Dual-supply voltage level translator/transceiver; 3-stateRev. 8 — 10 December 2018Product data sheet

### 1. General description

The 74AVC1T45 is a single bit, dual supply transceiver with 3-state output that enables bidirectional level translation. It features two 1-bit input-output ports (A and B), a direction control input (DIR) and dual supply pins ( $V_{CC(A)}$  and  $V_{CC(B)}$ ). Both  $V_{CC(A)}$  and  $V_{CC(B)}$  can be supplied at any voltage between 0.8 V and 3.6 V making the device suitable for translating between any of the low voltage nodes (0.8 V, 1.2 V, 1.5 V, 1.8 V, 2.5 V and 3.3 V). Pins A and DIR are referenced to  $V_{CC(A)}$  and pin B is referenced to  $V_{CC(B)}$ . A HIGH on DIR allows transmission from A to B and a LOW on DIR allows transmission from B to A.

The device is fully specified for partial power-down applications using I<sub>OFF</sub>. The I<sub>OFF</sub> circuitry disables the output, preventing any damaging backflow current through the device when it is powered down. In suspend mode when either V<sub>CC(A)</sub> or V<sub>CC(B)</sub> are at GND level, both A and B are in the high-impedance OFF-state.

### 2. Features and benefits

- Wide supply voltage range:
  - V<sub>CC(A)</sub>: 0.8 V to 3.6 V
  - $V_{CC(B)}$ : 0.8 V to 3.6 V
- High noise immunity
- Complies with JEDEC standards:
  - JESD8-12 (0.8 V to 1.3 V)
  - JESD8-11 (0.9 V to 1.65 V)
  - JESD8-7 (1.2 V to 1.95 V)
  - JESD8-5 (1.8 V to 2.7 V)
  - JESD8-B (2.7 V to 3.6 V)
- ESD protection:
  - HBM JESD22-A114E Class 3B exceeds 8000 V
  - MM JESD22-A115-A exceeds 200 V
  - CDM JESD22-C101C exceeds 1000 V
- Maximum data rates:
  - 500 Mbit/s (1.8 V to 3.3 V translation)
  - 320 Mbit/s (< 1.8 V to 3.3 V translation)
  - 320 Mbit/s (translate to 2.5 V or 1.8 V)
  - 280 Mbit/s (translate to 1.5 V)
  - 240 Mbit/s (translate to 1.2 V)
- Suspend mode
- Latch-up performance exceeds 100 mA per JESD 78 Class II
- Inputs accept voltages up to 3.6 V
- Low noise overshoot and undershoot < 10 % of V<sub>CC</sub>
- I<sub>OFF</sub> circuitry provides partial Power-down mode operation
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

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### 3. Ordering information

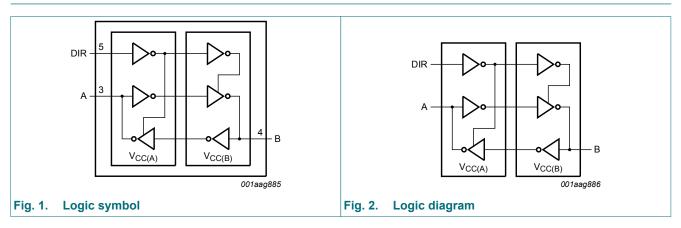
Type number	Package								
	Temperature range	Name	Description	Version					
74AVC1T45GW	-40 °C to +125 °C	SC-88	plastic surface-mounted package; 6 leads	SOT363					
74AVC1T45GM	-40 °C to +125 °C	XSON6	plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1.45 x 0.5 mm	SOT886					
74AVC1T45GN	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 0.9 x 1.0 x 0.35 mm	SOT1115					
74AVC1T45GS	-40 °C to +125 °C	XSON6	extremely thin small outline package; no leads; 6 terminals; body 1.0 x 1.0 x 0.35 mm	SOT1202					
74AVC1T45GX	-40 °C to +125 °C	X2SON6	plastic thermal extremely thin small outline package; no leads; 6 terminals; body 1 x 0.8 x 0.35 mm	SOT1255					

### 4. Marking

Table 2. Marking	
Type number	Marking code[1]
74AVC1T45GW	B5
74AVC1T45GM	B5
74AVC1T45GN	B5
74AVC1T45GS	B5
74AVC1T45GX	B5

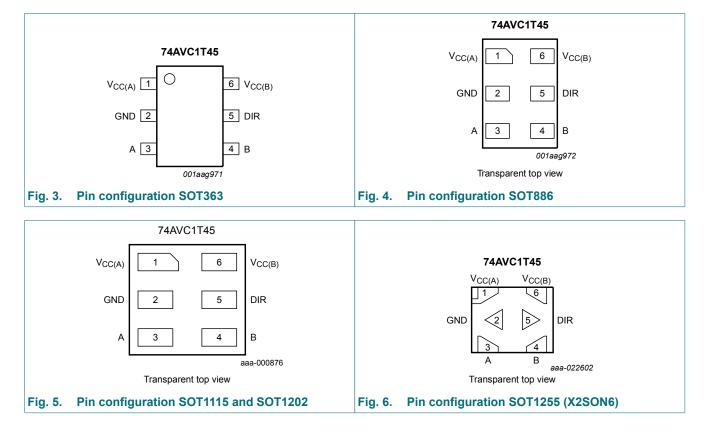
[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

### 5. Functional diagram



### 6. Pinning information

6.1. Pinning



### 6.2. Pin description

Table 3. Pir	n description
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Symbol	Pin	Description
V <sub>CC(A)</sub>	1	supply voltage port A and DIR
GND	2	ground (0 V)
A	3	data input or output
В	4	data input or output
DIR	5	direction control
V <sub>CC(B)</sub>	6	supply voltage port B

### 7. Functional description

#### **Table 4. Function table**

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

Supply voltage	Input	Input/output[1]		
V <sub>CC(A)</sub> , V <sub>CC(B)</sub> DIR[2]		A B		
0.8 V to 3.6 V	L	A = B	input	
0.8 V to 3.6 V	Н	input	B = A	
GND[3]	Х	Z	Z	

[1] The input circuit of the data I/O is always active.

