## PSR-MC32



## Safety relay for emergency stop, safety door, and light grid monitoring with wide range input

Data sheet

106786\_en\_01

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## 1 Description

## Intended Use

The safety relay is used to monitor single or two-channel signal generators and to control actuators.

When the sensor circuit is interrupted, the safety relay initiates the safe state.

The safety relay interrupts circuits in a safety-related way.

## Possible signal generators

- Emergency stop button
- Door locking mechanisms
- Light grids

## Contact type

- 3 undelayed enabling current paths
- 1 undelayed enabling current path

The enabling current paths drop out without delay according to stop category 0 (EN 60204-1).

## Control

- Single or two channel
- Equivalent or non-equivalent
- Automatic or manual, monitored start

## Achievable safety integrity

 Suitable up to category 4, PL e (EN ISO 13849-1), SILCL 3 (EN 62061)

## Additional features

- 24 V AC/DC ... 230 V AC/DC wide range input
- Cross circuiting detection
- Option of screw or spring-cage terminal blocks for plug-in
- 22.5 mm housing width

## Zulassungen





## WARNING: Risk of electric shock

Observe the safety regulations and installation notes in the corresponding section.

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Make sure you always use the latest documentation. It can be downloaded from the product at <u>phoenixcontact.net/products</u>.



This document is valid for the products listed in the "Ordering data".

This document meets the same requirements as the original operating instructions with respect to the contents.





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## 3 Ordering data

Description	Туре	Order No.	Pcs./Pkt.
Safety relay for emergency stop, safety doors, and light grids up to SILCL 3, Cat. 4, PL e, 1 or 2-channel operation, automatic or manual, monitored start, 3 enabling current paths, 1 signaling current path, $U_S = 24 \dots 230$ V AC/DC, plug-in screw terminal block	PSR-MC32-3NO-1NC-24- 230UC-SC	2700524	1
Safety relay for emergency stop, safety doors, and light grids up to SILCL 3, Cat. 4, PL e, 1 or 2-channel operation, automatic or manual, monitored start, 3 enabling current paths, 1 signaling current path, $U_S = 24 \dots 230$ V AC/DC, plug-in spring-cage terminal block	PSR-MC32-3NO-1NC-24- 230UC-SP	2700525	1

## 4 Technical data

Hardware/firmware version	
HW/FW	≥ 00/
The technical data and safety characteristics are vali	d as of the specified HW/FW version.
Input data	
Rated control circuit supply voltage US	24 V AC/DC 230 V AC/DC -15 % / +10 %
Rated control supply current IS	typ. 103 mA (24 V DC) typ. 47 mA (48 V DC) typ. 38 mA (110 V AC) typ. 21 mA (230 V AC)
Input voltage range "0" signal	0 V DC 5 V DC (for safe Off; at S10/S12/S13)
Input current range "0" signal	0 mA 2 mA (for safe Off; at S10/S12/S13)
Inrush current	< 80 A ( $\Delta t$ = 50 µs at U <sub>s</sub> ) < 5 mA (with U <sub>s</sub> /l <sub>x</sub> at S10/S12/S13) > -5 mA (with U <sub>s</sub> /l <sub>x</sub> to S22) < 10 mA (with U <sub>s</sub> /l <sub>x</sub> at S34/S35)
Current consumption	< 5 mA (at U <sub>s</sub> /I <sub>x</sub> to S10/S12/S13/S34/S35) > -5 mA (with U <sub>s</sub> /I <sub>x</sub> to S22)
Power consumption at U <sub>S</sub>	2.7 W (with DC) 2.9 W (with AC)
Apparent power	typ. 5 VA (at U <sub>S</sub> )
Voltage at input/start and feedback circuit	24 V DC -20 % / +25 %
Filter time	2 ms (at A1 in the event of voltage dips at U <sub>s</sub> ) max. 1.5 ms (to S10-S12; test pulse width; at 24 V DC) 7.5 ms (to S10-S12; test pulse rate; at 24 V DC) Test pulse rate = 5 x Test pulse width
Max. permissible overall conductor resistance (Input and reset circuit at ${\rm U}_{\rm S})$	150 Ω
Typical response time at U <sub>s</sub>	< 100 ms (manual, monitored start) < 150 ms (automatic start)
Typical starting time with Us	< 200 ms (when controlled via A1)
Typical release time with Us	< 20 ms (when actuation is via the sensor circuit)

