

74HC160

Presettable synchronous BCD decade counter;
asynchronous reset

Rev. 4 — 27 March 2019

Product data sheet

1. General description

The 74HC160 is a synchronous presettable decade counter with an internal look-ahead carry. Synchronous operation is provided by having all flip-flops clocked simultaneously on the positive-going edge of the clock (CP). The outputs (Q0 to Q3) of the counters may be preset HIGH or LOW. A LOW at the parallel enable input (PE) disables the counting action and causes the data at the data inputs (D0 to D3) to be loaded into the counter on the positive-going edge of the clock. Preset takes place regardless of the levels at count enable inputs (CEP and CET). A LOW at the master reset input (MR) sets Q0 to Q3 LOW regardless of the levels at input pins CP, PE, CET and CEP (thus providing an asynchronous clear function). The look-ahead carry simplifies serial cascading of the counters. Both CEP and CET must be HIGH to count. The CET input is fed forward to enable the terminal count output (TC). The TC output thus enabled will produce a HIGH output pulse of a duration approximately equal to a HIGH output of Q0. This pulse can be used to enable the next cascaded stage. The maximum clock frequency for the cascaded counters is determined by the CP to TC propagation delay and CEP to CP set-up time, according to the following formula:

$$f_{\max} = \frac{1}{t_{P(\max)} (\text{CP to TC}) + t_{\text{SU}} (\text{CEP to CP})}$$

Inputs include clamp diodes. This enables the use of current limiting resistors to interface inputs to voltages in excess of V_{CC} .

2. Features and benefits

- Complies with JEDEC standard no. 7A
- CMOS input levels
- Synchronous counting and loading
- 2 count enable inputs for n-bit cascading
- Asynchronous reset
- Positive-edge triggered clock
- ESD protection:
 - HBM JESD22-A114F exceeds 2000 V
 - MM JESD22-A115-A exceeds 200 V
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

3. Ordering information

Table 1. Ordering information

Type number	Package			
	Temperature range	Name	Description	Version
74HC160D	-40 °C to +125 °C	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1