The DIR input circuit is referenced to  $V_{CC(A)}$ . [2]

When either  $V_{CC(A)}$  or  $V_{CC(B)}$  is at GND level, the device goes into suspend mode. [3]

### 8. Limiting values

#### Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			-0.5	+4.6	V
V <sub>CC(B)</sub>	supply voltage B			-0.5	+4.6	V
I <sub>IK</sub>	input clamping current	V <sub>I</sub> < 0 V		-50	-	mA
VI	input voltage		[1]	-0.5	+4.6	V
Ι <sub>ΟΚ</sub>	output clamping current	V <sub>O</sub> < 0 V		-50	-	mA
Vo	output voltage	Active mode	[1][2][3]	-0.5	V <sub>CCO</sub> + 0.5	V
		Suspend or 3-state mode	[1]	-0.5	+4.6	V
lo	output current	$V_{O} = 0 V$ to $V_{CCO}$		-	±50	mA
I <sub>CC</sub>	supply current	I <sub>CC(A)</sub> or I <sub>CC(B)</sub>		-	100	mA
I <sub>GND</sub>	ground current			-100	-	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
P <sub>tot</sub>	total power dissipation	$T_{amb}$ = -40 °C to +125 °C	[4]	-	250	mW

The minimum input voltage ratings and output voltage ratings may be exceeded if the input and output current ratings are observed. [1] [2]

 $V_{\text{CCO}}$  is the supply voltage associated with the output port.

 $V_{CCO}$  + 0.5 V should not exceed 4.6 V. [3]

For SC-88 packages: above 87.5 °C the value of Ptot derates linearly with 4.0 mW/K. [4]

For X2SON6 and XSON6 packages: above 118 °C the value of Ptot derates linearly with 7.8 mW/K.

### 9. Recommended operating conditions

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>CC(A)</sub>	supply voltage A			0.8	3.6	V
V <sub>CC(B)</sub>	supply voltage B			0.8	3.6	V
VI	input voltage			0	3.6	V
Vo	output voltage	Active mode	[1]	0	V <sub>CCO</sub>	V
		Suspend or 3-state mode		0	3.6	V
T <sub>amb</sub>	ambient temperature			-40	+125	°C
Δt/ΔV	input transition rise and fall rate	V <sub>CCI</sub> = 0.8 V to 3.6 V	[2]	-	5	ns/V

 $V_{\text{CCO}}$  is the supply voltage associated with the output port. [1]

[2] V<sub>CCI</sub> is the supply voltage associated with the input port.

### 10. Static characteristics

#### Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).[1]

Symbol	Parameter	Conditions	Т	Unit		
			Min	Тур	Max	
V <sub>OH</sub>	HIGH-level output voltage	$V_{I} = V_{IH} \text{ or } V_{IL}$				
		$I_{\rm O}$ = -1.5 mA; $V_{\rm CC(A)}$ = $V_{\rm CC(B)}$ = 0.8 V	-	0.69	-	V
V <sub>OL</sub>	LOW-level output voltage	$V_{I} = V_{IH} \text{ or } V_{IL}$				
		$I_{O}$ = 1.5 mA; $V_{CC(A)}$ = $V_{CC(B)}$ = 0.8 V	-	0.07	-	V
I <sub>I</sub>	input leakage current	DIR input; $V_1 = 0 V \text{ or } 3.6 V$ ; $V_{CC(A)} = V_{CC(B)} = 0.8 V \text{ to } 3.6 V$	-	±0.025	±0.25	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V or $V_{CCO}$ ; [2] $V_{CC(A)} = V_{CC(B)} = 0.8$ V to 3.6 V	-	±0.5	±2.5	μA
I <sub>OFF</sub>	power-off leakage current	A port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; $V_{CC(A)}$ = 0 V; V <sub>CC(B)</sub> = 0.8 V to 3.6 V	-	±0.1	±1	μA
		B port; V <sub>I</sub> or V <sub>O</sub> = 0 V to 3.6 V; V <sub>CC(B)</sub> = 0 V; V <sub>CC(A)</sub> = 0.8 V to 3.6 V	-	±0.1	±1	μA
Cı	input capacitance	DIR input; V <sub>1</sub> = 0 V or 3.3 V; V <sub>CC(A)</sub> = V <sub>CC(B)</sub> = 3.3 V	-	1.0	-	pF
C <sub>I/O</sub>	input/output capacitance	A and B port; Suspend mode; V <sub>O</sub> = V <sub>CCO</sub> or GND; V <sub>CC(A)</sub> = V <sub>CC(B)</sub> = 3.3 V	-	4.0	-	pF

[1]

 $V_{CCO}$  is the supply voltage associated with the output port. For I/O ports, the parameter  $I_{OZ}$  includes the input leakage current. [2]

