Notification about the transfer of the semiconductor business

The semiconductor business of Panasonic Corporation was transferred on September 1, 2020 to Nuvoton Technology Corporation (hereinafter referred to as "Nuvoton"). Accordingly, Panasonic Semiconductor Solutions Co., Ltd. became under the umbrella of the Nuvoton Group, with the new name of Nuvoton Technology Corporation Japan (hereinafter referred to as "NTCJ").

In accordance with this transfer, semiconductor products will be handled as NTCJ-made products after September 1, 2020. However, such products will be continuously sold through Panasonic Corporation.

Publisher of this Document is NTCJ.

If you would find description "Panasonic" or "Panasonic semiconductor solutions", please replace it with NTCJ.

* Except below description page

"Request for your special attention and precautions in using the technical information and semiconductors described in this book"

Nuvoton Technology Corporation Japan

Panasonic ____

MIP2E1DMTSCF

種別/Type シリコンMOS		形集積回路/Silicon MOSFET type Integrated Circuit									
		即用/For a Switching Power Supply Control									
構造/Structure CMOS形/CM											
		— A 1 — B		マーク記号/マーキング゙/Markin g		M I P 2 E 1 D					
Α.	絶対最大定格/A	bsolute Maximu	m Ratings								
No.	項目/	ĺtem	定格/Ratings					単 位 /Unit			
1	ドレイン電圧 DRAIN Voltage		VD		7	0 0			V		
2	コントロール電圧 CONTROL Voltage		VC	1 0			V				
3	出力電流 Output Current		ΙD	0.43				A			
4	出力ピーク電流 Output Peak Current		IDP	0.61				A			
5	コントロール電流 CONTROL Current		IC	0. 1				А			
6	6 <mark>チャネル部温度 Channel Temperature</mark> 7 保存温度 Storage Temperature		Τch		150				°C		
7			Tstg	-55 ~ +150				°C			
В.	 電気的特性/Ele	ectrical charac	teristics		測定条件/Me	asure conditi	on (Tc	=25°C:	±3°C)		
No.	項目/	'Item	記号 /Symbol		条件/Measure 測定図-1参照/ 1)		Тур.	Lir Min	nit Max	Unit	
No.	項目/ 【コントロール樹		∕Symbol	(別紙	測定図-1参照。 1)	∕See Figure			1	Unit	
No. 1		售能∕Control fu	∕Symbol	(別紙 *は設計(測定図-1参照。 1)	∕See Figure			1	Unit kHz	
No. 1 2	【コントロール樹 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy	幾能/Control fu ≳y	∕Symbol unctions:	(別紙 *は設計(Vc=Vc (C	測定図-1参照, 1) R証項目/Desi	∕See Figure	[tem]	Min	Max		
1	【コントロール樹 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWMゲイン PWM Gain	幾能/Control fu ≳y	∕Symbol unctions: fosc	(別紙 *は設計(Vc=Vc (C	測定図-1参照, 1) R証項目/Desi NT)-0.2V	∕See Figure	Item] 100	Min 90	Max 110	kHz	
1	【コントロール機 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWMゲイン	幾能/Control fu ;y , /cle	<pre>/Symbol unctions: fosc MAXDC</pre>	(別紙 *は設計(Vc=Vc (C	測定図-1参照, 1) R証項目/Desi NT)-0.2V	∕See Figure	Item] 100 69	Min 90	Max 110	kHz %	
1 2 *3	【コントロール機 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWM f ain スロープ補償値 Slope Compensat 【電源/Supply:	幾能/Control fu ;y , /cle	<pre>/Symbol unctions: fosc MAXDC GPWM m</pre>	(別紙 *は設計(Vc=Vc(C Vc=Vc(C	測定図-1参照, 1) R証項目/Desi NT)-0.2V NT)-0.2V	∕See Figure	Item] 100 69 11	Min 90	Max 110	kHz % dB	
1 2 *3	【コントロール機 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWM fáin スロープ補償値 Slope Compensat 【電源/Supply: 起動前動作電流 Before Auto-res	機能/Control fu cy vcle :e Value *は設計保証項目	<pre>/Symbol unctions: fosc MAXDC GPWM m</pre>	(別紙 *は設計(Vc=Vc(C Vc=Vc(C	測定図-1参照, 1) R証項目/Desi NT)-0.2V NT)-0.2V	∕See Figure	Item] 100 69 11	Min 90	Max 110	kHz % dB	
1 2 *3 *4	【コントロール機 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWMがイン PWM Gain スロープ補償値 Slope Compensat 【電源/Supply: 起動前動作電流 Before Auto-res 動作時電流 Operating Curr	機能/Control fu sy // // // // // / / / / / / / / / / /	✓ Symbol unctions : : fosc MAXDC GPWM m ∃/Design C	(別紙 *は設計住 Vc=Vc(C Vc=Vc(C Guaranted	測定図-1参照, 1) R証項目/Desi NT)-0.2V NT)-0.2V	∕See Figure gn Guarantee :	[tem] 100 69 11 15	Min 90 66	Max 110 72	kHz % dB mA/us	
1 2 *3 *4 5 6	【コントロール機 出力周波数 Output Frequenc 最大デューティーサイクル Maximum Duty Cy PWMゲイン PWM Gain スロープ補償値 Slope Compensat 【電源/Supply: 起動前動作電流 Before Auto-res 動作時電流	機能/Control fu sy // // // // // / / / / / / / / / / /	<pre>/ Symbol inctions :: fosc MAXDC GPWM m]/Design G IC(SB) IC(OP)</pre>	(別紙 *は設計住 Vc=Vc(C Vc=Vc(C Guaranted	測定図-1参照, 1) R証項目/Desi NT)-0.2V NT)-0.2V NT)-0.2V	∕See Figure gn Guarantee : (2)	Item] 100 69 11 15 0.30	Min 90 66 0.05	Max 110 72 0.6	kHz % dB mA/us mA	

