

HEF4015B

Dual 4-bit static shift register

Rev. 9 — 21 March 2016

Product data sheet

1. General description

The HEF4015B is a dual edge-triggered 4-bit static shift register (serial-to-parallel converter). Each shift register has a serial data input (D), a clock input (CP), four fully buffered parallel outputs (Q0 to Q3) and an overriding asynchronous master reset input (MR). Information present on D is shifted to the first register position, and all the data in the register is shifted one position to the right on the LOW-to-HIGH transition of CP. A HIGH on MR clears the register and forces Q0 to Q3 to LOW, independent of CP and D. The clock input's Schmitt trigger action makes the input highly tolerant of slower clock rise and fall times.

It operates over a recommended V_{DD} power supply range of 3 V to 15 V referenced to V_{SS} (usually ground). Unused inputs must be connected to V_{DD} , V_{SS} , or another input.

2. Features and benefits

- Tolerant of slow clock rise and fall times
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$.
- Complies with JEDEC standard JESD 13-B

3. Applications

- Serial-to-parallel converter
- Buffer stores
- General purpose register

4. Ordering information

Table 1. Ordering information

All types operate from $-40\text{ }^{\circ}\text{C}$ to $+85\text{ }^{\circ}\text{C}$.

| Type number | Package | | Version |
|-------------|---------|--|----------|
| | Name | Description | |
| HEF4015BT | SO16 | plastic small outline package; 16 leads; body width 3.9 mm | SOT109-1 |