#### Table 8. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions	-40 °C to	o +85 °C	-40 °C to	Unit	
			Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level	data input					
	input voltage	V <sub>CCI</sub> = 0.8 V	0.70V <sub>CCI</sub>	-	0.70V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 1.1 V to 1.95 V	0.65V <sub>CCI</sub>	-	0.65V <sub>CCI</sub>	-	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	1.6	-	1.6	-	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	2	-	2	-	V
		DIR input					
		V <sub>CC(A)</sub> = 0.8 V	0.70V <sub>CC(A)</sub>	-	0.70V <sub>CC(A)</sub>	-	V
		V <sub>CC(A)</sub> = 1.1 V to 1.95 V	0.65V <sub>CC(A)</sub>	-	0.65V <sub>CC(A)</sub>	-	V
		V <sub>CC(A)</sub> = 2.3 V to 2.7 V	1.6	-	1.6	-	V
		V <sub>CC(A)</sub> = 3.0 V to 3.6 V	2	_	2	-	V
/ <sub>IL</sub> LOW-level	data input						
i	input voltage	V <sub>CCI</sub> = 0.8 V	_	0.30V <sub>CCI</sub>	-	0.30V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 1.1 V to 1.95 V	_	0.35V <sub>CCI</sub>	-	0.35V <sub>CCI</sub>	V
		V <sub>CCI</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		V <sub>CCI</sub> = 3.0 V to 3.6 V	-	0.9	-	0.9	V
		DIR input					
		V <sub>CC(A)</sub> = 0.8 V	-	0.30V <sub>CC(A)</sub>	-	0.30V <sub>CC(A)</sub>	V
		V <sub>CC(A)</sub> = 1.1 V to 1.95 V	-	0.35V <sub>CC(A)</sub>	-	0.35V <sub>CC(A)</sub>	V
		V <sub>CC(A)</sub> = 2.3 V to 2.7 V	-	0.7	-	0.7	V
		$V_{CC(A)} = 3.0 \text{ V to } 3.6 \text{ V}$	-	0.9	-	0.9	V
√он	HIGH-level output voltage	$V_{I} = V_{IH} \text{ or } V_{IL}$					
		$I_{O} = -100 \ \mu A;$ $V_{CC(A)} = V_{CC(B)} = 0.8 \ V \ to \ 3.6 \ V$	V <sub>CCO</sub> - 0.1	-	V <sub>CCO</sub> - 0.1	-	V
		$I_{O}$ = -3 mA; $V_{CC(A)}$ = $V_{CC(B)}$ = 1.1 V	0.85	-	0.85	-	V
		$I_{O}$ = -6 mA; $V_{CC(A)}$ = $V_{CC(B)}$ = 1.4 V	1.05	-	1.05	-	V
		$I_{O} = -8 \text{ mA};$ $V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	1.2	-	1.2	-	V
		$I_{O} = -9 \text{ mA};$ $V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	1.75	-	1.75	-	V
		$I_{O} = -12 \text{ mA};$ $V_{CC(A)} = V_{CC(B)} = 3.0 \text{ V}$	2.3	-	2.3	-	V
/ <sub>OL</sub>	LOW-level output voltage	$V_{I} = V_{IH} \text{ or } V_{IL}$ $I_{O} = 100 \ \mu\text{A};$	-	0.1	-	0.1	V
		$V_{CC(A)} = V_{CC(B)} = 0.8 \text{ V to } 3.6 \text{ V}$		0.25		0.25	V
		$I_{O} = 3 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.1 \text{ V}$	-		-		v V
		$I_{O} = 6 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.4 \text{ V}$ $I_{O} = 8 \text{ mA}; V_{CC(A)} = V_{CC(B)} = 1.65 \text{ V}$	-	0.35 0.45	-	0.35 0.45	V
		$I_{O} = 9 \text{ mA; } V_{CC(A)} = V_{CC(B)} = 2.3 \text{ V}$	-	0.55	-	0.55	V
		$I_{O} = 12 \text{ mA};$ $V_{CC(A)} = V_{CC(B} = 3.0 \text{ V}$	-	0.7	-	0.7	V

Symbol	Parameter	Conditions		-40 °C t	o +85 °C	-40 °C to	o +125 °C	Unit
				Min	Мах	Min	Max	_
lı	input leakage current	DIR input; V <sub>I</sub> = 0 V or 3.6 V; V <sub>CC(A)</sub> = V <sub>CC(B)</sub> = 0.8 V to 3.6 V		-	±1	-	±1.5	μA
I <sub>OZ</sub>	OFF-state output current	A or B port; $V_O = 0$ V or $V_{CCO}$ ; $V_{CC(A)} = V_{CC(B)} = 3.6$ V	[3]	-	±5	-	±7.5	μA
I <sub>OFF</sub>	power-off leakage	A port; V <sub>1</sub> or V <sub>0</sub> = 0 V to 3.6 V; V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 0.8 V to 3.6 V		-	±5	-	±35	μA
	current	$      B \ \text{port; } V_{1} \ \text{or } V_{O} = 0 \ \text{V to } 3.6 \ \text{V;} \\ V_{CC(B)} = 0 \ \text{V; } V_{CC(A)} = 0.8 \ \text{V to } 3.6 \ \text{V} $		-	±5	-	±35	μA
I <sub>CC</sub>	supply current	A port; $V_1 = 0$ V or $V_{CCI}$ ; $I_0 = 0$ A						
		V <sub>CC(A)</sub> = 0.8 V to 3.6 V; V <sub>CC(B)</sub> = 0.8 V to 3.6 V		-	8	-	12	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V		-	8	-	12	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 3.6 V		-2	-	-8	-	μA
		B port; $V_1 = 0$ V or $V_{CCI}$ ; $I_0 = 0$ A						
		V <sub>CC(A)</sub> = 0.8 V to 3.6 V; V <sub>CC(B)</sub> = 0.8 V to 3.6 V		-	8	-	12	μA
		V <sub>CC(A)</sub> = 3.6 V; V <sub>CC(B)</sub> = 0 V		-2	-	-8	-	μA
		V <sub>CC(A)</sub> = 0 V; V <sub>CC(B)</sub> = 3.6 V		-	8	-	12	μA
				-	16	-	24	μA

[1]

[2]

 $V_{CCO}$  is the supply voltage associated with the output port.  $V_{CCI}$  is the supply voltage associated with the data input port. For I/O ports, the parameter  $I_{OZ}$  includes the input leakage current. [3]

### **11. Dynamic characteristics**

#### Table 9. Typical dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 9; for wave forms see Fig. 7 and Fig. 8[1]

Symbol	Parameter	Conditions	V <sub>CC(B)</sub>						Unit			
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V				
V <sub>CC(A)</sub> = 0.8 V and T <sub>amb</sub> = 25 °C												
t <sub>pd</sub>	propagation delay	A to B	15.5	8.1	7.6	7.7	8.4	9.2	ns			
		B to A	15.5	12.7	12.3	12.2	12.0	11.8	ns			
t <sub>dis</sub>	disable time	DIR to A	12.2	12.2	12.2	12.2	12.2	12.2	ns			
		DIR to B	11.7	7.9	7.6	8.2	8.7	10.2	ns			
t <sub>en</sub>	enable time	DIR to A	27.2	20.6	19.9	20.4	20.7	22.0	ns			
		DIR to B	27.7	20.3	19.8	19.9	20.6	21.4	ns			

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ ;  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ ;  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{en}$  is a calculated value using the formula shown in <u>Section 12.4</u>

#### Table 10. Typical dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 9; for wave forms see Fig. 7 and Fig. 8[1]

Symbol	Parameter	Conditions	V <sub>CC(A)</sub>						
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	
V <sub>CC(B)</sub> = (	0.8 V and T <sub>amb</sub> = 25	°C							
t <sub>pd</sub>	propagation delay	A to B	15.5	12.7	12.3	12.2	12.0	11.8	ns
		B to A	15.5	8.1	7.6	7.7	8.4	9.2	ns
t <sub>dis</sub>	disable time	DIR to A	12.2	4.9	3.8	3.7	2.8	3.4	ns
		DIR to B	11.7	9.2	9.0	8.8	8.7	8.6	ns
t <sub>en</sub>	enable time	DIR to A	27.2	17.3	16.6	16.5	17.1	17.8	ns
		DIR to B	27.7	17.6	16.1	15.9	14.8	15.2	ns

