption. This can be done with two control bits:

- The Peripheral Enable bit, generically named, "XXXEN", located in the module's main control SFR.
- The Peripheral Module Disable (PMD) bit, generically named, "XXXMD", located in one of the PMD control registers.

Both bits have similar functions in enabling or disabling its associated module. Setting the PMD bit for a module disables all clock sources to that module, reducing its power consumption to an absolute minimum. In this state, the control and status registers associated with the peripheral will also be disabled, so writes to those registers will have no effect and read values will be invalid. Many peripheral modules have a corresponding PMD bit.

In contrast, disabling a module by clearing its XXXEN bit disables its functionality, but leaves its registers available to be read and written to. This reduces power consumption, but not by as much as setting the PMD bit does. Most peripheral modules have an enable bit; exceptions include input capture, output compare and RTCC.

To achieve more selective power savings, peripheral modules can also be selectively disabled when the device enters Idle mode. This is done through the control bit of the generic name format, "XXXIDL". By default, all modules that can operate during Idle mode will do so. Using the disable on Idle feature allows further reduction of power consumption during Idle mode, enhancing power savings for extremely critical power applications.

10.0 I/O PORTS

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 12. *"I/O Ports with Peripheral Pin Select (PPS)"* (DS39711). The information in this data sheet supersedes the information in the FRM.

All of the device pins (except VDD, VSS, MCLR and OSCI/CLKI) are shared between the peripherals and the parallel I/O ports. All I/O input ports feature Schmitt Trigger (ST) inputs for improved noise immunity.

10.1 Parallel I/O (PIO) Ports

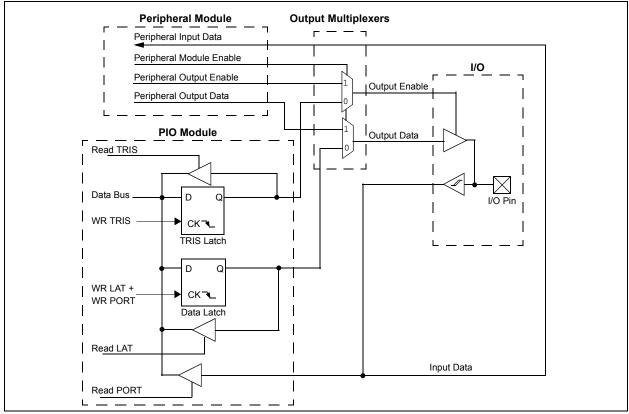
A parallel I/O port that shares a pin with a peripheral is, in general, subservient to the peripheral. The peripheral's output buffer data and control signals are provided to a pair of multiplexers. The multiplexers select whether the peripheral or the associated port has ownership of the output data and control signals of the I/O pin. The logic also prevents "loop through", in which a port's digital output can drive the input of a peripheral that shares the same pin. Figure 10-1 shows how ports are shared with other peripherals and the associated I/O pin to which they are connected. When a peripheral is enabled and the peripheral is actively driving an associated pin, the use of the pin as a general purpose output pin is disabled. The I/O pin may be read, but the output driver for the parallel port bit will be disabled. If a peripheral is enabled, but the peripheral is not actively driving a pin, that pin may be driven by a port.

All port pins have three registers directly associated with their operation as digital I/O and one register associated with their operation as analog input. The Data Direction register (TRISx) determines whether the pin is an input or an output. If the data direction bit is a '1', then the pin is an input. All port pins are defined as inputs after a Reset. Reads from the Output Latch register (LATx), read the latch; writes to the latch, write the latch. Reads from the port (PORTx), read the port pins; writes to the port pins, write the latch.

Any bit and its associated data and control registers that are not valid for a particular device will be disabled. That means the corresponding LATx and TRISx registers, and the port pin will read as zeros.

When a pin is shared with another peripheral or function that is defined as an input only, it is regarded as a dedicated port because there is no other competing source of inputs.





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10.1.1 I/O PORT WRITE/READ TIMING

One instruction cycle is required between a port direction change or port write operation and a read operation of the same port. Typically, this instruction would be a NOP.

10.1.2 OPEN-DRAIN CONFIGURATION

In addition to the PORT, LAT and TRIS registers for data control, each port pin can also be individually configured for either a digital or open-drain output. This is controlled by the Open-Drain Control register, ODCx, associated with each port. Setting any of the bits configures the corresponding pin to act as an open-drain output.

The open-drain feature allows the generation of outputs higher than VDD (e.g., 5V) on any desired digital only pins by using external pull-up resistors. The maximum open-drain voltage allowed is the same as the maximum VIH specification.

10.1.3 CONFIGURING D+ AND D- PINS (RG2 AND RG3)

The input buffers of the RG2 and RG3 pins are by default, tri-stated. To use these pins as input pins, the UTRDIS bit (U1CNFG2<0>) should be set which enables the input buffers on these pins.

10.2 Configuring Analog Port Pins (ANSEL)

The ANSx and TRISx registers control the operation of the pins with analog function. Each port pin with analog function is associated with one of the ANS bits (see Register 10-1 through Register 10-7), which decides if the pin function should be analog or digital. Refer to Table 10-1 for detailed behavior of the pin for different ANSx and TRISx bit settings.

When reading the PORT register, all pins configured as analog input channels will read as cleared (a low level).

10.2.1 ANALOG INPUT PINS AND VOLTAGE CONSIDERATIONS

The voltage tolerance of pins used as device inputs is dependent on the pin's input function. Pins that are used as digital only inputs are able to handle DC voltages of up to 5.5V, a level typical for digital logic circuits. In contrast, pins that also have analog input functions of any kind can only tolerate voltages up to VDD. Voltage excursions beyond VDD on these pins should always be avoided. Table 10-2 summarizes the input capabilities. Refer to **Section 30.1 "DC Characteristics"** for more details.

Pin Function	ANSx Setting	TRISx Setting	Comments
Analog Input	1	1	It is recommended to keep ANSx = 1.
Analog Output	1	1	It is recommended to keep ANSx = 1.
Digital Input	0	1	Firmware must wait at least one instruction cycle after configuring a pin as a digital input before a valid input value can be read.
Digital Output	0	0	Make sure to disable the analog output function on the pin if any is present.

TABLE 10-1: CONFIGURING ANALOG/DIGITAL FUNCTION OF AN I/O PIN

TABLE 10-2: INPUT VOLTAGE LEVELS FOR PORT OR PIN TOLERATED DESCRIPTION INPUT

Port or Pin	Tolerated Input	Description
PORTA ⁽¹⁾ <10:9, 7:6>		
PORTB<15:0>		
PORTC ⁽¹⁾ <15:12, 4>		
PORTD<7:6>	VDD	Only VDD input levels are tolerated.
PORTE ⁽¹⁾ <9>		
PORTF<0>		
PORTG<9:6, 3:2>		
PORTA ⁽¹⁾ <15:14, 5:0>		
PORTC ⁽¹⁾ <3:1>		
PORTD ⁽¹⁾ <15:8, 5:0>		Tolerates input levels above VDD, useful
PORTE ⁽¹⁾ <8:0>	5.5V	for most standard logic.
PORTF ⁽¹⁾ <13:12, 8:7, 5:1>		
PORTG ⁽¹⁾ <15:12, 1:0>		

Note 1: Not all of the pins of these PORTS are implemented in 64-pin devices (PIC24FJXXXDAX06); refer to the device pinout diagrams for the details.

REGISTER 10-1: ANSA: PORTA ANALOG FUNCTION SELECTION REGISTER⁽¹⁾

D 44/ 4							
bit 15							bit 8
_	—	_	_	—	ANSA10	ANSA9	—
U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-1	U-0

R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0	U-0
ANSA7	ANSA6	—	—	—		-	—
bit 7							bit 0

L	.egend:					
F	R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-	n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-11 Unimplemente	ed: Read as '0'
------------------------	-----------------

bit 10-9	 ANSA<10:9>: Analog Function Selection bits 1 = Pin is configured in Analog mode; I/O port read is disabled 0 = Pin is configured in Digital mode; I/O port read is enabled
bit 8	Unimplemented: Read as '0'
bit 7-6	ANSA<7:6>: Analog Function Selection bits
	 1 = Pin is configured in Analog mode; I/O port read is disabled 0 = Pin is configured in Digital mode; I/O port read is enabled
bit 5-0	Unimplemented: Read as '0'

Note 1: This register is not available on 64-pin devices (PIC24FJXXXDAX06).

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REGISTER 10-2: ANSB: PORTB ANALOG FUNCTION SELECTION REGISTER

R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
ANSB15	ANSB14	ANSB13	ANSB12	ANSB11	ANSB10	ANSB9	ANSB8
bit 15							bit 8
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1

bit 7							bit 0
ANSB7	ANSB6	ANSB5	ANSB4	ANSB3	ANSB2	ANSB1	ANSB0
R/VV-1	R/ VV- I	R/VV-1	R/ W- I	R/W-1	R/ VV- I	R/VV-1	FK/ VV- I

Legend:				
R = Readable bit	R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-0 ANSB<15:0>: Analog Function Selection bits

1 = Pin is configured in Analog mode; I/O port read is disabled

0 = Pin is configured in Digital mode; I/O port read is enabled

REGISTER 10-3: ANSC: PORTC ANALOG FUNCTION SELECTION REGISTER

U-0	R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0	
—	ANSC14	ANSC13	—	—	—	—	—	
bit 15							bit 8	
U-0	U-0	U-0	R/W-1	U-0	U-0	U-0	U-0	
_	—	—	ANSC4 ⁽¹⁾	—	—	—	—	
bit 7		•					bit 0	
Legend:								
R = Readabl	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at	-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknow			iown	
bit 15	Unimplemen	ted: Read as 'd)'					
bit 14-13	ANSC<14:13	>: Analog Fund	tion Selection	bits				
	1 = Pin is cor	nfigured in Anal	log mode; I/O	port read is disa	abled			

0 = Pin is configured in Digital mode; I/O port read is enabled

- bit 12-5 **Unimplemented:** Read as '0'
- bit 4 ANSC4: Analog Function Selection bit⁽¹⁾
 - 1 = Pin is configured in Analog mode; I/O port read is disabled
 - 0 = Pin is configured in Digital mode; I/O port read is enabled
- bit 3-0 Unimplemented: Read as '0'

Note 1: This bit is not available on 64-pin devices (PIC24FJXXXDAX06).

REGISTER 10-4: ANSD: PORTD ANALOG FUNCTION SELECTION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0	U-0
ANSD7	ANSD6	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
bit 7-6	ANSD<7:6>: Analog Function Selection bits
	 1 = Pin is configured in Analog mode; I/O port read is disabled 0 = Pin is configured in Digital mode; I/O port read is enabled
bit 5-0	Unimplemented: Read as '0'

REGISTER 10-5: ANSE: PORTE ANALOG FUNCTION SELECTION REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	R/W-1	U-0
—	—	—	—	—	—	ANSE9	—
bit 15				•			bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-10 Unimplemented: Read as '0'

bit 9 ANSE9: Analog Function Selection bits

1 = Pin is configured in Analog mode; I/O port read is disabled

- 0 = Pin is configured in Digital mode; I/O port read is enabled
- bit 8-0 Unimplemented: Read as '0'

Note 1: This register is not available in 64-pin devices (PIC24FJXXXDAX06).

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REGISTER 10-6: ANSF: PORTF ANALOG FUNCTION SELECTION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—			—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-1
—	—	—	—	—	—	_	ANSF0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-1 Unimplemented: Read as '0'

bit 0

bit 9-6

ANSF0: Analog Function Selection bits

1 = Pin is configured in Analog mode; I/O port read is disabled

0 = Pin is configured in Digital mode; I/O port read is enabled

REGISTER 10-7: ANSG: PORTG ANALOG FUNCTION SELECTION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-1	R/W-1
_	_	—	—		—	ANSG9	ANSG8
bit 15							bit 8
R/W-1	R/W-1	U-0	U-0	U-0	U-0	U-0	U-0
ANSG7	ANSG6	—	—		—	—	—
bit 7	-	-					bit 0
Legend:							
R = Readable bit		W = Writable bit		U = Unimplemented bit, read as '0'			
-n = Value at POR '1' =		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	
=							

bit 15-10 **Unimplemented:** Read as '0'

ANSG<9:6>: Analog Function Selection bits

- 1 = Pin is configured in Analog mode; I/O port read is disabled
- 0 = Pin is configured in Digital mode; I/O port read is enabled
- bit 5-0 Unimplemented: Read as '0'

10.3 Input Change Notification

The input change notification function of the I/O ports allows the PIC24FJ256DA210 family of devices to generate interrupt requests to the processor in response to a Change-Of-State (COS) on selected input pins. This feature is capable of detecting input Change-Of-States, even in Sleep mode, when the clocks are disabled. Depending on the device pin count, there are up to 84 external inputs that may be selected (enabled) for generating an interrupt request on a Change-Of-State.

Registers, CNEN1 through CNEN6, contain the interrupt enable control bits for each of the CN input pins. Setting any of these bits enables a CN interrupt for the corresponding pins.

Each CN pin has a both a weak pull-up and a weak pull-down connected to it. The pull-ups act as a current source that is connected to the pin, while the pull-downs act as a current sink that is connected to the pin. These eliminate the need for external resistors when push button or keypad devices are connected. The pull-ups and pull-downs are separately enabled using the CNPU1 through CNPU6 registers (for pull-ups), and the CNPD1 through CNPD6 registers (for pull-downs). Each CN pin has individual control bits for its pull-up and pull-down. Setting a control bit enables the weak pull-up or pull-down for the corresponding pin.

When the internal pull-up is selected, the pin pulls up to VDD - 1.1V (typical). When the internal pull-down is selected, the pin pulls down to Vss.

Note: Pull-ups on change notification pins should always be disabled whenever the port pin is configured as a digital output.

Note: To use CN83 and CN84, which are on the D+ and D- pins, the UTRDIS bit (U1CNFG2<0>) should be set.

EXAMPLE 10-1: PORT WRITE/READ IN ASSEMBLY

MOV	0xFF00, W0	; Configure PORTB<15:8> as inputs
MOV	W0, TRISB	; and PORTB<7:0> as outputs
NOP		; Delay 1 cycle
BTSS	PORTB, #13	; Next Instruction

EXAMPLE 10-2: PORT WRITE/READ IN 'C'

TRISB = 0xFF00;	<pre>// Configure PORTB<15:8> as inputs and PORTB<7:0> as outputs</pre>
Nop();	// Delay 1 cycle
<pre>If (PORTBbits.RB13) { };</pre>	// Next Instruction

10.4 Peripheral Pin Select (PPS)

A major challenge in general purpose devices is providing the largest possible set of peripheral features while minimizing the conflict of features on I/O pins. In an application that needs to use more than one peripheral multiplexed on a single pin, inconvenient work arounds in application code or a complete redesign may be the only option.

The Peripheral Pin Select (PPS) feature provides an alternative to these choices by enabling the user's peripheral set selection and its placement on a wide range of I/O pins. By increasing the pinout options available on a particular device, users can better tailor the microcontroller to their entire application, rather than trimming the application to fit the device.

The Peripheral Pin Select feature operates over a fixed subset of digital I/O pins. Users may independently map the input and/or output of any one of many digital peripherals to any one of these I/O pins. PPS is performed in software and generally does not require the device to be reprogrammed. Hardware safeguards are included that prevent accidental or spurious changes to the peripheral mapping once it has been established.

10.4.1 AVAILABLE PINS

The PPS feature is used with a range of up to 44 pins, depending on the particular device and its pin count. Pins that support the Peripheral Pin Select feature include the designation, "RPn" or "RPIn", in their full pin designation, where "n" is the remappable pin number. "RP" is used to designate pins that support both remappable input and output functions, while "RPI" indicates pins that support remappable input functions only.

PIC24FJ256DA210 family devices support a larger number of remappable input only pins than remappable input/output pins. In this device family, there are up to 32 remappable input/output pins, depending on the pin count of the particular device selected; these are numbered, RP0 through RP31. Remappable input only pins are numbered above this range, from RPI32 to RPI43 (or the upper limit for that particular device).

See Table 1-1 for a summary of pinout options in each package offering.

10.4.2 AVAILABLE PERIPHERALS

The peripherals managed by the PPS are all digital only peripherals. These include general serial communications (UART and SPI), general purpose timer clock inputs, timer related peripherals (input capture and output compare) and external interrupt inputs. Also included are the outputs of the comparator module, since these are discrete digital signals.

PPS is not available for l^2C^{TM} , change notification inputs, RTCC alarm outputs, EPMP signals, graphics controller signals or peripherals with analog inputs.

A key difference between pin select and non-pin select peripherals is that pin select peripherals are not associated with a default I/O pin. The peripheral must always be assigned to a specific I/O pin before it can be used. In contrast, non pin select peripherals are always available on a default pin, assuming that the peripheral is active and not conflicting with another peripheral.

10.4.2.1 Peripheral Pin Select Function Priority

Pin-selectable peripheral outputs (e.g., OC, UART transmit) will take priority over general purpose digital functions on a pin, such as EPMP and port I/O. Specialized digital outputs, such as USB functionality, will take priority over PPS outputs on the same pin. The pin diagrams list peripheral outputs in the order of priority. Refer to them for priority concerns on a particular pin.

Unlike PIC24F devices with fixed peripherals, pin selectable peripheral inputs will never take ownership of a pin. The pin's output buffer will be controlled by the TRISx setting or by a fixed peripheral on the pin. If the pin is configured in digital mode then the PPS input will operate correctly. If an analog function is enabled on the pin the PPS input will be disabled.

10.4.3 CONTROLLING PERIPHERAL PIN SELECT

PPS features are controlled through two sets of Special Function Registers (SFRs): one to map peripheral inputs and one to map outputs. Because they are separately controlled, a particular peripheral's input and output (if the peripheral has both) can be placed on any selectable function pin without constraint.

The association of a peripheral to a peripheral-selectable pin is handled in two different ways, depending on if an input or an output is being mapped.

10.4.3.1 Input Mapping

The inputs of the Peripheral Pin Select options are mapped on the basis of the peripheral; that is, a control register associated with a peripheral dictates the pin it will be mapped to. The RPINRx registers are used to configure peripheral input mapping (see Register 10-8 through Register 10-28). Each register contains two sets of 6-bit fields, with each set associated with one of the pin-selectable peripherals. Programming a given peripheral's bit field with an appropriate 6-bit value maps the RPn/RPIn pin with that value to that peripheral. For any given device, the valid range of values for any of the bit fields corresponds to the maximum number of Peripheral Pin Selections supported by the device.

Input Name	Function Name	Register	Function Mapping Bits
External Interrupt 1	INT1	RPINR0	INT1R<5:0>
External Interrupt 2	INT2	RPINR1	INT2R<5:0>
External Interrupt 3	INT3	RPINR1	INT3R<5:0>
External Interrupt 4	INT4	RPINR2	INT4R<5:0>
Input Capture 1	IC1	RPINR7	IC1R<5:0>
Input Capture 2	IC2	RPINR7	IC2R<5:0>
Input Capture 3	IC3	RPINR8	IC3R<5:0>
Input Capture 4	IC4	RPINR8	IC4R<5:0>
Input Capture 5	IC5	RPINR9	IC5R<5:0>
Input Capture 6	IC6	RPINR9	IC6R<5:0>
Input Capture 7	IC7	RPINR10	IC7R<5:0>
Input Capture 8	IC8	RPINR10	IC8R<5:0>
Input Capture 9	IC9	RPINR15	IC9R<5:0>
Output Compare Fault A	OCFA	RPINR11	OCFAR<5:0>
Output Compare Fault B	OCFB	RPINR11	OCFBR<5:0>
SPI1 Clock Input	SCK1IN	RPINR20	SCK1R<5:0>
SPI1 Data Input	SDI1	RPINR20	SDI1R<5:0>
SPI1 Slave Select Input	SS1IN	RPINR21	SS1R<5:0>
SPI2 Clock Input	SCK2IN	RPINR22	SCK2R<5:0>
SPI2 Data Input	SDI2	RPINR22	SDI2R<5:0>
SPI2 Slave Select Input	SS2IN	RPINR23	SS2R<5:0>
SPI3 Clock Input	SCK3IN	RPINR28	SCK3R<5:0>
SPI3 Data Input	SDI3	RPINR28	SDI3R<5:0>
SPI3 Slave Select Input	SS3IN	RPINR29	SS3R<5:0>
Timer2 External Clock	T2CK	RPINR3	T2CKR<5:0>
Timer3 External Clock	T3CK	RPINR3	T3CKR<5:0>
Timer4 External Clock	T4CK	RPINR4	T4CKR<5:0>
Timer5 External Clock	T5CK	RPINR4	T5CKR<5:0>
UART1 Clear To Send	U1CTS	RPINR18	U1CTSR<5:0>
UART1 Receive	U1RX	RPINR18	U1RXR<5:0>
UART2 Clear To Send	U2CTS	RPINR19	U2CTSR<5:0>
UART2 Receive	U2RX	RPINR19	U2RXR<5:0>
UART3 Clear To Send	U3CTS	RPINR21	U3CTSR<5:0>
UART3 Receive	U3RX	RPINR17	U3RXR<5:0>
UART4 Clear To Send	U4CTS	RPINR27	U4CTSR<5:0>
UART4 Receive	U4RX	RPINR27	U4RXR<5:0>

TABLE 10-3: SELECTABLE INPUT SOURCES (MAPS INPUT TO FUNCTION)⁽¹⁾

Note 1: Unless otherwise noted, all inputs use the Schmitt Trigger (ST) input buffers.

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10.4.3.2 Output Mapping

In contrast to inputs, the outputs of the Peripheral Pin Select options are mapped on the basis of the pin. In this case, a control register associated with a particular pin dictates the peripheral output to be mapped. The RPORx registers are used to control output mapping. Each register contains two 6-bit fields, with each field being associated with one RPn pin (see Register 10-29 through Register 10-44). The value of the bit field corresponds to one of the peripherals and that peripheral's output is mapped to the pin (see Table 10-4).

Because of the mapping technique, the list of peripherals for output mapping also includes a null value of '000000'. This permits any given pin to remain disconnected from the output of any of the pin-selectable peripherals.

TABLE 10-4 :	SELECTABLE OUTPUT SOURCES	(MAPS FUNCTION TO OUTPUT)

Output Function Number ⁽¹⁾	Function	Output Name
0	NULL ⁽²⁾	Null
1	C1OUT	Comparator 1 Output
2	C2OUT	Comparator 2 Output
3	U1TX	UART1 Transmit
4	U1RTS ⁽³⁾	UART1 Request To Send
5	U2TX	UART2 Transmit
6	U2RTS ⁽³⁾	UART2 Request To Send
7	SDO1	SPI1 Data Output
8	SCK10UT	SPI1 Clock Output
9	SS1OUT	SPI1 Slave Select Output
10	SDO2	SPI2 Data Output
11	SCK2OUT	SPI2 Clock Output
12	SS2OUT	SPI2 Slave Select Output
18	OC1	Output Compare 1
19	OC2	Output Compare 2
20	OC3	Output Compare 3
21	OC4	Output Compare 4
22	OC5	Output Compare 5
23	OC6	Output Compare 6
24	OC7	Output Compare 7
25	OC8	Output Compare 8
28	U3TX	UART3 Transmit
29	U3RTS ⁽³⁾	UART3 Request To Send
30	U4TX	UART4 Transmit
31	U4RTS ⁽³⁾	UART4 Request To Send
32	SDO3	SPI3 Data Output
33	SCK3OUT	SPI3 Clock Output
34	SS3OUT	SPI3 Slave Select Output
35	OC9	Output Compare 9
36	C3OUT	Comparator 3 Output
37-63	(unused)	NC

Note 1: Setting the RPORx register with the listed value assigns that output function to the associated RPn pin.

2: The NULL function is assigned to all RPn outputs at device Reset and disables the RPn output function.

3: IrDA[®] BCLK functionality uses this output.

10.4.3.3 Mapping Limitations

The control schema of the Peripheral Pin Select is extremely flexible. Other than systematic blocks that prevent signal contention, caused by two physical pins being configured as the same functional input or two functional outputs configured as the same pin, there are no hardware enforced lock outs. The flexibility extends to the point of allowing a single input to drive multiple peripherals or a single functional output to drive multiple output pins.

10.4.3.4 Mapping Exceptions for PIC24FJ256DA210 Devices

Although the PPS registers theoretically allow for up to 64 remappable I/O pins, not all of these are implemented in all devices. For PIC24FJ256DA210 family devices, the maximum number of remappable pins available are 44, which includes 12 input only pins. In addition, some pins in the RP and RPI sequences are unimplemented in lower pin count devices. The differences in available remappable pins are summarized in Table 10-5.

When developing applications that use remappable pins, users should also keep these things in mind:

- For the RPINRx registers, bit combinations corresponding to an unimplemented pin for a particular device are treated as invalid; the corresponding module will not have an input mapped to it. For all PIC24FJ256DA210 family devices, this includes all values greater than 43 ('101011').
- For RPORx registers, the bit fields corresponding to an unimplemented pin will also be unimplemented. Writing to these fields will have no effect.

10.4.4 CONTROLLING CONFIGURATION CHANGES

Because peripheral remapping can be changed during run time, some restrictions on peripheral remapping are needed to prevent accidental configuration changes. PIC24F devices include three features to prevent alterations to the peripheral map:

- · Control register lock sequence
- Continuous state monitoring
- Configuration bit remapping lock

10.4.4.1 Control Register Lock

Under normal operation, writes to the RPINRx and RPORx registers are not allowed. Attempted writes will appear to execute normally, but the contents of the registers will remain unchanged. To change these registers, they must be unlocked in hardware. The register lock is controlled by the IOLOCK bit (OSCCON<6>). Setting IOLOCK prevents writes to the control registers; clearing IOLOCK allows writes.

To set or clear IOLOCK, a specific command sequence must be executed:

- 1. Write 46h to OSCCON<7:0>.
- 2. Write 57h to OSCCON<7:0>.
- 3. Clear (or set) IOLOCK as a single operation.

Unlike the similar sequence with the oscillator's LOCK bit, IOLOCK remains in one state until changed. This allows all of the Peripheral Pin Selects to be configured with a single unlock sequence, followed by an update to all control registers, then locked with a second lock sequence.

10.4.4.2 Continuous State Monitoring

In addition to being protected from direct writes, the contents of the RPINRx and RPORx registers are constantly monitored in hardware by shadow registers. If an unexpected change in any of the registers occurs (such as cell disturbances caused by ESD or other external events), a Configuration Mismatch Reset will be triggered.

10.4.4.3 Configuration Bit Pin Select Lock

As an additional level of safety, the device can be configured to prevent more than one write session to the RPINRx and RPORx registers. The IOL1WAY (CW2<4>) Configuration bit blocks the IOLOCK bit from being cleared after it has been set once. If IOLOCK remains set, the register unlock procedure will not execute and the Peripheral Pin Select Control registers cannot be written to. The only way to clear the bit and re-enable peripheral remapping is to perform a device Reset.

In the default (unprogrammed) state, IOL1WAY is set, restricting users to one write session. Programming IOL1WAY allows users unlimited access (with the proper use of the unlock sequence) to the Peripheral Pin Select registers.

TABLE 10-5: REMAPPABLE PIN EXCEPTIONS FOR PIC24FJ256DA210 FAMILY DEVICES

Device Pin Count		RP Pins (I/O)	RPI Pins		
Device Fill Coulit	Total	Unimplemented Total		Unimplemented	
64-Pin (PIC24FJXXXDAX06)	28	RP5, RP15, RP30, RP31	1	RPI32-36, RPI38-43	
100/121-Pin (PIC24FJXXXDAX10)	32	_	12	_	

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10.4.5 CONSIDERATIONS FOR PERIPHERAL PIN SELECTION

The ability to control Peripheral Pin Selection introduces several considerations into application design that could be overlooked. This is particularly true for several common peripherals that are available only as remappable peripherals.

The main consideration is that the Peripheral Pin Selects are not available on default pins in the device's default (Reset) state. Since all RPINRx registers reset to '111111' and all RPORx registers reset to '000000', all Peripheral Pin Select inputs are tied to Vss and all Peripheral Pin Select outputs are disconnected.

Note:	In tying Peripheral Pin Select inputs to
	RP63, RP63 need not exist on a device for
	the registers to be reset to it.

This situation requires the user to initialize the device with the proper peripheral configuration before any other application code is executed. Since the IOLOCK bit resets in the unlocked state, it is not necessary to execute the unlock sequence after the device has come out of Reset. For application safety, however, it is best to set IOLOCK and lock the configuration after writing to the control registers.

Because the unlock sequence is timing-critical, it must be executed as an assembly language routine in the same manner as changes to the oscillator configuration. If the bulk of the application is written in 'C', or another high-level language, the unlock sequence should be performed by writing in-line assembly.

Choosing the configuration requires the review of all Peripheral Pin Selects and their pin assignments, especially those that will not be used in the application. In all cases, unused pin-selectable peripherals should be disabled completely. Unused peripherals should have their inputs assigned to an unused RPn/RPIn pin function. I/O pins with unused RPn functions should be configured with the null peripheral output.

The assignment of a peripheral to a particular pin does not automatically perform any other configuration of the pin's I/O circuitry. In theory, this means adding a pin-selectable output to a pin may mean inadvertently driving an existing peripheral input when the output is driven. Users must be familiar with the behavior of other fixed peripherals that share a remappable pin and know when to enable or disable them. To be safe, fixed digital peripherals that share the same pin should be disabled when not in use. Along these lines, configuring a remappable pin for a specific peripheral does not automatically turn that feature on. The peripheral must be specifically configured for operation, and enabled as if it were tied to a fixed pin. Where this happens in the application code (immediately following device Reset and peripheral configuration or inside the main application routine) depends on the peripheral and its use in the application.

A final consideration is that Peripheral Pin Select functions neither override analog inputs nor reconfigure pins with analog functions for digital I/O. If a pin is configured as an analog input on device Reset, it must be explicitly reconfigured as digital I/O when used with a Peripheral Pin Select.

Example 10-3 shows a configuration for bidirectional communication with flow control using UART1. The following input and output functions are used:

- Input Functions: U1RX, U1CTS
- Output Functions: U1TX, U1RTS

EXAMPLE 10-3: CONFIGURING UART1 INPUT AND OUTPUT FUNCTIONS

// Unlock Regi	sters		
asm volatile("MOV	#OSCCON, w1	\n"
		#0x46, w2	\n"
	"MOV	#0x57, w3	\n"
	"MOV.b	w2, [w1]	\n"
	"MOV.b	w3, [w1]	\n"
	"BCLR (DSCCON,#6");	
// or use C30 1	built-ir	n macro:	
//builtin_v	write_OS	CCONL (OSCCON &	0xbf);
// Configure I:	זווד דוומי	uctions (Table	10-2))
// Assign U	-		10 277
RPINR18bits			
// Assign U	J1CTS To) Pin RP1	
RPINR18bits	s.U1CTSF	2 = 1;	
// Configure O	utput Fi	unctions (Table	e 10-4)
// Assign U	JITX To	Pin RP2	
RPOR1bits.	RP2R = 3	;	
// Assign (
RPOR1bits.P	RP3R = 4	;	
// Lock Regist	ora		
asm volatile		#OSCCON w1	\n"
asiii voracric		#0x46, w2	
		#0x57, w3	
		w2, [w1]\	
		w3, [w1]	\n"
		OSCCON, #6")	
// or use C30	built-in	n macro:	
// builtin w			0x40);
	_		

10.4.6 PERIPHERAL PIN SELECT REGISTERS

The PIC24FJ256DA210 family of devices implements a total of 37 registers for remappable peripheral configuration:

- Input Remappable Peripheral Registers (21)
- Output Remappable Peripheral Registers (16)

Note: Input and output register values can only be changed if IOLOCK (OSCCON<6>) = 0. See Section 10.4.4.1 "Control Register Lock" for a specific command sequence.

REGISTER 10-8: RPINR0: PERIPHERAL PIN SELECT INPUT REGISTER 0

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT1R5	INT1R4	INT1R3	INT1R2	INT1R1	INT1R0
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable bit		U = Unimplemented bit, read as '0'			
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown			iown

bit 15-14	Unimplemented: Read as '0'
bit 13-8	INT1R<5:0>: Assign External Interrupt 1 (INT1) to Corresponding RPn or RPIn Pin bits
bit 7-0	Unimplemented: Read as '0'

REGISTER 10-9: RPINR1: PERIPHERAL PIN SELECT INPUT REGISTER 1

-n = Value at POR '1' = Bit is set		'0' = Bit is cleared x = Bit is unknown					
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
Legend:							
~							
bit 7			1	1	1	1	bit
_		INT2R5	INT2R4	INT2R3	INT2R2	INT2R1	INT2R0
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
bit 15							bit
_	—	INT3R5	INT3R4	INT3R3	INT3R2	INT3R1	INT3R0
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1

Unimplemented: Read as '0'
INT3R<5:0>: Assign External Interrupt 3 (INT3) to Corresponding RPn or RPIn Pin bits
Unimplemented: Read as '0'
INT2R<5:0>: Assign External Interrupt 2 (INT2) to Corresponding RPn or RPIn Pin bits

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REGISTER 10-10: RPINR2: PERIPHERAL PIN SELECT INPUT REGISTER 2

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	INT4R5	INT4R4	INT4R3	INT4R2	INT4R1	INT4R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-6 Unimplemented: Read as '0'

bit 5-0 INT4R<5:0>: Assign External Interrupt 4 (INT4) to Corresponding RPn or RPIn Pin bits

REGISTER 10-11: RPINR3: PERIPHERAL PIN SELECT INPUT REGISTER 3

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
	—	T3CKR5	T3CKR4	T3CKR3	T3CKR2	T3CKR1	T3CKR0
bit 15							bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
	—	T2CKR5	T2CKR4	T2CKR3	T2CKR2	T2CKR1	T2CKR0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' = Bit is set			'0' = Bit is clea	ared	x = Bit is unkr	nown	

bit 15-14 Unimplemented: Read as '0'

bit 13-8 T3CKR<5:0>: Assign Timer3 External Clock (T3CK) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 T2CKR<5:0>: Assign Timer2 External Clock (T2CK) to Corresponding RPn or RPIn Pin bits

REGISTER 10-12: RPINR4: PERIPHERAL PIN SELECT INPUT REGISTER 4

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	T5CKR5	T5CKR4	T5CKR3	T5CKR2	T5CKR1	T5CKR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	T4CKR5	T4CKR4	T4CKR3	T4CKR2	T4CKR1	T4CKR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	ad as 'O'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13-8	T5CKR<5:0>: Assign Timer5 External Clock (T5CK) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	T4CKR<5:0>: Assign Timer4 External Clock (T4CK) to Corresponding RPn or RPIn Pin bits

REGISTER 10-13: RPINR7: PERIPHERAL PIN SELECT INPUT REGISTER 7

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC2R5	IC2R4	IC2R3	IC2R2	IC2R1	IC2R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC1R5	IC1R4	IC1R3	IC1R2	IC1R1	IC1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 IC2R<5:0>: Assign Input Capture 2 (IC2) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 IC1R<5:0>: Assign Input Capture 1 (IC1) to Corresponding RPn or RPIn Pin bits

REGISTER 10-14: RPINR8: PERIPHERAL PIN SELECT INPUT REGISTER 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC4R5	IC4R4	IC4R3	IC4R2	IC4R1	IC4R0
bit 15					•	•	bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—		IC3R5	IC3R4	IC3R3	IC3R2	IC3R1	IC3R0
bit 7					•		bit 0
Legend:							

Legenu.			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13-8	IC4R<5:0>: Assign Input Capture 4 (IC4) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	IC3R<5:0>: Assign Input Capture 3 (IC3) to Corresponding RPn or RPIn Pin bits

REGISTER 10-15: RPINR9: PERIPHERAL PIN SELECT INPUT REGISTER 9

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	IC6R5	IC6R4	IC6R3	IC6R2	IC6R1	IC6R0
bit 15							bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
_	—	IC5R5	IC5R4	IC5R3	IC5R2	IC5R1	IC5R0
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable I	oit	U = Unimplem	nented bit, rea	d as '0'	
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown	

bit 15-14 Unimplemented: Read as '0'

bit 13-8 IC6R<5:0>: Assign Input Capture 6 (IC6) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 IC5R<5:0>: Assign Input Capture 5 (IC5) to Corresponding RPn or RPIn Pin bits

REGISTER 10-16: RPINR10: PERIPHERAL PIN SELECT INPUT REGISTER 10

bit 15							bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
_	—	IC7R5	IC7R4	IC7R3	IC7R2	IC7R1	IC7R0
bit 7							bit 0

R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13-8	IC8R<5:0>: Assign Input Capture 8 (IC8) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	IC7R<5:0>: Assign Input Capture 7 (IC7) to Corresponding RPn or RPIn Pin bits

REGISTER 10-17: RPINR11: PERIPHERAL PIN SELECT INPUT REGISTER 11

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	OCFBR5	OCFBR4	OCFBR3	OCFBR2	OCFBR1	OCFBR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	OCFAR5	OCFAR4	OCFAR3	OCFAR2	OCFAR1	OCFAR0
bit 7							bit 0

Legend:						
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-14 Unimplemented: Read as '0'

bit 13-8 OCFBR<5:0>: Assign Output Compare Fault B (OCFB) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 OCFAR<5:0>: Assign Output Compare Fault A (OCFA) to Corresponding RPn or RPIn Pin bits

REGISTER 10-18: RPINR15: PERIPHERAL PIN SELECT INPUT REGISTER 15

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
		IC9R5	IC9R4	IC9R3	IC9R2	IC9R1	IC9R0
bit 15				· ·			bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_		—	—	—	_	_
bit 7							bit 0
Legend:							
R = Readable	bit	W = Writable b	oit	U = Unimplem	ented bit, read	l as '0'	
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			iown	

bit 13-8 IC9R<5:0>: Assign Input Capture 9 (IC9) to Corresponding RPn or RPIn Pin bits

bit 7-0 Unimplemented: Read as '0'

REGISTER 10-19: RPINR17: PERIPHERAL PIN SELECT INPUT REGISTER 17

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U3RXR5	U3RXR4	U3RXR3	U3RXR2	U3RXR1	U3RXR0
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_		—		_			
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimplem	nented bit, read	as '0'	

'0' = Bit is cleared

bit 15-14 **Unimplemented:** Read as '0'

'1' = Bit is set

bit 13-8 U3RXR<5:0>: Assign UART3 Receive (U3RX) to Corresponding RPn or RPIn Pin bits

bit 7-0 Unimplemented: Read as '0'

-n = Value at POR

x = Bit is unknown

REGISTER 10-20: RPINR18: PERIPHERAL PIN SELECT INPUT REGISTER 18

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U1CTSR5	U1CTSR4	U1CTSR3	U1CTSR2	U1CTSR1	U1CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U1RXR5	U1RXR4	U1RXR3	U1RXR2	U1RXR1	U1RXR0
bit 7							bit 0

Legend:							
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown				

bit 15-14	Unimplemented: Read as '0'
bit 13-8	U1CTSR<5:0>: Assign UART1 Clear to Send (U1CTS) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	U1RXR<5:0>: Assign UART1 Receive (U1RX) to Corresponding RPn or RPIn Pin bits

REGISTER 10-21: RPINR19: PERIPHERAL PIN SELECT INPUT REGISTER 19

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U2CTSR5	U2CTSR4	U2CTSR3	U2CTSR2	U2CTSR1	U2CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U2RXR5	U2RXR4	U2RXR3	U2RXR2	U2RXR1	U2RXR0
bit 7							bit 0

Legend:					
R = Readable bit	R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-14 Unimplemented: Read as '0'

bit 13-8 U2CTSR<5:0>: Assign UART2 Clear to Send (U2CTS) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 U2RXR<5:0>: Assign UART2 Receive (U2RX) to Corresponding RPn or RPIn Pin bits

REGISTER 10-22: RPINR20: PERIPHERAL PIN SELECT INPUT REGISTER 20

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK1R5	SCK1R4	SCK1R3	SCK1R2	SCK1R1	SCK1R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI1R5	SDI1R4	SDI1R3	SDI1R2	SDI1R1	SDI1R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14	Unimplemented: Read as '0'
bit 13-8	SCK1R<5:0>: Assign SPI1 Clock Input (SCK1IN) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	SDI1R<5:0>: Assign SPI1 Data Input (SDI1) to Corresponding RPn or RPIn Pin bits

REGISTER 10-23: RPINR21: PERIPHERAL PIN SELECT INPUT REGISTER 21

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U3CTSR5	U3CTSR4	U3CTSR3	U3CTSR2	U3CTSR1	U3CTSR0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS1R5	SS1R4	SS1R3	SS1R2	SS1R1	SS1R0
bit 7							bit 0

Legend:				
R = Readable bit	= Readable bit W = Writable bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14 Unimplemented: Read as '0'

bit 13-8 U3CTSR<5:0>: Assign UART3 Clear to Send (U3CTS) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 SS1R<5:0>: Assign SPI1 Slave Select Input (SS1IN) to Corresponding RPn or RPIn Pin bits

REGISTER 10-24: RPINR22: PERIPHERAL PIN SELECT INPUT REGISTER 22

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	_	SCK2R5	SCK2R4	SCK2R3	SCK2R2	SCK2R1	SCK2R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI2R5	SDI2R4	SDI2R3	SDI2R2	SDI2R1	SDI2R0
bit 7							bit 0

Legend:				
R = Readable bit W = Writable bit		U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14	Unimplemented: Read as '0'
bit 13-8	SCK2R<5:0>: Assign SPI2 Clock Input (SCK2IN) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	SDI2R<5:0>: Assign SPI2 Data Input (SDI2) to Corresponding RPn or RPIn Pin bits

REGISTER 10-25: RPINR23: PERIPHERAL PIN SELECT INPUT REGISTER 23

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SS2R5	SS2R4	SS2R3	SS2R2	SS2R1	SS2R0
bit 7							bit 0

Legend:				
R = Readable bit W = Writable bit		U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-6 Unimplemented: Read as '0'

bit 5-0 SS2R<5:0>: Assign SPI2 Slave Select Input (SS2IN) to Corresponding RPn or RPIn Pin bits

REGISTER 10-26: RPINR27: PERIPHERAL PIN SELECT INPUT REGISTER 27

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	U4CTSR5	U4CTSR4	U4CTSR3	U4CTSR2	U4CTSR1	U4CTSR0
bit 15							bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1

bit 0

Legend:					
R = Readable bit	R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-14	Unimplemented: Read as '0'
bit 13-8	U4CTSR<5:0>: Assign UART4 Clear to Send (U4CTS) to Corresponding RPn or RPIn Pin bits
bit 7-6	Unimplemented: Read as '0'
bit 5-0	U4RXR<5:0>: Assign UART4 Receive (U4RX) to Corresponding RPn or RPIn Pin bits

REGISTER 10-27: RPINR28: PERIPHERAL PIN SELECT INPUT REGISTER 28

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SCK3R5	SCK3R4	SCK3R3	SCK3R2	SCK3R1	SCK3R0
bit 15							bit 8

U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
—	—	SDI3R5	SDI3R4	SDI3R3	SDI3R2	SDI3R1	SDI3R0
bit 7							bit 0

Legend:				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14 Unimplemented: Read as '0'

bit 13-8 SCK3R<5:0>: Assign SPI3 Clock Input (SCK3IN) to Corresponding RPn or RPIn Pin bits

bit 7-6 Unimplemented: Read as '0'

bit 5-0 SDI3R<5:0>: Assign SPI3 Data Input (SDI3) to Corresponding RPn or RPIn Pin bits

bit 7

x = Bit is unknown

REGISTER 10-28: RPINR29: PERIPHERAL PIN SELECT INPUT REGISTER 29

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	—	—	—	—	—	—	—
bit 15							bit 8
U-0	U-0	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
_	_	SS3R5	SS3R4	SS3R3	SS3R2	SS3R1	SS3R0
bit 7	•						bit 0
Legend:							
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'							

'0' = Bit is cleared

bit 15-6 Unimplemented: Read as '0'

'1' = Bit is set

-n = Value at POR

bit 5-0 SS3R<5:0>: Assign SPI3 Slave Select Input (SS31IN) to Corresponding RPn or RPIn Pin bits

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REGISTER 10-29: RPOR0: PERIPHERAL PIN SELECT OUTPUT REGISTER 0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	RP1R5	RP1R4	RP1R3	RP1R2	RP1R1	RP1R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	RP0R5	RP0R4	RP0R3	RP0R2	RP0R1	RP0R0
bit 7					•	bit 0	
Legend:							
R = Readable bit W = Writable bit U = Unimplemented bit, read			l as '0'				
-n = Value at POR '1' = Bit is set		'0' = Bit is cleared x = Bit is unknown		nown			

bit 15-14 Unimplemented: Read as '0'

bit 13-8 RP1R<5:0>: RP1 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP1 (see Table 10-4 for peripheral function numbers). bit 7-6 Unimplemented: Read as '0'

bit 5-0 RP0R<5:0>: RP0 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP0 (see Table 10-4 for peripheral function numbers).

REGISTER 10-30: RPOR1: PERIPHERAL PIN SELECT OUTPUT REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP3R5	RP3R4	RP3R3	RP3R2	RP3R1	RP3R0
bit 15		•				•	bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP2R5	RP2R4	RP2R3	RP2R2	RP2R1	RP2R0
bit 7					•	•	bit 0
Legend:							

0				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14 Unimplemented: Read as '0'

bit 13-8 RP3R<5:0>: RP3 Output Pin Mapping bits

Peripheral output number n is assigned to pin, RP3 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 RP2R<5:0>: RP2 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP2 (see Table 10-4 for peripheral function numbers).

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP5R5 ⁽¹⁾	RP5R4 ⁽¹⁾	RP5R3 ⁽¹⁾	RP5R2 ⁽¹⁾	RP5R1 ⁽¹⁾	RP5R0 ⁽¹⁾
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
		00405		BB (B			

00	00		10000		10000		10.00
—	—	RP4R5	RP4R4	RP4R3	RP4R2	RP4R1	RP4R0
bit 7							bit 0

Legend:				
R = Readable bit	W = Writable bit	= Writable bit U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14	Unimplemented: Read as '0'
bit 13-8	RP5R<5:0>: RP5 Output Pin Mapping bits ⁽¹⁾
	Peripheral output number n is assigned to pin, RP5 (see Table 10-4 for peripheral function numbers).
bit 7-6	Unimplemented: Read as '0'
bit 5-0	RP4R<5:0>: RP4 Output Pin Mapping bits
	Peripheral output number n is assigned to pin, RP4 (see Table 10-4 for peripheral function numbers).

Note 1: Unimplemented in 64-pin devices; read as '0'.

REGISTER 10-32: RPOR3: PERIPHERAL PIN SELECT OUTPUT REGISTER 3

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_	RP7R5	RP7R4	RP7R3	RP7R2	RP7R1	RP7R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	_	RP6R5	RP6R4	RP6R3	RP6R2	RP6R1	RP6R0
bit 7							bit 0

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-14	Unimplemented: Read as '0'
bit 13-8	RP7R<5:0>: RP7 Output Pin Mapping bits
	Peripheral output number n is assigned to pin, RP7 (see Table 10-4 for peripheral function numbers).
bit 7-6	Unimplemented: Read as '0'
bit 5-0	RP6R<5:0>: RP6 Output Pin Mapping bits
	Peripheral output number n is assigned to pin, RP6 (see Table 10-4 for peripheral function numbers).

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REGISTER 10-33: RPOR4: PERIPHERAL PIN SELECT OUTPUT REGISTER 4

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP9R5	RP9R4	RP9R3	RP9R2	RP9R1	RP9R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP8R5	RP8R4	RP8R3	RP8R2	RP8R1	RP8R0
bit 7							bit 0
Leaend:							

Legena.					
R = Readable bit W = Writable bit		U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-14 Unimplemented: Read as '0'

- bit 13-8**RP9R<5:0>:** RP9 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP9 (see Table 10-4 for peripheral function numbers).bit 7-6**Unimplemented:** Read as '0'
- bit 5-0 **RP8R<5:0>:** RP8 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP8 (see Table 10-4 for peripheral function numbers).

REGISTER 10-34: RPOR5: PERIPHERAL PIN SELECT OUTPUT REGISTER 5

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP11R5	RP11R4	RP11R3	RP11R2	RP11R1	RP11R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP10R5	RP10R4	RP10R3	RP10R2	RP10R1	RP10R0
bit 7							bit 0

Legend:					
R = Readable bit	W = Writable bit	bit U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RP11R<5:0>:** RP11 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP11 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP10R<5:0>:** RP10 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP10 (see Table 10-4 for peripheral function numbers).

REGISTER 10-35: RPOR6: PERIPHERAL PIN SELECT OUTPUT REGISTER 6

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP13R5	RP13R4	RP13R3	RP13R2	RP13R1	RP13R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP12R5	RP12R4	RP12R3	RP12R2	RP12R1	RP12R0
bit 7							bit 0

Legend:				
R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 15-14	Unimplemented: Read as '0'
bit 13-8	RP13R<5:0>: RP13 Output Pin Mapping bits
	Peripheral output number n is assigned to pin, RP13 (see Table 10-4 for peripheral function numbers).
bit 7-6	Unimplemented: Read as '0'
bit 5-0	RP12R<5:0>: RP12 Output Pin Mapping bits
	Peripheral output number n is assigned to pin, RP12 (see Table 10-4 for peripheral function numbers).

REGISTER 10-36: RPOR7: PERIPHERAL PIN SELECT OUTPUT REGISTER 7

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP15R5 ⁽¹⁾	RP15R4 ⁽¹⁾	RP15R3 ⁽¹⁾	RP15R2 ⁽¹⁾	RP15R1 ⁽¹⁾	RP15R0 ⁽¹⁾
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP14R5	RP14R4	RP14R3	RP14R2	RP14R1	RP14R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RP15R<5:0>:** RP15 Output Pin Mapping bits⁽¹⁾

Peripheral output number n is assigned to pin, RP0 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP14R<5:0>:** RP14 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP14 (see Table 10-4 for peripheral function numbers).

Note 1: Unimplemented in 64-pin devices; read as '0'.

REGISTER 10-37: RPOR8: PERIPHERAL PIN SELECT OUTPUT REGISTER 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP17R5	RP17R4	RP17R3	RP17R2	RP17R1	RP17R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP16R5	RP16R4	RP16R3	RP16R2	RP16R1	RP16R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

- bit 13-8**RP17R<5:0>:** RP17 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP17 (see Table 10-4 for peripheral function numbers).bit 7-6**Unimplemented:** Read as '0'bit 5-0**RP16R<5:0>:** RP16 Output Pin Mapping bits
- bit 5-0 **RP16R<5:0>:** RP16 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP16 (see Table 10-4 for peripheral function numbers).

REGISTER 10-38: RPOR9: PERIPHERAL PIN SELECT OUTPUT REGISTER 9

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP19R5	RP19R4	RP19R3	RP19R2	RP19R1	RP19R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP18R5	RP18R4	RP18R3	RP18R2	RP18R1	RP18R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	1 as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RP19R<5:0>:** RP19 Output Pin Mapping bits

Peripheral output number n is assigned to pin, RP19 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP18R<5:0>:** RP18 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP18 (see Table 10-4 for peripheral function numbers).

REGISTER 10-39: RPOR10: PERIPHERAL PIN SELECT OUTPUT REGISTER 10

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—		RP21R5	RP21R4	RP21R3	RP21R2	RP21R1	RP21R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP20R5	RP20R4	RP20R3	RP20R2	RP20R1	RP20R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

- bit 13-8**RP21R<5:0>:** RP21 Output Pin Mapping bits
Peripheral output number n is assigned to pin, RP21 (see Table 10-4 for peripheral function numbers).bit 7-6**Unimplemented:** Read as '0'
- bit 5-0 **RP20R<5:0>:** RP20 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP20 (see Table 10-4 for peripheral function numbers).

REGISTER 10-40: RPOR11: PERIPHERAL PIN SELECT OUTPUT REGISTER 11

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP23R5	RP23R4	RP23R3	RP23R2	RP23R1	RP23R0
bit 15							bit 8

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP22R5	RP22R4	RP22R3	RP22R2	RP22R1	RP22R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RP23R<5:0>:** RP23 Output Pin Mapping bits

Peripheral output number n is assigned to pin, RP23 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP22R<5:0>:** RP22 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP22 (see Table 10-4 for peripheral function numbers).

Legend:							
bit 7							bit 0
—	—	RP24R5	RP24R4	RP24R3	RP24R2	RP24R1	RP24R0
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
bit 15					•	•	bit 8
	—	RP25R5	RP25R4	RP25R3	RP25R2	RP25R1	RP25R0
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

- bit 13-8
 RP25R<5:0>: RP25 Output Pin Mapping bits

 Peripheral output number n is assigned to pin, RP25 (see Table 10-4 for peripheral function numbers).

 bit 7-6
 Unimplemented: Read as '0'

 Uit 5.0
 RP25 (see Table 10-4 for peripheral function numbers).
- bit 5-0 **RP24R<5:0>:** RP24 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP24 (see Table 10-4 for peripheral function numbers).

REGISTER 10-42: RPOR13: PERIPHERAL PIN SELECT OUTPUT REGISTER 13

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP27R5	RP27R4	RP27R3	RP27R2	RP27R1	RP27R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP26R5	RP26R4	RP26R3	RP26R2	RP26R1	RP26R0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		bit	U = Unimplem	nented bit, read	l as '0'		

bit 15-14 **Unimplemented:** Read as '0'

bit 13-8 **RP27R<5:0>:** RP27 Output Pin Mapping bits

'1' = Bit is set

Peripheral output number n is assigned to pin, RP27 (see Table 10-4 for peripheral function numbers).

'0' = Bit is cleared

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP26R<5:0>:** RP26 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP26 (see Table 10-4 for peripheral function numbers).

-n = Value at POR

x = Bit is unknown

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
	—	RP29R5	RP29R4	RP29R3	RP29R2	RP29R1	RP29R0
bit 15							bit 8
11_0	11_0						P/\//_0

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—	—	RP28R5	RP28R4	RP28R3	RP28R2	RP28R1	RP28R0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

- bit 13-8
 RP29R<5:0>: RP29 Output Pin Mapping bits

 Peripheral output number n is assigned to pin, RP29 (see Table 10-4 for peripheral function numbers).

 bit 7-6
 Unimplemented: Read as '0'
- bit 5-0 **RP28R<5:0>:** RP28 Output Pin Mapping bits Peripheral output number n is assigned to pin, RP28 (see Table 10-4 for peripheral function numbers).

REGISTER 10-44: RPOR15: PERIPHERAL PIN SELECT OUTPUT REGISTER 15⁽¹⁾

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
_	—	RP31R5	RP31R4	RP31R3	RP31R2	RP31R1	RP31R0
bit 15							bit 8
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
—		RP30R5	RP30R4	RP30R3	RP30R2	RP30R1	RP30R0
bit 7							bit 0
Legend:							

Logena.			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-14 Unimplemented: Read as '0'

bit 13-8 **RP31R<5:0>:** RP31 Output Pin Mapping bits⁽¹⁾

Peripheral output number n is assigned to pin, RP31 (see Table 10-4 for peripheral function numbers).

bit 7-6 Unimplemented: Read as '0'

bit 5-0 **RP30R<5:0>:** RP30 Output Pin Mapping bits⁽¹⁾

Peripheral output number n is assigned to pin, RP30 (see Table 10-4 for peripheral function numbers).

Note 1: Unimplemented in 64-pin devices; read as '0'.

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NOTES:

11.0 TIMER1

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 14. "Timers" (DS39704). The information in this data sheet supersedes the information in the FRM.

The Timer1 module is a 16-bit timer, which can serve as the time counter for the Real-Time Clock (RTC) or operate as a free-running, interval timer/counter. Timer1 can operate in three modes:

- 16-Bit Timer
- 16-Bit Synchronous Counter
- · 16-Bit Asynchronous Counter

Timer1 also supports these features:

- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during CPU Idle and Sleep modes
- Interrupt on 16-Bit Period Register Match or Falling Edge of External Gate Signal

Figure 11-1 presents a block diagram of the 16-bit timer module.

To configure Timer1 for operation:

- 1. Set the TON bit (= 1).
- 2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
- 3. Set the Clock and Gating modes using the TCS and TGATE bits.
- 4. Set or clear the TSYNC bit to configure synchronous or asynchronous operation.
- 5. Load the timer period value into the PR1 register.
- 6. If interrupts are required, set the interrupt enable bit, T1IE. Use the priority bits, T1IP<2:0>, to set the interrupt priority.

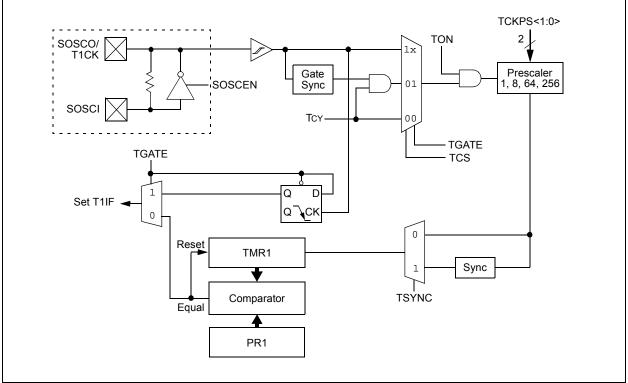


FIGURE 11-1: 16-BIT TIMER1 MODULE BLOCK DIAGRAM

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON		TSIDL			—	_	—
bit 15							bit
			DAVO	11.0	DAMO		
U-0	R/W-0 TGATE	R/W-0	R/W-0	U-0	R/W-0 TSYNC	R/W-0	U-0
 bit 7	IGAIL	TCKPS1	TCKPS0	—	TSTINC	TCS	bit
							DIL
Legend:							
R = Readab	le bit	W = Writable	bit	U = Unimpler	mented bit, rea	d as '0'	
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkno	own
bit 15	TON: Timer1	On hit					
	1 = Starts 16						
	0 = Stops 16	-bit Timer1					
bit 14	Unimplemen	ted: Read as '	Ο'				
bit 13	•	in Idle Mode bit					
		nue module operation module operation			le mode		
bit 12-7	Unimplemen	ted: Read as '	כ'				
bit 6	TGATE: Time	er1 Gated Time	Accumulation	Enable bit			
		ored.					
bit 5-4	TCKPS<1:0>	: Timer1 Input	Clock Prescale	Select bits			
	11 = 1:256 10 = 1:64 01 = 1:8 00 = 1:1						
bit 3	Unimplemen	ted: Read as '	D'				
bit 2	TSYNC: Time	er1 External Clo	ock Input Syncl	nronization Sel	ect bit		
		nize external cle ynchronize exte <u>0:</u>		it			
bit 1	-	Clock Source S	Select bit				
		clock from T1C clock (Fosc/2)	K pin (on the r	ising edge)			
bit 0		ted: Read as '	כ'				
	Changing the val		hile the timer is	s running (TON	l = 1) causes t	he timer prescal	e counter to

12.0 TIMER2/3 AND TIMER4/5

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 14. "Timers" (DS39704). The information in this data sheet supersedes the information in the FRM.

The Timer2/3 and Timer4/5 modules are 32-bit timers, which can also be configured as four independent, 16-bit timers with selectable operating modes.

As 32-bit timers, Timer2/3 and Timer4/5 can each operate in three modes:

- Two independent 16-bit timers with all 16-bit operating modes (except Asynchronous Counter mode)
- Single 32-bit timer
- Single 32-bit synchronous counter

They also support these features:

- Timer Gate Operation
- Selectable Prescaler Settings
- Timer Operation during Idle and Sleep modes
- Interrupt on a 32-Bit Period Register Match
- ADC Event Trigger (only on Timer2/3 in 32-bit mode and Timer3 in 16-bit mode)

Individually, all four of the 16-bit timers can function as synchronous timers or counters. They also offer the features listed above, except for the ADC Event Trigger; this is implemented only on Timer2/3 in 32-bit mode and Timer3 in 16-bit mode. The operating modes and enabled features are determined by setting the appropriate bit(s) in the T2CON, T3CON, T4CON and T5CON registers. T2CON and T4CON are shown in generic form in Register 12-1; T3CON and T5CON are shown in Register 12-2.

For 32-bit timer/counter operation, Timer2 and Timer4 are the least significant word; Timer3 and Timer4 are the most significant word of the 32-bit timers.

Note: For 32-bit operation, T3CON and T5CON control bits are ignored. Only T2CON and T4CON control bits are used for setup and control. Timer2 and Timer4 clock and gate inputs are utilized for the 32-bit timer modules, but an interrupt is generated with the Timer3 or Timer5 interrupt flags. To configure Timer2/3 or Timer4/5 for 32-bit operation:

- 1. Set the T32 bit (T2CON<3> or T4CON<3> = 1).
- 2. Select the prescaler ratio for Timer2 or Timer4 using the TCKPS<1:0> bits.
- Set the Clock and Gating modes using the TCS and TGATE bits. If TCS is set to an external clock, RPINRx (TxCK) must be configured to an available RPn/RPIn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)".
- Load the timer period value. PR3 (or PR5) will contain the most significant word (msw) of the value while PR2 (or PR4) contains the least significant word (lsw).
- 5. If interrupts are required, set the interrupt enable bit, T3IE or T5IE; use the priority bits, T3IP<2:0> or T5IP<2:0>, to set the interrupt priority. Note that while Timer2 or Timer4 controls the timer, the interrupt appears as a Timer3 or Timer5 interrupt.
- 6. Set the TON bit (= 1).

The timer value, at any point, is stored in the register pair, TMR<3:2> (or TMR<5:4>). TMR3 (TMR5) always contains the most significant word of the count, while TMR2 (TMR4) contains the least significant word.

To configure any of the timers for individual 16-bit operation:

- Clear the T32 bit corresponding to that timer (T2CON<3> for Timer2 and Timer3 or T4CON<3> for Timer4 and Timer5).
- 2. Select the timer prescaler ratio using the TCKPS<1:0> bits.
- 3. Set the Clock and Gating modes using the TCS and TGATE bits. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.
- 4. Load the timer period value into the PRx register.
- 5. If interrupts are required, set the interrupt enable bit, TxIE; use the priority bits, TxIP<2:0>, to set the interrupt priority.
- 6. Set the TON (TxCON<15> = 1) bit.