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5. Functional diagram

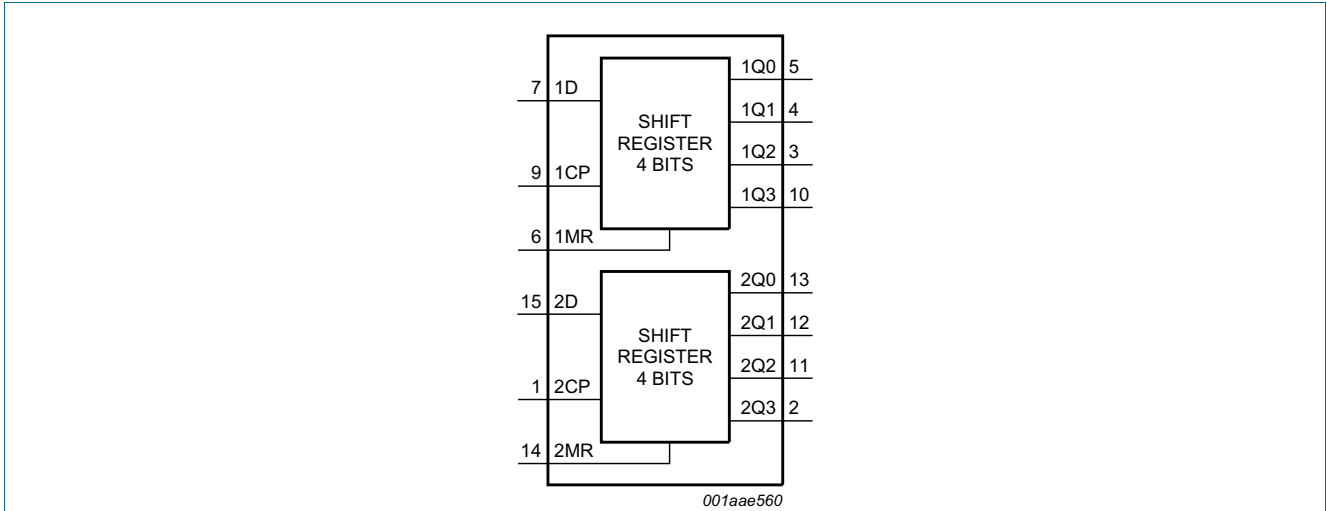


Fig 1. Functional diagram

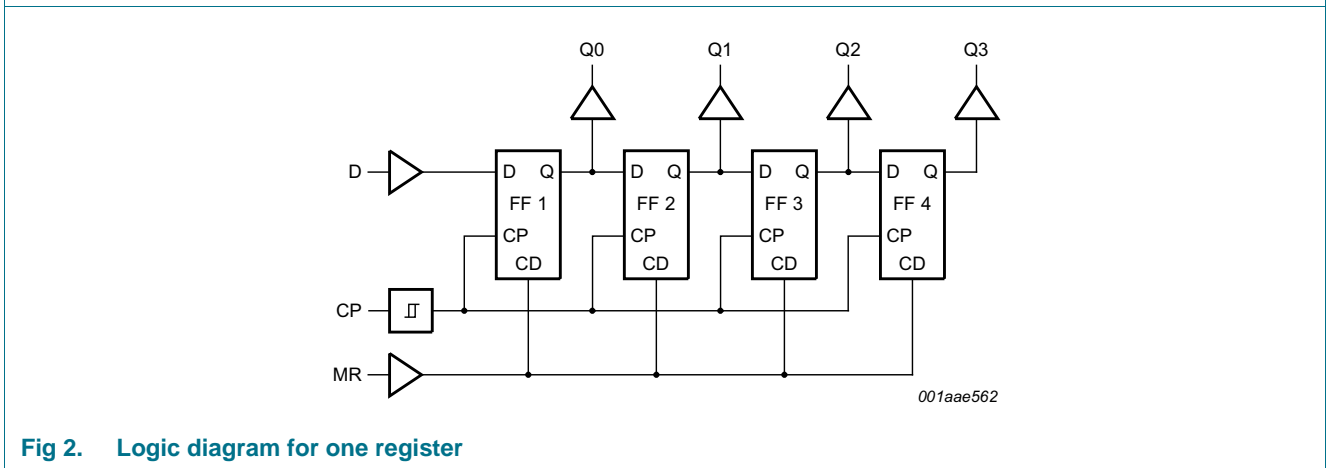


Fig 2. Logic diagram for one register

6. Pinning information

6.1 Pinning

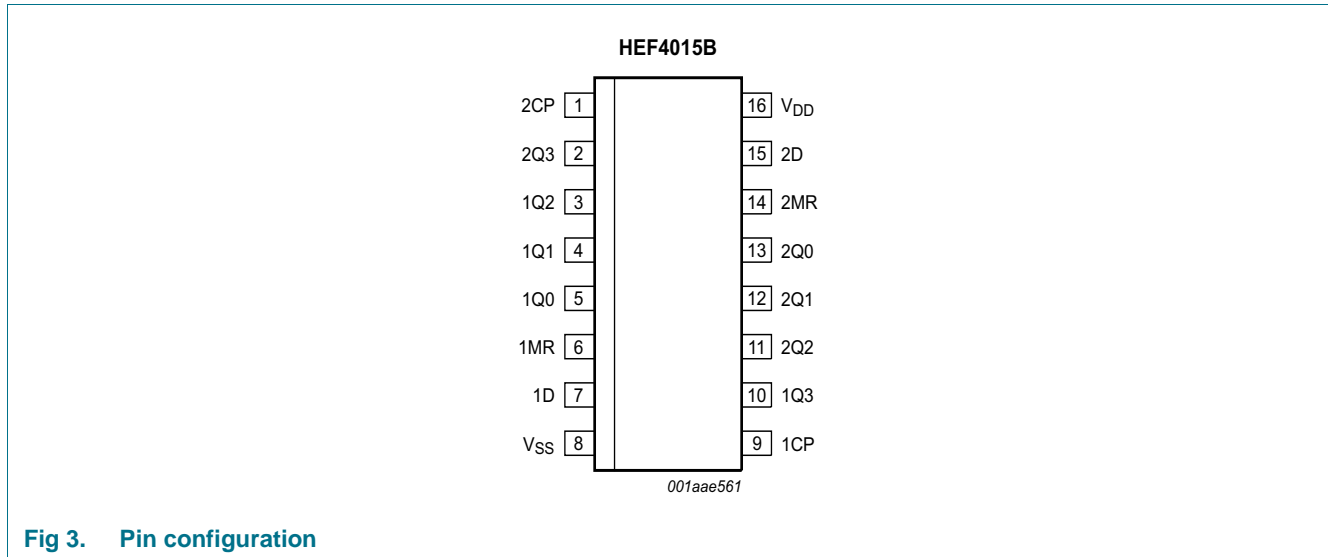


Fig 3. Pin configuration

6.2 Pin description

Table 2. Pin description

| Symbol | Pin | Description |
|-----------------|---------------|--|
| 1Q0 to 1Q3 | 5, 4, 3, 10 | parallel output |
| 2Q0 to 2Q3 | 13, 12, 11, 2 | parallel output |
| 1MR, 2MR | 6, 14 | master reset input (active HIGH) |
| 1D, 2D | 7, 15 | serial data input |
| V _{SS} | 8 | ground supply voltage |
| 1CP, 2CP | 9, 1 | clock input (LOW-to-HIGH edge-triggered) |
| V _{DD} | 16 | supply voltage |

7. Functional description

Table 3. Function table [\[1\]](#)

| number of clock pulse transitions | Input | | | Output | | | |
|-----------------------------------|-------|----|----|-----------|-----------|-----------|-----------|
| | CP | D | MR | Q0 | Q1 | Q2 | Q3 |
| 1 | ↑ | D1 | L | D1 | X | X | X |
| 2 | ↑ | D2 | L | D2 | D1 | X | X |
| 3 | ↑ | D3 | L | D3 | D2 | D1 | X |
| 4 | ↑ | D4 | L | D4 | D3 | D2 | D1 |
| | ↓ | X | L | no change | no change | no change | no change |
| | X | X | H | L | L | L | L |

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care; D_n = either HIGH or LOW;
 ↑ = positive-going transition; ↓ = negative-going transition.

8. Limiting values

Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|-------------------------|--|------|----------------|------|