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ ;  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ ;  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{en}$  is a calculated value using the formula shown in <u>Section 12.4</u>

#### Table 11. Typical power dissipation capacitance

Voltages are referenced to GND (ground = 0 V).[1][2]

Symbol	Parameter	Conditions	$V_{CC(A)} = V_{CC(B)}$						
			0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V	
T <sub>amb</sub> = 25	5 °C								
C <sub>PD</sub>	power dissipation capacitance	A port: (direction A to B); B port: (direction B to A)	1	2	2	2	2	2	pF
		A port: (direction B to A); B port: (direction A to B)	9	11	11	12	14	17	pF

[1]  $C_{PD}$  is used to determine the dynamic power dissipation (P<sub>D</sub> in  $\mu$ W).

 $P_{D} = C_{PD} \times V_{CC}^{2} \times f_{i} \times N + \Sigma (C_{L} \times V_{CC}^{2} \times f_{o}) \text{ where:}$ 

 $f_i$  = input frequency in MHz;

f<sub>o</sub> = output frequency in MHz;

C<sub>L</sub> = load capacitance in pF;

 $V_{CC}$  = supply voltage in V;

N = number of inputs switching;

 $\Sigma(C_L \times V_{CC}^2 \times f_0)$  = sum of the outputs.

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#### Table 12. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 9; for wave forms see Fig. 7 and Fig. 8[1]

Symbol	Parameter	Conditions					Vc	C(B)					Unit
			1.2 V	±0.1 V	1.5 V:	±0.1 V	1.8 V±	:0.15 V	2.5 V	±0.2 V	3.3 V	±0.3 V	1
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	1
V <sub>CC(A)</sub> =	1.1 V to 1.3 V;	T <sub>amb</sub> = -40 °C	to +85 °	°C	1					1		1	
t <sub>pd</sub>	propagation	A to B	1.0	9.0	0.7	6.8	0.6	6.1	0.5	5.7	0.5	6.1	ns
	delay	B to A	1.0	9.0	0.8	8.0	0.7	7.7	0.6	7.2	0.5	7.1	ns
t <sub>dis</sub>	disable time	DIR to A	2.2	8.8	2.2	8.8	2.2	8.8	2.2	8.8	2.2	8.8	ns
		DIR to B	2.2	8.4	1.8	6.7	2.0	6.9	1.7	6.2	2.4	7.2	ns
t <sub>en</sub>	enable time	DIR to A	-	17.4	-	14.7	-	14.6	-	13.4	-	14.3	ns
		DIR to B	-	17.8	-	15.6	-	14.9	-	14.5	-	14.9	ns
V <sub>CC(A)</sub> =	1.4 V to 1.6 V;	T <sub>amb</sub> = -40 °C	to +85 °	°C									
t <sub>pd</sub>	propagation	A to B	1.0	8.0	0.7	5.4	0.6	4.6	0.5	3.7	0.5	3.5	ns
	delay	B to A	1.0	6.8	0.8	5.4	0.7	5.1	0.6	4.7	0.5	4.5	ns
t <sub>dis</sub>	disable time	DIR to A	1.6	6.3	1.6	6.3	1.6	6.3	1.6	6.3	1.6	6.3	ns
		DIR to B	2.0	7.6	1.8	5.9	1.6	6.0	1.2	4.8	1.7	5.5	ns
t <sub>en</sub>	enable time	DIR to A	-	14.4	-	11.3	-	11.1	-	9.5	-	10.0	ns
		DIR to B	-	14.3	-	11.7	-	10.9	-	10.0	-	9.8	ns
V <sub>CC(A)</sub> =	1.65 V to 1.95	V; T <sub>amb</sub> = -40 °	C to +8	5 °C									
t <sub>pd</sub>	propagation	A to B	1.0	7.7	0.6	5.1	0.5	4.3	0.5	3.4	0.5	3.1	ns
	delay	B to A	1.0	6.1	0.7	4.6	0.5	4.4	0.5	3.9	0.5	3.7	ns
t <sub>dis</sub>	disable time	DIR to A	1.6	5.5	1.6	5.5	1.6	5.5	1.6	5.5	1.6	5.5	ns
		DIR to B	1.8	7.7	1.8	5.7	1.4	5.8	1.0	4.5	1.5	5.2	ns
t <sub>en</sub>	enable time	DIR to A	-	13.8	-	10.3	-	10.2	-	8.4	-	8.9	ns
		DIR to B	-	13.2	-	10.6	-	9.8	-	8.9	-	8.6	ns
$V_{CC(A)} =$	2.3 V to 2.7 V;	T <sub>amb</sub> = -40 °C	to +85 °	°C									
t <sub>pd</sub>	propagation	A to B	1.0	7.2	0.5	4.7	0.5	3.9	0.5	3.0	0.5	2.6	ns
	delay	B to A	1.0	5.7	0.6	3.8	0.5	3.4	0.5	3.0	0.5	2.8	ns
t <sub>dis</sub>	disable time	DIR to A	1.5	4.2	1.5	4.2	1.5	4.2	1.5	4.2	1.5	4.2	ns
		DIR to B	1.7	7.3	2.0	5.2	1.5	5.1	0.6	4.2	1.1	4.8	ns
t <sub>en</sub>	enable time	DIR to A	-	13.0	-	9.0	-	8.5	-	7.2	-	7.6	ns
		DIR to B	-	11.4	-	8.9	-	8.1	-	7.2	-	6.8	ns
$V_{CC(A)} =$	3.0 V to 3.6 V;	T <sub>amb</sub> = -40 °C	to +85 °	°C									
t <sub>pd</sub>	propagation	A to B	1.0	7.1	0.5	4.5	0.5	3.7	0.5	2.8	0.5	2.4	ns
	delay	B to A	1.0	6.1	0.6	3.6	0.5	3.1	0.5	2.6	0.5	2.4	ns
t <sub>dis</sub>	disable time	DIR to A	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	ns
		DIR to B	1.7	7.2	0.7	5.5	0.6	5.5	0.7	4.1	1.7	4.7	ns
t <sub>en</sub>	enable time	DIR to A	-	13.3	-	9.1	-	8.6	-	6.7	-	7.1	ns
		DIR to B	-	11.8	-	9.2	-	8.4	-	7.5	-	7.1	ns

