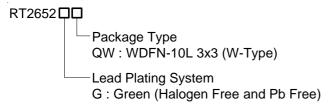


# 2A, 1.2MHz Synchronous Step-Down Converter

## **General Description**

The RT2652 is a high efficiency synchronous, step-down DC-DC converter. The available input voltage range is from 2.7V to 5.5V the regulated output voltage is adjustable from 0.6V to VIN while delivering up to 2A of output current. The internal synchronous low on-resistance power switches increase efficiency and eliminate the need for an external Schottky diode. The switching frequency is fixed internally at 1.2MHz. The 100% duty cycle provides low dropout operation extending battery life in portable systems. Current mode operation with internal compensation allows the transient response to be optimized. The RT2652 is available in the WDFN-10L 3x3 package.

## **Ordering Information**



### Note:

#### Richtek products are:

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- RoHS compliant and compatible with the current requirements of IPC/JEDEC J-STD-020.
- ▶ Suitable for use in SnPb or Pb-free soldering processes.

### **Features**

• High Efficiency: Up to 95%

• Fixed Frequency : 1.2MHz

No Schottky Diode Required

Internal Compensation

• 0.6V Reference Allows Low Output Voltage

• 100% Duty Cycle for Low Dropout Operation

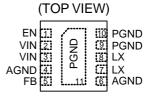
• OCP, UVP, OTP

• RoHS Compliant and Halogen Free

## **Applications**

- Enterprise Servers
- Ethernet Switches & Routers
- Global Storage
- Telecom & Industrial
- Cell Phones & DSC's

## **Pin Configuration**



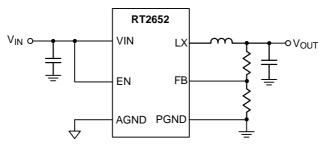
WDFN-10L 3x3

# **Marking Information**



0K= : Product Code YMDNN : Date Code

# **Simplified Application Circuit**

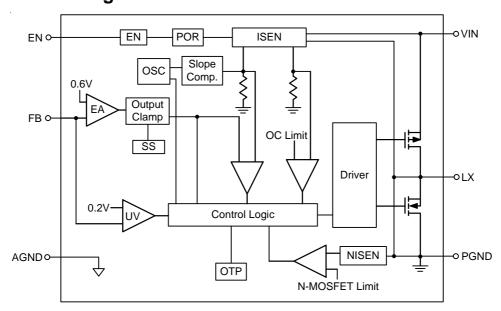




# **Functional Pin Description**

Pin No.	Pin Name	Pin Function				
1	EN	Enable Control Input. Pull high to turn on. Do not float.				
2, 3	VIN	Power Input. Decouple this pin to GND with a 22µF ceramic capacitor at least.				
4, 6	AGND	Analog Ground.				
5	FB	Feedback Voltage Input. This pin receives the feedback voltage from an external resistive divider connected across the output.				
7, 8	LX	Power MOSFET Switch Node. Connect this pin to the inductor.				
9, 10, 11 (Exposed Pad)	PGND	Power Ground. The exposed pad must be soldered to a large PCB and connected to GND for maximum power dissipation.				

# **Functional Block Diagram**



# **Operation**

The RT2652 is a monolithic, constant-frequency, current mode step-down DC-DC converter. During normal operation, the internal high side MOSFET is turned on at the beginning of each cycle. Current in the inductor increases until the peak inductor current reaches the value defined by the internal error amplifier. The error amplifier adjusts the voltage of its output by comparing the feedback signal from a resistor divider on the FB pin with an internal 0.6V reference. When the load current increases, it causes a reduction in the feedback voltage relative to the reference. The error amplifier raises its output voltage until the average inductor current matches the new load current. When the

high side MOSFET turns off, the synchronous power switch (N-MOSFET) turns on until either the bottom current limit is reached or the beginning of the next cycle. The operating frequency is set by the internal oscillator at 1.2MHz. In VIN larger than 6V condition, the high side MOSFET is turned off and the low side MOSFET is switched on until either the VIN over voltage condition is cleared or the low side MOSFET's current limit is reached.

