







SN65HVD1785, SN65HVD1786, SN65HVD1787 SN65HVD1791, SN65HVD1792, SN65HVD1793 SLLS872J - JANUARY 2008 - REVISED MARCH 2023

## SN65HVD17xx Fault-Protected RS-485 Transceivers With Extended **Common-Mode Range**

#### 1 Features

- Bus-Pin Fault Protection to:
  - > ±70 V ('HVD1785, 86, 91, 92)
  - > ±30 V ('HVD1787, 93)
- Common-Mode Voltage Range (-20 V to 25 V) More Than Doubles TIA/EIA 485 Requirement
- Bus I/O Protection
  - ±16 kV JEDEC HBM Protection
- Reduced Unit Load for Up to 256 Nodes
- Failsafe Receiver for Open-Circuit, Short-Circuit and Idle-Bus Conditions
- Low Power Consumption
  - Low Standby Supply Current, 1 μA Typical
  - I<sub>CC</sub> 5 mA Quiescent During Operation
- Power-Up, Power-Down Glitch-Free Operation

## 2 Applications

Designed for RS-485 and RS-422 Networks

## 3 Description

These devices are designed to survive overvoltage faults such as direct shorts to power supplies, miswiring faults, connector failures, cable crushes, and tool mis-applications. They are also robust to ESD events, with high levels of protection to human-body model specifications.

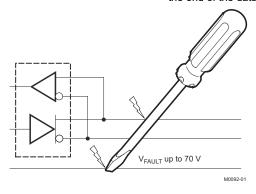
These devices combine a differential driver and a differential receiver, which operate from a single power supply. In the 'HVD1785, 'HVD1786, and 'HVD1787, the driver differential outputs and the receiver differential inputs are connected internally to form a bus port suitable for half-duplex (two-wire bus) communication. In the 'HVD1793, the driver differential outputs and the receiver differential inputs are separate pins, to form a bus port suitable for fullduplex (four-wire bus) communication. These ports feature a wide common-mode voltage range, making the devices suitable for multipoint applications over long cable runs. These devices are characterized from -40°C to 105°C.

For similar features with 3.3-V supply operation, see the SN65HVD1781 (SLLS877).

#### **Device Information**

| -   |                        | ••                |
|---|------------------------|-------------------|
| PART NUMBER                                 | PACKAGE <sup>(1)</sup> | BODY SIZE (NOM)   |
| SN65HVD1785,                                | SOIC (8)               | 4.90 mm × 3.91 mm |
| SN65HVD1786,<br>SN65HVD1787                 | PDIP (8)               | 9.81 mm × 6.35 mm |
| SN65HVD1791,<br>SN65HVD1792,<br>SN65HVD1793 | SOIC (14)              | 8.65 mm × 3.91 mm |

For all available packages, see the orderable addendum at the end of the datasheet.



**Example of Bus Short to Power Supply** 



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| •        | Added Receiver enabled $V_{CM} > V_{CC}$ condition and values to the Driver enabled time  |                |
|----------|---|----------------|
| С        | hanges from Revision D (June 2008) to Revision E (July 2008)  | Page           |
| •        | Changed - Removed Product Preview label   |                |
| •        | Changed SN65HVD1792 Removed Product Preview label   |                |
| •        | Changed SN65HVD1793 Removed Product Preview label   | 4              |
| С        | hanges from Revision C (March 2008) to Revision D (June 2008)   | Page           |
| •        | Added Features Bullet: Power-Up, Power-Down Glitch-Free Operation   |                |
| •        | Changed (Preview) to part number SN65HVD1791 in the Product Selection Guide   |                |
| •        | Added section - APPLICATION INFORMATION   |                |
| •        | Changed Receiver disabled by default - Enable from X to OPEN. Output from OPEN to Z   | 18             |
| С        | hanges from Revision B (March 2008) to Revision C (March 2008)  | Page           |
| •        | Changed Rec Op Table. Signaling rate, HVD1787, HVD1793 From: 20 Mbps max to 10 Mbps max   | 6              |
| С        | hanges from Revision A (March 2008) to Revision B (March 2008)  | Page           |
| •        | Added $T_A \le 85^{\circ}$ C and $T_A \le 105^{\circ}$ C conditions and values to the Receiver low-level output voltage<br>Changed the max value for Supply Current (quiescent) Driver and receiver disabled, From 1 $\mu$ A To 5 $\mu$ |                |
| _<br>C   | hanges from Revision * (January 2008) to Revision A (March 2008)  | Page           |
| <u>.</u> | Changed Features Bullet From: Low Standby Supply Current, 2 µA Max To: Low Standby Supply Curre   |                |
|          | µA Typ  |                |
| •        | Deleted columns to the PRODUCT SELECTION GUIDE for Package Options and Status   |                |
| •        | Added text: For similar features with 3.3 V supply operation  |                |
| •        | Changed the Product Selection Guide Signaling Rate for SN65HVD1787 From 20 Mbps To: 10 Mbps   |                |
| •        | Changed the Product Selection Guide Signaling Rate for SN65HVD1793 From 20 Mbps To: 10 Mbps   | <mark>4</mark> |
| •        | Deleted The Competitive Comparison table  |                |
| •        | Added $ V_{OD} $ RS-485 with common-mode load $T_A \le 85^{\circ}$ C and $T_A \le 105^{\circ}$ C  | <mark>7</mark> |
| •        | Changed $\Delta V_{OC}$ From min = -0.2 mV and max 0.2 mV To: min = -100 mV and max 100 mV  | <mark>7</mark> |
| •        | Changed HVD1785/1791 Driver differential output rise/fall time max value From 2.5 µs To: 2.6 µs   |                |
| •        | Changed HVD1787/1793 Driver differential output rise/fall time max value From 1.5 ns To: 30 ns  |                |
| •        | Changed Receiver propagation delay max value From 50 ns To: 70 ns   |                |
| •        | Changed t <sub>PLZ</sub> , t <sub>PHZ</sub> Receiver disable time From 3000 ns To 100 ns  | 9              |
| •        | Deleted graph DIFFERENTIAL OUTPUT VOLTAGE vs DIFFERENTIAL LOAD CURRENT  | 10             |



## **5 Product Selection Guide**

| PART NUMBER | DUPLEX | SIGNALING RATE | NODES     | CABLE LENGTH |
|-------------|--------|----------------|-----------|--------------|
| SN65HVD1785 | Half   | 115 kbps       | Up to 256 | 1500 m       |
| SN65HVD1786 | Half   | 1 Mbps         | Up to 256 | 150 m        |
| SN65HVD1787 | Half   | 10 Mbps        | Up to 64  | 50 m         |
| SN65HVD1791 | Full   | 115 kbps       | Up to 256 | 1500 m       |
| SN65HVD1792 | Full   | 1 Mbps         | Up to 256 | 150 m        |
| SN65HVD1793 | Full   | 10 Mbps        | Up to 64  | 50 m         |

## **6 Pin Configuration and Functions**

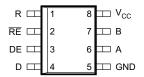
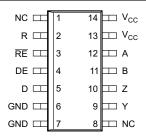


Figure 6-1. D or P Package 8-Pin SOIC or PDIP SN65HVD1785, 1786, 1787 (Top View)

## **Pin Functions (SN65HVD1785, SN65HVD1786, SN65HVD1787)**

| P               | PIN |                      | DESCRIPTION  |  |  |
|-----------------|-----|----------------------|--|--|--|
| NAME            | NO. | TYPE                 | DESCRIPTION  |  |  |
| Α               | 6   | Bus input/<br>output | Driver output or receiver input (complementary to B) |  |  |
| В               | 7   | Bus input/<br>output | Driver output or receiver input (complementary to A) |  |  |
| D               | 4   | Digital input        | Driver data input                                    |  |  |
| DE              | 3   | Digital input        | Driver enable, active high                           |  |  |
| GND             | 5   | Reference potential  | Local device ground                                  |  |  |
| R               | 1   | Digital output       | Receive data output                                  |  |  |
| RE              | 2   | Digital input        | ceiver enable, active low                            |  |  |
| V <sub>CC</sub> | 8   | Supply               | 4.5-V-to-5.5-V supply                                |  |  |





NC - No internal connection

Pins 6 and 7 are connected together internally.

Pins 13 and 14 are connected together internally.