| V_{DD} | supply voltage | | -0.5 | +18 | V |
| I_{IK} | input clamping current | $V_I < -0.5\text{ V}$ or $V_I > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| V_I | input voltage | | -0.5 | $V_{DD} + 0.5$ | V |
| I_{OK} | output clamping current | $V_O < -0.5\text{ V}$ or $V_O > V_{DD} + 0.5\text{ V}$ | - | ± 10 | mA |
| $I_{I/O}$ | input/output current | | - | ± 10 | mA |
| I_{DD} | supply current | | - | 50 | mA |
| T_{stg} | storage temperature | | -65 | +150 | °C |
| T_{amb} | ambient temperature | | -40 | +85 | °C |
| P_{tot} | total power dissipation | $T_{amb} = -40\text{ °C}$ to $+85\text{ °C}$ | | | |
| | | SO16 package [1] | - | 500 | mW |
| P | power dissipation | per output | - | 100 | mW |

[1] For SO16 package: P_{tot} derates linearly with 8 mW/K above 70 °C.

9. Recommended operating conditions

Table 5. Recommended operating conditions

| Symbol | Parameter | Conditions | Min | Typ | Max | Unit |
|---------------------|-------------------------------------|------------------------|-----|-----|----------|-----------------|
| V_{DD} | supply voltage | | 3 | - | 15 | V |
| V_I | input voltage | | 0 | - | V_{DD} | V |
| T_{amb} | ambient temperature | in free air | -40 | - | +85 | °C |
| $\Delta t/\Delta V$ | input transition rise and fall rate | $V_{DD} = 5\text{ V}$ | - | - | 3.75 | $\mu\text{s/V}$ |
| | | $V_{DD} = 10\text{ V}$ | - | - | 0.5 | $\mu\text{s/V}$ |
| | | $V_{DD} = 15\text{ V}$ | - | - | 0.08 | $\mu\text{s/V}$ |

10. Static characteristics

Table 6. Static characteristics

$V_{SS} = 0\text{ V}$; $V_I = V_{SS}$ or V_{DD} unless otherwise specified.