3



# Absolute Maximum Ratings (Note 1)

• Supply Voltage, VIN	0.3V to 6.5V
• Switch Node Voltage, LX	
• Other Pins	0.3V to 6.5V
<ul> <li>Power Dissipation, P<sub>D</sub> @ T<sub>A</sub>= 25°C</li> </ul>	
WDFN-10L 3x3	1.429W
Package Thermal Resistance (Note 2)	
WDFN-10L 3x3, $\theta_{JA}$	70°C/W
WDFN-10L 3x3, $\theta_{\text{JC}}$	8.2°C/W
• Junction Temperature	150°C
• Lead Temperature (Soldering, 10 sec.)	260°C
Storage Temperature Range	−65°C to 150°C
ESD Susceptibility (Note 3)	
HBM (Human Body Model)	2kV
Recommended Operating Conditions (Note 4)	
Supply Voltage, VIN	2.7V to 5.5V

• Junction Temperature Range ------ -40°C to 125°C
• Ambient Temperature Range ------ -40°C to 85°C

## **Electrical Characteristics**

( $V_{IN} = 3.3V$ ,  $T_A = 25$ °C unless otherwise specified)

Parameter		Symbol	Test Conditions	Min	Тур	Max	Unit	
Feedback Reference Voltage		V <sub>REF</sub>		0.594	0.6	0.606	V	
Feedback Leakage Current		I <sub>FB</sub>			0.1	0.4	μΑ	
DC Bias Current			Active, V <sub>FB</sub> =0.7V, not switching		110	220	μΑ	
			Shutdown			1	μΑ	
Output Voltage Line Regulation			V <sub>IN</sub> = 2.7V to 5.5V		0.04		%/V	
Output Voltage Load Regulation			I <sub>OUT</sub> = 10mA to 2000mA		0.2		%/A	
Switch Leakage Current			EN = 0V			1	μΑ	
Switching Frequency				0.96	1.2	1.44	MHz	
Switch	High-Side	R <sub>DS(ON)_</sub> H			110	130	mΩ	
On-Resistance	Low-Side	R <sub>DS(ON)_L</sub>			70	90		
P-MOSFET Current Limit		I <sub>LIM</sub>		2.5	3.5		Α	
Under Voltage Lockout Threshold			VDD Rising		2.4		V	
			VDD Falling		2.2		V	
EN Input Voltage	Logic-High	VIH		1.5			\/	
	Logic-Low	VIL				0.3	V	
EN Pull Low Resistance					500		kΩ	

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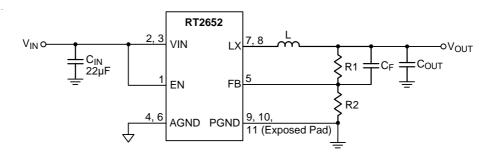


Parameter	Symbol	Test Conditions	Min	Тур	Max	Unit
Over Temperature Protection (latch-off)				150		°C
Soft-Start Time			1.3			ms
V <sub>OUT</sub> Discharge Resistance				100	150	Ω
V <sub>OUT</sub> UVP (latch-off)				33		%

- **Note 1.** Stresses beyond those listed "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions may affect device reliability.
- Note 2.  $\theta_{JA}$  is measured at  $T_A = 25^{\circ}C$  on a high effective thermal conductivity four-layer test board per JEDEC 51-7.  $\theta_{JC}$  is measured at the exposed pad of the package.
- Note 3. Devices are ESD sensitive. Handling precaution is recommended.
- Note 4. The device is not guaranteed to function outside its operating conditions..



# **Typical Application Circuit**

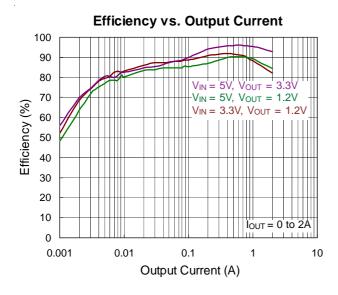


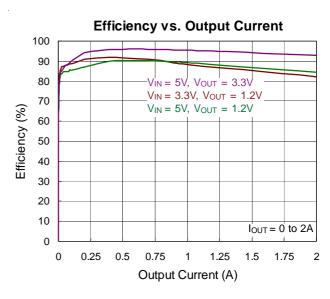
**Table 1. Recommended Component Selection** 

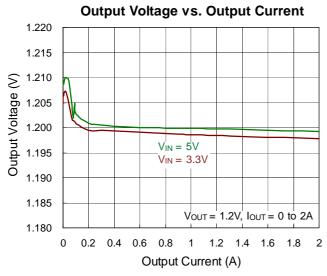
V <sub>OUT</sub> (V)	<b>R1 (k</b> Ω)	<b>R2 (k</b> Ω)	C <sub>F</sub> (pF)	<b>L (μH)</b>	C <sub>OUT</sub> (μ <b>F</b> )
3.3	37	8.2	200	2	22
2.5	26	8.2	200	2	22
1.8	16.5	8.2	200	1.5	22
1.5	12.3	8.2	200	1.5	22
1.2	8.2	8.2	200	1.5	22
1	5.6	8.2	200	1.5	22