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ ;  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ ;  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{en}$  is a calculated value using the formula shown in <u>Section 12.4</u>

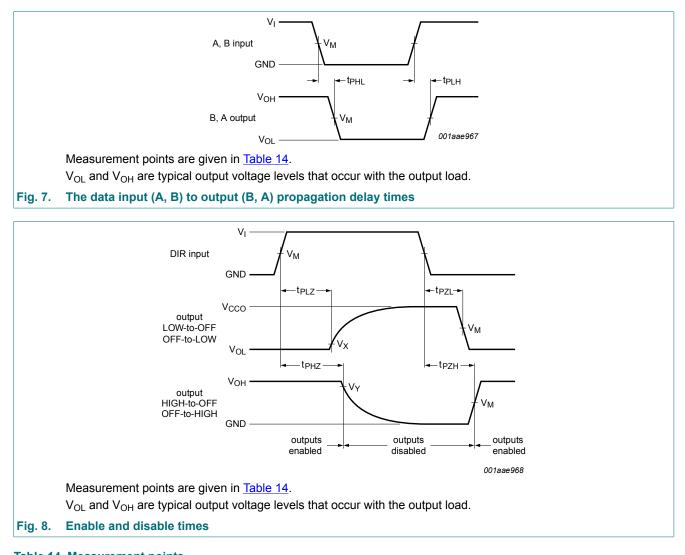
#### Table 13. Dynamic characteristics

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 9; for wave forms see Fig. 7 and Fig. 8[1]

Symbol	Parameter	Conditions					Vc	C(B)					Unit
			1.2 V	±0.1 V	1.5 V:	±0.1 V	1.8 V±	:0.15 V	2.5 V	±0.2 V	3.3 V±0.3 V		
			Min	Max	Min	Max	Min	Мах	Min	Max	Min	Max	
V <sub>CC(A)</sub> =	1.1 V to 1.3 V;	T <sub>amb</sub> = -40 °C	to +125	°C									
t <sub>pd</sub>	propagation	A to B	1.0	9.9	0.7	7.5	0.6	6.8	0.5	6.3	0.5	6.8	ns
	delay	B to A	1.0	9.9	0.8	8.8	0.7	8.5	0.6	8.0	0.5	7.9	ns
t <sub>dis</sub>	disable time	DIR to A	2.2	9.7	2.2	9.7	2.2	9.7	2.2	9.7	2.2	9.7	ns
		DIR to B	2.2	9.2	1.8	7.4	2.0	7.6	1.7	6.9	2.4	8.0	ns
t <sub>en</sub>	enable time	DIR to A	-	19.1	-	16.2	-	16.1	-	14.9	-	15.9	ns
		DIR to B	-	19.6	-	17.2	-	16.5	-	16.0	-	16.5	ns
V <sub>CC(A)</sub> =	1.4 V to 1.6 V;	T <sub>amb</sub> = -40 °C	to +125	°C									
t <sub>pd</sub>	propagation	A to B	1.0	8.8	0.7	6.0	0.6	5.1	0.5	4.1	0.5	3.9	ns
	delay	B to A	1.0	7.5	0.8	6.0	0.7	5.7	0.6	5.2	0.5	5.0	ns
t <sub>dis</sub>	disable time	DIR to A	1.6	7.0	1.6	7.0	1.6	7.0	1.6	7.0	1.6	7.0	ns
		DIR to B	2.0	8.3	1.8	6.5	1.6	6.6	1.2	5.3	1.7	6.1	ns
t <sub>en</sub>	enable time	DIR to A	-	15.8	-	12.5	-	12.3	-	10.5	-	11.1	ns
		DIR to B	-	15.8	-	13.0	-	12.1	-	11.1	-	10.9	ns
$V_{CC(A)} =$	1.65 V to 1.95	V; T <sub>amb</sub> = -40 °	'C to +1	25 °C	I	1	1	1		1	1	1	1
t <sub>pd</sub>	propagation	A to B	1.0	8.5	0.6	5.7	0.5	4.8	0.5	3.8	0.5	3.5	ns
	delay	B to A	1.0	6.8	0.7	5.1	0.5	4.9	0.5	4.3	0.5	4.1	ns
t <sub>dis</sub>	disable time	DIR to A	1.6	6.1	1.6	6.1	1.6	6.1	1.6	6.1	1.6	6.1	ns
		DIR to B	1.8	8.5	1.8	6.3	1.4	6.4	1.0	5.0	1.5	5.8	ns
t <sub>en</sub>	enable time	DIR to A	-	15.3	-	11.4	-	11.3	-	9.3	-	9.9	ns
		DIR to B	-	14.6	-	11.8	-	10.9	-	9.9	-	9.6	ns
V <sub>CC(A)</sub> =	2.3 V to 2.7 V;	T <sub>amb</sub> = -40 °C	to +125	°C									
t <sub>pd</sub>	propagation	A to B	1.0	8.0	0.5	5.2	0.5	4.3	0.5	3.3	0.5	2.9	ns
	delay	B to A	1.0	6.3	0.6	4.2	0.5	3.8	0.5	3.3	0.5	3.1	ns
t <sub>dis</sub>	disable time	DIR to A	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	1.5	4.7	ns
		DIR to B	1.7	8.0	2.0	5.8	1.5	5.7	0.6	4.7	1.1	5.3	ns
t <sub>en</sub>	enable time	DIR to A	-	14.3	-	10.0	-	9.5	-	8.0	-	8.4	ns
		DIR to B	-	12.7	-	9.9	-	9.0	-	8.0	-	7.6	ns
V <sub>CC(A)</sub> =	3.0 V to 3.6 V;	T <sub>amb</sub> = -40 °C	to +125	°C									-
t <sub>pd</sub>	propagation	A to B	1.0	7.9	0.5	5.0	0.5	4.1	0.5	3.1	0.5	2.7	ns
	delay	B to A	1.0	6.8	0.6	4.0	0.5	3.5	0.5	2.9	0.5	2.7	ns
t <sub>dis</sub>	disable time	DIR to A	1.5	5.2	1.5	5.2	1.5	5.2	1.5	5.2	1.5	5.2	ns
		DIR to B	1.7	7.9	0.7	6.1	0.6	6.1	0.7	4.6	1.7	5.2	ns
t <sub>en</sub>	enable time	DIR to A	-	14.7	-	10.1	-	9.6	-	7.5	-	7.9	ns
		DIR to B	-	13.1	-	10.2	-	9.3	-	8.3	-	7.9	ns