4. Functional diagram

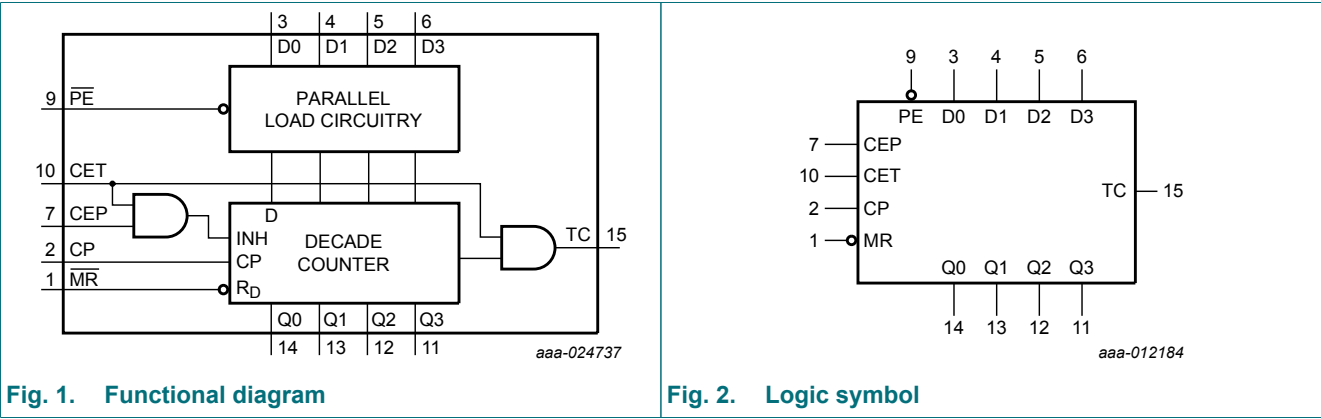


Fig. 1. Functional diagram

Fig. 2. Logic symbol

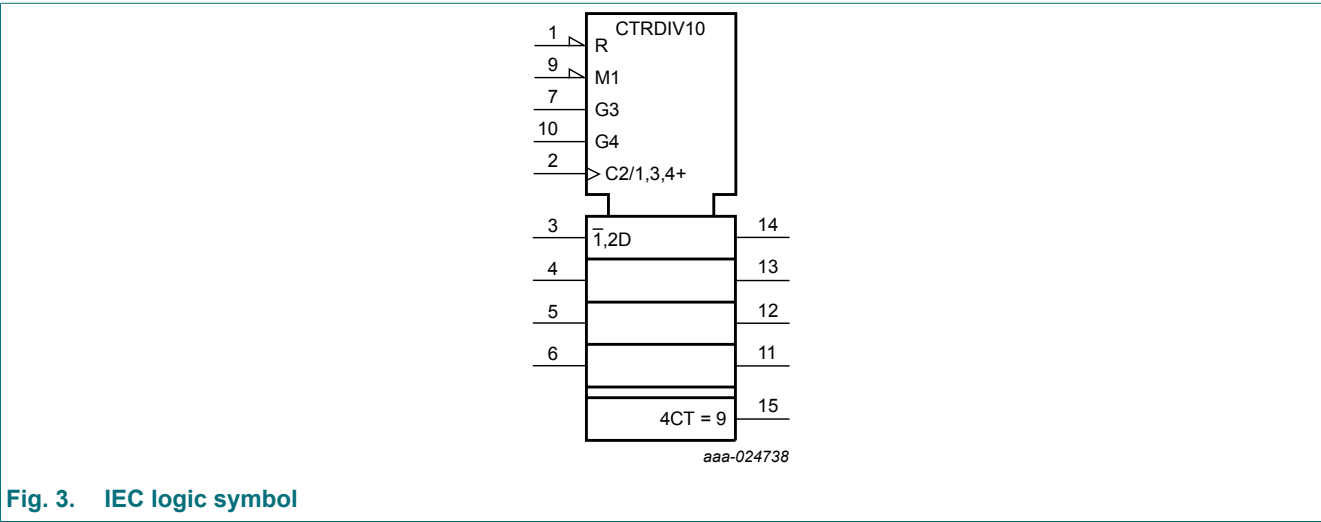


Fig. 3. IEC logic symbol

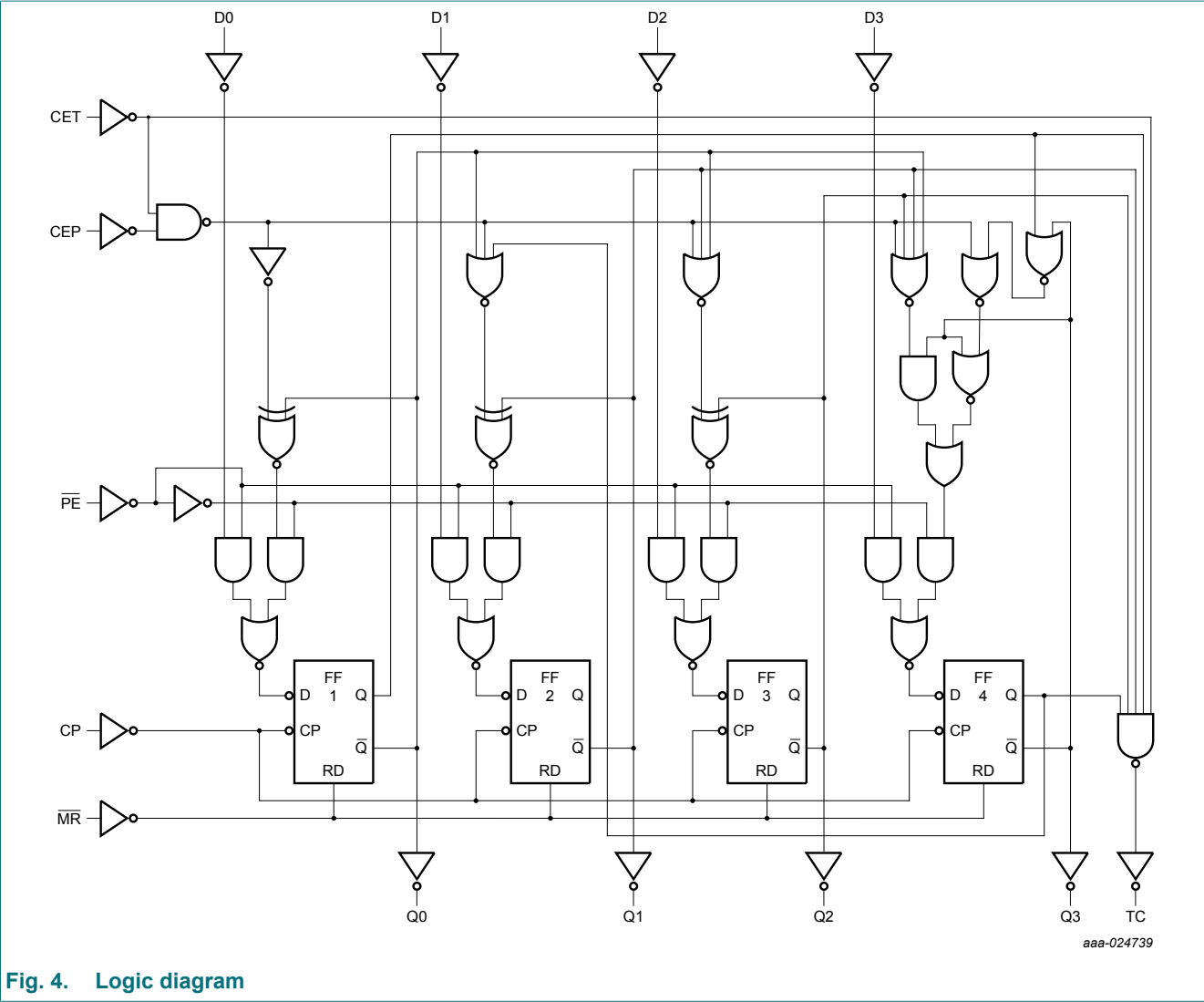


Fig. 4. Logic diagram

5. Pinning information

5.1. Pinning

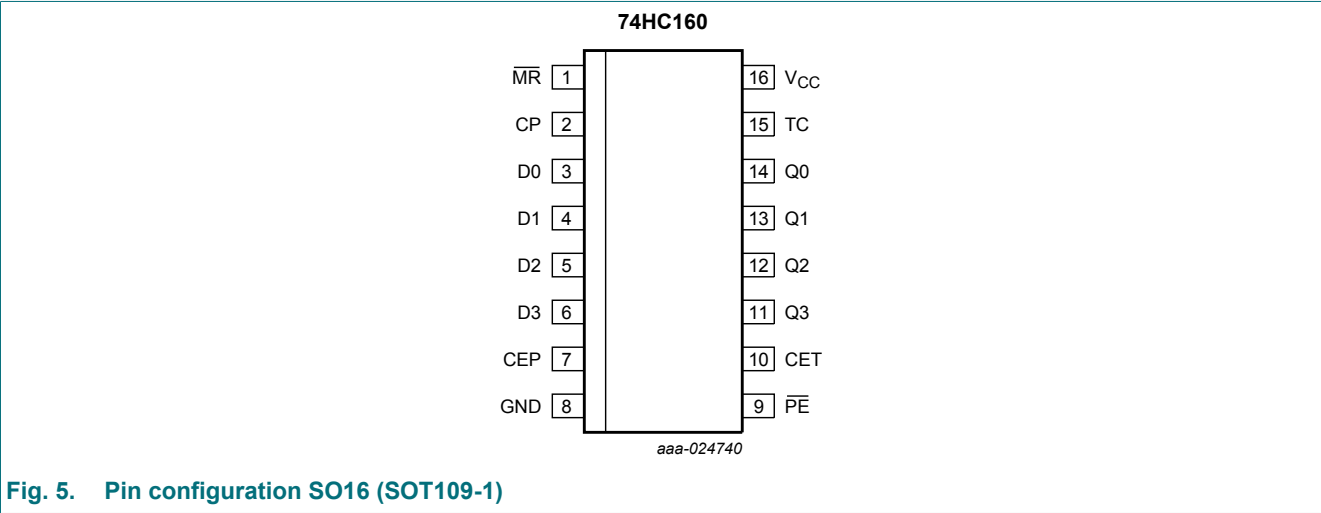


Fig. 5. Pin configuration SO16 (SOT109-1)

5.2. Pin description

Table 2. Pin description

Symbol	Pin	Description
MR	1	asynchronous master reset (active LOW)
CP	2	clock input (LOW-to-HIGH, edge triggered)
D0, D1, D2, D3	3, 4, 5, 6	data input
CEP	7	count enable input
GND	8	ground (0 V)
PE	9	parallel enable input (active LOW)
CET	10	count enable carry input
Q0, Q1, Q2, Q3	14, 13, 12, 11	flip-flop output
TC	15	terminal count output
V _{CC}	16	supply voltage

6. Functional description

Table 3. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; ↑ = LOW-to-HIGH clock transition;
h = HIGH voltage level one set-up time prior to the LOW-to-HIGH CP transition;
l = LOW voltage level one set-up time prior to the LOW-to-HIGH CP transition;
q_n = lower case letters indicate the state of the referenced output one set-up time prior to the LOW-to-HIGH CP transition.

