

NXS0101

Dual supply translating transceiver; open drain; auto direction sensing Rev. 5 — 16 November 2023 Pro-

Product data sheet

1. General description

The NXS0101 is a 1-bit, dual supply translating transceiver with auto direction sensing, that enables bidirectional voltage level translation. It features one 1-bit input-output port (A and B), one output enable input (OE) and two supply pins ($V_{CC(A)}$ and $V_{CC(B)}$). $V_{CC(A)}$ can be supplied at any voltage between 1.65 V and 3.6 V and $V_{CC(B)}$ can be supplied at any voltage between 2.3 V and 5.5 V, making the device suitable for translating between any of the voltage nodes (1.8 V, 2.5 V, 3.3 V and 5.0 V). Pins A and OE are referenced to $V_{CC(A)}$ and pin B is referenced to $V_{CC(B)}$. A LOW level at pin OE causes the output to assume a high-impedance OFF-state. This device is fully specified for partial power-down applications using I_{OFF} . The I_{OFF} circuitry disables the output, preventing the damaging backflow current through the device when it is powered down.

2. Features and benefits

- Wide supply voltage range:
 - $V_{CC(A)}$: 1.65 V to 3.6 V and $V_{CC(B)}$: 2.3 V to 5.5 V
- Maximum data rates:
 - Push-pull: 24 Mbps
- I_{OFF} circuitry provides partial Power-down mode operation
- Inputs accept voltages up to 5.5 V
- ESD protection:
 - HBM: ANSI/ESDA/JEDEC JS-001 class 2 exceeds 2500 V for A port
 - HBM: ANSI/ESDA/JEDEC JS-001 class 3B exceeds 8000 V for B port
 - CDM: ANSI/ESDA/JEDEC JS-002 class C3 exceeds 1500 V
- Latch-up performance exceeds 100 mA per JESD 78B Class II
- Multiple package options
- Specified from -40 °C to +85 °C and -40 °C to +125 °C

3. Applications

- Desktop PC
- Handset
- Smartphone
- Tablet

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4. Ordering information

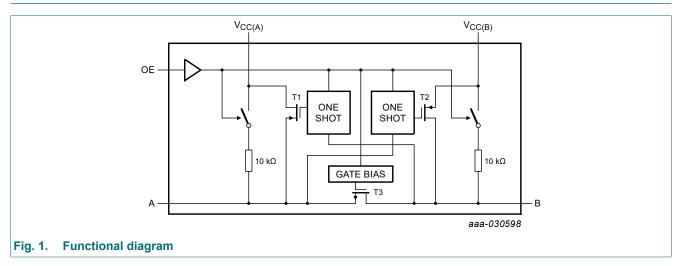
| Type number | Package | | | | | | | | |
|-------------|-------------------|--------|--|-----------------|--|--|--|--|--|
| | Temperature range | Name | Description | Version | | | | | |
| NXS0101GW | -40 °C to +125 °C | TSSOP6 | plastic thin shrink small outline package; 6 leads; body width 1.25 mm | <u>SOT363-2</u> | | | | | |
| NXS0101GM | -40 °C to +125 °C | XSON6 | plastic extremely thin small outline package; no leads; 6 terminals; body 1 × 1.45 × 0.5 mm | <u>SOT886</u> | | | | | |
| NXS0101GS | -40 °C to +125 °C | XSON6 | extremely thin small outline package; no leads; 6 terminals; body 1.0 × 1.0 × 0.35 mm | <u>SOT1202</u> | | | | | |

5. Marking

| Table 2. Marking | | | | | |
|------------------|-----------------|--|--|--|--|
| Type number | Marking code[1] | | | | |
| NXS0101GW | m1 | | | | |
| NXS0101GM | m1 | | | | |
| NXS0101GS | m1 | | | | |

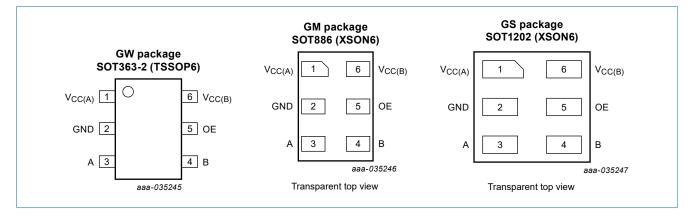
[1] The pin 1 indicator is located on the lower left corner of the device, below the marking code.

6. Functional diagram



7. Pinning information

7.1. Pinning



7.2. Pin description

| Table 3. Pin description | | |
|--------------------------|-----|---|
| Symbol | Pin | Description |
| V _{CC(A)} | 1 | supply voltage A |
| GND | 2 | ground (0 V) |
| A | 3 | data input or output (referenced to $V_{CC(A)}$) |
| В | 4 | data input or output (referenced to $V_{CC(B)}$) |
| OE | 5 | output enable input (active HIGH; referenced to $V_{CC(A)}$) |
| V _{CC(B)} | 6 | supply voltage B |

8. Functional description

Table 4. Function table

H = HIGH voltage level; L = LOW voltage level; X = don't care; Z = high-impedance OFF-state.

| Supply voltage | | Input | Input/output | | |
|---|----------------|-------|-----------------|-----------------|--|
| V _{CC(A)} [1] V _{CC(B)} | | OE | Α | В | |
| 1.65 V to 3.6 V | 2.3 V to 5.5 V | L | Z | Z | |
| 1.65 V to 3.6 V | 2.3 V to 5.5 V | Н | input or output | output or input | |
| GND | 2.3 V to 5.5 V | Х | Z | Z | |
| 1.65 V to 3.6 V | GND | Х | Z | Z | |