| Symbol | Parameter | Conditions | V_{DD} | $T_{amb} = -40\text{ }^{\circ}\text{C}$ | | $T_{amb} = 25\text{ }^{\circ}\text{C}$ | | $T_{amb} = 85\text{ }^{\circ}\text{C}$ | | Unit |
|----------|---------------------------|--------------------------------|----------|---|-----------|--|-----------|--|-----------|---------------|
| | | | | Min | Max | Min | Max | Min | Max | |
| V_{IH} | HIGH-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 3.5 | - | 3.5 | - | 3.5 | - | V |
| | | | 10 V | 7.0 | - | 7.0 | - | 7.0 | - | V |
| | | | 15 V | 11.0 | - | 11.0 | - | 11.0 | - | V |
| V_{IL} | LOW-level input voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 1.5 | - | 1.5 | - | 1.5 | V |
| | | | 10 V | - | 3.0 | - | 3.0 | - | 3.0 | V |
| | | | 15 V | - | 4.0 | - | 4.0 | - | 4.0 | V |
| V_{OH} | HIGH-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | 4.95 | - | 4.95 | - | 4.95 | - | V |
| | | | 10 V | 9.95 | - | 9.95 | - | 9.95 | - | V |
| | | | 15 V | 14.95 | - | 14.95 | - | 14.95 | - | V |
| V_{OL} | LOW-level output voltage | $ I_O < 1\text{ }\mu\text{A}$ | 5 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 10 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| | | | 15 V | - | 0.05 | - | 0.05 | - | 0.05 | V |
| I_{OH} | HIGH-level output current | $V_O = 2.5\text{ V}$ | 5 V | - | -1.7 | - | -1.4 | - | -1.1 | mA |
| | | $V_O = 4.6\text{ V}$ | 5 V | - | -0.52 | - | -0.44 | - | -0.36 | mA |
| | | $V_O = 9.5\text{ V}$ | 10 V | - | -1.3 | - | -1.1 | - | -0.9 | mA |
| | | $V_O = 13.5\text{ V}$ | 15 V | - | -3.6 | - | -3.0 | - | -2.4 | mA |
| I_{OL} | LOW-level output current | $V_O = 0.4\text{ V}$ | 5 V | 0.52 | - | 0.44 | - | 0.36 | - | mA |
| | | $V_O = 0.5\text{ V}$ | 10 V | 1.3 | - | 1.1 | - | 0.9 | - | mA |
| | | $V_O = 1.5\text{ V}$ | 15 V | 3.6 | - | 3.0 | - | 2.4 | - | mA |
| I_I | input leakage current | | 15 V | - | ± 0.3 | - | ± 0.3 | - | ± 1.0 | μA |
| I_{DD} | supply current | $I_O = 0\text{ A}$ | 5 V | - | 20 | - | 20 | - | 150 | μA |
| | | | 10 V | - | 40 | - | 40 | - | 300 | μA |
| | | | 15 V | - | 80 | - | 80 | - | 600 | μA |
| C_I | input capacitance | | - | - | - | 7.5 | - | - | pF | |

11. Dynamic characteristics

Table 7. Dynamic characteristics
 $V_{SS} = 0\text{ V}$; $C_L = 50\text{ pF}$; $T_{amb} = 25\text{ }^\circ\text{C}$.