Operating mode	Inputs						Outputs	
	MR	CP	CEP	CET	PE	Dn	Qn	TC
Reset (clear)	L	X	X	X	X	X	L	L
Parallel load	H	↑	X	X	l	l	L	L
	H	↑	X	X	l	h	H	[1]
Count	H	↑	h	h	h	X	count	[1]
Hold (do nothing)	H	X	l	X	h	X	q _n	[1]
	H	X	X	l	h	X	q _n	L

[1] The TC output is HIGH when CET is HIGH and the counter is at terminal count (HLLH);

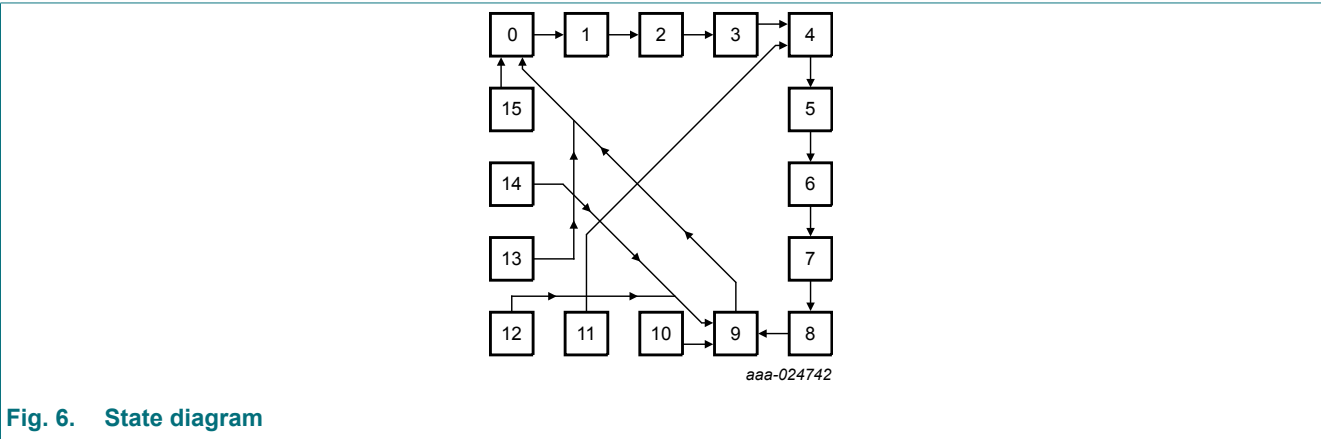
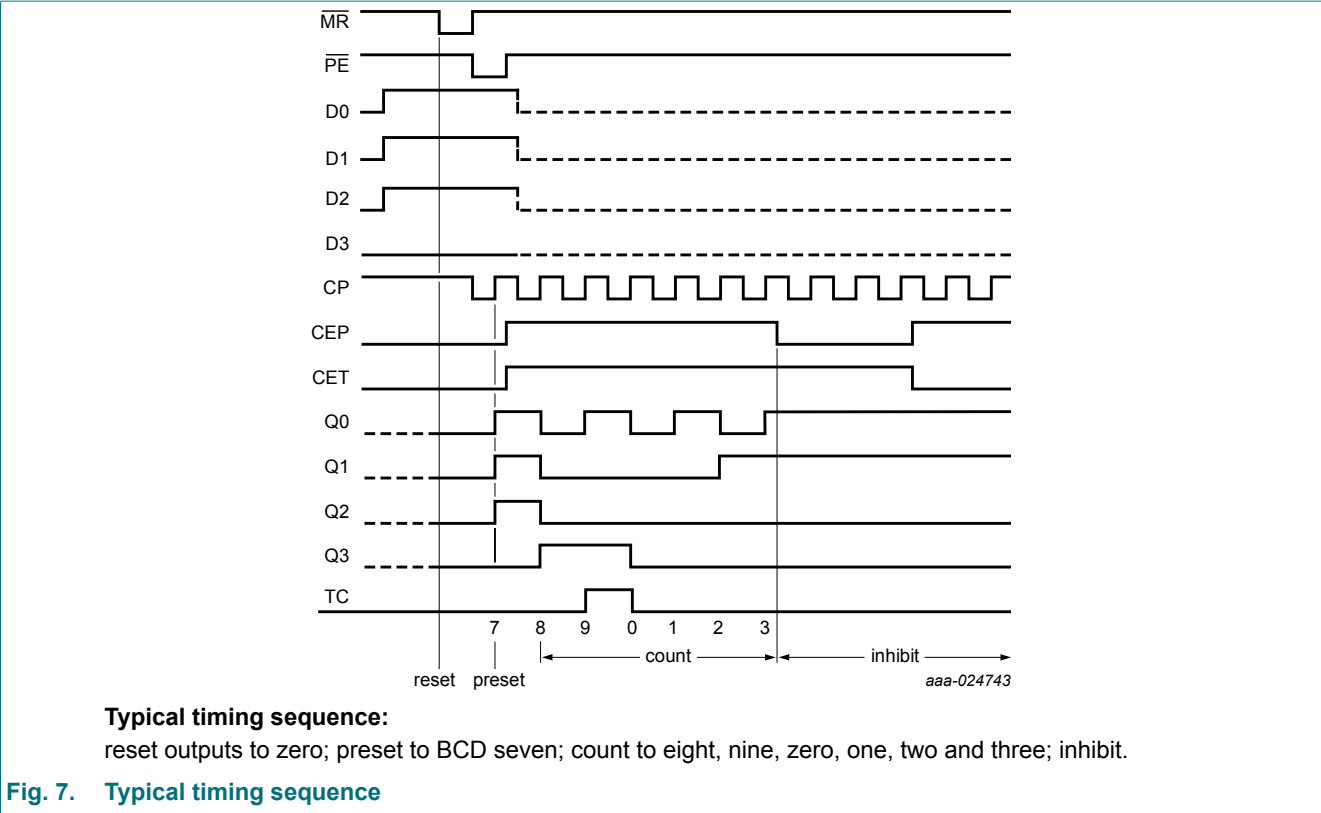