## Figure 6-2. D Package 14-Pin SOIC SN65VD1791, 1792, 1793 (Top View)

#### **Pin Functions (SN65HVD1791, SN65HVD1792, SN65HVD1793)**

| PIN             |        | TYPE                | DESCRIPTION                         |  |
|-----------------|--------|---------------------|-------------------------------------|--|
| NAME            | NO.    | ITPE                | DESCRIPTION                         |  |
| A               | 12     | Bus input           | Receiver input (complementary to B) |  |
| В               | 11     | Bus input           | Receiver input (complementary to A) |  |
| Υ               | 9      | Bus output          | Driver output (complementary to Z)  |  |
| Z               | 10     | Bus output          | Driver output (complementary to Y)  |  |
| D               | 5      | Digital input       | ver data input                      |  |
| DE              | 4      | Digital input       | Driver enable, active high          |  |
| GND             | 6, 7   | Reference potential | Local device ground                 |  |
| R               | 2      | Digital output      | Receive data output                 |  |
| RE              | 3      | Digital input       | Receiver enable, active low         |  |
| V <sub>CC</sub> | 13, 14 | Supply              | / to 5.5-V supply                   |  |
| NC              | 1, 8   | No connect          | No connect; should be left floating |  |



## 7 Specifications

## 7.1 Absolute Maximum Ratings<sup>(1)</sup>

|                  |                                |                           |           | MIN  | MAX                   | UNIT |
|------------------|--------------------------------|---------------------------|-----------|------|-----------------------|------|
| V <sub>CC</sub>  | V <sub>CC</sub> Supply voltage |                           |           | -0.5 | 7                     | V    |
|                  |                                | 'HVD1785, 86, 91, 92, 93  | A, B pins | -70  | 70                    | V    |
|                  | Voltage at bus pins            | 'HVD1787                  | A, B pins | -70  | 30                    | V    |
|                  |                                | 'HVD1793                  | Y, Z pins | -70  | 30                    | V    |
|                  | Input voltage at any logic pin | 1                         |           | -0.3 | V <sub>CC</sub> + 0.3 | V    |
|                  | Transient overvoltage pulse    | through 100 Ω per TIA-485 |           | -100 | 100                   | V    |
|                  | Receiver output current        |                           |           | -24  | 24                    | mA   |
| TJ               | Junction temperature           |                           |           | 170  | °C                    |      |
| T <sub>stg</sub> | Storage temperature            |                           |           |      | 160                   | °C   |

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 7.2 ESD Ratings

|                    |   |  |                       | VALUE  | UNIT |
|--------------------|---|--|-----------------------|--------|------|
|                    | Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> , Bus terminals and GND |  | ±16000                |        |      |
|                    |   | JEDEC Standard 22, Test Method A114  | All pins              | ±4000  |      |
| V <sub>(ESD)</sub> | Electrostatic<br>discharge  | Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup> , JEDEC Standard 22, Test Method C101 |                       |        | V    |
|                    |   | Machine Model, JEDEC Standard 22, Test Method A115   |                       | ±400   |      |
|                    |   | IEC 60749-26 ESD (human-body model)  | Bus terminals and GND | ±16000 |      |

<sup>(1)</sup> JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

## 7.3 Recommended Operating Conditions

|                   |                          |  | MIN | NOM | MAX             | UNIT |
|-------------------|--------------------------|--|-----|-----|-----------------|------|
| V <sub>CC</sub>   | Supply voltage           | Supply voltage   |     | 5   | 5.5             | V    |
| VI                | Input voltage at         | any bus terminal (separately or common mode) <sup>(1)</sup>                      | -20 |     | 25              | V    |
| V <sub>IH</sub>   | High-level input         | t voltage (driver, driver enable, and receiver enable inputs)                    | 2   |     | V <sub>CC</sub> | V    |
| V <sub>IL</sub>   | Low-level input          | voltage (driver, driver enable, and receiver enable inputs)                      | 0   |     | 8.0             | V    |
| V <sub>ID</sub>   | Differential inpu        | ıt voltage   | -25 |     | 25              | V    |
|                   | Output current, driver   |  | -60 |     | 60              | mA   |
| I <sub>O</sub>    | Output current, receiver |  | -8  |     | 8               | mA   |
| $R_L$             | Differential load        | I resistance   | 54  | 60  |                 | Ω    |
| C <sub>L</sub>    | Differential load        | I capacitance  |     | 50  |                 | pF   |
|                   |                          | HVD1785, HVD1791   |     |     | 115             | kbps |
| 1/t <sub>UI</sub> | Signaling rate           | HVD1786, HVD1792   |     |     | 1               | Mhna |
|                   |                          | HVD1787, HVD1793   |     |     | 10              | Mbps |
| T <sub>A</sub>    | Operating free-          | Operating free-air temperature (see application section for thermal information) |     |     | 105             | °C   |
| TJ                | Junction tempe           | rature   | -40 |     | 150             | °C   |

<sup>(1)</sup> By convention, the least positive (most negative) limit is designated as minimum in this data sheet.

<sup>(2)</sup> JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.



#### 7.4 Thermal Information

| THERMAL METRIC <sup>(1)</sup> |  | · ·      | , SN65HVD1786,<br>IVD1787 | SN65HVD1791,<br>SN65HVD1792,<br>SN65HVD1793 | UNIT |
|-------------------------------|--|----------|---------------------------|---|------|
|                               |  | D (SOIC) | P (PDIP)                  | D (SOIC)                                    |      |
|                               |  | 8 PINS   | 8 PINS                    | 14 PINS                                     |      |
| $R_{\theta JA}$               | Junction-to-ambient thermal resistance       | 138      | 59                        | 95  | °C/W |
| R <sub>θJA (low-K)</sub>      | Junction-to-case (top) thermal resistance    | 242      | 128                       | 168   | °C/W |
| R <sub>0</sub> JC(top)        | Junction-to-board thermal resistance         | 61       | 61                        | 44  | °C/W |
| $R_{\theta JB}$               | Junction-to-top characterization parameter   | 62       | 39                        | 40  | °C/W |
| ΨЈТ                           | Junction-to-board characterization parameter | 3.4      | 17.6                      | 8.2   | °C/W |
| ΨЈВ                           | Junction-to-case (bottom) thermal resistance | 33.4     | 28.3                      | 25  | °C/W |

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report, SPRA953.

#### 7.5 Electrical Characteristics

over recommended operating conditions (unless otherwise noted)