[1]  $t_{pd}$  is the same as  $t_{PLH}$  and  $t_{PHL}$ ;  $t_{dis}$  is the same as  $t_{PLZ}$  and  $t_{PHZ}$ ;  $t_{en}$  is the same as  $t_{PZL}$  and  $t_{PZH}$ .  $t_{en}$  is a calculated value using the formula shown in <u>Section 12.4</u>

### 11.1. Waveforms and test circuit

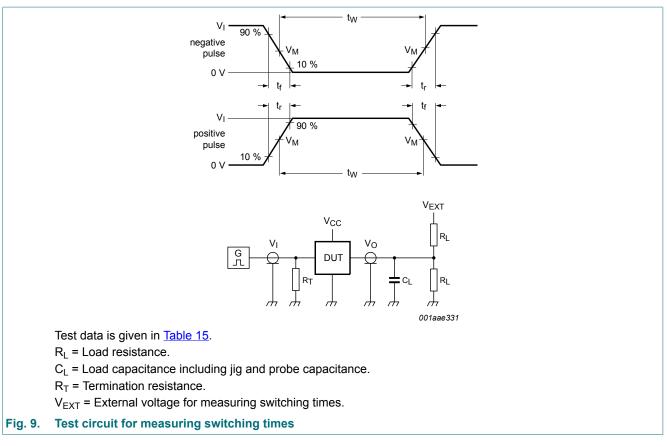


Supply voltage	Input [1]	Output [2]	Output [2]			
V <sub>CC(A)</sub> , V <sub>CC(B)</sub>	V <sub>M</sub>	V <sub>M</sub>	V <sub>X</sub>	V <sub>Y</sub>		
1.1 V to 1.6 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.1 V	V <sub>OH</sub> - 0.1 V		
1.65 V to 2.7 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.15 V	V <sub>OH</sub> - 0.15 V		
3.0 V to 3.6 V	0.5V <sub>CCI</sub>	0.5V <sub>CCO</sub>	V <sub>OL</sub> + 0.3 V	V <sub>OH</sub> - 0.3 V		

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2]  $V_{CCO}$  is the supply voltage associated with the output port.

#### Dual-supply voltage level translator/transceiver; 3-state



#### Table 15. Test data

Supply voltage	Supply voltage Input		Load		V <sub>EXT</sub>			
$V_{CC(A)}, V_{CC(B)}$	V <sub>I</sub> [1]	Δt/ΔV [2]	CL	RL	t <sub>PLH</sub> , t <sub>PHL</sub>	t <sub>PZH</sub> , t <sub>PHZ</sub>	t <sub>PZL</sub> , t <sub>PLZ</sub> [3]	
1.1 V to 1.6 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V <sub>CCO</sub>	
1.65 V to 2.7 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V <sub>CCO</sub>	
3.0 V to 3.6 V	V <sub>CCI</sub>	≤ 1.0 ns/V	15 pF	2 kΩ	open	GND	2V <sub>CCO</sub>	

[1]  $V_{CCI}$  is the supply voltage associated with the data input port.

[2] dV/dt ≥ 1.0 V/ns

[3]  $V_{CCO}$  is the supply voltage associated with the output port.

### **12.** Application information

#### 12.1. Unidirectional logic level-shifting application

The circuit given in Fig. 10 is an example of the 74AVC1T45 being used in an unidirectional logic level-shifting application.

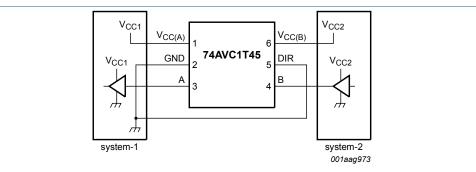
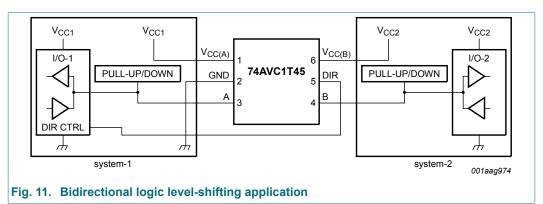


Fig. 10. Unidirectional logic level-shifting application

Pin	Name	Function	Description
1	V <sub>CC(A)</sub>	V <sub>CC1</sub>	supply voltage of system-1 (0.8 V to 3.6 V)
2	GND	GND	device GND
3	A	OUT	output level depends on V <sub>CC1</sub> voltage
4	В	IN	input threshold value depends on $V_{\text{CC2}}$ voltage
5	DIR	DIR	the GND (LOW level) determines B port to A port direction
6	V <sub>CC(B)</sub>	V <sub>CC2</sub>	supply voltage of system-2 (0.8 V to 3.6 V)

#### 12.2. Bidirectional logic level-shifting application

Fig. 11 shows the 74AVC1T45 being used in a bidirectional logic level-shifting application. Since the device does not have an output enable pin, the system designer should take precautions to avoid bus contention between system-1 and system-2 when changing directions.



<u>Table 17</u> gives a sequence that will illustrate data transmission from system-1 to system-2 and then from system-2 to system-1.

 Table 17. Description bidirectional logic level-shifting application

H = HIGH voltage level; L = LOW voltage level; Z = high-impedance OFF-state.

State	DIR CTRL	I/O-1	I/O-2	Description
1	Н	output	input	system-1 data to system-2
2	Н	Z	Z	system-2 is getting ready to send data to system-1. I/O-1 and I/O-2 are disabled. The bus-line state depends on bus hold.
3	L	Z	Z	DIR bit is set LOW. I/O-1 and I/O-2 still are disabled. The bus-line state depends on bus hold.
4	L	input	output	system-2 data to system-1

#### 12.3. Power-up considerations

The device is designed such that no special power-up sequence is required other than GND being applied first.