Fig. 6. State diagram

Presetable synchronous BCD decade counter; asynchronous reset



7. Limiting values

Table 4. Limiting values
In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	Min	Max	Unit
V _{CC}	supply voltage		-0.5	+7.0	V
I _{IK}	input clamping current	V _I < -0.5 V or V _I > V _{CC} + 0.5 V	-	±20	mA
I _{OK}	output clamping current	V _O < -0.5 V or V _O > V _{CC} + 0.5 V	-	±20	mA
I _O	output current	-0.5 V < V _O < V _{CC} + 0.5 V	-	±25	mA
I _{CC}	supply current		-	+50	mA
I _{GND}	ground current		-50	-	mA
T _{stg}	storage temperature		-65	+150	°C
P _{tot}	total power dissipation	[1]	-	500	mW

[1] For SO16 package: above 70 °C the value of P_{tot} derates linearly at 8 mW/K.

8. Recommended operating conditions

Table 5. Recommended operating conditions

Voltages are referenced to GND (ground = 0 V)

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
V_{CC}	supply voltage		2.0	5.0	6.0	V
V_I	input voltage		0	-	V_{CC}	V
V_O	output voltage		0	-	V_{CC}	V
T_{amb}	ambient temperature		-40	+25	+125	°C
$\Delta t/\Delta V$	input transition rise and fall rate	$V_{CC} = 2.0\text{ V}$	-	-	625	ns/V
		$V_{CC} = 4.5\text{ V}$	-	1.67	139	ns/V
		$V_{CC} = 6.0\text{ V}$	-	-	83	ns/V

9. Static characteristics

Table 6. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
V_{IH}	HIGH-level input voltage	$V_{CC} = 2.0\text{ V}$	1.5	1.2	-	1.5	-	1.5	-	V
		$V_{CC} = 4.5\text{ V}$	3.15	2.4	-	3.15	-	3.15	-	V
		$V_{CC} = 6.0\text{ V}$	4.2	3.2	-	4.2	-	4.2	-	V
V_{IL}	LOW-level input voltage	$V_{CC} = 2.0\text{ V}$	-	0.8	0.5	-	0.5	-	0.5	V
		$V_{CC} = 4.5\text{ V}$	-	2.1	1.35	-	1.35	-	1.35	V
		$V_{CC} = 6.0\text{ V}$	-	2.8	1.8	-	1.8	-	1.8	V
V_{OH}	HIGH-level output voltage	$V_I = V_{IH}$ or V_{IL}								
		$I_O = -20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$	1.9	2.0	-	1.9	-	1.9	-	V
		$I_O = -20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$	4.4	4.5	-	4.4	-	4.4	-	V
		$I_O = -20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$	5.9	6.0	-	5.9	-	5.9	-	V
		$I_O = -4.0\text{ mA}; V_{CC} = 4.5\text{ V}$	3.98	4.32	-	3.84	-	3.7	-	V
V_{OL}	LOW-level output voltage	$V_I = V_{IH}$ or V_{IL}								
		$I_O = 20\text{ }\mu\text{A}; V_{CC} = 2.0\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 20\text{ }\mu\text{A}; V_{CC} = 4.5\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 20\text{ }\mu\text{A}; V_{CC} = 6.0\text{ V}$	-	0	0.1	-	0.1	-	0.1	V
		$I_O = 4.0\text{ mA}; V_{CC} = 4.5\text{ V}$	-	0.15	0.26	-	0.33	-	0.4	V
I_I	input leakage current	$V_I = V_{CC}$ or GND; $V_{CC} = 6.0\text{ V}$	-	-	± 0.1	-	± 1.0	-	± 1.0	μA
		$V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$	-	-	8.0	-	80.0	-	160.0	μA
		$V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$	-	-	8.0	-	80.0	-	160.0	μA
		$V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$	-	-	8.0	-	80.0	-	160.0	μA
		$V_I = V_{CC}$ or GND; $I_O = 0\text{ A}; V_{CC} = 6.0\text{ V}$	-	-	8.0	-	80.0	-	160.0	μA
C_I	input capacitance		-	3.5	-	-	-	-	-	pF

10. Dynamic characteristics

Table 7. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); $C_L = 50$ pF unless otherwise specified; for test circuit see Fig. 13.

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
t_{pd}	propagation delay	CP to Qn; see Fig. 8 [1]								
		$V_{CC} = 2.0$ V	-	61	185	-	230	-	280	ns
		$V_{CC} = 4.5$ V	-	22	37	-	46	-	56	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	19	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	18	31	-	39	-	48	ns
		CP to TC; see Fig. 8								
		$V_{CC} = 2.0$ V	-	69	215	-	270	-	325	ns
		$V_{CC} = 4.5$ V	-	25	43	-	54	-	65	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	21	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	20	31	-	46	-	55	ns
		CET to TC; see Fig. 9								
		$V_{CC} = 2.0$ V	-	47	150	-	190	-	225	ns
		$V_{CC} = 4.5$ V	-	17	30	-	38	-	45	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	14	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	14	26	-	33	-	38	ns
t_{PHL}	High to LOW propagation delay	$\overline{MR}$ to Qn; see Fig. 10								
		$V_{CC} = 2.0$ V	-	69	210	-	265	-	315	ns
		$V_{CC} = 4.5$ V	-	25	42	-	53	-	63	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	21	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	20	36	-	45	-	54	ns
		$\overline{MR}$ to TC; see Fig. 10								
		$V_{CC} = 2.0$ V	-	69	220	-	275	-	330	ns
		$V_{CC} = 4.5$ V	-	25	44	-	55	-	66	ns
		$V_{CC} = 5.0$ V; $C_L = 15$ pF	-	21	-	-	-	-	-	ns
		$V_{CC} = 6.0$ V	-	20	37	-	47	-	56	ns
t_t	transition time	see Fig. 8 and Fig. 9 [2]								
		$V_{CC} = 2.0$ V	-	19	75	-	95	-	110	ns
		$V_{CC} = 4.5$ V	-	7	15	-	19	-	22	ns
		$V_{CC} = 6.0$ V	-	6	13	-	16	-	19	ns
t_W	pulse width	CP HIGH or LOW; see Fig. 8								
		$V_{CC} = 2.0$ V	80	22	-	100	-	120	-	ns
		$V_{CC} = 4.5$ V	16	8	-	20	-	24	-	ns
		$V_{CC} = 6.0$ V	14	3	-	17	-	20	-	ns
t_W	pulse width	$\overline{MR}$ LOW; see Fig. 10								
		$V_{CC} = 2.0$ V	80	28	-	100	-	120	-	ns
		$V_{CC} = 4.5$ V	16	10	-	20	-	24	-	ns
		$V_{CC} = 6.0$ V	14	8	-	17	-	20	-	ns