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Input data	
Recovery time	< 500 ms
Restart time	<1s
Maximum switching frequency	1 Hz
Concurrence input 1/2	∞
Operating voltage display	1 x green LED
Status display	3 x green LED
Protective circuit	U <sub>S</sub> : surge protection 275 V varistor / 411 V suppressor diode Inputs: protection against polarity reversal, surge protection 38.6 V suppressor diode
Output data	
Contact type	3 enabling current paths 1 signaling current path
Contact material	AgSnO <sub>2</sub>
Minimum switching voltage	5 V AC/DC
Maximum switching voltage	250 V AC/DC (Observe the load curve)
Limiting continuous current	6 A
Maximum inrush current	6 A
Inrush current, minimum	10 mA
Sq. Total current $I_{TH}^{2} = I_{1}^{2} + I_{2}^{2} + + I_{N}^{2}$	72 A <sup>2</sup> (observe derating)
Interrupting rating (ohmic load) max.	1500 VA (N/O contact, 250 V AC, $\tau = 0$ ms) For additional values, see load curve
Maximum interrupting rating (inductive load)	48 W (N/O contact, 24 V DC, $\tau = 40$ ms) 40 W (N/O contact, 48 V DC, $\tau = 40$ ms) 36 W (N/O contact, 60 V DC, $\tau = 40$ ms) 35 W (N/O contact, 110 V DC, $\tau = 40$ ms) 33 W (N/O contact, 220 V DC, $\tau = 40$ ms) 1500 VA (N/O contact, 250 V AC, $\tau = 40$ ms)
Switching capacity	min. 50 mW
Mechanical service life	10 x 10 <sup>6</sup> cycles
Switching capacity according to IEC 60947-5-1	5 A (24 V (DC13)) 5 A (250 V (AC15))
Output fuse	6 A gL/gG 4 A gL/gG (for low-demand applications)
General data	
Relay type	Electromechanical relay with forcibly guided contacts in accordance with EN 50205
Nominal operating mode	100% operating factor
Degree of protection	IP20
Min. degree of protection of inst. location	IP54
Mounting type	DIN rail mounting
Mounting position	vertical or horizontal
Assembly instructions	See derating curve
Type of housing	PBT yellow

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General data				
Air clearances and creepage distances between the	according to			
power circuits	DIN EN 50178; EN 60947-5	i-1		
Rated insulation voltage	250 V AC			
Rated surge voltage/insulation	and enabling current path (3 (41/42) Basic insulation 4 kV betwe Safe isolation, reinforced ins circuits	en enabling current path (23/24 33/34) and signaling current pat en all current paths and housing sulation 6 kV between all other		
	See "Insulation coordination	"		
Degree of pollution	2			
Overvoltage category				
Maximum power dissipation for nominal condition	17.3 W (at $I_L^2 = 72 A^2$ )			
Note on power dissipation	See "Calculating the power	dissipation"		
Dimensions	Screw connection	Spring-cage connection		
W x H x D	22.5 x 112.2 x 114.5 mm	22.5 x 117.4 x 114.5 mm		
Connection data	Screw connection	Spring-cage connection		
Conductor cross section, solid	$0.2 \text{ mm}^2 \dots 2.5 \text{ mm}^2$	$0.2 \text{ mm}^2 \dots 1.5 \text{ mm}^2$		
Conductor cross section, flexible	0.2 mm <sup>2</sup> 2.5 mm <sup>2</sup>	0.2 mm <sup>2</sup> 1.5 mm <sup>2</sup>		
Conductor cross section AWG/kcmil	24 12	24 16		
Stripping length	7 mm	8 mm		
Screw thread	МЗ			
Ambient conditions				
Ambient temperature (operation)	-40 °C 55 °C (observe de	rating)		
Ambient temperature (storage/transport)	-40 °C 85 °C			
Max. permissible relative humidity (operation)	75 % (on average, 85% infre	equently, non-condensing)		
Max. permissible humidity (storage/transport)	75 % (on average, 85% infre	equently, non-condensing)		
Maximum altitude	$\leq$ 2000 m (Above sea level)			
Information on operating height	See the "Using PSR devices 2000 m above sea level" se			
Shock	15g			
Vibration (operation)	10 Hz150 Hz, 2g			
Conformance/Approvals				
Conformance	CE-compliant			
The full EC Declaration of Conformity can be downloade	ed for the product at phoenixco	ntact.net/products.		
Approvals				
Safety data				

Safety parameters for IEC 61508 - High demand	
SIL	3
PFH <sub>D</sub>	1.00 x 10 <sup>-9</sup> (5 A DC13; 5 A AC15; 8760 switching cycles/year)
Demand rate	< 12 Months
Proof test interval	240 Months
Duration of use	240 Months
Safety parameters for IEC 61508 - Low demand	
SIL	3
PFD <sub>avg</sub>	1,49 x 10 <sup>-4</sup>
Proof test interval	56 Months
Duration of use	240 Months
Safety characteristic data according to EN ISO 1384	9
Category	4 (5 A DC13; 5 A AC15; 8760 switching cycles/year)
Performance level	e
Duration of use	240 Months
For applications in PL e, the required demand rate for the	e safety function is once per month.
Safety parameters for EN 62061	

## Safety parameters for EN 62061

SILCL

3

## 5 Safety regulations and installation notes



## WARNING: Death, serious personal injury or damage to equipment

Depending on the application, incorrect handling of the device may pose serious risks for the user or cause damage to equipment.