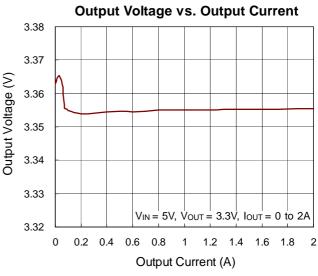


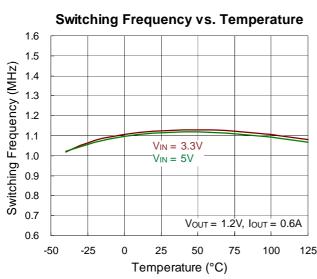
# **Typical Operating Characteristics**

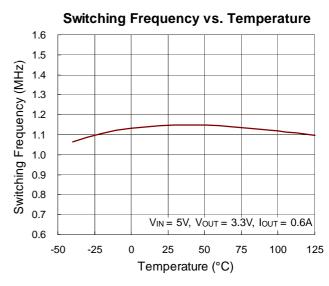




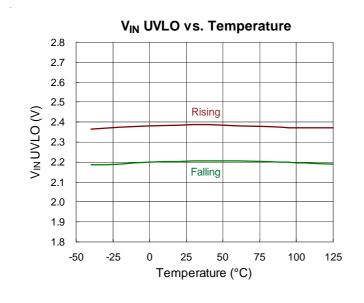


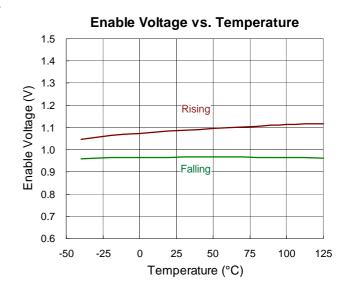


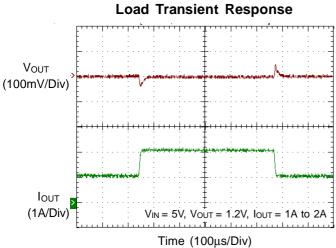


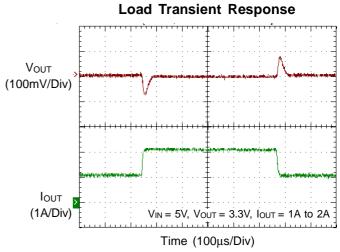


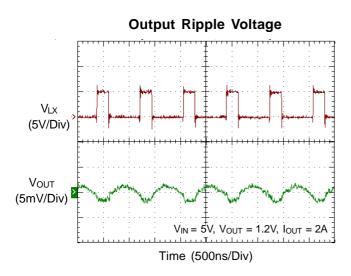


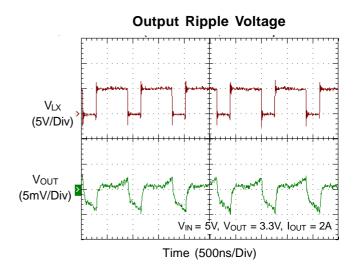








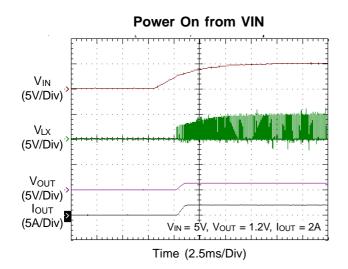


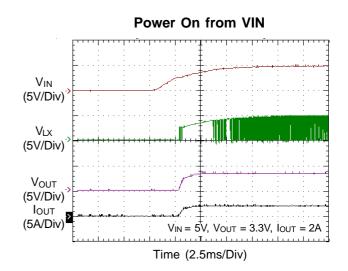


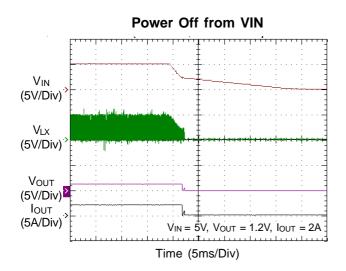
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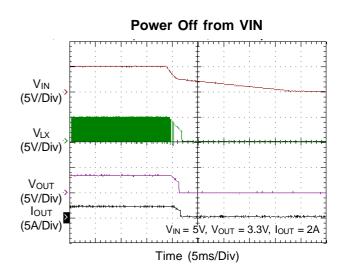
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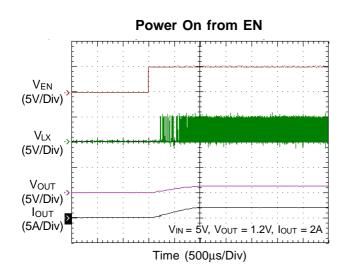