 $\label{eq:VCC(A)} \mbox{ must be less than or equal to } V_{CC(B)}.$

9. Limiting values

Table 5. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134). Voltages are referenced to GND (ground = 0 V).

| Symbol | Parameter | Conditions | | Min | Max | Unit |
|--------------------|-------------------------|--|-----------|------|------------------------|------|
| V _{CC(A)} | supply voltage A | | | -0.5 | +6.5 | V |
| V _{CC(B)} | supply voltage B | | | -0.5 | +6.5 | V |
| VI | input voltage | OE | [1] | -0.5 | +6.5 | V |
| | | Power-down or 3-state mode | | | | |
| | | A, B | [1] | -0.5 | +6.5 | V |
| | | Active mode | | | | |
| | | A, B | [1][2][3] | -0.5 | V _{CCI} + 0.5 | V |
| Vo | output voltage | Power-down or 3-state mode | | | | |
| | | А, В | [1] | -0.5 | +6.5 | V |
| | | Active mode | | | | |
| | | А, В | [1][3][4] | -0.5 | V _{CCO} + 0.5 | V |
| I _{IK} | input clamping current | V ₁ < 0 V | | -50 | - | mA |
| I _{ОК} | output clamping current | V _O < 0 V | | -50 | - | mA |
| l _o | output current | $V_0 = 0 V$ to V_{CCO} | [4] | - | ±50 | mA |
| I _{CC} | supply current | I _{CC(A)} or I _{CC(B)} | | - | 100 | mA |
| I _{GND} | ground current | | | -100 | - | mA |
| T _{stg} | storage temperature | | | -65 | +150 | °C |
| P _{tot} | total power dissipation | T _{amb} = -40 °C to +125 °C | [5] | - | 250 | mW |

[1] The minimum input and minimum output voltage ratings may be exceeded if the input and output current ratings are observed.

[2] V_{CCI} is the supply voltage associated with the input.

[3] V_{CCI} + 0.5 V or V_{CCO} + 0.5 V should not exceed 6.5 V.

[4] V_{CCO} is the supply voltage associated with the output.

[5] For SOT363-2 (TSSOP6) package: P_{tot} derates linearly with 3.7 mW/K above 83 °C.

For SOT886 (XSON6) package: Ptot derates linearly with 3.3 mW/K above 74 °C.

For SOT1202 (XSON6) package: Ptot derates linearly with 3.3 mW/K above 74 °C.

10. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|--------------------|-------------------------------------|--|------|------------------|-------------|
| V _{CC(A)} | supply voltage A | | 1.65 | 3.6 | V |
| V _{CC(B)} | supply voltage B | | 2.3 | 5.5 | V |
| VI | input voltage | OE | 0 | 5.5 | V |
| | | Power-down or 3-state mode | | | |
| | | A | 0 | 3.6 | V |
| | | В | 0 | 5.5 | V V V |
| | | Active mode | | | |
| | | A, B [3] | 0 | V _{CCI} | V |
| Vo | output voltage | Power-down or 3-state mode | | | |
| | | A | 0 | 3.6 | V |
| | | В | 0 | 5.5 | V |
| | | Active mode | | | |
| | | A, B [4] | 0 | V _{CCO} | V |
| T _{amb} | ambient temperature | | -40 | +125 | °C |
| Δt/ΔV | input transition rise and fall rate | A or B port; push-pull driving | | | |
| | | $V_{CC(A)} = 1.65 V \text{ to } 3.6 V;$ $V_{CC(B)} = 2.3 V \text{ to } 5.5 V$ | - | 10 | ns/V |
| | | OE input | | | |
| | | $V_{CC(A)} = 1.65 V \text{ to } 3.6 V;$ $V_{CC(B)} = 2.3 V \text{ to } 5.5 V$ | - | 10 | ns/V |

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[1] The A and B sides of an unused I/O pair must be held in the same state, both at V_{CCI} or both at GND.

[2]

 $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}.$ V_{CCI} is the supply voltage associated with the input. [3]

 V_{CCO} is the supply voltage associated with the output. [4]

11. Static characteristics

Table 7. Typical static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.[1]

| Symbol | Parameter | Conditions | Min | Тур | Max | Unit |
|------------------|-----------------------------|---|-----|-----|------|------|
| I _I | input leakage current | OE input; V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | - | ±1 | μA |
| I _{OZ} | OFF-state output current | A or B port; $V_{CC(A)} = 1.65 \text{ V to } 3.6 \text{ V}; V_{CC(B)} = 2.3 \text{ V to } 5.5 \text{ V}; \text{ OE} = 0 \text{ V}$ | - | - | ±1 | μA |
| I _{OFF} | power-off | A port; $V_{CC(A)} = 0 V$; $V_{CC(B)} = 0 V$ to 5.5 V | - | - | ±1 | μA |
| | leakage current | B port; $V_{CC(B)} = 0 V$; $V_{CC(A)} = 0 V$ to 3.6 V | - | - | ±1 | μA |
| CI | input capacitance | OE input; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V | - | 1.6 | - | pF |
| C _{I/O} | input/output | A port; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V | | | | |
| | capacitance | enabled | - | 10 | ±1 µ | pF |
| | | disabled | - | 4 | - | pF |
| | | B port; V _{CC(A)} = 3.3 V; V _{CC(B)} = 3.3 V | | | | |
| | | enabled | - | 10 | - | pF |
| | | disabled | - | 7 | - | pF |