Observe all the safety notes and warning instructions provided in this chapter and elsewhere in this document.

#### General

 Observe the safety regulations of electrical engineering and industrial safety and liability associations.

Disregarding these safety regulations may result in death, serious personal injury or damage to equipment.

#### Power supply units for power supply

- Provide external protection for the input area (A1/A2).
- Make sure that the power supply unit is able to supply four times the nominal current of the external fuse, to ensure that it trips in the event of an error.

#### Startup, mounting, and modifications

Startup, mounting, modifications, and upgrades may only be carried out by an electrically skilled person.

- Before working on the device, disconnect the power.
- Carry out wiring according to the application. Refer to the "Application examples" section for this.

Reliable operation is only ensured if the device is installed in housing protected from dust and humidity.

• Install the device in housing protected from dust and humidity (min. IP54).

#### In operation

During operation, parts of electrical switching devices carry hazardous voltages.

• Protective covers must not be removed when operating electrical switching devices.

For emergency stop applications, automatic startup of the machine can pose serious risks for the user.

• The machine must be prevented from restarting automatically by a higher-level controller.

With the manual, monitored reset device, a machine start may not be triggered in accordance with EN ISO 13849-1. Inductive loads can lead to welded relay contacts.

Connect a quitable and effective protective circu

- Connect a suitable and effective protective circuit to inductive loads.
- Implement the protective circuit parallel to the load and not parallel to the switch contact.

Magnetic fields can influence the device. The magnetic field strength of the environment must not exceed 30 A/m.

• Do not use the device in the vicinity of strong magnetic fields (e.g., caused by transformers or magnetic iron).

Noise emission may occur when operating relay modules. Wireless reception may be disrupted in residential areas.

The device is a Class A product.

- Observe the requirements for noise emission for electrical and electronic equipment (EN 61000-6-4).
- Implement appropriate precautions against noise emission.

#### **Faulty devices**

The devices may be damaged following an error. Correct operation can no longer be ensured.

• In the event of an error, replace the device.

Only the manufacturer or their authorized representative may perform the following activities. Otherwise the warranty is invalidated.

- Repairs to the device
- Opening the housing

#### Taking out of service and disposal

- Dispose of the device in accordance with environmental regulations.
- Make sure that the device can never be reused.

## 6 Function description

## 6.1 Single-channel sensor circuit

The sensor circuit is not designed with redundancy.

The safety relay does not detect short and cross-circuits in the sensor circuit.

## 6.2 Two-channel sensor circuit

The sensor circuit is designed with redundancy.

With the corresponding wiring, the safety relay detects short and cross-circuits in the sensor circuit.

## 6.3 Automatic start

The device starts automatically after the sensor circuit has been closed.

## 6.4 Manual, monitored start

When the sensor circuit is closed, the device starts once the start circuit has been closed and opened again by pressing and releasing the reset button.

A connected reset button is monitored.

## 6.5 Safe shutdown

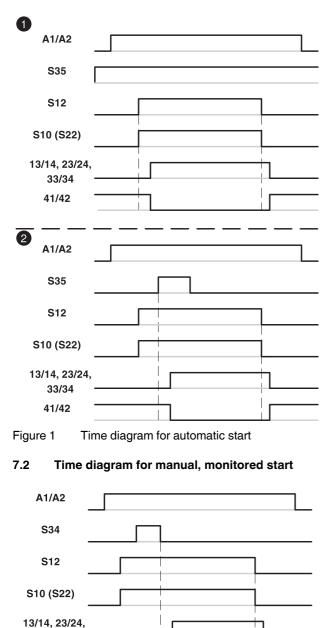
When the sensor circuit opens, the enabling current paths open without delay.

When the enabling current paths are open, the device is in the safe state.

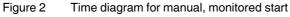
The signaling current path closes.

## 7 Function and time diagrams

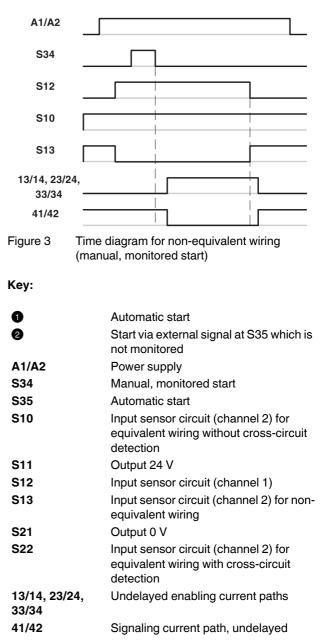
## 7.1 Time diagram for automatic start







## 7.3 Time diagram for non-equivalent wiring



33/34

#### 8 **Basic circuit diagram**

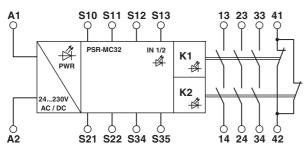


Figure 4 Block diagram

Key:

• •	
A1	24 V AC/DC 230 V AC/DC power supply (L)
A2	Power supply (N)
S10	Input sensor circuit (channel 2) for equivalent wiring without cross-circuit detection
S11	Output 24 V
S12	Input sensor circuit (channel 1)
S13	Input sensor circuit (channel 2) for non- equivalent wiring
S21	Output 0 V
S22	Input sensor circuit (channel 2) for equivalent wiring with cross-circuit detection
S34	Manual, monitored start
S35	Automatic start
13/14	
23/24	Undelayed enabling current paths
33/34	
41/42	Signaling current path, undelayed

#### 8.1 Insulation coordination

	A1/A2	Logic	13/14	23/24	33/34	41/42
A1/A2	-	6 kV ST				
Logic	-	-	6 kV ST	6 kV ST	6 kV ST	6 kV ST
13/14	-	-	-	6 kV ST	6 kV ST	6 kV ST
23/24	-	-	-	-	4 kV BI	4 kV BI
33/34	-	-	-	-	-	4 kV Bl
41/42	-	-	-	-	-	-

Key:

BI **Basic insulation** Safe isolation

ST

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## **Basic insulation**

(rated surge voltage of 4 kV)

A mixture of SELV and PELV is strictly prohibited. Only switch 230 V AC at one of the enable contacts if the adjacent contact carries the same potential.

## Safe isolation/reinforced insulation

(rated surge voltage of 6 kV)

Reinforced insulation (e.g., thanks to greater air clearances and creepage distances between conductive paths) is designed for one overvoltage category higher than basic insulation. This means that SELV circuits of  $U \le 25 \text{ V AC}$  or  $U \le 60 \text{ V DC}$  and circuits with higher voltages can be mixed.

## 9 Derating

## 9.1 Horizontal mounting position

The derating curve applies for the following conditions:

- Mounting on a horizontal DIN rail
- Devices mounted next to each other without spacing

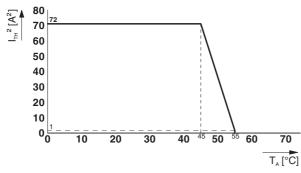


Figure 5 Derating curve - horizontal mounting position, without spacing

## 9.1.1 Horizontal mounting position with spacing

If the devices are mounted in the **horizontal** mounting position with  $\geq$  9 mm spacing between one another, no derating is required **up to 60°C**.

## 9.2 Vertical mounting position

The derating curve applies for the following conditions:

- Mounting on a vertical DIN rail
- Devices mounted next to each other without spacing

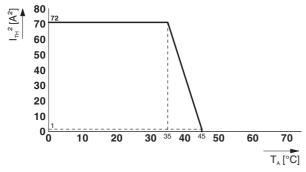


Figure 6 Derating curve - vertical mounting position, without spacing

## 9.2.1 Vertical mounting position with spacing

The derating curve applies for the following conditions:

- Mounting on a vertical DIN rail
- Devices mounted next to each other with ≥ 9 mm spacing

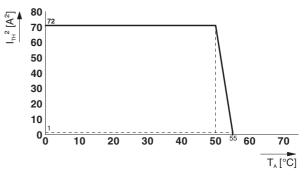
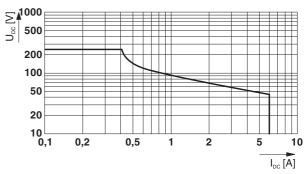


Figure 7 Derating curve - vertical mounting position, with spacing

## 10 Load curve

## 10.1 Ohmic load

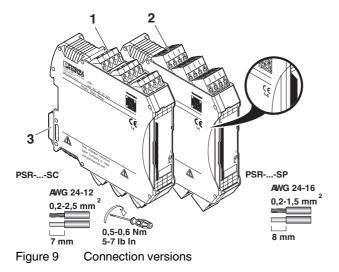




Relay load curve - ohmic load

## 11 Operating and indication elements

## 11.1 Connection versions



- 1 COMBICON plug-in screw terminal block
- 2 COMBICON plug-in spring-cage terminal block
- 3 Metal lock for fixing to DIN rail



The year the device was constructed can be found underneath the CE designation on the housing.

## 11.2 Connection assignment

		A1	24 V AC/DC 230 V AC/DC power supply (L)
		A2	Power supply (N)
A1 A2	S21	S21	Output 0 V
S11 S35 S		S11	Output 24 V
		S35	Automatic start
PWR		S34	Manual, monitored start
IN 1/2		S22	Input sensor circuit (channel 2) for equivalent wiring with cross-circuit detection
K1		S10	Input sensor circuit (channel 2) for equivalent wiring without cross-circuit detection
K2		S12	Input sensor circuit (channel 1)
		S13	Input sensor circuit (channel 2) for non-equivalent wiring
		PWR	Power LED (green)
×t	VC32	IN1/2	Status indicator sensor circuit; LED (green)
<b>EDPHENIX</b>	PSR-MC32	K1	Status indicator safety circuit; LED (green)
	≏	K2	Status indicator safety circuit; LED (green)
		41/42	Signaling current path, undelayed
13 1		13/14	
	3 34	23/24	Undelayed enabling current paths
		33/34	

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## 12 Mounting and removing

- Mount the device on a 35 mm DIN rail according to EN 60715.
- To remove the device, use a screwdriver to release the snap-on foot.