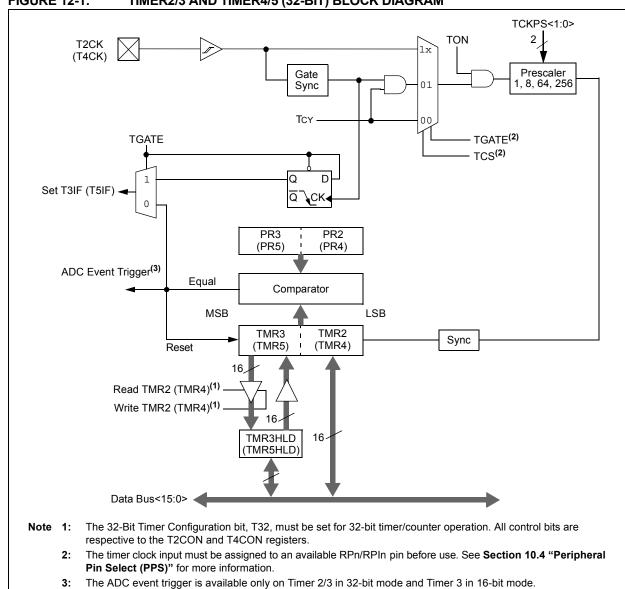
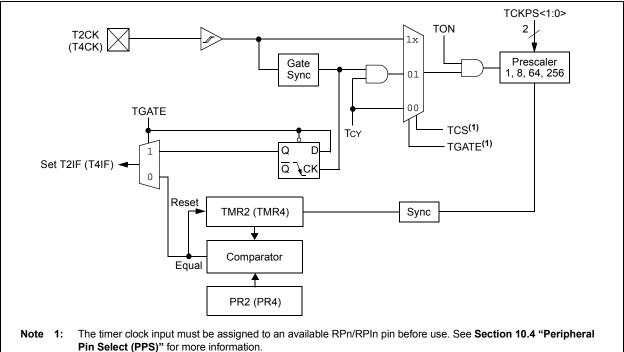
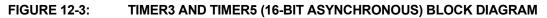
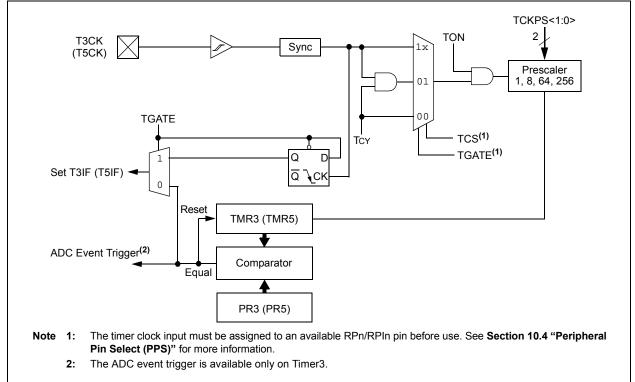


FIGURE 12-1: TIMER2/3 AND TIMER4/5 (32-BIT) BLOCK DIAGRAM









R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON		TSIDL	—	_	_	—	
bit 15							bit 8
U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	U-0
	TGATE	TCKPS1	TCKPS0	T32 ⁽¹⁾	_	TCS ⁽²⁾	_
bit 7							bit (
Legend:							
R = Reada	able bit	W = Writable	bit	U = Unimplem	nented bit, rea	d as '0'	
-n = Value	at POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkno	own
bit 15	TON: Timer When TxCO						
		2-bit Timerx/y					
		2-bit Timerx/y					
	When TxCO						
	1 = Starts 1						
	0 = Stops 1						
bit 14	-	nted: Read as 'o					
bit 13	•	in Idle Mode bit					
		inue module ope e module operat			e mode		
bit 12-7		nted: Read as '		•			
bit 6	-	erx Gated Time		nahla hit			
	When TCS =						
	This bit is ig						
	When TCS =	<u>= 0:</u>					
		me accumulation					
		ime accumulation					
bit 5-4		>: Timerx Input (Clock Prescale	Select bits			
	11 = 1:256 10 = 1:64						
	01 = 1:8						
	00 = 1:1						
bit 3	T32: 32-Bit	Timer Mode Sele	ect bit ⁽¹⁾				
		and Timery form					
		and Timery act a					
		de, T3CON cont		tect 32-bit tim	er operation.		
bit 2		nted: Read as '					
bit 1		Clock Source S		ining odge)			
		al clock from pin, I clock (Fosc/2)	TXCK (on the r	ising eage)			
bit 0		nted: Read as ')'				
Note 1:	In T4CON, the T T5CON control I	45 bit is impleme	ented instead of		32-bit mode. I	n 32-bit mode, th	ne T3CON oi
2:	If TCS = 1, RPIN Section 10.4 "P	NRx (TxCK) mus	t be configured		e RPn/RPIn pi	n. For more infor	mation, see
3:	Changing the va	alue of TxCON w		running (TON	= 1) causes t	he timer prescale	e counter to

REGISTER 12-1: TxCON: TIMER2 AND TIMER4 CONTROL REGISTER⁽³⁾

REGISTER 12-2: TyCON: TIMER3 AND TIMER5 CONTROL REGISTER⁽³⁾

R/W-0	U-0	R/W-0	U-0	U-0	U-0	U-0	U-0
TON ⁽¹⁾		TSIDL ⁽¹⁾	—	_	—	_	—
bit 15	- -	•					bit 8
U-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	U-0
_	TGATE ⁽¹⁾	TCKPS1 ⁽¹⁾	TCKPS0 ⁽¹⁾	—	—	TCS ^(1,2)	—
bit 7							bit 0

Legend:				
R = Reada	able bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value	at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown
bit 15	TON: Tim	ery On bit ⁽¹⁾		
		5 16-bit Timery 5 16-bit Timery		
bit 14	Unimpler	mented: Read as '0'		
bit 13	TSIDL: S	top in Idle Mode bit ⁽¹⁾		
		ontinue module operation wh nue module operation in Idle		
bit 12-7	Unimpler	nented: Read as '0'		
bit 6	TGATE: 7	Timery Gated Time Accumula	ation Enable bit ⁽¹⁾	
		ignored.		
bit 5-4	TCKPS<	I:0>: Timery Input Clock Pre	scale Select bits ⁽¹⁾	
	11 = 1:25 10 = 1:64 01 = 1:8 00 = 1:1	-		
bit 3-2	Unimpler	nented: Read as '0'		
bit 1	TCS: Tim	ery Clock Source Select bit ⁽¹	l,2)	
		nal clock from pin, TyCK (on nal clock (Fosc/2)	the rising edge)	
bit 0	Unimpler	nented: Read as '0'		
Note 1:		operation is enabled (T2CON timer functions are set through		e bits have no effect on Timery
2:	•			pin. See Section 10.4 "Periphera

- Pin Select (PPS)" for more information.
- **3:** Changing the value of TyCON while the timer is running (TON = 1) causes the timer prescale counter to reset and is not recommended.

NOTES:

13.0 INPUT CAPTURE WITH DEDICATED TIMERS

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 34. *"Input Capture with Dedicated Timer"* (DS39722). The information in this data sheet supersedes the information in the FRM.

Devices in the PIC24FJ256DA210 family comprise nine independent input capture modules. Each of the modules offers a wide range of configuration and operating options for capturing external pulse events and generating interrupts.

Key features of the input capture module include:

- Hardware configurable for 32-bit operation in all modes by cascading two adjacent modules
- Synchronous and Trigger modes of output compare operation, with up to 30 user-selectable sync/trigger sources available
- A 4-level FIFO buffer for capturing and holding timer values for several events
- · Configurable interrupt generation
- Up to 6 clock sources available for each module, driving a separate internal 16-bit counter

The module is controlled through two registers: ICxCON1 (Register 13-1) and ICxCON2 (Register 13-2). A general block diagram of the module is shown in Figure 13-1.

13.1 General Operating Modes

13.1.1 SYNCHRONOUS AND TRIGGER MODES

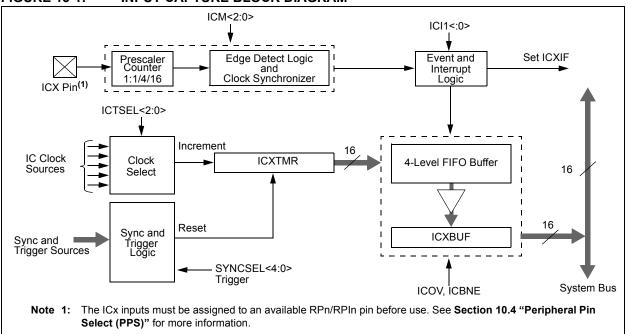
When the input capture module operates in a free-running mode, the internal 16-bit counter, ICxTMR, counts up continuously, wrapping around from FFFFh to 0000h on each overflow, with its period synchronized to the selected external clock source. When a capture event occurs, the current 16-bit value of the internal counter is written to the FIFO buffer.

In Synchronous mode, the module begins capturing events on the ICx pin as soon as its selected clock source is enabled. Whenever an event occurs on the selected sync source, the internal counter is reset. In Trigger mode, the module waits for a Sync event from another internal module to occur before allowing the internal counter to run.

Standard, free-running operation is selected by setting the SYNCSEL bits (ICxCON2<4:0>) to '00000' and clearing the ICTRIG bit (ICxCON2<7>). Synchronous and Trigger modes are selected any time the SYNCSEL bits are set to any value except '00000'. The ICTRIG bit selects either Synchronous or Trigger mode; setting the bit selects Trigger mode operation. In both modes, the SYNCSEL bits determine the sync/trigger source.

When the SYNCSEL bits are set to '00000' and ICTRIG is set, the module operates in Software Trigger mode. In this case, capture operations are started by manually setting the TRIGSTAT bit (ICxCON2<6>).

FIGURE 13-1: INPUT CAPTURE BLOCK DIAGRAM



13.1.2 CASCADED (32-BIT) MODE

By default, each module operates independently with its own 16-bit timer. To increase resolution, adjacent even and odd modules can be configured to function as a single 32-bit module. (For example, Modules 1 and 2 are paired, as are Modules 3 and 4, and so on.) The odd numbered module (ICx) provides the Least Significant 16 bits of the 32-bit register pairs and the even module (ICy) provides the Most Significant 16 bits. Wrap-arounds of the ICx registers cause an increment of their corresponding ICy registers.

Cascaded operation is configured in hardware by setting the IC32 bits (ICxCON2<8>) for both modules.

13.2 Capture Operations

The input capture module can be configured to capture timer values and generate interrupts on rising edges on ICx or all transitions on ICx. Captures can be configured to occur on all rising edges or just some (every 4^{th} or 16^{th}). Interrupts can be independently configured to generate on each event or a subset of events.

To set up the module for capture operations:

- 1. Configure the ICx input for one of the available Peripheral Pin Select pins.
- 2. If Synchronous mode is to be used, disable the sync source before proceeding.
- 3. Make sure that any previous data has been removed from the FIFO by reading ICxBUF until the ICBNE bit (ICxCON1<3>) is cleared.
- 4. Set the SYNCSEL bits (ICxCON2<4:0>) to the desired sync/trigger source.
- 5. Set the ICTSEL bits (ICxCON1<12:10>) for the desired clock source.
- 6. Set the ICI bits (ICxCON1<6:5>) to the desired interrupt frequency
- 7. Select Synchronous or Trigger mode operation:
 - a) Check that the SYNCSEL bits are not set to '00000'.
 - b) For Synchronous mode, clear the ICTRIG bit (ICxCON2<7>).
 - c) For Trigger mode, set ICTRIG, and clear the TRIGSTAT bit (ICxCON2<6>).
- 8. Set the ICM bits (ICxCON1<2:0>) to the desired operational mode.
- 9. Enable the selected sync/trigger source.

For 32-bit cascaded operations, the setup procedure is slightly different:

- 1. Set the IC32 bits for both modules (ICyCON2<8>) and (ICxCON2<8>), enabling the even numbered module first. This ensures the modules will start functioning in unison.
- 2. Set the ICTSEL and SYNCSEL bits for both modules to select the same sync/trigger and time base source. Set the even module first, then the odd module. Both modules must use the same ICTSEL and SYNCSEL settings.
- Clear the ICTRIG bit of the even module (ICyCON2<7>). This forces the module to run in Synchronous mode with the odd module, regardless of its trigger setting.
- 4. Use the odd module's ICI bits (ICxCON1<6:5>) to set the desired interrupt frequency.
- Use the ICTRIG bit of the odd module (ICxCON2<7>) to configure Trigger or Synchronous mode operation.
- Note: For Synchronous mode operation, enable the sync source as the last step. Both input capture modules are held in Reset until the sync source is enabled.
- Use the ICM bits of the odd module (ICxCON1<2:0>) to set the desired capture mode.

The module is ready to capture events when the time base and the sync/trigger source are enabled. When the ICBNE bit (ICxCON1<3>) becomes set, at least one capture value is available in the FIFO. Read input capture values from the FIFO until the ICBNE clears to '0'.

For 32-bit operation, read both the ICxBUF and ICyBUF for the full 32-bit timer value (ICxBUF for the Isw, ICyBUF for the msw). At least one capture value is available in the FIFO buffer when the odd module's ICBNE bit (ICxCON1<3>) becomes set. Continue to read the buffer registers until ICBNE is cleared (performed automatically by hardware).

REGISTER 13-1: ICxCON1: INPUT CAPTURE x CONTROL REGISTER 1

U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0			
_		ICSIDL	ICTSEL2	ICTSEL1	ICTSEL0		—			
bit 15			•				bit 8			
U-0	R/W-0	R/W-0	R-0, HSC	R-0, HSC	R/W-0	R/W-0	R/W-0			
	ICI1	ICIO	ICOV	ICBNE	ICM2 ⁽¹⁾	ICM1 ⁽¹⁾	ICM0 ⁽¹⁾			
bit 7	1011	1010	1001	IODITE	TOTILE	101111	bit (
Legend:		HSC = Hardy	vare Settable/C	learable bit						
R = Readat	ole hit	W = Writable			nented bit, read	l as '0'				
-n = Value a		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	NOW/D			
					aicu					
bit 15-14	Unimpleme	nted: Read as '	0'							
bit 13	ICSIDL: Inpu	ut Capture x Mo	dule Stop in Idl	e Control bit						
		, pture module h	-							
	0 = Input ca	pture module co	ontinues to ope	rate in CPU Id	le mode					
bit 12-10		>: Input Captur		bits						
		m clock (Fosc/2	2)							
	110 = Reser 101 = Reser									
	101 = Reserved 100 = Timer									
	011 = Timer	-								
	010 = Timer									
	001 = Timer 000 = Timer									
bit 9-7		o nted: Read as '	0'							
bit 6-5	-	elect Number of		atorrupt bite						
DIL 0-5		pt on every four	-	-						
		pt on every third								
	01 = Interru	pt on every sec	ond capture ev							
		pt on every cap								
bit 4	•	Capture x Over	•	g bit (read-only	')					
		pture overflow of t capture overflo								
bit 3				s hit (read-only	v)					
bito	-	ICBNE: Input Capture x Buffer Empty Status bit (read-only) 1 = Input capture buffer is not empty, at least one more capture value can be read								
		pture buffer is e								
bit 2-0	ICM<2:0>: Ir	nput Capture Me	ode Select bits	1)						
		upt mode: input node (rising edo					is in Sleep o			
	110 = Unus	Idle mode (rising edge detect only, all other control bits are not applicable) 110 = Unused (module disabled)								
	101 = Presc	aler Capture m	ode: capture or	n every 16 th ris	ing edge					
		aler Capture m								
		le Capture mod le Capture mod								
		Detect Capture				falling), ICI<1:	0> bits do no			
	contro	ol interrupt gene	eration for this r			0,.				
	000 = Input	capture module	e turned off							

Note 1: The ICx input must also be configured to an available RPn/RPIn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)".

U-0	U-0	U-0	U-0	U-0	U-0	U-0	R/W-0		
_	_		_	—	—		IC32		
bit 15							bit 8		
R/W-0	R/W-0 HS	U-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-1		
ICTRIG	TRIGSTAT	_	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0		
bit 7							bit C		
Legend:		HS = Hardwa	re Settable bit						
R = Readab	le bit	W = Writable	bit	U = Unimplemented bit, read as '0'					
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unknown			
bit 8	1 = ICx and I	Cy operate in	ules Enable bit cascade as a 3 ently as a 16-bi	2-bit module (th		set in both mod	dules)		
bit 7	1 = Trigger IC	ICTRIG: ICx Sync/Trigger Select bit 1 = Trigger ICx from the source designated by the SYNCSELx bits 0 = Synchronize ICx with the source designated by the SYNCSELx bits							
bit 6	1 = Timer sou	 TRIGSTAT: Timer Trigger Status bit 1 = Timer source has been triggered and is running (set in hardware, can be set in software) 0 = Timer source has not been triggered and is being held clear 							
bit 5	Unimplement	ted: Read as '	0'	· ·					
bit 4-0	Unimplemented: Read as '0' SYNCSEL<4:0>: Synchronization/Trigger Source Selection bits 11111 = Reserved 11101 = Input Capture 9 ⁽²⁾ 11101 = Input Capture 6 ⁽²⁾ 11100 = CTMU ⁽¹⁾ 11011 = A/D ⁽¹⁾								

- $11011 = A/D^{(1)}$ 11010 = Comparator 3⁽¹⁾
- 11001 = Comparator 2⁽¹⁾
- 11000 = Comparator 1⁽¹⁾
- 10111 = Input Capture 4⁽²⁾ 10110 = Input Capture 3⁽²⁾
- 10101 = Input Capture 2⁽²⁾
- 10100 = Input Capture 1⁽²⁾
- 10011 = Input Capture 8⁽²⁾
- 10010 = Input Capture 7⁽²⁾
- 1000x = Reserved
- 01111 = Timer5 01110 = Timer4
- 01101 = Timer3
- 01100 = Timer2
- 01011 = Timer1
- 01010 = Input Capture 5⁽²⁾
- 01001 = Output Compare 9
- 00010 = Output Compare 2
- 00001 = Output Compare 1
- 00000 = Not synchronized to any other module
- Note 1: Use these inputs as trigger sources only and never as sync sources.
 - 2: Never use an IC module as its own trigger source, by selecting this mode.

14.0 OUTPUT COMPARE WITH DEDICATED TIMERS

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 35. "Output Compare with Dedicated Timer" (DS39723). The information in this data sheet supersedes the information in the FRM.

Devices in the PIC24FJ256DA210 family feature all of the 9 independent output compare modules. Each of these modules offers a wide range of configuration and operating options for generating pulse trains on internal device events, and can produce pulse-width modulated waveforms for driving power applications.

Key features of the output compare module include:

- Hardware configurable for 32-bit operation in all modes by cascading two adjacent modules
- Synchronous and Trigger modes of output compare operation, with up to 31 user-selectable trigger/sync sources available
- Two separate period registers (a main register, OCxR, and a secondary register, OCxRS) for greater flexibility in generating pulses of varying widths
- Configurable for single pulse or continuous pulse generation on an output event, or continuous PWM waveform generation
- Up to 6 clock sources available for each module, driving a separate internal 16-bit counter

14.1 General Operating Modes

14.1.1 SYNCHRONOUS AND TRIGGER MODES

When the output compare module operates in a free-running mode, the internal 16-bit counter, OCxTMR, runs counts up continuously, wrapping around from 0xFFFF to 0x0000 on each overflow, with its period synchronized to the selected external clock source. Compare or PWM events are generated each time a match between the internal counter and one of the period registers occurs.

In Synchronous mode, the module begins performing its compare or PWM operation as soon as its selected clock source is enabled. Whenever an event occurs on the selected sync source, the module's internal counter is reset. In Trigger mode, the module waits for a sync event from another internal module to occur before allowing the counter to run.

Free-running mode is selected by default or any time that the SYNCSEL bits (OCxCON2<4:0>) are set to '00000'. Synchronous or Trigger modes are selected any time the SYNCSEL bits are set to any value except '00000'. The OCTRIG bit (OCxCON2<7>) selects either Synchronous or Trigger mode; setting the bit selects Trigger mode operation. In both modes, the SYNCSEL bits determine the sync/trigger source.

14.1.2 CASCADED (32-BIT) MODE

By default, each module operates independently with its own set of 16-bit timer and duty cycle registers. To increase resolution, adjacent even and odd modules can be configured to function as a single 32-bit module. (For example, Modules 1 and 2 are paired, as are Modules 3 and 4, and so on.) The odd numbered module (OCx) provides the Least Significant 16 bits of the 32-bit register pairs and the even module (OCy) provides the Most Significant 16 bits. Wrap-arounds of the OCx registers cause an increment of their corresponding OCy registers.

Cascaded operation is configured in hardware by setting the OC32 bit (OCxCON2<8>) for both modules. For more details on cascading, refer to the "*PIC24F Family Reference Manual*", **Section 35.** "**Output Compare with Dedicated Timer**".

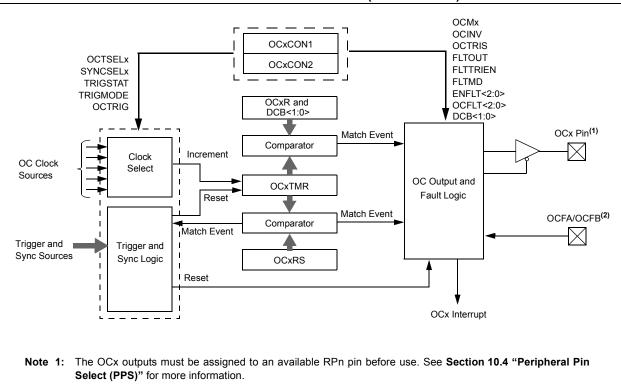


FIGURE 14-1: OUTPUT COMPARE BLOCK DIAGRAM (16-BIT MODE)

2: The OCFA/OCFB fault inputs must be assigned to an available RPn/RPIn pin before use. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

14.2 Compare Operations

In Compare mode (Figure 14-1), the output compare module can be configured for single-shot or continuous pulse generation. It can also repeatedly toggle an output pin on each timer event.

To set up the module for compare operations:

- 1. Configure the OCx output for one of the available Peripheral Pin Select pins.
- Calculate the required values for the OCxR and (for Double Compare modes) OCxRS Duty Cycle registers:
 - a) Determine the instruction clock cycle time. Take into account the frequency of the external clock to the timer source (if one is used) and the timer prescaler settings.
 - b) Calculate time to the rising edge of the output pulse relative to the timer start value (0000h).
 - c) Calculate the time to the falling edge of the pulse based on the desired pulse width and the time to the rising edge of the pulse.

- 3. Write the rising edge value to OCxR and the falling edge value to OCxRS.
- 4. Set the Timer Period register, PRy, to a value equal to or greater than the value in OCxRS.
- 5. Set the OCM<2:0> bits for the appropriate compare operation (= 0xx).
- For Trigger mode operations, set OCTRIG to enable Trigger mode. Set or clear TRIGMODE to configure trigger operation and TRIGSTAT to select a hardware or software trigger. For Synchronous mode, clear OCTRIG.
- Set the SYNCSEL<4:0> bits to configure the trigger or synchronization source. If free-running timer operation is required, set the SYNCSEL bits to '00000' (no sync/trigger source).
- Select the time base source with the OCTSEL<2:0> bits. If necessary, set the TON bits for the selected timer, which enables the compare time base to count. Synchronous mode operation starts as soon as the time base is enabled; Trigger mode operation starts after a trigger source event occurs.

For 32-bit cascaded operation, these steps are also necessary:

- Set the OC32 bits for both registers (OCyCON2<8>) and (OCxCON2<8>). Enable the even numbered module first to ensure the modules will start functioning in unison.
- Clear the OCTRIG bit of the even module (OCyCON2), so the module will run in Synchronous mode.
- 3. Configure the desired output and Fault settings for OCy.
- 4. Force the output pin for OCx to the output state by clearing the OCTRIS bit.
- If Trigger mode operation is required, configure the trigger options in OCx by using the OCTRIG (OCxCON2<7>), TRIGMODE (OCxCON1<3>) and SYNCSEL (OCxCON2<4:0>) bits.
- Configure the desired Compare or PWM mode of operation (OCM<2:0>) for OCy first, then for OCx.

Depending on the output mode selected, the module holds the OCx pin in its default state and forces a transition to the opposite state when OCxR matches the timer. In Double Compare modes, OCx is forced back to its default state when a match with OCxRS occurs. The OCxIF interrupt flag is set after an OCxR match in Single Compare modes and after each OCxRS match in Double Compare modes.

Single-shot pulse events only occur once, but may be repeated by simply rewriting the value of the OCxCON1 register. Continuous pulse events continue indefinitely until terminated.

14.3 Pulse-Width Modulation (PWM) Mode

In PWM mode, the output compare module can be configured for edge-aligned or center-aligned pulse waveform generation. All PWM operations are double-buffered (buffer registers are internal to the module and are not mapped into SFR space).

To configure the output compare module for PWM operation:

- 1. Configure the OCx output for one of the available Peripheral Pin Select pins.
- 2. Calculate the desired duty cycles and load them into the OCxR register.
- 3. Calculate the desired period and load it into the OCxRS register.
- Select the current OCx as the synchronization source by writing 0x1F to the SYNCSEL<4:0> bits (OCxCON2<4:0>) and '0' to the OCTRIG bit (OCxCON2<7>).
- 5. Select a clock source by writing to the OCTSEL<2:0> bits (OCxCON<12:10>).
- 6. Enable interrupts, if required, for the timer and output compare modules. The output compare interrupt is required for PWM Fault pin utilization.
- Select the desired PWM mode in the OCM<2:0> bits (OCxCON1<2:0>).
- Appropriate Fault inputs may be enabled by using the ENFLT<2:0> bits as described in Register 14-1.
- If a timer is selected as a clock source, set the selected timer prescale value. The selected timer's prescaler output is used as the clock input for the OCx timer, and not the selected timer output.

Note: This peripheral contains input and output functions that may need to be configured by the Peripheral Pin Select. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

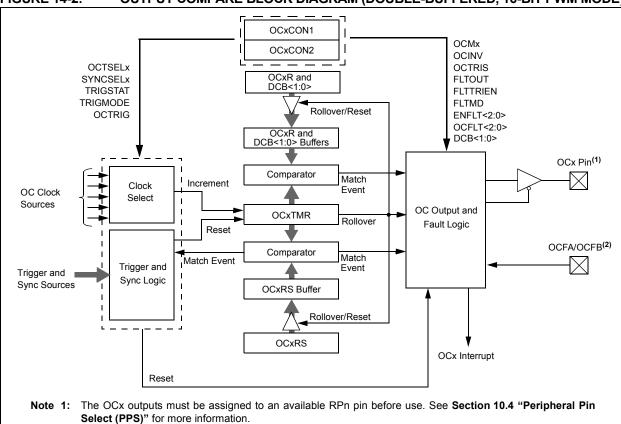


FIGURE 14-2: OUTPUT COMPARE BLOCK DIAGRAM (DOUBLE-BUFFERED, 16-BIT PWM MODE)

2: The OCFA/OCFB fault inputs must be assigned to an available RPn/RPIn pin before use. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

14.3.1 PWM PERIOD

The PWM period is specified by writing to PRy, the Timer Period register. The PWM period can be calculated using Equation 14-1.

EQUATION 14-1: CALCULATING THE PWM PERIOD⁽¹⁾

PWM Period = $[(PRy) + 1 \cdot TCY \cdot (Timer Prescale Value)]$

where:

PWM Frequency = 1/[PWM Period]

Note 1: Based on TCY = TOSC * 2; Doze mode and PLL are disabled.

Note: A PRy value of N will produce a PWM period of N + 1 time base count cycles. For example, a value of 7 written into the PRy register will yield a period consisting of 8 time base cycles.

14.3.2 PWM DUTY CYCLE

The PWM duty cycle is specified by writing to the OCxRS and OCxR registers. The OCxRS and OCxR registers can be written to at any time, but the duty cycle value is not latched until a match between PRy and TMRy occurs (i.e., the period is complete). This provides a double buffer for the PWM duty cycle and is essential for glitchless PWM operation.

Some important boundary parameters of the PWM duty cycle include:

- If OCxR, OCxRS, and PRy are all loaded with 0000h, the OCx pin will remain low (0% duty cycle).
- If OCxRS is greater than PRy, the pin will remain high (100% duty cycle).

See Example 14-1 for PWM mode timing details. Table 14-1 and Table 14-2 show example PWM frequencies and resolutions for a device operating at 4 MIPS and 10 MIPS, respectively.

EQUATION 14-2: CALCULATION FOR MAXIMUM PWM RESOLUTION⁽¹⁾

 $Maximum PWM Resolution (bits) = \underbrace{\left(\frac{FCY}{FPWM \bullet (Timer Prescale Value)}\right)}_{\log_{10}(2)} bits$

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

EXAMPLE 14-1: PWM PERIOD AND DUTY CYCLE CALCULATIONS⁽¹⁾

1. Find the Timer Period register value for a desired PWM frequency of 52.08 kHz, where Fosc = 8 MHz with PLL (32 MHz device clock rate) and a Timer2 prescaler setting of 1:1.

$$TCY = 2 * TOSC = 62.5$$
 ns

PWM Period = 1/PWM Frequency = 1/52.08 kHz = 19.2 ms

PWM Period = $(PR2 + 1) \bullet TCY \bullet (Timer2 Prescale Value)$

 $19.2 \text{ ms} = \text{PR2} + 1) \cdot 62.5 \text{ ns} \cdot 1$

PR2 = 306

2. Find the maximum resolution of the duty cycle that can be used with a 52.08 kHz frequency and a 32 MHz device clock rate:

PWM Resolution = $log_{10}(FCY/FPWM)/log_{10}2)$ bits

 $= (\log_{10}(16 \text{ MHz}/52.08 \text{ kHz})/\log_{10}2) \text{ bits}$

= 8.3 bits

Note 1: Based on TCY = 2 * TOSC; Doze mode and PLL are disabled.

PWM Frequency	7.6 Hz	61 Hz	122 Hz	977 Hz	3.9 kHz	31.3 kHz	125 kHz		
Timer Prescaler Ratio	8	1	1	1	1	1	1		
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh		
Resolution (bits)	16	16	15	12	10	7	5		

TABLE 14-1: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 4 MIPS (Fcy = 4 MHz)⁽¹⁾

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

TABLE 14-2: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS AT 16 MIPS (Fcy = 16 MHz)⁽¹⁾

PWM Frequency	30.5 Hz	244 Hz	488 Hz	3.9 kHz	15.6 kHz	125 kHz	500 kHz
Timer Prescaler Ratio	8	1	1	1	1	1	1
Period Register Value	FFFFh	FFFFh	7FFFh	0FFFh	03FFh	007Fh	001Fh
Resolution (bits)	16	16	15	12	10	7	5

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

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REGISTER 14-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1

U-0 U-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 ENFLT1(2) ENFLT2⁽²⁾ OCSIDL OCTSEL2 OCTSEL1 **OCTSEL0** bit 15 bit 8 R/W-0 R/W-0, HSC R/W-0, HSC R/W-0, HSC R/W-0 R/W-0 R/W-0 R/W-0 ENFLT0⁽²⁾ OCFLT2⁽²⁾ OCFLT1⁽²⁾ OCFLT0⁽²⁾ TRIGMODE OCM2⁽¹⁾ OCM1⁽¹⁾ OCM0⁽¹⁾ bit 7 bit 0 Legend: HSC = Hardware Settable/Clearable bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-14 Unimplemented: Read as '0' bit 13 **OCSIDL:** Stop Output Compare x in Idle Mode Control bit 1 = Output Compare x halts in CPU Idle mode 0 = Output Compare x continues to operate in CPU Idle mode OCTSEL<2:0>: Output Compare x Timer Select bits bit 12-10 111 = Peripheral clock (FCY) 110 = Reserved 101 = Reserved 100 = Timer1 clock (only synchronous clock is supported) 011 = Timer5 clock 010 = Timer4 clock 001 = Timer3 clock 000 = Timer2 clock ENFLT2: Fault Input 2 Enable bit⁽²⁾ bit 9 1 = Fault 2 (Comparator 1/2/3 out) is enabled⁽³⁾ 0 = Fault 2 is disabled bit 8 ENFLT1: Fault Input 1 Enable bit⁽²⁾ 1 = Fault 1 (OCFB pin) is enabled⁽⁴⁾ 0 = Fault 1 is disabled ENFLT0: Fault Input 0 Enable bit⁽²⁾ bit 7 1 = Fault 0 (OCFA pin) is enabled⁽⁴⁾ 0 = Fault 0 is disabled OCFLT2: PWM Fault 2 (Comparator 1/2/3) Condition Status bit^(2,3) bit 6 1 = PWM Fault 2 has occurred 0 = No PWM Fault 2 has occurred bit 5 OCFLT1: PWM Fault 1 (OCFB pin) Condition Status bit^(2,4) 1 = PWM Fault 1 has occurred 0 = No PWM Fault 1 has occurred OCFLT0: PWM Fault 0 (OCFA pin) Condition Status bit^(2,4) bit 4 1 = PWM Fault 0 has occurred 0 = No PWM Fault 0 has occurred Note 1: The OCx output must also be configured to an available RPn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)". 2: The Fault input enable and Fault status bits are valid when OCM<2:0> = 111 or 110. 3: The Comparator 1 output controls the OC1-OC3 channels; Comparator 2 output controls the OC4-OC6 channels; Comparator 3 output controls the OC7-OC9 channels.

4: The OCFA/OCFB Fault input must also be configured to an available RPn/RPIn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)".

REGISTER 14-1: OCxCON1: OUTPUT COMPARE x CONTROL REGISTER 1 (CONTINUED)

- bit 3 TRIGMODE: Trigger Status Mode Select bit
 - 1 = TRIGSTAT (OCxCON2<6>) is cleared when OCxRS = OCxTMR or in software
 - 0 = TRIGSTAT is only cleared by software

bit 2-0 OCM<2:0>: Output Compare x Mode Select bits⁽¹⁾

- 111 = Center-Aligned PWM mode on $OCx^{(2)}$
 - 110 = Edge-Aligned PWM Mode on $OCx^{(2)}$
 - 101 = Double Compare Continuous Pulse mode: Initialize the OCx pin low, the toggle OCx state continuously on alternate matches of OCxR and OCxRS
 - 100 = Double Compare Single-Shot mode: Initialize the OCx pin low, toggle the OCx state on matches of OCxR and OCxRS for one cycle
 - 011 = Single Compare Continuous Pulse mode: Compare events continuously toggle the OCx pin
 - 010 = Single Compare Single-Shot mode: Initialize OCx pin high, compare event forces the OCx pin low
 - 001 = Single Compare Single-Shot mode: Initialize OCx pin low, compare event forces the OCx pin high
 - 000 = Output compare channel is disabled
- Note 1: The OCx output must also be configured to an available RPn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)".
 - 2: The Fault input enable and Fault status bits are valid when OCM<2:0> = 111 or 110.
 - **3:** The Comparator 1 output controls the OC1-OC3 channels; Comparator 2 output controls the OC4-OC6 channels; Comparator 3 output controls the OC7-OC9 channels.
 - 4: The OCFA/OCFB Fault input must also be configured to an available RPn/RPIn pin. For more information, see Section 10.4 "Peripheral Pin Select (PPS)".

REGISTER 14-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0
FLTMD	FLTOUT	FLTTRIEN	OCINV	—	DCB1 ⁽³⁾	DCB0 ⁽³⁾	OC32
bit 15							bit 8

R/W-0	R/W-0 HS	R/W-0	R/W-0	R/W-1	R/W-1	R/W-0	R/W-0
OCTRIG	TRIGSTAT	OCTRIS	SYNCSEL4	SYNCSEL3	SYNCSEL2	SYNCSEL1	SYNCSEL0
bit 7							bit 0

Legend:	HS = Hardware Settable bit		
R = Reada	e bit W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value	POR '1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown
bit 15	FLTMD: Fault Mode Select bit		
	 Fault mode is maintained until the Faul cleared in software 	t source is removed an	d the corresponding OCFLT0 bit is
	0 = Fault mode is maintained until the Faul	source is removed and	a new PWM period starts
bit 14	FLTOUT: Fault Out bit		
	1 = PWM output is driven high on a Fault0 = PWM output is driven low on a Fault		
bit 13	FLTTRIEN: Fault Output State Select bit		
	 1 = Pin is forced to an output on a Fault co 0 = Pin I/O condition is unaffected by a Fault 		
bit 12	OCINV: OCMP Invert bit		
	1 = OCx output is inverted0 = OCx output is not inverted		
bit 11	Unimplemented: Read as '0'		
bit 10-9	DCB<11:0>: PWM Duty Cycle Least Signifi	cant bits ⁽³⁾	
	11 = Delay OCx falling edge by $\frac{3}{4}$ of the in 10 = Delay OCx falling edge by $\frac{1}{2}$ of the in	-	
	$01 = Delay OCx falling edge by \frac{1}{2} of the in01 = Delay OCx falling edge by \frac{1}{4} of the in00 = OCx falling edge occurs at the start of$	struction cycle	
bit 8	OC32: Cascade Two OC Modules Enable b	•	
bit o	1 = Cascade module operation enabled		
	0 = Cascade module operation disabled		
bit 7	OCTRIG: OCx Trigger/Sync Select bit		
	 1 = Trigger OCx from the source designate 0 = Synchronize OCx with the source designate 		
bit 6	TRIGSTAT: Timer Trigger Status bit		
bit 0	1 = Timer source has been triggered and is	running	
	0 = Timer source has not been triggered ar		
bit 5	OCTRIS: OCx Output Pin Direction Select b	bit	
	1 = OCx pin is tri-stated0 = Output compare peripheral x is connect	ed to an OCx pin	
	ever use an OC module as its own trigger sou YNCSEL setting.	rce, either by selecting	this mode or another equivalent

- 2: Use these inputs as trigger sources only and never as sync sources.
- 3: The DCB<1:0> bits are double-buffered in the PWM modes only (OCM<2:0> (OCxCON1<2:0>) = 111, 110).

REGISTER 14-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2 (CONTINUED)

- bit 4-0 SYNCSEL<4:0>: Trigger/Synchronization Source Selection bits
 - 11111 = This OC module⁽¹⁾
 - 11110 = Input Capture 9⁽²⁾
 - 11101 = Input Capture 6⁽²⁾
 - 11100 = CTMU⁽²⁾
 - 11011 = A/D⁽²⁾
 - 11010 = Comparator 3⁽²⁾
 - 11001 = Comparator 2⁽²⁾
 - 11000 = Comparator 1⁽²⁾ 10111 = Input Capture 4⁽²⁾
 - 10110 = Input Capture 3⁽²⁾

 - 10101 = Input Capture 2⁽²⁾
 - 10100 = Input Capture 1⁽²⁾
 - 10011 = Input Capture 8⁽²⁾
 - 10010 = Input Capture 7⁽²⁾
 - 1000x = Reserved
 - 01111 = Timer5
 - 01110 = Timer4
 - 01101 = Timer3
 - 01100 = Timer2 01011 = Timer1

 - 01010 =Input Capture $5^{(2)}$ 01001 = Output Compare 9⁽¹⁾

 - 01000 = Output Compare 8⁽¹⁾ 00111 = Output Compare 7⁽¹⁾
 - $00110 = Output Compare 6^{(1)}$
 - 00101 = Output Compare 5⁽¹⁾
 - 00100 = Output Compare 4⁽¹⁾
 - 00011 = Output Compare 3⁽¹⁾
 - 00010 = Output Compare $2^{(1)}$
 - 00001 = Output Compare 1⁽¹⁾
 - 00000 = Not synchronized to any other module
- Note 1: Never use an OC module as its own trigger source, either by selecting this mode or another equivalent SYNCSEL setting.
 - 2: Use these inputs as trigger sources only and never as sync sources.
 - 3: The DCB<1:0> bits are double-buffered in the PWM modes only (OCM<2:0> (OCxCON1<2:0>) = 111, 110).

NOTES:

15.0 SERIAL PERIPHERAL INTERFACE (SPI)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 23. "Serial Peripheral Interface (SPI)" (DS39699). The information in this data sheet supersedes the information in the FRM.

The Serial Peripheral Interface (SPI) module is a synchronous serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, shift registers, display drivers, A/D Converters, etc. The SPI module is compatible with the SPI and SIOP Motorola[®] interfaces. All devices of the PIC24FJ256DA210 family include three SPI modules.

The module supports operation in two buffer modes. In Standard mode, data is shifted through a single serial buffer. In Enhanced Buffer mode, data is shifted through an 8-level FIFO buffer.

Note:	Do not perform read-modify-write opera-					
	tions (such as bit-oriented instructions) on					
	the SPIxBUF register in either Standard or					
	Enhanced Buffer mode.					

The module also supports a basic framed SPI protocol while operating in either Master or Slave mode. A total of four framed SPI configurations are supported.

The SPI serial interface consists of four pins:

- SDIx: Serial Data Input
- SDOx: Serial Data Output
- SCKx: Shift Clock Input or Output
- SSx: Active-Low Slave Select or Frame Synchronization I/O Pulse

The SPI module can be configured to operate using 2, 3 or 4 pins. In the 3-pin mode, SSx is not used. In the 2-pin mode, both SDOx and SSx are not used.

Block diagrams of the module in Standard and Enhanced modes are shown in Figure 15-1 and Figure 15-2.

Note: In this section, the SPI modules are referred to together as SPIx or separately as SPI1, SPI2 or SPI3. Special Function Registers will follow a similar notation. For example, SPIxCON1 and SPIxCON2 refer to the control registers for any of the 3 SPI modules.

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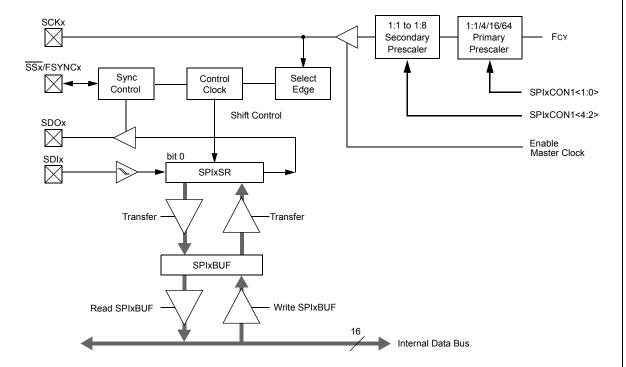
To set up the SPI module for the Standard Master mode of operation:

- 1. If using interrupts:
 - a) Clear the SPIxIF bit in the respective IFS register.
 - b) Set the SPIxIE bit in the respective IEC register.
 - c) Write the SPIxIP bits in the respective IPC register to set the interrupt priority.
- Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 1.
- 3. Clear the SPIROV bit (SPIxSTAT<6>).
- 4. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).
- Write the data to be transmitted to the SPIxBUF register. Transmission (and reception) will start as soon as data is written to the SPIxBUF register.

To set up the SPI module for the Standard Slave mode of operation:

- 1. Clear the SPIxBUF register.
- 2. If using interrupts:
 - a) Clear the SPIxIF bit in the respective IFS register.
 - b) Set the SPIxIE bit in the respective IEC register.
 - c) Write the SPIxIP bits in the respective IPC register to set the interrupt priority.
- Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 0.
- 4. Clear the SMP bit.
- If the CKE bit (SPIxCON1<8>) is set, then the SSEN bit (SPIxCON1<7>) must be set to enable the SSx pin.
- 6. Clear the SPIROV bit (SPIxSTAT<6>).
- 7. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).





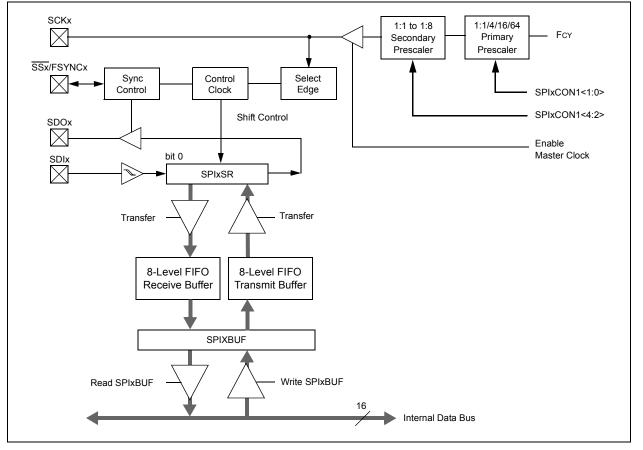
To set up the SPI module for the Enhanced Buffer Master mode of operation:

- 1. If using interrupts:
 - a) Clear the SPIxIF bit in the respective IFS register.
 - b) Set the SPIxIE bit in the respective IEC register.
 - c) Write the SPIxIP bits in the respective IPC register.
- Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 1.
- 3. Clear the SPIROV bit (SPIxSTAT<6>).
- 4. Select Enhanced Buffer mode by setting the SPIBEN bit (SPIxCON2<0>).
- 5. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).
- 6. Write the data to be transmitted to the SPIxBUF register. Transmission (and reception) will start as soon as data is written to the SPIxBUF register.

To set up the SPI module for the Enhanced Buffer Slave mode of operation:

- 1. Clear the SPIxBUF register.
- 2. If using interrupts:
 - a) Clear the SPIxIF bit in the respective IFS register.
 - b) Set the SPIxIE bit in the respective IEC register.
 - c) Write the SPIxIP bits in the respective IPC register to set the interrupt priority.
- Write the desired settings to the SPIxCON1 and SPIxCON2 registers with MSTEN (SPIxCON1<5>) = 0.
- 4. Clear the SMP bit.
- 5. If the CKE bit is set, then the SSEN bit must be set, thus enabling the SSx pin.
- 6. Clear the SPIROV bit (SPIxSTAT<6>).
- 7. Select Enhanced Buffer mode by setting the SPIBEN bit (SPIxCON2<0>).
- 8. Enable SPI operation by setting the SPIEN bit (SPIxSTAT<15>).

FIGURE 15-2: SPIX MODULE BLOCK DIAGRAM (ENHANCED MODE)



REGISTER 15-1: SPIx STATUS AND CONTROL REGISTER

R/W-0	U-0	R/W-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC			
SPIEN ⁽¹⁾		SPISIDL			SPIBEC2	SPIBEC1	SPIBEC0			
bit 15							bit 8			
R-0, HSC	R/C-0, HS	R-0, HSC	R/W-0	R/W-0	R/W-0	R-0, HSC	R-0, HSC			
SRMPT	SPIROV	SRXMPT	SISEL2	SISEL1	SISEL0	SPITBF	SPIRBF			
bit 7							bit 0			
Legend:		C = Clearable			are Settable bit					
R = Readable	e bit	W = Writable	bit	U = Unimpler	mented bit, read	d as '0'				
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	nown			
HSC = Hardv	ware Settable/0	Clearable bit								
		(1)								
bit 15		Enable bit ⁽¹⁾	- E							
	1 = Enables 0 = Disables	module and co	ntigures SCKX	, SDOX, SDIX a	and SSx as seri	ial port pins				
bit 14		nted: Read as '	۱'							
bit 13	•	op in Idle Mode								
		nue module ope		evice enters Idl	le mode					
		e module operat								
bit 12-11	Unimpleme	nted: Read as 'd)'							
bit 10-8	SPIBEC<2:0	>: SPIx Buffer E	Element Count	bits (valid in E	nhanced Buffer	r mode)				
	Master mode: Number of SPI transfers pending.									
	Slave mode: Number of SPI transfers unread.									
bit 7	SRMPT: Shift Register (SPIxSR) Empty bit (valid in Enhanced Buffer mode)									
		ift register is em ift register is not		to send or rece	eive					
bit 6	SPIROV: Re	ceive Overflow	Flag bit							
	(The user so	yte/word is comp ftware has not re	ad the previou			r.)				
	0 = No overflow has occurred									
bit 5	SRXMPT: Receive FIFO Empty bit (valid in Enhanced Buffer mode)									
	 Receive FIFO is empty Receive FIFO is not empty 									
bit 4-2		: SPIx Buffer Int	-	its (valid in Enh	anced Buffer n	node)				
511 4 2		upt when the SF	-	-		louc)				
		upt when the las				TX FIFO is emp	ty			
		upt when the las								
		upt when one da				e TX FIFO has	one open spot			
		upt when the SP upt when the SP								
		upt when data is				s set)				
		upt when the last					npty (SRXMPT			
	bit set	:)								
Note 1: If		se functions mu	et ho assignor	to available P	Dn/DDIn nine h	oforo uso Soo	Section 10 4			

Note 1: If SPIEN = 1, these functions must be assigned to available RPn/RPIn pins before use. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

REGISTER 15-1: SPIx STATUS AND CONTROL REGISTER (CONTINUED)

bit 1		SPITBF: SPIx Transmit Buffer Full Status bit
		1 = Transmit not yet started, SPIxTXB is full
		0 = Transmit started, SPIxTXB is empty
		In Standard Buffer mode:
		Automatically set in hardware when the CPU writes to the SPIxBUF location, loading SPIxTXB. Automatically cleared in hardware when the SPIx module transfers data from SPIxTXB to SPIxSR.
		In Enhanced Buffer mode:
		Automatically set in hardware when the CPU writes to the SPIxBUF location, loading the last available buffer location.
		Automatically cleared in hardware when a buffer location is available for a CPU write.
bit 0		SPIRBF: SPIx Receive Buffer Full Status bit
		1 = Receive complete, SPIxRXB is full
		0 = Receive is not complete, SPIxRXB is empty
		In Standard Buffer mode:
		Automatically set in hardware when SPIx transfers data from SPIxSR to SPIxRXB.
		Automatically cleared in hardware when the core reads the SPIxBUF location, reading SPIxRXB.
		In Enhanced Buffer mode:
		Automatically set in hardware when SPIx transfers data from the SPIxSR to the buffer, filling the last unread buffer location.
		Automatically cleared in hardware when a buffer location is available for a transfer from SPIxSR.
Note	1:	If SPIEN = 1, these functions must be assigned to available RPn/RPIn pins before use. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

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U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
_	_	_	DISSCK ⁽¹⁾	DISSDO ⁽²⁾	MODE16	SMP	CKE ⁽³⁾				
bit 15							bit 8				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
SSEN ⁽⁴⁾	-	MSTEN	SPRE2	SPRE1	SPRE0	PPRE1	PPRE0				
bit 7	ON	WOTEN	OFICEZ	OFICET	GINE	TTRET	bit C				
Legend:											
R = Reada	ble bit	W = Writable	bit	II = I Inimplem	nented bit, read	as '0'					
-n = Value		'1' = Bit is set		'0' = Bit is clea	-	x = Bit is unkr	own				
	atron	1 - Dit 13 301			area						
bit 15-13	Unimplement	ted: Read as '	0'								
bit 12	-			modes only) ⁽¹)						
		DISSCK: Disable SCKx Pin bit (SPI Master modes only) ⁽¹⁾ 1 = Internal SPI clock is disabled; pin functions as I/O									
	0 = Internal S	SPI clock is ena	abled								
bit 11		able SDOx Pin									
		 1 = SDOx pin is not used by the module; pin functions as I/O 0 = SDOx pin is controlled by the module 									
bit 10	•		•	at hit							
	MODE16: Word/Byte Communication Select bit 1 = Communication is word-wide (16 bits)										
		ication is byte-									
bit 9	SMP: SPIx Data Input Sample Phase bit										
	Master mode:										
			ne end of data of								
	0 = Input data Slave mode:	a sampled at tr	ne middle of da	ta output time							
		cleared when	SPIx is used in	Slave mode.							
bit 8	CKE: SPIx CI	ock Edge Sele	ct bit ⁽³⁾								
	1 = Serial output data changes on transition from active clock state to Idle clock state (see bit 6)										
		-	-		ck state to activ	e clock state (s	see bit 6)				
bit 7			(Slave mode) b	pit ⁽⁴⁾							
		s used for Slav s not used by f		is controlled by	y the port functi	on					
bit 6	CKP: Clock P	olarity Select I	bit								
			s a high level; a								
			s a low level; ad	ctive state is a l	nigh level						
bit 5		ter Mode Enab	le bit								
	1 = Master m 0 = Slave mo										
Note 1:	If DISSCK = 0, SO			available RPn	pin. See Sectio	on 10.4 "Perip	heral Pin				
2:	Select (PPS)" for If DISSDO = 0, SI			ı available RPn	pin. See Secti	on 10.4 "Perij	oheral Pin				
-	Select (PPS)" for			1							
	The CKE bit is no SPI modes (FRMI	EN = 1).									
4:	If SSEN = 1, \overline{SSx}	must be config more informa		ilable RPn/PRI	n pin. See Sec	tion 10.4 "Per	ipheral Pin				

REGISTER 15-2: SPIxCON1: SPIx CONTROL REGISTER 1

REGISTER 15-2: SPIXCON1: SPIX CONTROL REGISTER 1 (CONTINUED)

- bit 4-2 **SPRE<2:0>:** Secondary Prescale bits (Master mode)
 - 111 = Secondary prescale 1:1
 - 110 = Secondary prescale 2:1
 - •

 - 000 = Secondary prescale 8:1
- bit 1-0 **PPRE<1:0>:** Primary Prescale bits (Master mode)
 - 11 = Primary prescale 1:1
 - 10 = Primary prescale 4:1
 - 01 = Primary prescale 16:1
 - 00 = Primary prescale 64:1
- Note 1: If DISSCK = 0, SCKx must be configured to an available RPn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.
 - 2: If DISSDO = 0, SDOx must be configured to an available RPn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.
 - **3:** The CKE bit is not used in the Framed SPI modes. The user should program this bit to '0' for the Framed SPI modes (FRMEN = 1).
 - 4: If SSEN = 1, SSx must be configured to an available RPn/PRIn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0				
FRMEN	SPIFSD	SPIFPOL	—	—	—	—	—				
bit 15							bit 8				
U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0				
—	—			—	—	SPIFE	SPIBEN				
bit 7							bit 0				
Legend:											
R = Readabl	e bit	W = Writable I	oit	U = Unimplen	nented bit, rea	id as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unk	nown				
bit 15	EDMEN: Eror	ned SPIx Supp	ort hit								
DIL 15											
		SPIx support is SPIx support is									
bit 14		ne Sync Pulse		trol on SSx Pin	bit						
	1 = Frame sy	nc pulse input	(slave)								
	0 = Frame sy	nc pulse outpu	t (master)								
bit 13	SPIFPOL: Fra	ame Sync Pulse	e Polarity bit (F	Frame mode or	ıly)						
		nc pulse is acti									
		nc pulse is acti									
bit 12-2	•	ted: Read as '0									
bit 1		e Sync Pulse E	•								
	,	 1 = Frame sync pulse coincides with the first bit clock 0 = Frame sync pulse precedes the first bit clock 									
L:1 0	-										
bit 0		anced Buffer E									
		d buffer is enab d buffer is disat		node)							
			neu (Leyady II	noue)							

REGISTER 15-3: SPIxCON2: SPIx CONTROL REGISTER 2

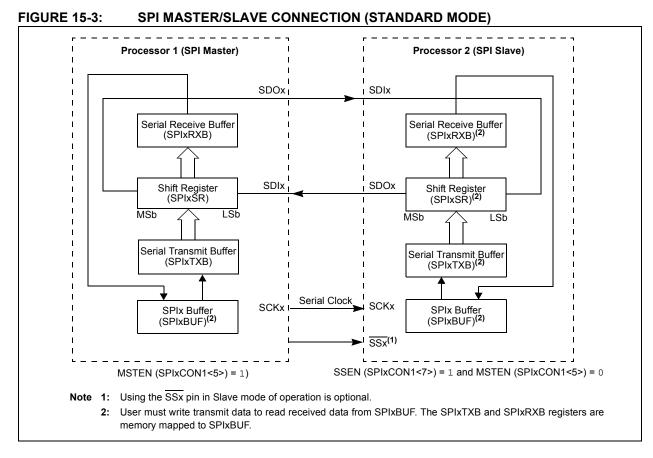


FIGURE 15-4: SPI MASTER/SLAVE CONNECTION (ENHANCED BUFFER MODES)

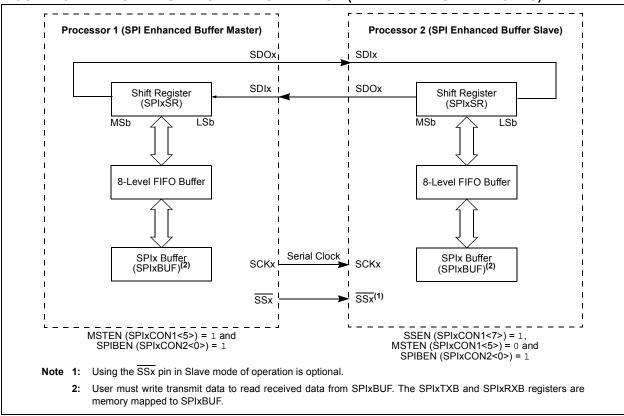
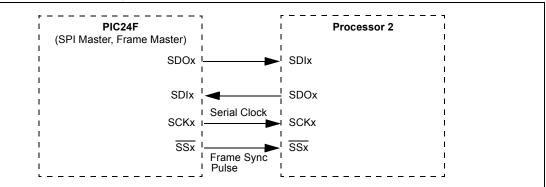


FIGURE 15-5: SPI MASTER, FRAME MASTER CONNECTION DIAGRAM





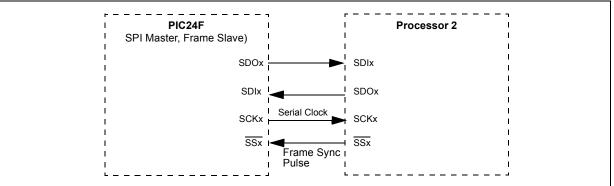


FIGURE 15-7: SPI SLAVE, FRAME MASTER CONNECTION DIAGRAM

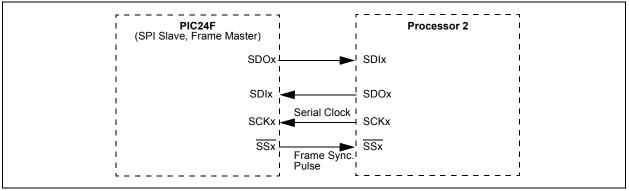
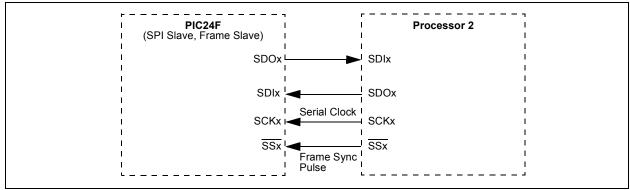


FIGURE 15-8: SPI SLAVE, FRAME SLAVE CONNECTION DIAGRAM



EQUATION 15-1: RELATIONSHIP BETWEEN DEVICE AND SPI CLOCK SPEED⁽¹⁾

FCY

 $FSCK = \frac{1001}{Primary Prescaler x Secondary Prescaler}$

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

TABLE 15-1: SAMPLE SCKx FREQUENCIES^(1,2)

Fcy = 16 MHz	Secondary Prescaler Settings					
	1:1	2:1	4:1	6:1	8:1	
	1:1	Invalid	8000	4000	2667	2000
Drimon / Droccolor Sottings	4:1	4000	2000	1000	667	500
Primary Prescaler Settings	16:1	1000	500	250	167	125
	64:1	250	125	63	42	31
Fcy = 5 MHz						
	1:1	5000	2500	1250	833	625
Drimon / Drocoolor Cottings	4:1	1250	625	313	208	156
Primary Prescaler Settings	16:1	313	156	78	52	39
	64:1	78	39	20	13	10

Note 1: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

2: SCKx frequencies shown in kHz.

 $[\]ensuremath{\textcircled{}^\circ}$ 2010 Microchip Technology Inc.

NOTES:

16.0 INTER-INTEGRATED CIRCUIT™ (I²C™)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 24. "Inter-Integrated Circuit™ (I²C™)" (DS39702). The information in this data sheet supersedes the information in the FRM.

The Inter-Integrated CircuitTM (I²CTM) module is a serial interface useful for communicating with other peripheral or microcontroller devices. These peripheral devices may be serial EEPROMs, display drivers, A/D Converters, etc.

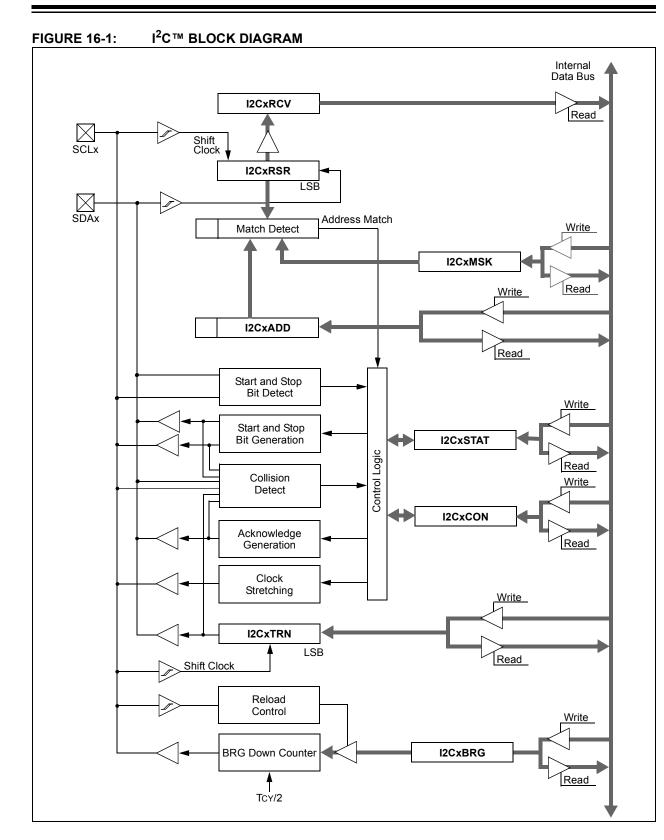
The I²C module supports these features:

- Independent master and slave logic
- · 7-bit and 10-bit device addresses
- General call address, as defined in the I²C protocol
- Clock stretching to provide delays for the processor to respond to a slave data request
- Both 100 kHz and 400 kHz bus specifications
- · Configurable address masking
- Multi-Master modes to prevent loss of messages in arbitration
- Bus Repeater mode, allowing the acceptance of all messages as a slave regardless of the address
- Automatic SCL
- A block diagram of the module is shown in Figure 16-1.

16.1 Communicating as a Master in a Single Master Environment

The details of sending a message in Master mode depends on the communications protocol for the device being communicated with. Typically, the sequence of events is as follows:

- 1. Assert a Start condition on SDAx and SCLx.
- 2. Send the I²C device address byte to the slave with a write indication.
- 3. Wait for and verify an Acknowledge from the slave.
- 4. Send the first data byte (sometimes known as the command) to the slave.
- 5. Wait for and verify an Acknowledge from the slave.
- 6. Send the serial memory address low byte to the slave.
- 7. Repeat steps 4 and 5 until all data bytes are sent.
- 8. Assert a Repeated Start condition on SDAx and SCLx.
- 9. Send the device address byte to the slave with a read indication.
- 10. Wait for and verify an Acknowledge from the slave.
- 11. Enable master reception to receive serial memory data.
- 12. Generate an ACK or NACK condition at the end of a received byte of data.
- 13. Generate a Stop condition on SDAx and SCLx.



16.2 Setting Baud Rate When Operating as a Bus Master

To compute the Baud Rate Generator reload value, use Equation 16-1.