[1] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

Table 8. Typical supply current

At recommended operating conditions; voltages are referenced to GND (ground = 0 V); T_{amb} = 25 °C.

| V _{CC(A)} | | V _{CC(B)} | | | | | | |
|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|--------------------|----|--|
| | 2.5 | 5 V | 3. | 3 V | 5.0 | V | | |
| | I _{CC(A)} | I _{CC(B)} | I _{CC(A)} | I _{CC(B)} | I _{CC(A)} | I _{CC(B)} | | |
| 1.8 V | 0.1 | 0.5 | 0.1 | 1.5 | 0.1 | 4.6 | μA | |
| 2.5 V | 0.1 | 0.1 | 0.1 | 0.8 | 0.1 | 3.8 | μA | |
| 3.3 V | - | - | 0.1 | 0.1 | 0.1 | 2.8 | μA | |

Table 9. Static characteristics

At recommended operating conditions; voltages are referenced to GND (ground = 0 V).[1]

| Symbol | Parameter | Conditions | -40 °C to | • +85 °C | -40 °C to | +125 °C | Unit |
|-----------|---------------|---|--------------------------|--------------------|--------------------------|--------------------|------|
| | | | Min | Max | Min | Max | |
| VIH | HIGH-level | A port | | | | | |
| input vol | input voltage | V _{CC(A)} = 1.65 V to 1.95 V; V _{CC(B)} = 2.3 V to 5.5 V | V _{CC(A)} - 0.2 | V _{CC(A)} | V _{CC(A)} - 0.2 | V _{CC(A)} | V |
| | | V _{CC(A)} = 2.3 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | V _{CC(A)} - 0.4 | V _{CC(A)} | V _{CC(A)} - 0.4 | V _{CC(A)} | V |
| | | B port | | | | | |
| | | $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V | V _{CC(B)} - 0.4 | V _{CC(B)} | V _{CC(B)} - 0.4 | V _{CC(B)} | V |
| | | OE input | | | | | |
| | | $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V | 0.65V _{CC(A)} | V _{CC(A)} | 0.65V _{CC(A)} | V _{CC(A)} | V |

| Symbol | Parameter | Conditions | -40 °C t | o +85 °C | -40 °C to | o +125 °C | Unit |
|------------------|-----------------------------|--|------------------------|------------------------|------------------------|------------------------|------|
| | | | Min | Max | Min | Мах | 1 |
| VIL | LOW-level | A or B port | | | | | |
| | input voltage | $V_{CC(A)}$ = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | 0 | 0.15 | 0 | 0.15 | V |
| | | OE input | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | 0 | 0.35V _{CC(A)} | 0 | 0.35V _{CC(A)} | V |
| V _{OH} | HIGH-level | A port; I_O = -20 µA; $V_I \ge V_{CC(B)}$ - 0.4 V | | | | | |
| | output voltage | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | 0.67V _{CC(A)} | - | 0.67V _{CC(A)} | - | V |
| | | B port; $I_O = -20 \ \mu A$; $V_I \ge V_{CC(A)} - 0.2 \ V$ | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | 0.67V _{CC(B)} | - | 0.67V _{CC(B)} | - | V |
| V _{OL} | LOW-level | A or B port; I _O = 1 mA; V _I ≤ 0.15 V | | | | | |
| | output voltage | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 0.4 | - | 0.4 | V |
| I _I | input leakage current | OE input; $V_{CC(A)} = 1.65$ V to 3.6 V; $V_{CC(B)} = 2.3$ V to 5.5 V | - | ±2 | - | ±12 | μA |
| I _{OZ} | OFF-state output current | A or B port; $V_{CC(A)} = 1.65$ V to 3.6 V; $V_{CC(B)} = 2.3$ V to 5.5 V | - | ±2 | - | ±12 | μA |
| I _{OFF} | power-off leakage | A port; $V_{CC(A)} = 0 V$; $V_{CC(B)} = 0 V$ to 5.5 V | - | ±2 | - | ±12 | μA |
| | current | B port; $V_{CC(B)} = 0 V$; $V_{CC(A)} = 0 V$ to 3.6 V | - | ±2 | - | ±12 | μA |
| I _{CC} | supply current | $OE = 0 V \text{ or } V_{CC(A)}$; An, Bn open | | | | | |
| | | I _{CC(A)} | | | | | |
| | | $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V | - | 2.4 | - | 15 | μA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | 2.2 | - | 15 | μA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | -1 | - | -8 | μA |
| | | I _{CC(B)} | | | | | |
| | | $V_{CC(A)}$ = 1.65 V to 3.6 V; $V_{CC(B)}$ = 2.3 V to 5.5 V | - | 12 | - | 30 | μA |
| | | V _{CC(A)} = 3.6 V; V _{CC(B)} = 0 V | - | -1 | - | -5 | μA |
| | | V _{CC(A)} = 0 V; V _{CC(B)} = 5.5 V | - | 1 | - | 6 | μA |
| | | $I_{CC(A)} + I_{CC(B)}$ | | | | | |
| | | V _{CC(A)} = 1.65 V to 3.6 V; V _{CC(B)} = 2.3 V to 5.5 V | - | 14.4 | - | 30 | μA |

[1] $V_{CC(A)}$ must be less than or equal to $V_{CC(B)}$.