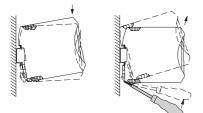


Figure 10 Mounting and removing

## 13 Wiring

• Connect the cables to the connection terminal blocks using a screwdriver.

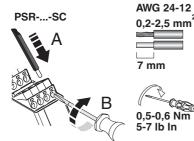


Figure 11 Connecting the cables for PSR-...-SC (screw terminal block)

AWG 24-16



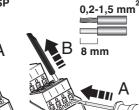


Figure 12

Connecting the cables for PSR-...-SC (spring-cage terminal block)

It is recommended that ferrules are used to connect stranded cables.

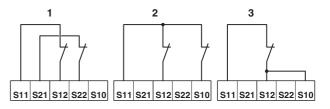


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For compliance with UL approval, use copper wire that is approved up to 60°C/75°C.

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- 13.1 Signal generator connection versions
- Connect suitable signal generators to S10/S11/S12/ S13 and S21/S22.



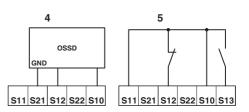


Figure 13 Signal generator connection versions

- 1 Two-channel connection with cross-circuit monitoring
- 2 Two-channel connection without cross-circuit monitoring
- **3** Single-channel connection
- 4 Two-channel connection with **external** cross-circuit monitoring
- 5 Two-channel, non-equivalent connection

#### 13.2 Start and feedback circuit connection variants

#### Automatic start

• Bridge the contacts S11/S35.

#### Manual, monitored start

- Connect a reset button to S11/S34.
- A connected reset button is monitored.

## Start and feedback circuit

 Place the relevant N/C contacts in path S11/S34 or S11/S35 to monitor external contactors or extension devices with force-guided contacts.

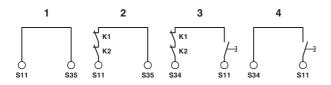


Figure 14 Start and feedback circuit connection variants

- 1 Automatic start
- 2 Automatic start with monitored contact extension
- 3 Manual, monitored start with monitored contact extension
- 4 Manual, monitored start

## 14 Startup

 Apply the rated control circuit supply voltage (24 V AC/DC ... 230 V AC/DC) at terminal blocks A1/A2.

The Power LED lights up.

• Close the sensor circuit at S10/S11/S12/S13 and S21/S22 as per the wiring.

The IN1/2 LED lights up.



Single or two-channel sensor circuit: see "Signal generator connection versions".

## Automatic start

The enabling current paths 13/14, 23/24 and 33/34 close. The K1 and K2 LEDs light up.

Signaling current path 41/42 opens.

#### Manual, monitored start

- Press the reset button.
- Release the reset button.

The enabling current paths 13/14, 23/24 and 33/34 close. The K1 and K2 LEDs light up.

Signaling current path 41/42 opens.

## 15 Calculating the power dissipation



The total power dissipation of the safety relay is based on the input power dissipation and the contact power dissipation for the same and for different load currents.

#### Input power dissipation

 $P_{Input} = 2,7 \text{ W} \text{ (with DC)}$  $P_{Input} = 2,9 \text{ W} \text{ (with AC)}$ 

#### **Contact power dissipation**

With the same load currents:

 $P_{Contact} = n \bullet I_{L}^{2} \bullet 200 \text{ m}\Omega$ With different load currents:  $P_{Contact} = (I_{L1}^{2} + I_{L2}^{2} + \dots + I_{Ln}^{2}) \bullet 200 \text{ m}\Omega$ 

## **Total power dissipation**

$$\begin{split} & \mathsf{P}_{Total} = \mathsf{P}_{Input} + \mathsf{P}_{Contact} \\ & \text{therefore} \\ & \mathsf{P}_{Total} = \mathsf{P}_{Input} + \mathsf{n} \bullet \mathsf{I_L}^2 \bullet 200 \text{ m}\Omega \\ & \text{or} \\ & \mathsf{P}_{Total} = \mathsf{P}_{Input} + (\mathsf{I_{L1}}^2 + \mathsf{I_{L2}}^2 + ... + \mathsf{I_{Ln}}^2) \bullet 200 \text{ m}\Omega \end{split}$$

- P Power dissipation in mW
- n Number of enabling current paths used
- IL Contact load current

## 16 Diagnostics

The following section describes the LED indicators for general states and error messages as well as possible causes and remedies.

## Function test/proof test

To verify the device function, proceed as follows:

- Demand the safety function by actuating the corresponding safety equipment.
- Check whether the safety function was executed correctly by switching the device on again.

If the device does not switch on again, the proof test failed.

#### 16.1 General states



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WARNING: Loss of functional safety due to malfunction.