| Symbol | Parameter | Conditions | V _{DD} | Extrapolation formula ^[1] | Min | Typ | Max | Unit |
|------------------|-------------------------------|---|-----------------|--------------------------------------|-----|-----|-----|------|
| t _{PHL} | HIGH to LOW propagation delay | nCP to Qn; see Figure 4 | 5 V | 103 ns + (0.55 ns/pF)C _L | - | 130 | 260 | ns |
| | | | 10 V | 44 ns + (0.23 ns/pF)C _L | - | 55 | 110 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| | | nMR to Qn; see Figure 6 | 5 V | 78 ns + (0.55 ns/pF)C _L | - | 105 | 210 | ns |
| | | | 10 V | 34 ns + (0.23 ns/pF)C _L | - | 45 | 90 | ns |
| | | | 15 V | 27 ns + (0.16 ns/pF)C _L | - | 35 | 70 | ns |
| t _{PLH} | LOW to HIGH propagation delay | nCP to Qn see Figure 4 | 5 V | 93 ns + (0.55 ns/pF)C _L | - | 120 | 240 | ns |
| | | | 10 V | 44 ns + (0.23 ns/pF)C _L | - | 55 | 110 | ns |
| | | | 15 V | 32 ns + (0.16 ns/pF)C _L | - | 40 | 80 | ns |
| t _t | transition time | see Figure 4 | 5 V | 10 ns + (1.00 ns/pF)C _L | - | 60 | 120 | ns |
| | | | 10 V | 9 ns + (0.42 ns/pF)C _L | - | 30 | 60 | ns |
| | | | 15 V | 6 ns + (0.28 ns/pF)C _L | - | 20 | 40 | ns |
| t _{su} | set-up time | nD to nCP; see Figure 5 | 5 V | | +25 | -15 | - | ns |
| | | | 10 V | | +25 | -10 | - | ns |
| | | | 15 V | | +20 | -5 | - | ns |
| t _h | hold time | nD to nCP; see Figure 5 | 5 V | | 40 | 20 | - | ns |
| | | | 10 V | | 20 | 10 | - | ns |
| | | | 15 V | | 15 | 8 | - | ns |
| t _w | pulse width | nCP LOW; minimum width; see Figure 5 | 5 V | | 60 | 30 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 20 | 10 | - | ns |
| | | nMR HIGH; minimum width; see Figure 6 | 5 V | | 80 | 40 | - | ns |
| | | | 10 V | | 30 | 15 | - | ns |
| | | | 15 V | | 24 | 12 | - | ns |
| t _{rec} | recovery time | pin nMR; see Figure 6 | 5 V | | 50 | 20 | - | ns |
| | | | 10 V | | 30 | 10 | - | ns |
| | | | 15 V | | 20 | 5 | - | ns |
| f _{max} | maximum frequency | see Figure 5 | 5 V | | 7 | 15 | - | MHz |
| | | | 10 V | | 15 | 30 | - | MHz |
| | | | 15 V | | 22 | 44 | - | MHz |

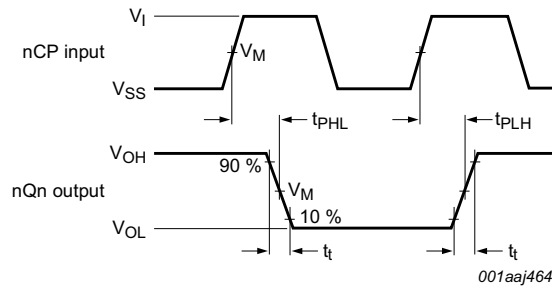
[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C_L in pF).

Table 8. Dynamic power dissipation P_D

P_D can be calculated from the formulas shown. $V_{SS} = 0\text{ V}$; $t_r = t_f \leq 20\text{ ns}$; $T_{amb} = 25\text{ }^\circ\text{C}$.

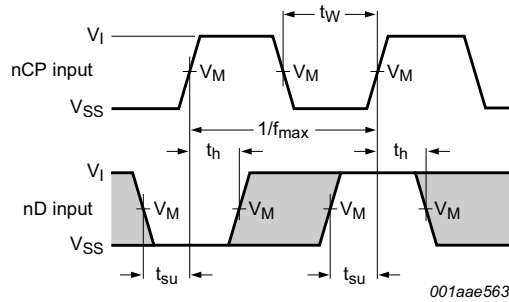
| Symbol | Parameter | V_{DD} | Typical formula for P_D (μW) | where: |
|--------|---------------------------|----------|---|--|
| P_D | dynamic power dissipation | 5 V | $P_D = 1500 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | f_i = input frequency in MHz; f_o = output frequency in MHz; C_L = output load capacitance in pF; V_{DD} = supply voltage in V; $\Sigma(C_L \times f_o)$ = sum of the outputs. |
| | | 10 V | $P_D = 6300 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |
| | | 15 V | $P_D = 17000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2$ | |

12. Waveforms



Measurement points are given in [Table 9](#).