Presettable synchronous BCD decade counter; asynchronous reset

Symbol	Parameter	Conditions	25 °C			-40 °C to +85 °C		-40 °C to +125 °C		Unit
			Min	Typ	Max	Min	Max	Min	Max	
t _{rec}	recovery time	MR to CP; see Fig. 10								
		V _{CC} = 2.0 V	100	30	-	125	-	150	-	ns
		V _{CC} = 4.5 V	20	11	-	25	-	30	-	ns
		V _{CC} = 6.0 V	17	9	-	21	-	26	-	ns
t _{su}	set-up time	Dn to CP; see Fig. 11								
		V _{CC} = 2.0 V	80	22	-	100	-	120	-	ns
		V _{CC} = 4.5 V	16	8	-	20	-	24	-	ns
		V _{CC} = 6.0 V	14	6	-	17	-	20	-	ns
		PE to CP; see Fig. 11								
		V _{CC} = 2.0 V	135	41	-	170	-	205	-	ns
		V _{CC} = 4.5 V	27	15	-	34	-	41	-	ns
		V _{CC} = 6.0 V	23	12	-	29	-	35	-	ns
		CEP, CET to CP; see Fig. 12								
		V _{CC} = 2.0 V	200	63	-	250	-	300	-	ns
		V _{CC} = 4.5 V	40	23	-	50	-	60	-	ns
		V _{CC} = 6.0 V	34	18	-	43	-	51	-	ns
t _h	hold time	Dn to CP; see Fig. 11								
		V _{CC} = 2.0 V	0	-17	-	0	-	0	-	ns
		V _{CC} = 4.5 V	0	-6	-	0	-	0	-	ns
		V _{CC} = 6.0 V	0	-5	-	0	-	0	-	ns
		PE to CP; see Fig. 11								
		V _{CC} = 2.0 V	0	-41	-	0	-	0	-	ns
		V _{CC} = 4.5 V	0	-15	-	0	-	0	-	ns
		V _{CC} = 6.0 V	0	-12	-	0	-	0	-	ns
		CEP, CET to CP; see Fig. 12								
		V _{CC} = 2.0 V	0	-58	-	0	-	0	-	ns
		V _{CC} = 4.5 V	0	-21	-	0	-	0	-	ns
		V _{CC} = 6.0 V	0	-17	-	0	-	0	-	ns
f _{max}	maximum frequency	CP; see Fig. 8								
		V _{CC} = 2.0 V	6	18	-	4.8	-	4	-	MHz
		V _{CC} = 4.5 V	30	55	-	24	-	20	-	MHz
		V _{CC} = 5.0 V; C _L = 15 pF	-	61	-	-	-	-	-	MHz
		V _{CC} = 6.0 V	35	66	-	28	-	24	-	MHz
C _{PD}	power dissipation capacitance	V _I = GND to V _{CC} ; f _i = 1 MHz [3]	-	39	-	-	-	-	-	pF

[1] t_{pd} is the same as t_{PHL} and t_{PLH}.

[2] t_i is the same as t_{THL} and t_{TLH}.

[3] C_{PD} is used to determine the dynamic power dissipation (P_D in μW):

$$P_D = C_{PD} \times V_{CC}^2 \times f_i \times N + \sum (C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f_i = input frequency in MHz;

f_o = output frequency in MHz;