EQUATION 16-1:	COMPUTING BAUD RATE
	RELOAD VALUE ^(1,2)

$$FSCL = \frac{FCY}{I2CxBRG + 1 + \frac{FCY}{10,000,000}}$$

or:
$$I2CxBRG = \left(\frac{FCY}{FSCL} - \frac{FCY}{10,000,000} - 1\right)$$

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

2: These clock rate values are for guidance only. The actual clock rate can be affected by various system level parameters. The actual clock rate should be measured in its intended application.

16.3 Slave Address Masking

The I2CxMSK register (Register 16-3) designates address bit positions as "don't care" for both 7-Bit and 10-Bit Addressing modes. Setting a particular bit location (= 1) in the I2CxMSK register causes the slave module to respond whether the corresponding address bit value is a '0' or a '1'. For example, when I2CxMSK is set to '00100000', the slave module will detect both addresses, '0000000' and '0100000'.

To enable address masking, the Intelligent Peripheral Management Interface (IPMI) must be disabled by clearing the IPMIEN bit (I2CxCON<11>).

Note: As a result of changes in the I²C[™] protocol, the addresses in Table 16-2 are reserved and will not be Acknowledged in Slave mode. This includes any address mask settings that include any of these addresses.

Demoired Original Factor	Fair	I2CxB		
Required System FscL	FCY	(Decimal)	(Hexadecimal)	Actual FscL
100 kHz	16 MHz	157	9D	100 kHz
100 kHz	8 MHz	78	4E	100 kHz
100 kHz	4 MHz	39	27	99 kHz
400 kHz	16 MHz	37	25	404 kHz
400 kHz	8 MHz	18	12	404 kHz
400 kHz	4 MHz	9	9	385 kHz
400 kHz	2 MHz	4	4	385 kHz
1 MHz	16 MHz	13	D	1.026 MHz
1 MHz	8 MHz	6	6	1.026 MHz
1 MHz	4 MHz	3	3	0.909 MHz

TABLE 16-1: I2C[™] CLOCK RATES(1,2)

Note 1: Based on Fcy = Fosc/2; Doze mode and PLL are disabled.

2: These clock rate values are for guidance only. The actual clock rate can be affected by various system level parameters. The actual clock rate should be measured in its intended application.

TABLE 16-2:	I ² C [™] RESERVED ADDRESSES ⁽¹⁾
-------------	---

Slave Address	R/W Bit	Description					
0000 000	0	General Call Address ⁽²⁾					
0000 000	1	Start Byte					
0000 001	x	CBus Address					
0000 01x	x	Reserved					
0000 1xx	x	HS Mode Master Code					
1111 0xx	x	10-Bit Slave Upper Byte ⁽³⁾					
1111 1xx	x	Reserved					

Note 1: The address bits listed here will never cause an address match, independent of address mask settings.

- **2:** The address will be Acknowledged only if GCEN = 1.
- 3: A match on this address can only occur on the upper byte in 10-Bit Addressing mode.

R/W-0	U-0	R/W-0	R/W-1, HC	R/W-0	R/W-0	R/W-0	R/W-0				
I2CEN	—	I2CSIDL	SCLREL	IPMIEN	A10M	DISSLW	SMEN				
bit 15							bita				
R/W-0	R/W-0	R/W-0	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC	R/W-0, HC				
GCEN	STREN	ACKDT	ACKEN	RCEN	PEN	RSEN	SEN				
bit 7		•	·			•	bit				
Legend:		HC = Hardwa	are Clearable bi	t							
R = Readab	le bit	W = Writable	bit	U = Unimplem	nented bit, read	1 as '0'					
-n = Value a	t POR	'1' = Bit is se	t	'0' = Bit is clea	ared	x = Bit is unkn	own				
bit 15	I2CEN: I2Cx	Enable bit									
	1 = Enables	the I2Cx modu	lle and configure ule. All l ² C™ pir	es the SDAx ar	nd SCLx pins a	s serial port pir	IS				
bit 14		nted: Read as '	•		a by port furior						
bit 13	-	op in Idle Mode									
			peration when d		n Idle mode						
	0 = Continues module operation in Idle mode										
bit 12	SCLREL: SCLx Release Control bit (when operating as I ² C slave)										
	1 = Releases SCLx clock 0 = Holds SCLx clock low (clock stretch)										
	If STREN = 1:										
	Bit is R/W (i.e., software may write '0' to initiate stretch and write '1' to release clock). Hardware is clear										
	at the beginning of slave transmission. Hardware is clear at the end of slave reception. If STREN = 0:										
		e., software m	ay only write '1	' to release clo	ock). Hardware	e clear at begir	nning of slav				
bit 11	IPMIEN: Intelligent Platform Management Interface (IPMI) Enable bit										
	 1 = IPMI Support mode is enabled; all addresses are Acknowledged 0 = IPMI mode is disabled 										
bit 10	A10M: 10-Bit Slave Addressing bit										
	1 = I2CxADD is a 10-bit slave address										
		D is a 7-bit slav									
bit 9	DISSLW: Disable Slew Rate Control bit										
	 1 = Slew rate control disabled 0 = Slew rate control enabled 										
	SMEN: SMB	us Input Levels	bit								
bit 8	1 = Enables I/O pin thresholds compliant with SMBus specifications										
bit 8	0 = Disables the SMBus input thresholds										
				2							
bit 8 bit 7	GCEN: Gene	eral Call Enable	e bit (when operation	•	,		1 				
	GCEN: Gene 1 = Enables	eral Call Enable interrupt when		•	,	xRSR (module	is enabled fo				
	GCEN: Gene 1 = Enables receptio	eral Call Enable interrupt when	e bit (when opera a general call a	•	,	xRSR (module	is enabled fo				
bit 7	GCEN: Gene 1 = Enables receptio 0 = General	eral Call Enable interrupt when n) call address di	e bit (when opera a general call a	address is rece	ived in the I2C	xRSR (module	is enabled fo				
	GCEN: Gene 1 = Enables receptio 0 = General STREN: SCI Used in conj	eral Call Enable interrupt when n) call address di _x Clock Stretcl unction with the	e bit (when opera a general call a sabled n Enable bit (wh	address is rece en operating a	ived in the I2C	xRSR (module	is enabled f				

REGISTER 16-1: I2CxCON: I2Cx CONTROL REGISTER (CONTINUED)

bit 5	 ACKDT: Acknowledge Data bit (when operating as I²C master. Applicable during master receive.) Value that will be transmitted when the software initiates an Acknowledge sequence. 1 = Sends NACK during Acknowledge 0 = Sends ACK during Acknowledge
bit 4	ACKEN: Acknowledge Sequence Enable bit (when operating as I ² C master. Applicable during master receive.)
	 1 = Initiates Acknowledge sequence on SDAx and SCLx pins and transmits the ACKDT data bit. Hardware is clear at the end of the master Acknowledge sequence. 0 = Acknowledge sequence is not in progress
bit 3	RCEN: Receive Enable bit (when operating as I ² C master)
	 1 = Enables Receive mode for I²C. Hardware is clear at the end of the eighth bit of the master receive data byte.
	0 = Receive sequence is not in progress
bit 2	PEN: Stop Condition Enable bit (when operating as I ² C master)
	 1 = Initiates Stop condition on the SDAx and SCLx pins. Hardware is clear at the end of the master Stop sequence.
	0 = Stop condition is not in progress
bit 1	RSEN: Repeated Start Condition Enabled bit (when operating as I ² C master)
	 1 = Initiates Repeated Start condition on the SDAx and SCLx pins. Hardware is clear at the end of the master Repeated Start sequence
	0 = Repeated Start condition is not in progress
bit 0	SEN: Start Condition Enabled bit (when operating as I ² C master)
	1 = Initiates Start condition on SDAx and SCLx pins. Hardware is clear at end of the master Start sequence.
	0 = Start condition is not in progress

REGISTER 16-2: I2CxSTAT: I2Cx STATUS REGISTER

R-0, HSC	R-0, HSC	U-0	U-0	U-0	R/C-0, HS	R-0, HSC	R-0, HSC
ACKSTAT	TRSTAT	—	—		BCL	GCSTAT	ADD10
bit 15							bit 8
R/C-0, HS	R/C-0, HS	R-0, HSC	R/C-0, HSC	R/C-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IWCOL	I2COV	D/A	Р	S	R/W	RBF	TBF
bit 7							bit 0
Legend:		C = Clearat	le hit	HS = Hardware	Settable bit		
R = Readab	ole bit	W = Writabl			ented bit, read as	· 'O'	
-n = Value a		'1' = Bit is s		'0' = Bit is clear		x = Bit is unkno	wn
	lware Settable						
bit 15	ACKSTAT:	Acknowledge	e Status bit				
		was detected					
		as detected la		Acknowledge.			
bit 14		ansmit Status		lonnou go.			
				licable to maste	r transmit operat	ion.)	
			progress (8 b	oits + ACK)			
			ot in progress	ter transmission:	hardware is clear	at the end of slav	ve Acknowledge.
bit 13-11		ented: Read		,			er ion ion ougoi
bit 10	BCL: Maste	er Bus Collisio	on Detect bit				
			een detected	during a master	operation		
	0 = No colli Hardware is		etection of a b	us collision			
bit 9		eneral Call S					
Site			s was received	d			
			s was not rece				
				ches the genera	l call address; ha	rdware is clear a	t Stop detection.
bit 8		-Bit Address					
		address was r address was r					
	Hardware is	set at the mat	ch of the 2 nd by	te of the matche	d 10-bit address; ł	nardware is clear	at Stop detection.
bit 7		ite Collision [
		-	o the I2CxTR	N register failed	because the I ² C	module is busy	
	0 = No colli Hardware is		currence of wi	rite to I2CxTRN	while busy (clear	ed by software).	
bit 6		ceive Overflov			, , , ,	, , , , , , , , , , , , , , , , , , ,	
			while the I2C	xRCV register is	s still holding the	previous byte	
	0 = No ove		ompt to transf	or 12Cypsp to 1	2CxRCV (cleare	d by coffwara)	
bit 5	_		-	as I ² C slave)		u by soltware).	
DIL D			st byte receive	· · ·			
	0 = Indicate	es that the las	st byte receive	ed was a device			
	Hardware is	s clear at the	e device addr		dware is set afte	er a transmissio	n finishes or by
	reception of	f a slave byte					

REGISTER 16-2: I2CxSTAT: I2Cx STATUS REGISTER (CONTINUED)

bit 4	P: Stop bit
	1 = Indicates that a Stop bit has been detected last
	0 = Stop bit was not detected last
	Hardware is set or clear when Start, Repeated Start or Stop is detected.
bit 3	S: Start bit
	 1 = Indicates that a Start (or Repeated Start) bit has been detected last 0 = Start bit was not detected last
	Hardware is set or clear when Start, Repeated Start or Stop is detected.
bit 2	R/W : Read/Write Information bit (when operating as I ² C slave)
	1 = Read – indicates data transfer is output from slave
	0 = Write – indicates data transfer is input to slave
	Hardware is set or clear after the reception of an I ² C device address byte.
bit 1	RBF: Receive Buffer Full Status bit
	1 = Receive is complete, I2CxRCV is full
	0 = Receive not complete, I2CxRCV is empty
	Hardware is set when I2CxRCV is written with the received byte; hardware is clear when the software reads I2CxRCV.
bit 0	TBF: Transmit Buffer Full Status bit
	1 = Transmit is in progress, I2CxTRN is full
	0 = Transmit is complete, I2CxTRN is empty

Hardware is set when software writes to I2CxTRN; hardware is clear at the completion of data transmission.

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REGISTER 16-3: I2CxMSK: I2Cx SLAVE MODE ADDRESS MASK REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
0-0	0-0	0-0	0-0	0-0	0-0		-
—						AMSK9	AMSK8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| AMSK7 | AMSK6 | AMSK5 | AMSK4 | AMSK3 | AMSK2 | AMSK1 | AMSK0 |
| bit 7 | | | | | | | bit 0 |

Legend:					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-10 Unimplemented: Read as '0'

bit 9-0

AMSK<9:0>: Mask for Address Bit x Select bits

1 = Enable masking for bit x of the incoming message address; bit match is not required in this position

0 = Disable masking for bit x; bit match is required in this position

17.0 UNIVERSAL ASYNCHRONOUS RECEIVER TRANSMITTER (UART)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 21. "UART" (DS39708). The information in this data sheet supersedes the information in the FRM.

The Universal Asynchronous Receiver Transmitter (UART) module is one of the serial I/O modules available in the PIC24F device family. The UART is a full-duplex, asynchronous system that can communicate with peripheral devices, such as personal computers, LIN/J2602, RS-232 and RS-485 interfaces. The module also supports a hardware flow control option with the UxCTS and UxRTS pins, and also includes an IrDA[®] encoder and decoder.

The primary features of the UART module are:

- Full-Duplex, 8 or 9-Bit data transmission through the UxTX and UxRX pins
- Even, Odd or No Parity options (for 8-bit data)
- · One or two Stop bits

FIGURE 17-1:

 Hardware Flow Control option with the UxCTS and UxRTS pins

- Fully Integrated Baud Rate Generator with 16-Bit Prescaler
- Baud Rates Ranging from 15 bps to 1 Mbps at 16 MIPS
- 4-Deep, First-In-First-Out (FIFO) Transmit Data Buffer
- 4-Deep FIFO Receive Data Buffer
- Parity, Framing and Buffer Overrun Error Detection
- Support for 9-bit mode with Address Detect $(9^{th} bit = 1)$
- · Transmit and Receive Interrupts
- Loopback mode for Diagnostic Support
- · Support for Sync and Break Characters
- Supports Automatic Baud Rate Detection
- IrDA[®] Encoder and Decoder Logic
- 16x Baud Clock Output for IrDA Support

A simplified block diagram of the UART is shown in Figure 17-1. The UART module consists of these key important hardware elements:

- · Baud Rate Generator
- Asynchronous Transmitter
- Asynchronous Receiver

Baud Rate Generator IrDA® Hardware Flow Control UXRTS/BCLKx UxCTS UARTx Receiver UARTx Transmitter UARTx Transmitter UXRX VarX <tr

UART SIMPLIFIED BLOCK DIAGRAM

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17.1 UART Baud Rate Generator (BRG)

The UART module includes a dedicated, 16-bit Baud Rate Generator. The UxBRG register controls the period of a free-running, 16-bit timer. Equation 17-1 shows the formula for computation of the baud rate with BRGH = 0.

EQUATION 17-1: UART BAUD RATE WITH BRGH = $0^{(1,2)}$

Baud Rate =
$$\frac{FCY}{16 \cdot (UxBRG + 1)}$$

UxBRG = $\frac{FCY}{16 \cdot Baud Rate} - 1$

Note 1: FCY denotes the instruction cycle clock frequency (FOSC/2).

2: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

Example 17-1 shows the calculation of the baud rate error for the following conditions:

- Fcy = 4 MHz
- Desired Baud Rate = 9600

The maximum baud rate (BRGH = 0) possible is Fcy/16 (for UxBRG = 0) and the minimum baud rate possible is Fcy/(16 * 65536).

Equation 17-2 shows the formula for computation of the baud rate with BRGH = 1.

EQUATION 17-2: UART BAUD RATE WITH BRGH = $1^{(1,2)}$

Baud Rate =
$$\frac{FCY}{4 \cdot (UxBRG + 1)}$$

UxBRG = $\frac{FCY}{4 \cdot Baud Rate} - 1$

- **Note 1:** FCY denotes the instruction cycle clock frequency.
 - 2: Based on FCY = FOSC/2; Doze mode and PLL are disabled.

The maximum baud rate (BRGH = 1) possible is FCY/4 (for UxBRG = 0) and the minimum baud rate possible is FCY/(4 * 65536).

Writing a new value to the UxBRG register causes the BRG timer to be reset (cleared). This ensures the BRG does not wait for a timer overflow before generating the new baud rate.

EXAMPLE 17-1: BAUD RATE ERROR CALCULATION (BRGH = 0)⁽¹⁾

Desired Baud Rate	= FCY/(16 (BRGx + 1))
Solving for BRGx Va	lue:
BRGx BRGx	= ((FCY/Desired Baud Rate)/16) - 1 = ((4000000/9600)/16) - 1
BRGx	= 25
Calculated Baud Rate	= 4000000/(16(25+1)) = 9615
Error	 = (Calculated Baud Rate – Desired Baud Rate) Desired Baud Rate = (9615 – 9600)/9600
Note: Based or	FCY = FOSC/2; Doze mode and PLL are disabled.

17.2 Transmitting in 8-Bit Data Mode

- 1. Set up the UART:
 - a) Write appropriate values for data, parity and Stop bits.
 - b) Write appropriate baud rate value to the UxBRG register.
 - c) Set up transmit and receive interrupt enable and priority bits.
- 2. Enable the UART.
- 3. Set the UTXEN bit (causes a transmit interrupt two cycles after being set).
- 4. Write a data byte to the lower byte of UxTXREG word. The value will be immediately transferred to the Transmit Shift Register (TSR) and the serial bit stream will start shifting out with the next rising edge of the baud clock.
- Alternately, the data byte may be transferred while UTXEN = 0 and then the user may set UTXEN. This will cause the serial bit stream to begin immediately because the baud clock will start from a cleared state.
- 6. A transmit interrupt will be generated as per interrupt control bit, UTXISELx.

17.3 Transmitting in 9-Bit Data Mode

- 1. Set up the UART (as described in **Section 17.2** "**Transmitting in 8-Bit Data Mode**").
- 2. Enable the UART.
- 3. Set the UTXEN bit (causes a transmit interrupt).
- 4. Write UxTXREG as a 16-bit value only.
- 5. A word write to UxTXREG triggers the transfer of the 9-bit data to the TSR. The serial bit stream will start shifting out with the first rising edge of the baud clock.
- 6. A transmit interrupt will be generated as per the setting of control bit, UTXISELx.

17.4 Break and Sync Transmit Sequence

The following sequence will send a message frame header, made up of a Break, followed by an auto-baud Sync byte.

- 1. Configure the UART for the desired mode.
- 2. Set UTXEN and UTXBRK to set up the Break character.
- 3. Load the UxTXREG with a dummy character to initiate transmission (value is ignored).
- 4. Write '55h' to UxTXREG; this loads the Sync character into the transmit FIFO.
- 5. After the Break has been sent, the UTXBRK bit is reset by hardware. The Sync character now transmits.

17.5 Receiving in 8-Bit or 9-Bit Data Mode

- 1. Set up the UART (as described in Section 17.2 "Transmitting in 8-Bit Data Mode").
- 2. Enable the UART.
- 3. A receive interrupt will be generated when one or more data characters have been received as per interrupt control bit, URXISELx.
- 4. Read the OERR bit to determine if an overrun error has occurred. The OERR bit must be reset in software.
- 5. Read UxRXREG.

The act of reading the UxRXREG character will move the next character to the top of the receive FIFO, including a new set of PERR and FERR values.

17.6 Operation of UxCTS and UxRTS Control Pins

UARTx Clear to Send (UxCTS) and Request to Send (UxRTS) are the two hardware controlled pins that are associated with the UART module. These two pins allow the UART to operate in Simplex and Flow Control mode. They are implemented to control the transmission and reception between the Data Terminal Equipment (DTE). The UEN<1:0> bits in the UxMODE register configure these pins.

17.7 Infrared Support

The UART module provides two types of infrared UART support: one is the IrDA clock output to support an external IrDA encoder and decoder device (legacy module support), and the other is the full implementation of the IrDA encoder and decoder. Note that because the IrDA modes require a 16x baud clock, they will only work when the BRGH bit (UxMODE<3>) is '0'.

17.7.1 IrDA CLOCK OUTPUT FOR EXTERNAL IrDA SUPPORT

To support external IrDA encoder and decoder devices, the BCLKx pin (same as the UxRTS pin) can be configured to generate the 16x baud clock. With UEN<1:0> = 11, the BCLKx pin will output the 16x baud clock if the UART module is enabled. It can be used to support the IrDA codec chip.

17.7.2 BUILT-IN IrDA ENCODER AND DECODER

The UART has full implementation of the IrDA encoder and decoder as part of the UART module. The built-in IrDA encoder and decoder functionality is enabled using the IREN bit (UxMODE<12>). When enabled (IREN = 1), the receive pin (UxRX) acts as the input from the infrared receiver. The transmit pin (UxTX) acts as the output to the infrared transmitter.

REGISTER	17-1: UXM	ODE: UARTX I	NODE REG	ISTER			
R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0
UARTEN ⁽¹⁾		USIDL	IREN ⁽²⁾	RTSMD	—	UEN1	UEN0
bit 15							bit 8
R/W-0, HC	R/W-0	R/W-0, HC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
WAKE	LPBACK	ABAUD	RXINV	BRGH	PDSEL1	PDSEL0	STSEL
bit 7		, (2), (32)	104111	Bitteri	· DOLL ·	1 00220	bit 0
Lagandi		HC = Hardware		4			
Legend: R = Readabl	lo hit	W = Writable bi			nented bit, read	L 25 (0)	
-n = Value at		'1' = Bit is set	it.	'0' = Bit is clea		x = Bit is unkn	own
							OWIT
bit 15	UARTEN: UA	RTx Enable bit ⁽¹)				
		s enabled; all UA					
		disabled; all UAF	RTx pins are c	ontrolled by port	latches; UART>	c power consump	otion is minimal
bit 14	-	ted: Read as '0'					
bit 13		in Idle Mode bit		uice enterne Idle	mada		
		ue module operation			mode		
bit 12		Encoder and Dec					
		oder and decode					
	0 = IrDA enc	oder and decode	r are disable	d			
bit 11		le Selection for U					
		in is in Simplex r in is in Flow Con					
bit 10	Unimplemen	ted: Read as '0'					
bit 9-8	UEN<1:0>: ∪	ARTx Enable bit	S				
		UxRX and BCLK				controlled by po	ort latches
		UxRX, <u>UxCTS</u> ar UxRX and <u>UxRT</u>				controlled by p	ort latches
		ind UxRX pins an					
	latches	· · ·		,			
bit 7	WAKE: Wake	-up on Start Bit I	Detect During	Sleep Mode Er	nable bit		
		ill continue to sa			is generated or	n the falling edge	e, bit is cleared
		are on the followi -up is enabled	ing rising eag	e			
bit 6		RTx Loopback N	/lode Select b	bit			
		, oopback mode					
	0 = Loopbacl	k mode is disable	ed				
bit 5		-Baud Enable b					.
	cleared in	aud rate measu n hardware upon e measurement i	completion		r – requires re	ception of a Sy	nc field (55h);
Note 4: 1					finance of the second	weileble DD= /D/	
S	ection 10.4 "P	the peripheral inp eripheral Pin Se	elect (PPS)"	for more informa	ation.	ivaliable RPN/RI	-in pin. See
2 • ⊤	his feature is or	nlv available for t	he 16y BRG	mode (BRGH =	()		

REGISTER 17-1: UxMODE: UARTx MODE REGISTER

2: This feature is only available for the 16x BRG mode (BRGH = 0).

REGISTER 17-1: UXMODE: UARTX MODE REGISTER (CONTINUED)

- bit 4 **RXINV:** Receive Polarity Inversion bit
 - 1 = UxRX Idle state is '0'
 - 0 = UxRX Idle state is '1'
- bit 3 BRGH: High Baud Rate Enable bit
 - 1 = High-Speed mode (4 BRG clock cycles per bit)
 - 0 = Standard-Speed mode (16 BRG clock cycles per bit)
- bit 2-1 **PDSEL<1:0>:** Parity and Data Selection bits
 - 11 = 9-bit data, no parity
 - 10 = 8-bit data, odd parity
 - 01 = 8-bit data, even parity
 - 00 = 8-bit data, no parity
- bit 0 STSEL: Stop Bit Selection bit
 - 1 = Two Stop bits
 - 0 = One Stop bit
- Note 1: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.
 - **2:** This feature is only available for the 16x BRG mode (BRGH = 0).

REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER

R/W-0	R/W-0	R/W-0	U-0	R/W-0 HC	R/W-0	R-0, HSC	R-1, HSC	
UTXISEL1	UTXINV ⁽¹⁾	UTXISEL0		UTXBRK	UTXEN ⁽²⁾	UTXBF	TRMT	
bit 15 bit 8								

R/W-0	R/W-0	R/W-0	R-1, HSC	R-0, HSC	R-0, HSC	R/C-0, HS	R-0, HSC
URXISEL1	URXISEL0	ADDEN	RIDLE	PERR	FERR	OERR	URXDA
bit 7							bit 0

Legend:	C = Clearable bit	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	
HS = Hardware Settable bit	HC = Hardware Clearable bit			

bit 15,13 UTXISEL<1:0>: Transmission Interrupt Mode Selection bits

- 11 = Reserved; do not use
- 10 = Interrupt when a character is transferred to the Transmit Shift Register (TSR) and as a result, the transmit buffer becomes empty
- 01 = Interrupt when the last character is shifted out of the Transmit Shift Register; all transmit operations are completed
- 00 = Interrupt when a character is transferred to the Transmit Shift Register (this implies there is at least one character open in the transmit buffer)

bit 14 UTXINV: IrDA[®] Encoder Transmit Polarity Inversion bit⁽¹⁾

IREN = 0:

	IREN = 0:
	1 = UxTX is Idle '0'
	0 = UxTX is Idle '1'
	IREN = 1:
	1 = UxTX is Idle '1'
	0 = UxTX is Idle '0'
bit 12	Unimplemented: Read as '0'
bit 11	UTXBRK: Transmit Break bit
	 1 = Send Sync Break on next transmission – Start bit, followed by twelve '0' bits, followed by Stop bit; cleared by hardware upon completion
	0 = Sync Break transmission is disabled or completed
bit 10	UTXEN: Transmit Enable bit ⁽²⁾
	 1 = Transmit is enabled, UxTX pin controlled by UARTx 0 = Transmit is disabled, any pending transmission is aborted and the buffer is reset; UxTX pin is controlled by port.
bit 9	UTXBF: Transmit Buffer Full Status bit (read-only)
	1 = Transmit buffer is full
	0 = Transmit buffer is not full, at least one more character can be written
bit 8	TRMT: Transmit Shift Register Empty bit (read-only)
	1 = Transmit Shift Register is empty and transmit buffer is empty (the last transmission has completed)
	0 = Transmit Shift Register is not empty, a transmission is in progress or queued

Note 1: Value of bit only affects the transmit properties of the module when the $IrDA^{\textcircled{B}}$ encoder is enabled (IREN = 1).

2: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

REGISTER 17-2: UxSTA: UARTx STATUS AND CONTROL REGISTER (CONTINUED)

bit 7-6	URXISEL<1:0>: Receive Interrupt Mode Selection bits
	 11 = Interrupt is set on an RSR transfer, making the receive buffer full (i.e., has 4 data characters) 10 = Interrupt is set on an RSR transfer, making the receive buffer 3/4 full (i.e., has 3 data characters) 0x = Interrupt is set when any character is received and transferred from the RSR to the receive buffer; receive buffer has one or more characters
bit 5	ADDEN: Address Character Detect bit (bit 8 of received data = 1)
	 1 = Address Detect mode is enabled If 9-bit mode is not selected, this does not take effect. 0 = Address Detect mode is disabled
bit 4	RIDLE: Receiver Idle bit (read-only)
	 1 = Receiver is Idle 0 = Receiver is active
bit 3	PERR: Parity Error Status bit (read-only)
	 1 = Parity error has been detected for the current character (character at the top of the receive FIFO) 0 = Parity error has not been detected
bit 2	FERR: Framing Error Status bit (read-only)
	 1 = Framing error has been detected for the current character (character at the top of the receive FIFO) 0 = Framing error has not been detected
bit 1	OERR: Receive Buffer Overrun Error Status bit (clear/read-only)
	 1 = Receive buffer has overflowed 0 = Receive buffer has not overflowed (clearing a previously set OERR bit (1 → 0 transition); will reset the receiver buffer and the RSR to the empty state
bit 0	URXDA: Receive Buffer Data Available bit (read-only)
	 1 = Receive buffer has data, at least one more character can be read 0 = Receive buffer is empty
Note 1:	Value of bit only affects the transmit properties of the module when the $IrDA^{\textcircled{R}}$ encoder is enabled (IREN = 1).

2: If UARTEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

NOTES:

18.0 UNIVERSAL SERIAL BUS WITH ON-THE-GO SUPPORT (USB OTG)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the *"PIC24F Family Reference Manual"*, Section 27. "USB On-The-Go (OTG)" (DS39721). The information in this data sheet supersedes the information in the FRM.

PIC24FJ256DA210 family devices contain a full-speed and low-speed compatible, On-The-Go (OTG) USB Serial Interface Engine (SIE). The OTG capability allows the device to act either as a USB peripheral device or as a USB embedded host with limited host capabilities. The OTG capability allows the device to dynamically switch from device to host operation using OTG's Host Negotiation Protocol (HNP).

For more details on OTG operation, refer to the "On-The-Go Supplement to the USB 2.0 Specification", published by the USB-IF. For more details on USB operation, refer to the "Universal Serial Bus Specification", v2.0.

The USB OTG module offers these features:

- USB functionality in Device and Host modes, and OTG capabilities for application-controlled mode switching
- Software-selectable module speeds of full speed (12 Mbps) or low speed (1.5 Mbps, available in Host mode only)
- Support for all four USB transfer types: control, interrupt, bulk and isochronous
- 16 bidirectional endpoints for a total of 32 unique endpoints
- · DMA interface for data RAM access
- Queues up to sixteen unique endpoint transfers without servicing
- Integrated, on-chip USB transceiver with support for off-chip transceivers via a digital interface
- Integrated VBUS generation with on-chip comparators and boost generation, and support of external VBUS comparators and regulators through a digital interface
- Configurations for on-chip bus pull-up and pull-down resistors

A simplified block diagram of the USB OTG module is shown in Figure 18-1.

The USB OTG module can function as a USB peripheral device or as a USB host, and may dynamically switch between Device and Host modes under software control. In either mode, the same data paths and Buffer Descriptors (BDs) are used for the transmission and reception of data.

In discussing USB operation, this section will use a controller-centric nomenclature for describing the direction of the data transfer between the microcontroller and the USB. RX (Receive) will be used to describe transfers that move data from the USB to the microcontroller and TX (Transmit) will be used to describe transfers that move data from the microcontroller to the USB. Table 18-1 shows the relationship between data direction in this nomenclature and the USB tokens exchanged.

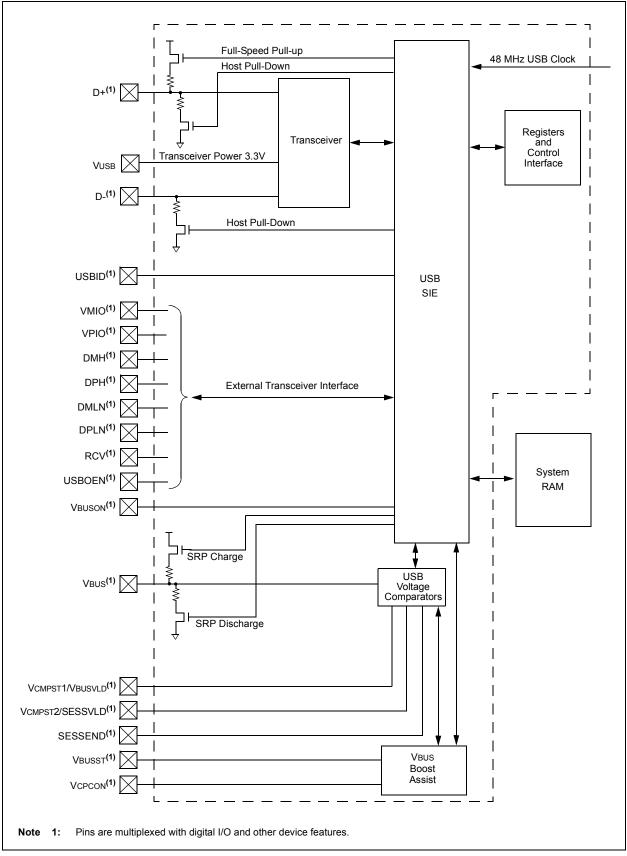
TABLE 18-1:CONTROLLER-CENTRIC
DATA DIRECTION FOR USB
HOST OR TARGET

USB Mode	Direction				
OSD MODE	RX	тх			
Device	OUT or SETUP	IN			
Host	IN	OUT or SETUP			

This chapter presents the most basic operations needed to implement USB OTG functionality in an application. A complete and detailed discussion of the USB protocol and its OTG supplement are beyond the scope of this data sheet. It is assumed that the user already has a basic understanding of USB architecture and the latest version of the protocol.

Not all steps for proper USB operation (such as device enumeration) are presented here. It is recommended that application developers use an appropriate device driver to implement all of the necessary features. Microchip provides a number of application-specific resources, such as USB firmware and driver support. Refer to <u>www.microchip.com/usb</u> for the latest firmware and driver support.

FIGURE 18-1: USB OTG MODULE BLOCK DIAGRAM



18.1 Hardware Configuration

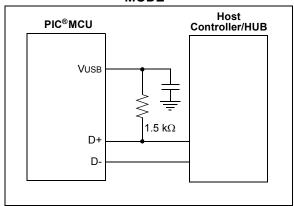
18.1.1 DEVICE MODE

18.1.1.1 D+ Pull-up Resistor

PIC24FJ256DA210 family devices have a built-in 1.5 kΩ resistor on the D+ line that is available when the microcontroller is operating in Device mode. This is used to signal an external Host that the device is operating in Full-Speed Device mode. It is engaged by setting the USBEN bit (U1CON<0>). If the OTGEN bit (U1OTGCON<2>) is set, then the D+ pull-up is enabled through the DPPULUP bit (U1OTGCON<7>).

Alternatively, an external resistor may be used on D+, as shown in Figure 18-2.

FIGURE 18-2: EXTERNAL PULL-UP FOR FULL-SPEED DEVICE MODE



18.1.1.2 Power Modes

Many USB applications will likely have several different sets of power requirements and configuration. The most common power modes encountered are:

- Bus Power Only mode
- Self-Power Only mode
- Dual Power with Self-Power Dominance

Bus Power Only mode (Figure 18-3) is effectively the simplest method. All power for the application is drawn from the USB.

To meet the inrush current requirements of the USB 2.0 Specification, the total effective capacitance appearing across VBUs and ground must be no more than 10 μ F.

In the USB Suspend mode, devices must consume no more than 2.5 mA from the 5V VBUS line of the USB cable. During the USB Suspend mode, the D+ or D-pull-up resistor must remain active, which will consume some of the allowed suspend current.

In Self-Power Only mode (Figure 18-4), the USB application provides its own power, with very little power being pulled from the USB. Note that an attach indication is added to indicate when the USB has been connected and the host is actively powering VBUS.

To meet compliance specifications, the USB module (and the D+ or D- pull-up resistor) should not be enabled until the host actively drives VBUS high. One of the 5.5V tolerant I/O pins may be used for this purpose.

The application should never source any current onto the 5V V $_{\rm BUS}$ pin of the USB cable.

The Dual Power mode with Self-Power Dominance (Figure 18-5) allows the application to use internal power primarily, but switch to power from the USB when no internal power is available. Dual power devices must also meet all of the special requirements for inrush current and Suspend mode current previously described, and must not enable the USB module until VBUS is driven high.

FIGURE 18-3: BUS POWER ONLY

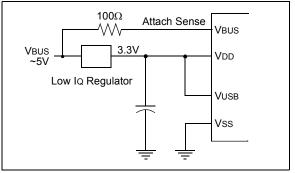


FIGURE 18-4: SELF-POWER ONLY

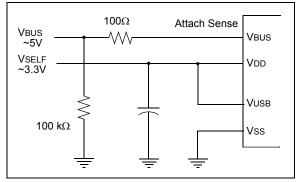
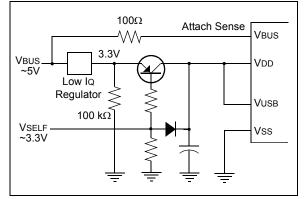


FIGURE 18-5: DUA

DUAL POWER EXAMPLE



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18.1.2 HOST AND OTG MODES

18.1.2.1 D+ and D- Pull-Down Resistors

PIC24FJ256DA210 family devices have a built-in 15 kΩ pull-down resistor on the D+ and D- lines. These are used in tandem to signal to the bus that the microcontroller is operating in Host mode. They are engaged by setting the HOSTEN bit (U1CON<3>). If the OTGEN bit (U1OTGCON<2>) is set, then these pull-downs are enabled by setting the DPPULDWN and DMPULDWN bits (U1OTGCON<5:4>).

18.1.2.2 Power Configurations

In Host mode, as well as Host mode in On-The-Go operation, the USB 2.0 Specification requires that the host application should supply power on VBUS. Since

the microcontroller is running below VBUS, and is not able to source sufficient current, a separate power supply must be provided.

When the application is always operating in Host mode, a simple circuit can be used to supply VBUS and regulate current on the bus (Figure 18-6). For OTG operation, it is necessary to be able to turn VBUS on or off as needed, as the microcontroller switches between Device and Host modes. A typical example using an external charge pump is shown in Figure 18-7.

FIGURE 18-6: HOST INTERFACE EXAMPLE

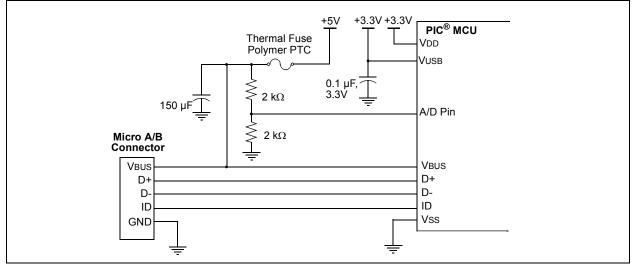
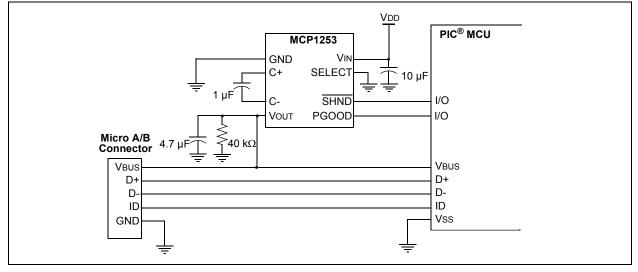


FIGURE 18-7: OTG INTERFACE EXAMPLE



18.1.2.3 VBUS Voltage Generation with External Devices

When operating as a USB host, either as an A-device in an OTG configuration or as an embedded host, VBUS must be supplied to the attached device. PIC24FJ256DA210 family devices have an internal VBUS boost assist to help generate the required 5V VBUS from the available voltages on the board. This is comprised of a simple PWM output to control a Switch mode power supply, and built-in comparators to monitor output voltage and limit current.

To enable voltage generation:

- Verify that the USB module is powered (U1PWRC<0> = 1) and that the VBUS discharge is disabled (U1OTGCON<0> = 0).
- 2. Set the PWM period (U1PWMRRS<7:0>) and duty cycle (U1PWMRRS<15:8>) as required.
- 3. Select the required polarity of the output signal based on the configuration of the external circuit with the PWMPOL bit (U1PWMCON<9>).
- 4. Select the desired target voltage using the VBUSCHG bit (U1OTGCON<1>).
- 5. Enable the PWM counter by setting the CNTEN bit to '1' (U1PWMCON<8>).
- 6. Enable the PWM module by setting the PWMEN bit (U1PWMCON<15>) to '1'.
- 7. Enable the VBUS generation circuit (U10TGCON<3> = 1).
 - Note: This section describes the general process for VBUS voltage generation and control. Please refer to the "*PIC24F Family Reference Manual*" for additional examples.

18.1.3 USING AN EXTERNAL INTERFACE

Some applications may require the USB interface to be isolated from the rest of the system. PIC24FJ256DA210 family devices include a complete interface to communicate with and control an external USB transceiver, including the control of data line pull-ups and pull-downs. The VBUS voltage generation control circuit can also be configured for different VBUS generation topologies.

Refer to the "*PIC24F Family Reference Manual*", **Section 27. "USB On-The-Go (OTG)**" for information on using the external interface.

18.1.4 CALCULATING TRANSCEIVER POWER REQUIREMENTS

The USB transceiver consumes a variable amount of current depending on the characteristic impedance of the USB cable, the length of the cable, the VUSB supply voltage and the actual data patterns moving across the USB cable. Longer cables have larger capacitances and consume more total energy when switching output states. The total transceiver current consumption will be application-specific. Equation 18-1 can help estimate how much current actually may be required in full-speed applications.

Refer to the "*PIC24F Family Reference Manual*", **Section 27. "USB On-The-Go (OTG)**" for a complete discussion on transceiver power consumption.

EQUATION 18-1: ESTIMATING USB TRANSCEIVER CURRENT CONSUMPTION

 $\mathsf{IXCVR} = \frac{40 \text{ mA} \cdot \mathsf{VUSB} \cdot \mathsf{PZERO} \cdot \mathsf{PIN} \cdot \mathsf{LCABLE}}{3.3 \text{ V} \cdot 5 \text{ m}} + \mathsf{IPULLUP}$

Legend: VUSB – Voltage applied to the VUSB pin in volts (3.0V to 3.6V).

PZERO – Percentage (in decimal) of the IN traffic bits sent by the PIC[®] microcontroller that are a value of '0'.

PIN – Percentage (in decimal) of total bus bandwidth that is used for IN traffic.

LCABLE – Length (in meters) of the USB cable. The USB 2.0 Specification requires that full-speed applications use cables no longer than 5m.

IPULLUP – Current which the nominal, 1.5 k Ω pull-up resistor (when enabled) must supply to the USB cable.

18.2 USB Buffer Descriptors and the BDT

Endpoint buffer control is handled through a structure called the Buffer Descriptor Table (BDT). This provides a flexible method for users to construct and control endpoint buffers of various lengths and configurations.

The BDT can be located in any available, 512-byte aligned block of data RAM. The BDT Pointer (U1BDTP1) contains the upper address byte of the BDT and sets the location of the BDT in RAM. The user must set this pointer to indicate the table's location.

The BDT is composed of Buffer Descriptors (BDs) which are used to define and control the actual buffers in the USB RAM space. Each BD consists of two, 16-bit "soft" (non-fixed-address) registers, BDnSTAT and BDnADR, where n represents one of the 64 possible BDs (range of 0 to 63). BDnSTAT is the status register for BDn, while BDnADR specifies the starting address for the buffer associated with BDn.

Note: Since BDnADR is a 16-bit register, only the first 64 Kbytes of RAM can be accessed by the USB module.

Depending on the endpoint buffering configuration used, there are up to 64 sets of Buffer Descriptors, for a total of 256 bytes. At a minimum, the BDT must be at least 8 bytes long. This is because the USB Specification mandates that every device must have Endpoint 0 with both input and output for initial setup.

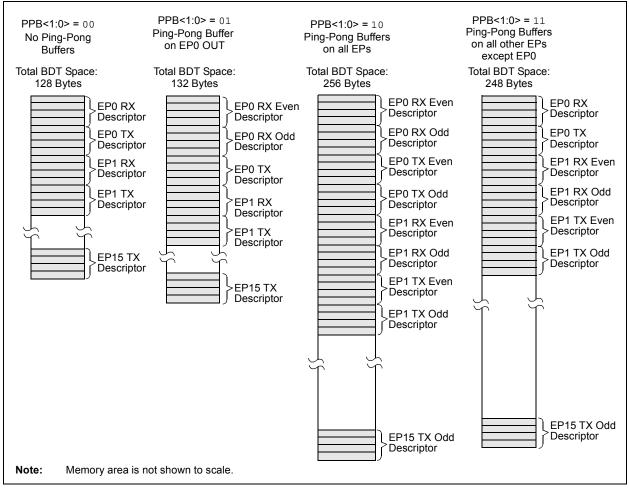
Endpoint mapping in the BDT is dependent on three variables:

- Endpoint number (0 to 15)
- Endpoint direction (RX or TX)
- Ping-pong settings (U1CNFG1<1:0>)

Figure 18-8 illustrates how these variables are used to map endpoints in the BDT.

In Host mode, only Endpoint 0 Buffer Descriptors are used. All transfers utilize the Endpoint 0 Buffer Descriptor and Endpoint Control register (U1EP0). For received packets, the attached device's source endpoint is indicated by the value of ENDPT<3:0> in the USB status register (U1STAT<7:4>). For transmitted packet, the attached device's destination endpoint is indicated by the value written to the Token register (U1TOK).

FIGURE 18-8: BDT MAPPING FOR ENDPOINT BUFFERING MODES



BDs have a fixed relationship to a particular endpoint, depending on the buffering configuration. Table 18-2 provides the mapping of BDs to endpoints. This relationship also means that gaps may occur in the BDT if endpoints are not enabled contiguously. This, theoretically, means that the BDs for disabled endpoints could be used as buffer space. In practice, users should avoid using such spaces in the BDT unless a method of validating BD addresses is implemented.

18.2.1 BUFFER OWNERSHIP

Because the buffers and their BDs are shared between the CPU and the USB module, a simple semaphore mechanism is used to distinguish which is allowed to update the BD and associated buffers in memory. This is done by using the UOWN bit as a semaphore to distinguish which is allowed to update the BD and associated buffers in memory. UOWN is the only bit that is shared between the two configurations of BDnSTAT.

When UOWN is clear, the BD entry is "owned" by the microcontroller core. When the UOWN bit is set, the BD entry and the buffer memory are "owned" by the USB peripheral. The core should not modify the BD or its

corresponding data buffer during this time. Note that the microcontroller core can still read BDnSTAT while the SIE owns the buffer and vice versa.

The Buffer Descriptors have a different meaning based on the source of the register update. Register 18-1 and Register 18-2 show the differences in BDnSTAT depending on its current "ownership".

When UOWN is set, the user can no longer depend on the values that were written to the BDs. From this point, the USB module updates the BDs as necessary, overwriting the original BD values. The BDnSTAT register is updated by the SIE with the token PID and the transfer count is updated.

18.2.2 DMA INTERFACE

The USB OTG module uses a dedicated DMA to access both the BDT and the endpoint data buffers. Since part of the address space of the DMA is dedicated to the Buffer Descriptors, a portion of the memory connected to the DMA must comprise a contiguous address space properly mapped for the access by the module.

TABLE 18-2:	ASSIGNMENT OF BUFFER DESCRIPTORS FOR THE DIFFERENT
	BUFFERING MODES

		BDs Assigned to Endpoint										
Endpoint	Mode 0 (No Ping-Pong)		Mode 1 (Ping-Pong on EP0 OUT)		Mode 2 (Ping-Pong on all EPs)		Mode 3 (Ping-Pong on all other EPs, except EP0)					
	Out	In	Out	In	Out	In	Out	In				
0	0	1	0 (E), 1 (O)	2	0 (E), 1 (O)	2 (E), 3 (O)	0	1				
1	2	3	3	4	4 (E), 5 (O)	6 (E), 7 (O)	2 (E), 3 (O)	4 (E), 5 (O)				
2	4	5	5	6	8 (E), 9 (O)	10 (E), 11 (O)	6 (E), 7 (O)	8 (E), 9 (O)				
3	6	7	7	8	12 (E), 13 (O)	14 (E), 15 (O)	10 (E), 11 (O)	12 (E), 13 (O)				
4	8	9	9	10	16 (E), 17 (O)	18 (E), 19 (O)	14 (E), 15 (O)	16 (E), 17 (O)				
5	10	11	11	12	20 (E), 21 (O)	22 (E), 23 (O)	18 (E), 19 (O)	20 (E), 21 (O)				
6	12	13	13	14	24 (E), 25 (O)	26 (E), 27 (O)	22 (E), 23 (O)	24 (E), 25 (O)				
7	14	15	15	16	28 (E), 29 (O)	30 (E), 31 (O)	26 (E), 27 (O)	28 (E), 29 (O)				
8	16	17	17	18	32 (E), 33 (O)	34 (E), 35 (O)	30 (E), 31 (O)	32 (E), 33 (O)				
9	18	19	19	20	36 (E), 37 (O)	38 (E), 39 (O)	34 (E), 35 (O)	36 (E), 37 (O)				
10	20	21	21	22	40 (E), 41 (O)	42 (E), 43 (O)	38 (E), 39 (O)	40 (E), 41 (O)				
11	22	23	23	24	44 (E), 45 (O)	46 (E), 47 (O)	42 (E), 43 (O)	44 (E), 45 (O)				
12	24	25	25	26	48 (E), 49 (O)	50 (E), 51 (O)	46 (E), 47 (O)	48 (E), 49 (O)				
13	26	27	27	28	52 (E), 53 (O)	54 (E), 55 (O)	50 (E), 51 (O)	52 (E), 53 (O)				
14	28	29	29	30	56 (E), 57 (O)	58 (E), 59 (O)	54 (E), 55 (O)	56 (E), 57 (O)				
15	30	31	31	32	60 (E), 61 (O)	62 (E), 63 (O)	58 (E), 59 (O)	60 (E), 61 (O)				

Legend: (E) = Even transaction buffer, (O) = Odd transaction buffer

REGISTER 18-1: BDnSTAT: BUFFER DESCRIPTOR n STATUS REGISTER PROTOTYPE, USB MODE (BD0STAT THROUGH BD63STAT)

R/W-x	R/W-x	R/W-x, HSC					
UOWN	DTS	PID3	PID2	PID1	PID0	BC9	BC8
bit 15		•					bit 8

| R/W-x, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| BC7 | BC6 | BC5 | BC4 | BC3 | BC2 | BC1 | BC0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15	 UOWN: USB Own bit 1 = The USB module owns the BD and its corresponding buffer; the CPU must not modify the BD or the buffer
bit 14	DTS: Data Toggle Packet bit 1 = Data 1 packet 0 = Data 0 packet
bit 13-10	PID<3:0>: Packet Identifier bits (written by the USB module) In Device mode: Represents the PID of the received token during the last transfer. In Host mode:
bit 9-0	Represents the last returned PID or the transfer status indicator. BC<9:0>: Byte Count bits This represents the number of bytes to be transmitted or the maximum number of bytes to be received during a transfer. Upon completion, the byte count is updated by the USB module with the actual number of bytes transmitted or received.

REGISTER 18-2: BDnSTAT: BUFFER DESCRIPTOR n STATUS REGISTER PROTOTYPE, CPU MODE (BD0STAT THROUGH BD63STAT)

R/W-x	R/W-x	r-0	r-0	R/W-x	R/W-x	R/W-x, HSC	R/W-x, HSC
UOWN	DTS ⁽¹⁾	Reserved	Reserved	DTSEN	BSTALL	BC9	BC8
bit 15							bit 8

| R/W-x, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| BC7 | BC6 | BC5 | BC4 | BC3 | BC2 | BC1 | BC0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/	Clearable bit	r = Reserved bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	id as '0'
-n = Value at POR	'1' = Bit is set	'r' = Reserved bit	x = Bit is unknown

bit 15	UOWN: USB Own bit
	 The microcontroller core owns the BD and its corresponding buffer; the USB module ignores all other fields in the BD
bit 14	DTS: Data Toggle Packet bit ⁽¹⁾
	1 = Data 1 packet
	0 = Data 0 packet
bit 13-12	Reserved: Maintain as '0'
bit 11	DTSEN: Data Toggle Synchronization Enable bit
	 1 = Data toggle synchronization is enabled; data packets with incorrect sync value will be ignored 0 = No data toggle synchronization is performed
bit 10	BSTALL: Buffer Stall Enable bit
	 1 = Buffer STALL enabled; STALL handshake issued if a token is received that would use the BD in the given location (UOWN bit remains set, BD value is unchanged); corresponding EPSTALL bit will get set on any STALL handshake 0 = Buffer STALL disabled
bit 9-0	BC<9:0>: Byte Count bits
	This represents the number of bytes to be transmitted or the maximum number of bytes to be received during a transfer. Upon completion, the byte count is updated by the USB module with the actual number of bytes transmitted or received.

Note 1: This bit is ignored unless DTSEN = 1.

18.3 USB Interrupts

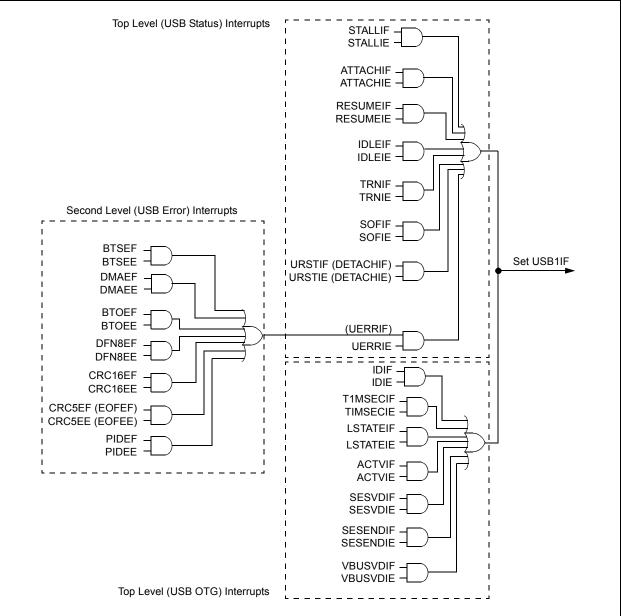
The USB OTG module has many conditions that can be configured to cause an interrupt. All interrupt sources use the same interrupt vector.

Figure 18-9 shows the interrupt logic for the USB module. There are two layers of interrupt registers in the USB module. The top level consists of overall USB status interrupts; these are enabled and flagged in the U1IE and U1IR registers, respectively. The second



level consists of USB error conditions, which are enabled and flagged in the U1EIR and U1EIE registers. An interrupt condition in any of these triggers a USB Error Interrupt Flag (UERRIF) in the top level.

Interrupts may be used to trap routine events in a USB transaction. Figure 18-10 provides some common events within a USB frame and their corresponding interrupts.



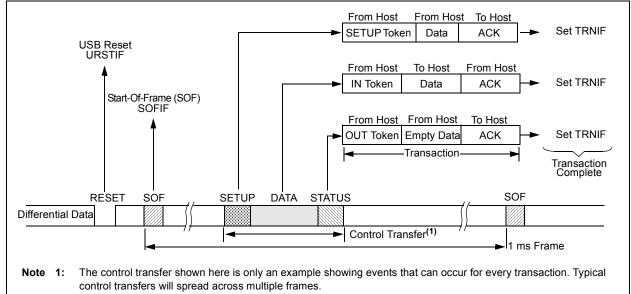
Downloaded From Oneyac.com

18.3.1 CLEARING USB OTG INTERRUPTS

Unlike device level interrupts, the USB OTG interrupt status flags are not freely writable in software. All USB OTG flag bits are implemented as hardware set only bits. Additionally, these bits can only be cleared in software by writing a '1' to their locations (i.e., performing a MOV type instruction). Writing a '0' to a flag bit (i.e., a BCLR instruction) has no effect.

Note: Throughout this data sheet, a bit that can only be cleared by writing a '1' to its location is referred to as "Write 1 to clear". In register descriptions, this function is indicated by the descriptor, "K".





18.4 Device Mode Operation

The following section describes how to perform a common Device mode task. In Device mode, USB transfers are performed at the transfer level. The USB module automatically performs the status phase of the transfer.

18.4.1 ENABLING DEVICE MODE

- Reset the Ping-Pong Buffer Pointers by setting, then clearing, the Ping-Pong Buffer Reset bit, PPBRST (U1CON<1>).
- 2. Disable all interrupts (U1IE and U1EIE = 00h).
- 3. Clear any existing interrupt flags by writing FFh to U1IR and U1EIR.
- 4. Verify that VBUS is present (non OTG devices only).

- 5. Enable the USB module by setting the USBEN bit (U1CON<0>).
- 6. Set the OTGEN bit (U1OTGCON<2>) to enable OTG operation.
- Enable the endpoint zero buffer to receive the first setup packet by setting the EPRXEN and EPHSHK bits for Endpoint 0 (U1EP0<3,0> = 1).
- 8. Power up the USB module by setting the USBPWR bit (U1PWRC<0>).
- 9. Enable the D+ pull-up resistor to signal an attach by setting DPPULUP bit (U10TGCON<7>).

18.4.2 RECEIVING AN IN TOKEN IN DEVICE MODE

- 1. Attach to a USB host and enumerate as described in "Chapter 9 of the USB 2.0 Specification".
- 2. Create a data buffer and populate it with the data to send to the host.
- 3. In the appropriate (even or odd) TX BD for the desired endpoint:
 - a) Set up the status register (BDnSTAT) with the correct data toggle (DATA0/1) value and the byte count of the data buffer.
 - b) Set up the address register (BDnADR) with the starting address of the data buffer.
 - c) Set the UOWN bit of the status register to 1^{1} .
- When the USB module receives an IN token, it automatically transmits the data in the buffer. Upon completion, the module updates the status register (BDnSTAT) and sets the Transfer Complete Interrupt Flag, TRNIF (U1IR<3>).

18.4.3 RECEIVING AN OUT TOKEN IN DEVICE MODE

- 1. Attach to a USB host and enumerate as described in *"Chapter 9 of the USB 2.0 Specification"*.
- 2. Create a data buffer with the amount of data you are expecting from the host.
- 3. In the appropriate (even or odd) TX BD for the desired endpoint:
 - a) Set up the status register (BDnSTAT) with the correct data toggle (DATA0/1) value and the byte count of the data buffer.
 - b) Set up the address register (BDnADR) with the starting address of the data buffer.
 - c) Set the UOWN bit of the status register to '1'.
- When the USB module receives an OUT token, it automatically receives the data sent by the host to the buffer. Upon completion, the module updates the status register (BDnSTAT) and sets the Transfer Complete Interrupt Flag, TRNIF (U1IR<3>).

18.5 Host Mode Operation

The following sections describe how to perform common Host mode tasks. In Host mode, USB transfers are invoked explicitly by the host software. The host software is responsible for the Acknowledge portion of the transfer. Also, all transfers are performed using the Endpoint 0 Control register (U1EP0) and Buffer Descriptors.

18.5.1 ENABLE HOST MODE AND DISCOVER A CONNECTED DEVICE

- Enable Host mode by setting the HOSTEN bit (U1CON<3>). This causes the Host mode control bits in other USB OTG registers to become available.
- Enable the D+ and D- pull-down resistors by setting the DPPULDWN and DMPULDWN bits (U10TGCON<5:4>). Disable the D+ and Dpull-up resistors by clearing the DPPULUP and DMPULUP bits (U10TGCON<7:6>).
- At this point, SOF generation begins with the SOF counter loaded with 12,000. Eliminate noise on the USB by clearing the SOFEN bit (U1CON<0>) to disable Start-Of-Frame packet generation.
- 4. Enable the device attached interrupt by setting the ATTACHIE bit (U1IE<6>).
- Wait for the device attached interrupt (U1IR<6> = 1). This is signaled by the USB device changing the state of D+ or D- from '0' to '1' (SE0 to J state). After it occurs, wait 100 ms for the device power to stabilize.
- Check the state of the JSTATE and SE0 bits in U1CON. If the JSTATE bit (U1CON<7>) is '0', the connecting device is low speed. If the connecting device is low speed, set the low LSPDEN and LSPD bits (U1ADDR<7> and U1EP0<7>) to enable low-speed operation.
- Reset the USB device by setting the USBRST bit (U1CON<4>) for at least 50 ms, sending Reset signaling on the bus. After 50 ms, terminate the Reset by clearing USBRST.
- 8. In order to keep the connected device from going into suspend, enable the SOF packet generation by setting the SOFEN bit.
- 9. Wait 10 ms for the device to recover from Reset.
- 10. Perform enumeration as described by "Chapter 9 of the USB 2.0 Specification".

18.5.2 COMPLETE A CONTROL TRANSACTION TO A CONNECTED DEVICE

- 1. Follow the procedure described in Section 18.5.1 "Enable Host Mode and Discover a Connected Device" to discover a device.
- Set up the Endpoint Control register for bidirectional control transfers by writing 0Dh to U1EP0 (this sets the EPCONDIS, EPTXEN and EPHSHK bits).
- 3. Place a copy of the device framework setup command in a memory buffer. See *"Chapter 9 of the USB 2.0 Specification"* for information on the device framework command set.
- 4. Initialize the Buffer Descriptor (BD) for the current (even or odd) TX EP0 to transfer the eight bytes of command data for a device framework command (i.e., GET DEVICE DESCRIPTOR):
 - a) Set the BD data buffer address (BD0ADR) to the starting address of the 8-byte memory buffer containing the command.
 - b) Write 8008h to BD0STAT (this sets the UOWN bit and sets a byte count of 8).
- Set the USB device address of the target device in the address register (U1ADDR<6:0>). After a USB bus Reset, the device USB address will be zero. After enumeration, it will be set to another value between 1 and 127.
- 6. Write D0h to U1TOK; this is a SETUP token to Endpoint 0, the target device's default control pipe. This initiates a SETUP token on the bus, followed by a data packet. The device handshake is returned in the PID field of BD0STAT after the packets are complete. When the USB module updates BD0STAT, a transfer done interrupt is asserted (the TRNIF flag is set). This completes the setup phase of the setup transaction as referenced in *"Chapter 9 of the USB Specification"*.
- 7. To initiate the data phase of the setup transaction (i.e., get the data for the GET DEVICE DESCRIPTOR command), set up a buffer in memory to store the received data.

- 8. Initialize the current (even or odd) RX or TX (RX for IN, TX for OUT) EP0 BD to transfer the data.
 - a) Write C040h to BD0STAT. This sets the UOWN, configures Data Toggle (DTS) to DATA1 and sets the byte count to the length of the data buffer (64 or 40h in this case).
 - b) Set BD0ADR to the starting address of the data buffer.
- 9. Write the Token register with the appropriate IN or OUT token to Endpoint 0, the target device's default control pipe (e.g., write 90h to U1TOK for an IN token for a GET DEVICE DESCRIPTOR command). This initiates an IN token on the bus followed by a data packet from the device to the host. When the data packet completes, the BD0STAT is written and a transfer done interrupt is asserted (the TRNIF flag is set). For control transfers with a single packet data phase, this completes the data phase of the setup transaction as referenced in *"Chapter 9 of the USB Specification"*. If more data needs to be transferred, return to step 8.
- 10. To initiate the status phase of the setup transaction, set up a buffer in memory to receive or send the zero length status phase data packet.
- 11. Initialize the current (even or odd) TX EP0 BD to transfer the status data:
 - a) Set the BDT buffer address field to the start address of the data buffer.
 - b) Write 8000h to BD0STAT (set UOWN bit, configure DTS to DATA0 and set byte count to 0).
- 12. Write the Token register with the appropriate IN or OUT token to Endpoint 0, the target device's default control pipe (e.g., write 01h to U1TOK for an OUT token for a GET DEVICE DESCRIPTOR command). This initiates an OUT token on the bus followed by a zero length data packet from the host to the device. When the data packet completes, the BD is updated with the handshake from the device and a transfer done interrupt is asserted (the TRNIF flag is set). This completes the status phase of the setup transaction as described in *"Chapter 9 of the USB Specification"*.
 - Note: Only one control transaction can be performed per frame.