Fig 4. Waveforms showing nCP propagation delays and nQn transition times

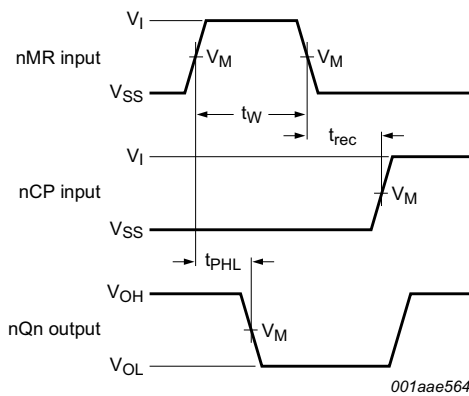


The shaded area indicates where the input is permitted to change for predictable output performance.

Set-up and hold times are shown as positive values but may be specified as negative values;

Measurement points are given in [Table 9](#).

Fig 5. Waveforms showing set-up times, hold times, and minimum clock pulse width

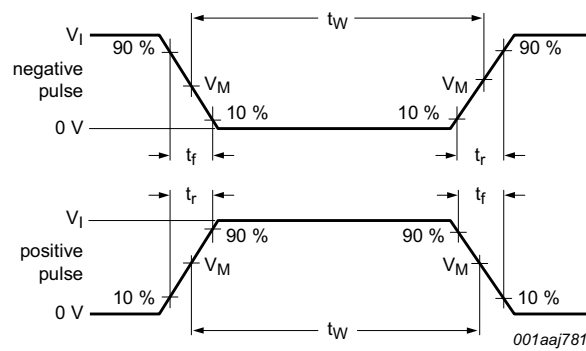


Measurement points are given in [Table 9](#).

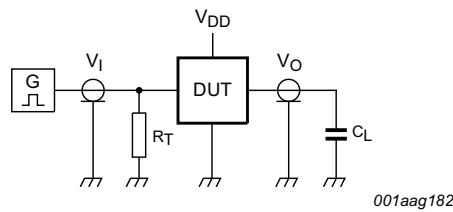
Fig 6. Waveforms showing MR recovery time, propagation delay and minimum pulse width

Table 9. Measurement points

| Supply voltage | Input | Output |
|-----------------|--------------------|--------------------|
| V _{DD} | V _M | V _M |
| 5 V to 15 V | 0.5V _{DD} | 0.5V _{DD} |



a. Input waveforms



b. Test circuit

Test data is given in [Table 10](#).

Definitions for test circuit:

DUT = Device Under Test;

C_L = load capacitance including jig and probe capacitance;

R_T = termination resistance should be equal to the output impedance Z_o of the pulse generator.

Fig 7. Test circuit for measuring switching times

Table 10. Test data

| Supply voltage | Input | | Load |
|----------------|----------------------|--------------|-------|
| V_{DD} | V_I | t_r, t_f | C_L |
| 5 V to 15 V | V_{SS} or V_{DD} | ≤ 20 ns | 50 pF |