12. Dynamic characteristics

Table 10. Dynamic characteristics for temperature range -40 °C to +85 °C

Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 5; for waveforms see Fig. 2 to Fig. 4.

| Symbol | Parameter | Conditions | | | Vc | C(B) | | | Unit |
|----------------------|----------------------------------|-----------------------------------|-------|---------|-------|---------|---------|---------|------|
| | | | 2.5 V | ± 0.2 V | 3.3 V | ± 0.3 V | 5.0 V : | ± 0.5 V |] |
| | | | Min | Max | Min | Max | Min | Мах | |
| V _{CC(A)} = | 1.8 V ± 0.15 V | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 4.6 | - | 4.7 | - | 5.8 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 7.1 | - | 6.8 | - | 7.0 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 4.4 | - | 4.5 | - | 4.7 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 5.3 | - | 4.5 | - | 0.5 | ns |
| t _{en} | enable time | OE to A, B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A, B; no external load [1][| 2] - | 25 | - | 25 | - | 25 | ns |
| | | OE to A | - | 140 | - | 140 | - | 145 | ns |
| | | OE to B | - | 125 | - | 175 | - | 125 | ns |
| t _{TLH} | LOW to HIGH | A port | 3.2 | 9.5 | 2.3 | 9.3 | 1.8 | 7.6 | ns |
| | output transition time | B port | 3.3 | 10.8 | 2.7 | 9.1 | 2.7 | 7.6 | ns |
| t _{THL} | HIGH to LOW | A port | 2.0 | 5.9 | 1.9 | 6.0 | 1.7 | 13.3 | ns |
| | output transition time | B port | 2.9 | 7.6 | 2.8 | 7.9 | 2.8 | 10.5 | ns |
| t _W | pulse width | data inputs | 41 | - | 41 | - | 41 | - | ns |
| f _{data} | data rate | | - | 24 | - | 24 | - | 24 | Mbps |
| $V_{CC(A)} =$ | 2.5 V ± 0.2 V | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 3.2 | - | 3.3 | - | 3.4 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 3.5 | - | 4.4 | - | 4.6 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 3.0 | - | 3.6 | - | 4.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 2.5 | - | 1.6 | - | 0.7 | ns |
| t _{en} | enable time | OE to A, B | - | 200 | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A, B; no external load [1][| 2] - | 20 | - | 20 | - | 20 | ns |
| | | OE to A | - | 105 | - | 105 | - | 105 | ns |
| | | OE to B | - | 125 | - | 175 | - | 120 | ns |
| t _{TLH} | LOW to HIGH | A port | 2.8 | 7.5 | 2.6 | 6.6 | 1.8 | 6.5 | ns |
| | output transition time | B port | 3.2 | 8.5 | 2.9 | 7.9 | 2.4 | 6.8 | ns |
| t _{THL} | HIGH to LOW | A port | 1.9 | 5.7 | 1.9 | 5.5 | 1.8 | 5.3 | ns |
| | output transition time | B port | 2.2 | 7.8 | 2.4 | 6.7 | 2.6 | 6.9 | ns |
| t _W | pulse width | data inputs | 41 | - | 41 | - | 41 | - | ns |
| f _{data} | data rate | | - | 24 | - | 24 | - | 24 | Mbps |

| Symbol | Parameter | Conditions | | | Vc | C(B) | | | Unit |
|----------------------|----------------------------------|-------------------------------------|-------|---------|-----|---------|---------|---------|------|
| | | | 2.5 V | ± 0.2 V | | ± 0.3 V | 5.0 V : | ± 0.5 V | - |
| | | | Min | Max | Min | Max | Min | Max | - |
| V _{CC(A)} = | 3.3 V ± 0.3 V | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | - | - | 2.4 | - | 3.1 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | - | - | 4.2 | - | 4.4 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | - | - | 2.5 | - | 3.3 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | - | - | 2.5 | - | 2.6 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A, B; no external load [1][2] | - | - | - | 15 | - | 15 | ns |
| | | OE to A | - | - | - | 150 | - | 150 | ns |
| | | OE to B | - | - | - | 170 | - | 120 | ns |
| t _{TLH} | LOW to HIGH | A port | - | - | 2.3 | 6.2 | 1.9 | 6.3 | ns |
| | output transition time | B port | - | - | 2.5 | 6.9 | 2.1 | 7.4 | ns |
| t _{THL} | HIGH to LOW | A port | - | - | 2.0 | 5.4 | 1.9 | 5.0 | ns |
| | output transition time | B port | - | - | 2.3 | 7.4 | 2.4 | 7.6 | ns |
| t _W | pulse width | data inputs | - | - | 41 | - | 41 | - | ns |
| f _{data} | data rate | | - | - | - | 24 | - | 24 | Mbps |

[1]

t_{dis} is the same as t_{PLZ} and t_{PHZ}. The disable time with no external load indicates the delay between when OE goes LOW and when outputs actually become disabled. [2]

Table 11. Dynamic characteristics for temperature range -40 °C to +125 °C

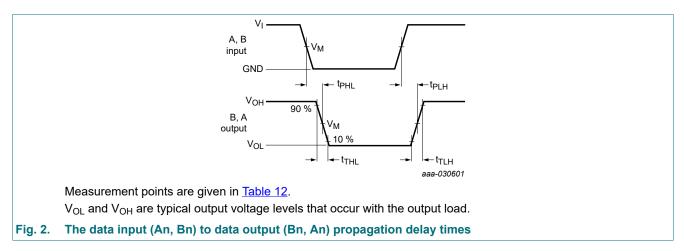
Voltages are referenced to GND (ground = 0 V); for test circuit see Fig. 5; for waveforms see Fig. 2 to Fig. 4.