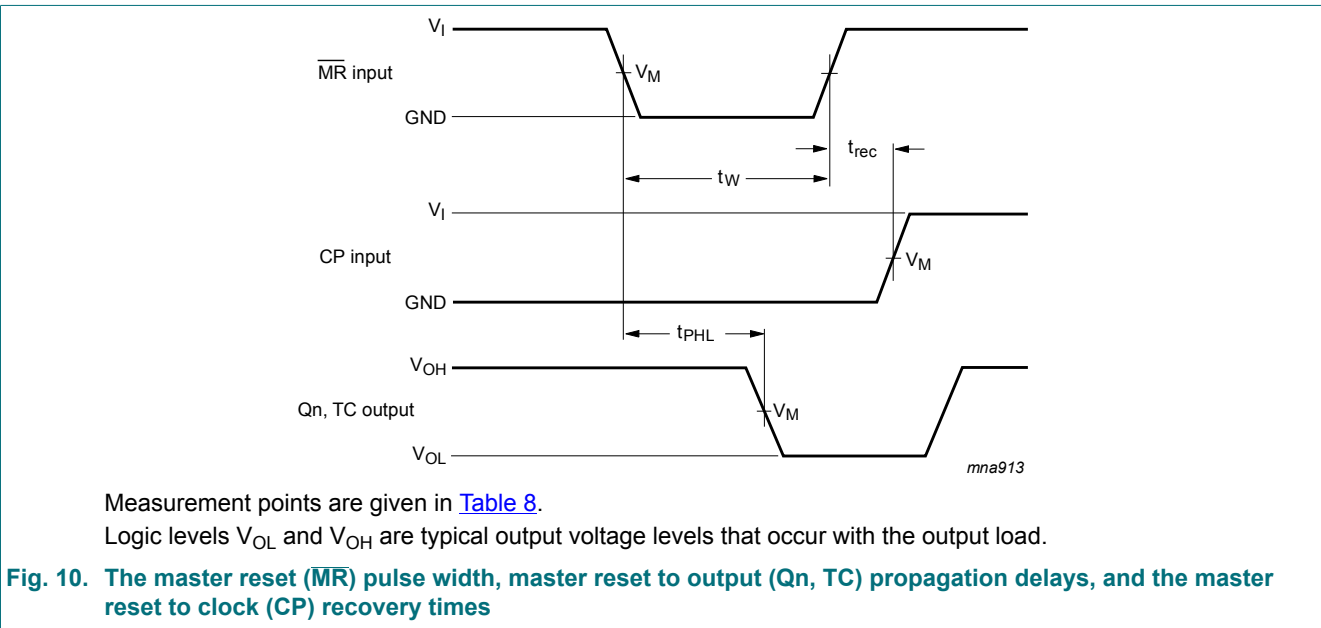
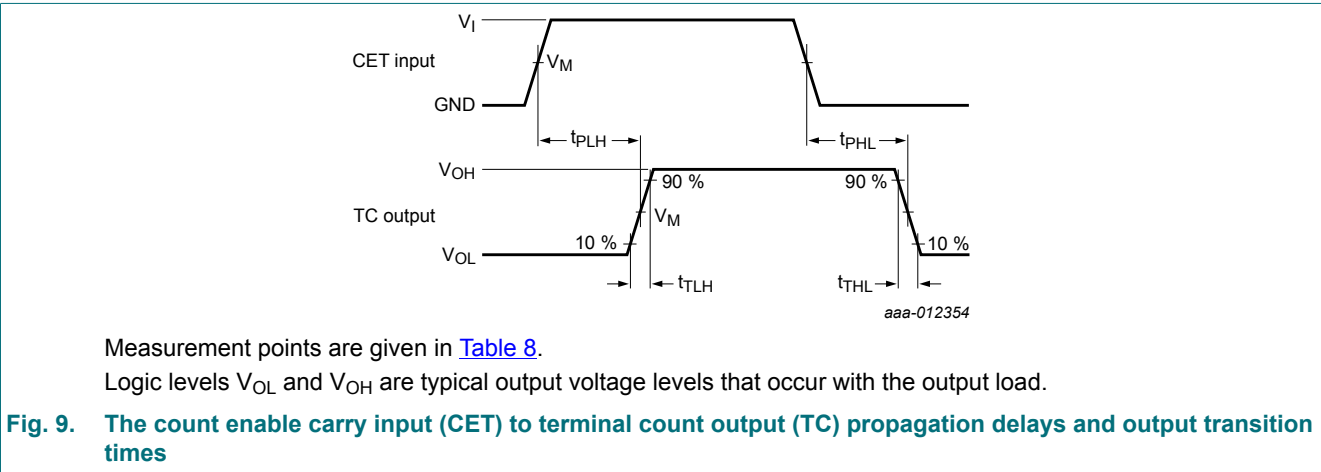
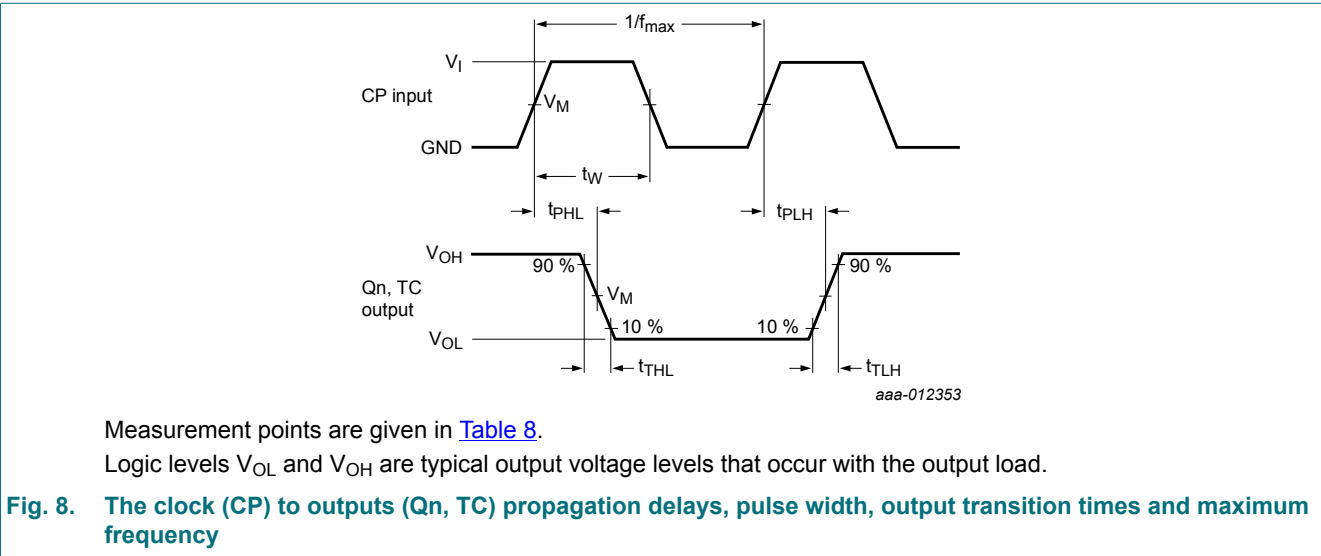
C_L = output load capacitance in pF;

V_{CC} = supply voltage in V;

N = number of inputs switching;

Σ(C_L × V_{CC}² × f_o) = sum of outputs.