V <sub>CC(A)</sub>	V <sub>CC(B)</sub>	V <sub>CC(B)</sub>							
	0 V	0.8 V	1.2 V	1.5 V	1.8 V	2.5 V	3.3 V		
0 V	0	0.1	0.1	0.1	0.1	0.1	0.1	μA	
0.8 V	0.1	0.1	0.1	0.1	0.1	0.7	2.3	μA	
1.2 V	0.1	0.1	0.1	0.1	0.1	0.3	1.4	μA	
1.5 V	0.1	0.1	0.1	0.1	0.1	0.1	0.9	μA	
1.8 V	0.1	0.1	0.1	0.1	0.1	0.1	0.5	μA	
2.5 V	0.1	0.7	0.3	0.1	0.1	0.1	0.1	μA	
3.3 V	0.1	2.3	1.4	0.9	0.5	0.1	0.1	μA	

#### Table 18. Typical total supply current (I<sub>CC(A)</sub> + I<sub>CC(B)</sub>)

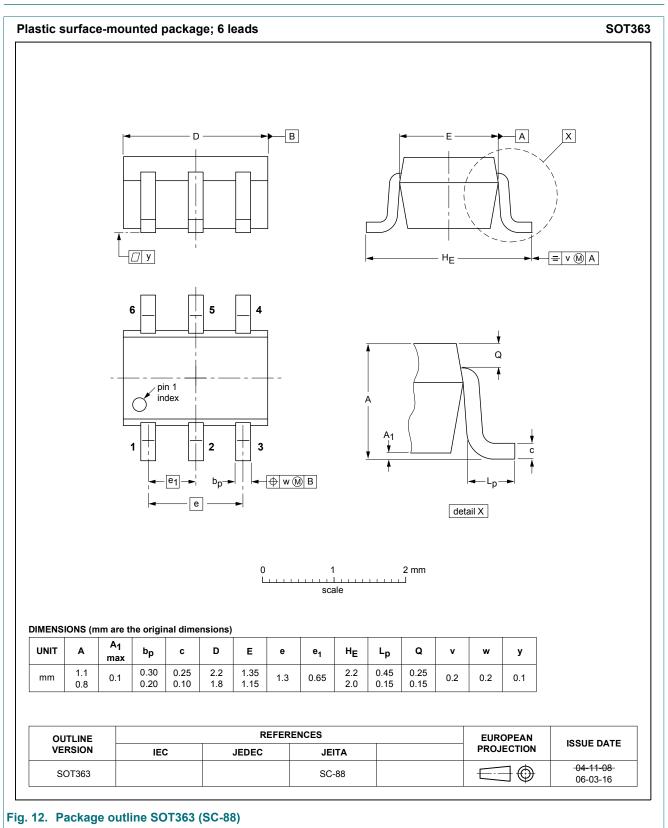
#### 12.4. Enable times

Calculate the enable times for the 74AVC1T45 using the following formulas:

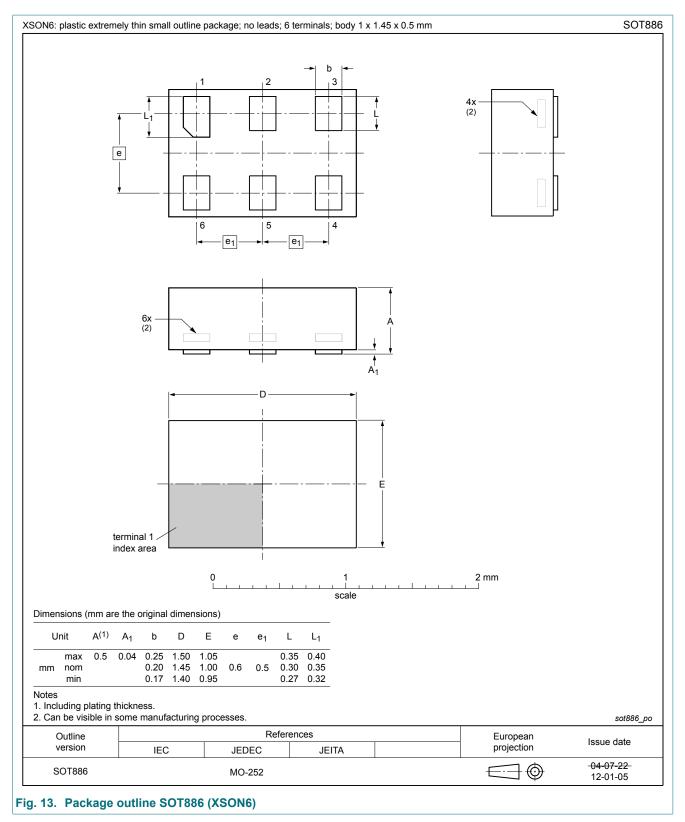
- $t_{en}$  (DIR to A) =  $t_{dis}$  (DIR to B) +  $t_{pd}$  (B to A)
- $t_{en}$  (DIR to B) =  $t_{dis}$  (DIR to A) +  $t_{pd}$  (A to B)

In a bidirectional application, these enable times provide the maximum delay from the time the DIR bit is switched until an output is expected. For example, if the 74AVC1T45 initially is transmitting from A to B, then the DIR bit is switched, the B port of the device must be disabled before presenting it with an input. After the B port has been disabled, an input signal applied to it appears on the corresponding A port after the specified propagation delay.