18.5.3 SEND A FULL-SPEED BULK DATA TRANSFER TO A TARGET DEVICE

- Follow the procedure described in Section 18.5.1 "Enable Host Mode and Discover a Connected Device" and Section 18.5.2 "Complete a Control Transaction to a Connected Device" to discover and configure a device.
- To enable transmit and receive transfers with handshaking enabled, write 1Dh to U1EP0. If the target device is a low-speed device, also set the LSPD (U1EP0<7>) bit. If you want the hardware to automatically retry indefinitely if the target device asserts a NAK on the transfer, clear the Retry Disable bit, RETRYDIS (U1EP0<6>).
- 3. Set up the BD for the current (even or odd) TX EP0 to transfer up to 64 bytes.
- 4. Set the USB device address of the target device in the address register (U1ADDR<6:0>).
- 5. Write an OUT token to the desired endpoint to U1TOK. This triggers the module's transmit state machines to begin transmitting the token and the data.
- 6. Wait for the Transfer Done Interrupt Flag, TRNIF. This indicates that the BD has been released back to the microprocessor and the transfer has completed. If the retry disable bit is set, the handshake (ACK, NAK, STALL or ERROR (0Fh)) is returned in the BD PID field. If a STALL interrupt occurs, the pending packet must be dequeued and the error condition in the target device cleared. If a detach interrupt occurs (SE0 for more than 2.5 μs), then the target has detached (U1IR<0> is set).
- 7. Once the transfer done interrupt occurs (TRNIF is set), the BD can be examined and the next data packet queued by returning to step 2.
- **Note:** USB speed, transceiver and pull-ups should only be configured during the module setup phase. It is not recommended to change these settings while the module is enabled.

18.6 OTG Operation

18.6.1 SESSION REQUEST PROTOCOL (SRP)

An OTG A-device may decide to power down the VBUS supply when it is not using the USB link through the Session Request Protocol (SRP). Software may do this by clearing VBUSON (U10TGCON<3>). When the VBUS supply is powered down, the A-device is said to have ended a USB session.

An OTG A-device or embedded host may repower the VBUS supply at any time (initiate a new session). An OTG B-device may also request that the OTG A-device repower the VBUS supply (initiate a new session). This is accomplished via Session Request Protocol (SRP).

Prior to requesting a new session, the B-device must first check that the previous session has definitely ended. To do this, the B-device must check for two conditions:

1. VBUS supply is below the session valid voltage, and

2. Both D+ and D- have been low for at least 2 ms.

The B-device will be notified of Condition 1 by the SESENDIF (U1OTGIR<2>) interrupt. Software will have to manually check for Condition 2.

Note:	When the A-device powers down the VBUS
	supply, the B-device must disconnect its
	pull-up resistor from power. If the device is
	self-powered, it can do this by clearing
	DPPULUP (U1OTGCON<7>) and
	DMPULUP (U1OTGCON<6>).

The B-device may aid in achieving Condition 1 by discharging the VBUS supply through a resistor. Software may do this by setting VBUSDIS (U1OTGCON<0>).

After these initial conditions are met, the B-device may begin requesting the new session. The B-device begins by pulsing the D+ data line. Software should do this by setting DPPULUP (U10TGCON<7>). The data line should be held high for 5 to 10 ms.

The B-device then proceeds by pulsing the VBUS supply. Software should do this by setting PUVBUS (U1CNFG2<4>). When an A-device detects SRP signaling (either via the ATTACHIF (U1IR<6>) interrupt or via the SESVDIF (U1OTGIR<3>) interrupt), the A-device must restore the VBUS supply by either setting VBUSON (U1OTGCON<3>) or by setting the I/O port controlling the external power source.

The B-device should not monitor the state of the VBUS supply while performing VBUS supply pulsing. When the B-device does detect that the VBUS supply has been restored (via the SESVDIF (U1OTGIR<3>) interrupt), the B-device must reconnect to the USB link by pulling up D+ or D- (via the DPPULUP or DMPULUP).

The A-device must complete the SRP by driving USB Reset signaling.

18.6.2 HOST NEGOTIATION PROTOCOL (HNP)

In USB OTG applications, a Dual Role Device (DRD) is a device that is capable of being either a host or a peripheral. Any OTG DRD must support Host Negotiation Protocol (HNP).

HNP allows an OTG B-device to temporarily become the USB host. The A-device must first enable the B-device to follow HNP. Refer to the "On-The-Go Supplement to the USB 2.0 Specification" for more information regarding HNP. HNP may only be initiated at full speed.

After being enabled for HNP by the A-device, the B-device requests being the host any time that the USB link is in suspend state, by simply indicating a disconnect. This can be done in software by clearing DPPULUP and DMPULUP. When the A-device detects the disconnect condition (via the URSTIF (U1IR<0>) interrupt), the A-device may allow the B-device to take over as host. The A-device does this by signaling connect as a full-speed function. Software may accomplish this by setting DPPULUP.

If the A-device responds instead with resume signaling, the A-device remains as host. When the B-device detects the connect condition (via ATTACHIF (U1IR<6>), the B-device becomes host. The B-device drives Reset signaling prior to using the bus.

When the B-device has finished in its role as host, it stops all bus activity and turns on its D+ pull-up resistor by setting DPPULUP. When the A-device detects a suspend condition (Idle for 3 ms), the A-device turns off its D+ pull-up. The A-device may also power-down the VBUS supply to end the session. When the A-device detects the connect condition (via ATTACHIF), the A-device resumes host operation and drives Reset signaling.

18.6.3 **EXTERNAL VBUS COMPARATORS**

The external VBUS comparator option is enabled by setting the UVCMPDIS bit (U1CNFG2<1>). This disables the internal VBUS comparators, removing the need to attach VBUS to the microcontroller's VBUS pin.

The external comparator interface uses either the VCMPST1 and VCMPST2 pins, or the VBUSVLD, SESSVLD and SESSEND pins, based upon the setting of the UVCMPSEL bit (U1CNFG2<5>). These pins are digital inputs and should be set in the following patterns (see Table 18-3), based on the current level of the VBUS voltage.

TABLE 18-3: **EXTERNAL VBUS COMPARATOR STATES**

If UVCMPSEL = 0

VCMPST1	VCMPST2 Bus Condition					
0	0	0 VBUS < VB_SESS_END				
1	0	VB_SESS_END < VBUS < VA_SESS_VLD				
0	1	VA_SESS_VLD < VBUS < VA_VBUS_VLD				
1	1	VBUS > VBUS_VLD				

IF UVCMPSEL = 1

VBUSVLD	SESSVLD	SESSEND	Bus Condition						
0	0	1 VBUS < VB_SESS_END							
0	0	0	VB_SESS_END < VBUS < VA_SESS_VLD						
0	1	0	VA_SESS_VLD < VBUS < VA_VBUS_VLD						
1	1	0	VBUS > VBUS_VLD						

18.7 USB OTG Module Registers

There are a total of 37 memory mapped registers associated with the USB OTG module. They can be divided into four general categories:

- USB OTG Module Control (12)
- USB Interrupt (7)
- USB Endpoint Management (16)
- USB VBUS Power Control (2)

This total does not include the (up to) 128 BD registers in the BDT. Their prototypes, described in Register 18-1 and Register 18-2, are shown separately in **Section 18.2 "USB Buffer Descriptors and the BDT"**. With the exception of U1PWMCON and U1PWMRRS, all USB OTG registers are implemented in the Least Significant Byte of the register. Bits in the upper byte are unimplemented and have no function. Note that some registers are instantiated only in Host mode, while other registers have different bit instantiations and functions in Device and Host modes.

The registers described in the following sections are those that have bits with specific control and configuration features. The following registers are used for data or address values only:

- U1BDTP1: Specifies the 256-word page in data RAM used for the BDT; 8-bit value with bit 0 fixed as '0' for boundary alignment.
- U1FRML and U1FRMH: Contains the 11-bit byte counter for the current data frame.
- U1PWMRRS: Contains the 8-bit value for PWM duty cycle bits<15:8> and PWM period bits<7:0> for the VBUS boost assist PWM module.

18.7.1 USB OTG MODULE CONTROL REGISTERS

REGISTER 18-3: U10TGSTAT: USB OTG STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R-0, HSC	U-0	R-0, HSC	U-0	R-0, HSC	R-0, HSC	U-0	R-0, HSC
ID	—	LSTATE	—	SESVD	SESEND	—	VBUSVD
bit 7							bit 0

Legend:	U = Unimplemented b	U = Unimplemented bit, read as '0'					
R = Readable bit	W = Writable bit	HSC = Hardware Setta	ble/Clearable bit				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown				

bit 15-8	Unimplemented: Read as '0'
bit 7	ID: ID Pin State Indicator bit
	 1 = No plug is attached, or a type B cable has been plugged into the USB receptacle 0 = A type A plug has been plugged into the USB receptacle
bit 6	Unimplemented: Read as '0'
bit 5	LSTATE: Line State Stable Indicator bit
	 1 = The USB line state (as defined by SE0 and JSTATE) has been stable for the previous 1 ms 0 = The USB line state has not been stable for the previous 1 ms
bit 4	Unimplemented: Read as '0'
bit 3	SESVD: Session Valid Indicator bit
	1 = The VBUS voltage is above VA_SESS_VLD (as defined in the USB OTG Specification) on the A or B-device
	0 = The VBUS voltage is below VA_SESS_VLD on the A or B-device
bit 2	SESEND: B Session End Indicator bit
	1 = The VBUS voltage is below VB_SESS_END (as defined in the USB OTG Specification) on the B-device
	0 = The VBUS voltage is above VB_SESS_END on the B-device
bit 1	Unimplemented: Read as '0'
bit 0	VBUSVD: A VBUS Valid Indicator bit
	1 = The VBUS voltage is above VA_VBUS_VLD (as defined in the USB OTG Specification) on the A-device
	0 = The VBUS voltage is below VA VBUS VLD on the A-device

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
				<u> </u>		<u> </u>	_			
bit 15							bit			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
DPPULUF	DMPULUP	DPPULDWN ⁽¹⁾	DMPULDWN ⁽¹⁾	VBUSON ⁽¹⁾	OTGEN ⁽¹⁾	VBUSCHG ⁽¹⁾	VBUSDIS ⁽¹			
bit 7							bit			
Legend:										
R = Reada	ble bit	W = Writable bi	t	U = Unimplen	nented bit. re	ad as '0'				
-n = Value		'1' = Bit is set	-	'0' = Bit is cle		x = Bit is unkn	own			
							-			
bit 15-8	Unimpleme	nted: Read as '0	,							
bit 7	DPPULUP:	D+ Pull-up Enabl	le bit							
		line pull-up resis								
		line pull-up resis								
bit 6		DMPULUP: D- Pull-up Enable bit								
	 1 = D- data line pull-up resistor is enabled 0 = D- data line pull-up resistor is disabled 									
bit 5		I: D+ Pull-Down								
bito			esistor is enabled							
			esistor is disabled							
bit 4	DMPULDWI	PULDWN: D- Pull-Down Enable bit ⁽¹⁾								
		line pull-down re								
		-	sistor is disabled							
bit 3		BUS Power-on bi	t(I)							
		e is powered ie is not powered								
bit 2		G Features Enal								
			D+/D- pull-up and	d pull-down bit	s are enable	d				
	0 = USB OT	rG is disabled; D	+/D- pull-up and p 3EN (U1CON<3,0	oull-down bits			y the setting			
bit 1	VBUSCHG:	VBUS Charge Se	elect bit ⁽¹⁾							
	1 = VBUS lin	e is set to charge	e to 3.3V							
		e is set to charge								
bit 0		/BUS Discharge E								
			hrough a resistor							
	0 = VBUS lin	e is not discharg	60							

Note 1: These bits are only used in Host mode; do not use in Device mode.

REGISTER 18-5: U1PWRC: USB POWER CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—	—	—	—	—	—	—	—	
bit 15 bit 8								

R/W-0, HS	U-0	U-0	R/W-0	U-0	U-0	R/W-0, HC	R/W-0	
UACTPND	—	—	USLPGRD	_	-	USUSPND	USBPWR	
bit 7 bit 0								

Legend:	HS = Hardware Settable bit	HC = Hardware Clearal	ble bit
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
bit 7	UACTPND: USB Activity Pending bit
	 1 = Module should not be suspended at the moment (requires the USLPGRD bit to be set) 0 = Module may be suspended or powered down
bit 6-5	Unimplemented: Read as '0'
bit 4	USLPGRD: Sleep/Suspend Guard bit
	 1 = Indicate to the USB module that it is about to be suspended or powered down 0 = No suspend
bit 3-2	Unimplemented: Read as '0'
bit 1	 USUSPND: USB Suspend Mode Enable bit 1 = USB OTG module is in Suspend mode; USB clock is gated and the transceiver is placed in a low-power state 0 = Normal USB OTG operation
bit 0	USBPWR: USB Operation Enable bit 1 = USB OTG module is enabled 0 = USB OTG module is disabled ⁽¹⁾
Note 1:	Do not clear this bit unless the HOSTEN, USBEN and OTGEN bits (U1CON<3,0> and U1OTGCON<2>)

are all cleared.

REGISTER 18-6: U1STAT: USB STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	_	—	—	—	—	—
bit 15							bit 8

R-0, HSC	U-0	U-0					
ENDPT3	ENDPT2	ENDPT1	ENDPT0	DIR	PPBI ⁽¹⁾	—	—
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'					
R = Readable bit	W = Writable bit	HSC = Hardware Settable/Clearable bit				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-8 bit 7-4	Unimplemented: Read as '0' ENDPT<3:0>: Number of the Last Endpoint Activity bits (Represents the number of the BDT updated by the last USB transfer.) 1111 = Endpoint 15 1110 = Endpoint 14
	•
	0001 = Endpoint 1
	0000 = Endpoint 0
bit 3	DIR: Last BD Direction Indicator bit
	 1 = The last transaction was a transmit transfer (TX) 0 = The last transaction was a receive transfer (RX)
bit 2	PPBI: Ping-Pong BD Pointer Indicator bit ⁽¹⁾
	1 = The last transaction was to the odd BD bank0 = The last transaction was to the even BD bank
bit 1-0	Unimplemented: Read as '0'

Note 1: This bit is only valid for endpoints with available even and odd BD registers.

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8
U-0	R-x, HSC	R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0
	SE0	PKTDIS		HOSTEN	RESUME	PPBRST	USBEN
bit 7							bit 0
Legend:		U = Unimplen	nented bit, read	l as '0'			
R = Readal	ole bit	W = Writable	bit	HSC = Hardw	are Settable/C	learable bit	
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	nown
bit 15-7	Unimplemen	ted: Read as ')'				
bit 6	SE0: Live Sin	gle-Ended Zero	o Flag bit				
	0	nded zero is ac		3 bus			
	•	e-ended zero is					
bit 5		ket Transfer Di					
		n and packet pr n and packet pr			atically set whe	in a SETUP tok	en is received
bit 4	Unimplemen	ted: Read as ')'				
bit 3	HOSTEN: Ho	st Mode Enable	e bit				
		t capability is e		wns on D+ and	D- are activate	ed in hardware	
		t capability is d					
bit 2		esume Signaling	-				
		signaling is act signaling is dis					
bit 1		g-Pong Buffers					
		l Ping-Pong Bu			anks		
hit O	•	ng Buffer Point		ει			
bit 0		3 Module Enable Iule and support		enabled (device	attached). D± :	null-un is activat	ed in hardware
		dule and support	• •	•		•	

REGISTER 18-7: U1CON: USB CONTROL REGISTER (DEVICE MODE)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
_		<u> </u>	—	<u> </u>		—	_				
bit 15							bit				
R-x, HSC	R-x, HSC	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
JSTATE	SE0	TOKBUSY	USBRST	HOSTEN	RESUME	PPBRST	SOFEN				
bit 7							bit				
Legend:		U = Unimplem	ented bit, read	d as '0'							
R = Readab	le bit	W = Writable I	oit	HSC = Hardw	are Settable/C	learable bit					
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown				
bit 15-8	Unimplemen	ted: Read as '0)'								
bit 7		e Differential Re		•							
		lifferential '0' in	low speed, diff	ferential '1' in fu	ull speed) is de	tected on the L	JSB				
	0 = No J stat										
bit 6		SE0: Live Single-Ended Zero Flag bit									
	 1 = Single-ended zero is active on the USB bus 0 = No single-ended zero is detected 										
bit 5	•	TOKBUSY: Token Busy Status bit									
	1 = Token is being executed by the USB module in On-The-Go state										
	0 = No token is being executed										
bit 4	USBRST: Mo	USBRST: Module Reset bit									
	1 = USB Reset has been generated; for software Reset, application must set this bit for 50 ms, the										
	clear it 0 = USB Reset is terminated										
bit 3											
DIL S		HOSTEN: Host Mode Enable bit									
	 1 = USB host capability is enabled; pull-downs on D+ and D- are activated in hardware 0 = USB host capability is disabled 										
bit 2	RESUME: Resume Signaling Enable bit										
	1 = Resume signaling is activated; software must set bit for 10 ms and then clear to enable remote										
	wake-up 0 = Resume signaling is disabled										
bit 1		g-Pong Buffers									
		I Ping-Pong Builers		the even BD h	anks						
		ng Buffer Pointe									
bit 0		t-Of-Frame Ena									
	1 = Start-Of-I	1 = Start-Of-Frame token is sent every one 1 ms									
	0 = Start-Of-Frame token is disabled										

REGISTER 18-9: U1ADDR: USB ADDRESS REGISTER								
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—	—	—	—	—	—	—	—	
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
LSPDEN ⁽¹⁾	ADDR6	ADDR5	ADDR4	ADDR3	ADDR2	ADDR1	ADDR0	
bit 7	•			·		•	bit 0	
Legend:								
R = Readable	bit	W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1' =		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		
bit 15-8	Unimplemen	ted: Read as '	o'					

bit 7	LSPDEN: Low-Speed Enable Indicator bit ⁽¹⁾
	1 = USB module operates at low speed
	0 = USB module operates at full speed
bit 6-0	ADDR<6:0>: USB Device Address bits

Note 1: Host mode only. In Device mode, this bit is unimplemented and read as '0'.

REGISTER 18-10: U1TOK: USB TOKEN REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PID3 | PID2 | PID1 | PID0 | EP3 | EP2 | EP1 | EP0 |
| bit 7 | | | | | | | bit 0 |

Legend:						
R = Readable bit	R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'					
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-8	Unimplemented: Read as '0'
bit 7-4	PID<3:0>: Token Type Identifier bits
	1101 = SETUP (TX) token type transaction ⁽¹⁾ 1001 = IN (RX) token type transaction ⁽¹⁾ 0001 = OUT (TX) token type transaction ⁽¹⁾
bit 3-0	EP<3:0>: Token Command Endpoint Address bits
	This value must specify a valid endpoint on the attached device

This value must specify a valid endpoint on the attached device.

Note 1: All other combinations are reserved and are not to be used.

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REGISTER 18-11: U1SOF: USB OTG START-OF-TOKEN THRESHOLD REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	-	_	—	—
bit 15	·			÷			bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CNT7	CNT6	CNT5	CNT4	CNT3	CNT2	CNT1	CNT0
bit 7	•			•			bit 0
Legend:							

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'	
-n = Value at POR (1' = Bit is set 0' = Bit is cleared x = Bit is unknown	

bit 15-8 Unimplemented: Read as '0'

bit 7-0	CNT<7:0>: Start-Of-Frame Size bits Value represents 10 + (packet size of n bytes). For example:
	0100 1010 = 64-byte packet
	0010 1010 = 32-byte packet
	0001 0010 = 8-byte packet

REGISTER 18-12: U1CNFG1: USB CONFIGURATION REGISTER 1

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
		—	_		—					
bit 15							bit 8			
R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0			
UTEYE			USBSIDL	_		PPB1	PPB0			
bit 7			COBOIDE			11.51	bit 0			
Legend:										
R = Read	able bit	W = Writable	bit	U = Unimplem	nented bit, rea	d as '0'				
-n = Value	e at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	iown			
bit 15-8 bit 7 bit 6 bit 5 bit 4	UTEYE: USB 1 = Eye patte 0 = Eye patte UOEMON: US 1 = <u>OE</u> signa 0 = OE signa Unimplement USBSIDL: US	l is inactive ted: Read as ' SB OTG Stop in	est Enable bit led Enable bit ⁽¹⁾ dicates interval o ['] n Idle Mode bit			es are driving				
			tion in Idle mod	ie device enters de	s Idle mode					
bit 3-2	Unimplement	ted: Read as '	0'							
bit 1-0	11 = Even/Oo 10 = Even/Oo 01 = Even/Oo	dd ping-pong b dd ping-pong b dd ping-pong b	uffers are enal	bled for Endpoin bled for all endp bled for OUT En	points					
Note 1:	This bit is only act	s bit is only active when the UTRDIS bit (U1CNFG2<0>) is set.								

REGISTER 18-13: U1CNFG2: USB CONFIGURATION REGISTER 2

	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
_	_	_	—			_	_			
bit 15				•	•		bit			
U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
—	—	UVCMPSEL	PUVBUS	EXTI2CEN	UVBUSDIS ⁽¹⁾	UVCMPDIS ⁽¹⁾	UTRDIS ⁽¹⁾			
bit 7							bit			
Legend:										
R = Readab		W = Writable b	bit		nented bit, read	l as '0'				
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkno	own			
bit 15-6	Unimplemer	nted: Read as '0	,							
bit 5		VBUS Compara								
		SVLD, SESSVLD				ns				
	0 = Use VCMPST1 and VCMPST2 as comparator interface pins									
	PUVBUS: VBUS Pull-Up Enable bit									
bit 4	PUVBUS: VE	•	ble bit							
bit 4	PUVBUS: VE 1 = Pull-up c	n Vв∪s pin is er	ole bit nabled							
	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c	on VBUS pin is er on VBUS pin is di	ble bit nabled sabled							
	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I	on VB∪s pin is er on VB∪s pin is di ² C™ Interface F	ole bit nabled sabled for External M	odule Control E	Enable bit					
	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External	on VB∪s pin is er on VB∪s pin is di ² C™ Interface F module(s) is con	ble bit habled sabled for External M htrolled via the	odule Control E e l ² C™ interfac	Enable bit					
bit 3	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External	on VB∪s pin is er on VB∪s pin is di ² C™ Interface F module(s) is con module(s) contr	ole bit nabled sabled for External M ntrolled via the olled via the d	odule Control E e l ² C™ interfac ledicated pins	Enable bit e					
bit 4 bit 3 bit 2	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS:	on VB∪s pin is er on VB∪s pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo	ole bit nabled sabled for External M ntrolled via the olled via the o ost Regulator I	odule Control E e I ² C™ interfac ledicated pins Builder Disable	Enable bit e bit ⁽¹⁾	rface is enabled	4			
bit 3	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS: 1 = On-chip	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I	ole bit nabled sabled or External M ntrolled via the olled via the o ost Regulator I builder is disa	odule Control E e I ² C™ interfac ledicated pins Builder Disable bled; digital out	Enable bit e bit ⁽¹⁾	rface is enabled	ł			
bit 3 bit 2	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS: 1 = On-chip 0 = On-chip	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I boost regulator I	ole bit nabled sabled or External M ntrolled via the olled via the o ost Regulator I builder is disal builder is activ	odule Control E e l ² C™ interfac ledicated pins Builder Disable bled; digital out re	Enable bit e bit ⁽¹⁾	rface is enabled	1			
bit 3 bit 2	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS: 1 = On-chip 0 = On-chip UVCMPDIS:	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I on-Chip VBUS (ole bit nabled sabled for External M ntrolled via the olled via the o bat Regulator I builder is disa builder is activ Comparator Di	odule Control E e I ² C™ interfac ledicated pins Builder Disable bled; digital out re sable bit ⁽¹⁾	Enable bit e bit ⁽¹⁾ put control inte					
bit 3 bit 2	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS: 1 = On-chip 0 = On-chip UVCMPDIS: 1 = On-chip	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I boost regulator I	ole bit nabled sabled for External M ntrolled via the olled via the o bost Regulator I builder is disa builder is activ Comparator Di mparator is disa	odule Control E e l ² C™ interfac ledicated pins Builder Disable bled; digital out re sable bit ⁽¹⁾ sabled; digital ii	Enable bit e bit ⁽¹⁾ put control inte					
bit 3	PUVBUS: Ve 1 = Pull-up c 0 = Pull-up c EXTI2CEN: I 1 = External 0 = External UVBUSDIS: 1 = On-chip 0 = On-chip UVCMPDIS: 1 = On-chip 0 = On-chip	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I boost regulator I On-Chip VBUS C charge VBUS con charge VBUS con	ole bit nabled sabled for External M ntrolled via the olled via the o ost Regulator I builder is disa builder is activ Comparator Di mparator is di mparator is activ	odule Control E e I ² C™ interfac ledicated pins Builder Disable bled; digital out e sable bit ⁽¹⁾ sabled; digital in tive	Enable bit e bit ⁽¹⁾ put control inte					
bit 3 bit 2 bit 1	PUVBUS: Ver 1 = Pull-up of 0 = Pull-up of EXTI2CEN: If 1 = External 0 = External UVBUSDIS: 1 = On-chip UVCMPDIS: 1 = On-chip 0 = On-chip UTRDIS: On	on VBUS pin is er on VBUS pin is di ² C™ Interface F module(s) is con module(s) contr On-Chip 5V Boo boost regulator I on-Chip VBUS C charge VBUS con	ble bit nabled sabled for External M ntrolled via the olled via the o best Regulator I builder is disal builder is activ Comparator Di mparator is di mparator is di er Disable bit ⁽	odule Control E e I ² C™ interfac ledicated pins Builder Disable bled; digital out re sable bit ⁽¹⁾ sabled; digital in tive	Enable bit e bit ⁽¹⁾ put control inte nput status inte	rface is enabled				

Note 1: Never change these bits while the USBPWR bit is set (U1PWRC<0> = 1).

18.7.2 USB INTERRUPT REGISTERS

REGISTER 18-14: U1OTGIR: USB OTG INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	<u> </u>	<u> </u>	_	<u> </u>			—
bit 15							bit 8
544.0.110				5/// 0 1/0			5// 0 110
R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	U-0	R/K-0, HS
IDIF	T1MSECIF	LSTATEIF	ACTVIF	SESVDIF	SESENDIF		VBUSVDIF
bit 7							bit (
Legend:		U = Unimplem	ented bit. read	1 as '0'			
R = Readable	bit	K = Write '1' to			re Settable bit		
-n = Value at I		'1' = Bit is set		'0' = Bit is clea		x = Bit is unl	known
	-						-
bit 15-8	Unimplement	ted: Read as '0)'				
bit 7	IDIF: ID State	Change Indica	tor bit				
	1 = Change i	n ID state is de	tected				
	0 = No ID sta	ite change is de	etected				
bit 6	T1MSECIF: 1	Millisecond Tir	mer bit				
		lisecond timer					
		lisecond timer		d			
bit 5	-	ne State Stable					
	1 = USB line the last ti	-	d by the SE0 a	IND JSTATE DIts	s) has been stab	le for 1 ms, b	ut different fror
		state has not b	een stable for	1 ms			
bit 4	ACTVIF: Bus	Activity Indicat	or bit				
		n the D+/D- line		letected			
		y on the D+/D-					
bit 3	SESVDIF: Se	ssion Valid Cha	ange Indicator	bit			
					USB OTG Spe	cification) ⁽¹⁾	
		not crossed V					
bit 2		B-Device VBUS	•				
		ange on B-devi cification) ⁽¹⁾	ce detected; V	BUS has cross	ed VB_SESS_I	END (as defi	ned in the USI
		s not crossed V	A SESS END	1			
bit 1		ted: Read as '0					
bit 0	-	A-Device VBUS		tor bit			
	1 = VBUS cha	ange on A-devid	•		sed VA_VBUS_	VLD (as def	ined in the USI
	UIG Spe	cification) ⁽¹⁾					
	0 = No VBUS	change on A-d	evice is detect	ed			

Note: Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

REGISTER 18-15: U1OTGIE: USB OTG INTERRUPT ENABLE REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0
IDIE	T1MSECIE	LSTATEIE	ACTVIE	SESVDIE	SESENDIE	_	VBUSVDIE
bit 7							bit 0

Legend:				
R = Readal	ble bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value a	at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown
bit 15-8	-	mented: Read as '0'		
bit 7		Interrupt Enable bit		
		rupt is enabled rupt is disabled		
L:1 0		•		
bit 6		IE: 1 Millisecond Timer Inter	rupt Enable bit	
		rupt is enabled rupt is disabled		
bit 5		E: Line State Stable Interrup	t Enable bit	
		rupt is enabled		
		rupt is disabled		
bit 4	ACTVIE:	Bus Activity Interrupt Enable	e bit	
	1 = Inter	rupt is enabled		
	0 = Inter	rupt is disabled		
bit 3	SESVDIE	E: Session Valid Interrupt En	able bit	
		rupt is enabled		
		rupt is disabled		
bit 2		IE: B-Device Session End Ir	iterrupt Enable bit	
		rupt is enabled		
		rupt is disabled		
bit 1	-	mented: Read as '0'		
bit 0		IE: A-Device VBUS Valid Inte	errupt Enable bit	
		rupt is enabled		
	0 = inter	rupt is disabled		

REGISTER 18-16: U1IR: USB INTERRUPT STATUS REGISTER (DEVICE MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
—		—	—	—	—	—	—	
bit 15							bit 8	
R/K-0, HS	U-0	R/K-0, HS	R/K-0, HS	R/K-0, HS	R/K-0, HS	R-0	R/K-0, HS	
STALLIF	—	RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	URSTIF	
bit 7							bit 0	
Legend: U = Unimplemented bit, read a			l as '0'					
R = Readable bit K = Write '1' to clear bit			o clear bit	HS = Hardware Settable bit				
-n = Value at POR '1' = Bit is set			'0' = Bit is clea	ared	x = Bit is unkr	nown		

bit 15-8	Unimplemented: Read as '0'
bit 7	STALLIF: STALL Handshake Interrupt bit
	 1 = A STALL handshake was sent by the peripheral during the handshake phase of the transaction in Device mode
	0 = A STALL handshake has not been sent
bit 6	Unimplemented: Read as '0'
bit 5	RESUMEIF: Resume Interrupt bit
	 1 = A K-state is observed on the D+ or D- pin for 2.5 μs (differential '1' for low speed, differential '0' for full speed) 0 = No K-state is observed
bit 4	IDLEIF: Idle Detect Interrupt bit
	 1 = Idle condition is detected (constant Idle state of 3 ms or more) 0 = No Idle condition is detected
bit 3	TRNIF: Token Processing Complete Interrupt bit
	 1 = Processing of the current token is complete; read the U1STAT register for endpoint information 0 = Processing of the current token is not complete; clear the U1STAT register or load the next token from STAT (clearing this bit causes the STAT FIFO to advance)
bit 2	SOFIF: Start-Of-Frame Token Interrupt bit
	 1 = A Start-Of-Frame token is received by the peripheral or the Start-Of-Frame threshold is reached by the host
	0 = No Start-Of-Frame token is received or threshold reached
bit 1	UERRIF: USB Error Condition Interrupt bit (read-only)
	 1 = An unmasked error condition has occurred; only error states enabled in the U1EIE register can set this bit
	0 = No unmasked error condition has occurred
bit 0	URSTIF: USB Reset Interrupt bit
	1 = Valid USB Reset has occurred for at least 2.5 μs; Reset state must be cleared before this bit can be reasserted
	0 = No USB Reset has occurred. Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise oper- ations to write to a single bit position will cause all set bits at the moment of the write to become cleared.
Note:	Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

REGISTER 18-17: U1IR: USB INTERRUPT STATUS REGISTER (HOST MODE ONLY)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/K-0, HS	R-0	R/K-0, HS					
STALLIF	ATTACHIF	RESUMEIF	IDLEIF	TRNIF	SOFIF	UERRIF	DETACHIF
bit 7							bit 0

Legend:	U = Unimplemented bit, re	ad as '0'	
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable	e bit
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented: Read as '0'
bit 7	STALLIF: STALL Handshake Interrupt bit
	 1 = A STALL handshake was sent by the peripheral device during the handshake phase of the transaction in Device mode A STALL handshake has not been cent
-:+ C	0 = A STALL handshake has not been sent
bit 6	ATTACHIF: Peripheral Attach Interrupt bit
	 1 = A peripheral attachment has been detected by the module; it is set if the bus state is not SE0 and there has been no bus activity for 2.5 μs 0 = No peripheral attacement has been detected
bit 5	RESUMEIF: Resume Interrupt bit
	 1 = A K-state is observed on the D+ or D- pin for 2.5 μs (differential '1' for low speed, differential '0' for full speed)
	0 = No K-state is observed
bit 4	IDLEIF: Idle Detect Interrupt bit
	 1 = Idle condition is detected (constant Idle state of 3 ms or more) 0 = No Idle condition is detected
bit 3	TRNIF: Token Processing Complete Interrupt bit
	 1 = Processing of the current token is complete; read the U1STAT register for endpoint information 0 = Processing of the current token not complete; clear the U1STAT register or load the next token from U1STAT
bit 2	SOFIF: Start-Of-Frame Token Interrupt bit
	 1 = A Start-Of-Frame token received by the peripheral or the Start-Of-Frame threshold reached by the host 0 = No Start-Of-Frame token received or threshold reached
bit 1	UERRIF: USB Error Condition Interrupt bit
	 1 = An unmasked error condition has occurred; only error states enabled in the U1EIE register can set this bit
	0 = No unmasked error condition has occurred
bit 0	DETACHIF: Detach Interrupt bit
	 1 = A peripheral detachment has been detected by the module; Reset state must be cleared before this bit can be reasserted
	0 = No peripheral detachment is detected. Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bit- wise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.
Note:	Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause

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all set bits at the moment of the write to become cleared.

REGISTER 18-18: U1IE: USB INTERRUPT ENABLE REGISTER (ALL USB MODES)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	_	—		—	-	—
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
STALLIE	ATTACHIE ⁽¹⁾	RESUMEIE	IDLEIE	TRNIE	SOFIE	UERRIE	URSTIE
							DETACHIE

Legend:					
R = Readabl	e bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR		'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	
bit 15-8 bit 7	-	nented: Read as '0' STALL Handshake Interrup	ot Enable bit		

DIT 7	STALLIE: STALL Handshake Interrupt Enable bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 6	ATTACHIE: Peripheral Attach Interrupt bit (Host mode only) ⁽¹⁾
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 5	RESUMEIE: Resume Interrupt bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 4	IDLEIE: Idle Detect Interrupt bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 3	TRNIE: Token Processing Complete Interrupt bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 2	SOFIE: Start-Of-Frame Token Interrupt bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 1	UERRIE: USB Error Condition Interrupt bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled
bit 0	URSTIE or DETACHIE: USB Reset Interrupt (Device mode) or USB Detach Interrupt (Host mode) Enable bit
	1 = Interrupt is enabled
	0 = Interrupt is disabled

- ·
- Note 1: Unimplemented in Device mode, read as '0'.

bit 7

bit 0

REGISTER 18-19: U1EIR: USB ERROR INTERRUPT STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

R/K-0, HS	U-0	R/K-0, HS					
BTSEF	—	DMAEF	BTOEF	DFN8EF	CRC16EF	CRC5EF	PIDEF
						EOFEF	
bit 7							bit 0

Legend:	U = Unimplemented bit, read as '0'					
R = Readable bit	K = Write '1' to clear bit	HS = Hardware Settable bit				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-8	Unimplemented: Read as '0'
bit 7	BTSEF: Bit Stuff Error Flag bit
	 1 = Bit stuff error has been detected 0 = No bit stuff error has been detected
bit 6	Unimplemented: Read as '0'
bit 5	 DMAEF: DMA Error Flag bit 1 = A USB DMA error condition is detected; the data size indicated by the BD byte count field is less than the number of received bytes, the received data is truncated 0 = No DMA error
bit 4	BTOEF: Bus Turnaround Time-out Error Flag bit 1 = Bus turnaround time-out has occurred 0 = No bus turnaround time-out
bit 3	DFN8EF: Data Field Size Error Flag bit
	 1 = Data field was not an integral number of bytes 0 = Data field was an integral number of bytes
bit 2	CRC16EF: CRC16 Failure Flag bit
	1 = CRC16 failed 0 = CRC16 passed
bit 1	<u>For Device mode:</u> CRC5EF: CRC5 Host Error Flag bit
	 1 = Token packet is rejected due to CRC5 error 0 = Token packet is accepted (no CRC5 error)
	<u>For Host mode:</u> EOFEF: End-Of-Frame Error Flag bit 1 = End-Of-Frame error has occurred 0 = End-Of-Frame interrupt is disabled
bit 0	PIDEF: PID Check Failure Flag bit
5.00	1 = PID check failed
	0 = PID check passed

Note: Individual bits can only be cleared by writing a '1' to the bit position as part of a word write operation on the entire register. Using Boolean instructions or bitwise operations to write to a single bit position will cause all set bits at the moment of the write to become cleared.

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U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
_			—								
bit 15							bit 8				
R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
BTSEE	—	DMAEE	BTOEE	DFN8EE	CRC16EE	CRC5EE EOFEE	PIDEE				
bit 7							bit				
Logondy											
Legend: R = Readab	le bit	W = Writable	bit	U = Unimpler	nented bit, read	1 as '0'					
-n = Value a		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkn	own				
				0 20000			•••••				
bit 15-8	Unimpleme	ented: Read as '	0'								
bit 7	BTSEE: Bit	Stuff Error Interr	upt Enable bit								
	1 = Interrupt is enabled										
		ot is disabled									
bit 6	-	ented: Read as '									
bit 5	DMAEE: DMA Error Interrupt Enable bit										
	 1 = Interrupt is enabled 0 = Interrupt is disabled 										
bit 4	•		me-out Error Ir	terrunt Enable	hit						
	BTOEE: Bus Turnaround Time-out Error Interrupt Enable bit 1 = Interrupt is enabled										
	0 = Interrupt is disabled										
bit 3	DFN8EE: Data Field Size Error Interrupt Enable bit										
	1 = Interrupt is enabled										
	0 = Interrupt is disabled										
bit 2	CRC16EE: CRC16 Failure Interrupt Enable bit										
	 1 = Interrupt is enabled 0 = Interrupt is disabled 										
bit 1	For Device mode:										
	CRC5EE: CRC5 Host Error Interrupt Enable bit										
	1 = Interrupt is enabled										
	0 = Interrupt is disabled										
	For Host mode: EOFEE: End-of-Frame Error interrupt Enable bit										
		ot is enabled	·								
	0 = Interrup	ot is disabled									
bit 0	PIDEE: PID	Check Failure I	nterrupt Enable	e bit							
DIEU	PIDEE: PID Check Failure Interrupt Enable bit 1 = Interrupt is enabled										

18.7.3 USB ENDPOINT MANAGEMENT REGISTERS

REGISTER 18-21: U1EPn: USB ENDPOINT n CONTROL REGISTERS (n = 0 TO 15)

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
	—	—	—	—	—	—	—			
bit 15							bit 8			
DAMO	DAMO		DAALO	DAALO	DAMA	DAMA	DAMO			
R/W-0 LSPD ⁽¹⁾	R/W-0 RETRYDIS ⁽¹⁾	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
bit 7	RETRIDIS	_	EPCONDIS	EPRXEN	EPTXEN	EPSTALL	EPHSHK bit (
							DIL			
Legend:										
R = Readab	le bit	W = Writable	bit	U = Unimplen	nented bit, rea	d as '0'				
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unki	nown			
bit 15-8	Unimplement				(1)					
bit 7			onnection Enab	-	only) ⁽¹⁾					
			ow-speed devic							
			ow-speed devic							
bit 6	RETRYDIS : Retry Disable bit (U1EP0 only) ⁽¹⁾									
	 Retry NAK transactions is disabled Retry NAK transactions is enabled; retry is done in hardware 									
bit 5	-			y is done in he	liuwale					
bit 4	Unimplemented: Read as '0' EPCONDIS: Bidirectional Endpoint Control bit									
	If EPTXEN and EPRXEN = 1:									
	1 = Disable Endpoint n from control transfers; only TX and RX transfers are allowed									
	0 = Enable Endpoint n for control (SETUP) transfers; TX and RX transfers are also allowed									
	For all other combinations of EPTXEN and EPRXEN:									
	This bit is ignored.									
bit 3	EPRXEN: End	•								
	1 = Endpoint n receive is enabled									
	 0 = Endpoint n receive is disabled EPTXEN: Endpoint Transmit Enable bit 									
bit 2		•								
	 1 = Endpoint n transmit is enabled 0 = Endpoint n transmit is disabled 									
bit 1										
	EPSTALL: Endpoint Stall Status bit 1 = Endpoint n was stalled									
	0 = Endpoint n was not stalled									
bit 0	•									
	EPHSHK: Endpoint Handshake Enable bit 1 = Endpoint handshake is enabled									
	1 = Endpoint	handshake is	enabled							
			enabled disabled (typica	Illy used for isc	chronous end	points)				

Note 1: These bits are available only for U1EP0 and only in Host mode. For all other U1EPn registers, these bits are always unimplemented and read as '0'.

18.7.4 USB VBUS POWER CONTROL REGISTER

REGISTER 18-22: U1PWMCON: USB VBUS PWM GENERATOR CONTROL REGISTER

R/W-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0				
PWMEN	—	—	—	—	_	PWMPOL	CNTEN				
bit 15				-			bit 8				
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0				
—	_		—			—	_				
bit 7							bit 0				
Legend:											
R = Readab	ole bit	W = Writable	bit	U = Unimplemented bit, read as '0'							
-n = Value a	at POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unknown					
bit 15	PWMEN: PWM Enable bit										
		1 = PWM generator is enabled									
				eld in the Rese	et state specifie	ed by PWMPOL					
bit 14-10	Unimplemen	ted: Read as '0)'								
bit 9	PWMPOL: P	WM Polarity bit									
	1 = PWM out	tput is active-lo	w and resets h	igh							
	0 = PWM out	0 = PWM output is active-high and resets low									
bit 8	CNTEN: PWM Counter Enable bit										
	1 = Counter	is enabled									
	0 = Counter	is disabled									
bit 7-0	Unimplemen	ted: Read as 'd)'								

19.0 ENHANCED PARALLEL MASTER PORT (EPMP)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 42. "Enhanced Parallel Master Port (EPMP)" (DS39730). The information in this data sheet supersedes the information in the FRM.

The Enhanced Parallel Master Port (EPMP) module is present in PIC24FJXXXDAX10 devices and not in PIC24FJXXXDAX06 devices. The EPMP provides a parallel 4-bit (Master mode only), 8-bit (Master and Slave modes) or 16-bit (Master mode only) data bus interface to communicate with off-chip modules, such as memories, FIFOs, LCD controllers and other microcontrollers. This module can serve as either the master or the slave on the communication bus. For EPMP Master modes, all external addresses are mapped into the internal Extended Data Space (EDS). This is done by allocating a region of the EDS for each chip select, and then assigning each chip select to a particular external resource, such as a memory or external controller. This region should not be assigned to another device resource, such as RAM or SFRs. To perform a write or read on an external resource, the CPU should simply perform a write or read within the address range assigned for EPMP.

Note: The EPMP module is not present in 64-pin devices (PIC24FJXXXDAX06).

The EPMP has an alternative master feature. The graphics controller module can control the EPMP directly in Alternate Master mode to access an external graphics buffer.

Key features of the EPMP module are:

- Extended Data Space (EDS) interface allows
 Direct Access from the CPU
- Up to 23 Programmable Address Lines
- · Up to 2 Chip Select Lines
- Up to 2 Acknowledgement Lines (one per chip select)
- 4-bit, 8-bit or 16-bit wide Data Bus
- Programmable Strobe Options (per chip select)
 Individual Read and Write Strobes or;
- Read/Write Strobe with Enable Strobe
- Programmable Address/Data Multiplexing
- Programmable Address Wait States
- Programmable Data Wait States (per chip select)
- Programmable Polarity on Control Signals (per chip select)
- · Legacy Parallel Slave Port Support
- · Enhanced Parallel Slave Support
 - Address Support
 - 4-Byte Deep Auto-Incrementing Buffer
- Alternate Master feature

19.1 ALTPMP Setting

Many of the lower order EPMP address pins are shared with ADC inputs. This is an untenable situation for users that need both the ADC channels and the EPMP bus. If the user does not need to use all the address bits, then by clearing the ALTPMP (CW3<12>) Configuration bit, the lower order address bits can be mapped to higher address pins, which frees the ADC channels.

Pin	ALTPMP = 0	ALTPMP = 1
RA14	PMCS2	PMA22
RC4	PMA22	PMCS2
RF12	PMA5	PMA18
RG6	PMA18	PMA5
RG7	PMA20	PMA4
RA3	PMA4	PMA20
RG8	PMA21	PMA3
RA4	PMA3	PMA21

TABLE 19-1: ALTERNATE EPMP PINS

Pin Name	Туре	Description
PMA<22:16>	0	Address bus bits<22-16>
	0	Address bus bit<15>
PMA<15>, PMCS2	0	Chip Select 2 (alternate location)
	I/O	Data bus bit<15> when port size is 16 bits and address is multiplexed
	0	Address bus bit<14>
PMA<14>, PMCS1	0	Chip Select 1 (alternate location)
	I/O	Data bus bit 14 when port size is 16-bit and address is multiplexed
	0	Address bus bit< 13-8>
PMA<13:8>	I/O	Data bus bits<13-8> when port size is 16 bits and addres is multiplexed
PMA<7:3>	0	Address bus bit< 7-3>
PMA<2>, PMALU	0	Address bus bit<2>
	0	Address latch upper strobe for multiplexed address
	I/O	Address bus bit<1>
PMA<1>, PMALH	0	Address latch high strobe for multiplexed address
	I/O	Address bus bit<0>
PMA<0>, PMALL	0	Address latch low strobe for multiplexed address
PMD<15:8>	I/O	Data bus bits<15-8> when address is not multiplexed
	I/O	Data bus bits<7-4>
PMD<7:4>	0	Address bus bits<7-4> when port size is 4 bits and addre is multiplexed with 1 address phase
PMD<3:0>	I/O	Data bus bits<3-0>
PMCS1	I/O	Chip Select 1
PMCS2	0	Chip Select 2
PMWR, PMENB	I/O	Write strobe or Enable signal depending on Strobe mode
PMRD, PMRD/PMWR	I/O	Read strobe or Read/Write signal depending on Strobe mode
PMBE1	0	Byte indicator
PMBE0	0	Nibble or byte indicator
PMACK1	I	Acknowledgment 1
PMACK2	I	Acknowledgment 2

TABLE 19-2: PARALLEL MASTER PORT PIN DESCRIPTION

R/W-0	U-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0					
PMPEN		PSIDL	ADRMUX1	ADRMUX0	—	MODE1	MODE0					
bit 15		•	•				bit 8					
R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0					
CSF1	CSF0	ALP	ALMODE		BUSKEEP	IRQM1	IRQM0					
bit 7		,	/				bit (
Legend:												
R = Readabl	le bit	W = Writable	e bit	U = Unimplem	ented bit, read	l as '0'						
-n = Value at	t POR	'1' = Bit is se	t	'0' = Bit is clea	ared	x = Bit is unkr	nown					
bit 15	PMPEN: Par	allel Master P	ort Enable bit									
	1 = EPMP is 0 = EPMP is											
bit 14	Unimplemer	nted: Read as	·'0'									
bit 13	•	in Idle Mode k										
	1 = Disconti	nue module op	peration when de	vice enters Idle	mode							
	1 = Discontinue module operation when device enters Idle mode0 = Continue module operation in Idle mode											
bit 12-11	ADRMUX<1:0>: Address/Data Multiplexing Selection bits											
		 11 = Lower address bits are multiplexed with data bits using 3 address phases 10 = Lower address bits are multiplexed with data bits using 2 address phases 										
			•		•							
	 01 = Lower address bits are multiplexed with data bits using 1 address phase 00 = Address and data appear on separate pins 											
bit 10		nted: Read as		e pins								
bit 9-8	•		Mode Select bits									
	11 = Master mode											
	10 = Enhanced PSP; pins used are PMRD, PMWR, PMCS, PMD<7:0> and PMA<1:0>											
	01 = Buffered PSP; pins used are PMRD, PMWR, PMCS and PMD<7:0> 00 = Legacy Parallel Slave Port; PMRD, PMWR, PMCS and PMD<7:0> pins are used											
bit 7-6				,								
	CSF<1:0>: Chip Select Function bits 11 = Reserved											
	10 = PMA<15> used for Chip Select 2, PMA<14> used for Chip Select 1											
	01 = PMA<15> used for Chip Select 2, PMCS1 used for Chip Select 1 00 = PMCS2 used for Chip Select 2, PMCS1 used for Chip Select 1											
=				S1 used for Chi	p Select 1							
bit 5		s Latch Polari	•									
	0 = Active-lo	w (PMALL, P	MALH and PMA									
bit 4	-		Strobe Mode bit									
		 1 = Enable "smart" address strobes (each address phase is only present if the current access would cause a different address in the latch than the previous address) 										
		ainerent addre		han the previous	s address)							
bit 3		nted: Read as										
bit 2	=	Bus Keeper bi										
	1 = Data bus	s keeps its las	t value when not bedance state wh									
bit 1-0			uest Mode bits	ion not actively								
		• •	hen Read Buffer	3 is read or Wr	ite Buffer 3 is v	vritten (Ruffere	d PSP mode					
		read or write	operation when F									
			t the end of a rea	ad/write cvcle								

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R-0, HSC	U-0	R/C-0, HS	R/C-0, HS	R-0, HSC	R-1, HSC	R/W-0	R/W-0	
BUSY	_	ERROR	TIMEOUT	AMREQ	CURMST	MSTSEL1	MSTSEL0	
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
RADDR23	RADDR22	RADDR21	RADDR20	RADDR19	RADDR18	RADDR17	RADDR16	
bit 7							bit 0	
1			0.44.61.614			- h:4		
Legend:	hla hit	HS = Hardware		HSC = Hardware			a hit	
R = Reada		W = Writable k	DIT	U = Unimplementer				
-n = Value	at POR	'1' = Bit is set		'0' = Bit is cleared		x = Bit is unk	known	
bit 15	BUSY BUSY	bit (Master mod	de only)					
	1 = Port is b	-	ue enigy					
	0 = Port is n							
bit 14	Unimplemer	nted: Read as '	0'					
bit 13	ERROR: Erro	or bit						
	1 = Transact	tion error (illega	I transaction w	vas requested)				
		tion completed	successfully					
bit 12	TIMEOUT: T	ime-Out bit						
		tion timed out	6 11					
L:1 44		tion completed						
bit 11		ernate Master F	•					
		rnate Master is rnate Master is						
bit 10		urrent Master bi	•	<u> </u>				
		ccess is grante						
		ccess is grante		master				
bit 9-8	MSTSEL<1:	0>: Parallel Por	t Master Selee	ct bits				
			lirect access (EPMP Bypass mod	de)			
	10 = Reserve							
	01 = Alternat 00 = CPU	te master						
bit 7-0		16>: Parallel M	aster Port Res	served Address Spa	ace bits ⁽¹⁾			
Note 1:	RADDR<23:16>: Parallel Master Port Reserved Address Space bits ⁽¹⁾ If RADDR<23:16> = 00000000, then the last EDS address for Chip Select 2 will be 0xFFFFFF.							

REGISTER 19-2: PMCON2: EPMP CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0				
PTWREN	PTRDEN	PTBE1EN	PTBE0EN		AWAITM1	AWAITM0	AWAITE				
bit 15	•		•			•	bit 8				
	DAMA	DAVA	DANO	DAMA	DANA		DAMA				
U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
	PTEN22	PTEN21	PTEN20	PTEN19	PTEN18	PTEN17	PTEN16				
bit 7							bit C				
Legend:											
R = Readable	e bit	W = Writable	bit	U = Unimple	mented bit, re	ad as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cl	eared	x = Bit is unkno	wn				
bit 15		rite/Enable Stro		e bit							
		PMENB port is e									
		PMENB port is o									
bit 14		PTRDEN: Read/Write Strobe Port Enable bit									
		1 = PMRD/PMWR port is enabled 0 = PMRD/PMWR port is disabled									
		•									
bit 13	PTBE1EN: High Nibble/Byte Enable Port Enable bit										
	 1 = PMBE1 port is enabled 0 = PMBE1 port is disabled 										
h# 40											
bit 12		PTBE0EN: Low Nibble/Byte Enable Port Enable bit 1 = PMBE0 port is enabled									
		port is enabled									
bit 11		nted: Read as '	o'								
bit 10-9	-)>: Address Lat		Staton bita							
DIL 10-9				States Dits							
		11 = Wait of 3½ Tcy 10 = Wait of 2½ Tcy									
		10 = Walt of 2/2 ICY 0.1 = Walt of 1/2 TCY									
	00 = Wait of	½ TCY									
bit bit 8	AWAITE: Ad	dress Hold Afte	r Address Latcl	h Strobe Wait	States bits						
	1 = Wait of 1	1⁄4 TCY									
	0 = Wait of 1/2	4 TCY									
bit 7	Unimplemer	ted: Read as '	0'								
bit 6-0	PTEN<22:16	>: EPMP Addre	ess Port Enable	e bits							
	1 = PMA<22	::16> function a	s EPMP addres	ss lines							
	0 = PMA<22										

REGISTER 19-3: PMCON3: EPMP CONTROL REGISTER 3

REGISTER	13-4. FINC									
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
PTEN15	PTEN14	PTEN13	PTEN12	PTEN11	PTEN10	PTEN9	PTEN8			
bit 15							bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
PTEN7	PTEN6	PTEN5	PTEN4	PTEN3	PTEN2	PTEN1	PTEN0			
bit 7							bit 0			
Legend:										
R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'							
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown			lown			
bit 15	PTEN15: PM	A15 Port Enab	le bit							
	1 = PMA15 f	unctions as eitl	ner Address Li	ne 15 or Chip S	Select 2					
	0 = PMA15 f	unctions as po	t I/O							
bit 14	PTEN14: PM	A14 Port Enab	le bit							
	1 = PMA14 f	unctions as eith	ner Address Li	ne 14 or Chip S	Select 1					
	0 = PMA14 f	unctions as po	rt I/O							
bit 13-3	PTEN<13:3>	: EPMP Addres	ss Port Enable	bits						
	1 = PMA<13	:3> function as	EPMP addres	s lines						
	0 = PMA<13	:3> function as	port I/Os							
bit 2-0	PTEN<2:0>:	PMALU/PMAL	H/PMALL Stro	be Enable bits						
		1 = PMA<2:0> function as either address lines or address latch strobes 0 = PMA<2:0> function as port I/Os								

REGISTER 19-4: PMCON4: EPMP CONTROL REGISTER 4

0 = PMA<2:0> function as port I/Os

R/W-0	R/W-0	R/W-0	R/W-0	U-0	R/W-0	R/W-0	R/W-0			
CSDIS	CSP	CSPTEN	BEP	0-0	WRSP	R/W-0	R/W-0			
bit 15	COP	COFTEN	DEF		WROF	RDSP	-			
51115							bi			
R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	U-0	U-0			
ACKP	PTSZ1	PTSZ0					0-0			
bit 7	11021	11020					bi			
510 1							51			
Legend:										
R = Readable	bit	W = Writable b	it	U = Unimp	lemented bit, re	ad as '0'				
n = Value at F	POR	'1' = Bit is set		'0' = Bit is o		x = Bit is unkno	own			
bit 15	CSDIS: Chi	o Select x Disab	le bit							
		the Chip Select		/						
	0 = Enable	the Chip Select	x functionality							
bit 14	•	Select x Polarity	bit							
		nigh <u>(PMCS</u> x) ow (PMCSx)								
bit 13		MCSx Port Enal	ala hit							
		port is enabled								
		port is disabled								
pit 12	BEP: Chip S	Select x Nibble/E	Byte Enable Po	plarity bit						
		Byte enable activ								
		Byte enable activ		0, PMBE1)						
bit 11	-	nted: Read as '								
bit 10	-	WRSP: Chip Select x Write Strobe Polarity bit For Slave modes and Master mode when SM = 0:								
		odes and Maste robe active-high		<u>SM = 0:</u>						
		robe active-low								
	For Master I	mode when SM	<u>= 1:</u>							
		strobe active-hig	· <u>·</u> · ·							
		strobe active-lov	. ,							
bit 9		Select x Read	•							
		odes and Maste		SIVI = 0.						
	 1 = Read strobe active-high (PMRD) 0 = Read strobe active-low (PMRD) 									
	For Master mode when SM = 1:									
	 1 = Read/write strobe active-high (PMRD/PMWR) 0 = Read/Write strobe active-low (PMRD/PMWR) 									
bit 8				PIVIVR)						
DILO		elect x Strobe M		D/PMWR an						
	 1 = Read/Write and enable strobes (PMRD/PMWR and PMENB) 0 = Read and write strobes (PMRD and PMWR) 									
bit 7	ACKP: Chip Select x Acknowledge Polarity bit									
		tive-high <u>(PMAC</u> tive-low (PMAC								
oit 6-5	PTSZ<1:0>	Chip Select x F	ort Size bits							
	11 = Reser									
		port size (PMD<								
		ort size (PMD<3 ort size (PMD<7								

	10-0. 1 1010						
R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾	R/W ⁽¹⁾
BASE23	BASE22	BASE21	BASE20	BASE19	BASE18	BASE17	BASE16
bit 15							bit 8
R/W ⁽¹⁾	U-0	U-0	U-0	R/W ⁽¹⁾	U-0	U-0	U-0
BASE15	—	_	_	BASE11	—	—	—
bit 7							bit 0
Legend:							
R = Readabl	e bit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'	
-n = Value at	POR	'1' = Bit is se	' = Bit is set '0' = Bit is cleared x = Bit is unknown				wn

bit 15-7 BASE<23:15>: Chip Select x Base Address bits⁽²⁾

bit 6-4 Unimplemented: Read as '0'

bit 3 BASE<11>: Chip Select x Base Address bits⁽²⁾

bit 2-0 Unimplemented: Read as '0'

Note 1: Value at POR is 0x0200 for PMCS1BS and 0x0600 for PMCS2BS.

2: If the whole PMCS2BS register is written together as 0x0000, then the last EDS address for the Chip Select 1 will be 0xFFFFFF. In this case, the Chip Select 2 should not be used. PMCS1BS has no such feature.