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit | |
|----------------------|----------------------------------|-------------------------------------|--------------------|------|-------|---------------|-----|---------------|------|--|
| | | | 2.5 V ± 0.2 V 3.5 | | 3.3 V | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Max | - | |
| $V_{CC(A)} =$ | 1.8 V ± 0.15 V | | | 1 | 1 | 1 | I | 1 | 1 | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 5.8 | - | 5.9 | - | 7.3 | ns | |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 8.5 | - | 8.5 | - | 8.8 | ns | |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 5.5 | - | 5.7 | - | 5.9 | ns | |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 6.7 | - | 5.7 | - | 0.7 | ns | |
| t _{en} | enable time | OE to A, B | - | 200 | - | 200 | - | 200 | ns | |
| t _{dis} | disable time | OE to A, B; no external load [1][2] | - | 30 | - | 30 | - | 30 | ns | |
| | | OE to A | - | 140 | - | 140 | - | 250 | ns | |
| | | OE to B | - | 125 | - | 175 | - | 125 | ns | |
| t _{TLH} | LOW to HIGH | A port | 3.2 | 11.9 | 2.3 | 11.7 | 1.8 | 9.5 | ns | |
| | output transition time | B port | 3.3 | 13.5 | 2.7 | 11.4 | 2.7 | 9.5 | ns | |
| t _{THL} | HIGH to LOW | A port | 2.0 | 7.4 | 1.9 | 7.5 | 1.7 | 16.7 | ns | |
| | output transition time | B port | 2.9 | 9.5 | 2.8 | 9.4 | 2.8 | 12.5 | ns | |
| t _W | pulse width | data inputs | 50 | - | 41 | - | 41 | - | ns | |
| f _{data} | data rate | | - | 20 | - | 24 | - | 24 | Mbps | |
| V _{CC(A)} = | 2.5 V ± 0.2 V | | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | 4.0 | - | 4.2 | - | 4.3 | ns | |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | 4.4 | - | 5.2 | - | 5.5 | ns | |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | 3.8 | - | 4.5 | - | 5.4 | ns | |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | 3.2 | - | 2.0 | - | 0.9 | ns | |
| t _{en} | enable time | OE to A, B | - | 200 | - | 200 | - | 200 | ns | |
| t _{dis} | disable time | OE to A, B; no external load [1][2] | - | 25 | - | 25 | - | 25 | ns | |
| | | OE to A | - | 105 | - | 105 | - | 105 | ns | |
| | | OE to B | - | 125 | - | 175 | - | 120 | ns | |
| t _{TLH} | LOW to HIGH | A port | 2.8 | 9.3 | 2.6 | 8.3 | 1.8 | 7.8 | ns | |
| | output transition time | B port | 3.2 | 10.4 | 2.9 | 9.7 | 2.4 | 8.3 | ns | |
| t _{THL} | HIGH to LOW | A port | 1.9 | 7.2 | 1.9 | 6.9 | 1.8 | 6.7 | ns | |
| | output transition time | B port | 2.2 | 9.8 | 2.4 | 8.4 | 2.6 | 8.3 | ns | |
| t _W | pulse width | data inputs | 50 | - | 41 | - | 41 | - | ns | |
| f _{data} | data rate | | - | 20 | - | 24 | - | 24 | Mbps | |

| Symbol | Parameter | Conditions | V _{CC(B)} | | | | | | Unit |
|----------------------|--|-------------------------------------|--------------------|-----|---------------|-----|---------------|-----|------|
| | | | 2.5 V ± 0.2 V | | 3.3 V ± 0.3 V | | 5.0 V ± 0.5 V | | |
| | | | Min | Max | Min | Max | Min | Мах | |
| V _{CC(A)} = | 3.3 V ± 0.3 V | | | | | | | | |
| t _{PHL} | HIGH to LOW propagation delay | A to B | - | - | - | 3.0 | - | 3.9 | ns |
| t _{PLH} | LOW to HIGH propagation delay | A to B | - | - | - | 5.3 | - | 5.5 | ns |
| t _{PHL} | HIGH to LOW propagation delay | B to A | - | - | - | 3.2 | - | 4.2 | ns |
| t _{PLH} | LOW to HIGH propagation delay | B to A | - | - | - | 3.2 | - | 3.3 | ns |
| t _{en} | enable time | OE to A, B | - | - | - | 200 | - | 200 | ns |
| t _{dis} | disable time | OE to A, B; no external load [1][2] | - | - | - | 20 | - | 20 | ns |
| | | OE to A | - | - | - | 150 | - | 150 | ns |
| | | OE to B | - | - | - | 170 | - | 120 | ns |
| t _{TLH} | LOW to HIGH output transition time | A port | - | - | 2.3 | 7.0 | 1.9 | 7.4 | ns |
| | | B port | - | - | 2.5 | 8.0 | 2.1 | 9.3 | ns |
| t _{THL} | HIGH to LOW output transition time | A port | - | - | 2.0 | 6.8 | 1.9 | 6.3 | ns |
| | | B port | - | - | 2.3 | 9.3 | 2.4 | 9.5 | ns |
| t _W | pulse width | data inputs | - | - | 41 | - | 41 | - | ns |
| f _{data} | data rate | | - | - | - | 24 | - | 24 | Mbps |

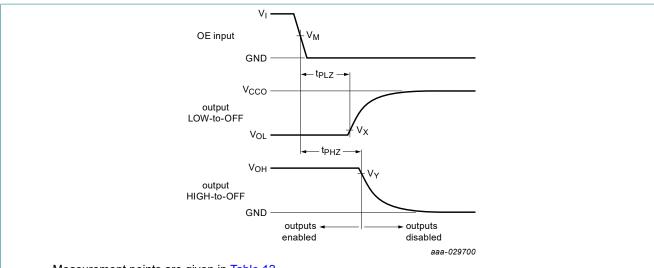
[2] The disable time with no external load indicates the delay between when OE goes LOW and when outputs actually become disabled.

