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[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420), [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)

SLVS676D –JUNE 2006–REVISED JULY 2015

TPS6242x 2.25-MHz 600-mA and 1000-mA Dual Step-Down Converter in Small 3-mm × 3-mm VSON Package

Texas

High Efficiency up to 95%

INSTRUMENTS

-
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-
-
- Optional EasyScale™ One-Pin Serial Interface for
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-
-

-
- PDAs, Pocket PCs
-
-
- Digital Radios
- • Digital Cameras **Device Information[\(1\)](#page-0-0)**

$V_{\text{OUT2}} = 1.8V$ SW1 FB 1 SW2 ADJ2 DEF_1 C_{OUT2} = 22 µF C_{in} 10 μF V IN 2.5V – 6V VIN EN₁ EN_2 MODE/ **DATA** TPS62420 **GND** $\sum_{R_2} R_2$ $\sum_{m_2} C_m$ \sum_{n_2} Up to 1000mA 360kΩ R₂₂ 180kΩ 2.2 μH C_{ff2} 33pF E₁₁ Pup to 600mA .
270kΩ R12 180kΩ L1 $V_{\text{out1}} = 1.5V$ 2.2 μH $C_{\text{OUT1}} = 22 \text{ }\mu\text{F}$

1 Features 3 Description

The TPS6242x device is a synchronous dual stepdown DC–DC converter. It provides two independent V_{IN} Range from 2.5 V to 6 V
output voltage rails powered by 1-cell Li-Ion or 3-cell
2.25-MHz Fixed Frequency Operation
NiMH/NiCD batteries. The device is also suitable to NiMH/NiCD batteries. The device is also suitable to • Output Current 600 mA and 1000 mA operate from a standard 3.3-V or 5-V voltage rail.

Adjustable Output Voltage from 0.6 V to V_{IN} With an input voltage range of 2.5 V to 6 V, the • Pin Selectable Output Voltage Supports Simple TPS6242x is ideal for battery-powered portable Dynamic Voltage Scaling and The Contract applications like smart phones, PDAs, and other portable equipment.

Dynamic Output Voltage Adjustment Mith the EasyScale™ serial interface the output
Power-Save Mode at Light Load Currents voltages can be modified during operation. It Power-Save Mode at Light Load Currents

therefore supports dynamic voltage scaling for low

nower DSP and processors power DSP and processors.

Output Voltage Accuracy in PWM Mode ±1% The TPS6242x operates at 2.25-MHz fixed switching
Typical 32-uA Quiescent Current for both frequency and enter the nower-save mode operation • Typical 32-μA Quiescent Current for both frequency and enter the power-save mode operation at light load currents to maintain high efficiency over • 100% Duty Cycle for Lowest Dropout the entire load current range. For low-noise Available in a 10-Pin VSON (3 mm x 3 mm) applications the devices can be forced into fixed-
frequency PWM mode by pulling the MODE/DATA
pin High. In the shutdown mode, the current **2 Applications 2** *Applications* **2** *Applications* **2** *CONSIDERED 2 <i>CONSIDERED 2 CONSIDERED 2 CONSIDERED 2 CONSIDERED 2 ADPLICATIONS CONSIDERED 2 ADPLICATIONS CONSIDERED 2* Formulation Cell Phones, Smart-phones and Capacitors in the use of small inductors and capacitors to achieve a

Small solution size.

OMAP™ and Low Power DSP Supply The TPS6242x operates over a free-air temperature Portable Media Players

Fortable Media Players **For a structure in a 10-pin eadless package (3 mm × 3 mm VSON)**

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Typical Application Schematic Efficiency vs Output Current

An IMPORTANT NOTICE at the end of this data sheet addresses availability, warranty, changes, use in safety-critical applications, **INTERNATION PRODUCTION PRODUCTION DATA**

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4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision C (June 2010) to Revision D Page

• Added *Pin Configuration and Functions* section, *ESD Ratings* table, *Feature Description* section, *Device Functional Modes*, *Application and Implementation* section, *Power Supply Recommendations* section, *Layout* section, *Device and Documentation Support* section, and *Mechanical, Packaging, and Orderable Information* section [1](#page-0-3)

5 Device Comparison Table

(1) Contact TI for other fixed output voltage options.