R/W-0 R/W R/W R/W R/W R/W R/W R/W	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	U-0				
RW-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 R/W-0 DWAITB1 DWAITB1 DWAITM2 DWAITM1 DWAITM1 DWAITE1 DWAITE0 DWAITE0 bit	ACKM1	ACKM0	AMWAIT2	AMWAIT1	AMWAIT0	_	_	_				
DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITE1 DWAITE0 bit7 bit7 bit7 bit7 bit7 bit7 Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' bit -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-14 ACKM-1:0>: Chip Select x Acknowledge Mode bits x = Bit is unknown x = Bit is unknown 00 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = DMACKx is used to determine when a read/write operation is complete 01 = DMACKx is used to determine when a read/write operation is complete 01 = DMACKx is used to determine when a read/write operation is complete 01 = DMACKx is used to determine when a read/write operation is complete 01 = DMACKx is used to determine when a read/write operation is complete 01 = DMat DMACK 02 = DMACKx is used to determine when a read/write Strobe Wait States bits 01 = Wait of 10 alternate master cycles 00 = Wait of 10 alternate master cycles 00 = Wait of 10 alternate master cycles 00 = Wait of 10 al	bit 15							bit				
DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITB1 DWAITE1 DWAITE0 bit 7 bit 7 bit 7 bit 7 bit 7 bit 7 Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' in a Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15 bit 15-14 ACKM ACKM clip Select x Acknowledge Mode bits 11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete with time-out If DWAITM3:30> = 0000, the maximum time-out is 255 Tcy, else it is DWAITM<3:0> cycles. 00 = PMACkx is used to determine when a read/write operation is complete with time-out If DWAITM:3:0> = 0000, the maximum time-out is 255 Tcy, else it is DWAITM<3:0> cycles. 01 = PMACkx is not used 01 = Mait of 10 alternate master cycles 00 = Wait of 3 alternate master cycles 00 = Wait of 3 alternate master cycles 00 = Wait of 3 alternate master cycles 00 = Wait of 10/ Tcy 01 = Wait of 10/ Tcy 00 = Wait of 10/ Tcy 01 = Wait of 10/ Tcy 00 = Wait of 10/ Tcy 01 = Wait of 15/ Tcy 00 = Wait of 10/ Tcy 01 = Wait of 15/ Tcy 000 = Wait of 10/ Tcy 01 = Wait of 15/ Tcy 000 = Wait of 10/ Tcy 000 = Wait of 10/ Tcy	DANA	DAMA	DAALO	DAALO	DAMA	D111	DAMA	DAMA				
bit 7					-			1				
Legend: R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-14 ACKM<10>: Chip Select x Acknowledge Mode bits 11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete with time-out If DWAITM<3:0> = 0000, the maximum time-out is 255 Tcv, else it is DWAITM<3:0> cycles. 00 = PMACKx is not used 00 = PMACKx is not used 11 = Wait of 10 alternate master cycles 11 = Wait of 10 alternate master cycles 11 = Wait of 10 alternate master cycles 10 = WAITB<10>: Chip Select x Alternate Before Read/Write Strobe Wait States bits 11 = Wait of 3/k Tcv 10 = Wait of 3/k Tcv 10 = Wait of 1/k Tcv 00 = Wait of 1/k Tcv 00 = Wait of 1/k Tcv 111 = Wait of 15/k Tcv 112 = Wait of 15/k Tcv 113 = Wait of 15/k Tcv 114 = Wait of 15/k Tcv 115 = Wait of 15/k Tcv 115 = Wait of 17/k Tcv 11		DWAITBU	DWAITM3	DWAITM2	DWAITM1	DWAITMU	DWAITE1					
R - Readable bit W = Writable bit U = Unimplemented bit, read as '0' '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-14 ACKM<1:0>: Chip Select x Acknowledge Mode bits 11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is out to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is not used 01 = PMACKx is not used 01 = Wait of 10 alternate master cycles 01 = Wait of 10 alternate master cycles 01 = Wait of 4 alternate master cycles 010 = Wait of 4 alternate master cycles 010 = Wait of 3% Tcy 11 = Wait of 3% Tcy 11 = Wait of 1% Tcy 01 = Wait of 1% Tcy 02 = Wait of 1% Tcy 03 = Wait of 1% Tcy 04 = Wait of 1% Tcy 05 = Trey 05 = Trey 05 = Wait of 1% Tcy 05 = Trey 05 = Wait of 1% Tcy 05 = Wait	DIT 7							DIC				
R - Readable bit W = Writable bit U = Unimplemented bit, read as '0' '1' = Bit is set '0' = Bit is cleared x = Bit is unknown bit 15-14 ACKM<1:0>: Chip Select x Acknowledge Mode bits 11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is out to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is not used 01 = PMACKx is not used 01 = Wait of 10 alternate master cycles 01 = Wait of 10 alternate master cycles 01 = Wait of 4 alternate master cycles 010 = Wait of 4 alternate master cycles 010 = Wait of 3% Tcy 11 = Wait of 3% Tcy 11 = Wait of 1% Tcy 01 = Wait of 1% Tcy 02 = Wait of 1% Tcy 03 = Wait of 1% Tcy 04 = Wait of 1% Tcy 05 = Trey 05 = Trey 05 = Wait of 1% Tcy 05 = Trey 05 = Wait of 1% Tcy 05 = Wait	Leaend:											
 In = Value at POR 11' = Bit is set 0' = Bit is cleared x = Bit is unknown ACKM<1:0>: Chip Select x Acknowledge Mode bits 11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete with time-out if DWAITM<3:0> = 0000, the maximum time-out is 255 TCr, else it is DWAITM<3:0> cycles. 00 = PMACKx is not used bit 13-11 AWWAIT<2:0>: Chip Select x Alternate Master Wait States bits 111 = Wait of 10 alternate master cycles 001 = Wait of 4 alternate master cycles 001 = Wait of 3 alternate master cycles 001 = Wait of 3 alternate master cycles 001 = Wait of 3 alternate master cycles 001 = Wait of 2½ TCY 10 = Wait of 1½ TCY 10 = Wait of 1½ TCY 11 = Wait of 1½ TCY 11 = Wait of 1½ TCY 11 = Wait of 1½ TCY 111 = Wait of 1½ T	-	le bit	W = Writable	oit	U = Unimplem	nented bit, read	as '0'					
 ACKM<1:0>: Chip Select x Acknowledge Mode bits = Reserved = PMACKx is used to determine when a read/write operation is complete with time-out if DWAITM<3:0> = 0000, the maximum time-out is 255 TCY, else it is DWAITM<3:0> cycles. = PMACKx is not used AMWAIT = PMACK is is a durate master cycles = Wait of 10 alternate master cycles = Wait of 4 alternate master cycles = Wait of 3 alternate master cycles = Wait of 3 alternate master cycles = Wait of 3 alternate master cycles = Wait of 2% TCY = Wait of 1% TC					-			own				
11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is not used 00 = PMACKx is not used 11 = Wait of 10 alternate master cycles 01 = Wait of 4 alternate master cycles 01 = Wait of 4 alternate master cycles 01 = Wait of 3 alternate master cycles 02 = Wait of 3 alternate master cycles 03 = Wait of 3 alternate master cycles 04 = Wait of 3 alternate master cycles 05 = Wait of 3 alternate master cycles 05 = Wait of 3 alternate master cycles 06 = Wait of 3% Tcv 10 = Wait of 1% Tcv 10 = Wait of 1% Tcv 11 = Wait of 1% Tcv 111 = Wait of 3% Tcv 112 = Wait of 3% Tcv 113 = Wait of 3% Tcv 114 = Wait of 3% Tcv 115 = Wait of 3% Tcv 115 = Wait of 3% Tcv 115 = Wait of 3% Tcv 116 = Wait of 3% Tcv 117 = Wait of 3% Tcv 118 = Wait of 3% Tcv 118 = Wait of 3% Tcv 119 = Wait of 3% Tcv 110 = Wait of 1% Tcv 111 = Wait of 3% Tcv 112 = Wait of 3% Tcv 113 = Wait of 3% Tcv 114 = Wait of 3% Tcv 115 = Wait of 3%												
11 = Reserved 10 = PMACKx is used to determine when a read/write operation is complete 01 = PMACKx is used to determine when a read/write operation is complete with time-out If DWAITM<3:0> = 0000, the maximum time-out is 255 Tcv, else it is DWAITM<3:0> cycles. 00 = PMACKx is not used bit 13-11 Atwain for a liternate master cycles 00 = Wait of 4 alternate master cycles 00 = Wait of 3 Alternate master cycles 00 = Wait of 32 Tcv 00 = Wait of 32 Tcv 0 = Wait of 1% Tcv 0 = Wait of 1% Tcv 0 = Wait of 1% Tcv 0 = Wait of 3% Tcv 0 = Wait of 3% Tcv <t< td=""><td>bit 15-14</td><td>ACKM<1:0></td><td>: Chip Select x</td><td>Acknowledge</td><td>Mode bits</td><td></td><td></td><td></td></t<>	bit 15-14	ACKM<1:0>	: Chip Select x	Acknowledge	Mode bits							
 01 = PMACKx is used to determine when a read/write operation is complete with time-out If DWAITM<3:0> = 0000, the maximum time-out is 255 TcY, else it is DWAITM<3:0> cycles. 00 = PMACKx is not used bit 13-11 AMWAIT<2:0>: Chip Select x Alternate Master Wait States bits 111 = Wait of 10 alternate master cycles 000 = Wait of 4 alternate master cycles 000 = Wait of 3 alternate master cycles 001 = Wait of 3'/, TcY 10 = Wait of 1'/, TcY 00 = Wait of 1'/, TcY 00 = Wait of 1'/, TcY 000 = Wait of 1'/, TcY 0000 = Wait of 1'/, TcY 0000 = Wait of 1'/, TcY<td></td><td></td><td>-</td><td>5</td><td></td><td></td><td></td><td></td>			-	5								
 01 = PMACKx is used to determine when a read/write operation is complete with time-out If DWAITM<3:0> = 0000, the maximum time-out is 255 TcY, else it is DWAITM<3:0> cycles. 00 = PMACKx is not used bit 13-11 AMWAIT<2:0>: Chip Select x Alternate Master Wait States bits 111 = Wait of 10 alternate master cycles 000 = Wait of 4 alternate master cycles 000 = Wait of 3 alternate master cycles 001 = Wait of 3'/, TcY 10 = Wait of 1'/, TcY 00 = Wait of 1'/, TcY 00 = Wait of 1'/, TcY 000 = Wait of 1'/, TcY 0000 = Wait of 1'/, TcY 0000 = Wait of 1'/, TcY<td></td><td>10 = PMAC</td><td><pre>Kx is used to de</pre></td><td>termine when</td><td>a read/write op</td><td>eration is comp</td><td>olete</td><td></td>		10 = PMAC	<pre>Kx is used to de</pre>	termine when	a read/write op	eration is comp	olete					
00 = PMACKx is not used 00 = Vait of 10 alternate master cycles 001 = Wait of 10 alternate master cycles 000 = Wait of 3 alternate master cycles 001 = Wait of 3 alternate master cycles 000 = Wait of 3 alternate master cycles 001 = Wait of 3 / TcY 00 = Wait of 1/4 TcY 00 = Wait of 1/4 TcY 000 = Wa		01 = PMACH	<pre>Kx is used to de</pre>	termine when	a read/write op	eration is comp	lete with time-					
bit 13-11 AMWAIT<2:0>: Chip Select x Alternate Master Wait States bits 111 = Wait of 10 alternate master cycles 001 = Wait of 3 alternate master cycles 000 = Wait of 3 alternate master cycles 000 = Wait of 3 alternate master cycles 000 = Wait of 3 alternate master cycles 11 = Wait of 3 & Tcv 10 = Wait of 2 & Tcv 10 = Wait of 2 & Tcv 10 = Wait of 2 & Tcv 11 = Wait of 1 & Tcv 11 = Wait of 3 & Tcv 11 = Wai				00, the maxim	um time-out is 2	255 TCY, else it	is DWAITM<3:	0> cycles.				
111 = Wait of 10 alternate master cycles 001 = Wait of 4 alternate master cycles 000 = Wait of 3 alternate master cycles 001 = Wait of 3'/ TcY 0 = Wait of 1'/ TcY 0												
001 = Wait of 4 alternate master cycles 000 = Wait of 3 alternate master cycles bit 10-8 Unimplemented: Read as '0' bit 7-6 DWAITB<	bit 13-11		•		aster Wait State	es bits						
001 = Wait of 4 alternate master cycles 000 = Wait of 3 alternate master cycles bit 10-8 Unimplemented: Read as 'o' DWAITB<1:0>: Chip Select x Data Setup Before Read/Write Strobe Wait States bits 11 = Wait of 3'\% TcY 00 = Wait of 2'\% TcY 01 = Wait of 1'\% TcY 00 = Wait of 1'\% TcY 000 = Wait of 1'\% TcY 01 = Wait of 1'\% TcY												
000 = Wait of 3 alternate master cycles bit 10-8 Unimplemented: Read as '0' bit 7-6 DWAITB<1:0:: Chip Select x Data Setup Before Read/Write Strobe Wait States bits			of 4 alternate m	aster cycles								
bit 10-8 Unimplemented: Read as '0' bit 7-6 DWAITB<1:0>: Chip Select x Data Setup Before Read/Write Strobe Wait States bits 11 = Wait of 3¼ TcY 10 = Wait of 2¼ TcY 01 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY bit 5-2 DWAITM<3:0>: Chip Select x Data Read/Write Strobe Wait States bits For Write operations: 1111 = Wait of 15½ TcY 0001 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 0001 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 1111 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 1111 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 1111 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 11 = Wait of 1½ TcY 01 = Wait of 1½ TcY 02 = Wait of 1½ TcY 03 = Wait of 1½ TcY 04 = Wait of 1½ TcY 05 = Wait of 1½ TcY 11 = Wait of 1½ TcY 11 = Wait of 1½ TcY 12 = Wait of 1½ TcY 13 = Wait of 1½ TcY 14 = Wait of 1½ TcY 15 = Wait of 1½ TcY 16 = Wait of 1½ TcY 17 = Wait of 1½ TcY 18 = Wait of 3 TcY 19 = Wait of 1½ TcY 10 = Wait of 1½ TcY 10 = Wait of 2 TcY 11 = Wait of 3 TcY 11 = Wait of 3 TcY 11 = Wait of 1 TcY 11 = Wait of 1 TcY												
bit 7-6 DWAITB<1:0>: Chip Select x Data Setup Before Read/Write Strobe Wait States bits 11 = Wait of 3¼ TcY 10 = Wait of 2¼ TcY 01 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY bit 5-2 DWAITM<3:0>: Chip Select x Data Read/Write Strobe Wait States bits For Write operations: 1111 = Wait of 15½ TcY 0001 = Wait of 1½ TcY 0000 = Wait of 1½ TcY 0001 = Wait of 1½ TcY 111 = Wait of 1½ TcY 000 = Wait of 1½ TcY 111 = Wait of 1½ TcY 000 = Wait of ½ TcY 111 = Wait of 3½ TcY 111 = Wait of 3¼ TcY 111 = Wait of 3¼ TcY 111 = Wait of 1¼ TcY 01 = Wait of 3 TcY 11 = Wait of 1 TcY	bit 10-8	· · · · · · · · · · · · · · · · · · ·										
11 = Wait of 3¼ Tcy 10 = Wait of 2¼ Tcy 01 = Wait of 1¼ Tcy 00 = Wait of 1¼ Tcy 00 = Wait of 1¼ Tcy 00 = Wait of 1½ Tcy 111 = Wait of 1½ Tcy 000 = Wait of 1½ Tcy 01 = Wait of 3½ Tcy 02 = Wait of 3½ Tcy 03 = Wait of 3½ Tcy 04 = Wait of 3½ Tcy 05 = Wait of 1½ Tcy 06 = Wait of 1½ Tcy 07 = Wait of 1½ Tcy 08 = Wait of 1½ Tcy 09 = Wait of 1½ Tcy 01 = Wait of 1½ Tcy 02 = Wait of 1½ Tcy 03 = Wait of 1½ Tcy 04 = Wait of 1½ Tcy <td< td=""><td>bit 7-6</td><td>•</td><td></td><td></td><td>Before Read/W</td><td>/rite Strobe Wai</td><td>it States bits</td><td></td></td<>	bit 7-6	•			Before Read/W	/rite Strobe Wai	it States bits					
 01 = Wait of 1¼ Tcy 00 = Wait of ¼ Tcy 00 = Wait of ¼ Tcy 00 = Wait of ¼ Tcy bit 5-2 DWAITM<3:0>: Chip Select x Data Read/Write Strobe Wait States bits For Write operations: 1111 = Wait of 15½ Tcy 0001 = Wait of 1½ Tcy 0000 = Wait of 1½ Tcy 0000 = Wait of 1½ Tcy 0001 = Wait of 1½ Tcy 0001 = Wait of 1½ Tcy 0000 = Wait of 1½ Tcy 0001 = Wait of 1½ Tcy 0000 = Wait of 1½ Tcy 0001 = Wait of 1½ Tcy 0000 = Wait of 1½ Tcy 000 = Wait of 1½ Tcy 01 = Wait of 1½ Tcy 02 = Wait of 1½ Tcy 03 = Wait of 1½ Tcy 04 = Wait of 1½ Tcy 05 = Wait of 1½ Tcy 06 = Wait of 1½ Tcy 07 = Wait of 1½ Tcy 08 = Wait of 1½ Tcy 09 = Wait of 1½ Tcy 00 = Wait of 1½ Tcy 00 = Wait of 1½ Tcy 00 = Wait of 1∑ Tcy 01 = Wait of 1 Tcy 												
00 = Wait of ¼ TcY bit 5-2 DWAITM<3:0>: Chip Select x Data Read/Write Strobe Wait States bits For Write operations: 1111 = Wait of 15½ TcY 0001 = Wait of 1½ TcY 0000 = Wait of ½ TcY For Read operations: 1111 = Wait of 15¾ TcY 0001 = Wait of 1¾ TcY 0000 = Wait of 1¾ TcY 0000 = Wait of 1¾ TcY 0000 = Wait of 1¾ TcY 11 = Wait of 3¼ TcY 11 = Wait of 3¼ TcY 10 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY 11 = Wait of 1¼ TcY 00 = Wait of 1¼ TcY 11 = Wait of 1⅓ TcY 11 = Wait of 1ℜ TcY		10 = Wait of	21⁄4 TCY									
bit 5-2 DWAITM<3:0>: Chip Select x Data Read/Write Strobe Wait States bits For Write operations: 1111 = Wait of 15½ TCY 0001 = Wait of 1½ TCY 0000 = Wait of 1½ TCY For Read operations: 1111 = Wait of 15¾ TCY 0001 = Wait of 1¾ TCY 0000 = Wait of 3¼ TCY 0000 = Wait of 3¼ TCY 0000 = Wait of 3¼ TCY 11 = Wait of 3¼ TCY 10 = Wait of 3¼ TCY 10 = Wait of 1¼ TCY 00 = Wait of 2 TCY 01 = Wait of 2 TCY 01 = Wait of 1 TCY		01 = Wait of	1¼ Tcy									
For Write operations:1111 = Wait of 15½ Tcy 0001 = Wait of 1½ Tcy 0000 = Wait of ½ TcyFor Read operations:1111 = Wait of 15% Tcy 0001 = Wait of 1% Tcy 0000 = Wait of 3% Tcy 011 = Wait of 3% Tcy 011 = Wait of 3% Tcy 112 = Wait of 3% Tcy 113 = Wait of 3% Tcy 113 = Wait of 3% Tcy 114 = Wait of 3% Tcy 114 = Wait of 1% Tcy 115 = Wait of 1% Tcy 116 = Wait of 1% Tcy 116 = Wait of 1% Tcy 116 = Wait of 1% Tcy 117 = Wait of 3 Tcy 117 = Wait of 3 Tcy 116 = Wait of 2 Tcy 116 = Wait of 2 Tcy 116 = Wait of 2 Tcy 116 = Wait of 1 Tcy 116 = Wait of 1 Tcy 117 = Wait of 1 Tcy 117 = Wait of 1 Tcy 117 = Wait of 1 Tcy 118 = Wait of 1 Tcy 118 = Wait of 1 Tcy 118 = Wait of 1 Tcy		00 = Wait of	¼ TCY									
1111 = Wait of 15½ Tcy $0001 = Wait of 1½ Tcy$ $0000 = Wait of ½ Tcy$ $For Read operations:$ $1111 = Wait of 15% Tcy$ $0001 = Wait of 1% Tcy$ $0001 = Wait of 1% Tcy$ $0000 = Wait of 1% Tcy$ $0000 = Wait of 3% Tcy$ bit 1-0 $DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits$ $For Write operations:$ $11 = Wait of 3% Tcy$ $0 = Wait of 2% Tcy$ $0 = Wait of 1% Tcy$ $0 = Wait of 1% Tcy$ $0 = Wait of 1% Tcy$ $0 = Wait of 3% Tcy$ $11 = Wait of 3% Tcy$ $11 = Wait of 3% Tcy$ $0 = Wait of 2% Tcy$ $0 = Wait of 1% Tcy$	bit 5-2	DWAITM<3:	0>: Chip Select	t x Data Read/	Write Strobe W	ait States bits						
<pre>0001 = Wait of 1½ Tcy 0000 = Wait of ½ Tcy For Read operations: 1111 = Wait of 15¼ Tcy 0001 = Wait of 1¾ Tcy 0000 = Wait of ¾ Tcy 0000 = Wait of ¾ Tcy 000 = Wait of ¾ Tcy 000 = Wait of ¾ Tcy 11 = Wait of 3¼ Tcy 10 = Wait of 3¼ Tcy 10 = Wait of 3¼ Tcy 01 = Wait of 1¼ Tcy 00 = Wait of 1¼ Tcy 00 = Wait of ¼ Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy</pre>												
$0000 = Wait of \frac{1}{2} TcyFor Read operations:1111 = Wait of 15% Tcy0001 = Wait of 1%$ Tcy 0000 = Wait of 3% Tcy bit 1-0 DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits For Write operations: 11 = Wait of 3% Tcy 10 = Wait of 3% Tcy 10 = Wait of 2% Tcy 01 = Wait of 1% Tcy 00 = Wait of 1% Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 2 Tcy 01 = Wait of 1 Tcy		1111 = Wait	of 151/2 TCY									
$0000 = Wait of \frac{1}{2} TcyFor Read operations:1111 = Wait of 15% Tcy0001 = Wait of 1%$ Tcy 0000 = Wait of 3% Tcy bit 1-0 DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits For Write operations: 11 = Wait of 3% Tcy 10 = Wait of 3% Tcy 10 = Wait of 2% Tcy 01 = Wait of 1% Tcy 00 = Wait of 1% Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 2 Tcy 01 = Wait of 1 Tcy		 0001 = Wait	of 1½ Tcy									
1111 = Wait of 15% Tcy 0001 = Wait of 1% Tcy 0000 = Wait of % Tcy bit 1-0 DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits For Write operations: 11 = Wait of 3¼ Tcy 10 = Wait of 3¼ Tcy 10 = Wait of 3¼ Tcy 10 = Wait of 1¼ Tcy 01 = Wait of 1¼ Tcy 00 = Wait of ¼ Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy												
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 0000 = Wait of ³⁄₄ Tcy bit 1-0 DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits For Write operations: 11 = Wait of 3¹⁄₄ Tcy 10 = Wait of 2¹⁄₄ Tcy 11 = Wait of 1¹⁄₄ Tcy 10 = Wait of 1¹⁄₄ Tcy 10 = Wait of 1¹⁄₄ Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy 		1111 = Wait										
 0000 = Wait of ³⁄₄ Tcy bit 1-0 DWAITE<1:0>: Chip Select x Data Hold After Read/Write Strobe Wait States bits For Write operations: 11 = Wait of 3¹⁄₄ Tcy 10 = Wait of 2¹⁄₄ Tcy 11 = Wait of 1¹⁄₄ Tcy 10 = Wait of 1¹⁄₄ Tcy 10 = Wait of 1¹⁄₄ Tcy 11 = Wait of 3 Tcy 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy 		 0001 = Wait	1.001 = Wait of 13/4 Tex									
For Write operations: $11 =$ Wait of $3\frac{1}{4}$ Tcy $10 =$ Wait of $2\frac{1}{4}$ Tcy $01 =$ Wait of $1\frac{1}{4}$ Tcy $00 =$ Wait of $\frac{1}{4}$ Tcy $\overline{Por Read operations:}$ $11 =$ Wait of 3 Tcy $10 =$ Wait of 2 Tcy $01 =$ Wait of 1 Tcy												
For Write operations: $11 =$ Wait of $3\frac{1}{4}$ Tcy $10 =$ Wait of $2\frac{1}{4}$ Tcy $01 =$ Wait of $1\frac{1}{4}$ Tcy $00 =$ Wait of $\frac{1}{4}$ Tcy $\overline{Por Read operations:}$ $11 =$ Wait of 3 Tcy $10 =$ Wait of 2 Tcy $01 =$ Wait of 1 Tcy	bit 1-0	DWAITE<1:0										
11 = Wait of 3¼ TCY 10 = Wait of 2¼ TCY 01 = Wait of 1¼ TCY 00 = Wait of ¼ TCY For Read operations: 11 = Wait of 3 TCY 10 = Wait of 2 TCY 01 = Wait of 1 TCY		For Write op	erations:									
01 = Wait of 1¼ Tcy 00 = Wait of ¼ Tcy <u>For Read operations:</u> 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy												
00 = Wait of ¼ Tcy <u>For Read operations:</u> 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy		10 = Wait of	2¼ TCY									
For Read operations: 11 = Wait of 3 Tcy 10 = Wait of 2 Tcy 01 = Wait of 1 Tcy												
11 = Wait of 3 TCY 10 = Wait of 2 TCY 01 = Wait of 1 TCY												
10 = Wait of 2 Tcy 01 = Wait of 1 Tcy												
01 = Wait of 1 Tcy												

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REGISTE		ISTAT: EPMP		•		•	
R-0, HSC	R/W-0 HS	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
IBF	IBOV			IB3F	IB2F	IB1F	IB0F
bit 15							bit
R-1, HSC		U-0	U-0	R-1, HSC	R-1, HSC	R-1, HSC	R-1, HSC
OBE	OBUF	—		OB3E	OB2E	OB1E	OB0E
bit 7							bit
Legend:		HS = Hardware	e Settable bit	HSC = Hardw	are Settable/C	earable bit	
R = Reada	ble bit	W = Writable b	it	U = Unimplem	nented bit, read	as '0'	
-n = Value		'1' = Bit is set		'0' = Bit is clea		x = Bit is unkn	iown
bit 15	IBF: Input B	uffer Full Status	bit				
bit 15	IBF: Input B	uffer Full Status	bit				
	1 = All writa	able input buffer i	egisters are ful	I			
	0 = Some c	or all of the writat	ole input buffer i	registers are en	npty		
bit 14	IBOV: Input	Buffer Overflow	Status bit				
	1 = A write	attempt to a full	input register o	ccurred (must b	e cleared in so	ftware)	
	0 = No ove	rflow occurred					
bit 13-12	Unimpleme	nted: Read as '	כי				
bit 11-8	IBxF: Input	Buffer x Status F	ull bit ⁽¹⁾				
		uffer contains un uffer does not co			ear this bit)		
bit 7	OBE: Outpu	It Buffer Empty S	Status bit				
	•	lable output buffe		empty			
		or all of the reada	•		full		
bit 6	OBUF: Out	out Buffer Under	low Status bit	-			
	-	occurred from ar		register (must b	e cleared in so	ftware)	
	0 = No und	erflow occurred					
bit 5-4	Unimpleme	nted: Read as '	כי				
bit 3-0	OBxE: Outp	out Buffer x Statu	s Empty bit				
	1 = Output	buffer is empty (writing data to t	he buffer will cle	ear this bit)		
	•	buffer contains u	•		,		
Note 1:	Even though a	an individual bit re	epresents the b	yte in the buffer	, the bits corres	sponding to the	Word (byte (
	and 1, or byte	2 and 3) gets cle	eared even on b	yte reading.		-	

REGISTER 19-9: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	—	—	_	—	_	—	_
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
_	—	—	—	—	_	RTSECSEL ⁽¹⁾	PMPTTL ⁽²⁾
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable b	bit	U = Unimplem	nented bit, rea	ad as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
bit 15-2	Unimplemer	nted: Read as '0	1				
bit 1	RTSECSEL:	RTCC Seconds	Clock Output	Select bit ⁽¹⁾			
	1 = RTCC se	econds clock is s	selected for the	e RTCC pin			
	0 = RTCC al	arm pulse is sel	ected for the F	RTCC pin			

bit 0 PMPTTL: EPMP Module TTL Input Buffer Select bit⁽²⁾

- 1 = EPMP module inputs (PMDx, PMCS1) use TTL input buffers
- 0 = EPMP module inputs use Schmitt Trigger input buffers

Note 1: To enable the actual RTCC output, the RTCOE (RCFGCAL<10>) bit must also be set.

2: Unimplemented in 64-pin devices (PIC24FJXXXDAX06); maintain as '0'.

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NOTES:

20.0 REAL-TIME CLOCK AND CALENDAR (RTCC)

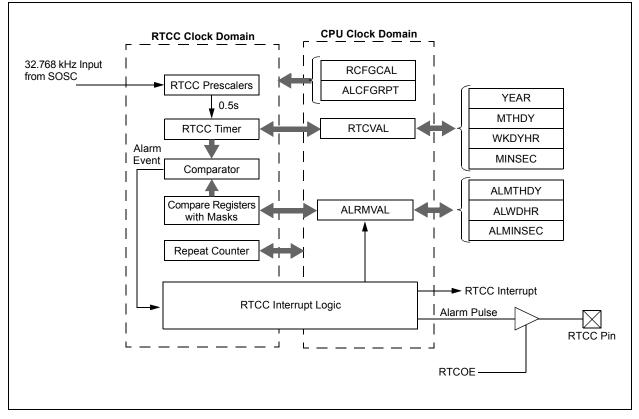
Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 29. "Real-Time Clock and Calendar (RTCC)" (DS39696). The information in this data sheet supersedes the information in the FRM.

The Real-Time Clock and Calendar (RTCC) provides a function that can be calibrated.

Key features of the RTCC module are:

- · Operates in Sleep mode
- Provides hours, minutes and seconds using 24-hour format
- FIGURE 20-1: RTCC BLOCK DIAGRAM

- · Visibility of half of one second period
- Provides calendar weekday, date, month and year
- Alarm configurable for half a second, one second,10 seconds, one minute, 10 minutes, one hour, one day, one week, one month or one year
- Alarm repeat with decrementing counter
- Alarm with indefinite repeat chime
- Year, 2000 to 2099, leap year correction
- BCD format for smaller software overhead
- · Optimized for long-term battery operation
- User calibration of the 32.768 kHz clock crystal/32K INTRC frequency with periodic auto-adjust
 - Calibration to within ±2.64 seconds error per month
 - Calibrates up to 260 ppm of crystal error



20.1 RTCC Module Registers

The RTCC module registers are organized into three categories:

- RTCC Control Registers
- RTCC Value Registers
- Alarm Value Registers

20.1.1 REGISTER MAPPING

To limit the register interface, the RTCC Timer and Alarm Time registers are accessed through the corresponding register pointers. The RTCC Value register window (RTCVALH and RTCVALL) uses the RTCPTR bits (RCFGCAL<9:8>) to select the desired Timer register pair (see Table 20-1).

By writing the RTCVALH byte, the RTCC Pointer value, RTCPTR<1:0> bits, decrement by one until they reach '00'. Once they reach '00', the MINUTES and SECONDS value will be accessible through RTCVALH and RTCVALL until the pointer value is manually changed.

TABLE 20-1: RTCVAL REGISTER MAPPING

RTCPTR	RTCC Value Register Window			
<1:0>	RTCVAL<15:8>	RTCVAL<7:0>		
00	MINUTES	SECONDS		
01	WEEKDAY	HOURS		
10	MONTH	DAY		
11		YEAR		

The Alarm Value register window (ALRMVALH and ALRMVALL) uses the ALRMPTR bits (ALCFGRPT<9:8>) to select the desired Alarm register pair (see Table 20-2).

By writing the ALRMVALH byte, the Alarm Pointer value bits, ALRMPTR<1:0>, decrement by one until they reach '00'. Once they reach '00', the ALRMMIN and ALRMSEC value will be accessible through ALRMVALH and ALRMVALL until the pointer value is manually changed.

EXAMPLE 20-1: SETTING THE RTCWREN BIT

```
asm volatile("disi #5");
asm volatile("mov #0x55, w7");
asm volatile("mov w7, _NVMKEY");
asm volatile("mov #0xAA, w8");
asm volatile("mov w8, _NVMKEY");
asm volatile("bset _RCFGCAL, #13"); //
```

TABLE 20-2: ALRMVAL REGISTER MAPPING

ALRMPTR	Alarm Value Register Window			
<1:0>	ALRMVAL<15:8>	ALRMVAL<7:0>		
00	ALRMMIN	ALRMSEC		
01	ALRMWD	ALRMHR		
10	ALRMMNTH	ALRMDAY		
11	_	_		

Considering that the 16-bit core does not distinguish between 8-bit and 16-bit read operations, the user must be aware that when reading either the ALRMVALH or ALRMVALL bytes, they will decrement the ALRMPTR<1:0> value. The same applies to the RTCVALH or RTCVALL bytes with the RTCPTR<1:0> being decremented.

Note:	This only applies to read operations and
	not write operations.

20.1.2 WRITE LOCK

In order to perform a write to any of the RTCC Timer registers, the RTCWREN (RCFGCAL<13>) bit must be set (refer to Example 20-1).

Note: To avoid accidental writes to the timer, it is recommended that the RTCWREN bit (RCFGCAL<13>) is kept clear at any other time. For the RTCWREN bit to be set, there is only 1 instruction cycle time window allowed between the unlock sequence and the setting of RTCWREN; therefore, it is recommended that code follow the procedure in Example 20-1.

For applications written in C, the unlock sequence should be implemented using in-line assembly.

//set the RTCWREN bit

20.1.3 RTCC CONTROL REGISTERS

REGISTER 20-1: RCFGCAL: RTCC CALIBRATION AND CONFIGURATION REGISTER⁽¹⁾

R/W-0	U-0	R/W-0	R-0, HSC	R-0, HSC	R/W-0	R/W-0, HSC	R/W-0, HSC	
RTCEN ⁽²⁾	_	RTCWREN	RTCSYNC	HALFSEC ⁽³⁾	RTCOE	RTCPTR1	RTCPTR0	
oit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
CAL7	CAL6	CAL5	CAL4	CAL3	CAL2	CAL1	CAL0	
pit 7							bit (
Legend:		HSC = Hardw	are Settable/C	learable bit				
R = Readable	e bit	W = Writable b	oit	U = Unimplem	ented bit, rea	d as '0'		
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ired	x = Bit is unkn	iown	
		(2)						
bit 15		CC Enable bit ⁽²⁾	-1					
		nodule is enable nodule is disable						
bit 14		nted: Read as '0						
oit 13	-	RTCC Value Re		Enable bit				
		H and RTCVAL	•		y the user			
		H and RTCVAL				n to by the user		
bit 12	RTCSYNC:	RTCC Value Reg	disters Read S	vnchronization	hit			
	1 = RTCVALH, RTCVALL and ALCFGRPT registers can change while reading due to a rollover ripple resulting in an invalid data read. If the register is read twice and results in the same data, the data							
			d ALCFGRPT	registers can c	hange while i			
	resulting	, in an invalid da	d ALCFGRPT ta read. If the	registers can c	hange while i			
	resulting can be a	in an invalid da assumed to be v	nd ALCFGRPT ta read. If the r alid.	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
bit 11	resulting can be a 0 = RTCVAL	in an invalid da assumed to be va _H, RTCVALL or	nd ALCFGRPT ta read. If the r alid. ALCFGRPT r	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
bit 11	resulting can be a 0 = RTCVAL HALFSEC: H	in an invalid da assumed to be v	nd ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
bit 11	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second	g in an invalid da assumed to be va .H, RTCVALL or Half-Second Stat	nd ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
bit 11 bit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal	in an invalid da assumed to be va .H, RTCVALL or Half-Second Stat half period of a s	nd ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o	in an invalid da assumed to be va LH, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit	registers can c register is read t	hange while i twice and res	ults in the same	data, the data	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled	nd ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit	registers can c register is read egisters can be	hange while i twice and res read without	ults in the same	data, the data	
	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1:	in an invalid da assumed to be va LH, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit	registers can c register is read f egisters can be dow Pointer bits	hange while i twice and res read without	ults in the same	data, the data	
bit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the	in an invalid da assumed to be va LH, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the data rollover ripple /ALL registers	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R R<1:0> value dec	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the	a in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R R<1:0> value dec : <u>8>:</u>	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF RTCVAL<15 11 = Reserv 10 = MONTH	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <<1:0> value dec :8>: ed	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF RTCVAL<15 11 = Reserv 10 = MONTH 01 = WEEKI	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <<1:0> value dec : <u>8>:</u> ed H DAY	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
bit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF <u>RTCVAL<15</u> 11 = Reserv 10 = MONTH 01 = WEEKI 00 = MINUT	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <1:0> value dec : <u>8>:</u> ed H DAY ES	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
pit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF <u>RTCVAL<15</u> 11 = Reserv 10 = MONTH 01 = WEEKI 00 = MINUT <u>RTCVAL<7:C</u>	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <1:0> value dec : <u>8>:</u> ed H DAY ES	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
bit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF <u>RTCVAL<15</u> 11 = Reserv 10 = MONTH 01 = WEEKI 00 = MINUT	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <1:0> value dec : <u>8>:</u> ed H DAY ES	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the dat	
bit 10	resulting can be a 0 = RTCVAL HALFSEC: H 1 = Second 0 = First hal RTCOE: RTC 1 = RTCC o 0 = RTCC o RTCPTR<1: Points to the The RTCPTF <u>RTCVAL<15</u> 11 = Reserv 10 = MONTH 01 = WEEKI 00 = MINUT <u>RTCVAL<7:C</u> 11 = YEAR	in an invalid da assumed to be va H, RTCVALL or Half-Second Stat half period of a sec CC Output Enab utput is enabled utput is disabled 0>: RTCC Value corresponding R <1:0> value dec : <u>8>:</u> ed H DAY ES)>:	d ALCFGRPT ta read. If the r alid. ALCFGRPT r tus bit ⁽³⁾ second ond le bit Register Wind TCC Value reg	registers can c register is read f egisters can be dow Pointer bits gisters when rea	hange while i twice and res read without ding the RTC	ults in the same concern over a r VALH and RTCV	data, the data rollover ripple /ALL registers	

Note 1: The RCFGCAL register is only affected by a POR.

- **2:** A write to the RTCEN bit is only allowed when RTCWREN = 1.
- 3: This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

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REGISTER 20-1: RCFGCAL: RTCC CALIBRATION AND CONFIGURATION REGISTER⁽¹⁾

bit 7-0	CAL<7:0>: RTC Drift Calibration bits					
	01111111 =	Maximum positive adjustment; adds 508 RTC clock pulses every one minute				
	:					
	11111111 = 00000001 =	Minimum negative adjustment; subtracts 4 RTC clock pulses every one minute Minimum positive adjustment; adds 4 RTC clock pulses every one minute No adjustment				
	: 10000000 =	Maximum negative adjustment; subtracts 512 RTC clock pulses every one minute				

- **Note 1:** The RCFGCAL register is only affected by a POR.
 - 2: A write to the RTCEN bit is only allowed when RTCWREN = 1.
 - 3: This bit is read-only. It is cleared to '0' on a write to the lower half of the MINSEC register.

REGISTER 20-2: PADCFG1: PAD CONFIGURATION CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0
—	—	—	—	—	—	RTSECSEL ⁽¹⁾	PMPTTL
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-2	Unimplemented: Read as '0'
bit 1	RTSECSEL: RTCC Seconds Clock Output Select bit ⁽¹⁾
	 1 = RTCC seconds clock is selected for the RTCC pin 0 = RTCC alarm pulse is selected for the RTCC pin
bit 0	PMPTTL: EPMP Module TTL Input Buffer Select bit
	1 = EPMP module inputs (PMDx, PMCS1) use TTL input buffers
	0 = EPMP module inputs use Schmitt Trigger input buffers

Note 1: To enable the actual RTCC output, the RTCOE (RCFGCAL<10>) bit must also be set.

REGISTER 20-3: ALCFGRPT: ALARM CONFIGURATION REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0, HSC	R/W-0, HS0
ALRMEN	CHIME	AMASK3	AMASK2	AMASK1	AMASK0	ALRMPTR1	ALRMPTR
bit 15							bit
R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HSC	R/W-0, HS0
ARPT7	ARPT6	ARPT5	ARPT4	ARPT3	ARPT2	ARPT1	ARPT0
bit 7		,			, <u>-</u>		bit
Legend:			are Settable/Cl				
R = Readable	bit	W = Writable	bit	U = Unimplem	nented bit, read	l as '0'	
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkn	own
bit 15	ALRMEN: Ala 1 = Alarm is CHIME = 0 = Alarm is o	enabled (clear 0)	ed automatica	lly after an ala	rm event whe	never ARPT<7	:0> = 00h ar
bit 14	CHIME: Chim	e Enable bit					
		,	Γ<7:0> bits are T<7:0> bits sto			to FFh	
bit 13-10			Configuration b				
		a month a week a day hour 10 minutes minute 10 seconds second	when configure	ed for February	29 th , once eve	ery 4 years)	
bit 9-8	ALRMPTR<1	:0>: Alarm Valu	ue Register Wir	ndow Pointer bi	ts		
		R<1:0> value de 5:8>: mented NTH D IN <u>D>:</u> mented AY	-		-	ALH and ALRM H until it reache	-
	00 = ALRMSE	EC					
bit 7-0	ARPT<7:0>: /	Alarm Repeat (Counter Value b	oits			
		Alarm will repe	eat 255 more ti	mes			
				t. The counter is	s prevented from	m rolling over fr	om 00h to FF

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unless CHIME = 1.

20.1.4 RTCVAL REGISTER MAPPINGS

REGISTER 20-4: YEAR: YEAR VALUE REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

| R/W-x, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| YRTEN3 | YRTEN2 | YRTEN1 | YRTEN0 | YRONE3 | YRONE2 | YRONE1 | YRONE0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	Unimplemented:	Read	as	'0'
----------	----------------	------	----	-----

- bit 7-4 **YRTEN<3:0>:** Binary Coded Decimal Value of Year's Tens Digit bits Contains a value from 0 to 9.
- bit 3-0 **YRONE<3:0>:** Binary Coded Decimal Value of Year's Ones Digit bits Contains a value from 0 to 9.

Note 1: A write to the YEAR register is only allowed when RTCWREN = 1.

REGISTER 20-5: MTHDY: MONTH AND DAY VALUE REGISTER⁽¹⁾

U-0	U-0	U-0	R/W-x, HSC				
—	—	—	MTHTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0
bit 15							bit 8

U-0	U-0	R/W-x, HSC					
—	—	DAYTEN1	DAYTEN0	DAYONE3	DAYONE2	DAYONE1	DAYONE0
bit 7							bit 0

Legend:	HSC = Hardware Settable/C	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as 'O'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

 bit 15-13
 Unimplemented: Read as '0'

 bit 12
 MTHTEN0: Binary Coded Decimal Value of Month's Tens Digit bit

 Contains a value of 0 or 1.
 MTHONE<3:0>: Binary Coded Decimal Value of Month's Ones Digit bits

 bit 11-8
 MTHONE<3:0>: Binary Coded Decimal Value of Month's Ones Digit bits

 Contains a value from 0 to 9.
 Output

bit 7-6 Unimplemented: Read as '0'

- bit 5-4 **DAYTEN<1:0>:** Binary Coded Decimal Value of Day's Tens Digit bits Contains a value from 0 to 3.
- bit 3-0 **DAYONE<3:0>:** Binary Coded Decimal Value of Day's Ones Digit bits Contains a value from 0 to 9.

Note 1: A write to this register is only allowed when RTCWREN = 1.

REGISTER 20-6: WKDYHR: WEEKDAY AND HOURS VALUE REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	R/W-x, HSC	R/W-x, HSC	R/W-x, HSC
—	—	—	—	—	WDAY2	WDAY1	WDAY0
bit 15							bit 8

U-0	U-0	R/W-x, HSC					
—	—	HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11	Unimplemented: Read as '0'
bit 10-8	WDAY<2:0>: Binary Coded Decimal Value of Weekday Digit bits
	Contains a value from 0 to 6.
bit 7-6	Unimplemented: Read as '0'
bit 5-4	HRTEN<1:0>: Binary Coded Decimal Value of Hour's Tens Digit bits
	Contains a value from 0 to 2.
bit 3-0	HRONE<3:0>: Binary Coded Decimal Value of Hour's Ones Digit bits
	Contains a value from 0 to 9.

Note 1: A write to this register is only allowed when RTCWREN = 1.

REGISTER 20-7: MINSEC: MINUTES AND SECONDS VALUE REGISTER

U-0	R/W-x, HSC						
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0
bit 15							bit 8

U-0	R/W-x, HSC						
—	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	Unimplemented: Read as '0'
bit 14-12	MINTEN<2:0>: Binary Coded Decimal Value of Minute's Tens Digit bits
	Contains a value from 0 to 5.
bit 11-8	MINONE<3:0>: Binary Coded Decimal Value of Minute's Ones Digit bits
	Contains a value from 0 to 9.
bit 7	Unimplemented: Read as '0'
bit 6-4	SECTEN<2:0>: Binary Coded Decimal Value of Second's Tens Digit bits
	Contains a value from 0 to 5.
bit 3-0	SECONE<3:0>: Binary Coded Decimal Value of Second's Ones Digit bits
	Contains a value from 0 to 9.

20.1.5 ALRMVAL REGISTER MAPPINGS

REGISTER 20-8: ALMTHDY: ALARM MONTH AND DAY VALUE REGISTER⁽¹⁾

U-0	U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
_	—	_	MTHTEN0	MTHONE3	MTHONE2	MTHONE1	MTHONE0	
bit 15			•				bit 8	
		D 444	D 444	D 444	D 444	D 444	D 444	
U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	
	—	DAYTEN1	DAYTEN0	DAYONE3	DAYONE2	DAYONE1	DAYONE0	
bit 7							bit 0	
Legend:								
-				U = Unimplemented bit, read as '0'				
R = Readable	e bit	W = Writable	bit	U = Unimpler	nented bit, read	l as '0'		
R = Readable		W = Writable '1' = Bit is set		U = Unimplem '0' = Bit is clea		I as '0' x = Bit is unkn	iown	
							lown	
	POR						own	
-n = Value at	POR	<pre>'1' = Bit is set ted: Read as '0</pre>	0'		ared		lown	
-n = Value at bit 15-13	POR	'1' = Bit is set ted: Read as 'd	0'	ʻ0' = Bit is clea	ared		iown	
-n = Value at bit 15-13	POR Unimplemen MTHTEN0: B Contains a va	'1' = Bit is set ted: Read as '0 inary Coded De alue of 0 or 1.	₀ , ecimal Value o	ʻ0' = Bit is clea	ared Digit bit		lown	
-n = Value at bit 15-13 bit 12	POR Unimplemen MTHTEN0: B Contains a va MTHONE<3:	'1' = Bit is set ted: Read as '0 inary Coded De alue of 0 or 1.	^{D'} ecimal Value o ed Decimal Va	ʻ0' = Bit is clea f Month's Tens	ared Digit bit		iown	
-n = Value at bit 15-13 bit 12	POR Unimplemen MTHTEN0: B Contains a va MTHONE<3: Contains a va	'1' = Bit is set ted: Read as 'd inary Coded De alue of 0 or 1. 0>: Binary Code	o' ecimal Value o ed Decimal Va	ʻ0' = Bit is clea f Month's Tens	ared Digit bit		iown	
-n = Value at bit 15-13 bit 12 bit 11-8	POR Unimplemen MTHTEN0: B Contains a va MTHONE<3: Contains a va Unimplemen	 '1' = Bit is set ted: Read as '0 inary Coded De alue of 0 or 1. 0>: Binary Code alue from 0 to 9 ted: Read as '0 	o' ecimal Value o ed Decimal Va o'	ʻ0' = Bit is clea f Month's Tens	ared Digit bit Dnes Digit bits		iown	
<u>-n = Value at</u> bit 15-13 bit 12 bit 11-8 bit 7-6	POR Unimplemen MTHTEN0: B Contains a va MTHONE<3: Contains a va Unimplemen DAYTEN<1:0	 '1' = Bit is set ted: Read as '0 inary Coded De alue of 0 or 1. 0>: Binary Code alue from 0 to 9 ted: Read as '0 	o' ecimal Value o ed Decimal Va o' ed Decimal Value	'0' = Bit is clea f Month's Tens lue of Month's (ared Digit bit Dnes Digit bits		iown	
<u>-n = Value at</u> bit 15-13 bit 12 bit 11-8 bit 7-6	POR Unimplemen MTHTEN0: B Contains a va MTHONE<3: Contains a va Unimplemen DAYTEN<1:0 Contains a va	 '1' = Bit is set ted: Read as '0 inary Coded De alue of 0 or 1. 0>: Binary Code alue from 0 to 9 ted: Read as '0 >: Binary Code alue from 0 to 3 	o' ecimal Value o ed Decimal Va o' ed Decimal Valu	'0' = Bit is clea f Month's Tens lue of Month's (ared Digit bit Ones Digit bits s Digit bits		iown	

REGISTER 20-9: ALWDHR: ALARM WEEKDAY AND HOURS VALUE REGISTER⁽¹⁾

U-0	U-0	U-0	U-0	U-0	R/W-x	R/W-x	R/W-x
—	_	—	—	—	WDAY2	WDAY1	WDAY0
bit 15							bit 8
U-0	U-0	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x	R/W-x
—		HRTEN1	HRTEN0	HRONE3	HRONE2	HRONE1	HRONE0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit			U = Unimplemented bit, read as '0'				

-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11	Unimplemented: Read as '0'
bit 10-8	WDAY<2:0>: Binary Coded Decimal Value of Weekday Digit bits
	Contains a value from 0 to 6.
bit 7-6	Unimplemented: Read as '0'
bit 5-4	HRTEN<1:0>: Binary Coded Decimal Value of Hour's Tens Digit bits
	Contains a value from 0 to 2.
bit 3-0	HRONE<3:0>: Binary Coded Decimal Value of Hour's Ones Digit bits
	Contains a value from 0 to 9.

Note 1: A write to this register is only allowed when RTCWREN = 1.

REGISTER 20-10: ALMINSEC: ALARM MINUTES AND SECONDS VALUE REGISTER

U-0	R/W-x							
—	MINTEN2	MINTEN1	MINTEN0	MINONE3	MINONE2	MINONE1	MINONE0	
bit 15							bit 8	
U-0	R/W-x							
_	SECTEN2	SECTEN1	SECTEN0	SECONE3	SECONE2	SECONE1	SECONE0	
bit 7							bit 0	

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	Unimplemented: Read as '0'
bit 14-12	MINTEN<2:0>: Binary Coded Decimal Value of Minute's Tens Digit bits
	Contains a value from 0 to 5.
bit 11-8	MINONE<3:0>: Binary Coded Decimal Value of Minute's Ones Digit bits
	Contains a value from 0 to 9.
bit 7	Unimplemented: Read as '0'
bit 6-4	SECTEN<2:0>: Binary Coded Decimal Value of Second's Tens Digit bits
	Contains a value from 0 to 5.
bit 3-0	SECONE<3:0>: Binary Coded Decimal Value of Second's Ones Digit bits
	Contains a value from 0 to 9.

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20.2 Calibration

The real-time crystal input can be calibrated using the periodic auto-adjust feature. When properly calibrated, the RTCC can provide an error of less than 3 seconds per month. This is accomplished by finding the number of error clock pulses for one minute and storing the value into the lower half of the RCFGCAL register. The 8-bit signed value loaded into the lower half of RCFGCAL is multiplied by four and will either be added or subtracted from the RTCC timer, once every minute. Refer to the following steps for RTCC calibration:

- 1. Using another timer resource on the device, the user must find the error of the 32.768 kHz crystal.
- 2. Once the error is known, it must be converted to the number of error clock pulses per minute and loaded into the RCFGCAL register.

EQUATION 20-1: RTCC CALIBRATION

Error (clocks per minute) = (Ideal Frequency \dagger – Measured Frequency) x 60

†Ideal Frequency = 32,768H

3. a) If the oscillator is faster then ideal (negative result form Step 2), the RCFGCAL register value needs to be negative. This causes the specified number of clock pulses to be subtracted from the timer counter, once every minute.

b) If the oscillator is slower then ideal (positive result from Step 2), the RCFGCAL register value needs to be positive. This causes the specified number of clock pulses to be added to the timer counter, once every minute.

 Divide the number of error clocks per minute by 4 to get the correct CAL value and load the RCFGCAL register with the correct value.

(Each 1-bit increment in CAL adds or subtracts 4 pulses).

Writes to the lower half of the RCFGCAL register should only occur when the timer is turned off or immediately after the rising edge of the seconds pulse.

Note: It is up to the user to include in the error value the initial error of the crystal, drift due to temperature and drift due to crystal aging.

20.3 Alarm

- Configurable from half second to one year
- Enabled using the ALRMEN bit (ALCFGRPT<15>, Register 20-3)
- One-time alarm and repeat alarm options
 available

20.3.1 CONFIGURING THE ALARM

The alarm feature is enabled using the ALRMEN bit. This bit is cleared when an alarm is issued. Writes to ALRMVAL should only take place when ALRMEN = 0.

As shown in Figure 20-2, the interval selection of the alarm is configured through the AMASK bits (ALCFGRPT<13:10>). These bits determine which and how many digits of the alarm must match the clock value for the alarm to occur.

The alarm can also be configured to repeat based on a preconfigured interval. The amount of times this occurs, once the alarm is enabled, is stored in the ARPT bits, ARPT<7:0> (ALCFGRPT<7:0>). When the value of the ARPT bits equals 00h and the CHIME bit (ALCFGRPT<14>) is cleared, the repeat function is disabled and only a single alarm will occur. The alarm can be repeated up to 255 times by loading ARPT<7:0> with FFh.

After each alarm is issued, the value of the ARPT bits is decremented by one. Once the value has reached 00h, the alarm will be issued one last time, after which the ALRMEN bit will be cleared automatically and the alarm will turn off.

Indefinite repetition of the alarm can occur if the CHIME bit = 1. Instead of the alarm being disabled when the value of the ARPT bits reaches 00h, it rolls over to FFh and continues counting indefinitely while CHIME is set.

20.3.2 ALARM INTERRUPT

At every alarm event, an interrupt is generated. In addition, an alarm pulse output is provided that operates at half the frequency of the alarm. This output is completely synchronous to the RTCC clock and can be used as a trigger clock to other peripherals.

Note: Changing any of the registers, other then the RCFGCAL and ALCFGRPT registers and the CHIME bit while the alarm is enabled (ALRMEN = 1), can result in a false alarm event leading to a false alarm interrupt. To avoid a false alarm event, the timer and alarm values should only be changed while the alarm is disabled (ALRMEN = 0). It is recommended that the ALCFGRPT register and CHIME bit be changed when RTCSYNC = 0.

FIGURE 20-2:	ALARM MASK SE	TTINGS					
	ask Setting SK<3:0>)	Day of the Week	Month	Day	Hours	Minutes	Seconds
0000 – Eve 0001 – Eve	ry half second ry second						
0010 – Eve	ry 10 seconds						S
0011 – Eve	ry minute						S S
0100 – Eve	ry 10 minutes					m :	s s
0101 – Eve	ry hour					m m :	S S
0110 – Eve	ry day				h h :	m ;	S S
0111 – Eve	ry week	d			h h :	m m :	SS
1000 – Eve	ry month			d d	h h :	m m :	S S
1001 – Eve	ry year ⁽¹⁾		m m /	d d	h h :		S S
Note 1: A	nnually, except when confi	gured for F	ebruary 29.				

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NOTES:

21.0 32-BIT PROGRAMMABLE CYCLIC REDUNDANCY CHECK (CRC) GENERATOR

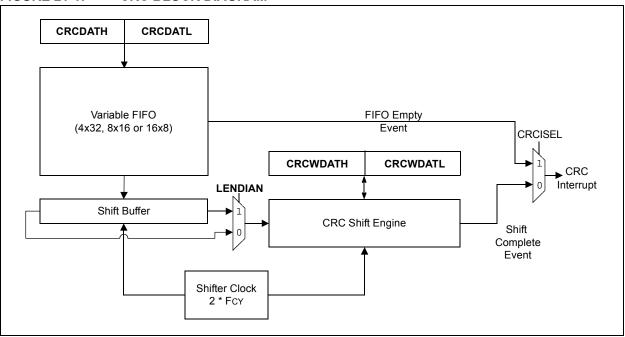
Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 41. "32-Bit Programmable Cyclic Redundancy Check (CRC)" (DS39729). The information in this data sheet supersedes the information in the FRM.

FIGURE 21-1:	CRC BLOCK DIAGRAM

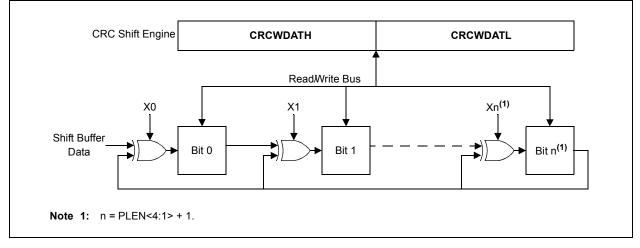
The 32-bit programmable CRC generator provides a hardware implemented method of quickly generating checksums for various networking and security applications. It offers the following features:

- User-programmable CRC polynomial equation, up to 32 bits
- · Programmable shift direction (little or big-endian)
- · Independent data and polynomial lengths
- Configurable interrupt output
- Data FIFO

Figure 21-1 displays a simplified block diagram of the CRC generator. A simple version of the CRC shift engine is displayed in Figure 21-2.







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21.1 User Interface

21.1.1 POLYNOMIAL INTERFACE

The CRC module can be programmed for CRC polynomials of up of up the 32^{nd} order, using up to 32 bits.

Polynomial length, which reflects the highest exponent in the equation, is selected by the PLEN<4:0> bits (CRCCON2<4:0>).

The CRCXORL and CRCXORH registers control which exponent terms are included in the equation. Setting a particular bit includes that exponent term in the equation; functionally, this includes an XOR operation on the corresponding bit in the CRC engine. Clearing the bit disables the XOR.

For example, consider two CRC polynomials, one a 16-bit and the other a 32-bit equation.

EQUATION 21-1: 16-BIT, 32-BIT CRC POLYNOMIALS

X16 + X12 + X5 + 1

and

 $\begin{array}{c} X32 + X26 + X23 + X22 + X16 + X12 + X11 + X10 + \\ X8 + X7 + X5 + X4 + X2 + X + 1 \end{array}$

To program these polynomial into the CRC generator, set the register bits as shown in Table 21-1.

Note that the appropriate positions are set to '1' to indicate they are used in the equation (for example, X26 and X23). The '0' bit required by the equation is always XORed; thus, X0 is a don't care. For a polynomial of length 32, it is assumed that the 32^{nd} bit will be used. Therefore, the X<31:1> bits do not have the 32^{nd} bit.

21.1.2 DATA INTERFACE

The module incorporates a FIFO that works with a variable data width. Input data width can be configured to any value between one and 32 bits using the DWIDTH<4:0> bits (CRCCON2<12:8>). When the data width is greater than 15, the FIFO is four words deep. When the DWITDH bits are between 15 and 8, the FIFO is 8 words deep. When the DWIDTH bits are less than 8, the FIFO is 16 words deep.

The data for which the CRC is to be calculated must first be written into the FIFO. Even if the data width is less than 8, the smallest data element that can be written into the FIFO is one byte. For example, if DWIDTH is five, then the size of the data is DWIDTH + 1 or six. The data is written as a whole byte; the two unused upper bits are ignored by the module.

Once data is written into the MSb of the CRCDAT registers (that is, MSb as defined by the data width), the value of the VWORD<4:0> bits (CRCCON1<12:8>) increments by one. For example, if DWIDTH is 24, the VWORD bits will increment when bit 7 of CRCDATH is written. Therefore, CRCDATL must always be written to before CRCDATH.

The CRC engine starts shifting data when the CRCGO bit is set and the value of VWORD is greater than zero.

Each word is copied out of the FIFO into a buffer register, which decrements VWORD. The data is then shifted out of the buffer. The CRC engine continues shifting at a rate of two bits per instruction cycle, until VWORD reaches zero. This means that for a given data width, it takes half that number of instructions for each word to complete the calculation. For example, it takes 16 cycles to calculate the CRC for a single word of 32-bit data.

When VWORD reaches the maximum value for the configured value of DWIDTH (4, 8 or 16), the CRCFUL bit becomes set. When VWORD reaches zero, the CRCMPT bit becomes set. The FIFO is emptied and the VWORD<4:0> bits are set to '00000' whenever CRCEN is '0'.

At least one instruction cycle must pass after a write to CRCWDAT before a read of the VWORD bits is done.

CRC Control Bits	Bit Values				
	16-Bit Polynomial	32-Bit Polynomial			
PLEN<4:0>	01111	11111			
X<31:16>	0000 0000 0000 0001	0000 0100 1100 0001			
X<15:0>	0001 0000 0010 000x	0001 1101 1011 011x			

TABLE 21-1: CRC SETUP EXAMPLES FOR 16 AND 32-BIT POLYNOMIALS

21.1.3 DATA SHIFT DIRECTION

The LENDIAN bit (CRCCON1<3>) is used to control the shift direction. By default, the CRC will shift data through the engine, MSb first. Setting LENDIAN (= 1) causes the CRC to shift data, LSb first. This setting allows better integration with various communication schemes and removes the overhead of reversing the bit order in software. Note that this only changes the direction the data is shifted into the engine. The result of the CRC calculation will still be a normal CRC result, not a reverse CRC result.

21.1.4 INTERRUPT OPERATION

The module generates an interrupt that is configurable by the user for either of two conditions.

If CRCISEL is '0', an interrupt is generated when the VWORD<4:0> bits make a transition from a value of '1' to '0'. If CRCISEL is '1', an interrupt will be generated after the CRC operation finishes and the module sets the CRCGO bit to '0'. Manually setting CRCGO to '0' will not generate an interrupt. Note that when an interrupt occurs, the CRC calculation would not yet be complete. The module will still need (PLEN + 1)/2 clock cycles after the interrupt is generated until the CRC calculation is finished.

21.1.5 TYPICAL OPERATION

To use the module for a typical CRC calculation:

- 1. Set the CRCEN bit to enable the module.
- Configure the module for desired operation:

 a) Program the desired polynomial using the CRCXORL and CRCXORH registers, and the PLEN<4:0> bits.

b) Configure the data width and shift direction using the DWIDTH and LENDIAN bits.

c) Select the desired interrupt mode using the CRCISEL bit.

- Preload the FIFO by writing to the CRCDATL and CRCDATH registers until the CRCFUL bit is set or no data is left.
- Clear old results by writing 00h to CRCWDATL and CRCWDATH. The CRCWDAT registers can also be left unchanged to resume a previously halted calculation.
- 5. Set the CRCGO bit to start calculation.
- 6. Write remaining data into the FIFO as space becomes available.
- When the calculation completes, CRCGO is automatically cleared. An interrupt will be generated if CRCISEL = 1.
- 8. Read CRCWDATL and CRCWDATH for the result of the calculation.

There are eight registers used to control programmable CRC operation:

- CRCCON1
- CRCCON2
- CRCXORL
- CRCXORH
- CRCDATL
- CRCDATH
- CRCWDATL
- CRCWDATH

The CRCCON1 and CRCCON2 registers (Register 21-1 and Register 21-2) control the operation of the module and configure the various settings.

The CRCXOR registers (Register 21-3 and Register 21-4) select the polynomial terms to be used in the CRC equation. The CRCDAT and CRCWDAT registers are each register pairs that serve as buffers for the double-word input data, and CRC processed output, respectively.

REGISTER	21-1: CRC0	CON1: CRC (CONTROL 1	REGISTER			
R/W-0	U-0	R/W-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
CRCEN	—	CSIDL	VWORD4	VWORD3	VWORD2	VWORD1	VWORD0
bit 15			- -				bit 8
R-0, HSC	R-1, HSC	R/W-0	R/W-0, HC	R/W-0	U-0	U-0	U-0
CRCFUL	CRCMPT	CRCISEL	CRCGO	LENDIAN	—	—	—
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	iown
HC = Hardwa	are Cleared	HSC = Hardw	/are Settable/C	learable bit			
bit 15	CRCEN: CRC	C Enable bit					
1 = Enables module							
	0 = Disables module; all state machines, pointers and CRCWDAT/CRCDATH reset; other SFRs a NOT reset.						
bit 14	NOT reset Unimplemented: Read as '0'						
bit 13	-						
DIL 13		Stop in Idle Mo	eration when de	wice enters Idu	a mode		
			tion in Idle mod		emoue		
bit 12-8		- >: Pointer Valu					
	Indicates the 16 when PLE		d words in the	FIFO. Has a m	aximum value	of 8 when PLE	N<4:0> ≥ 7 or
bit 7	CRCFUL: FIF	FO Full bit					
	1 = FIFO is f	ull					
	0 = FIFO is r	not full					
bit 6	CRCMPT: FI	O Empty bit					
	$1 = FIFO is \epsilon$						
1.1. F	0 = FIFO is r	1 3	la ati ana la it				
bit 5		RC Interrupt Se		of data is still a	aiffing through t		
			y; the final word ete and results a		ninung through t		
bit 4	CRCGO: Star			are ready			
DIL 4		C serial shifter					
		ial shifter is turi	ned off				
bit 3		ata Shift Directi					
			the CRC, star	ting with the LS	Sb (little endian)	
			the CRC, star				
bit 2-0	Unimplemen	ted: Read as '	0'				

U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_	_	—	DWIDTH4	DWIDTH3	DWIDTH2	DWIDTH1	DWIDTH0	
bit 15							bit 8	
U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
_	_	—	PLEN4	PLEN3	PLEN2	PLEN1	PLEN0	
bit 7 bit 0								
Legend:								
R = Readable	R = Readable bit W = Writable bit		bit	U = Unimplemented bit, read as '0'				
-n = Value at	n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown		iown		

bit 15-13	Unimplemented: Read as '0'
bit 12-8	DWIDTH<4:0>: Data Word Width Configuration bits
	Configures the width of the data word (data word width – 1).
bit 7-5	Unimplemented: Read as '0'
bit 4-0	PLEN<4:0>: Polynomial Length Configuration bits
	Configures the length of the polynomial (polynomial length – 1).