12.1. Waveforms and test circuit



NXS0101

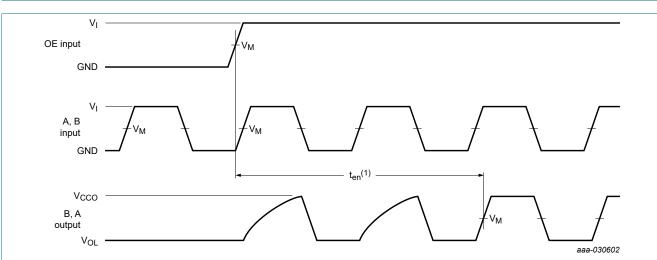
Dual supply translating transceiver; open drain; auto direction sensing



Measurement points are given in <u>Table 12</u>.

 V_{OL} and V_{OH} are typical output voltage levels that occur with the output load. V_{CCO} is the supply voltage associated with the output.

Fig. 3. Disable times



(1) The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. See also <u>Section 13.6</u>.

Measurement points are given in <u>Table 12</u>.

V_{OL} is a typical output voltage level that occur with the output load.

 V_{CCO} is the supply voltage associated with the output.

Fig. 4. Enable times

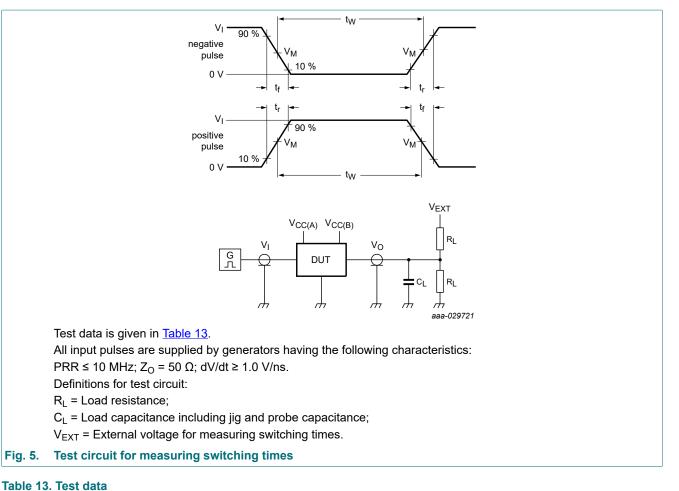
Table 12. Measurement points

| Supply voltage | Input | Output | | |
|------------------|---------------------|---------------------|--------------------------|--------------------------|
| V _{cco} | V _M [1] | V _M [2] | V _X | V _Y |
| 1.8 V ± 0.15 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} - 0.15 V |
| 2.5 V ± 0.2 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.15 V | V _{OH} - 0.15 V |
| 3.3 V ± 0.3 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.3 V | V _{OH} - 0.3 V |
| 5.0 V ± 0.5 V | 0.5V _{CCI} | 0.5V _{CCO} | V _{OL} + 0.3 V | V _{OH} - 0.3 V |

[1] V_{CCI} is the supply voltage associated with the input.

[2] V_{CCO} is the supply voltage associated with the output.

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Supply voltage Input Load VEXT V_{CC(A)} V_{CC(B)} V_I [1] Δt/ΔV C_L R_L [2] t_{PLH}, t_{PHL} t_{PZH}, t_{PHZ} t_{PZL}, t_{PLZ} [3] 1.65 V to 3.6 V 2.3 V to 5.5 V ≤ 1.0 ns/V 50 kΩ, 1 MΩ $2V_{CCO}$ V_{CCI} 15 pF open open

[1] V_{CCI} is the supply voltage associated with the input.

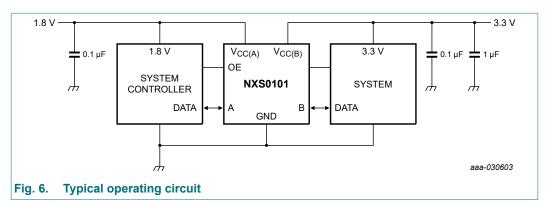
[2] For measuring data rate, pulse width, propagation delay and output rise and fall measurements, $R_L = 1 M\Omega$; for measuring enable and disable times, $R_L = 50 k\Omega$.

[3] V_{CCO} is the supply voltage associated with the output.

13. Application information

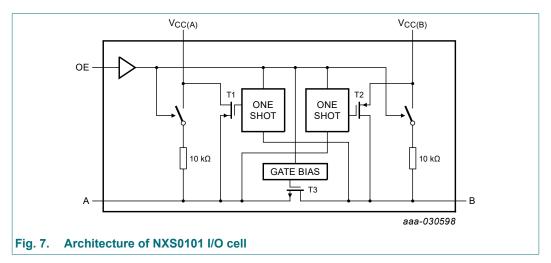
13.1. Applications

Voltage level-translation applications. The NXS0101 can be used in point-to-point applications to interface between devices or systems operating at different supply voltages. The device is primarily targeted at I^2C or 1-wire which use open-drain drivers, it may also be used in applications where push-pull drivers are connected to the ports, however the NXB0101 may be more suitable.



13.2. Architecture

The architecture of the NXS0101 is shown in Fig. 7. The device does not require an extra input signal to control the direction of data flow from A to B or B to A.