If the proof test contains errors, the device no longer functions correctly.

Replace the device.

PWR LED	IN1/2 LED	K1 LED	K2 LED	State	Notes
ON	OFF	OFF	OFF	No relay has picked up. The sensor circuit is inactive.	Possible error see error messages
ON	ON	OFF	OFF	The sensor circuit is active. Relays K1 and K2 are ready to start and await reset/ start command (S34 or S35).	
ON	ON	ON	ON	The sensor circuit is active. All relays are picked up.	-

## 16.2 Error Messages

PWR LED	IN1/2 LED	K1 LED	K2 LED	State	Possible cause	Corrective
ON	OFF	OFF	OFF	The sensor circuit is actively controlled, but no input LEDs are lit up.	Internal cross-circuit detection is active: potential cross-circuit in the sensor circuit.	Switch off the operating voltage and rectify the cross-circuit. Then perform a function test.
ON	ON	OFF	OFF	The sensor circuit is active. The reset/start circuit (S34 or S35) is/was activated. The safety circuit (K1 and K2) is not picking up.	External error: the readback contact (external actuator) is open in the reset circuit. Internal error: 1. The diagnostic contact is not working correctly. 2. An N/O contact is welded.	External error: check the actuator. Internal error: perform a power down reset with subsequent function test. If the error occurs again after the function test, replace the device.
ON	ON	OFF	OFF	The sensor circuit is active. The reset/start circuit (S34) is/was activated. The safety circuit (K1 and K2) is not picking up.	Error during manual reset S34 (stuck-at at the input).	Remove the error in the reset/start circuit. Then perform a function test.
ON	ON	OFF	ON	The sensor circuit is active. The reset/start circuit (S34 or S35) is/was activated. The safety circuit (K1) is not picking up.	External error: sensor circuit channel 1 was opened and reactivated. Internal error: diagnostics active.	External error: check the sensor circuit. Internal error: perform a power down reset with subsequent function test. If the error occurs again after the function test, replace the device.
ON	ON	ON	OFF	The sensor circuit is active. The reset/start circuit (S34 or S35) is/was activated. The safety circuit (K2) is not picking up.	External error: sensor circuit channel 2 was opened and reactivated. Internal error: diagnostics active.	External error: check the sensor circuit. Internal error: perform a power down reset with subsequent function test. If the error occurs again after the function test, replace the device.
OFF	OFF	OFF	OFF	The sensor circuit is active.	<ol> <li>No supply voltage at A1/A</li> <li>Over- or undervoltage at A1</li> </ol>	Check the supply voltage.

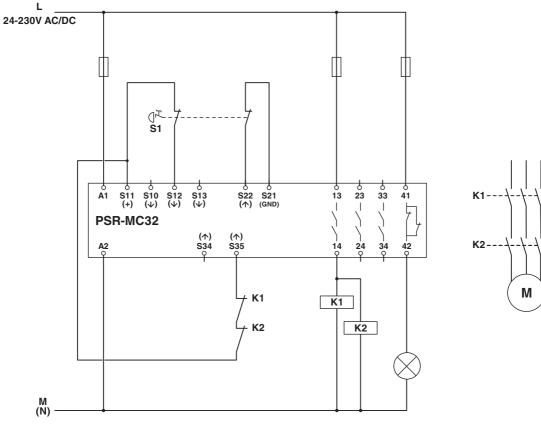
## 17 Application examples

## 17.1 Emergency stop monitoring/automatic start

- Two-channel emergency stop monitoring
- Automatic start
- Monitoring of external, force-guided contactors
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator can be ruled out



Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.





S1	Emergency stop button
K1/K2	Force-guided contactors

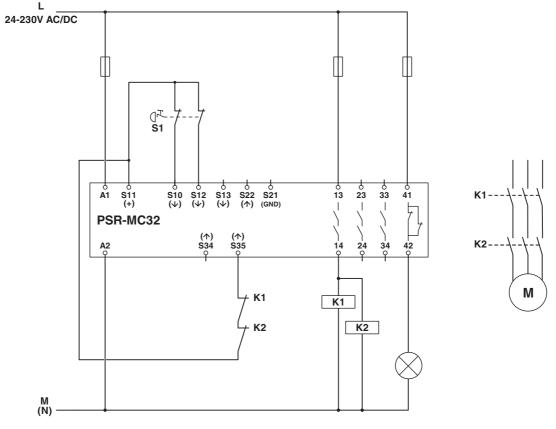
## 17.2 Emergency stop monitoring / automatic start / without cross-circuit detection

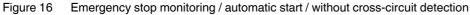
- Two-channel emergency stop monitoring
- Automatic start
- Monitoring of external, force-guided contactors
- No cross-circuit detection in the sensor circuit
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator and the sensor circuit can be ruled out

## **i**

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.

For sensor circuits in the field, prevent crosscircuits by using a cable installation that is protected mechanically.