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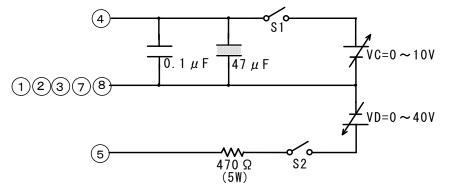
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9	起動/停止ヒステリシス電圧 Auto-restar hysteresis Voltage	⊿vc	S1=0PEN (2)	1.0	0. 5	1.5	۷
10	間欠動作時間比 Auto-restart duty cycle	TSW/TTIM	S1=OPEN	2			%
11	間欠動作周波数 Auto-restart frequency	fTIM	S1=OPEN	0. 5			Hz
12	コントロール端子充電電流 CONTROL Pin Charging Current	IC (CHG)	VC=0V	-1.9	-2.5	-1.2	mA
			VC=5V	-1.2	-2.0	-0.5	mA
13	コントロール電圧 CONTROL Pin Voltage	VC (CNT)		6. 2	5.7	6.6	۷
*14	コントロール電圧ヒステリシス CONTROL Pin Voltage hysteresis	⊿ VC (CNT)		10			mV
15	最小ドレイン電圧 DRAIN Supply Voltage	VD (MIN)			36		۷
	【保護機能/Circuit protection	า:*は設計	保証項目/Design Guarantee Item】				
16	過電流保護検出 Self-protection Current Limit	ILIMIT		0. 375	0. 335	0. 415	A
*17	オン時ブランキング 幅 Leading Edge Blanking Delay	ton(BLK)		0. 25			μs
*18	過電流保護遅れ時間 Current Limit Delay	td(OCL)		0. 1			μs
*19	過熱保護温度 Thermal Shutdown Temperature	ТОТР		140	130		°C
*20	ラッチリセット電圧 Power-up Reset Threshold Voltage	Vcreset	S2=OPEN	3. 3	2.3	4. 2	۷
	【出力/Output:*は設計保証項	目/Design	Guarantee Item】				
21	か抵抗 On-State Resistance	RDS (ON)	ID=0.1A (See Figure 2)	23		27	Ω
22	オフ時ドレイン端子リーク電流 OFF-State Current	IDSS	VDS=650V, Vc=6.5V	10		250	uA
23	ドレイン耐圧 Breakdown Voltage	VDSS	ID=0.25mA, Vc=6.5V		700		۷
24	立ち上がり時間 Rise tim	tr	(1)	0. 1			μs
25	立ち下がり時間 Fall time	tf	(1)	0. 1			μs
*26	熱抵抗 Thermal resistance (j-a)	Rth (j-a)	エポキシ基板(3cm×3cm)実装時 Ta=25℃ Surface Mounted on Epoxy Bord	90			°C/W