| $ V_{OD}  \  \   \text{Driver differential output voltage magnitude} \  \   \begin{array}{llllllllllllllllllllllllllllllllll$  | PARAMETER           |  | TEST CONDITIONS   |                        |                       | MIN  | TYP                   | MAX | UNIT |
|--|---------------------|--|---|------------------------|-----------------------|------|-----------------------|-----|------|
| $R_L = 100 \ \Omega, 4.75 \ V \le V_{CC} \le 5.25 \ V \qquad 2 \qquad 2.5 \\ \hline \Delta  Vool \ Change in magnitude of driver differential output voltage                                    $  | V <sub>OD</sub>     | Driver differential output voltage magnitude | mode load, V <sub>CC</sub> > 4.75 V,  |                        |                       |      |                       |     | V    |
| $ \Delta  V_{OD}                                     $   |                     |  | $R_L = 54 \Omega, 4.75 V \le V_0$   | <sub>CC</sub> ≤ 5.25   | V                     | 1.5  | 2                     |     |      |
| $\begin{array}{c ccccccccccccccccccccccccccccccccccc$  |                     |  | R <sub>L</sub> = 100 Ω, 4.75 V ≤ \  | / <sub>CC</sub> ≤ 5.25 | 5 V                   | 2    | 2.5                   |     |      |
|  | $\Delta  V_{OD} $   |  | R <sub>L</sub> = 54 Ω   |                        |                       | -0.2 | 0                     | 0.2 | V    |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   | V <sub>OC(SS)</sub> | Steady-state common-mode output voltage      |   |                        |                       | 1    | V <sub>CC</sub> /2    | 3   | V    |
| $V_{\text{CC}(PP)} \text{ voltage } \\ V_{\text{CD}} \text{ Differential output capacitance} \\ V_{\text{IT+}} \text{ Positive-going receiver differential input voltage threshold} \\ V_{\text{IT-}} \text{ Negative-going receiver differential input voltage threshold} \\ V_{\text{TM-}} \text{ Negative-going receiver differential input voltage threshold} \\ V_{\text{NM}} \text{ Receiver differential input voltage threshold hysteresis } (V_{\text{IT+}} - V_{\text{IT-}}) \\ V_{\text{OH}} \text{ Receiver high-level output voltage} \\ V_{\text{OL}} \text{ Receiver low-level output voltage} \\ I_{\text{OH}} = -400 \ \mu\text{A} \\ I_{\text{OH}} = -400 \ \mu$   | ΔV <sub>OC</sub>    |  |   |                        |                       | -100 | 0                     | 100 | mV   |
| $V_{IT+}  \begin{array}{c} \text{Positive-going receiver differential input voltage} \\ V_{IT-}  \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \text{threshold} \\ \end{array} \\ V_{IT-}  \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \text{threshold} \\ \end{array} \\ V_{CM} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} -200  -150  \text{mV} \\ \end{array} \\ \begin{array}{c} -200  -150  \text{mV} \\ \end{array} \\ \begin{array}{c} \text{MV} \\ \end{array} \\ \begin{array}{c} \text{MV} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{II}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{II}_{OH} = -200 \ \text{MeV} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{II}_{OH} = -20 \ \text{V to } 25 \ \text{V} \\ \end{array} \\ \begin{array}{c} \text{I}_{OH} = -200 \ \text{MeV} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{II}_{OH} = -200 \ \text{MeV} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} \text{Negative-going receiver differential input voltage} \\ \end{array} \\ \begin{array}{c} Negative-going receiver differential input vol$ | V <sub>OC(PP)</sub> | ·  | 1   | ıd resistoi            | rs,                   |      | 500                   |     | mV   |
| $V_{IT-}  \text{threshold} \\ V_{IT-}  \text{Negative-going receiver differential input voltage threshold} \\ V_{HYS}  \text{Receiver differential input voltage threshold hysteresis } (V_{IT+} - V_{IT-}) \\ V_{OH}  \text{Receiver high-level output voltage} \\ V_{OL}  \text{Receiver low-level output voltage} \\ I_{OH} = -8 \text{ mA} \\ I_{OH} = -400  \mu\text{A} \\ \hline I_{OH} = -400  \mu\text{A} \\ \hline I_{OL} = 8 \text{ mA} \\ \hline I_{OL} = 8 \text{ mA} \\ \hline I_{OS}  \text{Ta} \le 85^{\circ}\text{C} \\ \hline I_{OS}  \text{O.2}  0.4 \\ \hline I_{OS}  \text{Driver input, driver enable, and receiver enable input current}} \\ I_{OS}  \text{Driver short-circuit output current} \\ \hline I_{OS}  Driver short-circuit output$  | C <sub>OD</sub>     | Differential output capacitance              |   |                        |                       |      | 23                    |     | pF   |
| $\begin{array}{c} \text{ViT-} & \text{threshold} \\ \text{V}_{\text{HYS}} & \text{Receiver differential input voltage threshold} \\ \text{V}_{\text{HYS}} & \text{Receiver differential input voltage} \\ \text{V}_{\text{OH}} & \text{Receiver high-level output voltage} \\ \end{array} \begin{array}{c} I_{\text{OH}} = -8 \text{ mA} \\ I_{\text{OH}} = -400  \mu\text{A} \\ \end{array} \begin{array}{c} 2.4 & \frac{\text{V}_{\text{CC}} - }{0.3} \\ \text{V}_{\text{O}} \\ \end{array} \begin{array}{c} \text{V}_{\text{CC}} = 100 \\ \text{V}_{\text{O}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \text{MV}_{\text{CC}} = 100 \\ \end{array} \begin{array}{c} \text{MV}_{\text{CC}} = 100 \\ M$   | V <sub>IT+</sub>    |  |   |                        |                       |      | -100                  | -10 | mV   |
| $V_{OH}  \text{Receiver high-level output voltage} \qquad \begin{array}{ c c c c c c c c } \hline V_{OH}  \text{Receiver high-level output voltage} & \hline & I_{OH} = -8 \text{ mA} & 2.4 & \frac{V_{CC} -}{0.3} & V \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & I_{OH} = -400  \mu\text{A} & 4 & & & & \\ \hline & V_{OL}  \text{Receiver low-level output voltage} & I_{OL} = 8 \text{ mA} & \frac{T_A \le 85^{\circ}\text{C}}{T_A \le 105^{\circ}\text{C}} & 0.2 & 0.4 & V \\ \hline & I_{I}  \text{Driver input, driver enable, and receiver enable input current} & & -100 & 100 & \mu\text{A} \\ \hline & I_{OZ}  \text{Receiver output high-impedance current} & V_O = 0 \text{ V or } V_{CC}, \overline{\text{RE at }} V_{CC} & -1 & 1 & \mu\text{A} \\ \hline & I_{OS}  \text{Driver short-circuit output current} & & & -250 & 250 & \text{mA} \\ \hline & I_{I}  \text{Bus input current (disabled driver)} & & V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at 0 V} & V_{I} = -7 \text{ V} & -100 & -40 & \mu\text{A} \\ \hline & V_{I} = -7 \text{ V} & -100 & -40 & 0 & 0 \\ \hline & V_{I} = -7 \text{ V} & -100 & -40 & 0 & 0 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 12 \text{ V} & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.500 \\ \hline & V_{I} = 0.500 & 0.500 & 0.500 & 0.$   | V <sub>IT-</sub>    |  | V <sub>CM</sub> = -20 V to 25 V   |                        |                       | -200 | -150                  |     | mV   |
| $V_{OH}  \text{Receiver high-level output voltage}  \begin{array}{c ccccccccccccccccccccccccccccccccccc$   | $V_{HYS}$           |  |   |                        |                       | 30   | 50                    |     | mV   |
| $V_{OL}  \text{Receiver low-level output voltage} \qquad I_{OL} = 8 \text{ mA} \qquad \frac{T_{A} \leq 85^{\circ}\text{C}}{T_{A} \leq 105^{\circ}\text{C}} \qquad 0.2  0.4}{T_{A} \leq 105^{\circ}\text{C}} \qquad 0.2  0.5}  V$ $I_{I}  \text{Driver input, driver enable, and receiver enable input current} \qquad -100 \qquad 100  \mu A$ $I_{OZ}  \text{Receiver output high-impedance current} \qquad V_{O} = 0 \text{ V or } V_{CC}, \ \overline{\text{RE}} \text{ at } V_{CC} \qquad -1 \qquad 1  \mu A$ $I_{OS}  \text{Driver short-circuit output current} \qquad -250 \qquad 250  \text{mA}$ $I_{I}  \text{Bus input current (disabled driver)} \qquad V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \qquad V_{I} = 12 \text{ V} \qquad -100 \qquad -40 \qquad V_{I} = 12 \text{ V}$  | $V_{OH}$            | Receiver high-level output voltage           | I <sub>OH</sub> = -8 mA   |                        |                       | 2.4  | V <sub>CC</sub> – 0.3 |     | V    |
| $\begin{array}{c ccccccccccccccccccccccccccccccccccc$  |                     |  | I <sub>OH</sub> = -400 μA   |                        |                       | 4    |                       |     |      |
| $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$   | Voi                 | Receiver low-level output voltage            | lo. = 8 mA  | T <sub>A</sub> ≤ 85°   | C                     |      | 0.2                   | 0.4 | V    |
| input current $V_{O}=0\ V\ or\ V_{CC}$ , $\overline{RE}$ at $V_{CC}$ $V_{I}=12\ V_{I}=7\ V_{I}=12\ V_{I}$  | VOL                 | - Noserver level earput voltage              | IOL OTHER   | T <sub>A</sub> ≤ 105   | 5°C                   |      | 0.2                   | 0.5 | •    |
|  | l <sub>i</sub>      |  |   |                        | -100                  |      | 100                   | μΑ  |      |
| $V_{CC} = 4.5 \text{ to } 5.5 \text{ V or} \\ V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \\ V_{CC} = 0 \text{ V, DE at } 0 \text{ V} \\ 0 \text{ A} = 0 \text{ V} \\ 0 \text{ A} = 0 \text{ A} $  | l <sub>OZ</sub>     | Receiver output high-impedance current       | $V_O = 0 \text{ V or } V_{CC}, \overline{RE} \text{ at } V_{CC}$                          |                        | -1                    |      | 1                     | μΑ  |      |
| $V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$ Bus input current (disabled driver) $V_{CC} = 4.5 \text{ to } 5.5 \text{ V or } V_{I} = -7 \text{ V} -100 -40$ 87 93 $V_{I} = 12 \text{ V}$ 500  | I <sub>OS</sub>     | Driver short-circuit output current          |   |                        |                       | -250 |                       | 250 | mA   |
| I <sub>I</sub> Bus input current (disabled driver) $ \begin{array}{c ccccccccccccccccccccccccccccccccccc$  |                     |  |   | 85, 86,                | V <sub>I</sub> = 12 V |      | 75                    | 125 |      |
| $V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$   | ı.                  | Rus input current (disabled driver)          | $V_{CC} = 4.3 \text{ to } 3.3 \text{ V or}$<br>$V_{CC} = 0 \text{ V, DE at } 0 \text{ V}$ |                        | V <sub>I</sub> = -7 V | -100 | <del>-4</del> 0       |     | пΔ   |
| $V_1 = -7 V \qquad -400$   | 11                  | Bus input current (disabled univer)          |   |                        | V <sub>I</sub> = 12 V |      |                       | 500 | μΛ   |
|  |                     |  |   | 01, 93                 | V <sub>I</sub> = -7 V | -400 |                       |     |      |