REGISTER 21-3: CRCXORL: CRC XOR POLYNOMIAL REGISTER, LOW BYTE

-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
R = Readable	e bit	W = Writable	bit	U = Unimplemented bit, read as '0'			
Legend:							
bit 7							bit 0
X7	X6	X5	X4	X3	X2	X1	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	U-0
bit 15							bit 8
X15	X14	X13	X12	X11	X10	X9	X8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0

bit 15-1 X<15:1>: XOR of Polynomial Term xⁿ Enable bits

bit 0 Unimplemented: Read as '0'

REGISTER 21-4: CRCXORH: CRC XOR HIGH REGISTER

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| X23 | X22 | X21 | X20 | X19 | X18 | X17 | X16 |
| bit 7 | | | | | | | bit 0 |

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'	
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 X<31:16>: XOR of Polynomial Term xⁿ Enable bits

REGISTER 21-5: CRCDATL: CRC DATA LOW REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA15	DATA14	DATA13	DATA12	DATA11	DATA10	DATA9	DATA8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| DATA7 | DATA6 | DATA5 | DATA4 | DATA3 | DATA2 | DATA1 | DATA0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	d as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 DATA<15:0>: CRC Input Data bits

Writing to this register fills the FIFO; reading from this register returns '0'.

REGISTER 21-6: CRCDATH: CRC DATA HIGH REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA15	DATA14	DATA13	DATA12	DATA11	DATA10	DATA9	DATA8
bit 15				·	•	- -	bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DATA7	DATA6	DATA5	DATA4	DATA3	DATA2	DATA1	DATA0
bit 7				·		·	bit 0
Legend:							
R = Readable bit W = Writable bit			bit	U = Unimplemented bit, read as '0'			
-n = Value at POR '1' = Bit is set			'0' = Bit is cleared x = Bit is unknown			nown	

bit 15-0 DATA<15:0>: CRC Input Data bits

Writing to this register fills the FIFO; reading from this register returns '0'.

REGISTER 21-7: CRCWDATL: CRC SHIFT LOW REGISTER

| R/W-0, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| SDATA15 | SDATA14 | SDATA13 | SDATA12 | SDATA11 | SDATA10 | SDATA9 | SDATA8 |
| bit 15 | | | | | | | bit 8 |

| R/W-0, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| SDATA7 | SDATA6 | SDATA5 | SDATA4 | SDATA3 | SDATA2 | SDATA1 | SDATA0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/C	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-0 **SDATA<15:0>:** CRC Shift Register bits Writing to this register writes to the CRC Shift register through the CRC write bus. Reading from this register reads the CRC read bus.

REGISTER 21-8: CRCWDATH: CRC SHIFT HIGH REGISTER

| R/W-0, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| SDATA31 | SDATA30 | SDATA29 | SDATA28 | SDATA27 | SDATA26 | SDATA25 | SDATA24 |
| bit 15 | | | | | | | bit 8 |

| R/W-0, HSC |
|------------|------------|------------|------------|------------|------------|------------|------------|
| SDATA23 | SDATA22 | SDATA21 | SDATA20 | SDATA19 | SDATA18 | SDATA17 | SDATA16 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/C	SC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15-0 SDATA<31:16>: CRC Input Data bits

Writing to this register writes to the CRC Shift register through the CRC write bus. Reading from this register reads the CRC read bus.

NOTES:

22.0 GRAPHICS CONTROLLER MODULE (GFX)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 43. "Graphics Controller Module (GFX)" (DS39731). The information in this data sheet supersedes the information in the FRM.

The Graphics Controller (GFX) module is specifically designed to directly interface with the display glasses, with a built-in analog drive, to individually control pixels in the screen. The module also provides an accelerated rendering of vertical and horizontal lines, rectangles, copying of rectangular area between different locations on the screen, drawing texts and decompressing packed data. The use of the accelerated rendering is performed using command registers. Once initiated, the hardware will perform the rendering, and the software can either poll the status, or use the interrupts to continue rendering of the succeeding shapes. Key features of the GFX module include:

- Direct interface to three categories of display glasses:
 - Monochrome STN
 - Color STN
 - Color TFT
- Programmable vertical and horizontal synchronization signals' timing and display clock frequency to meet display's frame rates
- Optional internal or external display buffer to accommodate different types of display resolution
- · Graphic hardware accelerators:
 - Character Graphics Processing Unit (CHRGPU)
 - Rectangle Copy Graphics Processing Unit (RCCGPU)
 - Inflate Processing Unit (IPU)
- 256 Entries Color Look-up Table (CLUT)
- Supports 1/2/4/8/16 bits-per-pixel (bpp) color depth
- Programmable display resolution
- · Supports multiple display interfaces:
 - 4/8/16-bit Monochrome STN
 - 4/8/16-bit Color STN
 - 9/12/18/24-bit color TFT (18 and 24-bit displays are connected as 16-bit 5-6-5 RGB color format)

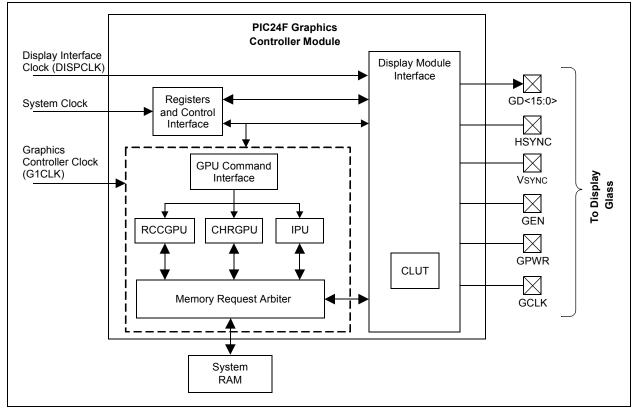


FIGURE 22-1: GRAPHICS MODULE OVERVIEW

22.1 GFX Module Registers

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
GCMD15	GCMD14	GCMD13	GCMD12	GCMD11	GCMD10	GCMD9	GCMD8
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
GCMD7	GCMD6	GCMD5	GCMD4	GCMD3	GCMD2	GCMD1	GCMD0
bit 7	<u>.</u>						bit 0

REGISTER 22-1: G1CMDL: GPU COMMAND LOW REGISTER

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented b	bit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 GCMD<15:0>: Low GPU Command bits

The full 32-bit command is defined by G1CMDH and G1CMDL (GCMD<31:0>). Writes to this register will not trigger the loading of GCMD <31:0> to the command FIFO. For command FIFO loading, see the G1CMDH register description.

REGISTER 22-2: G1CMDH: GPU COMMAND HIGH REGISTER

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| GCMD31 | GCMD30 | GCMD29 | GCMD28 | GCMD27 | GCMD26 | GCMD25 | GCMD24 |
| bit 15 | | | • | | | | bit 8 |
| | | | | | | | |
| R/W-0 |
GCMD23	GCMD22	GCMD21	GCMD20	GCMD19	GCMD18	GCMD17	GCMD16
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented b	oit, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 GCMD<31:16>: High GPU Command bits

The full 32-bit command is defined by G1CMDH and G1CMDL (GCMD<31:0>). A word write to the G1CMDH register triggers the loading of GCMD<31:0> to the command FIFO. Byte writes to the G1CMDH are allowed but only a high byte write will trigger the command loading to the FIFO. Low byte write to this register will only update the G1CMDH<7:0> bits.

REGISTER 22-3: G1CON1: DISPLAY CONTROL REGISTER 1

R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
G1EN	—	G1SIDL	GCMDWMK4	GCMDWMK3	GCMDWMK2	GCMDWMK1	GCMDWMK0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R-0, HSC				
PUBPP2	PUBPP1	PUBPP0	GCMDCNT4	GCMDCNT3	GCMDCNT2	GCMDCNT1	GCMDCNT0
bit 7							bit 0

Legend: H	HSC = Hardware Settable/Clearable bit					
R = Readable bit W	/ = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR '1	' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	G1EN: Module Enable bit 1 = Display module is enabled 0 = Display module is disabled
bit 14	Unimplemented: Read as '0'
bit 13	G1SIDL: Stop in Idle bit
	 1 = Display module stops in Idle mode 0 = Display module does not stop in Idle mode
bit 12-8	GCMDWMK<4:0>: Command FIFO Watermark bits
	Sets the command watermark level that triggers the CMDLVIF interrupt and sets the CMDLV flag; GCMDWMK<4:0> (10000 = Reserved)
	10000 = If the number of commands present in the FIFO goes from 16 to 15 commands, the CMDLVIF interrupt will trigger and the CMDLV flag will be set
	01111 = f the number of commands present in the FIFO goes from 15 to 14 commands, CMDLVIF interrupt will trigger and CMDLV flag will be set
	•
	00001 = If the number of commands present in the FIFO goes from 1 to 0 commands, the CMDLVIF interrupt will trigger and the CMDLV flag will be set 00000 = CMDLVIF interrupt will not trigger and the CMDLV flag will not be set
bit 7-5	PUBPP<2:0>: GPU bits-per-pixel (bpp) Setting bits
	Other = Reserved 100 = 16 bits-per-pixel 011 = 8 bits-per-pixel 010 = 4 bits-per-pixel 001 = 2 bits-per -pixel 000 = 1-bit -per-pixel
bit 4-0	GCMDCNT<4:0>: Command FIFO Occupancy Status bits
	When the FIFO is full, any additional commands written to the FIFO are discarded. 10000 = 16 commands are present in the FIFO 01111 = 15 commands are present in the FIFO
	0001 = 1 command is present in the FIFO 0000 = 0 command is present in the FIFO

REGISTER 22	2-4: G1CON	2: DISPLAY		EGISTER 2			
R/W-0	R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0
DPGWDTH1	DPGWDTH0	DPSTGER1	DPSTGER0	_	—	DPTEST1	DPTEST0
bit 15							bit 8
DAMO	DANO	DANO			DANO	DANIO	DAALO
R/W-0	R/W-0	R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0
DPBPP2 bit 7	DPBPP1	DPBPP0	_	_	DPMODE2	DPMODE1	DPMODE0 bit 0
							DILO
Legend:							
R = Readable I	oit	W = Writable	bit	U = Unimple	emented bit, re	ead as '0'	
-n = Value at P	OR	'1' = Bit is set		'0' = Bit is c	leared	x = Bit is unkno	own
bit 15-14	DPGWDTH<1: 11 = Reserved 10 = 16 bits wid 01 = 8 bits wid 00 = 4 bits wid	l de e e					
bit 13-12	These bits have DPSTGER<1:0				ata width is alwa	iys assumed to b	e 16 bits wide.
	Bit group Bit group Bit group 10 = Even bits	0: 0 4 8 12 – no 1: 1 5 9 13 – do 2: 2 6 10 14 – o 3: 3 7 11 15 – o of the display d	ot delayed blayed by ½ GI delayed by full delayed by 1 ½ data are delayed ata are delayed	PUCLK cycle GPUCLK cyc GPUCLK cy d by 1 full Gl d by ½ GPUC	cle ⁄cle PUCLK cycle; CLK cycle; eve	odd bits are not n bits are not de e	
bit 11-10	Unimplemente	ed: Read as '0'					
bit 9-8	DPTEST<1:0> 11 = Borders 10 = Bars 01 = Black scru 00 = Normal D	een					
bit 7-5	DPBPP<2:0>: This setting mu 100 = 16 bits- 011 = 8 bits-p 010 = 4 bits-p 001 = 2 bits-p 000 = 1 bit-pe Other = Reserv	ist match the G per-pixel er-pixel er-pixel er-pixel er-pixel			3PP<2:0> (G1	CON1<7:5>).	
bit 4-3	Unimplemente	ed: Read as '0'					
bit 2-0	DPMODE<2:03 011 = Color S 010 = Mono S 001 = TFT typ 000 = Display Other = Reserver	STN type STN type be off	s Type bits				

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0					
_	—	_	—	—	_	DPPINOE	DPPOWER					
bit 15							bit					
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0					
DPCLKPOL	DPENPOL	DPVSPOL	DPHSPOL	DPPWROE	DPENOE	DPVSOE	DPHSOE					
bit 7							bit					
Lonondi												
Legend: R = Readable	e bit	W = Writable bit		U = Unimple	mented bit. r	ead as '0'						
-n = Value at		'1' = Bit is set		'0' = Bit is cle		x = Bit is unl	known					
bit 15-10	Unimplomen	ted: Dood on '0'										
bit 9	-	i ted: Read as '0' isplay Pin Output F	Pad Enable bit									
лгэ				must he se	t to allow (GDBEN<15.0						
	DPPINOE is the master output enable and must be set to allow GDBEN<15:0>, DPENOE DPPWROE, DPVSOE and DPHSOE to enable the associated pads											
	1 = Enable display output pads											
	0 = Disable display output signals as set by GDBEN<15:0> Pins used by the signals are assigned to the next enabled module that uses the same pins.											
		the signals are ass als, GDBEN<15:0>										
	DPPINOE is s				lable specific	cuata signais	wrille					
oit 8		Display Power-up I	Power-Down Se	equencer Cont	rol bit							
	Refer to the "PIC24F Family Reference Manual", Section 43. "Graphics Controller Module (GFX)"											
	for details.	-			-		•					
		ay Power Sequence			,							
ait 7		er Control Sequend Display Glass Clo	•	•								
bit 7		atches data on the	. ,									
		atches data on the										
bit 6	DPENPOL: Display Enable Signal (GEN) Polarity bit											
	For TFT mode (DPMODE (G1CON2<2:0>) = 001):											
	1 = Active-high (GEN) 0 = Active-low (GEN)											
	0 = Active-low (GEN) For STN mode (DPMODE (G1CON2<2:0>) = 010 or 011):											
		nects to the shift c			Clock mode	e)						
		nects to the MOD										
bit 5	DPVSPOL: Display Vertical Synchronization (VSYNC) Polarity bit											
	1 = Active-hig											
L:1 4	0 = Active-lov	(<i>)</i>										
bit 4		Display Horizontal S	Synchronization	(HSYNC) POI	arity bit							
	1 = Active-hig 0 = Active-lov											
bit 3		Display Power-up/I	Power-Down Se	equencer Cont	rol port (GP)	NR) enable b	it					
		ort is enabled (pin		•	• •							
						- //						
	0 = GPWR p	ort is disabled (pin	can be used as		/O)							
bit 2		ort is disabled (pin splay Enable Port I			/0)							
bit 2		splay Enable Port I			/O)							

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REGISTER 22-5: G1CON3: DISPLAY CONTROL REGISTER 3 (CONTINUED)

bit 1	DPVSOE: Display Vertical Synchronization Port Enable bit
	1 = VSYNC port is enabled
	0 = VSYNC port is disabled
bit 0	DPHSOE: Display Horizontal Synchronization Port Enable bit
	1 = HSYNC port is enabled
	0 = HSYNC port is disabled

REGISTER 22-6: G1STAT: GFX STATUS REGISTER

R-0, HSC	U-0						
PUBUSY	—		_	—	—	—	—
bit 15							bit 8

bit

| R-0, HSC |
|----------|----------|----------|----------|----------|----------|----------|----------|
| IPUBUSY | RCCBUSY | CHRBUSY | VMRGN | HMRGN | CMDLV | CMDFUL | CMDMPT |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Setta	HSC = Hardware Settable/Clearable bit					
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'					
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown				

bit 15	PUBUSY: Processing Units are Busy Status bit
	This bit is logically equivalent to the ORed combination of IPUBUSY, RCCBUSY or CHRBUSY. 1 = At least one processing unit is busy 0 = None of the processing units are busy
bit 14-8	Unimplemented: Read as '0'
bit 7	IPUBUSY: Inflate Processing Unit Busy Status bit
	1 = IPU is busy0 = IPU is not busy
bit 6	RCCBUSY: Rectangle Copy Graphics Processing Unit Busy Status bit
	1 = RCCGPU is busy
	0 = RCCGPU is not busy
bit 5	CHRBUSY: Character Graphics Processing Unit Busy Status bit
	1 = CHRGPU is busy 0 = CHRGPU is not busy
bit 4	VMRGN: Vertical Blanking Status bit
	 1 = Display interface is in the vertical blanking period 0 = Display interface is not in the vertical blanking period
bit 3	HMRGN: Horizontal Blanking Status bit
	 1 = Display interface is in the horizontal blanking period 0 = Display interface is not in the horizontal blanking period
bit 2	CMDLV: Command Watermark Level Status bit
	The number of commands in the command FIFO changed from equal (=) to the command watermark value to less than (<) the Command Watermark value set in CMDWMK (G1CON1<12:8>) register bits. 1 = Command in FIFO is less than the set CMDWMK value 0 = Command in FIFO is equal to or greater than the set CMDWMK value
bit 1	CMDFUL: Command FIFO Full Status bit
	1 = Command FIFO is full 0 = Command FIFO is not full
bit 0	CMDMPT: Command FIFO Empty Status bit
	1 = Command FIFO is empty
	0 = Command FIFO is not empty

REGISTER 2	22-7: G1IE:	GFX INTERR		E REGISTER	र					
R/W-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0			
PUIE		—	—	—	—	—	—			
bit 15							bit 8			
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0			
IPUIE	RCCIE	CHRIE	VMRGNIE	HMRGNIE	CMDLVIE	CMDFULIE	CMDMPTIE			
bit 7							bit 0			
Legend:										
R = Readable	bit	W = Writable b	hit	II = Unimple	mented bit, re	ad as '0'				
-n = Value at I		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	nwn			
							10111			
bit 15	PUIE: Proces	sing Units Com	plete Interrupt	Enable bit						
	1 = Enables	the PU complet	te interrupt							
	0 = Disables	the PU comple	te interrupt							
bit 14-8	Unimplemen	ted: Read as ')'							
bit 7		•	it Complete Inte	errupt Enable	bit					
		the IPU comple								
		the IPU comple	•							
bit 6	RCCIE: Rectangle Copy Graphics Processing Unit Complete Interrupt bit 1 = Enables the RCCGPU complete interrupt									
			complete interru							
bit 5			Processing Uni	•	nt hit					
bit 5		the CHRGPU b	•	t busy interru	pron					
		the CHRGPU I								
bit 4			Interrupt Enab	le bit						
		•	nking period inte							
	0 = Disables	the vertical bla	nking period int	errupt						
bit 3	HMRGNIE: H	lorizontal Blank	ing Interrupt En	able bit						
			lanking period i							
			planking period	•						
bit 2	CMDLVIE: Command Watermark Interrupt Enable bit									
			vatermark interr							
h:+ 4			watermark inter	•						
bit 1) Full Interrupt E							
			FIFO full interrup							
bit 0			D Empty Interru	•						
			FIFO empty inte	•						
			FIFO empty inte							
				-						

R/W-0, HS	U-0	U-0	U-0	U-0	U-0	U-0	U-0		
PUIF	—	—	—	_	—	—	_		
bit 15							bit		
R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS	R/W-0, HS		
IPUIF ⁽¹⁾	RCCIF ⁽¹⁾	CHRIF ⁽¹⁾	VMRGNIF	HMRGNIF	CMDLVIF	CMDFULIF	CMDMPTIF		
bit 7	NOOI!	OF IIXII **	VIVILOINII	TIMICONI	CIVIDEVII		bit		
Legend:		HS = Hardwa	are Settable b	it					
R = Readal	ole bit	W = Writable	bit	U = Unimplem	ented bit, read	as '0'			
-n = Value a	at POR	'1' = Bit is se	t	'0' = Bit is clea	red	x = Bit is unkno	wn		
L:1 4 F									
bit 15		essing Units C	•						
				RCCIF and CHF and execution (r		t in software)			
			•	command execution (i		in soltware)			
bit 14-8		nted: Read as	• • •						
bit 7	-			Interrupt Flag b	it(1)				
				(must be cleare					
				mand execution	,				
bit 6	RCCIF: Rec	tangle Copy C	Graphics Proce	essing Unit Com	plete Interrupt F	-lag bit ⁽¹⁾			
		•		ecution (must be g command exec		ware)			
bit 5				Unit Complete I		(1)			
		-	-	ecution (must be					
				g command exec					
bit 4	VMRGNIF:	Vertical Blanki	ng Interrupt F	lag bit					
				anking period (m al blanking perio		in software)			
bit 3				•					
	 HMRGNIF: Horizontal Blanking Interrupt Flag bit 1 = Display interface is in the horizontal blanking period (must be cleared in software) 								
	0 = Display	interface is no	ot in the horizo	ontal blanking pe	riod				
bit 2	CMDLVIF: Command Watermark Interrupt Flag bit								
		and watermark and watermark		ed (must be clea	ared in software	9)			
bit 1		: Command FI	-						
	1 = Comma	and FIFO is ful	I (must be clea	ared in software)	I				
		and FIFO is no							
bit 0				errupt Flag bit	\				
	= 1 = 0.0 mm	and FIF() is en	nntv (must he	cleared in softwa	are)				

Note 1: The logic of each Processing Unit Status bit is the reverse of the PUIF. This provides flexibility on software code utilizing the processing units.

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
W1ADR15	W1ADR14	W1ADR13	W1ADR12	W1ADR11	W1ADR10	W1ADR9	W1ADR8
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
W1ADR7	W1ADR6	W1ADR5	W1ADR4	W1ADR3	W1ADR2	W1ADR1	W1ADR0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 W1ADR<15:0>: GPU Work Area 1 Start Address Low bits Work area address must point to an even byte address in memory.

REGISTER 22-10: G1W1ADRH: GPU WORK AREA 1 START ADDRESS REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	—	—	—	_	—	_	—
bit 15							bit 8

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| W1ADR23 | W1ADR22 | W1ADR21 | W1ADR20 | W1ADR19 | W1ADR18 | W1ADR17 | W1ADR16 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 W1ADR<23:16>: GPU Work Area 1 Start Address High bits

Work area address must point to an even byte address in memory.

REGISTER 22-11: G1W2ADRL: GPU WORK AREA 2 START ADDRESS REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
W2ADR15	W2ADR14	W2ADR13	W2ADR12	W2ADR11	W2ADR10	W2ADR9	W2ADR8
bit 15							bit 8

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| W2ADR7 | W2ADR6 | W2ADR5 | W2ADR4 | W2ADR3 | W2ADR2 | W2ADR1 | W2ADR0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0

-0 W2ADR<15:0>: GPU Work Area 2 Start Address Low bits

Work area address must point to an even byte address in memory.

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REGISTER 22-12: G1W2ADRH: GPU WORK AREA 2 START ADDRESS REGISTER HIGH

	U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
bit 15 bit i	—	—	_	_	—	—	—	_
	bit 15							bit 8

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| W2ADR23 | W2ADR22 | W2ADR21 | W2ADR20 | W2ADR19 | W2ADR18 | W2ADR17 | W2ADR16 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 Unimplemented: Read as '0'

bit 7-0 **W2ADR<23:16>:** GPU Work Area 2 Start Address High bits Work area address must point to an even byte address in memory.

REGISTER 22-13: G1PUW: GPU WORK AREA WIDTH REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	PUW10	PUW9	PUW8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| PUW7 | PUW6 | PUW5 | PUW4 | PUW3 | PUW2 | PUW1 | PUW0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

bit 10-0 **PUW<10:0>:** GPU Work Area Width bits (in pixels)

REGISTER 22-14: G1PUH: GPU WORK AREA HEIGHT REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
_	_	_	_	_	PUH10	PUH9	PUH8
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
PUH7	PUH6	PUH5	PUH4	PUH3	PUH2	PUH1	PUH0
bit 7							bit 0
Legend:							
R = Readable	e bit	W = Writable I	bit	U = Unimplem	nented bit, read	as '0'	
-n = Value at POR '1' = Bit is set			'0' = Bit is clea	ared	x = Bit is unk	nown	
bit 15-11	Unimplemer	ted: Read as '0)'				

bit 10-0 **PUH<10:0>:** GPU Work Area Height bits (in pixels)

REGISTER 22-15: G1DPADRL: DISPLAY BUFFER START ADDRESS REGISTER LOW

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DPADR15	DPADR14	DPADR13	DPADR12	DPADR11	DPADR10	DPADR9	DPADR8
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DPADR7	DPADR6	DPADR5	DPADR4	DPADR3	DPADR2	DPADR1	DPADR0
bit 7				<u>.</u>			bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **DPADR<15:0>:** Display Buffer Start Address Low bits Display buffer start address must point to an even byte address in memory.

REGISTER 22-16: G1DPADRH: DISPLAY BUFFER START ADDRESS REGISTER HIGH

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
_	_	—	_	—	—	_	—
bit 15							bit 8

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| DPADR23 | DPADR22 | DPADR21 | DPADR20 | DPADR19 | DPADR18 | DPADR17 | DPADR16 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **Unimplemented:** Read as '0'

bit 7-0 **DPADR<23:16>:** Display Buffer Start Address High bits

Display buffer start address must point to an even byte address in memory.

REGISTER 22-17: G1DPW: DISPLAY BUFFER WIDTH REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
_	—	—	—	—	DPW10	DPW9	DPW8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| DPW7 | DPW6 | DPW5 | DPW4 | DPW3 | DPW2 | DPW1 | DPW0 |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 **Unimplemented:** Read as '0'

bit 10-0 **DPW<10:0>:** Display Frame Width bits (in pixels)

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REGISTER 22-18: G1DPH: DISPLAY BUFFER HEIGHT REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	_	—	— DPH10		DPH9	DPH8
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
DPH7	DPH6	DPH5	DPH4	DPH3	DPH2	DPH1	DPH0
bit 7							bit 0
Legend:							
R = Readable bit W = Writable bit		oit	U = Unimplemented bit, read as '0'				
-n = Value at I	POR	'1' = Bit is set		'0' = Bit is cleared x = Bit is unknown			nown

bit 15-11 Unimplemented: Read as '0'

bit 10-0 **DPH<10:0>:** Display Frame Height bits (in pixels)

REGISTER 22-19: G1DPWT: DISPLAY TOTAL WIDTH REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
—	—	—	—	—	DPWT10	DPWT9	DPWT8
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| DPWT7 | DPWT6 | DPWT5 | DPWT4 | DPWT3 | DPWT2 | DPWT1 | DPWT0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-11 Unimplemented: Read as '0'

bit 10-0 **DPWT<10:0>:** Display Total Width bits (in pixels)

REGISTER 22-20: G1DPHT: DISPLAY TOTAL HEIGHT REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0	
—	—			_	DPHT10	DPHT9	DPHT8	
bit 15							bit 8	
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	
DPHT7	DPHT6	DPHT5	DPHT4	DPHT3	DPHT2	DPHT1	DPHT0	
bit 7				•	bit (
Legend:								
R = Readable bit W = Wr		W = Writable	bit	U = Unimplemented bit, read as '0'				
-n = Value at POR		'1' = Bit is set		'0' = Bit is cleared		x = Bit is unknown		

bit 15-11 Unimplemented: Read as '0'

bit 10-0 **DPHT<10:0>:** Display Total Height bits (in pixels)

REGISTER 22-21: G1ACTDA: ACTIVE DISPLAY AREA REGISTER

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| ACTLINE7 | ACTLINE6 | ACTLINE5 | ACTLINE4 | ACTLINE3 | ACTLINE2 | ACTLINE1 | ACTLINE0 |
| bit 15 | | | | | | | bit 8 |

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0		
ACTPIX7	ACTPIX6	ACTPIX5	ACTPIX4	ACTPIX3	ACTPIX2	ACTPIX1	ACTPIX0		
bit 7 bit 0									

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

 bit 15-8 ACTLINE<7:0>: Number of Lines Before the First Active (Displayed) Line bits Typically, ACTLINEx = VENSTx (G1DBLCON<15:8>). This register is added for versatility in the timing of the active lines. For TFT mode, DPMODE bits (G1CON2<2:0>) = 001; the minimum value is 2. For STN mode, DPMODE bits (G1CON2<2:0>) = 010,011,100; the minimum value is 0.
 bit 7-0 ACTPIX<7:0>: Number of Pixels Before the First Active (Displayed) Pixel bits (in DISPCLKs) Typically, ACTPIXx = HENSTx (G1DBLCON<7:0>). This register is added for versatility in the timing of the active pixels. Note that the programmed value

This register is added for versatility in the timing of the active pixels. Note that the programmed value is computed in DISPCLK cycles. This value is dependent on the DPGWDTH bit (G1CON2<15:14>). Refer to the "*PIC24F Family Reference Manual*", **Section 43. "Graphics Controller Module (GFX)"** for details.

REGISTER 22-22: G1HSYNC: HORIZONTAL SYNCHRONIZATION CONTROL REGISTER

REGISTER 2	2-22. 01113	TNC. HUKIZ	UNTAL STIN	CHRUNIZAI			n
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
HSLEN7	HSLEN6	HSLEN5	HSLEN4	HSLEN3	HSLEN2	HSLEN1	HSLEN0
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
HSST7	HSST6	HSST5	HSST4	HSST3	HSST2	HSST1	HSST0
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 HSLEN<7:0>: HSYNC Pulse-Width Configuration bits (in DISPCLKs)

DPHSOE bit (G1CON3<0>) must be set for the HSYNC signal to toggle; minimum value is 1.

bit 7-0 **HSST<7:0>:** HSYNC Start Delay Configuration bits (in DISPCLKs) This is the number of DISPCLK cycles from the start of horizontal blanking to the start of HSYNC active.

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REGISTER 22-23: G1VSYNC: VERTICAL SYNCHRONIZATION CONTROL REGISTER

VSLEN7 VSLEN6 VSLEN5 VSLEN4 VSLEN3 VSLEN2 VSLEN1 VSLEN0 bit 15 bit	R/W-0							
bit 15 bit	VSLEN7	VSLEN6	VSLEN5	VSLEN4	VSLEN3	VSLEN2	VSLEN1	VSLEN0
	bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| VSST7 | VSST6 | VSST5 | VSST4 | VSST3 | VSST2 | VSST1 | VSST0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit, rea	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

 bit 15-8
 VSLEN<7:0>: VSYNC Pulse-Width Configuration bits (in lines) The DPVSOE bit (G1CON3<1>) must be set for the VSYNC signal to toggle; minimum value is 1.

 bit 7-0
 VSST<7:0>: VSYNC Start Delay Configuration bits (in lines) This is the number of lines from the start of vertical blanking to the start of VSYNC active.

REGISTER 22-24: G1DBLCON: DISPLAY BLANKING CONTROL REGISTER

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| VENST7 | VENST6 | VENST5 | VENST4 | VENST3 | VENST2 | VENST1 | VENST0 |
| bit 15 | | • | | | | | bit 8 |
| | | | | | | | |
| R/W-0 |

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| HENST7 | HENST6 | HENST5 | HENST4 | HENST3 | HENST2 | HENST1 | HENST0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8 **VENST<7:0>:** Vertical Blanking Start to First Displayed Line Configuration bits (in lines) This is the number of lines from the start of vertical blanking to the first displayed line of a frame.

bit 7-0 **HENST<7:0>:** Horizontal Blanking Start to First Displayed Pixel Configuration bits (in DISPCLKs) This is the number of GCLK cycles from the start of horizontal blanking to the first displayed pixel of each displayed line.

REGISTER 22-25: G1CLUT: COLOR LOOK-UP TABLE CONTROL REGISTER

R/W-0	R-0, HSC	U-0	U-0	U-0	U-0	R/W-0	R/W-0	
CLUTEN	CLUTBUSY	_	—	—	—	CLUTTRD	CLUTRWEN	
bit 15								

| R/W-0 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| CLUTADR7 | CLUTADR6 | CLUTADR5 | CLUTADR4 | CLUTADR3 | CLUTADR2 | CLUTADR1 | CLUTADR0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable/Clearable bit					
R = Readable bit	W = Writable bit	U = Unimplemented bit, re	ad as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	CLUTEN: Color Look-up Table Enable Control bit 1 = Color look-up table is enabled 0 = Color look-up table is disabled
bit 14	CLUTBUSY: Color Look-up Table Busy Status bit 1 = A CLUT entry read/write access is being executed
bit 13-10	 0 = No CLUT entry read/write access is being executed Unimplemented: Read as '0'
bit 9	CLUTTRD: Color Look-up Table Read Trigger bit
	 Enabling this bit will trigger a read to the CLUT location determined by the CLUTADR bits (G1CLUT<7:0>) with CLUTRWEN enabled. 1 = CLUT read trigger is enabled (must be cleared in software after reading data in the G1CLUTRD register)
1.11.0	0 = CLUT read trigger is disabled
bit 8	CLUTRWEN: Color Look-up Table Read/Write Enable Control bit This bit must be set when reading or modifying entries on the CLUT and it must also be cleared when CLUT is used by the display controller.
	 1 = Color look-up table read/write enabled; display controller cannot access the CLUT 0 = Color look-up table read/write disabled; display controller can access the CLUT
bit 7-0	CLUTADR<7:0>: Color Look-up Table Memory Address bits

REGISTER 22-26: G1CLUTWR: COLOR LOOK-UP TABLE (CLUT) MEMORY WRITE DATA REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CLUTWR15	CLUTWR14	CLUTWR13	CLUTWR12	CLUTWR11	CLUTWR10	CLUTWR9	CLUTWR8
bit 15							bit 8

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| CLUTWR7 | CLUTWR6 | CLUTWR5 | CLUTWR4 | CLUTWR3 | CLUTWR2 | CLUTWR1 | CLUTWR0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit,	read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 CLUTWR<15:0>: Color Look-up Table Memory Write Data bits

A write to this register triggers a write to the CLUT memory at the address pointed to by the CLUTADR bits. A word write or a high byte write to this register triggers a write to the CLUT memory at the address pointed to by CLUTADR. Low byte write to this register will only update the G1CLUTWR<7:0> and no write to CLUT memory will be triggered. During power-up and power-down of the display, the most recent data written to this register will be used to control the timing of the GPWR signal. Refer to the *"PIC24F Family Reference Manual"*, Section 43. "Graphics Controller Module (GFX)" for details on writing entries to the CLUT.

REGISTER 22-27: G1CLUTRD: COLOR LOOK-UP TABLE (CLUT) MEMORY READ DATA REGISTER

				•	•		
R-0, HSC							
CLUTRD15	CLUTRD14	CLUTRD13	CLUTRD12	CLUTRD11	CLUTRD10	CLUTRD9	CLUTRD8
bit 15							bit 8
R-0, HSC							
CLUTRD7	CLUTRD6	CLUTRD5	CLUTRD4	CLUTRD3	CLUTRD2	CLUTRD1	CLUTRD0

bit 0

Legend:	HSC = Hardware Settable	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown				

bit 15-0 CLUTRD<15:0>: Color Look-up Table Memory Read Data bits

This register contains the most recent read from the CLUT memory pointed to by the CLUTADR bits (G1CLUT<7:0>). Reading of the CLUT memory is triggered when the CLUTTRD bit (G1CLUT<9>) goes from '0' to '1'. Refer to the "*PIC24F Family Reference Manual*", **Section 43.** "Graphics Controller Module (GFX)" for details on reading entries from the CLUT.

bit 7

REGISTER 22-28: G1MRGN: INTERRUPT ADVANCE REGISTER

_								
	R/W-0							
Γ	VBAMGN7	VBAMGN6	VBAMGN5	VBAMGN4	VBAMGN3	VBAMGN2	VBAMGN1	VBAMGN0
	bit 15							bit 8

| R/W-0 |
|---------|---------|---------|---------|---------|---------|---------|---------|
| HBAMGN7 | HBAMGN6 | HBAMGN5 | HBAMGN4 | HBAMGN3 | HBAMGN2 | HBAMGN1 | HBAMGN0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-8	VBAMGN<7:0>: Vertical Blanking Advance bits
	The number of DISPCLK cycles in advance that the vertical blanking interrupt will assert ahead of the
	actual start of the vertical blanking.
bit 7-0	HBAMGN<7:0>: Horizontal Blanking Advance bits

The number of DISPCLK cycles in advance that the horizontal blanking interrupt will assert ahead of the actual start of the horizontal blanking.

REGISTER 22-29: G1CHRX: CHARACTER-X COORDINATE PRINT POSITION REGISTER

U-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
—	—	—	—	—	CURPOSX10	CURPOSX9	CURPOSX8
bit 15							bit 8

| R-0, HSC |
|----------|----------|----------|----------|----------|----------|----------|----------|
| CURPOSX7 | CURPOSX6 | CURPOSX5 | CURPOSX4 | CURPOSX3 | CURPOSX2 | CURPOSX1 | CURPOSX0 |
| bit 7 | | | | | | | bit 0 |

Legend:	HSC = Hardware Settable	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	0' = Bit is cleared x = Bit is unknown				

bit 15-11 Unimplemented: Read as '0'

bit 10-0 CURPOSX<10:0>: Current Character Position in the X-Coordinate bits

REGISTER 22-30: G1CHRY: CHARACTER Y-COORDINATE PRINT POSITION REGISTER

U-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
—	—	—	—	—	CURPOSY10	CURPOSY9	CURPOSY8
bit 15							bit 8

| R-0, HSC |
|----------|----------|----------|----------|----------|----------|----------|----------|
| CURPOSY7 | CURPOSY6 | CURPOSY5 | CURPOSY4 | CURPOSY3 | CURPOSY2 | CURPOSY1 | CURPOSY0 |
| bit 7 | | | | • | | • | bit 0 |

Legend:	HSC = Hardware Settable/C	HSC = Hardware Settable/Clearable bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared x = Bit is unknown			

bit 15-11 Unimplemented: Read as '0'

bit 10-0 CURPOSY<10:0>: Current Character Position in the Y-Coordinate bits

REGISTER 22-31: G1IPU: INFLATE PROCESSOR STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC	R-0, HSC
—	—	HUFFERR ⁽²⁾	BLCKERR ⁽²⁾	LENERR ⁽²⁾	WRAPERR ⁽²⁾	IPUDONE ^(1,2)	BFINAL ^(1,2)
bit 7							bit 0

Legend:	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'			
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown		

bit 15-6	Unimplemented: Read as '0'
bit 5	HUFFERR: Undefined Huffmann Code Encountered Status bit ⁽²⁾
	1 = Undefined code is encountered
	0 = No undefined code is encountered
bit 4	BLCKERR: Undefined Block Code Encountered Status bit ⁽²⁾
	1 = Undefined block is encountered
	0 = No undefined block is encountered
bit 3	LENERR: Mismatch in Expected Block Length Status bit ⁽²⁾
	1 = Mismatch in block length is detected
	0 = No mismatch in block length is detected
bit 2	WRAPERR: Wrap-Around Error Status bit ⁽²⁾
	1 = Wrap-around error is encountered
	0 = No wrap-around error is encountered
bit 1	IPUDONE: IPU Decompression Status bit ^(1,2)
	1 = Decompression is done
	0 = Decompression is not yet done

- bit 0 BFINAL: Final Block Encountered Status bit^(1,2)
 - 1 = Final block is encountered
 - 0 = Final block is not encountered
- Note 1: IPUDONE and BFINAL status bits are set after successful decompression.
 - 2: All IPU status bits are available after each decompression. All status bits are automatically cleared every time a decompression command (IPU_DECOMPRESS) is issued.

REGISTER 22-32: G1DBEN: DATA I/O PAD ENABLE REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
GDBEN15	GDBEN14	GDBEN13	GDBEN12	GDBEN11	GDBEN10	GDBEN9	GDBEN8
bit 15							bit 8

| R/W-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| GDBEN7 | GDBEN6 | GDBEN5 | GDBEN4 | GDBEN3 | GDBEN2 | GDBEN1 | GDBEN0 |
| bit 7 | | | | | | | bit 0 |

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bi	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0 **GDBEN<15:0>:** Display Data Pads Output Enable bits

1 = Corresponding display data (GD<x>) pin is enabled

0 = Corresponding display data (GD<x>) pin is disabled

GDBEN<15:0> can be used to disable or enable specific data signals while the DPPINOE bit (G1CON3<9>) is set.

DPPINOE	GDBENx (where x = 0 to 15)	
1	1	Display data signal (GD) associated with GDBENx is enabled.
1	0	Display data signal (GD) associated with GDBENx is disabled.
0	х	Display data signal (GD) associated with GDBENx is disabled.

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22.2 Display Resolution and Memory Requirements

The PIC24FJ256DA210 family of devices has two variants in terms of on-board RAM (24-Kbyte and 96-Kbyte variants). The 24-Kbyte variant supports monochrome displays while the 96-Kbyte variant supports Quarter VGA (QVGA) color displays, up to 256 colors. Support of higher resolution displays with higher color depth requirements are available by extending the data space through external memory. Table 22-1 provides the summary of image buffer memory requirements of different display resolutions and color depth requirements.

22.3 Display Clock (GCLK) Source

Frequency of the Graphics Controller Display Clock (GCLK) signal is determined by programming the GCLKDIV bits (CLKDIV2<15:9>). For more information, refer to the "*PIC24F Family Reference Manual*", **Section 6. "Oscillator"** (DS39700).

22.4 Display Buffer and Work Areas Memory Locations

The PIC24FJ256DA210 family of devices has variants with two on-board RAM sizes. These are the 24-Kbyte and 96-Kbyte variants. These two RAM variants are further divided in terms of pin counts. The 100-pin count device will have the EPMP module available for extending RAM for applications. The 64-pin count device will not have the EPMP modules. Extending the RAM size is necessary for applications that require larger display buffers and work areas. It is recommended that the display buffers and work areas are not mapped into an area that overlaps the internal RAM and the external RAM. The external RAM can be interfaced using the EPMP module. For details, refer to the "PIC24F Family Reference Manual", Section 42. "Enhanced Parallel Master Port (EPMP)" (DS39730).

Display Resolution	Display Buffer Memory Requirements (Bytes)						
Display Resolution	1 Врр	2 Врр	4 Bpp	8 Врр	16 Bpp		
480x272 (WQVGA)	16320	32640	65280	130560	261120		
320x240 (QVGA)	9600	19200	38400	76800	153600		
240x160 (HQVGA)	4800	9600	19200	38400	76800		
160x160	3200	6400	12800	25600	51200		
160x120 (QQVGA)	2400	4800	9600	19200	38400		
128x64	1024	2048	4096	8192	16384		

TABLE 22-1: BUFFER MEMORY REQUIREMENTS vs. DISPLAY CONFIGURATION

Legend:

Less than 24-Kbyte RAM variants (PIC24FJXXXDA106)

Less than 96-Kbyte RAM variants (PIC24FJXXXDA2XX)

External Memory with 96 Kbytes/24 Kbytes of RAM variants (PIC24FJXXXDAX10)

23.0 10-BIT HIGH-SPEED A/D CONVERTER

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 17. "10-Bit A/D Converter" (DS39705). The information in this data sheet supersedes the information in the FRM.

The 10-bit A/D Converter has the following key features:

- · Successive Approximation (SAR) conversion
- · Conversion speeds of up to 500 ksps
- 24 analog input pins (PIC24FJXXXDAX10 devices) and 16 analog input pins (PIC24FJXXXDAX06 devices)
- External voltage reference input pins
- Internal band gap reference inputs
- · Automatic Channel Scan mode
- · Selectable conversion trigger source
- 32-word conversion result buffer
- · Selectable Buffer Fill modes
- · Four result alignment options
- · Operation during CPU Sleep and Idle modes

On all PIC24FJ256DA210 family devices, the 10-bit A/D Converter has 24 analog input pins, designated AN0 through AN23. In addition, there are two analog input pins for external voltage reference connections (VREF+ and VREF-). These voltage reference inputs may be shared with other analog input pins.

A block diagram of the A/D Converter is shown in Figure 23-1.

To perform an A/D conversion:

- 1. Configure the A/D module:
 - Configure the port pins as analog inputs and/or select band gap reference inputs (ANCFG registers).
 - b) Select the voltage reference source to match the expected range on analog inputs (AD1CON2<15:13>).
 - c) Select the analog conversion clock to match the desired data rate with the processor clock (AD1CON3<7:0>).
 - d) Select the appropriate sample/conversion sequence (AD1CON1<7:5> and AD1CON3<12:8>).
 - e) Select how the conversion results are presented in the buffer (AD1CON1<9:8>).
 - f) Select the interrupt rate (AD1CON2<6:2>).
 - g) Turn on the A/D module (AD1CON1<15>).
- 2. Configure the A/D interrupt (if required):
 - a) Clear the AD1IF bit.
 - b) Select the A/D interrupt priority.

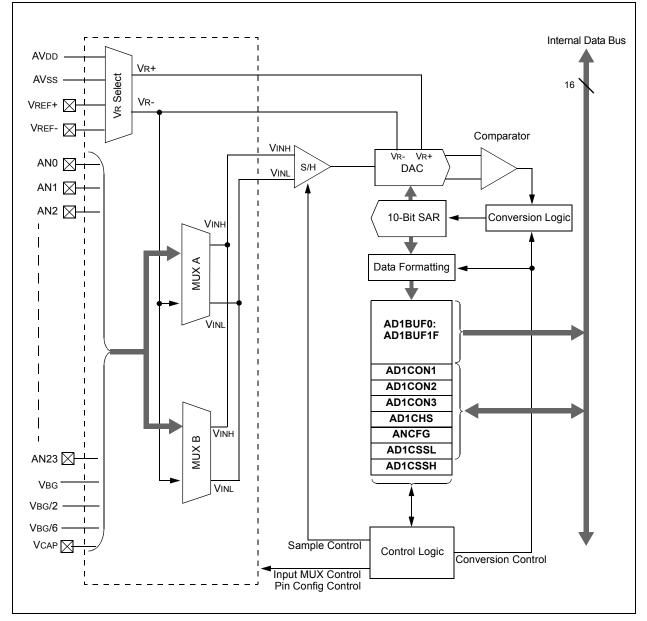


FIGURE 23-1: 10-BIT HIGH-SPEED A/D CONVERTER BLOCK DIAGRAM

REGISTER 23-1: AD1CON1: A/D CONTROL REGISTER 1 R/W-0 U-0 R/W-0 U-0 U-0 U-0 R/W-0 R/W-0 ADON⁽¹⁾ ADSIDL FORM1 FORM0 bit 15 bit 8 R/W-0 R/W-0 R/W-0 U-0 U-0 R/W-0 R-0, HSC R-0, HSC SSRC2 SSRC1 SSRC0 ASAM SAMP DONE _ bit 7 bit 0 Legend: HSC = Hardware Settable/Clearable bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknown ADON: A/D Operating Mode bit⁽¹⁾ bit 15 1 = A/D Converter module is operating 0 = A/D Converter is off bit 14 Unimplemented: Read as '0' bit 13 ADSIDL: Stop in Idle Mode bit 1 = Discontinue module operation when device enters Idle mode 0 = Continue module operation in Idle mode bit 12-10 Unimplemented: Read as '0' bit 9-8 FORM<1:0>: Data Output Format bits 11 = Signed fractional (sddd dddd dd00 0000) 10 = Fractional (dddd dddd dd00 0000) 01 = Signed integer (ssss sssd dddd dddd) 00 = Integer (0000 00dd dddd dddd) bit 7-5 SSRC<2:0>: Conversion Trigger Source Select bits 111 = Internal counter ends sampling and starts conversion (auto-convert) 110 = CTMU event ends sampling and starts conversion 101 = Reserved 100 = Timer5 compare ends sampling and starts conversion 011 = Reserved 010 = Timer3 compare ends sampling and starts conversion 001 = Active transition on INT0 pin ends sampling and starts conversion 000 = Clearing SAMP bit ends sampling and starts conversion bit 4-3 Unimplemented: Read as '0' bit 2 ASAM: A/D Sample Auto-Start bit 1 = Sampling begins immediately after the last conversion completes. The SAMP bit is auto-set. 0 = Sampling begins when the SAMP bit is set bit 1 SAMP: A/D Sample Enable bit 1 = A/D sample/hold amplifier is sampling input 0 = A/D sample/hold amplifier is holding bit 0 DONE: A/D Conversion Status bit 1 = A/D conversion is done 0 = A/D conversion is NOT done

Note 1: The values of the ADC1BUFx registers will not retain their values once the ADON bit is cleared. Read out the conversion values from the buffer before disabling the module.

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REGISTER 23-2: AD1CON2: A/D CONTROL REGISTER 2

R/W-0	R/W-0	R/W-0	r-0	U-0	R/W-0	U-0	U-0
VCFG2	VCFG1	VCFG0	r	—	CSCNA		—
bit 15							bit 8

R-0, HSC	R/W-0						
BUFS	SMPI4	SMPI3	SMPI2	SMPI1	SMPI0	BUFM	ALTS
bit 7							bit 0

Legend:	r = Reserved bit	HSC = Hardware Setta	ble/Clearable bit
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-13 VCFG<2:0>: Voltage Reference Configuration bits

VCFG<2:0>	VR+	VR-
000	AVDD	AVss
001	External VREF+ pin	AVss
010	AVDD	External VREF- pin
011	External VREF+ pin	External VREF- pin
1xx	AVDD	AVss

- bit 12 Reserved: Maintain as '0'
- bit 11 Unimplemented: Read as '0'
- bit 10 CSCNA: Scan Input Selections for the CH0+ S/H Input for MUX A Input Multiplexer Setting bit 1 = Scan inputs 0 = Do not scan inputs
- bit 9-8 Unimplemented: Read as '0'
- bit 7 **BUFS:** Buffer Fill Status bit (valid only when BUFM = 1)
 - 1 = A/D is currently filling buffer, 10-1F, user should access data in 00-0F
 - 0 = A/D is currently filling buffer, 00-0F, user should access data in 10-1F
- bit 6-2 SMPI<4:0>: Sample/Convert Sequences Per Interrupt Selection bits
 - 11111 = Interrupts at the completion of conversion for each 32nd sample/convert sequence
 - 11110 = Interrupts at the completion of conversion for each 31st sample/convert sequence
 - .
 - 00001 = Interrupts at the completion of conversion for each 2nd sample/convert sequence
 - 00000 = Interrupts at the completion of conversion for each sample/convert sequence

```
bit 1 BUFM: Buffer Mode Select bit
```

- 1 = Buffer is configured as two 16-word buffers (ADC1BUFn<31:16> and ADC1BUFn<15:0>)
- 0 = Buffer is configured as one 32-word buffer (ADC1BUFn<31:0>)
- bit 0 ALTS: Alternate Input Sample Mode Select bit
 - 1 = Uses MUX A input multiplexer settings for the first sample, then alternates between MUX B and MUX A input multiplexer settings for all subsequent samples
 - 0 = Always uses the MUX A input multiplexer settings

REGISTER 23-3: AD1CON3: A/D CONTROL REGISTER 3

R/W-0	r-0	r-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADRC	r	r	SAMC4	SAMC3	SAMC2	SAMC1	SAMC0
bit 15							bit 8

| R/W-0 |
|-------|-------|-------|-------|-------|-------|-------|-------|
| ADCS7 | ADCS6 | ADCS5 | ADCS4 | ADCS3 | ADCS2 | ADCS1 | ADCS0 |
| bit 7 | | | | | | | bit 0 |

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	d as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15	ADRC: A/D Conversion Clock Source bit
	1 = A/D internal RC clock
	0 = Clock is derived from the system clock
bit 14-13	Reserved: Maintain as '0'
bit 12-8	SAMC<4:0>: Auto-Sample Time bits
	11111 = 31 T AD
	00001 = 1 TAD
	00000 = 0 TAD (not recommended)
bit 7-0	ADCS<7:0>: A/D Conversion Clock Select bits
	11111111 = 256 * Tcy
	00000001 = 2 * TCY
	00000000 = Tcy

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REGISTER	23-4: AD1C	HS: A/D INF	PUT SELECT	REGISTER			
R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NB	—	—	CH0SB4 ⁽¹⁾	CH0SB3 ⁽¹⁾	CH0SB2 ⁽¹⁾	CH0SB1 ⁽¹⁾	CH0SB0 ⁽¹⁾
bit 15							bit 8
R/W-0	U-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CH0NA	—	—	CH0SA4 ⁽¹⁾	CH0SA3 ⁽¹⁾	CH0SA2 ⁽¹⁾	CH0SA1 ⁽¹⁾	CH0SA0 ⁽¹⁾
bit 7							bit (
Legend:							
R = Readabl	le bit	W = Writable	bit	U = Unimplem	nented bit, read	d as '0'	
-n = Value at		'1' = Bit is set	t	·0' = Bit is clea		x = Bit is unkr	nown
bit 15 bit 14-13	CH0NB: Char 1 = Channel (0 = Channel (Unimplement	0 negative inp 0 negative inp	ut is AN1 ut is VR-	or MUX B Multi	plexer Setting	bit	
bit 12-8	-			lect for MUX B ⁽	1)		
	11010 = Cha i 11001 = Chai 11000 = Cha i	nnel 0 positive nnel 0 positive nnel 0 positive nnel 0 positive nnel 0 positive	input is the con input is the base input is the base input is AN23 ⁽² input is AN23	nd gap divided- re voltage (VCA nd gap referenc nd gap divided- 2)	P) ce (VBG)		
bit 7	CH0NA: Char 1 = Channel (0 = Channel (0 negative inp	ut is AN1	or MUX A Multi	plexer Setting	bit	
bit 6-5	Unimplement	ted: Read as '	0'				
bit 4-0	CH0SA<4:0>	: Channel 0 Po	ositive Input Se	lect for MUX ⁽¹⁾			
	11011 = Chai 11010 = Chai 11001 = Chai 11000 = Chai	Channel used; nnel 0 positive nnel 0 positive nnel 0 positive nnel 0 positive	all inputs are fle input is the base input is the con input is the base	oating; used for nd gap divided- re voltage (VCA nd gap referend nd gap divided- 2)	by-six referend P) ce (VBG)	. ,	
	00001 = Chai 00000 = Chai	•	•				
Note 1: C	combinations not	shown here (2	11100 to 1111	0) are unimpler	nented; do not	use.	

REGISTER 23-4: AD1CHS: A/D INPUT SELECT REGISTER

- **Note 1:** Combinations not shown here (11100 to 11110) are unimplemented; do not use.
 - 2: Channel 0 positive inputs, AN16 through AN23, are not available on 64-pin devices (PIC24FJXXXDAX06).

REGISTER 23-5: ANCFG: A/D BAND GAP REFERENCE CONFIGURATION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—						—
bit 15							bit 8
U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0
	—	—	—	—	VBG6EN	VBG2EN	VBGEN
bit 7							bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	t, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-3	Unimplemented: Read as '0'
bit 2	VBG6EN: A/D Input VBG/6 Enable bit
	 1 = Band gap voltage divided-by-six reference (VBG/6) is enabled 0 = Band gap divided-by-six reference (VBG/6) is disabled
bit 1	VBG2EN: A/D Input VBG/2 Enable bit
	 1 = Band gap voltage divided-by-two reference (VBG/2) is enabled 0 = Band gap divided-by-two reference (VBG/2) is disabled
bit 0	VBGEN: A/D Input VBG Enable bit
	 Band gap voltage reference (VBG) is enabled Band gap reference (VBG) is disabled

REGISTER 23-6: AD1CSSL: A/D INPUT SCAN SELECT REGISTER (LOW)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL15	CSSL14	CSSL13	CSSL12	CSSL11	CSSL10	CSSL9	CSSL8
bit 15	•				•		bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CSSL7	CSSL6	CSSL5	CSSL4	CSSL3	CSSL2	CSSL1	CSSL0
bit 7	•		•		•		bit 0

Legend:			
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 15-0

- CSSL<15:0>: A/D Input Pin Scan Selection bits
- 1 = Corresponding analog channel is selected for input scan
- 0 = Analog channel is omitted from input scan

REGISTER 23-7: AD1CSSH: A/D INPUT SCAN SELECT REGISTER (HIGH)

R/W-0 CSSL21 ⁽¹⁾ W = Writable '1' = Bit is set		CSSL27 R/W-0 CSSL19 ⁽¹⁾ U = Unimplem '0' = Bit is clea	CSSL26 R/W-0 CSSL18 ⁽¹⁾	CSSL25 R/W-0 CSSL17 ⁽¹⁾	CSSL24 bit 8 R/W-0 CSSL16 ⁽¹⁾ bit 0
W = Writable '1' = Bit is set	CSSL20 ⁽¹⁾	U = Unimplem	CSSL18 ⁽¹⁾	CSSL17 ⁽¹⁾	R/W-0 CSSL16 ⁽¹⁾
W = Writable '1' = Bit is set	CSSL20 ⁽¹⁾	U = Unimplem	CSSL18 ⁽¹⁾	CSSL17 ⁽¹⁾	CSSL16 ⁽¹⁾
W = Writable '1' = Bit is set	CSSL20 ⁽¹⁾	U = Unimplem	CSSL18 ⁽¹⁾	CSSL17 ⁽¹⁾	CSSL16 ⁽¹⁾
W = Writable '1' = Bit is set	bit	U = Unimplem	nented bit, read	1	
'1' = Bit is set				d as '0'	bit
'1' = Bit is set				d as '0'	
'1' = Bit is set				d as '0'	
'1' = Bit is set				d as '0'	
		'0' = Bit is clea	a na al		
			ared	x = Bit is unkn	iown
ap divided-by-six channel is omitte D Input Band Ga	ed from input s ap Scan Select	ion bit	·		
core voltage (Vo channel is omitte D Input Half Ban ap reference (VB	ed from input s id Gap Scan S	can election bit			
channel is omitte					
D Input Band Ga ap divided-by-two channel is omitte	o reference (Vi	BG/2) is selected	d for input scar	n	
	Pin Scan Sele hannel selecte	ection bits ⁽¹⁾ ed for input scar	1		
(channel is omitte 5>: Analog Input onding analog c	channel is omitted from input s 5>: Analog Input Pin Scan Sele onding analog channel selecte	channel is omitted from input scan 5>: Analog Input Pin Scan Selection bits ⁽¹⁾	channel is omitted from input scan 5>: Analog Input Pin Scan Selection bits ⁽¹⁾ onding analog channel selected for input scan channel is omitted from input scan	channel is omitted from input scan 5>: Analog Input Pin Scan Selection bits ⁽¹⁾ onding analog channel selected for input scan

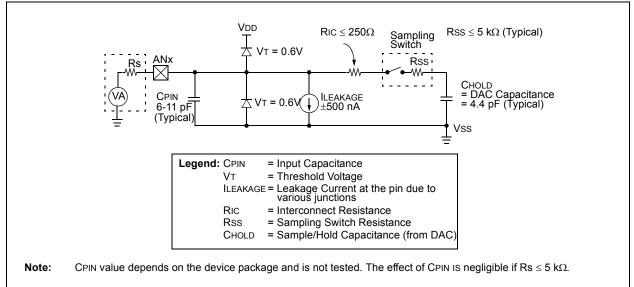
EQUATION 23-1: A/D CONVERSION CLOCK PERIOD⁽¹⁾

$$ADCS = \frac{TAD}{TCY} - 1$$

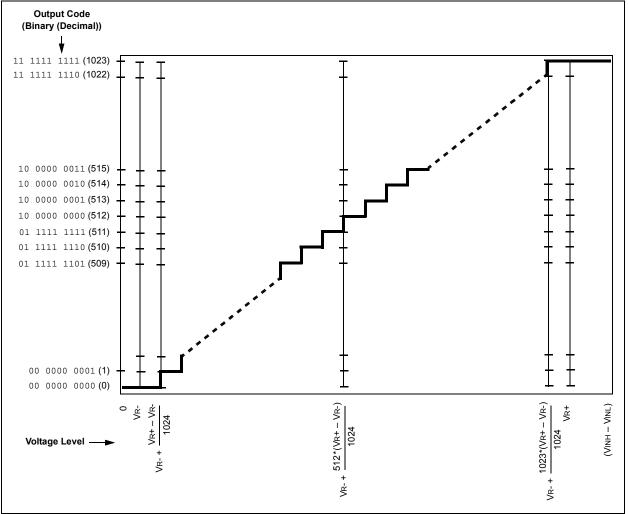
 $TAD = TCY \bullet (ADCS = 1)$

Note 1: Based on TCY = 2 * TOSC; Doze mode and PLL are disabled.









NOTES:

24.0 TRIPLE COMPARATOR MODULE

Note:	This data sheet summarizes the features
	of this group of PIC24F devices. It is not
	intended to be a comprehensive reference
	source. For more information, refer to the
	associated "PIC24F Family Reference
	Manual".

The triple comparator module provides three dual input comparators. The inputs to the comparator can be configured to use any one of five external analog inputs (CxINA, CxINB, CxINC, CxIND and VREF+) and a voltage reference input from one of the internal band gap references or the comparator voltage reference generator (VBG, VBG/2, VBG/6 and CVREF). The comparator outputs may be directly connected to the CxOUT pins. When the respective COE equals '1', the I/O pad logic makes the unsynchronized output of the comparator available on the pin.

A simplified block diagram of the module in shown in Figure 24-1. Diagrams of the possible individual comparator configurations are shown in Figure 24-2.

Each comparator has its own control register, CMxCON (Register 24-1), for enabling and configuring its operation. The output and event status of all three comparators is provided in the CMSTAT register (Register 24-2).