The NXS0101 is a "switch" type voltage translator, it employs two key circuits to enable voltage translation:

- **1.** A pass-gate transistor (N-channel) that ties the ports together.
- 2. An output edge-rate accelerator that detects and accelerates rising edges on the I/O pins.

The gate bias voltage of the pass gate transistor (T3) is set at approximately one threshold voltage above the V_{CC(A)} level of the low-voltage side. During a rising edge, the one shots turn on the PMOS transistors (T1, T2) for a short duration, accelerating the low-to-high transition. The one-shot is activated once the input transition reaches approximately $0.5V_{CCI}$. During the acceleration time the driver output resistance is between approximately $50 \ \Omega$ and $70 \ \Omega$. To avoid signal contention and minimize dynamic I_{CC}, the user should wait for the one-shot circuit to turn-off before applying a signal in the opposite direction. Pull-up resistors are included in the device for DC current sourcing capability.

13.3. Input driver requirements

As the NXS0101 is a switch type translator, properties of the input driver directly effect the output signal. The external open-drain or push-pull driver applied to an I/O determines the static current sinking capability of the system. The max data rate, HIGH-to-LOW output transition time (t_{THL}) and propagation delay (t_{PHL}) are dependent upon the output impedance and edge-rate of the external driver. The limits provided for these parameters in the datasheet assume a driver with output impedance below 50 Ω is used.

13.4. Output load considerations

The maximum lumped capacitive load that can be driven is dependant upon the one-shot pulse duration. In cases with very heavy capacitive loading there is a risk that the output will not reach the positive rail within the one-shot pulse duration. To avoid excessive capacitive loading and to ensure correct triggering of the one-shot it's recommended to use short trace lengths and low capacitance connectors on NXS0101 PCB layouts. To ensure low impedance termination and avoid output signal oscillations and one-shot re-triggering, the length of the PCB trace should be such that the round trip delay of any reflection is within the one-shot pulse duration.

13.5. Power up

During operation $V_{CC(A)}$ must never be higher than $V_{CC(B)}$, however during power-up $V_{CC(A)} \ge V_{CC(B)}$ does not damage the device, so any power supply can be ramped up first. There is no special power-up sequencing required. The NXS0101 includes circuitry that disables all output ports when either $V_{CC(A)}$ or $V_{CC(B)}$ is switched off.

13.6. Enable and disable

An output enable input (OE) is used to disable the device. Setting OE to LOW causes all I/Os to assume the high-impedance OFF-state. The disable time (t_{dis} with no external load) indicates the delay between when OE goes LOW and when outputs actually become disabled. The enable time (t_{en}) indicates the amount of time the user must allow for one one-shot circuitry to become operational after OE is taken HIGH. To ensure the high-impedance OFF-state during power-up or power-down, pin OE should be tied to GND through a pull-down resistor, the minimum value of the resistor is determined by the current-sourcing capability of the driver.

13.7. Pull-up or pull-down resistors on I/O lines

Each A port I/O has an internal 10 k Ω pull-up resistor to V_{CC(A)}, and each B port I/O has an internal 10 k Ω pull-up resistor to V_{CC(B)}. If a smaller value of pull-up resistor is required, an external resistor must be added parallel to the internal 10 k Ω , this will effect the V_{OL} level. When OE goes LOW the internal pull-ups of the NXS0101 are disabled.

14. Package outline

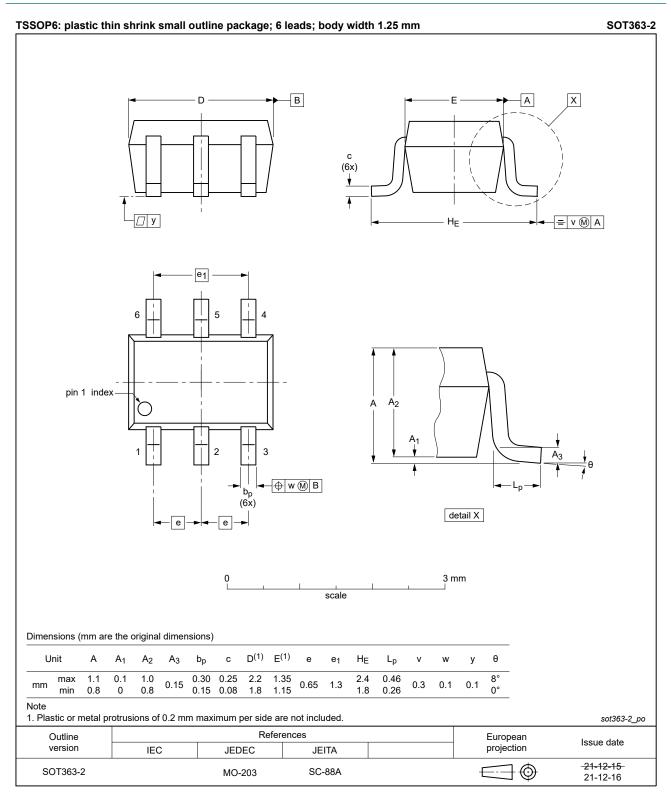


Fig. 8. Package outline SOT363-2 (TSSOP6)

NXS0101

Dual supply translating transceiver; open drain; auto direction sensing

SOT886 XSON6: plastic extremely thin small outline package; no leads; 6 terminals; body 1 x 1.45 x 0.5 mm