## 7.5 Electrical Characteristics (continued)

over recommended operating conditions (unless otherwise noted)

| PARAMETER |                            | TEST COM                          | NDITIONS  | MIN | TYP | MAX | UNIT |
|-----------|----------------------------|-----------------------------------|---|-----|-----|-----|------|
|           |                            | Driver and receiver enabled       | DE = V <sub>CC</sub> ,<br>RE = GND,<br>no load              |     | 4   | 6   |      |
| Icc       | Supply current (quiescent) | Driver enabled, receiver disabled | DE = V <sub>CC</sub> ,<br>RE = V <sub>CC</sub> ,<br>no load |     | 3   | 5   | mA   |
|           |                            | Driver disabled, receiver enabled | DE = GND,<br>RE = GND,<br>no load                           |     | 2   | 4   |      |
|           |                            | Driver and receiver disabled      | DE = GND,<br>D = open<br>RE = V <sub>CC</sub> ,<br>no load  |     | 0.5 | 5   | μА   |
|           | Supply current (dynamic)   | See Section 7.8                   | 1   |     |     |     |      |

## 7.6 Thermal Considerations

|          | PARAMET   | ER     | TEST CONDITIONS  | VALUE | UNIT |
|----------|---|--------|--|-------|------|
|          |   | 85, 91 | $V_{CC}$ = 5.5 V, $T_J$ = 150°C, $R_L$ = 300 $\Omega$ , $C_L$ = 50 pF (driver), $C_L$ = 15 pF (receiver) 5-V supply, unterminated <sup>(1)</sup>   | 290   |      |
|          | 85, 91  |        |  |       |      |
|          | P- Power dissipation                                  | 86     | $V_{CC} = 5.5 \text{ V}$ , $T_{J} = 150^{\circ}\text{C}$ , $R_{L} = 100 \Omega$ , $C_{L} = 50 \text{ pF (driver)}$ , $C_{L} = 15 \text{ pF (receiver)}$ 5-V supply, RS-422 load <sup>(1)</sup>   | 320   | mW   |
| PD       |   | 87     |  |       |      |
|          |   | 85, 91 | 14 5 5 4 7 45000 D 54 0 0 50 5 (1); )  |       |      |
|          | 86  | 86     | $V_{CC} = 5.5 \text{ V, } T_{J} = 150^{\circ}\text{C, } R_{L} = 54 \Omega, C_{L} = 50 \text{ pF (driver),}$<br>$C_{L} = 15 \text{ pF (receiver) } 5-\text{V supply, } RS-485 \text{ load}^{(1)}$ |       |      |
|          | 87  |        |  |       |      |
| $T_{SD}$ | T <sub>SD</sub> Thermal-shutdown junction temperature |        |  | 170   | °C   |

Driver and receiver enabled, 50% duty cycle square-wave signal at signaling rate: HVD1785, 1791 at 115 kbps, HVD1786 at 1 Mbps, HVD1787 at 10 Mbps)



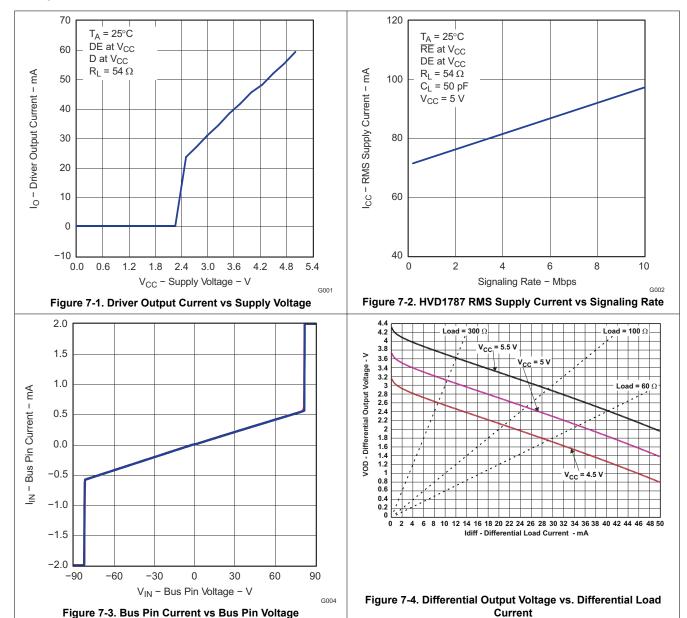
## 7.7 Switching Characteristics

over recommended operating conditions (unless otherwise noted)

|   | PARAMETER   | TEST CO                                  | NDITIONS                          | MIN | TYP | MAX | UNIT |
|---|---|--|-----------------------------------|-----|-----|-----|------|
| DRIVER (HVD                               | )1785 AND HVD1791)  |  |                                   | •   |     | •   |      |
| t <sub>r</sub> , t <sub>f</sub>           | Driver differential output rise/fall time                                   |  |                                   | 0.4 | 1.7 | 2.6 | μs   |
| t <sub>PHL</sub> , t <sub>PLH</sub>       | Driver propagation delay  | $R_L = 54 \Omega, C_L = 50$              | pF,                               |     | 0.8 | 2   | μs   |
| t <sub>SK(P)</sub>                        | Driver differential output pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub> | see Figure 8-3                           |                                   |     | 20  | 250 | ns   |
| t <sub>PHZ</sub> , t <sub>PLZ</sub>       | Driver disable time   |  |                                   |     | 0.1 | 5   | μs   |
|   | Debag and the firm  | Receiver enabled                         | See Figure 8-4<br>and Figure 8-5  |     | 0.2 | 3   |      |
| t <sub>PZH</sub> , t <sub>PZL</sub>       | Driver enable time  | Receiver disabled                        |                                   |     | 3   | 12  | μs   |
| DRIVER (HVD                               | 01786 AND HVD1792)  | 1  |                                   | 1   |     | 1   |      |
| t <sub>r</sub> , t <sub>f</sub>           | Driver differential output rise/fall time                                   |  |                                   | 50  |     | 300 | ns   |
| t <sub>PHL</sub> , t <sub>PLH</sub>       | Driver propagation delay  | $R_L = 54 \Omega, C_L = 50$              | pF,                               |     |     | 200 | ns   |
| t <sub>SK(P)</sub>                        | Driver differential output pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub> | see Figure 8-3                           |                                   |     |     | 25  | ns   |
| t <sub>PHZ</sub> , t <sub>PLZ</sub>       | Driver disable time   |  |                                   |     |     | 3   | μs   |
|   |   | Receiver enabled                         | See Figure 8-4 and Figure 8-5     |     |     | 300 | ns   |
| t <sub>PZH</sub> , t <sub>PZL</sub>       | Driver enable time  | Receiver disabled                        | and riguic 0-3                    |     |     | 10  | μs   |
|   |   | Receiver enabled                         | V <sub>CM</sub> > V <sub>CC</sub> |     | 500 |     | ns   |
| DRIVER (HVD                               | 01787 AND HVD1793)  |  |                                   |     |     |     |      |
| t <sub>r</sub> , t <sub>f</sub>           | Driver differential output rise/fall time                                   |  |                                   | 3   |     | 30  | ns   |
| t <sub>PHL</sub> , t <sub>PLH</sub>       | Driver propagation delay  | $R_L = 54 \Omega, C_L = 50$              | pF,                               |     |     | 50  | ns   |
| t <sub>SK(P)</sub>                        | Driver differential output pulse skew,  t <sub>PHL</sub> - t <sub>PLH</sub> | see Figure 8-3                           |                                   |     |     | 10  | ns   |
| t <sub>PHZ</sub> , t <sub>PLZ</sub>       | Driver disable time   |  |                                   |     |     | 3   | μs   |
|   |   | Receiver enabled                         | See Figure 8-4 and Figure 8-5     |     |     | 300 | ns   |
| t <sub>PZH</sub> , t <sub>PZL</sub>       | Driver enable time  | Receiver disabled                        | and rigure of o                   |     |     | 9   | μs   |
|   |   | Receiver enabled                         | V <sub>CM</sub> > V <sub>CC</sub> |     | 500 |     | ns   |
| RECEIVER (A                               | LL DEVICES UNLESS OTHERWISE NOT   | ED)                                      |                                   | •   |     | '   |      |
| t <sub>r</sub> , t <sub>f</sub>           | Receiver output rise/fall time  |  |                                   |     | 4   | 15  | ns   |
| + +                                       | Pagaivar pranagation delevitime   |  | 85, 86, 91, 92                    |     | 100 | 200 | no   |
| t <sub>PHL</sub> , t <sub>PLH</sub>       | Receiver propagation delay time   | $C_L = 15 \text{ pF},$<br>see Figure 8-6 | 87, 93                            |     |     | 70  | ns   |
| 4   | Receiver output pulse skew,   | 500 Figure 0-0                           | 85, 86, 91, 92                    |     | 6   | 20  |      |
| t <sub>SK(P)</sub>                        | t <sub>PHL</sub> - t <sub>PLH</sub>   |  | 87, 93                            |     |     | 5   | ns   |
| t <sub>PLZ</sub> , t <sub>PHZ</sub>       | Receiver disable time   | Driver enabled, see                      | Figure 8-7                        |     | 15  | 100 | ns   |
| t <sub>PZL(1)</sub> , t <sub>PZH(1)</sub> | Pagaivar anabla tima  | Driver enabled, see                      | Driver enabled, see Figure 8-7    |     |     | 300 | ns   |
| $t_{PZL(2)}, t_{PZH(2)}$                  | Receiver enable time  | Driver disabled, see                     | Driver disabled, see Figure 8-8   |     |     |     | μs   |