10.1. Waveforms and test circuit



Presetable synchronous BCD decade counter; asynchronous reset

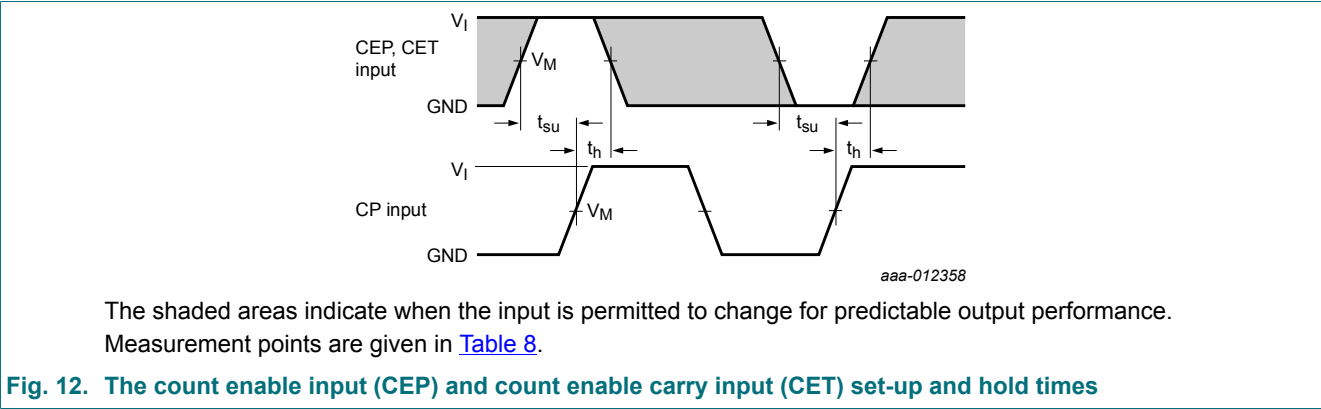
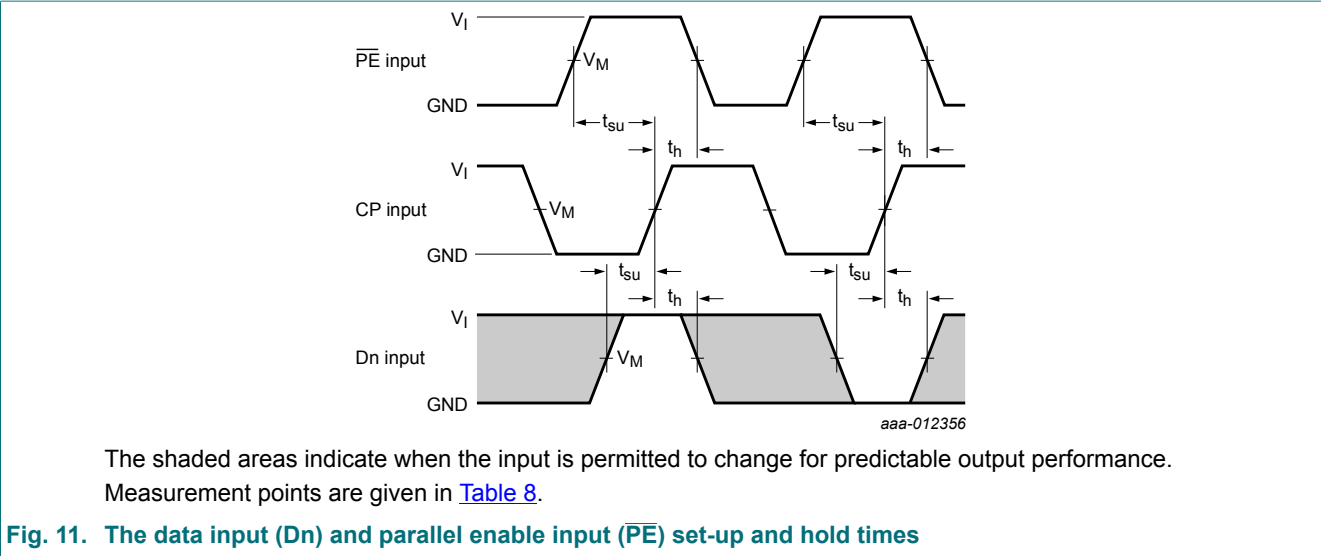