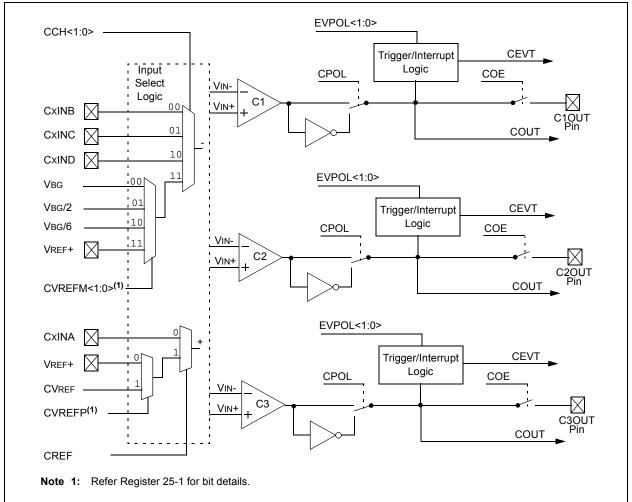
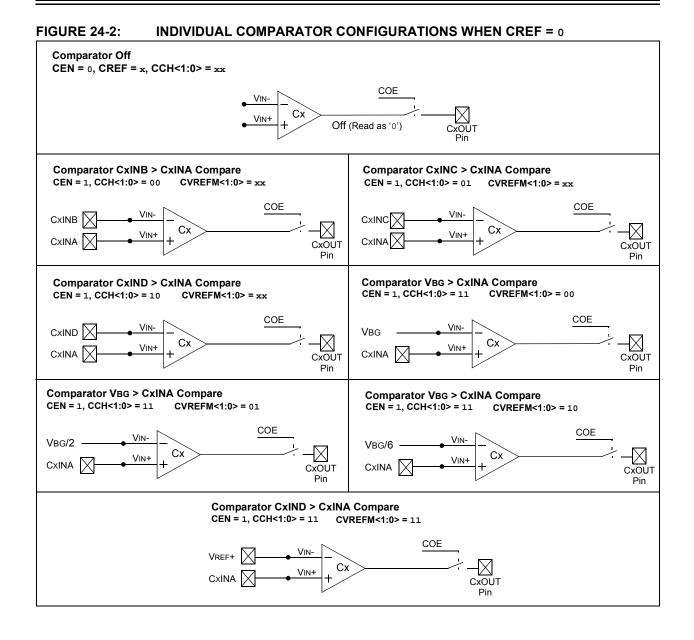


FIGURE 24-1: TRIPLE COMPARATOR MODULE BLOCK DIAGRAM



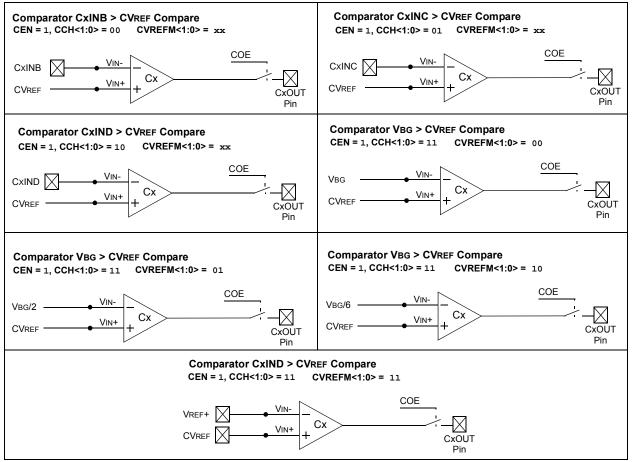
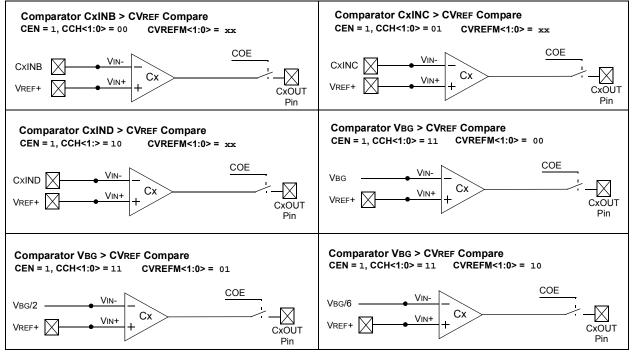


FIGURE 24-3: INDIVIDUAL COMPARATOR CONFIGURATIONS WHEN CREF = 1 AND CVREFP = 0





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REGISTER 24-1: CMxCON: COMPARATOR x CONTROL REGISTERS (COMPARATORS 1 THROUGH 3)

		,									
R/W-0	R/W-0	R/W-0	U-0	U-0	U-0	R/W-0, HS	R-0, HSC				
CEN	COE	CPOL	_	—	—	CEVT	COUT				
bit 15							bit 8				
R/W-0	R/W-0	U-0	R/W-0	U-0	U-0	R/W-0	R/W-0				
EVPOL1	EVPOL0	—	CREF	—	—	CCH1	CCH0				
bit 7	·						bit 0				
Legend:		HS = Hardware	Settable bit	HSC = Hardw	vare Settable/0	Clearable bit					
R = Readable	e bit	W = Writable b	it	U = Unimpler	nented bit, rea	ad as '0'					
-n = Value at	POR	'1' = Bit is set		'0' = Bit is cle	ared	x = Bit is unkr	iown				
bit 15	CEN: Compa	rator Enable bit									
		ator is enabled									
	0 = Compara	ator is disabled									
bit 14	COE: Compa	rator Output Ena	able bit								
		tor output is pre		OUT pin							
		tor output is inte									
bit 13		arator Output Po	,	t							
		ator output is inve ator output is not									
bit 12-10		ted: Read as '0									
bit 9	-										
Dit 9	CEVT: Comparator Event bit 1 = Comparator event that is defined by EVPOL<1:0> has occurred; subsequent triggers and interrupts										
	•	led until the bit i	•		occurred, subs	equent inggers	and interrupts				
	0 = Compara	tor event has no	t occurred								
bit 8	COUT: Comp	arator Output bi	t								
	When CPOL										
	1 = VIN + > VI										
	0 = VIN + < VI										
	$\frac{\text{When CPOL}}{1 = \text{VIN} + < \text{VI}}$										
	0 = VIN + > VI	IN-									
bit 7-6	EVPOL<1:0>	: Trigger/Event/l	nterrupt Polarit	y Select bits							
	11 = Trigger/	event/interrupt is	s generated on	any change of	the comparate	or output (while	CEVT = 0)				
		event/interrupt is		transition of the	e comparator o	output:					
		<u> = 0 (non-invert</u> low transition on									
	•	= 1 (inverted po	•								
		high transition or									
		event/interrupt is		transition of co	mparator outp	ut:					
		= 0 (non-inverte									
		high transition or = 1 (inverted po	•								
		low transition on									
		event/interrupt g		abled							
bit 5	Unimplemen	ted: Read as '0									

REGISTER 24-1: CMxCON: COMPARATOR x CONTROL REGISTERS (COMPARATORS 1 THROUGH 3) (CONTINUED)

- bit 4 CREF: Comparator Reference Select bits (non-inverting input)
 - 1 = Non-inverting input connects to the internal CVREF voltage
 - 0 = Non-inverting input connects to the CxINA pin
- bit 3-2 Unimplemented: Read as '0'
- bit 1-0 CCH<1:0>: Comparator Channel Select bits
 - 11 = Inverting input of the comparator connects to the internal selectable reference voltage specified by the CVREFM<1:0> bits in the CVRCON register
 - 10 = Inverting input of the comparator connects to the CxIND pin
 - 01 = Inverting input of the comparator connects to the CXINC pin
 - 00 = Inverting input of the comparator connects to the CxINB pin

REGISTER 24-2: CMSTAT: COMPARATOR MODULE STATUS REGISTER

R/W-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
CMIDL	—	—	—	—	C3EVT	C2EVT	C1EVT
bit 15							bit 8

U-0	U-0	U-0	U-0	U-0	R-0, HSC	R-0, HSC	R-0, HSC
—	—	—	—	—	C3OUT	C2OUT	C1OUT
bit 7							bit 0

Legend:	HSC = Hardware Settable/	HSC = Hardware Settable/Clearable bit				
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'				
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown			

bit 15	CMIDL: Comparator Stop in Idle Mode bit
	 1 = Discontinue operation of all comparators when device enters Idle mode 0 = Continue operation of all enabled comparators in Idle mode
bit 14-11	Unimplemented: Read as '0'
bit 10	C3EVT: Comparator 3 Event Status bit (read-only)
	Shows the current event status of Comparator 3 (CM3CON<9>).
bit 9	C2EVT: Comparator 2 Event Status bit (read-only)
	Shows the current event status of Comparator 2 (CM2CON<9>).
bit 8	C1EVT: Comparator 1 Event Status bit (read-only)
	Shows the current event status of Comparator 1 (CM1CON<9>).
bit 7-3	Unimplemented: Read as '0'
bit 2	C3OUT: Comparator 3 Output Status bit (read-only)
	Shows the current output of Comparator 3 (CM3CON<8>).
bit 1	C2OUT: Comparator 2 Output Status bit (read-only)
	Shows the current output of Comparator 2 (CM2CON<8>).
bit 0	C1OUT: Comparator 1 Output Status bit (read-only)
	Shows the current output of Comparator 1 (CM1CON<8>).

NOTES:

25.0 COMPARATOR VOLTAGE REFERENCE

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the "PIC24F Family Reference Manual", Section 19. "Comparator Module" (DS39710). The information in this data sheet supersedes the information in the FRM.

25.1 Configuring the Comparator Voltage Reference

The voltage reference module is controlled through the CVRCON register (Register 25-1). The comparator voltage reference provides two ranges of output voltage, each with 16 distinct levels. The range to be used is selected by the CVRR bit (CVRCON<5>). The primary difference between the ranges is the size of the steps selected by the CVREF Selection bits (CVR<3:0>), with one range offering finer resolution.

The comparator reference supply voltage can come from either VDD and VSS, or the external VREF+ and VREF-. The voltage source is selected by the CVRSS bit (CVRCON<4>).

The settling time of the comparator voltage reference must be considered when changing the CVREF output.

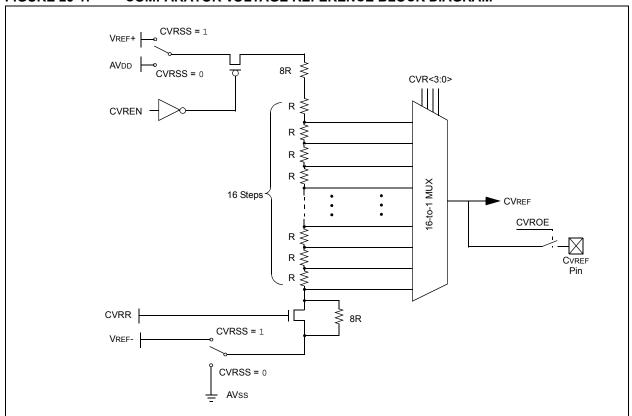


FIGURE 25-1: COMPARATOR VOLTAGE REFERENCE BLOCK DIAGRAM

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REGISTER 25-1: CVRCON: COMPARATOR VOLTAGE REFERENCE CONTROL REGISTER

U-0	U-0	U-0	U-0	U-0	R/W-0	R/W-0	R/W-0				
_	—	—	_	_	CVREFP	CVREFM1	CVREFM0				
bit 15		•					bit 8				
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0				
CVREN	CVROE	CVRR	CVRSS	CVR3	CVR2	CVR1	CVR0				
bit 7							bit 0				
Legend:											
R = Readabl	le bit	W = Writable I	oit	U = Unimpler	mented bit, read	d as '0'					
-n = Value at		'1' = Bit is set		'0' = Bit is cle		x = Bit is unkr	iown				
bit 15-11	Unimplement	ted: Read as 'o)'								
bit 10	CVREFP: Vol	tage Reference	e Select bit (va	lid only when C	CREF is '1')						
		used as a refer	•	•							
				-		voltage to the c	-				
bit 9-8	CVREFM<1:0>: Band Gap Reference Source Select bits (valid only when CCH<1:0> = 11)										
	 00 = Band gap voltage is provided as an input to the comparators 01 = Band gap voltage divided-by-two is provided as an input to the comparators 										
	10 = Band gap voltage divided-by-two is provided as an input to the comparators 10 = Band gap voltage divided-by-six is provided as an input to the comparators										
		oin is provided a									
bit 7	CVREN: Com	parator Voltage	e Reference E	nable bit							
	1 = CVREF circuit is powered on										
	0 = CVREF ci	rcuit is powered	d down								
bit 6		parator VREF C	•								
	 CVREF voltage level is output on the CVREF pin CVREF voltage level is disconnected from the CVREF pin 										
bit 5		arator VREF Ra			- pin						
DIL D		range should be	•		'RSRC/24 sten s	ize					
		range should be									
bit 4	CVRSS: Com	parator VREF S	ource Selectio	on bit							
		tor reference se									
		tor reference so	ource CVRSRC	= AVDD – AVS	S						
bit 3-0	CVR<3:0>: C	omparator VRE									
bit 3-0	CVR<3:0>: C When CVRR	omparator VRE = 1:	F Value Select								
bit 3-0	CVR<3:0>: C When CVRR	omparator VRE <u>= 1:</u> R<3:0>/ 24) • (0	F Value Select								

26.0 CHARGE TIME MEASUREMENT UNIT (CTMU)

Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the associated "PIC24F Family Reference Manual", Section 11. "Charge Time Measurement Unit (CTMU)" (DS39724). The information in this data sheet supersedes the information in the FRM.

The Charge Time Measurement Unit (CTMU) is a flexible analog module that provides accurate differential time measurement between pulse sources, as well as asynchronous pulse generation. Its key features include:

- Four edge input trigger sources
- Polarity control for each edge source
- · Control of edge sequence
- · Control of response to edges
- · Time measurement resolution of 1 nanosecond
- Accurate current source suitable for capacitive measurement

Together with other on-chip analog modules, the CTMU can be used to precisely measure time, measure capacitance, measure relative changes in capacitance or generate output pulses that are independent of the system clock. The CTMU module is ideal for interfacing with capacitive-based sensors.

The CTMU is controlled through two registers: CTMUCON and CTMUICON. CTMUCON enables the module, and controls edge source selection, edge source polarity selection, and edge sequencing. The CTMUICON register controls the selection and trim of the current source.

26.1 Measuring Capacitance

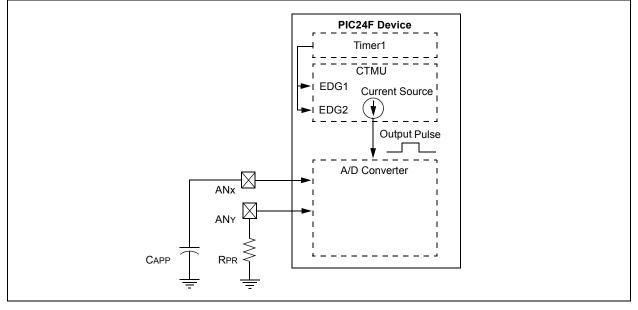
The CTMU module measures capacitance by generating an output pulse with a width equal to the time between edge events on two separate input channels. The pulse edge events to both input channels can be selected from four sources: two internal peripheral modules (OC1 and Timer1) and two external pins (CTEDG1 and CTEDG2). This pulse is used with the module's precision current source to calculate capacitance according to the relationship:

$$C = I \cdot \frac{dV}{dT}$$

For capacitance measurements, the A/D Converter samples an external capacitor (CAPP) on one of its input channels after the CTMU output's pulse. A precision resistor (RPR) provides current source calibration on a second A/D channel. After the pulse ends, the converter determines the voltage on the capacitor. The actual calculation of capacitance is performed in software by the application.

Figure 26-1 shows the external connections used for capacitance measurements, and how the CTMU and A/D modules are related in this application. This example also shows the edge events coming from Timer1, but other configurations using external edge sources are possible. A detailed discussion on measuring capacitance and time with the CTMU module is provided in the "*PIC24F Family Reference Manual*".

FIGURE 26-1: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR CAPACITANCE MEASUREMENT



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26.2 Measuring Time

Time measurements on the pulse width can be similarly performed using the A/D module's internal capacitor (CAD) and a precision resistor for current calibration. Figure 26-2 shows the external connections used for time measurements, and how the CTMU and A/D modules are related in this application. This example also shows both edge events coming from the external CTEDG pins, but other configurations using internal edge sources are possible. A detailed discussion on measuring capacitance and time with the CTMU module is provided in the "*PIC24F Family Reference Manual*".

26.3 Pulse Generation and Delay

The CTMU module can also generate an output pulse with edges that are not synchronous with the device's system clock. More specifically, it can generate a pulse with a programmable delay from an edge event input to the module. When the module is configured for pulse generation delay by setting the TGEN (CTMUCON<12>) bit, the internal current source is connected to the B input of Comparator 2. A capacitor (CDELAY) is connected to the Comparator 2 pin, C2INB, and the comparator voltage reference, CVREF, is connected to C2INA. CVREF is then configured for a specific trip point. The module begins to charge CDELAY when an edge event is detected. When CDELAY charges above the CVREF trip point, a pulse is output on CTPLS. The length of the pulse delay is determined by the value of CDELAY and the CVREF trip point.

Figure 26-3 shows the external connections for pulse generation, as well as the relationship of the different analog modules required. While CTEDG1 is shown as the input pulse source, other options are available. A detailed discussion on pulse generation with the CTMU module is provided in the "*PIC24F Family Reference Manual*".

FIGURE 26-2: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR TIME MEASUREMENT TIME

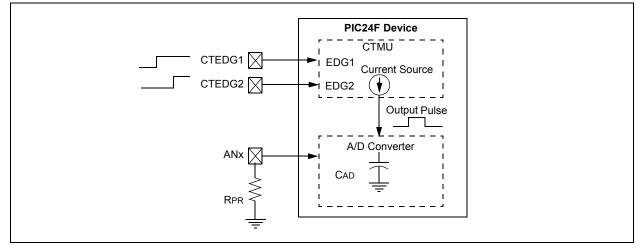
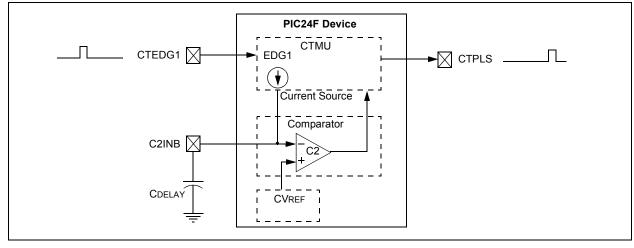


FIGURE 26-3: TYPICAL CONNECTIONS AND INTERNAL CONFIGURATION FOR PULSE DELAY GENERATION



REGISTER	26-1: CTML	JCON: CTMU	CONTROL	REGISTER			
R/W-0	U-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
CTMUEN	—	CTMUSIDL	TGEN ⁽¹⁾	EDGEN	EDGSEQEN	IDISSEN	CTTRIG
bit 15							bit 8
R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0, HSC	R/W-0, HSC
EDG2POL	EDG2SEL1	EDG2SEL0	EDG1POL	EDG1SEL1	EDG1SEL0	EDG2STAT	EDG1STAT
bit 7	•	I					bit (
Legend:		HSC = Hardw	are Settable/C	learable bit			
R = Readable	e bit	W = Writable I	bit	U = Unimplen	nented bit, read	as '0'	
-n = Value at	POR	'1' = Bit is set		'0' = Bit is clea		x = Bit is unkr	nown
bit 15	1 = Module is						
bit 14	0 = Module is	s disabled ted: Read as '(ı'				
bit 13	-	Stop in Idle Mod					
	1 = Discontin	ue module operat	ration when th		s Idle mode		
bit 12		Generation Ena					
		edge delay gen edge delay ger					
bit 10	EDGEN: Edg 1 = Edges ar 0 = Edges ar	e not blocked					
bit 10	1 = Edge 1 e	Edge Sequence vent must occu sequence is ne	r before Edge	2 event can oc	cur		
bit 9	IDISSEN: Ana 1 = Analog c	alog Current So urrent source o urrent source o	ource Control b utput is ground	bed			
bit 8	1 = Trigger o	ger Control bit utput is enabled utput is disable					
bit 7		dge 2 Polarity					
	•	s programmed f s programmed f	•	•			
bit 6-5	EDG2SEL<1: 11 = CTEDG 10 = CTEDG 01 = OC1 mc 00 = Timer1	2 pin odule	urce Select bit	S			
bit 4	1 = Edge 1 is	dge 1 Polarity s programmed f programmed f	or a positive e				
Note 1: If	TGEN = 1 the	nerinheral innut	s and outputs	must be config	ured to an avail	lable RPn/RPI	n nin See

REGISTER 26-1: CTMUCON: CTMU CONTROL REGISTER

Note 1: If TGEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. See **Section 10.4 "Peripheral Pin Select (PPS)"** for more information.

REGISTER 26-1: CTMUCON: CTMU CONTROL REGISTER (CONTINUED)

- bit 3-2EDG1SEL<1:0>: Edge 1 Source Select bits11 = CTEDG1 pin10 = CTEDG2 pin01 = OC1 module00 = Timer1 modulebit 1EDG2STAT: Edge 2 Status bit1 = Edge 2 event has occurred0 = Edge 2 event has not occurredbit 0EDG1STAT: Edge 1 Status bit1 = Edge 1 event has not occurred0 = Edge 1 event has not occurred
- Note 1: If TGEN = 1, the peripheral inputs and outputs must be configured to an available RPn/RPIn pin. See Section 10.4 "Peripheral Pin Select (PPS)" for more information.

REGISTER 26-2: CTMUICON: CTMU CURRENT CONTROL REGISTER

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ITRIM5	ITRIM4	ITRIM3	ITRIM2	ITRIM1	ITRIM0	IRNG1	IRNG0
bit 15					·		bit 8
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
			—	—			—
bit 7							bit 0
Legend:							
R = Readab	le bit	W = Writable		•	nented bit, read	1 as '0'	
-n = Value a	t POR	'1' = Bit is set		'0' = Bit is clea	ared	x = Bit is unkr	nown
	000000 = No 111111 = M 100010	inimum positive ominal current linimum negativ	output specifie ve change from	d by IRNG<1:0 nominal curre	I> Int		
bit 9-8	IRNG<1:0>: 0 11 = 100 × Ba 10 = 10 × Bas 01 = Base cu 00 = Current	Current Source ase Current se Current Irrent level (0.5 source is disat	Range Select 5 μA nominal) bled				
bit 7-0	Unimplemen	ted: Read as ')'				

27.0 SPECIAL FEATURES

- Note: This data sheet summarizes the features of this group of PIC24F devices. It is not intended to be a comprehensive reference source. For more information, refer to the following sections of the "*PIC24F Family Reference Manual*". The information in this data sheet supersedes the information in the FRMs.
 - Section 9. "Watchdog Timer (WDT)" (DS39697)
 - Section 32. "High-Level Device Integration" (DS39719)
 - Section 33. "Programming and Diagnostics" (DS39716)

PIC24FJ256DA210 family devices include several features intended to maximize application flexibility and reliability, and minimize cost through elimination of external components. These are:

- Flexible Configuration
- Watchdog Timer (WDT)
- Code Protection
- JTAG Boundary Scan Interface
- In-Circuit Serial Programming[™]
- In-Circuit Emulation

27.1 Configuration Bits

The Configuration bits can be programmed (read as '0'), or left unprogrammed (read as '1'), to select various device configurations. These bits are mapped starting at program memory location F80000h. A detailed explanation of the various bit functions is provided in Register 27-1 through Register 27-6.

Note that address F80000h is beyond the user program memory space. In fact, it belongs to the configuration memory space (800000h-FFFFFFh) which can only be accessed using table reads and table writes.

27.1.1 CONSIDERATIONS FOR CONFIGURING PIC24FJ256DA210 FAMILY DEVICES

In PIC24FJ256DA210 family devices, the configuration bytes are implemented as volatile memory. This means that configuration data must be programmed each time the device is powered up. Configuration data is stored in the three words at the top of the on-chip program memory space, known as the Flash Configuration Words. Their specific locations are shown in Table 27-1. These are packed representations of the actual device Configuration bits, whose actual locations are distributed among several locations in configuration space. The configuration data is automatically loaded from the Flash Configuration Words to the proper Configuration registers during device Resets.

Note:	Configuration data is reloaded on all types
	of device Resets.

When creating applications for these devices, users should always specifically allocate the location of the Flash Configuration Word for configuration data. This is to make certain that program code is not stored in this address when the code is compiled.

The upper byte of all Flash Configuration Words in program memory should always be '0000 0000'. This makes them appear to be NOP instructions in the remote event that their locations are ever executed by accident. Since Configuration bits are not implemented in the corresponding locations, writing '0's to these locations has no effect on device operation.

Note: Performing a page erase operation on the last page of program memory clears the Flash Configuration Words, enabling code protection as a result. Therefore, users should avoid performing page erase operations on the last page of program memory.

TABLE 27-1: FLASH CONFIGURATION WORD LOCATIONS FOR PIC24FJ256DA210 FAMILY DEVICES

Device		Configuration V	Vord Addresses	
Device	1	2	3	4
PIC24FJ128DAXXX	157FEh	157FCh	157FAh	157F8h
PIC24FJ256DAXXX	2ABFEh	2ABFCh	2ABFAh	2ABF8h

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 23							bit 16

r-x	R/PO-1	R/PO-1	R/PO-1	R/PO-1	r-1	R/PO-1	R/PO-1
reserved	JTAGEN	GCP	GWRP	DEBUG	reserved	ICS1	ICS0
bit 15							bit 8

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
FWDTEN	WINDIS	ALTVREF ⁽¹⁾	FWPSA	WDTPS3	WDTPS2	WDTPS1	WDTPS0
bit 7							bit 0

Legend:	r = Reserved bit			
R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'		
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown	

bit 23-16	Unimplemented: Read as '1'
bit 15	Reserved: The value is unknown; program as '0'
bit 14	JTAGEN: JTAG Port Enable bit
	1 = JTAG port is enabled0 = JTAG port is disabled
bit 13	GCP: General Segment Program Memory Code Protection bit
	 1 = Code protection is disabled 0 = Code protection is enabled for the entire program memory space
bit 12	GWRP: General Segment Code Flash Write Protection bit
	1 = Writes to program memory are allowed0 = Writes to program memory are not allowed
bit 11	DEBUG: Background Debugger Enable bit
	1 = Device resets into Operational mode0 = Device resets into Debug mode
bit 10	Reserved: Always maintain as '1'
bit 9-8	ICS<1:0>: Emulator Pin Placement Select bits
	 11 = Emulator functions are shared with PGEC1/PGED1 10 = Emulator functions are shared with PGEC2/PGED2 01 = Emulator functions are shared with PGEC3/PGED3 00 = Reserved; do not use
bit 7	FWDTEN: Watchdog Timer Enable bit
	1 = Watchdog Timer is enabled0 = Watchdog Timer is disabled
bit 6	WINDIS: Windowed Watchdog Timer Disable bit
	 1 = Standard Watchdog Timer is enabled 0 = Windowed Watchdog Timer is enabled; FWDTEN must be '1'
bit 5	ALTVREF: Alternate VREF Pin Selection bit ⁽¹⁾
	 1 = VREF is on a default pin (VREF+ on RA10 and VREF- on RA9) 0 = VREF is on an alternate pin (VREF+ on RB0 and VREF- on RB1)

Note 1: Unimplemented in 64-pin devices, maintain at '1' (VREF+ on RB0 and VREF- on RB1).

REGISTER 27-1: CW1: FLASH CONFIGURATION WORD 1 (CONTINUED)

- bit 4 FWPSA: WDT Prescaler Ratio Select bit
 - 1 = Prescaler ratio of 1:128
 - 0 = Prescaler ratio of 1:32
- bit 3-0 WDTPS<3:0>: Watchdog Timer Postscaler Select bits
 - 1111 = 1:32,768 1110 = 1:16,384 1101 **= 1:8,192** 1100 = 1:4,096 1011 = 1:2,048 1010 = 1:1,024 1001 = 1:512 1000 = 1:256 0111 = 1:128 0110 = 1:64 0101 = 1:32 0100 = 1:16 0011 = 1:8 0010 = 1:4 0001 = 1:2 0000 = 1:1
- Note 1: Unimplemented in 64-pin devices, maintain at '1' (VREF+ on RB0 and VREF- on RB1).

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R/PO-1 R/PO-1 R/PO-1 r-1 r-1 R/PO-1 FCKSM1 FCKSM0 OSCIOFCN IOL1WAY reserved POSCMD1 bit 7 Legend: r = Reserved bit R = Readable bit W = Writable bit U = Unimplemented bit, read as '0' -n = Value at POR '1' = Bit is set '0' = Bit is cleared x = Bit is unknow bit 23-16 Unimplemented: Read as '1' IESO: Internal External Switchover bit 1 = IESO mode (Two-Speed Start-up) is enabled 0 = IESO mode (Two-Speed Start-up) is disabled bit 14-12 PLLDIV<2:0>: 96 MHz PLL Prescaler Select bits PLLDIV 2:0>: 96 MHz PLL Prescaler Select bits	— bit 1 R/PO-1 FNOSC0 bit R/PO-1 POSCMD0 bit									
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bit 14-12 PLLDIV<2:0>: 96 MHz PLL Prescaler Select bits										
	0 = IESO mode (Two-Speed Start-up) is disabled									
111 = Oscillator input is divided by 12 (48 MHz input)										
	111 = Oscillator input is divided by 12 (48 MHz input)									
	110 = Oscillator input is divided by 8 (32 MHz input)									
	101 = Oscillator input is divided by 6 (24 MHz input) 100 = Oscillator input is divided by 5 (20 MHz input)									
011 = Oscillator input is divided by 4 (16 MHz input)										
010 = Oscillator input is divided by 3 (12 MHz input)										
001 = Oscillator input is divided by 2 (8 MHz input)										
000 = Oscillator input is used directly (4 MHz input)	000 = Oscillator input is used directly (4 MHz input)									
bit 11 PLL96MHZ: 96 MHz PLL Start-Up Enable bit										
1 = 96 MHz PLL is enabled automatically on start-up										
	0 = 96 MHz PLL is software controlled (can be enabled by setting the PLLEN bit in CLKDIV<5>)									
	FNOSC<2:0>: Initial Oscillator Select bits									
111 = Fast RC Oscillator with Postscaler (FRCDIV)110 = Reserved										
101 = Low-Power RC Oscillator (LPRC)										
100 = Secondary Oscillator (SOSC)										
011 = Primary Oscillator with PLL module (XTPLL, HSPLL, ECPLL)										
010 = Primary Oscillator (XT, HS, EC)										
001 = Fast RC Oscillator with Postscaler and PLL module (FRCPLL)										
	000 = Fast RC Oscillator (FRC)									
1x = Clock switching and Fail-Safe Clock Monitor are disabled	FCKSM<1:0>: Clock Switching and Fail-Safe Clock Monitor Configuration bits									
01 = Clock switching is enabled, Fail-Safe Clock Monitor is disabled										
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled										
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled										
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled bit 5 OSCIOFCN: OSCO Pin Configuration bit If POSCMD<1:0> = 11 or 00:										
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled bit 5 OSCIOFCN: OSCO Pin Configuration bit If POSCMD<1:0> = 11 or 00: 1 = OSCO/CLKO/RC15 functions as CLKO (Fosc/2)										
00 = Clock switching is enabled, Fail-Safe Clock Monitor is enabled bit 5 OSCIOFCN: OSCO Pin Configuration bit If POSCMD<1:0> = 11 or 00:										

REGISTER 27-2: CW2: FLASH CONFIGURATION WORD 2 (CONTINUED)

- bit 4 **IOL1WAY:** IOLOCK One-Way Set Enable bit
 - 1 = The IOLOCK bit (OSCCON<6>) can be set once, provided the unlock sequence has been completed. Once set, the Peripheral Pin Select registers cannot be written to a second time.
 - 0 = The IOLOCK bit can be set and cleared as needed, provided the unlock sequence has been completed
- bit 3-2 Reserved: Always maintain as '1'
- bit 1-0 **POSCMD<1:0>:** Primary Oscillator Configuration bits
 - 11 = Primary oscillator is disabled
 - 10 = HS Oscillator mode is selected
 - 01 = XT Oscillator mode is selected
 - 00 = EC Oscillator mode is selected

REGISTER 27-3: CW3: FLASH CONFIGURATION WORD 3

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 23							bit 16

R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1	R/PO-1
WPEND	WPCFG	WPDIS	ALTPMP ⁽¹⁾	WUTSEL1	WUTSEL0	SOSCSEL1	SOSCSEL0
bit 15			- -				bit 8

| R/PO-1 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| WPFP7 | WPFP6 | WPFP5 | WPFP4 | WPFP3 | WPFP2 | WPFP1 | WPFP0 |
| bit 7 | | | | | | | bit 0 |

Legend:	PO = Program-Once bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit, read	l as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 23-16	Unimplemented: Read as '1'
bit 15	WPEND: Segment Write Protection End Page Select bit
	 1 = Protected code segment upper boundary is at the last page of program memory; the lower boundary is the code page specified by WPFP<7:0> 0 = Protected code segment lower boundary is at the bottom of the program memory (000000h); upper boundary is the code page specified by WPFP<7:0>
bit 14	WPCFG: Configuration Word Code Page Write Protection Select bit
	 1 = Last page (at the top of program memory) and Flash Configuration Words are not write-protected⁽³⁾ 0 = Last page and Flash Configuration Words are write-protected, provided WPDIS = '0'
bit 13	WPDIS: Segment Write Protection Disable bit
	1 = Segmented code protection is disabled
	 Segmented code protection is enabled; protected segment is defined by the WPEND, WPCFG and WPFPx Configuration bits
bit 12	ALTPMP: Alternate EPMP Pin Mapping bit ⁽¹⁾
	 1 = EPMP pins are in default location mode 0 = EPMP pins are in alternate location mode
Note 1:	Unimplemented in 64-pin devices, maintain at '1'.
2:	Ensure that the SCLKI pin is made a digital input while using this configuration, see Table 10-1.
3:	Regardless of WPCFG status, if WPEND = 1 or if WPFP corresponds to the Configuration Word's page, the Configuration Word's page is protected.

REGISTER 27-3: CW3: FLASH CONFIGURATION WORD 3 (CONTINUED)

- bit 11-10 WUTSEL<1:0>: Voltage Regulator Standby Mode Wake-up Time Select bits 11 = Default regulator start-up time is used 01 = Fast regulator start-up time is used x0 = Reserved; do not use bit 9-8 SOSCSEL<1:0>: SOSC Selection Configuration bits 11 = Secondary oscillator is in Default (high drive strength) Oscillator mode 10 = Reserved; do not use 01 = Secondary oscillator is in Low-Power (low drive strength) Oscillator mode 00 = External clock (SCLKI) or Digital I/O mode⁽²⁾ bit 7-0 WPFP<7:0>: Write Protected Code Segment Boundary Page bits Designates the 512 instruction words page boundary of the protected code segment. If WPEND = 1: Specifies the lower page boundary of the code-protected segment; the last page being the last implemented page in the device. If WPEND = 0: Specifies the upper page boundary of the code-protected segment; Page 0 being the lower boundary. Note 1: Unimplemented in 64-pin devices, maintain at '1'. 2: Ensure that the SCLKI pin is made a digital input while using this configuration, see Table 10-1.
 - **3:** Regardless of WPCFG status, if WPEND = 1 or if WPFP corresponds to the Configuration Word's page, the Configuration Word's page is protected.

REGISTER 27-4: CW4: FLASH CONFIGURATION WORD 4

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	_	—	—	—	—
bit 23							bit 16

| r-1 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| reserved |
| bit 15 | | | | | | | bit 8 |

| r-1 |
|----------|----------|----------|----------|----------|----------|----------|----------|
| reserved |
| bit 7 | | | | | | | bit 0 |

Legend:	r = Reserved bit		
R = Readable bit	W = Writable bit	U = Unimplemented bit	, read as '0'
-n = Value at POR	'1' = Bit is set	'0' = Bit is cleared	x = Bit is unknown

bit 23-16 Unimplemented: Read as '0'

bit 15-0 **Reserved:** Always maintain as '1'

REGISTER 27-5: DEVID: DEVICE ID REGISTER

| U-0 |
|--------|--------|--------|--------|--------|--------|--------|--------|
| — | _ | | — | | | | — |
| bit 23 | | | | | | | bit 16 |
| | | | | | | | |
| R | R | R | R | R | R | R | R |
| FAMID7 | FAMID6 | FAMID5 | FAMID4 | FAMID3 | FAMID2 | FAMID1 | FAMID0 |
| bit 15 | | | | | | | bit 8 |
| | | | | | | | |
| R | R | R | R | R | R | R | R |
| DEV7 | DEV6 | DEV5 | DEV4 | DEV3 | DEV2 | DEV1 | DEV0 |
| bit 7 | | | | | | | bit 0 |

- bit 23-16 Unimplemented: Read as '1'
- bit 15-8 **FAMID<7:0>:** Device Family Identifier bits 01000001 = PIC24FJ256DA210 family
- bit 7-0 **DEV<7:0>:** Individual Device Identifier bits 00001000 = PIC24FJ128DA206 00001001 = PIC24FJ128DA106 00001010 = PIC24FJ128DA210 00001011 = PIC24FJ128DA110 00001100 = PIC24FJ256DA206 00001101 = PIC24FJ256DA106 00001110 = PIC24FJ256DA210 00001111 = PIC24FJ256DA110

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REGISTER 27-6: DEVREV: DEVICE REVISION REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	—	—	—	—	—	—	—	
bit 23							bit 16	
U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0	
	—	—	—	—	—	—	—	
bit 15							bit 8	
U-0	U-0	U-0	U-0	R	R	R	R	
	—	—	—	REV3	REV2	REV1	REV0	
bit 7							bit 0	
Legend: R	Legend: R = Readable bit			U = Unimplemented bit				

bit 23-4 Unimplemented: Read as '0'

bit 3-0 **REV<3:0>:** Device revision identifier bits

27.2 On-Chip Voltage Regulator

All PIC24FJ256DA210 family devices power their core digital logic at a nominal 1.8V. This may create an issue for designs that are required to operate at a higher typical voltage, such as 3.3V. To simplify system design, all devices in the PIC24FJ256DA210 family incorporate an on-chip regulator that allows the device to run its core logic from VDD.

The regulator is controlled by the ENVREG pin. Tying VDD to the pin enables the regulator, which in turn, provides power to the core from the other VDD pins. When the regulator is enabled, a low-ESR capacitor (such as ceramic) must be connected to the VCAP pin (Figure 27-1). This helps to maintain the stability of the regulator. The recommended value for the filter capacitor (CEFC) is provided in **Section 30.1 "DC Characteristics"**.

27.2.1 VOLTAGE REGULATOR LOW-VOLTAGE DETECTION

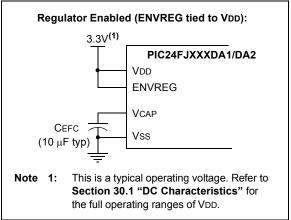
When the on-chip regulator is enabled, it provides a constant voltage of 1.8V nominal to the digital core logic.

The regulator can provide this level from a VDD of about 2.1V, all the way up to the device's VDDMAX. It does not have the capability to boost VDD levels. In order to prevent "brown-out" conditions when the voltage drops too low for the regulator, the Brown-out Reset occurs. Then the regulator output follows VDD with a typical voltage drop of 300 mV.

To provide information about when the regulator voltage starts reducing, the on-chip regulator includes a simple Low-Voltage Detect circuit, which sets the

Low-Voltage Detect Interrupt Flag, LVDIF (IFS4<8>). This can be used to generate an interrupt to trigger an orderly shutdown.

FIGURE 27-1: CONNECTIONS FOR THE ON-CHIP REGULATOR



27.2.2 ON-CHIP REGULATOR AND POR

When the voltage regulator is enabled, it takes approximately 10 μ s for it to generate output. During this time, designated as TVREG, code execution is disabled. TVREG is applied every time the device resumes operation after any power-down, including Sleep mode. TVREG is determined by the status of the VREGS bit (RCON<8>) and the WUTSEL Configuration bits (CW3<11:10>). Refer to **Section 30.0 "Electrical Characteristics"** for more information on TVREG.

27.2.3 ON-CHIP REGULATOR AND BOR

When the on-chip regulator is enabled, PIC24FJ256DA210 family devices also have a simple brown-out capability. If the voltage supplied to the regulator is inadequate to maintain the output level, the regulator Reset circuitry will generate a Brown-out Reset. This event is captured by the BOR (RCON<1>) flag bit. The brown-out voltage specifications are provided in **Section 7. "Reset"** (DS39712) in the *"PIC24F Family Reference Manual"*.

Note: For more information, see Section 30.0 "Electrical Characteristics". The information in this data sheet supersedes the information in the FRM.

27.2.4 VOLTAGE REGULATOR STANDBY MODE

When enabled, the on-chip regulator always consumes a small incremental amount of current over IDD/IPD, including when the device is in Sleep mode, even though the core digital logic does not require power. To provide additional savings in applications where power resources are critical, the regulator can be made to enter Standby mode on its own whenever the device goes into Sleep mode. This feature is controlled by the VREGS bit (RCON<8>). Clearing the VREGS bit enables the Standby mode. When waking up from Standby mode, the regulator needs to wait for TVREG to expire before wake-up.

The regulator wake-up time required for Standby mode is controlled by the WUTSEL<1:0> (CW3<11:10>) Configuration bits. The regulator wake-up time is lower when WUTSEL<1:0> = 01, and higher when WUTSEL<1:0> = 11. Refer to the TVREG specification in Table 30-10 for regulator wake-up time.

When the regulator's Standby mode is turned off (VREGS = 1), the device wakes up without waiting for TVREG. However, with the VREGS bit set, the power consumption while in Sleep mode will be approximately 40 μ A higher than what it would be if the regulator was allowed to enter Standby mode.

27.3 Watchdog Timer (WDT)

For PIC24FJ256DA210 family devices, the WDT is driven by the LPRC oscillator. When the WDT is enabled, the clock source is also enabled.

The nominal WDT clock source from LPRC is 31 kHz. This feeds a prescaler that can be configured for either 5-bit (divide-by-32) or 7-bit (divide-by-128) operation. The prescaler is set by the FWPSA Configuration bit. With a 31 kHz input, the prescaler yields a nominal WDT Time-out period (TWDT) of 1 ms in 5-bit mode or 4 ms in 7-bit mode.

A variable postscaler divides down the WDT prescaler output and allows for a wide range of time-out periods. The postscaler is controlled by the WDTPS<3:0> Configuration bits (CW1<3:0>), which allows the selection of a total of 16 settings, from 1:1 to 1:32,768. Using the prescaler and postscaler time-out periods, ranging from 1 ms to 131 seconds, can be achieved.

The WDT, prescaler and postscaler are reset:

- · On any device Reset
- On the completion of a clock switch, whether invoked by software (i.e., setting the OSWEN bit after changing the NOSC bits) or by hardware (i.e., Fail-Safe Clock Monitor)
- When a PWRSAV instruction is executed (i.e., Sleep or Idle mode is entered)
- When the device exits Sleep or Idle mode to resume normal operation
- By a CLRWDT instruction during normal execution

If the WDT is enabled, it will continue to run during Sleep or Idle modes. When the WDT time-out occurs, the device will wake the device and code execution will continue from where the PWRSAV instruction was executed. The corresponding SLEEP or IDLE (RCON<3:2>) bits will need to be cleared in software after the device wakes up.

The WDT Flag bit, WDTO (RCON<4>), is not automatically cleared following a WDT time-out. To detect subsequent WDT events, the flag must be cleared in software.

Note: The CLRWDT and PWRSAV instructions clear the prescaler and postscaler counts when executed.

27.3.1 WINDOWED OPERATION

The Watchdog Timer has an optional Fixed-Window mode of operation. In this Windowed mode, CLRWDT instructions can only reset the WDT during the last 1/4 of the programmed WDT period. A CLRWDT instruction executed before that window causes a WDT Reset, similar to a WDT time-out.

Windowed WDT mode is enabled by programming the WINDIS Configuration bit (CW1<6>) to '0'.

27.3.2 CONTROL REGISTER

The WDT is enabled or disabled by the FWDTEN Configuration bit. When the FWDTEN Configuration bit is set, the WDT is always enabled.

The WDT can be optionally controlled in software when the FWDTEN Configuration bit has been programmed to '0'. The WDT is enabled in software by setting the SWDTEN Control bit (RCON<5>). The SWDTEN control bit is cleared on any device Reset. The software WDT option allows the user to enable the WDT for critical code segments and disable the WDT during non-critical segments for maximum power savings.

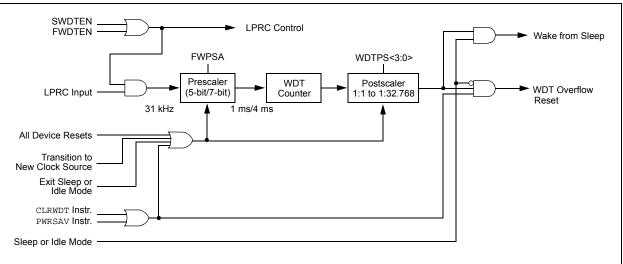


FIGURE 27-2: WDT BLOCK DIAGRAM

27.4 Program Verification and Code Protection

PIC24FJ256DA210 family devices provide two complimentary methods to protect application code from overwrites and erasures. These also help to protect the device from inadvertent configuration changes during run time.

27.4.1 GENERAL SEGMENT PROTECTION

For all devices in the PIC24FJ256DA210 family, the on-chip program memory space is treated as a single block, known as the General Segment (GS). Code protection for this block is controlled by one Configuration bit, GCP. This bit inhibits external reads and writes to the program memory space. It has no direct effect in normal execution mode.

Write protection is controlled by the GWRP bit in the Configuration Word. When GWRP is programmed to '0', internal write and erase operations to program memory are blocked.

27.4.2 CODE SEGMENT PROTECTION

In addition to global General Segment protection, a separate subrange of the program memory space can be individually protected against writes and erases. This area can be used for many purposes where a separate block of write and erase-protected code is needed, such as bootloader applications. Unlike common boot block implementations, the specially protected segment in the PIC24FJ256DA210 family devices can be located by the user anywhere in the program space and configured in a wide range of sizes.

Code segment protection provides an added level of protection to a designated area of program memory by disabling the NVM safety interlock whenever a write or erase address falls within a specified range. It does not override General Segment protection controlled by the GCP or GWRP bits. For example, if GCP and GWRP are enabled, enabling segmented code protection for the bottom half of program memory does not undo General Segment protection for the top half. The size and type of protection for the segmented code range are configured by the WPFPx, WPEND, WPCFG and WPDIS bits in Configuration Word 3. Code segment protection is enabled by programming the WPDIS bit (= 0). The WPFP bits specify the size of the segment to be protected, by specifying the 512-word code page that is the start or end of the protected segment. The specified region is inclusive, therefore, this page will also be protected.

The WPEND bit determines if the protected segment uses the top or bottom of the program space as a boundary. Programming WPEND (= 0) sets the bottom of program memory (000000h) as the lower boundary of the protected segment. Leaving WPEND unprogrammed (= 1) protects the specified page through the last page of implemented program memory, including the Configuration Word locations.

A separate bit, WPCFG, is used to protect the last page of program space, including the Flash Configuration Words. Programming WPCFG (= 0) protects the last page in addition to the pages selected by the WPEND and WPFP<7:0> bits setting. This is useful in circumstances where write protection is needed for both the code segment in the bottom of the memory and the Flash Configuration Words.

The various options for segment code protection are shown in Table 27-2.

27.4.3 CONFIGURATION REGISTER PROTECTION

The Configuration registers are protected against inadvertent or unwanted changes or reads in two ways. The primary protection method is the same as that of the RP registers – shadow registers contain a complimentary value which is constantly compared with the actual value. To safeguard against unpredictable events, Configuration bit changes resulting from individual cell level disruptions (such as ESD events) will cause a parity error and trigger a device Reset.

The data for the Configuration registers is derived from the Flash Configuration Words in program memory. When the GCP bit is set, the source data for device configuration is also protected as a consequence. Even if General Segment protection is not enabled, the device configuration can be protected by using the appropriate code segment protection setting.

Segmen	Segment Configuration Bits		Write/Eraca Brotaction of Code Segment
WPDIS	WPEND	WPCFG	Write/Erase Protection of Code Segment
1	Х	x	No additional protection is enabled; all program memory protection is configured by GCP and GWRP.
0	1	х	Addresses from the first address of the code page are defined by WPFP<7:0> through the end of implemented program memory (inclusive), write/erase protected, including Flash Configuration Words.
0	0	1	Address 000000h through the last address of the code page is defined by WPFP<7:0> (inclusive), write/erase protected.
0	0	0	Address 000000h through the last address of code page is defined by WPFP<7:0> (inclusive), write/erase protected and the last page, including Flash Configuration Words are write/erase protected.

TABLE 27-2: CODE SEGMENT PROTECTION CONFIGURATION OPTIONS

27.5 JTAG Interface

PIC24FJ256DA210 family devices implement a JTAG interface, which supports boundary scan device testing.

27.6 In-Circuit Serial Programming™

PIC24FJ256DA210 family microcontrollers can be serially programmed while in the end application circuit. This is simply done with two lines for clock (PGECx) and data (PGEDx), and three other lines for power (VDD), ground (VSS) and MCLR. This allows customers to manufacture boards with unprogrammed devices and then program the microcontroller just before shipping the product. This also allows the most recent firmware or a custom firmware to be programmed.

27.7 In-Circuit Debugger

When MPLAB[®] ICD 3 is selected as a debugger, the in-circuit debugging functionality is enabled. This function allows simple debugging functions when used with MPLAB IDE. Debugging functionality is controlled through the PGECx (Emulation/Debug Clock) and PGEDx (Emulation/Debug Data) pins.

To use the in-circuit debugger function of the device, the design must implement ICSP connections to MCLR, VDD, VSS and the PGECx/PGEDx pin pair designated by the ICS Configuration bits. In addition, when the feature is enabled, some of the resources are not available for general use. These resources include the first 80 bytes of data RAM and two I/O pins.

28.0 DEVELOPMENT SUPPORT

The PIC[®] microcontrollers and dsPIC[®] digital signal controllers are supported with a full range of software and hardware development tools:

- Integrated Development Environment
- MPLAB[®] IDE Software
- Compilers/Assemblers/Linkers
 - MPLAB C Compiler for Various Device Families
 - HI-TECH C for Various Device Families
 - MPASM[™] Assembler
 - MPLINK[™] Object Linker/ MPLIB[™] Object Librarian
 - MPLAB Assembler/Linker/Librarian for Various Device Families
- · Simulators
 - MPLAB SIM Software Simulator
- Emulators
 - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers
 - MPLAB ICD 3
 - PICkit™ 3 Debug Express
- Device Programmers
 - PICkit[™] 2 Programmer
 - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits, and Starter Kits

28.1 MPLAB Integrated Development Environment Software

The MPLAB IDE software brings an ease of software development previously unseen in the 8/16/32-bit microcontroller market. The MPLAB IDE is a Windows[®] operating system-based application that contains:

- A single graphical interface to all debugging tools
 - Simulator
 - Programmer (sold separately)
 - In-Circuit Emulator (sold separately)
 - In-Circuit Debugger (sold separately)
- · A full-featured editor with color-coded context
- A multiple project manager
- Customizable data windows with direct edit of contents
- · High-level source code debugging
- · Mouse over variable inspection
- Drag and drop variables from source to watch windows
- · Extensive on-line help
- Integration of select third party tools, such as IAR C Compilers

The MPLAB IDE allows you to:

- Edit your source files (either C or assembly)
- One-touch compile or assemble, and download to emulator and simulator tools (automatically updates all project information)
- · Debug using:
 - Source files (C or assembly)
 - Mixed C and assembly
 - Machine code

MPLAB IDE supports multiple debugging tools in a single development paradigm, from the cost-effective simulators, through low-cost in-circuit debuggers, to full-featured emulators. This eliminates the learning curve when upgrading to tools with increased flexibility and power.

28.2 MPLAB C Compilers for Various Device Families

The MPLAB C Compiler code development systems are complete ANSI C compilers for Microchip's PIC18, PIC24 and PIC32 families of microcontrollers and the dsPIC30 and dsPIC33 families of digital signal controllers. These compilers provide powerful integration capabilities, superior code optimization and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

28.3 HI-TECH C for Various Device Families

The HI-TECH C Compiler code development systems are complete ANSI C compilers for Microchip's PIC family of microcontrollers and the dsPIC family of digital signal controllers. These compilers provide powerful integration capabilities, omniscient code generation and ease of use.

For easy source level debugging, the compilers provide symbol information that is optimized to the MPLAB IDE debugger.

The compilers include a macro assembler, linker, preprocessor, and one-step driver, and can run on multiple platforms.

28.4 MPASM Assembler

The MPASM Assembler is a full-featured, universal macro assembler for PIC10/12/16/18 MCUs.

The MPASM Assembler generates relocatable object files for the MPLINK Object Linker, Intel[®] standard HEX files, MAP files to detail memory usage and symbol reference, absolute LST files that contain source lines and generated machine code and COFF files for debugging.

The MPASM Assembler features include:

- · Integration into MPLAB IDE projects
- User-defined macros to streamline assembly code
- Conditional assembly for multi-purpose source files
- Directives that allow complete control over the assembly process

28.5 MPLINK Object Linker/ MPLIB Object Librarian

The MPLINK Object Linker combines relocatable objects created by the MPASM Assembler and the MPLAB C18 C Compiler. It can link relocatable objects from precompiled libraries, using directives from a linker script.

The MPLIB Object Librarian manages the creation and modification of library files of precompiled code. When a routine from a library is called from a source file, only the modules that contain that routine will be linked in with the application. This allows large libraries to be used efficiently in many different applications.

The object linker/library features include:

- Efficient linking of single libraries instead of many smaller files
- Enhanced code maintainability by grouping related modules together
- Flexible creation of libraries with easy module listing, replacement, deletion and extraction

28.6 MPLAB Assembler, Linker and Librarian for Various Device Families

MPLAB Assembler produces relocatable machine code from symbolic assembly language for PIC24, PIC32 and dsPIC devices. MPLAB C Compiler uses the assembler to produce its object file. The assembler generates relocatable object files that can then be archived or linked with other relocatable object files and archives to create an executable file. Notable features of the assembler include:

- · Support for the entire device instruction set
- · Support for fixed-point and floating-point data
- Command line interface
- · Rich directive set
- Flexible macro language
- · MPLAB IDE compatibility

28.7 MPLAB SIM Software Simulator

The MPLAB SIM Software Simulator allows code development in a PC-hosted environment by simulating the PIC MCUs and dsPIC[®] DSCs on an instruction level. On any given instruction, the data areas can be examined or modified and stimuli can be applied from a comprehensive stimulus controller. Registers can be logged to files for further run-time analysis. The trace buffer and logic analyzer display extend the power of the simulator to record and track program execution, actions on I/O, most peripherals and internal registers.

The MPLAB SIM Software Simulator fully supports symbolic debugging using the MPLAB C Compilers, and the MPASM and MPLAB Assemblers. The software simulator offers the flexibility to develop and debug code outside of the hardware laboratory environment, making it an excellent, economical software development tool.

28.8 MPLAB REAL ICE In-Circuit Emulator System

MPLAB REAL ICE In-Circuit Emulator System is Microchip's next generation high-speed emulator for Microchip Flash DSC and MCU devices. It debugs and programs PIC[®] Flash MCUs and dsPIC[®] Flash DSCs with the easy-to-use, powerful graphical user interface of the MPLAB Integrated Development Environment (IDE), included with each kit.

The emulator is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with either a connector compatible with in-circuit debugger systems (RJ11) or with the new high-speed, noise tolerant, Low-Voltage Differential Signal (LVDS) interconnection (CAT5).

The emulator is field upgradable through future firmware downloads in MPLAB IDE. In upcoming releases of MPLAB IDE, new devices will be supported, and new features will be added. MPLAB REAL ICE offers significant advantages over competitive emulators including low-cost, full-speed emulation, run-time variable watches, trace analysis, complex breakpoints, a ruggedized probe interface and long (up to three meters) interconnection cables.

28.9 MPLAB ICD 3 In-Circuit Debugger System

MPLAB ICD 3 In-Circuit Debugger System is Microchip's most cost effective high-speed hardware debugger/programmer for Microchip Flash Digital Signal Controller (DSC) and microcontroller (MCU) devices. It debugs and programs PIC[®] Flash microcontrollers and dsPIC[®] DSCs with the powerful, yet easy-to-use graphical user interface of MPLAB Integrated Development Environment (IDE).

The MPLAB ICD 3 In-Circuit Debugger probe is connected to the design engineer's PC using a high-speed USB 2.0 interface and is connected to the target with a connector compatible with the MPLAB ICD 2 or MPLAB REAL ICE systems (RJ-11). MPLAB ICD 3 supports all MPLAB ICD 2 headers.

28.10 PICkit 3 In-Circuit Debugger/Programmer and PICkit 3 Debug Express

The MPLAB PICkit 3 allows debugging and programming of PIC[®] and dsPIC[®] Flash microcontrollers at a most affordable price point using the powerful graphical user interface of the MPLAB Integrated Development Environment (IDE). The MPLAB PICkit 3 is connected to the design engineer's PC using a full speed USB interface and can be connected to the target via an Microchip debug (RJ-11) connector (compatible with MPLAB ICD 3 and MPLAB REAL ICE). The connector uses two device I/O pins and the reset line to implement in-circuit debugging and In-Circuit Serial Programming[™].

The PICkit 3 Debug Express include the PICkit 3, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

28.11 PICkit 2 Development Programmer/Debugger and PICkit 2 Debug Express

The PICkit[™] 2 Development Programmer/Debugger is a low-cost development tool with an easy to use interface for programming and debugging Microchip's Flash families of microcontrollers. The full featured Windows[®] programming interface supports baseline (PIC10F, PIC12F5xx, PIC16F5xx), midrange (PIC12F6xx, PIC16F), PIC18F, PIC24, dsPIC30, dsPIC33, and PIC32 families of 8-bit, 16-bit, and 32-bit microcontrollers, and many Microchip Serial EEPROM products. With Microchip's powerful MPLAB Integrated Development Environment (IDE) the PICkit[™] 2 enables in-circuit debugging on most PIC[®] microcontrollers. In-Circuit-Debugging runs, halts and single steps the program while the PIC microcontroller is embedded in the application. When halted at a breakpoint, the file registers can be examined and modified.

The PICkit 2 Debug Express include the PICkit 2, demo board and microcontroller, hookup cables and CDROM with user's guide, lessons, tutorial, compiler and MPLAB IDE software.

28.12 MPLAB PM3 Device Programmer

The MPLAB PM3 Device Programmer is a universal, CE compliant device programmer with programmable voltage verification at VDDMIN and VDDMAX for maximum reliability. It features a large LCD display (128 x 64) for menus and error messages and a modular, detachable socket assembly to support various package types. The ICSP™ cable assembly is included as a standard item. In Stand-Alone mode, the MPLAB PM3 Device Programmer can read, verify and program PIC devices without a PC connection. It can also set code protection in this mode. The MPLAB PM3 connects to the host PC via an RS-232 or USB cable. The MPLAB PM3 has high-speed communications and optimized algorithms for quick programming of large memory devices and incorporates an MMC card for file storage and data applications.

28.13 Demonstration/Development Boards, Evaluation Kits, and Starter Kits

A wide variety of demonstration, development and evaluation boards for various PIC MCUs and dsPIC DSCs allows quick application development on fully functional systems. Most boards include prototyping areas for adding custom circuitry and provide application firmware and source code for examination and modification.

The boards support a variety of features, including LEDs, temperature sensors, switches, speakers, RS-232 interfaces, LCD displays, potentiometers and additional EEPROM memory.

The demonstration and development boards can be used in teaching environments, for prototyping custom circuits and for learning about various microcontroller applications.

In addition to the PICDEM[™] and dsPICDEM[™] demonstration/development board series of circuits, Microchip has a line of evaluation kits and demonstration software for analog filter design, KEELOQ[®] security ICs, CAN, IrDA[®], PowerSmart battery management, SEEVAL[®] evaluation system, Sigma-Delta ADC, flow rate sensing, plus many more.

Also available are starter kits that contain everything needed to experience the specified device. This usually includes a single application and debug capability, all on one board.

Check the Microchip web page (www.microchip.com) for the complete list of demonstration, development and evaluation kits.

29.0 INSTRUCTION SET SUMMARY

Note:	This chapter is a brief summary of the						
	PIC24F instruction set architecture and is						
	not intended to be a comprehensive						
	reference source.						

The PIC24F instruction set adds many enhancements to the previous PIC[®] MCU instruction sets, while maintaining an easy migration from previous PIC MCU instruction sets. Most instructions are a single program memory word. Only three instructions require two program memory locations.

Each single-word instruction is a 24-bit word divided into an 8-bit opcode, which specifies the instruction type and one or more operands, which further specify the operation of the instruction. The instruction set is highly orthogonal and is grouped into four basic categories:

- Word or byte-oriented operations
- Bit-oriented operations
- · Literal operations
- Control operations

Table 29-1 shows the general symbols used in describing the instructions. The PIC24F instruction set summary in Table 29-2 lists all the instructions, along with the status flags affected by each instruction.

Most word or byte-oriented W register instructions (including barrel shift instructions) have three operands:

- The first source operand which is typically a register 'Wb' without any address modifier
- The second source operand which is typically a register 'Ws' with or without an address modifier
- The destination of the result which is typically a register 'Wd' with or without an address modifier

However, word or byte-oriented file register instructions have two operands:

- The file register specified by the value 'f'
- The destination, which could either be the file register 'f' or the W0 register, which is denoted as 'WREG'

Most bit-oriented instructions (including simple rotate/shift instructions) have two operands:

- The W register (with or without an address modifier) or file register (specified by the value of 'Ws' or 'f')
- The bit in the W register or file register (specified by a literal value or indirectly by the contents of register 'Wb')

The literal instructions that involve data movement may use some of the following operands:

- A literal value to be loaded into a W register or file register (specified by the value of 'k')
- The W register or file register where the literal value is to be loaded (specified by 'Wb' or 'f')

However, literal instructions that involve arithmetic or logical operations use some of the following operands:

- The first source operand which is a register 'Wb' without any address modifier
- The second source operand which is a literal value
- The destination of the result (only if not the same as the first source operand), which is typically a register 'Wd' with or without an address modifier

The control instructions may use some of the following operands:

- · A program memory address
- The mode of the table read and table write instructions

All instructions are a single word, except for certain double-word instructions, which were made double-word instructions so that all the required information is available in these 48 bits. In the second word, the 8 MSbs are '0's. If this second word is executed as an instruction (by itself), it will execute as a NOP.

Most single-word instructions are executed in a single instruction cycle, unless a conditional test is true or the program counter is changed as a result of the instruction. In these cases, the execution takes two instruction cycles, with the additional instruction cycle(s) executed as a NOP. Notable exceptions are the BRA (unconditional/computed branch), indirect CALL/GOTO, all table reads and writes, and RETURN/RETFIE instructions, which are single-word instructions but take two or three cycles.

Certain instructions that involve skipping over the subsequent instruction require either two or three cycles if the skip is performed, depending on whether the instruction being skipped is a single-word or two-word instruction. Moreover, double-word moves require two cycles. The double-word instructions execute in two instruction cycles.