#### 7.8 Typical Characteristics





#### **8 Parameter Measurement Information**

Input generator rate is 100 kbps, 50% duty cycle, rise and fall times less than 6 nsec, output impedance 50  $\Omega$ .

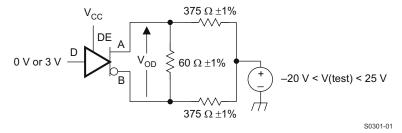


Figure 8-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

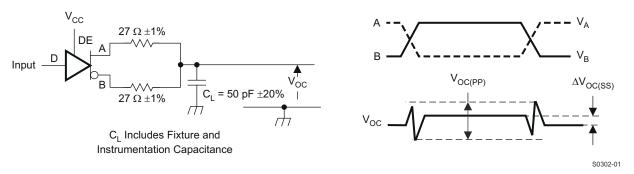


Figure 8-2. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

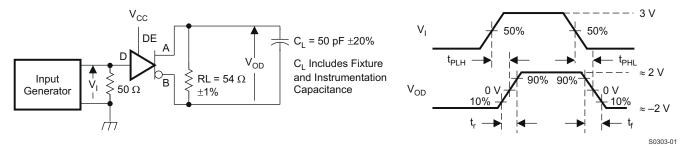
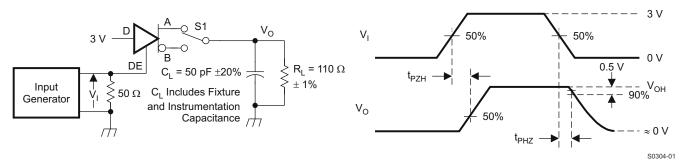


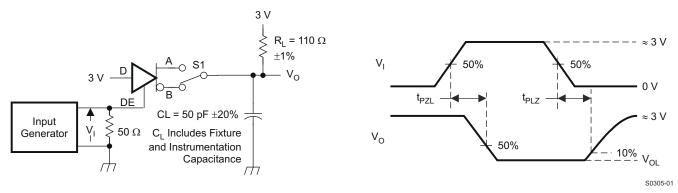
Figure 8-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays



D at 3 V to test non-inverting output, D at 0 V to test inverting output.

Figure 8-4. Measurement of Driver Enable and Disable Times With Active High Output and Pulldown Load





D at 0 V to test non-inverting output, D at 3 V to test inverting output.

Figure 8-5. Measurement of Driver Enable and Disable Times With Active-Low Output and Pullup Load

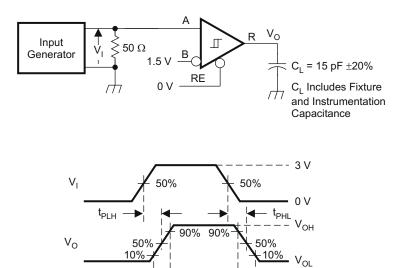


Figure 8-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays



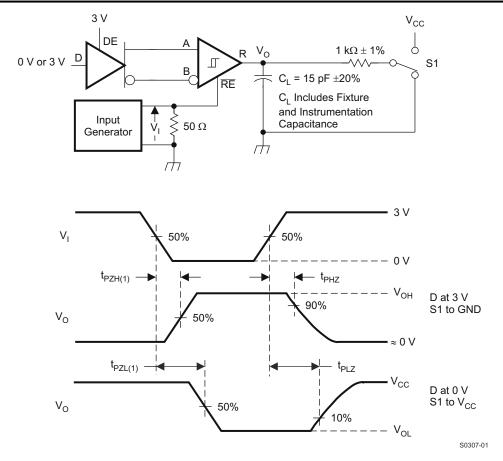


Figure 8-7. Measurement of Receiver Enable/Disable Times With Driver Enabled



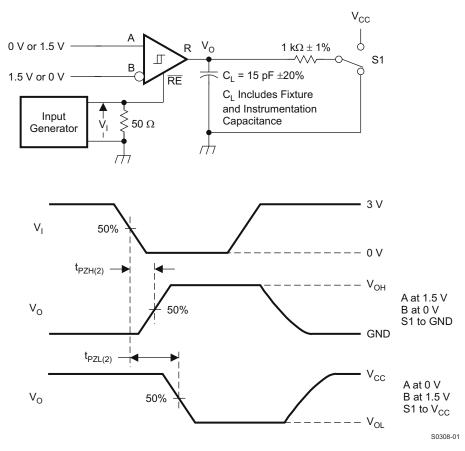


Figure 8-8. Measurement of Receiver Enable Times With Driver Disabled



## 9 Detailed Description

#### 9.1 Overview

The SN65HVD17xx family of RS-485 transceivers are designed to operate up to 115 kbps (HVD1785 and HVD1791), 1 Mbps (HVD1786 and HVD1792), or 10 Mbps (HVD1787 or HVD1793) and to withstand DC overvoltage faults on the bus interface pins. This helps to protect the devices against damages resulting from direct shorts to power supplies, cable mis-wirings, connector failures, or other common faults.

The SN65HVD178x devices are half-duplex, and thus have the transmitter and receiver bus interfaces connected together internally. The SN65HVD179x family leaves these two interfaces separate, allowing for full-duplex communication. The low receiver loading allows for up to 256 nodes to share a common RS-485 bus. The devices feature a wide common-mode range as well as fail-safe receivers, which ensure a stable logic-level output during bus open, short, or idle conditions.

#### 9.2 Functional Block Diagram

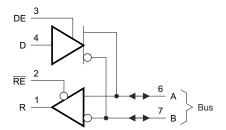


Figure 9-1. Half-Duplex Transceiver

Logic Diagram (Positive Logic)

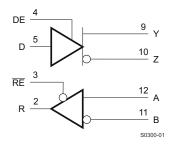


Figure 9-2. Full Duplex Transceiver

#### 9.3 Feature Description

#### 9.3.1 Hot-Plugging

These devices are designed to operate in hot swap or hot pluggable applications. Key features for hot-pluggable applications are power-up, power-down glitch free operation, default disabled input/output pins, and receiver failsafe. As shown in Figure 7-1, an internal Power-On Reset circuit keeps the driver outputs in a high-impedance state until the supply voltage has reached a level at which the device will reliably operate. This ensures that no spurious transitions (glitches) will occur on the bus pin outputs as the power supply turns on or turns off.