Key:

K1/K2 Force-guided contactors

## 17.3 Emergency stop monitoring/manual, monitored start

- Two-channel emergency stop monitoring
- Manual, monitored start
- Monitoring of external, force-guided contactors
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator can be ruled out
- i

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.

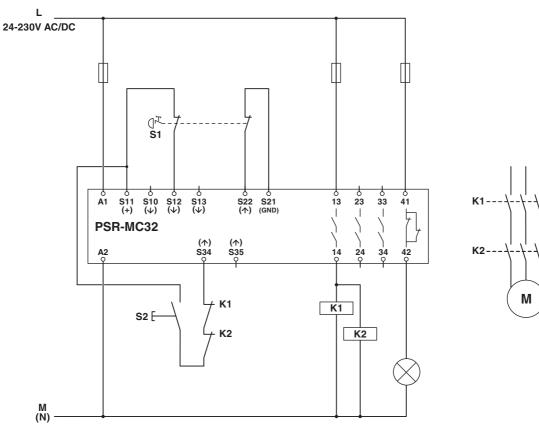


Figure 17 Emergency stop monitoring/manual, monitored start

- S1 Emergency stop button
- S2 Manual reset device
- K1/K2 Force-guided contactors

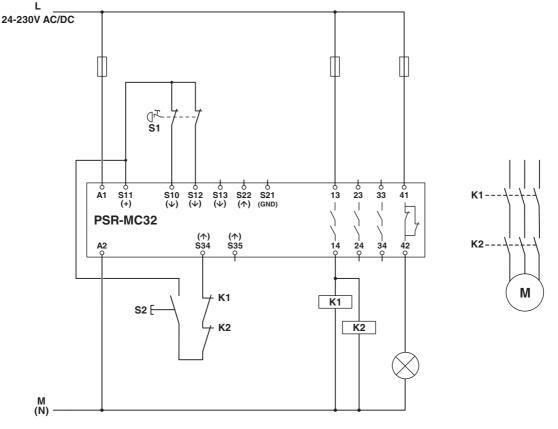
## 17.4 Emergency stop monitoring / manual, monitored start / without cross-circuit detection

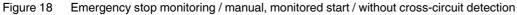
- Two-channel emergency stop monitoring
- Manual, monitored start
- Monitoring of external, force-guided contactors
- No cross-circuit detection in the sensor circuit
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator and the sensor circuit can be ruled out

# **i**

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.

For sensor circuits in the field, prevent crosscircuits by using a cable installation that is protected mechanically.





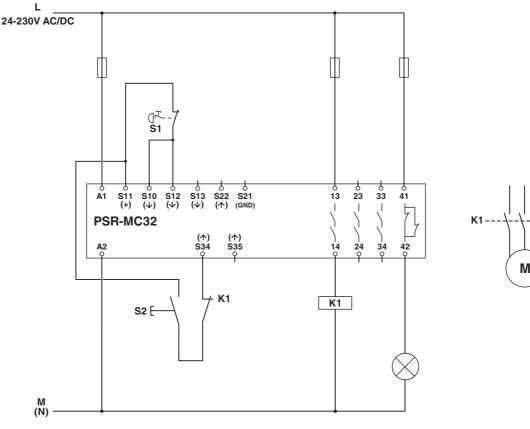
- S1 Emergency stop button
- S2 Manual reset device
- K1/K2 Force-guided contactors

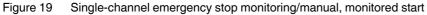
## 17.5 Single-channel emergency stop monitoring

- Single-channel emergency stop monitoring
- Manual, monitored start
- Monitoring of external contactors (optional)
- No cross-circuit detection in the sensor circuit
- Suitable up to category 1, PL c (EN ISO 13849-1), SIL 1 (EN 62061)



Feedback from contactor K1 is not essential in order to achieve category 1.





- S1 Emergency stop button
- S2 Manual reset device
- K1 Contactor

## 17.6 Magnetic switch monitoring/automatic start

- Two-channel, non-equivalent magnetic switch monitoring
- Automatic start
- Monitoring of external, force-guided contactors
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator can be ruled out

# i

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.

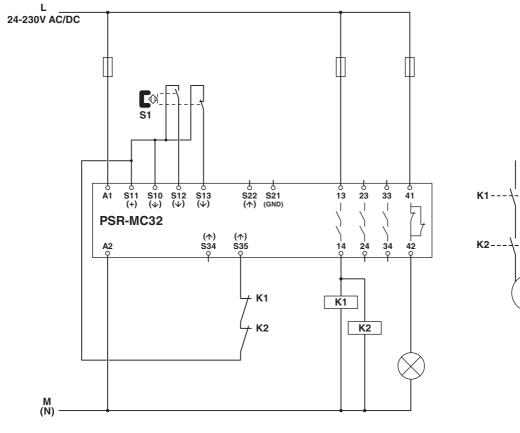


Figure 20 Magnetic switch monitoring/automatic start

Key:

- S1 Solenoid switch
- K1/K2 Force-guided contactors

Μ

## 17.7 Magnetic switch monitoring/manual, monitored start

- Two-channel, non-equivalent magnetic switch monitoring
- Manual, monitored start
- Monitoring of external, force-guided contactors
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator can be ruled out

## i

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.