TABLE 29-1: SYMBOLS USED IN OPCODE DESCRIPTIONS

Field	Description
#text	Means literal defined by "text"
(text)	Means "content of text"
[text]	Means "the location addressed by text"
{ }	Optional field or operation
<n:m></n:m>	Register bit field
.b	Byte mode selection
.d	Double-Word mode selection
.S	Shadow register select
.W	Word mode selection (default)
bit4	4-bit Bit Selection field (used in word addressed instructions) $\in \{015\}$
C, DC, N, OV, Z	MCU Status bits: Carry, Digit Carry, Negative, Overflow, Sticky Zero
Expr	Absolute address, label or expression (resolved by the linker)
f	File register address ∈ {0000h1FFFh}
lit1	1-bit unsigned literal $\in \{0,1\}$
lit4	4-bit unsigned literal ∈ {015}
lit5	5-bit unsigned literal ∈ {031}
lit8	8-bit unsigned literal ∈ {0255}
lit10	10-bit unsigned literal \in {0255} for Byte mode, {0:1023} for Word mode
lit14	14-bit unsigned literal ∈ {016383}
lit16	16-bit unsigned literal ∈ {065535}
lit23	23-bit unsigned literal \in {08388607}; LSB must be '0'
None	Field does not require an entry, may be blank
PC	Program Counter
Slit10	10-bit signed literal \in {-512511}
Slit16	16-bit signed literal ∈ {-3276832767}
Slit6	6-bit signed literal \in {-1616}
Wb	Base W register \in {W0W15}
Wd	Destination W register \in { Wd, [Wd], [Wd++], [Wd], [++Wd], [Wd] }
Wdo	Destination W register ∈ { Wnd, [Wnd], [Wnd++], [Wnd], [++Wnd], [Wnd], [Wnd+Wb] }
Wm,Wn	Dividend, Divisor working register pair (direct addressing)
Wn	One of 16 working registers ∈ {W0W15}
Wnd	One of 16 destination working registers ∈ {W0W15}
Wns	One of 16 source working registers \in {W0W15}
WREG	W0 (working register used in file register instructions)
Ws	Source W register ∈ { Ws, [Ws], [Ws++], [Ws], [++Ws], [Ws] }
Wso	Source W register ∈ { Wns, [Wns], [Wns++], [Wns], [++Wns], [Wns], [Wns+Wb] }

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
ADD	ADD	f	f = f + WREG	1	1	C, DC, N, OV, Z
	ADD	f,WREG	WREG = f + WREG	1	1	C, DC, N, OV, Z
	ADD	#lit10,Wn	Wd = lit10 + Wd	1	1	C, DC, N, OV, Z
	ADD	Wb,Ws,Wd	Wd = Wb + Ws	1	1	C, DC, N, OV, Z
	ADD	Wb,#lit5,Wd	Wd = Wb + lit5	1	1	C, DC, N, OV, Z
ADDC	ADDC	f	f = f + WREG + (C)	1	1	C, DC, N, OV, Z
	ADDC	f,WREG	WREG = f + WREG + (C)	1	1	C, DC, N, OV, Z
	ADDC	#lit10,Wn	Wd = lit10 + Wd + (C)	1	1	C, DC, N, OV, Z
	ADDC	Wb,Ws,Wd	Wd = Wb + Ws + (C)	1	1	C, DC, N, OV, Z
	ADDC	Wb,#lit5,Wd	Wd = Wb + lit5 + (C)	1	1	C, DC, N, OV, Z
AND	AND	f	f = f .AND. WREG	1	1	N, Z
	AND	f,WREG	WREG = f .AND. WREG	1	1	N, Z
	AND	#lit10,Wn	Wd = lit10 .AND. Wd	1	1	N, Z
	AND	Wb,Ws,Wd	Wd = Wb .AND. Ws	1	1	N, Z
	AND	Wb,#lit5,Wd	Wd = Wb .AND. lit5	1	1	N, Z
ASR	ASR	f	f = Arithmetic Right Shift f	1	1	C, N, OV, Z
	ASR	f,WREG	WREG = Arithmetic Right Shift f	1	1	C, N, OV, Z
	ASR	Ws,Wd	Wd = Arithmetic Right Shift Ws	1	1	C, N, OV, Z
	ASR	Wb, Wns, Wnd	Wnd = Arithmetic Right Shift Wb by Wns	1	1	N, Z
	ASR	Wb,#lit5,Wnd	Wnd = Arithmetic Right Shift Wb by lit5	1	1	N, Z
BCLR	BCLR	f,#bit4	Bit Clear f	1	1	None
	BCLR	Ws,#bit4	Bit Clear Ws	1	1	None
BRA	BRA	C,Expr	Branch if Carry	1	1 (2)	None
DRA	BRA	GE, Expr	Branch if Greater than or Equal	1	1 (2)	None
	BRA	GEU, Expr	Branch if Unsigned Greater than or Equal	1	1 (2)	None
	BRA	GT, Expr	Branch if Greater than	1	1 (2)	None
	BRA	GTU, Expr	Branch if Unsigned Greater than	1	1 (2)	None
	BRA	LE, Expr	Branch if Less than or Equal	1	1 (2)	None
	BRA	LEU, Expr	Branch if Unsigned Less than or Equal	1	1 (2)	None
	BRA		Branch if Less than	1	1 (2)	None
	BRA	LT, Expr LTU, Expr	Branch if Unsigned Less than	1		None
		· · · · ·		1	1 (2)	None
	BRA	N,Expr	Branch if Negative Branch if Not Carry	1	1 (2)	
	BRA	NC,Expr	,		1 (2)	None
	BRA	NN, Expr	Branch if Not Negative	1	1 (2)	None None
	BRA	NOV, Expr	Branch if Not Overflow	1	1 (2)	
	BRA	NZ,Expr	Branch if Not Zero	1	1 (2)	None
	BRA	OV,Expr	Branch if Overflow	1	1 (2)	None
	BRA	Expr	Branch Unconditionally	1	2	None
	BRA	Z,Expr	Branch if Zero	1	1 (2)	None
	BRA	Wn	Computed Branch	1	2	None
BSET	BSET	f,#bit4	Bit Set f	1	1	None
	BSET	Ws,#bit4	Bit Set Ws	1	1	None
BSW	BSW.C	Ws,Wb	Write C bit to Ws <wb></wb>	1	1	None
	BSW.Z	Ws,Wb	Write Z bit to Ws <wb></wb>	1	1	None
BTG	BTG	f,#bit4	Bit Toggle f	1	1	None
	BTG	Ws,#bit4	Bit Toggle Ws	1	1	None
BTSC	BTSC	f,#bit4	Bit Test f, Skip if Clear	1	1 (2 or 3)	None
	BTSC	Ws,#bit4	Bit Test Ws, Skip if Clear	1	1 (2 or 3)	None

TABLE 29-2:	INSTRUCTION SET OVERVIEW

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Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
BTSS	BTSS	f,#bit4	Bit Test f, Skip if Set	1	1 (2 or 3)	None
	BTSS	Ws,#bit4	Bit Test Ws, Skip if Set	1	1 (2 or 3)	None
BTST	BTST	f,#bit4	Bit Test f	1	1	Z
	BTST.C	Ws,#bit4	Bit Test Ws to C	1	1	С
	BTST.Z	Ws,#bit4	Bit Test Ws to Z	1	1	Z
	BTST.C	Ws,Wb	Bit Test Ws <wb> to C</wb>	1	1	С
	BTST.Z	Ws,Wb	Bit Test Ws <wb> to Z</wb>	1	1	Z
BTSTS	BTSTS	f,#bit4	Bit Test then Set f	1	1	Z
	BTSTS.C	Ws,#bit4	Bit Test Ws to C, then Set	1	1	С
	BTSTS.Z	Ws,#bit4	Bit Test Ws to Z, then Set	1	1	Z
CALL	CALL	lit23	Call Subroutine	2	2	None
	CALL	Wn	Call Indirect Subroutine	1	2	None
CLR	CLR	f	f = 0x0000	1	1	None
	CLR	WREG	WREG = 0x0000	1	1	None
	CLR	Ws	Ws = 0x0000	1	1	None
CLRWDT	CLRWDT		Clear Watchdog Timer	1	1	WDTO, Sleep
COM	COM	f	$f = \overline{f}$	1	1	N, Z
	СОМ	f,WREG	WREG = Ī	1	1	N, Z
	СОМ	Ws,Wd	$Wd = \overline{Ws}$	1	1	N, Z
CP	CP	f	Compare f with WREG	1	1	C, DC, N, OV, Z
CF	CP	Wb,#lit5	Compare Wb with lit5	1	1	C, DC, N, OV, Z
	CP	Wb,Ws	Compare Wb with Ws (Wb – Ws)	1	1	C, DC, N, OV, Z
CP0	CP0	f	Compare f with 0x0000	1	1	C, DC, N, OV, Z
CFU	CP0	¥ Ws	Compare Vs with 0x0000	1	1	C, DC, N, OV, Z
СРВ	CPB	f	Compare f with WREG, with Borrow	1	1	C, DC, N, OV, Z
CPB	CPB	Wb,#lit5	Compare Wb with lit5, with Borrow	1	1	C, DC, N, OV, Z
	CPB	Wb,Ws	Compare Wb with No, with Borrow $(Wb - Ws - \overline{C})$	1	1	C, DC, N, OV, Z
CPSEQ	CPSEQ	Wb,Wn	Compare Wb with Wn, Skip if =	1	1 (2 or 3)	None
CPSGT	CPSGT	Wb,Wn	Compare Wb with Wn, Skip if >	1	1 (2 or 3)	None
CPSLT	CPSLT	Wb,Wn	Compare Wb with Wn, Skip if <	1	1 (2 or 3)	None
CPSNE	CPSNE	Wb,Wn	Compare Wb with Wn, Skip if ≠	1	1 (2 or 3)	None
DAW	DAW.B	Wn	Wn = Decimal Adjust Wn	1	1	С
DEC	DEC	f	f = f -1	1	1	C, DC, N, OV, Z
	DEC	f,WREG	WREG = f –1	1	1	C, DC, N, OV, Z
	DEC	Ws,Wd	Wd = Ws - 1	1	1	C, DC, N, OV, Z
DEC2	DEC2	f	f = f - 2	1	1	C, DC, N, OV, Z
	DEC2	f,WREG	WREG = f – 2	1	1	C, DC, N, OV, Z
	DEC2	Ws,Wd	Wd = Ws - 2	1	1	C, DC, N, OV, Z
DISI	DISI	#lit14	Disable Interrupts for k Instruction Cycles	1	1	None
DIV	DIV.SW	Wm,Wn	Signed 16/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.SD	Wm,Wn	Signed 32/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.UW	Wm,Wn	Unsigned 16/16-bit Integer Divide	1	18	N, Z, C, OV
	DIV.UD	Wm,Wn	Unsigned 32/16-bit Integer Divide	1	18	N, Z, C, OV
EXCH	EXCH	Wns,Wnd	Swap Wns with Wnd	1	1	None
FF1L	FF1L	Ws,Wnd	Find First One from Left (MSb) Side	1	1	С
FF1R	FF1R	Ws,Wnd	Find First One from Right (LSb) Side	1	1	С

TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
GOTO	GOTO	Expr	Go to Address	2	2	None
	GOTO	Wn	Go to Indirect	1	2	None
INC	INC	f	f = f + 1	1	1	C, DC, N, OV, Z
	INC	f,WREG	WREG = f + 1	1	1	C, DC, N, OV, Z
	INC	Ws,Wd	Wd = Ws + 1	1	1	C, DC, N, OV, Z
INC2	INC2	f	f = f + 2	1	1	C, DC, N, OV, Z
	INC2	f,WREG	WREG = f + 2	1	1	C, DC, N, OV, Z
	INC2	Ws,Wd	Wd = Ws + 2	1	1	C, DC, N, OV, Z
IOR	IOR	f	f = f .IOR. WREG	1	1	N, Z
	IOR	f,WREG	WREG = f.IOR. WREG	1	1	N, Z
	IOR	#lit10,Wn	Wd = lit10 .IOR. Wd	1	1	N, Z
	IOR	Wb,Ws,Wd	Wd = Wb .IOR. Ws	1	1	N, Z
	IOR	Wb,#lit5,Wd	Wd = Wb .IOR. lit5	1	1	N, Z
LNK	LNK	#lit14	Link Frame Pointer	1	1	None
LSR	LSR	f	f = Logical Right Shift f	1	1	C, N, OV, Z
	LSR	f,WREG	WREG = Logical Right Shift f	1	1	C, N, OV, Z
	LSR	Ws,Wd	Wite Colleged Right Shift Ws	1	1	C, N, OV, Z
	LSR	Wb,Wns,Wnd	Wnd = Logical Right Shift Wb by Wns	1	1	N, Z
	LSR	Wb,#lit5,Wnd	Wnd = Logical Right Shift Wb by lit5	1	1	N, Z
MOV	MOV	f,Wn	Move f to Wn	1	1	None
110 V	MOV	[Wns+Slit10],Wnd	Move [Wns+Slit10] to Wnd	1	1	None
	MOV	f	Move [tviis sairio] to wild	1	1	N, Z
		f,WREG	Move f to WREG	1	1	N, Z
	MOV		Move 16-bit Literal to Wn	1	1	None
	MOV	#lit16,Wn		1	1	
	MOV.b	#lit8,Wn	Move 8-bit Literal to Wn	1	1	None
	MOV	Wn,f	Move Wn to f	1	1	None
	MOV	Wns,[Wns+Slit10]	Move Wns to [Wns+Slit10]			None
	MOV	Wso,Wdo	Move Ws to Wd	1	1	None
	MOV	WREG, f	Move WREG to f	1	1	N, Z
	MOV.D	Wns,Wd	Move Double from W(ns):W(ns+1) to Wd	1	2	None
	MOV.D	Ws,Wnd	Move Double from Ws to W(nd+1):W(nd)	1	2	None
MUL	MUL.SS	Wb,Ws,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Signed(Ws)	1	1	None
	MUL.SU	Wb,Ws,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(Ws)	1	1	None
	MUL.US	Wb,Ws,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Signed(Ws)	1	1	None
	MUL.UU	Wb,Ws,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(Ws)	1	1	None
	MUL.SU	Wb,#lit5,Wnd	{Wnd+1, Wnd} = Signed(Wb) * Unsigned(lit5)	1	1	None
	MUL.UU	Wb,#lit5,Wnd	{Wnd+1, Wnd} = Unsigned(Wb) * Unsigned(lit5)	1	1	None
	MUL	f	W3:W2 = f * WREG	1	1	None
NEG	NEG	f	$f = \overline{f} + 1$	1	1	C, DC, N, OV, Z
	NEG	f,WREG	WREG = \overline{f} + 1	1	1	C, DC, N, OV, Z
	NEG	Ws,Wd	$Wd = \overline{Ws} + 1$	1	1	C, DC, N, OV, Z
NOP	NOP		No Operation	1	1	None
	NOPR		No Operation	1	1	None
POP	POP	f	Pop f from Top-of-Stack (TOS)	1	1	None
	POP	Wdo	Pop from Top-of-Stack (TOS) to Wdo	1	1	None
	POP.D	Wnd	Pop from Top-of-Stack (TOS) to W(nd):W(nd+1)	1	2	None
	POP.S		Pop Shadow Registers	1	1	All
PUSH	PUSH	f	Push f to Top-of-Stack (TOS)	1	1	None
	PUSH	Wso	Push Wso to Top-of-Stack (TOS)	1	1	None
	PUSH.D	Wns	Push W(ns):W(ns+1) to Top-of-Stack (TOS)	1	2	None
	1 0011.0		Push Shadow Registers	1	1	None

TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)

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TABLE 29-2:	INSTRUCTION SET OVERVIEW	(CONTINUED)

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected
PWRSAV	PWRSAV	#lit1	Go into Sleep or Idle mode	1	1	WDTO, Sleep
RCALL	RCALL	Expr	Relative Call	1	2	None
	RCALL	Wn	Computed Call	1	2	None
REPEAT	REPEAT	#lit14	Repeat Next Instruction lit14 + 1 times	1	1	None
	REPEAT	Wn	Repeat Next Instruction (Wn) + 1 times	1	1	None
RESET	RESET		Software Device Reset	1	1	None
RETFIE	RETFIE		Return from Interrupt	1	3 (2)	None
RETLW	RETLW	#lit10,Wn	Return with Literal in Wn	1	3 (2)	None
RETURN	RETURN		Return from Subroutine	1	3 (2)	None
RLC	RLC	f	f = Rotate Left through Carry f	1	1	C, N, Z
	RLC	f,WREG	WREG = Rotate Left through Carry f	1	1	C, N, Z
	RLC	Ws,Wd	Wd = Rotate Left through Carry Ws	1	1	C, N, Z
RLNC	RLNC	f	f = Rotate Left (No Carry) f	1	1	N, Z
	RLNC	f,WREG	WREG = Rotate Left (No Carry) f	1	1	N, Z
	RLNC	Ws,Wd	Wd = Rotate Left (No Carry) Ws	1	1	N, Z
RRC	RRC	f	f = Rotate Right through Carry f	1	1	C, N, Z
	RRC	f,WREG	WREG = Rotate Right through Carry f	1	1	C, N, Z
	RRC	Ws,Wd	Wd = Rotate Right through Carry Ws	1	1	C, N, Z
RRNC	RRNC	f	f = Rotate Right (No Carry) f	1	1	N, Z
	RRNC	f,WREG	WREG = Rotate Right (No Carry) f	1	1	N, Z
	RRNC	Ws,Wd	Wd = Rotate Right (No Carry) Ws	1	1	N, Z
SE	SE	Ws,Wnd	Wnd = Sign-Extended Ws	1	1	C, N, Z
SETM	SETM	f	f = FFFFh	1	1	None
	SETM	WREG	WREG = FFFFh	1	1	None
	SETM	Ws	Ws = FFFFh	1	1	None
SL	SL	f	f = Left Shift f	1	1	C, N, OV, Z
	SL	f,WREG	WREG = Left Shift f	1	1	C, N, OV, Z
	SL	Ws,Wd	Wd = Left Shift Ws	1	1	C, N, OV, Z
	SL	Wb,Wns,Wnd	Wnd = Left Shift Wb by Wns	1	1	N, Z
	SL	Wb,#lit5,Wnd	Wnd = Left Shift Wb by lit5	1	1	N, Z
SUB	SUB	f	f = f – WREG	1	1	C, DC, N, OV, Z
	SUB	f,WREG	WREG = f – WREG	1	1	C, DC, N, OV, Z
	SUB	#lit10,Wn	Wn = Wn – lit10	1	1	C, DC, N, OV, Z
	SUB	Wb,Ws,Wd	Wd = Wb – Ws	1	1	C, DC, N, OV, Z
	SUB	Wb,#lit5,Wd	Wd = Wb – lit5	1	1	C, DC, N, OV, Z
SUBB	SUBB	f	$f = f - WREG - (\overline{C})$	1	1	C, DC, N, OV, Z
	SUBB	f,WREG	WREG = f – WREG – (\overline{C})	1	1	C, DC, N, OV, Z
	SUBB	#lit10,Wn	Wn = Wn - lit10 - (\overline{C})	1	1	C, DC, N, OV, Z
	SUBB	Wb,Ws,Wd	$Wd = Wb - Ws - (\overline{C})$	1	1	C, DC, N, OV, Z
	SUBB	Wb,#lit5,Wd	$Wd = Wb - lit5 - (\overline{C})$	1	1	C, DC, N, OV, Z
SUBR	SUBR	f	f = WREG - f	1	1	C, DC, N, OV, Z
DODIC	SUBR	f,WREG	WREG = WREG – f	1	1	C, DC, N, OV, Z
	SUBR	Wb,Ws,Wd	Wd = Ws – Wb	1	1	C, DC, N, OV, Z
	SUBR	Wb,#lit5,Wd	Wd = lit5 – Wb	1	1	C, DC, N, OV, Z
SUBBR						
	SUBBR	f	$f = WREG - f - (\overline{C})$	1	1	C, DC, N, OV, Z
	SUBBR	f,WREG	WREG = WREG – f – (\overline{C})	1	1	C, DC, N, OV, Z
	SUBBR	Wb,Ws,Wd	Wd = Ws - Wb - (C)	1	1	C, DC, N, OV, Z
	SUBBR	Wb,#lit5,Wd	$Wd = lit5 - Wb - (\overline{C})$	1	1	C, DC, N, OV, Z
SWAP	SWAP.b	Wn	Wn = Nibble Swap Wn	1	1	None
	SWAP	Wn	Wn = Byte Swap Wn	1	1	None
TBLRDH	TBLRDH	Ws,Wd	Read Prog<23:16> to Wd<7:0>	1	2	None

Assembly Mnemonic		Assembly Syntax	Description	# of Words	# of Cycles	Status Flags Affected		
TBLRDL	TBLRDL	Ws,Wd	Read Prog<15:0> to Wd	1	2	None		
TBLWTH	TBLWTH	Ws,Wd	Write Ws<7:0> to Prog<23:16>	1	2	None		
TBLWTL	TBLWTL	Ws,Wd	Write Ws to Prog<15:0>	1	2	None		
ULNK	ULNK		Unlink Frame Pointer	1	1	None		
XOR	XOR	f	f = f .XOR. WREG	1	1	N, Z		
	XOR	f,WREG	WREG = f .XOR. WREG	1	1	N, Z		
	XOR	#lit10,Wn	Wd = lit10 .XOR. Wd	1	1	N, Z		
	XOR	Wb,Ws,Wd	Wd = Wb .XOR. Ws	1	1	N, Z		
	XOR	Wb,#lit5,Wd	Wd = Wb .XOR. lit5	1	1	N, Z		
ZE	ZE	Ws,Wnd	Wnd = Zero-Extend Ws	1	1	C, Z, N		

TABLE 29-2: INSTRUCTION SET OVERVIEW (CONTINUED)

NOTES:

30.0 ELECTRICAL CHARACTERISTICS

This section provides an overview of the PIC24FJ256DA210 family electrical characteristics. Additional information will be provided in future revisions of this document as it becomes available.

Absolute maximum ratings for the PIC24FJ256DA210 family are listed below. Exposure to these maximum rating conditions for extended periods may affect device reliability. Functional operation of the device at these, or any other conditions above the parameters indicated in the operation listings of this specification, is not implied.

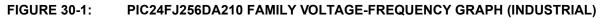
Absolute Maximum Ratings^(†)

Ambient temperature under bias	40°C to +100°C
Storage temperature	
Voltage on VDD with respect to Vss	-0.3V to +4.0V
Voltage on any combined analog and digital pin and MCLR, with respect to Vss	0.3V to (VDD + 0.3V)
Voltage on any digital only pin with respect to Vss when VDD < 3.0V	0.3V to (VDD + 0.3V)
Voltage on any digital only pin with respect to Vss when VDD > 3.0V	0.3V to (+5.5V)
Voltage on VBUS pin with respect to VSS, independent of VDD or VUSB	0.3V to (+5.5V)
Maximum current out of Vss pin	300 mA
Maximum current into VDD pin (Note 1)	250 mA
Maximum output current sunk by any I/O pin	25 mA
Maximum output current sourced by any I/O pin	25 mA
Maximum current sunk by all ports	200 mA
Maximum current sourced by all ports (Note 1)	200 mA
Note 4. Maximum allowable summatic a function of device maximum neuron discipation	r (as a Table 20.1)

Note 1: Maximum allowable current is a function of device maximum power dissipation (see Table 30-1).

†NOTICE: Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability.

30.1 DC Characteristics



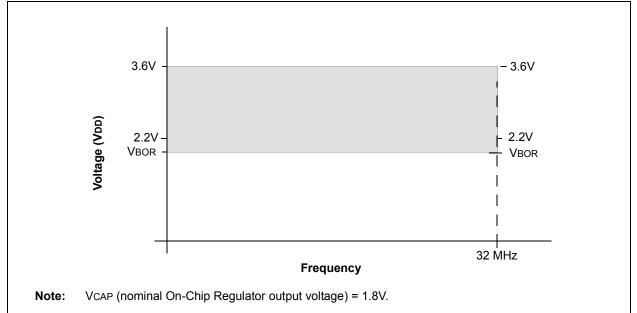


TABLE 30-1: THERMAL OPERATING CONDITIONS

Rating		Min	Тур	Мах	Unit
PIC24FJ256DA210 family:					
Operating Junction Temperature Range	TJ	-40	_	+125	°C
Operating Ambient Temperature Range	TA	-40	—	+85	°C
Power Dissipation (with ENVREG = 1): Internal Chip Power Dissipation: $PINT = VDD \times (IDD - \Sigma IOH)$ I/O Pin Power Dissipation:	PD	PINT + PI/O		W	
$PI/O = \Sigma (\{VDD - VOH\} \times IOH) + \Sigma (VOL \times IOL)$					
Maximum Allowed Power Dissipation	PDMAX	(TJ	max – Ta)/	θJA	W

TABLE 30-2: THERMAL PACKAGING CHARACTERISTICS

Characteristic	Symbol	Тур	Мах	Unit	Note
Package Thermal Resistance, 12x12x1 mm TQFP	θJA	69.4		°C/W	(Note 1)
Package Thermal Resistance, 10x10x1 mm TQFP	θJA	76.6	_	°C/W	(Note 1)
Package Thermal Resistance, 9x9x0.9 mm QFN	θJA	28.0	_	°C/W	(Note 1)
Package Thermal Resistance, 10x10x1.1 mm BGA	θJA	40.2	_	°C/W	(Note 1)

Note 1: Junction to ambient thermal resistance, Theta-JA (θ JA) numbers are achieved by package simulations.

DC CH	ARACTER	ISTICS		$\begin{array}{llllllllllllllllllllllllllllllllllll$				
Param No.	Symbol	Characteristic	Min	Тур	Max	Units	Conditions	
Operati	ing Voltag	e						
DC10	Supply V	oltage						
	Vdd		VBOR	—	3.6	V	Regulator enabled	
	VCAP ⁽²⁾		—	1.8V	_	V	Regulator enabled	
DC12	Vdr	RAM Data Retention Voltage ⁽¹⁾	1.5	—	_	V		
DC16	Vpor	VDD Start Voltage to Ensure Internal Power-on Reset Signal	Vss	—	_	V		
DC17	SVDD	VDD Rise Rate to Ensure Internal Power-on Reset Signal	0.05	—	_	V/ms	0-3.3V in 66 ms 0-2.5V in 50 ms	
	VBOR	Brown-out Reset Voltage on VDD Transition, High-to-Low	2.0	2.10	2.2	V	Regulator enabled	
	Vlvd	LVD Trip Voltage	_	VBOR + 0.10	_	V		

Note 1: This is the limit to which the RAM data can be retained, while the on-chip regulator output voltage starts following the VDD.

2: This is the on-chip regulator output voltage specification.

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DC CHARACT	ERISTICS		Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial					
Parameter No.	Typical ⁽¹⁾	Мах	Units	Conditions				
Operating Cur	rent (IDD) ⁽²⁾							
DC20D	0.8	1.3	mA	-40°C				
DC20E	0.8	1.3	mA	+25°C	3.3∨ ⁽³⁾	1 MIPS		
DC20F	0.8	1.3	mA	+85°C				
DC23D	3.0	4.8	mA	-40°C		4 MIPS		
DC23E	3.0	4.8	mA	+25°C	3.3∨ ⁽³⁾			
DC23F	3.0	4.8	mA	+85°C				
DC24D	12.0	18	mA	-40°C				
DC24E	12.0	18	mA	+25°C	3.3∨ ⁽³⁾	16 MIPS		
DC24F	12.0	18	mA	+85°C				
DC31D	55	95	μA	-40°C				
DC31E	55	95	μA	+25°C	3.3∨ ⁽³⁾	LPRC (31 kHz)		
DC31F	135	225	μA	+85°C				

TABLE 30-4: DC CHARACTERISTICS: OPERATING CURRENT (IDD)

Note 1: Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: The supply current is mainly a function of the operating voltage and frequency. Other factors, such as I/O pin loading and switching rate, oscillator type, internal code execution pattern and temperature, also have an impact on the current consumption. The test conditions for all IDD measurements are as follows: OSCI driven with external square wave from rail to rail. All I/O pins are configured as inputs and pulled to VDD. MCLR = VDD; WDT and FSCM are disabled. CPU, SRAM, program memory and data memory are operational. No peripheral modules are operating and all of the Peripheral Module Disable (PMD) bits are set.

3: On-chip voltage regulator enabled (ENVREG tied to VDD). Brown-out Reset (BOR) is enabled.

DC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial						
Parameter No.	Typical ⁽¹⁾	Мах	Units	Conditions					
Idle Current (IIDLE) ⁽²⁾								
DC40D	170	320	μA	-40°C					
DC40E	170	320	μA	+25°C	3.3∨ ⁽³⁾	1 MIPS			
DC40F	220	380	μA	+85°C					
DC43D	0.6	1.2	mA	-40°C					
DC43E	0.6	1.2	mA	+25°C	3.3∨ ⁽³⁾	4 MIPS			
DC43F	0.7	1.2	mA	+85°C					
DC47D	2.3	4.8	mA	-40°C					
DC47E	2.3	4.8	mA	+25°C	3.3∨ ⁽³⁾	16 MIPS			
DC47F	2.4	4.8	mA	+85°C					
DC50D	0.8	1.8	mA	-40°C		FRC (4 MIPS)			
DC50E	0.8	1.8	mA	+25°C	3.3∨ ⁽³⁾				
DC50F	1.0	1.8	mA	+85°C	7				
DC51D	40.0	85	μA	-40°C		LPRC (31 kHz)			
DC51E	40.0	85	μA	+25°C	3.3∨ ⁽³⁾				
DC51F	120.0	210	μA	+85°C	7				

TABLE 30-5: DC CHARACTERISTICS: IDLE CURRENT (IIDLE)

Note 1: Data in "Typical" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: Base IIDLE current is measured with the core off; OSCI driven with external square wave from rail to rail. All I/O pins are configured as inputs and pulled to VDD. MCLR = VDD; WDT and FSCM are disabled. No peripheral modules are operating and all of the Peripheral Module Disable (PMD) bits are set.

3: On-chip voltage regulator enabled (ENVREG tied to VDD). Brown-out Reset (BOR) is enabled.

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TABLE 30-6: DC CHARACTERISTICS: POWER-DOWN CURRENT (IPD)

DC CHARACTERISTICS			$\begin{array}{llllllllllllllllllllllllllllllllllll$						
Parameter No.	Typical ⁽¹⁾	Max	Units	Jnits Conditions					
Power-Down	Current (IPD) ⁽	2)	•	•					
DC60D	20.0	45	μA	-40°C					
DC60E	20.0	45	μA	+25°C	3.3∨ ⁽³⁾	Base power-down current ⁽⁴⁾			
DC60H	55.0	105	μA	+60°C	3.30(*)	Base power-down current			
DC60F	95.0	185	μA	+85°C					
DC61D	1.0	3.5	μA	-40°C					
DC61E	1.0	3.5	μA	+25°C	3.3∨ ⁽³⁾	31 kHz LPRC oscillator with RTCC, WDT or Timer1:∆lLPRC ⁽⁴⁾			
DC61H	1.0	3.5	μA	+60°C	3.30(*)				
DC61F	2.5	6.5	μA	+85°C					
DC62D	1.5	6	μA	-40°C					
DC62E	1.5	6	μA	+25°C	3.3∨ ⁽³⁾	Low drive strength, 32 kHz crystal with RTCC or Timer1: Δ Isosc;			
DC62H	1.5	6	μA	+60°C	3.30	SOSCSEL<1:0> = $01^{(4)}$			
DC62F	8.0	18	μA	+85°C					
DC63D	4.0	18	μA	-40°C					
DC63E	4.0	18	μA	+25°C	3.3∨ (3)	32 kHz crystal			
DC63H	6.5	18	μA	+60°C	3.30(0)	with RTCC or Timer1: Δ Isosc; SOSCSEL<1:0> = 11 ⁽⁴⁾			
DC63F	12.0	25	μA	+85°C					

Note 1: Data in the Typical column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: Base IPD is measured with the device in Sleep mode (all peripherals and clocks are shut down). All I/Os are configured as inputs and pulled high. WDT, etc., are all switched off, PMSLP bit is clear and the Peripheral Module Disable (PMD) bits for all unused peripherals are set.

3: On-chip voltage regulator enabled (ENVREG tied to VDD). Brown-out Reset (BOR) is enabled.

4: The △ current is the additional current consumed when the module is enabled. This current should be added to the base IPD current.

							V (unless otherwise
			Operating tempe	erature	$-40^{\circ}C \le T$	A ≤ +85°	C for Industrial
Param No.	Symbo I	Characteristic	Min	Typ ⁽¹⁾	Мах	Units	Conditions
	VIL	Input Low Voltage ⁽³⁾					
DI10		I/O Pins with ST Buffer	Vss		0.2 VDD	V	
DI11		I/O Pins with TTL Buffer	Vss		0.15 VDD	V	
DI15		MCLR	Vss		0.2 VDD	V	
DI16		OSCI (XT mode)	Vss	_	0.2 VDD	V	
DI17		OSCI (HS mode)	Vss		0.2 VDD	V	
DI18		I/O Pins with I ² C™ Buffer:	Vss	_	0.3 VDD	V	
DI19		I/O Pins with SMBus Buffer:	Vss		0.8	V	SMBus enabled
	Vih	Input High Voltage ⁽³⁾					
DI20		I/O Pins with ST Buffer: with Analog Functions, Digital Only	0.8 Vdd 0.8 Vdd	—	Vdd 5.5	V V	
DI21		I/O Pins with TTL Buffer: with Analog Functions, Digital Only	0.25 Vdd + 0.8 0.25 Vdd + 0.8	—	Vdd 5.5	V V	
DI25		MCLR	0.8 VDD	_	Vdd	V	
DI26		OSCI (XT mode)	0.7 Vdd		Vdd	V	
DI27		OSCI (HS mode)	0.7 Vdd	_	Vdd	V	
DI28		I/O Pins with I ² C™ Buffer: with Analog Functions, Digital Only	0.7 Vdd 0.7 Vdd		VDD 5.5	V V	
DI29		I/O Pins with SMBus Buffer: with Analog Functions, Digital Only	2.1 2.1		VDD 5.5	V V	$2.5V \le VPIN \le VDD$
DI30	ICNPU	CNxx Pull-up Current	150	350	550	μA	VDD = 3.3V, VPIN = VSS
DI30A	ICNPD	CNxx Pull-down Current	15	70	150	μA	VDD = 3.3V, VPIN = VDD
	lı∟	Input Leakage Current ⁽²⁾					
DI50		I/O Ports	_	_	<u>+</u> 1	μΑ	$Vss \le VPIN \le VDD$, pin at high-impedance
DI51		Analog Input Pins	_	_	<u>+</u> 1	μΑ	$Vss \le VPIN \le VDD,$ pin at high-impedance
DI55		MCLR	—	—	<u>+</u> 1	μA	$Vss \leq V \text{PIN} \leq V \text{DD}$
DI56		OSCI/CLKI	_	_	<u>+</u> 1	μA	$VSS \le VPIN \le VDD,$ EC, XT and HS modes

TABLE 30-7: DC CHARACTERISTICS: I/O PIN INPUT SPECIFICATIONS

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

2: Negative current is defined as current sourced by the pin.

3: Refer to Table 1-1 for I/O pins buffer types.

DC CH	ARACTE	RISTICS	$\begin{array}{llllllllllllllllllllllllllllllllllll$					
Param No.	Symbol	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Conditions	
	Vol	Output Low Voltage						
DO10		I/O Ports	_	_	0.4	V	IOL = 6.6 mA, VDD = 3.6V	
			—	—	0.4	V	IOL = 5.0 mA, VDD = 2.2V	
DO16		OSCO/CLKO	_	_	0.4	V	IOL = 6.6 mA, VDD = 3.6V	
			_	_	0.4	V	IOL = 5.0 mA, VDD = 2.2V	
	Vон	Output High Voltage						
DO20		I/O Ports	3.0	—	—	V	Іон = -3.0 mA, Vdd = 3.6V	
			2.4	—	—	V	ІОН = -6.0 mA, VDD = 3.6V	
			1.65	—	—	V	Іон = -1.0 mA, Vdd = 2.2V	
			1.4	_	—	V	Іон = -3.0 mA, Vdd = 2.2V	
DO26		OSCO/CLKO	2.4	—	_	V	Iон = -6.0 mA, Vdd = 3.6V	
			1.4	_	_	V	Iон = -1.0 mA, Vdd = 2.2V	

TABLE 30-8: DC CHARACTERISTICS: I/O PIN OUTPUT SPECIFICATIONS

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

TABLE 30-9: DC CHARACTERISTICS: PROGRAM MEMORY

DC CHARACTERISTICS			stated)	d Operat ng tempe	•	nditions: 2.2V to 3.6V (unless otherwise $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial		
Param No.	Symbol	Characteristic	Min Typ ⁽¹⁾ Max			Units	Conditions	
		Program Flash Memory						
D130	Eр	Cell Endurance	10000		_	E/W	-40°C to +85°C	
D131	Vpr	VDD for Read	VMIN	_	3.6	V	VMIN = Minimum operating voltage	
D132B		VDD for Self-Timed Write	VMIN		3.6	V	VMIN = Minimum operating voltage	
D133A	Tiw	Self-Timed Word Write Cycle Time	—	20	—	μS		
		Self-Timed Row Write Cycle Time	—	1.5	—	ms		
D133B	TIE	Self-Timed Page Erase Time	20	—	40	ms		
D134	TRETD	Characteristic Retention	20	—	—	Year	If no other specifications are violated	
D135	IDDP	Supply Current during Programming	—	16	—	mA		

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

TABLE 30-10: INTERNAL VOLTAGE REGULATOR SPECIFICATIONS

Operati	Operating Conditions: -40°C < TA < +85°C (unless otherwise stated)								
Param No.	Symbol	Characteristics	Min	Тур	Max	Units	Comments		
	Vrgout	Regulator Output Voltage		1.8	—	V			
	Vbg	Internal Band Gap Reference		1.2	—	V			
	Cefc	External Filter Capacitor Value	4.7	10	_	μF	Series resistance < 3 Ohm recommended; < 5 Ohm required.		
	TVREG		—	10	_	μS	VREGS = 1, VREGS = 0 with WUTSEL<1:0> = 01 or any POR or BOR		
			_	190	_	μS	Sleep wake-up with VREGS = 0 and WUTSEL<1:0> = 11		
	Tbg	Band Gap Reference Start-up Time		1	—	ms			

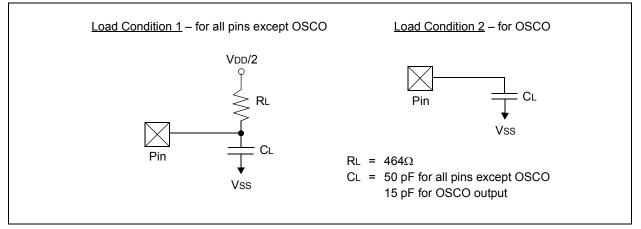
30.2 AC Characteristics and Timing Parameters

The information contained in this section defines the PIC24FJ256DA210 family AC characteristics and timing parameters.

TABLE 30-11: TEMPERATURE AND VOLTAGE SPECIFICATIONS - AC

	Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)
AC CHARACTERISTICS	Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial
	Operating voltage VDD range as described in Section 30.1 "DC Characteristics".

FIGURE 30-2: LOAD CONDITIONS FOR DEVICE TIMING SPECIFICATIONS

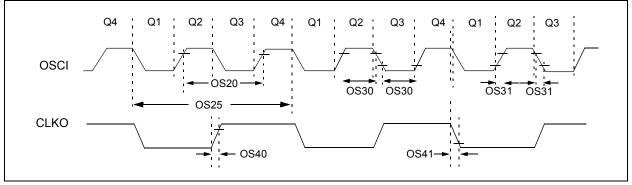


Param No.	Symbol	Characteristic	Min	Typ ⁽¹⁾	Max	Units	Conditions
DO50	Cosco	OSCO/CLKO Pin	_		15	pF	In XT and HS modes when external clock is used to drive OSCI
DO56	Сю	All I/O Pins and OSCO	—	_	50	pF	EC mode
DO58	Св	SCLx, SDAx		—	400	pF	In I ² C™ mode

TABLE 30-12: CAPACITIVE LOADING REQUIREMENTS ON OUTPUT PINS

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

FIGURE 30-3: EXTERNAL CLOCK TIMING



AC CH	ARACTE	RISTICS		Standard Operating Conditions: 2.2V to 3.6V (unless otherwiseOperating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial			
Param No.	Symbol	Characteristic	Min	Typ ⁽¹⁾	Мах	Units	Conditions
OS10	Fosc	External CLKI Frequency (External clocks allowed only in EC mode)	DC 4		32 48	MHz MHz	EC ECPLL
		Oscillator Frequency	3.5 4 10 10 31		10 8 32 32 33	MHz MHz MHz MHz kHz	XT XTPLL HS HSPLL SOSC
OS20	Tosc	Tosc = 1/Fosc	—	_	_	—	See parameter OS10 for Fosc value
OS25	Тсү	Instruction Cycle Time ⁽²⁾	62.5		DC	ns	
OS30	TosL, TosH	External Clock in (OSCI) High or Low Time	0.45 x Tosc	_	_	ns	EC
OS31	TosR, TosF	External Clock in (OSCI) Rise or Fall Time	—	—	20	ns	EC
OS40	TckR	CLKO Rise Time ⁽³⁾	—	6	10	ns	
OS41	TckF	CLKO Fall Time ⁽³⁾	—	6	10	ns	

TABLE 30-13: EXTERNAL CLOCK TIMING REQUIREMENTS

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

- 2: Instruction cycle period (Tcr) equals two times the input oscillator time base period. All specified values are based on characterization data for that particular oscillator type under standard operating conditions with the device executing code. Exceeding these specified limits may result in an unstable oscillator operation and/or higher than expected current consumption. All devices are tested to operate at "Min." values with an external clock applied to the OSCI/CLKI pin. When an external clock input is used, the "Max." cycle time limit is "DC" (no clock) for all devices.
- **3:** Measurements are taken in EC mode. The CLKO signal is measured on the OSCO pin. CLKO is low for the Q1-Q2 period (1/2 TCY) and high for the Q3-Q4 period (1/2 TCY).

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise statedOperating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial						
Param No.	Symbol	ymbol Characteristic ⁽¹⁾	Min	Тур ⁽²⁾	Мах	Units	Conditions		
OS50	Fplli	PLL Input Frequency	4	—	48	MHz	ECPLL mode		
	Range ⁽²⁾	4		32	MHz	HSPLL mode			
			4		8	MHz	XTPLL mode		
OS51	Fsys	PLL Output Frequency Range	95.76	—	96.24	MHz			
OS52	TLOCK	PLL Start-up Time (Lock Time)	_	—	200	μS			
OS53	DCLK	CLKO Stability (Jitter)	-0.25		0.25	%			

TARI E 30-14.	PLL CLOCK TIMING SPECIFICATIONS	$(V_{DD} = 2.2V TO 3.6V)$
IADLL 30-14.	FLE GLOCK HIMING SFLCII IGATIONS	(VDD - Z.ZV O J.OV)

Note 1: These parameters are characterized but not tested in manufacturing.

2: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated. Parameters are for design guidance only and are not tested.

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TABLE 30-15: INTERNAL RC ACCURACY

AC CHA		Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial						
Param No.	Min	Тур	Max	Units	Conditions			
F20	FRC Accuracy @ 8 MHz ^(1,2)	-1	±0.15	1	%	$-40^{\circ}C \leq Ta \leq +85^{\circ}C 2.2V \leq VDD \leq 3.6V$		
F21	-20	_	20	%	$-40^\circ C \le T A \le +85^\circ C$	VCAP (on-chip regulator output voltage) = 1.8V		

Frequency calibrated at 25°C and 3.3V. OSCTUN bits can be used to compensate for temperature drift.
 To achieve this accuracy, physical stress applied to the microcontroller package (ex., by flexing the PCB) must be kept to a minimum.

TABLE 30-16: RC OSCILLATOR START-UP TIME

AC CHA			Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial						
Param No.	Characteristic	Min	Тур	Мах	Units	Conditions			
	TFRC		15	_	μS				
	TLPRC		50	_	μS				

TABLE 30-17: RESET AND BROWN-OUT RESET REQUIREMENTS

AC CHARACTERISTICS			$\begin{array}{llllllllllllllllllllllllllllllllllll$						
Param No. Symbol Characteristic			Min	Тур	Мах	Units	Conditions		
SY10	TMCL	MCLR Pulse width (Low)	2	_		μs			
SY12	TPOR	Power-on Reset Delay		2	_	μs			
SY13	Tioz	I/O High-Impedance from MCLR Low or Watchdog Timer Reset	—	—	100	ns			
SY25 TBOR Brown-out Reset Pulse Width		1	_	_	μs	$V D D \leq V B O R$			
	Trst	Internal State Reset Time	_	50		μs			



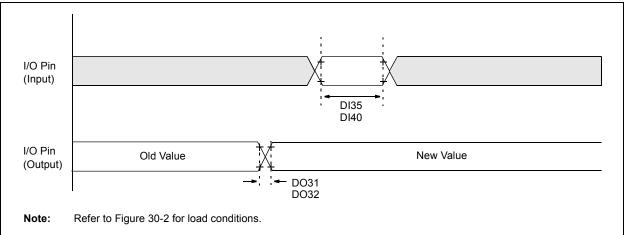


TABLE 30-18: CLKO AND I/O TIMING REQUIREMENTS

			stated)	Standard Operating Conditions: 2.2V to 3.6V (unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$ for Industrial						
Param No. Symbol Characteristic			Min	Typ ⁽¹⁾	Max	Units	Conditions			
DO31	TIOR	Port Output Rise Time	_	10	25	ns				
DO32	TIOF	Port Output Fall Time	_	10	25	ns				
DI35 TINP INTx Pin High or Low Time (input)		20	—	—	ns					
DI40 TRBP CNx High or Low Time (input)			2	—	—	Тсү				

Note 1: Data in "Typ" column is at 3.3V, 25°C unless otherwise stated.

TABLE 30-19: ADC MODULE SPECIFICATIONS

AC CH	ARACTERI	STICS	Standard O (unless oth Operating te	erwise s		: 2.2V to ≤ Ta ≤ +8	
Param No.	Symbol	Characteristic	Min.	Тур	Max.	Units	Conditions
			Device \$	Supply			
AD01	AVDD	Module VDD Supply	Greater of VDD – 0.3 or 2.2		Lesser of VDD + 0.3 or 3.6	V	
AD02	AVss	Module Vss Supply	Vss - 0.3	_	Vss + 0.3	V	
			Reference	e Inputs			
AD05	VREFH	Reference Voltage High	AVss + 1.7	_	AVDD	V	
AD06	VREFL	Reference Voltage Low	AVss	_	AVDD - 1.7	V	
AD07	VREF	Absolute Reference Voltage	AVss – 0.3		AVDD + 0.3	V	
			Analog	Input			
AD10	VINH-VINL	Full-Scale Input Span	VREFL		VREFH	V	(Note 2)
AD11	Vin	Absolute Input Voltage	AVss - 0.3		AVDD + 0.3	V	
AD12	VINL	Absolute VINL Input Voltage	AVss – 0.3		AVDD/2	V	
AD13		Leakage Current	_	±1.0	±610	nA	VINL = AVSS = VREFL = 0V, AVDD = VREFH = $3V$, Source Impedance = $2.5 \text{ k}\Omega$
AD17	Rin	Recommended Impedance of Analog Voltage Source	—	_	2.5K	Ω	10-bit
			ADC Ac	curacy			·
AD20B	Nr	Resolution	_	10	_	bits	
AD21B	INL	Integral Nonlinearity	—	±1	<±2	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD22B	DNL	Differential Nonlinearity	—	±0.5	<±1	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD23B	Gerr	Gain Error	—	±1	±3	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD24B	EOFF	Offset Error	—	±1	±2	LSb	VINL = AVSS = VREFL = 0V, AVDD = VREFH = 3V
AD25B		Monotonicity ⁽¹⁾	_	_	_	_	Guaranteed

Note 1: The ADC conversion result never decreases with an increase in the input voltage and has no missing codes.

2: Measurements taken with external VREF+ and VREF- used as the ADC voltage reference.

AC CHARACTERISTICS			Standard Operating Conditions: 2.2V to 3.6V(unless otherwise stated)Operating temperature $-40^{\circ}C \le TA \le +85^{\circ}C$					
Param No.	Symbol	Characteristic	Min.	Тур	Max.	Units	Conditions	
		Cloc	k Parame	ters				
AD50	Tad	ADC Clock Period	75	—	—	ns	Tcy = 75 ns, AD1CON3 in default state	
AD51	tRC	ADC Internal RC Oscillator Period	—	250	—	ns		
		Con	version R	ate				
AD55	tCONV	Conversion Time		12	—	TAD		
AD56	FCNV	Throughput Rate	_		500	ksps	AVDD > 2.7V	
AD57	tSAMP	Sample Time	—	1	—	Tad		
		Cloc	k Parame	ters	•			
AD61	tPSS	Sample Start Delay from Setting Sample bit (SAMP)	2	_	3	Tad		

TABLE 30-20: ADC CONVERSION TIMING REQUIREMENTS⁽¹⁾

Note 1: Because the sample caps will eventually lose charge, clock rates below 10 kHz can affect linearity performance, especially at elevated temperatures.

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NOTES:

31.0 PACKAGING INFORMATION

31.1 Package Marking Information

64-Lead TQFP (10x10x1 mm) Example MICROCHIP MICROCHIP XXXXXXXXXX PIC24FJ256 XXXXXXXXXXX DA106-I/ XXXXXXXXXXX PT_(e3) → YYWWNNN 1020017 \bigcirc 64-Lead QFN (9x9x0.9 mm) Example $\langle M \rangle$ \mathcal{M} XXXXXXXXXXXX PIC24FJ256 XXXXXXXXXXXX DA206-I/MR_{@3} XXXXXXXXXXXX 1010017 YYWWNNN 100-Lead TQFP (12x12x1 mm) Example Σ MICROCHIP MICROCHIP PIC24FJ256DA XXXXXXXXXXXXX XXXXXXXXXXXXX 110-I/PT@3 1020017 YYWWNNN Ο 121-BGA (10x10x1.1 mm) Example ΔT MICROCHIP MICROCHIP XXXXXXXXXXXXX PIC24FJ256DA XXXXXXXXXXXXX 110-I/BG@3 YYWWNNN 1020017 ()Г

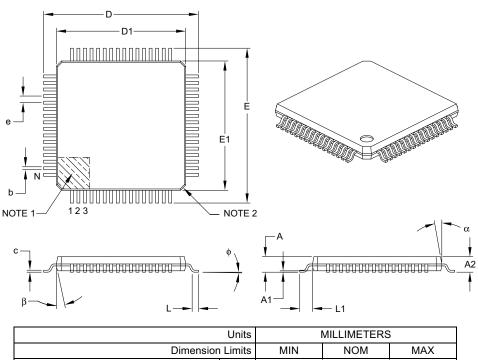
Legend	I: XXX	Customer-specific information
	Y	Year code (last digit of calendar year)
	ΥY	Year code (last 2 digits of calendar year)
	WW	Week code (week of January 1 is week '01')
	NNN	Alphanumeric traceability code
	e3	Pb-free JEDEC designator for Matte Tin (Sn)
	*	This package is Pb-free. The Pb-free JEDEC designator ((e_3))
		can be found on the outer packaging for this package.
-		
Note:		nt the full Microchip part number cannot be marked on one line, it will
		d over to the next line, thus limiting the number of available
	characters	s for customer-specific information.

31.2 Package Details

The following sections give the technical details of the packages.

64-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	MIN	NOM	MAX				
Number of Leads	N		64				
Lead Pitch	е		0.50 BSC				
Overall Height	A	-	-	1.20			
Molded Package Thickness	A2	0.95	1.00	1.05			
Standoff	A1	0.05	-	0.15			
Foot Length	L	0.45	0.60	0.75			
Footprint	L1		1.00 REF				
Foot Angle	φ	0°	3.5°	7°			
Overall Width	E		12.00 BSC				
Overall Length	D		12.00 BSC				
Molded Package Width	E1		10.00 BSC				
Molded Package Length	D1		10.00 BSC				
Lead Thickness	С	0.09	_	0.20			
Lead Width	b	0.17	0.22	0.27			
Mold Draft Angle Top	α	11°	12°	13°			
Mold Draft Angle Bottom	β	11°	12°	13°			

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Chamfers at corners are optional; size may vary.

3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.

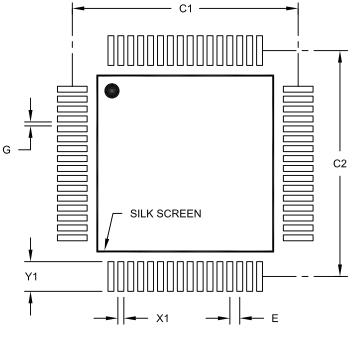
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-085B

64-Lead Plastic Thin Quad Flatpack (PT) – 10x10x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



RECOMMENDED LAND PATTERN

	MILLIM	ETERS		
Dimension	Limits	MIN	NOM	MAX
Contact Pitch	E		0.50 BSC	
Contact Pad Spacing	C1		11.40	
Contact Pad Spacing	C2		11.40	
Contact Pad Width (X64)	X1			0.30
Contact Pad Length (X64)	Y1			1.50
Distance Between Pads	G	0.20		

Notes:

1. Dimensioning and tolerancing per ASME Y14.5M

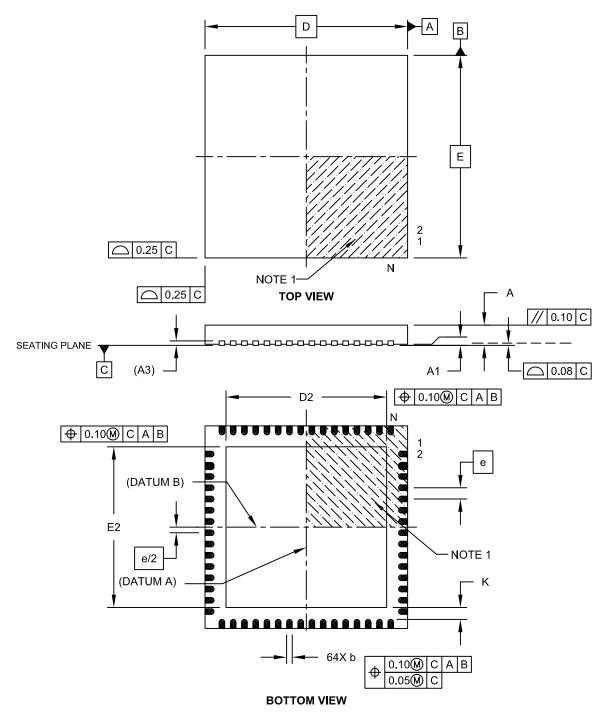
BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2085A

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64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]

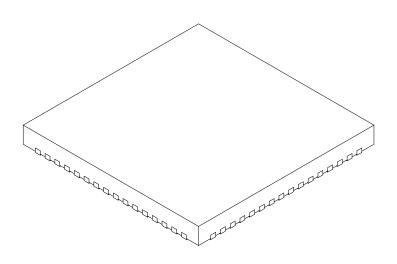
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-149B Sheet 1 of 2

64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units				
Dimension	Limits	MIN	NOM	MAX	
Number of Pins	N	64			
Pitch	е		0.50 BSC		
Overall Height	A	0.80	0.90	1.00	
Standoff	A1	0.00	0.02	0.05	
Contact Thickness	A3	0.20 REF			
Overall Width	E		9.00 BSC		
Exposed Pad Width	E2	7.05	7.15	7.50	
Overall Length	D		9.00 BSC		
Exposed Pad Length	D2	7.05	7.15	7.50	
Contact Width	b	0.18	0.25	0.30	
Contact Length	Contact Length L			0.50	
Contact-to-Exposed Pad	K	0.20	-	-	

Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

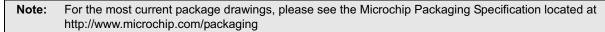
2. Package is saw singulated.

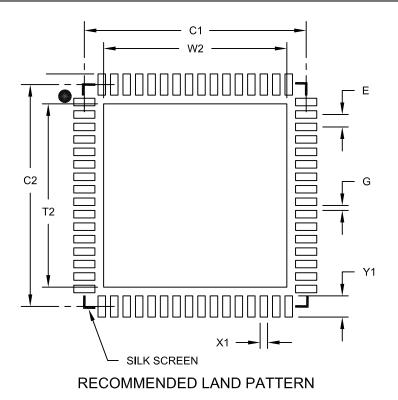
3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances. REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-149B Sheet 2 of 2

64-Lead Plastic Quad Flat, No Lead Package (MR) – 9x9x0.9 mm Body [QFN] With 0.40 mm Contact Length





Units		MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Contact Pitch	E	0.50 BSC			
Optional Center Pad Width	W2			7.35	
Optional Center Pad Length	T2			7.35	
Contact Pad Spacing	C1		8.90		
Contact Pad Spacing	C2		8.90		
Contact Pad Width (X64)	X1			0.30	
Contact Pad Length (X64)	Y1			0.85	
Distance Between Pads	G	0.20			

Notes:

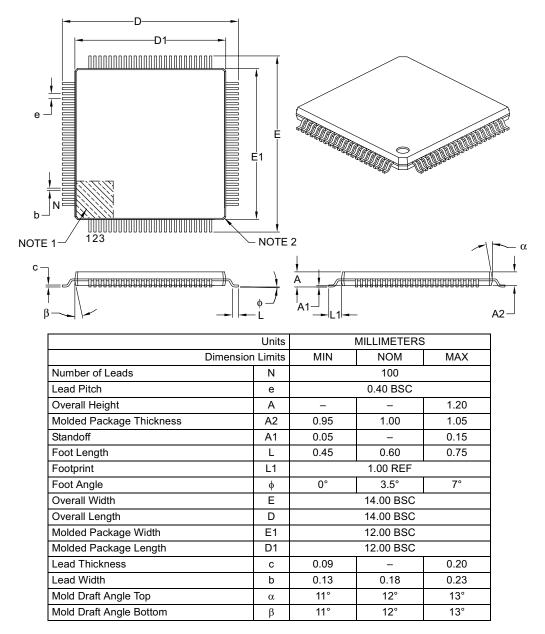
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2149A

100-Lead Plastic Thin Quad Flatpack (PT) – 12x12x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Notes:

1. Pin 1 visual index feature may vary, but must be located within the hatched area.

2. Chamfers at corners are optional; size may vary.

3. Dimensions D1 and E1 do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.25 mm per side.

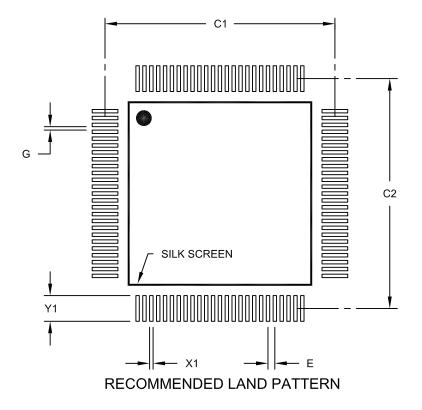
- 4. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-100B

100-Lead Plastic Thin Quad Flatpack (PT) – 12x12x1 mm Body, 2.00 mm [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Units		MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Contact Pitch	E	0.40 BSC			
Contact Pad Spacing	C1		13.40		
Contact Pad Spacing	C2		13.40		
Contact Pad Width (X100)	X1			0.20	
Contact Pad Length (X100)	Y1			1.50	
Distance Between Pads	G	0.20			

Notes:

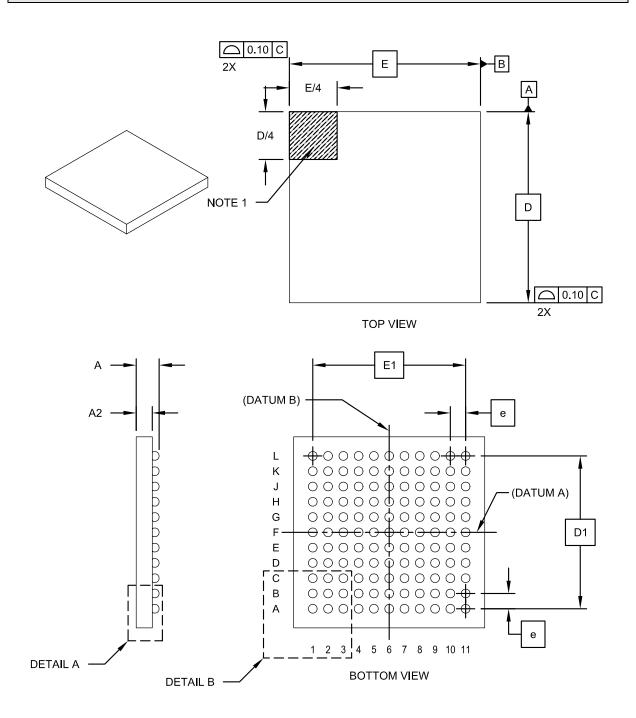
1. Dimensioning and tolerancing per ASME Y14.5M

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

Microchip Technology Drawing No. C04-2100A

121-Lead Plastic Thin Profile Ball Grid Array (BG) - 10x10x1.10 mm Body [XBGA]

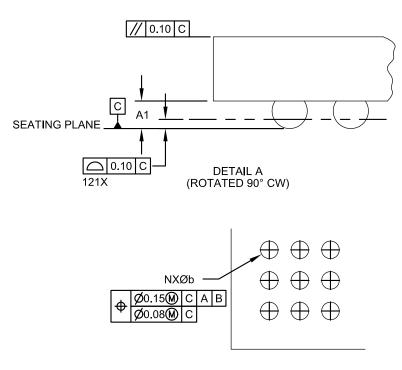
Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



Microchip Technology Drawing C04-148A Sheet 1 of 2

121-Lead Plastic Thin Profile Ball Grid Array (BG) - 10x10x1.10 mm Body [XBGA]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



DETAIL B

	Units	MILLIMETERS			
Dimension Limits		MIN	NOM	MAX	
Number of Contacts	N	121			
Contact Pitch	е	0.80 BSC			
Overall Height	Α	1.00	1.10	1.20	
Standoff	A1	0.25	0.30	0.35	
Molded Package Thickness	A2	0.55	0.60	0.65	
Overall Width	E	10.00 BSC			
Array Width	E1	8.00 BSC			
Overall Length	D	10.00 BSC			
Array Length	D1	8.00 BSC			
Contact Diameter	b	0.40 TYP			

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Dimensioning and tolerancing per ASME Y14.5M.
 - BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

3. The outer rows and colums of balls are located with respect to datums A and B.

Microchip Technology Drawing C04-148 Rev A Sheet 2 of 2

APPENDIX A: REVISION HISTORY

Revision A (February 2010)

Original data sheet for the PIC24FJ256DA210 family of devices.

Revision B (May 2010)

Minor changes throughout text and the values in **Section 30.0 "Electrical Characteristics"** were updated.

NOTES:

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PRODUCT IDENTIFICATION SYSTEM

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Product Group Pin Count —— Tape and Reel Fla Temperature Ran		Exa a) b) c)	amples:PIC24FJ128DA206-I/PT:PIC24F device with Graphics Controller and USB On-The-Go, 128-KB program memory, 96-KB data memory, 64-pin, Industrial temp., TQFP package.PIC24FJ256DA110-I/PT:PIC24F device with Graphics Controller and USB On-The-Go, 256-KB program memory, 24-KB data memory, 100-pin, Industrial temp., TQFP package.PIC24FJ256DA210-I/BG:PIC24FJ256DA210-I/BG:PIC24F device with Graphics Controller and USB On-The-Go, 256-KB program memory, 96-KB data memory, 121-pin, Industrial temp., BGA package.			
Architecture	24 = 16-bit modified Harvard without DSP					
Flash Memory Family	Flash Memory Family FJ = Flash program memory					
Product Group	DA2 = General purpose microcontrollers with Graphics Controller and USB On-The-Go					
Pin Count	06 = 64-pin 10 = 100-pin (TQFP)/121-pin (BGA)					
Temperature Range	I = -40° C to $+85^{\circ}$ C (Industrial)					
Package	PT = 100-lead (12x12x1 mm) TQFP (Thin Quad Flatpack) PT = 64-lead, TQFP (Thin Quad Flatpack) MR = 64-lead (9x9x0.9 mm) QFN (Quad Flatpack, No Lead) BG = 121-pin BGA package					
Pattern	Three-digit QTP, SQTP, Code or Special Requirements (blank otherwise) ES = Engineering Sample					



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