As shown in Section 9.4, the ENABLE inputs have the feature of default disable on both the driver enable and receiver enable. This ensures that the device will neither drive the bus nor report data on the R pin until the associated controller actively drives the enable pins.



#### 9.3.2 Receiver Failsafe

The differential receiver is failsafe to invalid bus states caused by:

- · open bus conditions such as a disconnected connector,
- · shorted bus conditions such as cable damage shorting the twisted-pair together,
- · or idle bus conditions that occur when no driver on the bus is actively driving.

In any of these cases, the differential receiver outputs a failsafe logic High state, so that the output of the receiver is not indeterminate.

In the HVD17xx family of RS-485 devices, receiver failsafe is accomplished by offsetting the receiver thresholds so that the "input indeterminate" range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a High when the differential input  $V_{ID}$  is more positive than 200 mV, and must output a Low when the  $V_{ID}$  is more negative than -200 mV. The HVD17xx receiver parameters which determine the failsafe performance are  $V_{IT+}$  and  $V_{IT-}$  and  $V_{HYS-}$ . In the *Electrical Characteristics* table,  $V_{IT-}$  has a typical value of -150 mV and a minimum (most negative) value of -200 mV, so differential signals more negative than -200 mV will always cause a Low receiver output. Similarly, differential signals more positive than 200 mV will always cause a High receiver output, because the typical value of  $V_{IT+}$  is -100mV, and  $V_{IT+}$  is never more positive than -10 mV under any conditions of temperature, supply voltage, or common-mode offset.

When the differential input signal is close to zero, it will still be above the  $V_{IT+}$  threshold, and the receiver output will be High. Only when the differential input is more negative than  $V_{IT-}$  will the receiver output transition to a Low state. So, the noise immunity of the receiver inputs during a bus fault condition includes the receiver hysteresis value  $V_{HYS}$  (the separation between  $V_{IT+}$  and  $V_{IT-}$ ) as well as the value of  $V_{IT+}$ .

For the HVD17xx devices, the typical noise immunity is typically about 150 mV, which is the negative noise level needed to exceed the  $V_{IT-}$  threshold ( $V_{IT-}$  TYP = -150 mV). In the worst case, the failsafe noise immunity is never less than 40 mV, which is set by the maximum positive threshold ( $V_{IT+}$  MAX = -10 mV) plus the minimum hysteresis voltage ( $V_{HYS}$  MIN = 30 mV).

#### 9.3.3 70-V Fault-Protection

The SN65HVD17xx family of RS-485 devices is designed to survive bus pin faults up to ±70V. The devices designed for fast signaling rate (10 Mbps) will not survive a bus pin fault with a direct short to voltages above 30V when:

- 1. the device is powered on AND
- 2a. the driver is enabled (DE=HIGH) AND D=HIGH AND the bus fault is applied to the A pin OR
- 2b. the driver is enabled (DE=HIGH) AND D=LOW AND the bus fault is applied to the B pin

Under other conditions, the device will survive shorts to bus pin faults up to 70V. Table 9-1 summarizes the conditions under which the device may be damaged, and the conditions under which the device will not be damaged.



|       |     |        | _          |         |
|-------|-----|--------|------------|---------|
| Iania | u_1 | Device | $C \cap D$ | anoitir |
|       |     |        |            |         |

| POWER | DE | D | A                           | В                           | RESULTS          |  |
|-------|----|---|-----------------------------|-----------------------------|------------------|--|
| OFF   | Х  | Х | -70V < V <sub>A</sub> < 70V | $-70V < V_B < 70V$          | Device survives  |  |
| ON    | LO | Х | -70V < V <sub>A</sub> < 70V | $-70V < V_B < 70V$          | Device survives  |  |
| ON    | HI | L | -70V < V <sub>A</sub> < 70V | -70V < V <sub>B</sub> < 30V | Device survives  |  |
| ON    | HI | L | -70V < V <sub>A</sub> < 70V | 30V < V <sub>B</sub>        | Damage may occur |  |
| ON    | HI | Н | -70V < V <sub>A</sub> < 30V | -70V < V <sub>B</sub> < 30V | Device survives  |  |
| ON    | HI | Н | 30V < V <sub>A</sub>        | -70V < V <sub>B</sub> < 30V | Damage may occur |  |

### 9.3.4 Additional Options

The SN65HVD17xx family also has options for J1708 applications, for always-enabled full-duplex versions (industry-standard SN65LBC179 footprint) and for inverting-polarity versions, which allow users to correct a reversal of the bus wires without re-wiring. Contact your local Texas Instruments representative for information on these options.

Table 9-2. SN65HVD17xx Options for J1708 Applications

| PART NUMBER                               |      | SN65HVD17xx |      |  |  |  |  |
|---|------|-------------|------|--|--|--|--|
| FOOTPRINT/FUNCTION                        | SLOW | MEDIUM      | FAST |  |  |  |  |
| Half-duplex (176 pinout)                  | 85   | 86          | 87   |  |  |  |  |
| Full-duplex no enables (179 pinout)       | 88   | 89          | 90   |  |  |  |  |
| Full-duplex with enables (180 pinout)     | 91   | 92          | 93   |  |  |  |  |
| Half-duplex with cable invert             | 94   | 95          | 96   |  |  |  |  |
| Full-duplex with cable invert and enables | 97   | 98          | 99   |  |  |  |  |
| J1708                                     | 08   | 09          | 10   |  |  |  |  |

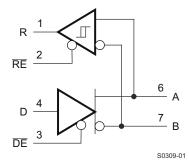


Figure 9-3. SN65HVD1708E Transceiver for J1708 Applications

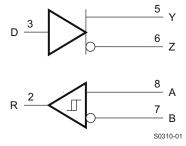
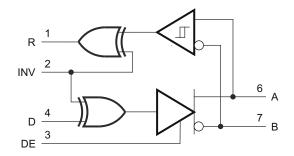


Figure 9-4. SN65HVD17xx Always-Enabled Driver Receiver





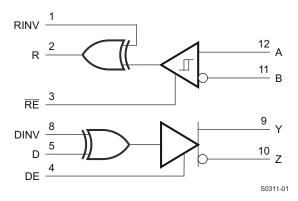


Figure 9-5. SN65HVD17xx Options With Inverting Feature to Correct for Miswired Cables

## 9.4 Device Functional Modes

**Table 9-3. Driver Function Table** 

| INPUT | ENABLE | OUTP | UTS |                                    |
|-------|--------|------|-----|------------------------------------|
| D     | DE     | A B  |     |                                    |
| Н     | Н      | Н    | L   | Actively drive bus high            |
| L     | Н      | L H  |     | Actively drive bus low             |
| Х     | L      | Z    | Z   | Driver disabled                    |
| Х     | OPEN   | Z    | Z   | Driver disabled by default         |
| OPEN  | Н      | Н    | L   | Actively drive bus high by default |

**Table 9-4. Receiver Function Table** 

| DIFFERENTIAL INPUT                | ENABLE | OUTPUT |                              |
|-----------------------------------|--------|--------|------------------------------|
| $V_{ID} = V_A - V_B$              | RE     | R      |                              |
| $V_{IT+} < V_{ID}$                | L      | Н      | Receive valid bus high       |
| $V_{IT-} < V_{ID} < V_{IT+}$      | L      | ?      | Indeterminate bus state      |
| V <sub>ID</sub> < V <sub>IT</sub> | L      | L      | Receive valid bus low        |
| Х                                 | Н      | Z      | Receiver disabled            |
| Х                                 | OPEN   | Z      | Receiver disabled by default |
| Open-circuit bus                  | L      | Н      | Fail-safe high output        |
| Short-circuit bus                 | L      | Н      | Fail-safe high output        |
| Idle (terminated) bus             | L      | Н      | Fail-safe high output        |



## 10 Application and Implementation

#### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 10.1 Application Information

The SN65HVD17xx family consists of both half-duplex and full-duplex transceivers that can be used for asynchronous data communication. Half-duplex implementations require one signaling pair (two wires), while full-duplex implementations require two signaling pairs (four wires). The driver and receiver enable pins of the SN65HVD17xx family allow for control over the direction of data flow. Since it is common for multiple transceivers to share a common communications bus, care should be taken at the system level to ensure that only one driver is enabled at a time. This avoids bus contention, a fault condition in which multiple drivers attempt to send data at the same time.