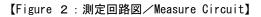


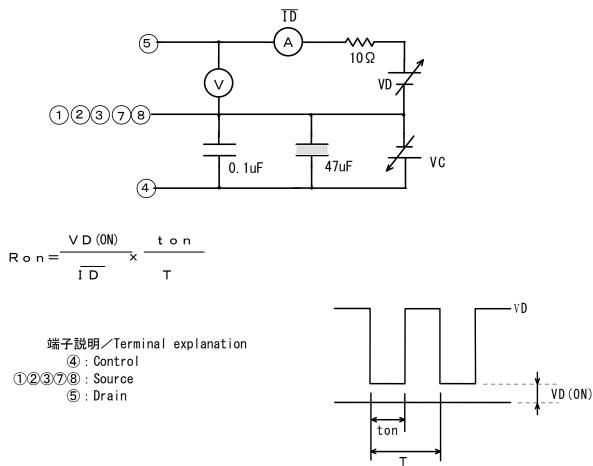
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【Figure 1 : 測定回路図/Measure Circuit】



* 本測定回路は、過電流保護検出値、出力特性の測定には使用できません。 This measurement circuit can't be useful for peak current and output characteristic measurement.



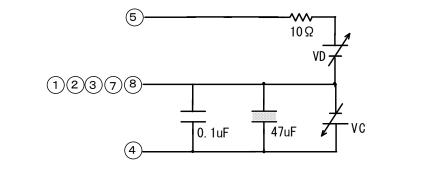


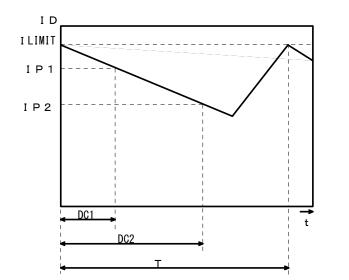
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【Figure 3: 測定回路図/Measure Circuit】





II IMIT=	DC2 · IP1-DC1 · IP2
	DC2-DC1
m=fosc∙	IP1—IP2
	DC2-DC1

端子説明/Terminal explanation ④:Control 12378 : Source (5): Drain

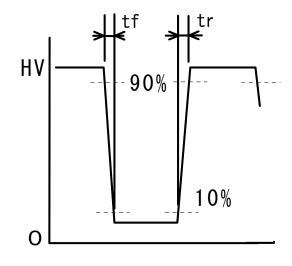
> *DC1, DC2は、VDをそれぞれVD1, VD2にしたときのデューティーサイクル (0<DC1<DC2<MAXDC) ightarrow DC1, DC2 is duty cycle when VD is VD1 and VD2, respectively.

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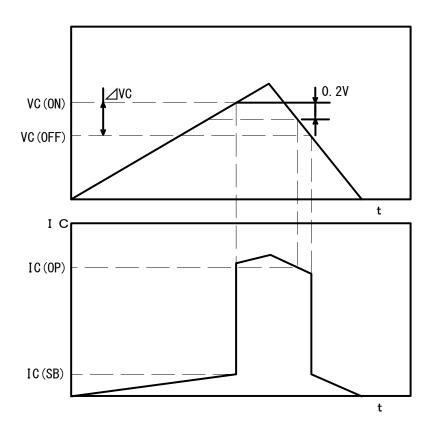


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[NOTE (1)]







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