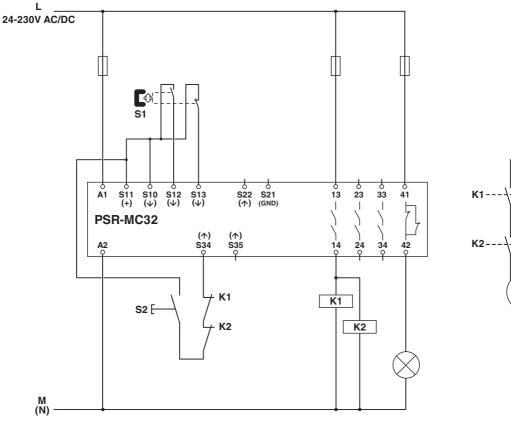


Figure 21 Magnetic switch monitoring/manual, monitored start

Key:

S1 Solenoid swite	ch
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- S2 Manual reset device
- K1/K2 Force-guided contactors

Μ

## 17.8 Light grid monitoring/manual, monitored start

- Two-channel light grid monitoring
- Manual, monitored start
- Monitoring of external, force-guided contactors
- Cross-circuit detection via light grid
- Suitable up to category 4, PL e (EN ISO 13849-1), SIL 3 (EN 62061), if cross-circuits in the control to the actuator can be ruled out

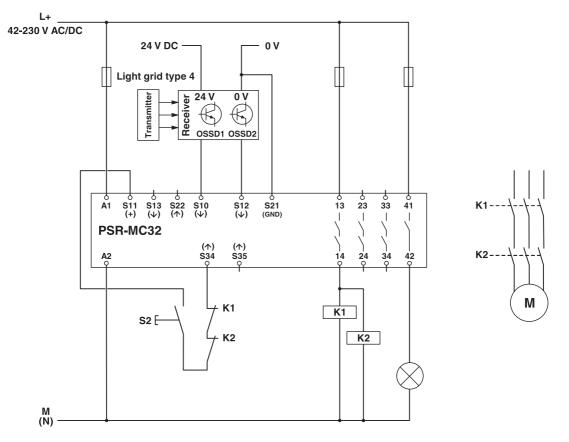


i

## WARNING: Loss of functional safety!

Make sure that the signal generator and the safety relay have the same ground potential.

Cross-circuits in the cable installation can be excluded if the safety relay and external contactors K1 and K2 are located in the same electrical installation space.





Key:

S2Manual reset deviceK1/K2Force-guided contactors

## 18 Attachment

i

## 18.1 Using PSR devices at altitudes greater than 2000 m above sea level

The following section describes the special conditions for using PSR devices at altitudes greater than 2000 m above sea level. Observe the relevant device-specific data (technical data, derating, etc.) according to the product documentation for the individual device.

#### Using the device at altitudes greater than 2000 m above sea level up to max. 4500 m above sea level is possible under the following conditions:

 Limit the rated control circuit supply voltage (U<sub>S</sub>) in accordance with the table below. Observe the technical data for the device.

U <sub>S</sub> according to the technical data for the device	U <sub>S</sub> when used at altitudes greater than 2000 m above sea level
< 150 V AC/DC	U <sub>S</sub> according to the technical data for the device still valid
> 150 V AC/DC	Limited to max. 150 V AC/ DC

2. Limit the maximum switching voltage in accordance with the table below. Observe the technical data for the device.

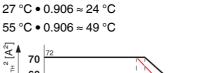
Max. switching voltage according to the technical data for the device	Max. switching voltage when used at altitudes greater than 2000 m above sea level
< 150 V AC/DC	Max. switching voltage according to the technical data for the device still valid
> 150 V AC/DC	Limited to max. 150 V AC/ DC

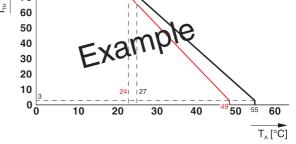
- 3. Reduce the maximum ambient temperature for operation by the corresponding factor in accordance with the table below.
- 4. If derating is specified, offset all the points of the derating curve by the corresponding factor in accordance with the table below.

Altitude above sea level	Temperature derating factor
2000 m	1
2500 m	0.953
3000 m	0.906
3500 m	0.859
4000 m	0.813
4500 m	0.766

## Example calculation for 3000 m

The following calculation and the illustrated derating curve are provided as examples. Perform the actual calculation and offset the derating curve for the device used according to the technical data and the "Derating" section.







## 18.2 Revision history

Version	Date	Contents
00	2016-10-17	First publication
01	2016-12-16	Technical data: Filter time at A1 inserted, interrupting rating revised; section calculating the power dissipation revised

>>Phoenix Contact(菲尼克斯)