## 10.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor,  $R_T$ , whose value matches the characteristic impedance,  $Z_0$ , of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.

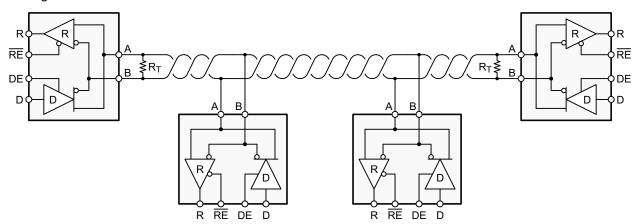


Figure 10-1. Typical RS-485 Network With Half-duplex Transceivers

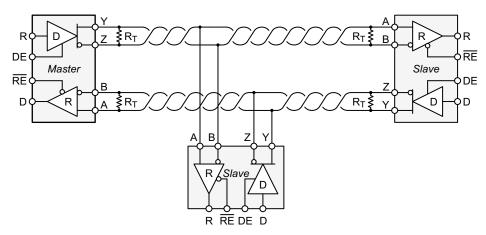


Figure 10-2. Typical RS-485 Network With Full-duplex Transceivers

#### 10.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

#### 10.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and cable length, which means the higher the data rate, the short the cable length; and conversely, the lower the data rate, the longer the cable length. While most RS-485 systems use data rates between 10 kbps and 100 kbps, some applications require data rates up to 250 kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.

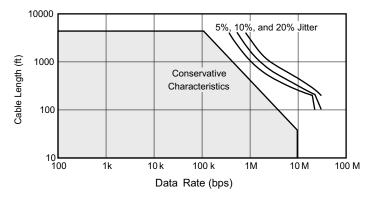


Figure 10-3. Cable Length vs Data Rate Characteristic

Even higher data rates are achievable (for example, 10 Mbps for the SN65HVD1787 and SN65HVD1793) in cases where the interconnect is short enough (or has suitably low attenuation at signal frequencies) to not degrade the data.

#### 10.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in Equation 1.

$$L_{\text{stub}} \le 0.1 \times t_{\text{r}} \times v \times c \tag{1}$$

#### where

- t<sub>r</sub> is the 10/90 rise time of the driver
- c is the speed of light (3 × 10<sup>8</sup> m/s)
- v is the signal velocity of the cable or trace as a factor of c

#### 10.2.1.3 Receiver Failsafe

The differential receiver of the SN75HVD17xx family is failsafe to invalid bus states caused by:

- Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

n any of these cases, the differential receiver will output a failsafe logic high state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the "input indeterminate" range does not include zero volts differential. In order to comply with the RS-422 and RS-485 standards, the receiver output must output a high when the differential input  $V_{\rm ID}$  is more positive than +200 mV, and must output a low



when VID is more negative than -200 mV. The receiver parameters which determine the failsafe performance are  $V_{IT(+)}$  and  $V_{IT(-)}$ . As shown in the Electrical Characteristics table, differential signals more negative than -200 mV will always cause a low receiver output, and differential signals more positive than +200 mV will always cause a high receiver output.

When the differential input signal is close to zero, it is still above the maximum  $V_{IT(+)}$  threshold of -10 mV, and the receiver output will be high.

#### 10.2.2 Detailed Design Procedure

Although the SN65HVD17xx family is internally protected against human-body-model ESD strikes up to 16 kV, additional protection against higher-energy transients can be provided at the application level by implementing external protection devices.

#### 10.2.3 Application Curve

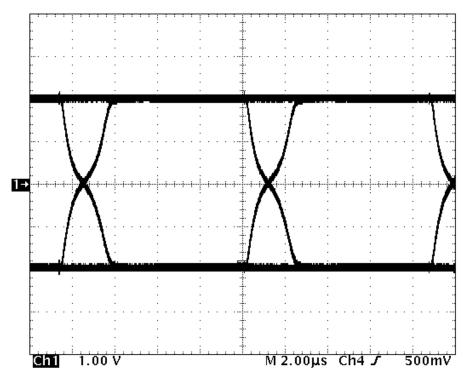


Figure 10-4. SN65HVD1785 Differential Output at 115 kbps

## 11 Power Supply Recommendations

To ensure reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100-nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.



## 12 Layout

## 12.1 Layout Guidelines

To ensure reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100-nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.

- 1. Place the protection circuitry close to the bus connector to prevent noise transients from entering the board.
- 2. Use V<sub>CC</sub> and ground planes to provide low-inductance power distribution. Note that high-frequency currents tend to follow the path of least inductance and not the path of least resistance.
- 3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
- Apply 100-nF-to-220-nF bypass capacitors as close as possible to the V<sub>CC</sub> pins of transceiver, UART, or controller ICs on the board.
- 5. Use at least two vias for V<sub>CC</sub> and ground connections of bypass capacitors and protection devices to minimize effective via-inductance.
- 6. Use  $1-k\Omega$ -to- $10-k\Omega$  pullup and pulldown resistors for enable lines to limit noise currents in these lines during transient events.
- 7. Insert series pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus terminals. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.
- 8. While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs) which reduce the transients to a few hundred volts of clamping voltage, and transient blocking units (TBUs) that limit transient current to less than 1 mA.

#### 12.2 Layout Example

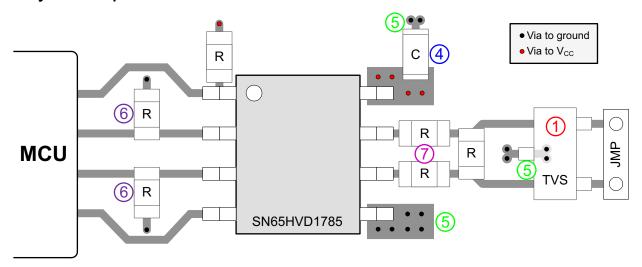


Figure 12-1. Layout Example (Half-Duplex Transceiver)



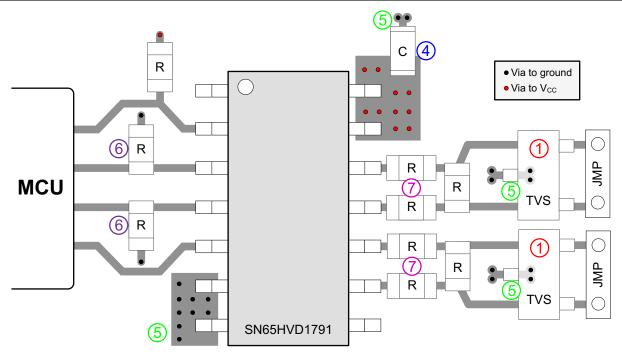


Figure 12-2. Layout Example (Full-Duplex Transceiver)



## 13 Device and Documentation Support

## 13.1 Documentation Support

For related documentation see the following:

SN65HVD1781, Fault-Protected RS-485 Transceivers With 3.3-V to 5-V Operation, (SLLS877)

#### 13.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 13.3 Support Resources

TI E2E<sup>™</sup> support forums are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

#### 13.4 Trademarks

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#### 13.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

#### 13.6 Glossary

TI Glossary

This glossary lists and explains terms, acronyms, and definitions.