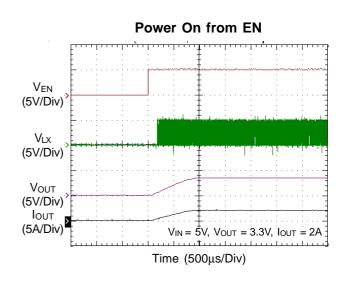






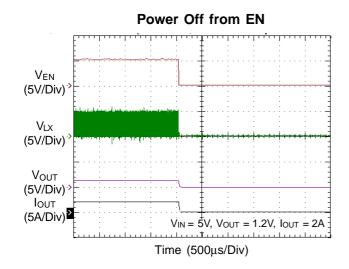


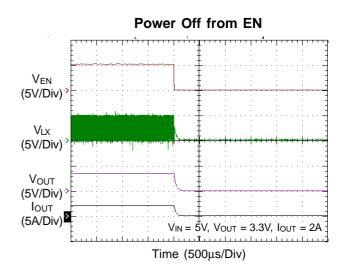


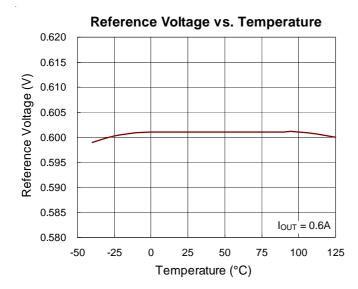


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## **Application Information**

The RT2652 is a single-phase buck PWM converter. It provides single feedback loop, current mode control with fast transient response. An internal 0.6V reference allows the output voltage to be precisely regulated for low output voltage applications. A fixed switching frequency (1.2MHz) oscillator and internal compensation are integrated to minimize external component count.

### **Output Voltage Setting**

The output voltage is set by an external resistive voltage divider according to the following equation:

$$V_{OUT} = V_{REF} \left( 1 + \frac{R1}{R2} \right)$$

Where  $V_{REF}$  is equals 0.6V (typ.).

The resistive voltage divider allows the FB pin to sense a fraction of the output voltage as shown in Figure 1.

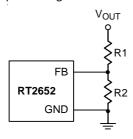


Figure 1. Setting the Output Voltage

### **Chip Enable and Disable**

The EN pin allows for power sequencing between the controller bias voltage and another voltage rail. The RT2652 remains in shutdown if the EN pin is lower than 400mV. The recommended EN falling slew rate is faster than 1V/ 33 $\mu$ s. When the EN pin rises above the V<sub>EN</sub> trip point, the RT2652 begins a new initialization and soft-start cycle.

### **Inductor Selection**

For a given input and output voltage, the inductor value and operating frequency determine the ripple current. The ripple current  $\Delta I_L$  increases with higher  $V_{IN}$  and decreases with higher inductance.

$$\Delta I_{L} = \left[ \frac{V_{OUT}}{f \times L} \right] \times \left[ 1 - \frac{V_{OUT}}{V_{IN}} \right]$$

Having a lower ripple current reduces not only the ESR losses in the output capacitors but also the output voltage ripple. Highest efficiency operation is achieved by reducing ripple current at low frequency, but a large inductor is required to attain this goal. For ripple current selection, the value of  $\Delta I_L = 0.4(I_{MAX})$  is a reasonable starting point. The largest ripple current occurs at the highest  $V_{IN}$ . To guarantee that the ripple current stays below a specified maximum value, the inductor should be chosen according to the following equation :

$$L = \left[ \frac{V_{OUT}}{f \times \Delta I_{L(MAX)}} \right] \times \left[ 1 - \frac{V_{OUT}}{V_{IN(MAX)}} \right]$$

### Slope Compensation and Inductor Peak Current

Slope compensation provides stability in constant frequency architectures by preventing sub-harmonic oscillations at duty cycles greater than 50%. It is accomplished internally by adding a compensating ramp to the inductor current signal. Normally, the maximum inductor peak current is reduced when slope compensation is added. In this IC, however, separated inductor current signal is used to monitor over current condition and this keeps the maximum output current relatively constant regardless of duty cycle.