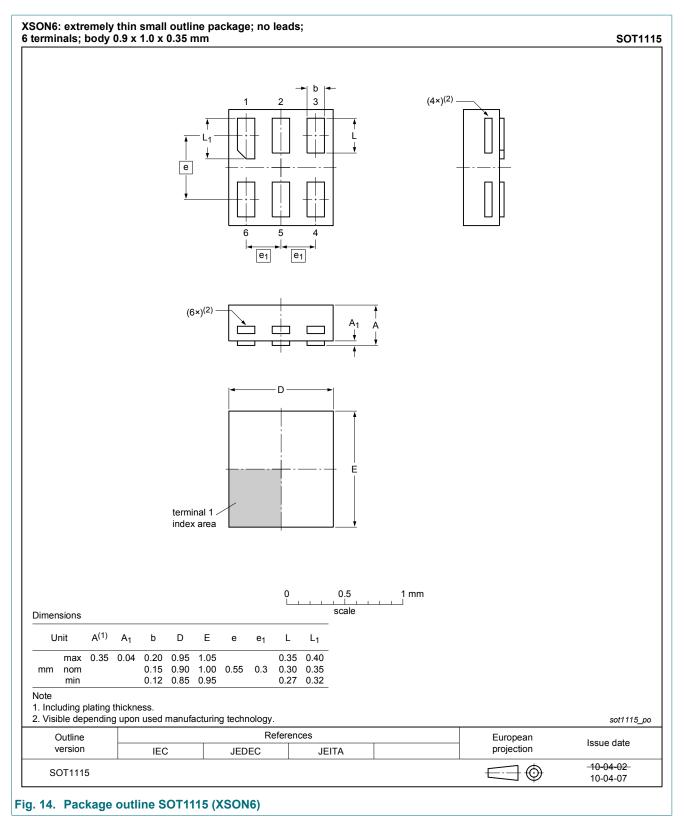
### 13. Package outline



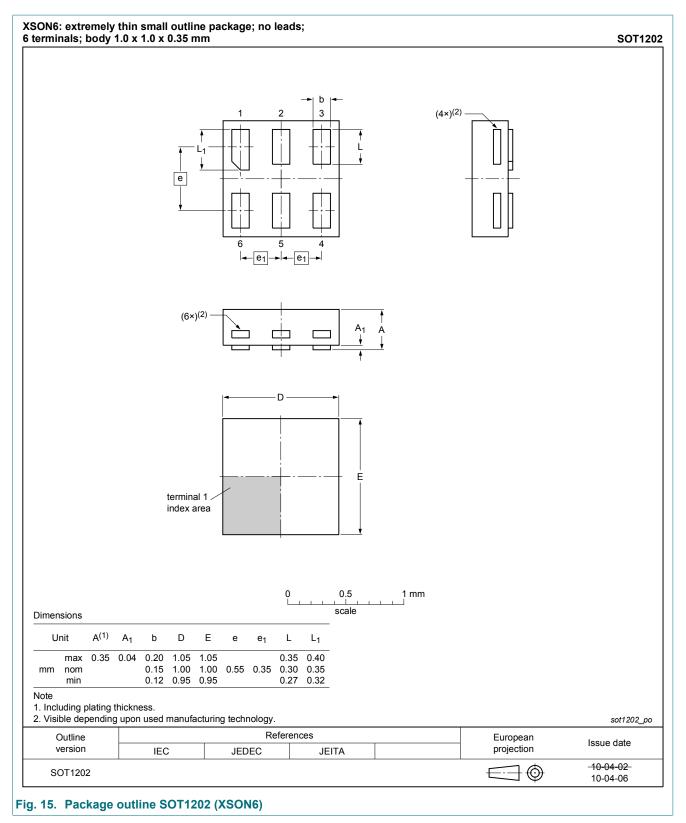
#### Dual-supply voltage level translator/transceiver; 3-state



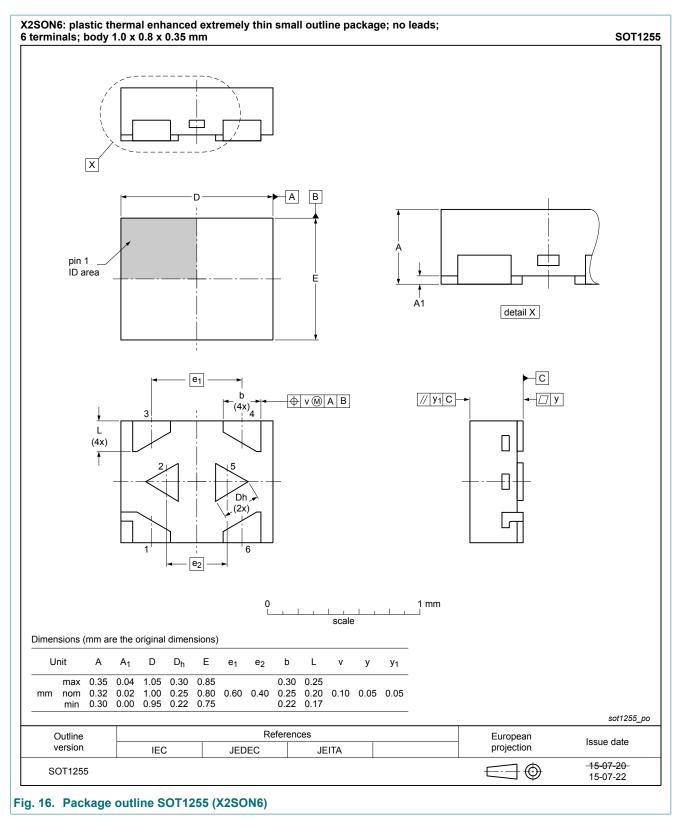
#### Dual-supply voltage level translator/transceiver; 3-state



#### Dual-supply voltage level translator/transceiver; 3-state



#### Dual-supply voltage level translator/transceiver; 3-state



### 14. Abbreviations

Acronym	Description
CDM	Charged Device Model
CMOS	Complementary Metal Oxide Semiconductor
DUT	Device Under Test
ESD	ElectroStatic Discharge
HBM	Human Body Model
ММ	Machine Model

### 15. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
74AVC1T45 v.8	20181210	Product data sheet	-	74AVC1T45 v.7
74AVC1T45 v.7	20170824	Product data sheet	-	74AVC1T45 v.6
Modifications:	Nexperia.	this data sheet has been re	•	
74AVC1T45 v.6	20160420	Product data sheet	-	74AVC1T45 v.5
Modifications:	Added type n	umber 74AVC1T45GX(SOT	1255/X2SON6 package	e).
74AVC1T45 v.5	20160106	Product data sheet	-	74AVC1T45 v.4
Modifications:	• <u>Table 16</u> : Lab	els for pins 4 and 5 correcte	ed.	
74AVC1T45 v.4	20120622	Product data sheet	-	74AVC1T45 v.3
Modifications:	Package outl	ine drawing of SOT886 (Fig	. 13) modified.	
74AVC1T45 v.3	20111021	Product data sheet	-	74AVC1T45 v.2
Modifications:		umber 74AVC1T45GN (SO umber 74AVC1T45GS (SO		,
74AVC1T45 v.2	20090505	Product data sheet	-	74AVC1T45 v.1
74AVC1T45 v.1	20080118	Product data sheet	-	-

### 16. Legal information

#### Data sheet status

Document status [1][2]	Product status [3]	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

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[2] The term 'short data sheet' is explained in section "Definitions".

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Product data sheet

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