Table 8. Measurement points

Input		Output
V_M	V_I	V_M
$0.5 \times V_{CC}$	GND to V_{CC}	$0.5 \times V_{CC}$

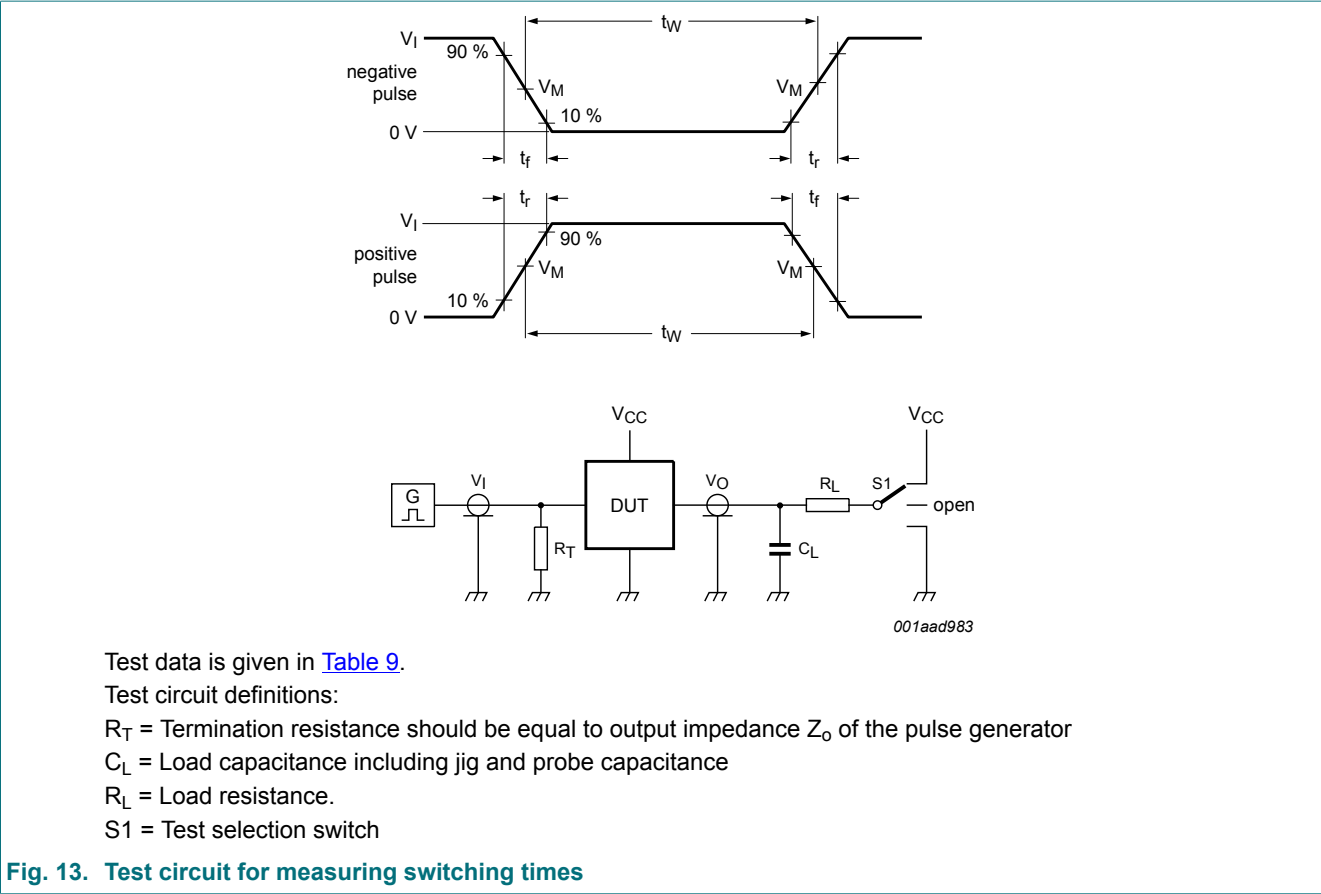


Fig. 13. Test circuit for measuring switching times

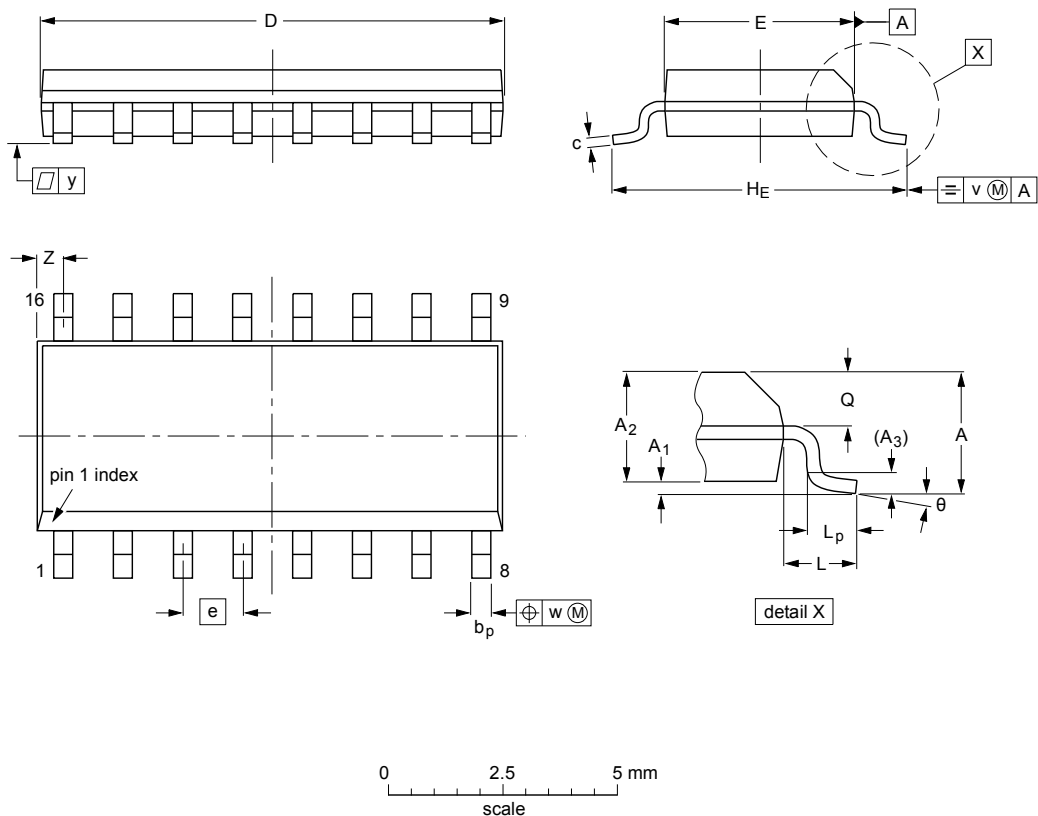
Table 9. Test data

Input		Load		S1 position
V_I	t_r, t_f	C_L	R_L	t_{PHL}, t_{PLH}
V_{CC}	6 ns	15 pF, 50 pF	1 kΩ	open

11. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1



DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A ₁	A ₂	A ₃	b _p	c	D ⁽¹⁾	E ⁽¹⁾	e	H _E	L	L _p	Q	v	w	y	Z ⁽¹⁾	θ
mm	1.75	0.25 0.10	1.45 1.25	0.25	0.49 0.36	0.25 0.19	10.0 9.8	4.0 3.8	1.27	6.2 5.8	1.05	1.0 0.4	0.7 0.6	0.25	0.25	0.1	0.7 0.3	8° 0°
inches	0.069	0.010 0.004	0.057 0.049	0.01	0.019 0.014	0.0100 0.0075	0.39 0.38	0.16 0.15	0.05	0.244 0.228	0.041	0.039 0.016	0.028 0.020	0.01	0.01	0.004	0.028 0.012	

Note
1. Plastic or metal protrusions of 0.15 mm (0.006 inch) maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	JEITA			
SOT109-1	076E07	MS-012				99-12-27 03-02-19

Fig. 14. Package outline SOT109-1 (SO16)

12. Abbreviations

Table 10. Abbreviations

Acronym	Description
CMOS	Complementary Metal-Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
MM	Machine Model

13. Revision history

Table 11. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74HC160 v.4	20190327	Product data sheet	-	74HC_HCT160 v.3
Modifications:	- The format of this data sheet has been redesigned to comply with the identity guidelines of Nexperia. - Legal texts have been adapted to the new company name where appropriate. - Type number 74HC160DB (SOT338-1) removed.			
74HC160 v.3	20160927	Product data sheet	-	74HC_HCT160 v.2
Modifications:	- The format of this data sheet has been redesigned to comply with the new identity guidelines of NXP Semiconductors. - Legal texts have been adapted to the new company name where appropriate. - Type numbers 74HCT160D, 74HCT160PW, 74HCT160N, 74HC160N and 74HC160PW removed.			
74HC_HCT160 v.2	19901201	Product specification	-	-

14. Legal information

Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

- [1] Please consult the most recently issued document before initiating or completing a design.
- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <https://www.nexperia.com>.

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