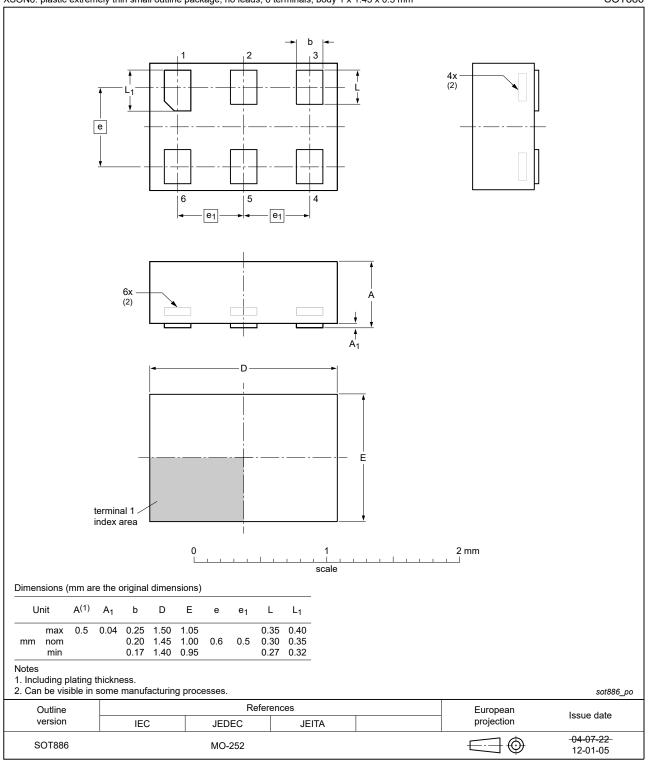


Fig. 9. Package outline SOT886 (XSON6)

NXS0101

Dual supply translating transceiver; open drain; auto direction sensing

XSON6: extremely thin small outline package; no leads; 6 terminals; body 1.0 x 1.0 x 0.35 mm

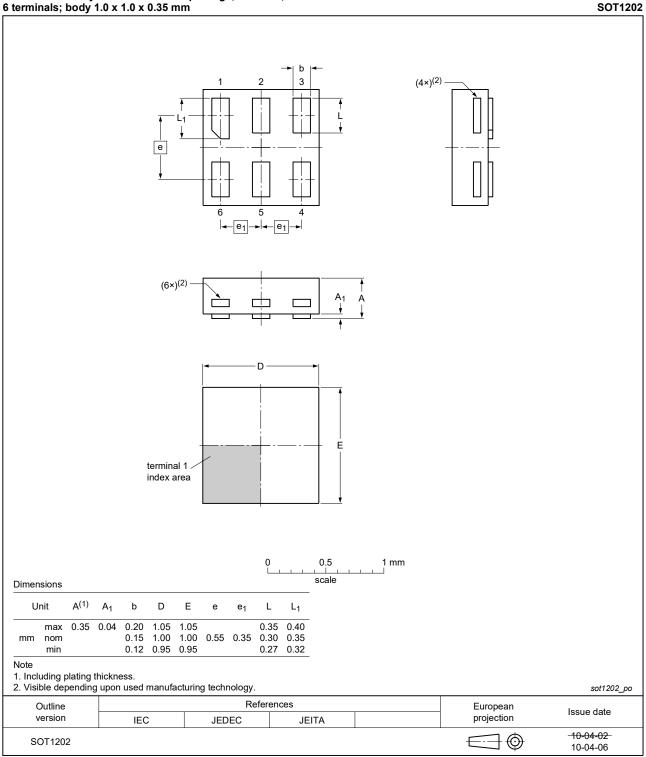


Fig. 10. Package outline SOT1202 (XSON6)

15. Abbreviations

| Acronym | Description |
|------------------|--------------------------|
| CDM | Charged Device Model |
| DUT | Device Under Test |
| ESD | ElectroStatic Discharge |
| HBM | Human Body Model |
| l ² C | Inter-Integrated Circuit |
| PCB | Printed Circuit Board |
| PRR | Pulse Rate Repetition |

16. Revision history

| Table 15. Revision history | | | | | | | |
|----------------------------|---------------------|--|---------------|---------------|--|--|--|
| Document ID | Release date | Data sheet status | Change notice | Supersedes | | | |
| NXS0101 v.5 | 20231116 | Product data sheet | - | NXS0101 v.4 | | | |
| Modifications: | <u>Section 2</u> : | • <u>Section 2</u> : ESD specification updated according to the latest JEDEC standard. | | | | | |
| NXS0101 v.4 | 20220209 | Product data sheet | - | NXS0101 v.3.1 | | | |
| Modifications: | Package S | Package SOT363 (SC-88) changed to SOT363-2 (TSSOP6). | | | | | |
| NXS0101 v.3.1 | 20210823 | Product data sheet | - | NXS0101 v.2 | | | |
| Modifications: | • <u>Table 10</u> a | <u>Table 10</u> and <u>Table 11</u> : Disable times updated. | | | | | |
| NXS0101 v.2 | 20200923 | Product data sheet | - | NXS0101 v.1.1 | | | |
| Modifications: | Type num | Type number NXS0101GW (SOT363 / SC-88) added. | | | | | |
| NXS0101 v.1.1 | 20200406 | Product data sheet | - | - | | | |

17. Legal information

Data sheet status

| Document status [1][2] | Product status [3] | Definition |
|-----------------------------------|-----------------------|---|
| Objective [short] data sheet | Development | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet | Qualification | This document contains data from the preliminary specification. |
| Product [short] data sheet | Production | This document contains the product specification. |

 Please consult the most recently issued document before initiating or completing a design.

- [2] The term 'short data sheet' is explained in section "Definitions".
- [3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the internet at <u>https://www.nexperia.com</u>.

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