## 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

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## **PACKAGING INFORMATION**

| Orderable Device | Status (1) | Package Type | Package<br>Drawing | Pins | Package<br>Qty | Eco Plan     | Lead finish/<br>Ball material | MSL Peak Temp      | Op Temp (°C) | Device Marking<br>(4/5) | Samples |
|------------------|------------|--------------|--------------------|------|----------------|--------------|-------------------------------|--------------------|--------------|-------------------------|---------|
| SN65HVD1785D     | ACTIVE     | SOIC         | D                  | 8    | 75             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1785                  | Samples |
| SN65HVD1785DG4   | ACTIVE     | SOIC         | D                  | 8    | 75             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1785                  | Samples |
| SN65HVD1785DR    | ACTIVE     | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1785                  | Samples |
| SN65HVD1785DRG4  | ACTIVE     | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1785                  | Samples |
| SN65HVD1785P     | ACTIVE     | PDIP         | Р                  | 8    | 50             | RoHS & Green | NIPDAU                        | N / A for Pkg Type | -40 to 105   | 65HVD1785               | Samples |
| SN65HVD1786D     | ACTIVE     | SOIC         | D                  | 8    | 75             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1786                  | Samples |
| SN65HVD1786DR    | ACTIVE     | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1786                  | Samples |
| SN65HVD1786DRG4  | ACTIVE     | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1786                  | Samples |
| SN65HVD1786P     | ACTIVE     | PDIP         | Р                  | 8    | 50             | RoHS & Green | NIPDAU                        | N / A for Pkg Type | -40 to 105   | 65HVD1786               | Samples |
| SN65HVD1787D     | ACTIVE     | SOIC         | D                  | 8    | 75             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1787                  | Samples |
| SN65HVD1787DR    | ACTIVE     | SOIC         | D                  | 8    | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1787                  | Samples |
| SN65HVD1791D     | ACTIVE     | SOIC         | D                  | 14   | 50             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1791                  | Samples |
| SN65HVD1791DG4   | ACTIVE     | SOIC         | D                  | 14   | 50             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1791                  | Samples |
| SN65HVD1791DR    | ACTIVE     | SOIC         | D                  | 14   | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1791                  | Samples |
| SN65HVD1792D     | ACTIVE     | SOIC         | D                  | 14   | 50             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1792                  | Samples |
| SN65HVD1792DR    | ACTIVE     | SOIC         | D                  | 14   | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1792                  | Samples |
| SN65HVD1793D     | ACTIVE     | SOIC         | D                  | 14   | 50             | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1793                  | Samples |
| SN65HVD1793DR    | ACTIVE     | SOIC         | D                  | 14   | 2500           | RoHS & Green | NIPDAU                        | Level-1-260C-UNLIM | -40 to 105   | VP1793                  | Samples |

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

## PACKAGE OPTION ADDENDUM



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NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

#### OTHER QUALIFIED VERSIONS OF SN65HVD1792:

■ Enhanced Product : SN65HVD1792-EP

NOTE: Qualified Version Definitions:

• Enhanced Product - Supports Defense, Aerospace and Medical Applications

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## TAPE AND REEL INFORMATION





| A0 | Dimension designed to accommodate the component width     |
|----|---|
| В0 | Dimension designed to accommodate the component length    |
| K0 | Dimension designed to accommodate the component thickness |
| W  | Overall width of the carrier tape                         |
| P1 | Pitch between successive cavity centers                   |

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

| Device        | Package<br>Type | Package<br>Drawing |    | SPQ  | Reel<br>Diameter<br>(mm) | Reel<br>Width<br>W1 (mm) | A0<br>(mm) | B0<br>(mm) | K0<br>(mm) | P1<br>(mm) | W<br>(mm) | Pin1<br>Quadrant |
|---------------|-----------------|--------------------|----|------|--------------------------|--------------------------|------------|------------|------------|------------|-----------|------------------|
| SN65HVD1785DR | SOIC            | D                  | 8  | 2500 | 330.0                    | 12.4                     | 6.4        | 5.2        | 2.1        | 8.0        | 12.0      | Q1               |
| SN65HVD1786DR | SOIC            | D                  | 8  | 2500 | 330.0                    | 12.4                     | 6.4        | 5.2        | 2.1        | 8.0        | 12.0      | Q1               |
| SN65HVD1787DR | SOIC            | D                  | 8  | 2500 | 330.0                    | 12.4                     | 6.4        | 5.2        | 2.1        | 8.0        | 12.0      | Q1               |
| SN65HVD1791DR | SOIC            | D                  | 14 | 2500 | 330.0                    | 16.4                     | 6.5        | 9.0        | 2.1        | 8.0        | 16.0      | Q1               |
| SN65HVD1792DR | SOIC            | D                  | 14 | 2500 | 330.0                    | 16.4                     | 6.5        | 9.0        | 2.1        | 8.0        | 16.0      | Q1               |
| SN65HVD1793DR | SOIC            | D                  | 14 | 2500 | 330.0                    | 16.4                     | 6.5        | 9.0        | 2.1        | 8.0        | 16.0      | Q1               |



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#### \*All dimensions are nominal

| Device        | Package Type | Package Drawing | Pins | SPQ  | Length (mm) | Width (mm) | Height (mm) |
|---------------|--------------|-----------------|------|------|-------------|------------|-------------|
| SN65HVD1785DR | SOIC         | D               | 8    | 2500 | 356.0       | 356.0      | 35.0        |
| SN65HVD1786DR | SOIC         | D               | 8    | 2500 | 356.0       | 356.0      | 35.0        |
| SN65HVD1787DR | SOIC         | D               | 8    | 2500 | 356.0       | 356.0      | 35.0        |
| SN65HVD1791DR | SOIC         | D               | 14   | 2500 | 356.0       | 356.0      | 35.0        |
| SN65HVD1792DR | SOIC         | D               | 14   | 2500 | 356.0       | 356.0      | 35.0        |
| SN65HVD1793DR | SOIC         | D               | 14   | 2500 | 356.0       | 356.0      | 35.0        |

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## **TUBE**



\*All dimensions are nominal

| Device         | Package Name | Package Type | Pins | SPQ | L (mm) | W (mm) | T (µm) | B (mm) |
|----------------|--------------|--------------|------|-----|--------|--------|--------|--------|
| SN65HVD1785D   | D            | SOIC         | 8    | 75  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1785DG4 | D            | SOIC         | 8    | 75  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1785P   | Р            | PDIP         | 8    | 50  | 506    | 13.97  | 11230  | 4.32   |
| SN65HVD1786D   | D            | SOIC         | 8    | 75  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1786P   | Р            | PDIP         | 8    | 50  | 506    | 13.97  | 11230  | 4.32   |
| SN65HVD1787D   | D            | SOIC         | 8    | 75  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1791D   | D            | SOIC         | 14   | 50  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1791DG4 | D            | SOIC         | 14   | 50  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1792D   | D            | SOIC         | 14   | 50  | 506.6  | 8      | 3940   | 4.32   |
| SN65HVD1793D   | D            | SOIC         | 14   | 50  | 506.6  | 8      | 3940   | 4.32   |

## D (R-PDSO-G14)

## PLASTIC SMALL OUTLINE



- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.



# D (R-PDSO-G14)

## PLASTIC SMALL OUTLINE



- A. All linear dimensions are in millimeters.
- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.





SMALL OUTLINE INTEGRATED CIRCUIT



- 1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.
- 3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed .006 [0.15] per side.
- 4. This dimension does not include interlead flash.
- 5. Reference JEDEC registration MS-012, variation AA.



SMALL OUTLINE INTEGRATED CIRCUIT



NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

SMALL OUTLINE INTEGRATED CIRCUIT



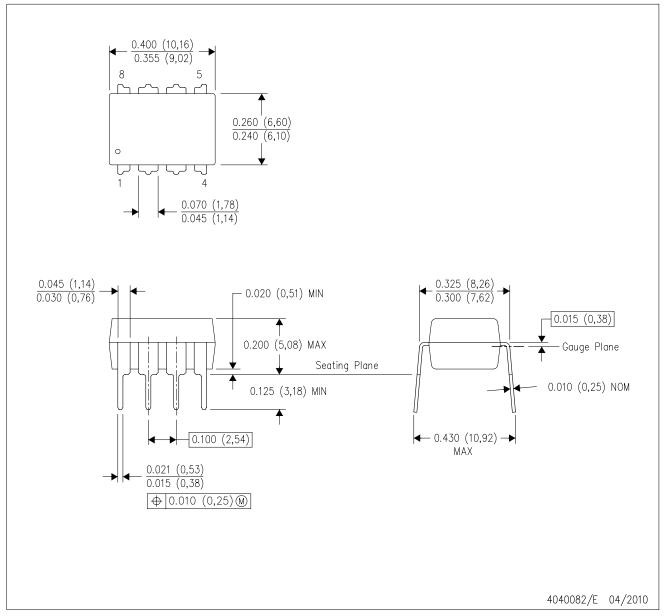
NOTES: (continued)

- 8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 9. Board assembly site may have different recommendations for stencil design.



# P (R-PDIP-T8)

## PLASTIC DUAL-IN-LINE PACKAGE



- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001 variation BA.



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