### **Low Dropout Operation**

The RT2652 is designed to operate down to an input supply voltage of 2.7V. One important consideration at low input supply voltage is that the R<sub>DS(ON)</sub> of the P-Channel and N-Channel power switches increases. The user should calculate the power dissipation when the RT2652 is used at 100% duty cycle with low input voltages to ensure that thermal limits are not exceeded. Slope compensation and inductor peak current slope compensation provides stability in constant frequency architectures by preventing sub-harmonic oscillations at duty cycles greater than 50%. It is accomplished internally by adding a compensating ramp to the inductor current signal. Normally, the maximum inductor peak current is reduced when slope compensation is added. In the RT2652, however, separated inductor current signals are used to monitor over current condition. This keeps the maximum output current relatively constant regardless of duty cycle.

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### **Short Circuit Protection**

When the output is shorted to ground, the inductor current decays very slowly during a single switching cycle. A current runaway detector is used to monitor inductor current. As current increases beyond the control of current loop, switching cycles will be skipped to prevent current runaway from occurring.

### **Under Voltage Lockout Threshold**

The IC includes an input Under Voltage Lockout Protection (UVLO). If the input voltage exceeds the UVLO rising threshold voltage, the converter resets and prepares the PWM for operation. If the input voltage falls below the UVLO falling threshold voltage during normal operation, the device stops switching. The UVLO rising and falling threshold voltage includes a hysteresis to prevent noise caused reset.

#### Thermal Shutdown

The device implements an internal thermal shutdown function when the junction temperature exceeds 150°C. The thermal shutdown disables the device until the junction temperature drops below the hysteresis (20°C typ.). Then, the device is re-enabled and automatically reinstates the power up sequence.

### **Thermal Considerations**

For continuous operation, do not exceed absolute maximum junction temperature. The maximum power dissipation depends on the thermal resistance of the IC package, PCB layout, rate of surrounding airflow, and difference between junction and ambient temperature. The maximum power dissipation can be calculated by the following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \theta_{JA}$$

where  $T_{J(MAX)}$  is the maximum junction temperature,  $T_A$  is the ambient temperature, and  $\theta_{JA}$  is the junction to ambient thermal resistance.

For recommended operating condition specifications, the maximum junction temperature is 125°C. The junction to ambient thermal resistance,  $\theta_{JA}$ , is layout dependent. For WDFN-10L 3x3 packages, the thermal resistance,  $\theta_{JA}$ , is 70°C/W on a standard JEDEC 51-7 four-layer thermal test

board. The maximum power dissipation at  $T_A = 25^{\circ}C$  can be calculated by the following formulas :

$$P_{D(MAX)} = (125^{\circ}C - 25^{\circ}C) / (70^{\circ}C/W) = 1.429W$$
 for WDFN-10L 3x3 package

The maximum power dissipation depends on the operating ambient temperature for fixed  $T_{J(MAX)}$  and thermal resistance,  $\theta_{JA}$ . The derating curves in Figure 2 allow the designer to see the effect of rising ambient temperature on the maximum power dissipation.

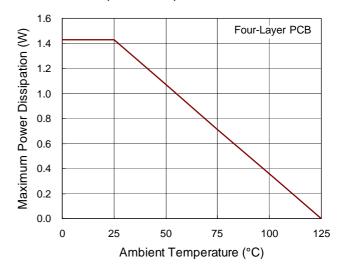
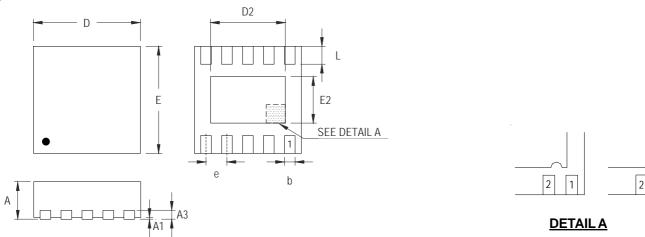


Figure 2. Derating Curve of Maximum Power Dissipation



### **Outline Dimension**



Pin #1 ID and Tie Bar Mark Options

Note: The configuration of the Pin #1 identifier is optional, but must be located within the zone indicated.

Symbol	Dimensions	n Millimeters	Dimensions In Inches		
	Min	Max	Min	Max	
А	0.700	0.800	0.028	0.031	
A1	0.000	0.050	0.000	0.002	
А3	0.175	0.250	0.007	0.010	
b	0.180	0.300	0.007	0.012	
D	2.950	3.050	0.116	0.120	
D2	2.300	2.650	0.091	0.104	
Е	2.950	3.050	0.116	0.120	
E2	1.500	1.750	0.059	0.069	
е	0.5	500	0.020		
L	0.350	0.450	0.014	0.018	

W-Type 10L DFN 3x3 Package

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