13. Package outline

SO16: plastic small outline package; 16 leads; body width 3.9 mm

SOT109-1

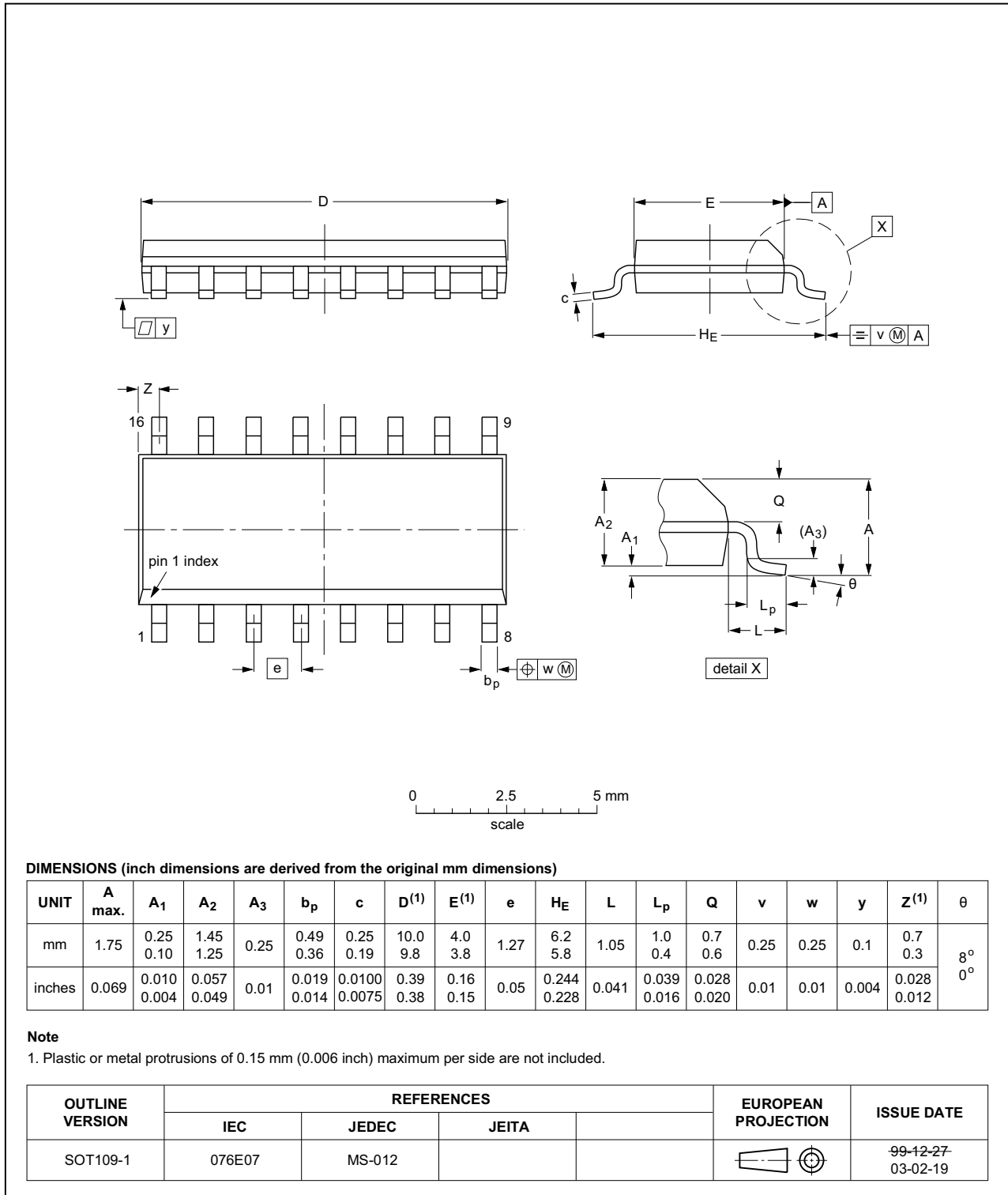


Fig 8. Package outline SOT109-1 (SO16)

14. Revision history

Table 11. Revision history

| Document ID | Release date | Data sheet status | Change notice | Supersedes |
|------------------|---|-----------------------|---------------|------------------|
| HEF4015B v.9 | 20160321 | Product data sheet | - | HEF4015B v.8 |
| Modifications: | <ul style="list-style-type: none"> Type number HEF4015BP (SOT38-4) removed. | | | |
| HEF4015B v.8 | 20111121 | Product data sheet | - | HEF4015B v.7 |
| Modifications: | <ul style="list-style-type: none"> Legal pages updated. Changes in “General description” and “Features and benefits”. | | | |
| HEF4015B v.7 | 20110914 | Product data sheet | - | HEF4015B v.6 |
| HEF4015B v.6 | 20091103 | Product data sheet | - | HEF4015B v.5 |
| HEF4015B v.5 | 20090624 | Product data sheet | - | HEF4015B v.4 |
| HEF4015B v.4 | 20090127 | Product data sheet | - | HEF4015B_CNV v.3 |
| HEF4015B_CNV v.3 | 19950101 | Product specification | - | HEF4015B_CNV v.2 |
| HEF4015B_CNV v.2 | 19950101 | Product specification | - | - |

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[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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