(2) The DRC (VSON 10 PIN) package is available in tape on reel. Add R suffix to order quantities of 3000 parts per reel, T suffix for 250 parts per reel.

(3) For the most current ordering information see the *[Mechanical,](#page-29-7) Packaging, and Orderable Information* section or see the TI website [www.ti.com.](http://www.ti.com)

6 Pin Configuration and Functions

Pin Functions

EXAS **STRUMENTS**

Pin Functions (continued)

7 Specifications

7.1 Absolute Maximum Ratings

Over operating free-air temperature range (unless otherwise noted)⁽¹⁾

(1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions* is not implied. Exposure to absolute–maximum–rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

7.2 ESD Ratings

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

7.3 Recommended Operating Conditions

Over operating free-air temperature range (unless otherwise noted)

7.4 Thermal Information

(1) For more information about traditional and new thermal metrics, see the *Semiconductor and IC Package Thermal Metrics* application report, [SPRA953.](http://www.ti.com/lit/pdf/spra953)

7.5 Electrical Characteristics

 $\rm{V_{IN}}$ = 3.6 V, $\rm{V_{OUT}}$ = 1.8 V, EN = V $_{IN}$, MODE = GND, L = 2.2 μH, $\rm{C_{OUT}}$ = 20 μF, T_A = –40°C to 85°C typical values are at T_A = 25°C (unless otherwise noted)

(1) Device is switching with no load on the output, $L = 3.3 \mu H$, value includes losses of the coil (2) These values are valid after the device has been already enabled one time (EN1 or EN2 =

These values are valid after the device has been already enabled one time (EN1 or EN2 = High) and supply voltage V_{IN} has not powered down.

(3) After the first enable, these values are valid when the device is disabled (EN1 and EN2 = Low) and supply voltage V_{IN} is powered up. The values remain valid until the device has been enabled first time (EN1 or EN2 = high).

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Electrical Characteristics (continued)

 V_{IN} = 3.6 V, V_{OUT} = 1.8 V, EN = V_{IN}, MODE = GND, L = 2.2 µH, C_{OUT} = 20 µF, T_A = -40°C to 85°C typical values are at T_A = 25°C (unless otherwise noted)

(4) At pins SW1 and SW2 an internal resistor of 1 MΩ is connected to GND

(5) Output voltage specification does not include tolerance of external voltage programming resistors

(6) Configuration L typ 2.2 μ H, C_{OUT} typical 20 μ F, see parameter measurement information, the output voltage ripple depends on the effective capacitance of the output capacitor, larger output capacitors lead to tighter output voltage tolerance

(7) In power-save mode, PWM operation is typically entered at $I_{PSM} = V_{IN}/32 \Omega$.
(8) For $V_{OUT} > 2.2$ V, V_{IN} min = $V_{OUT} + 0.3$ V

For $V_{\text{OUT}} > 2.2$ V, V_{IN} min = V_{OUT} +0.3 V

(9) This time is valid if one converter turns from shutdown mode (EN2 = 0) to active mode (EN2 = 1) and the other converter is already enabled (that is, EN1 = 1). In case both converters are turned from shutdown mode (EN1 and EN2 = Low) to active mode (EN1 and/or EN2 = 1) a value of typical 80 μs for ramp up of internal circuits needs to be added. After t_{Start} the converter starts switching and ramps V_{OUT}.

7.6 Dissipation Ratings

7.7 Typical Characteristics

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8 Detailed Description

8.1 Overview

The TPS6242x includes two synchronous step-down converters. The converters operate with typically 2.25-MHz fixed frequency pulse width modulation (PWM) at moderate to heavy load currents. If power-save mode is enabled, the converters automatically enter power-save mode at light load currents and operate in pulse frequency modulation (PFM). During PWM operation the converters use a unique fast response voltage mode controller scheme with input voltage feed-forward to achieve good line and load regulation allowing the use of small ceramic input and output capacitors. At the beginning of each clock cycle initiated by the clock signal, the P-channel MOSFET switch is turned on and the inductor current ramps up until the comparator trips and the control logic turns off the switch.

Each converter integrates two current limits, one in the P-channel MOSFET and another one in the N-channel MOSFET. When the current in the P-channel MOSFET reaches its current limit, the P-channel MOSFET is turned off and the N-channel MOSFET is turned on. If the current in the N-channel MOSFET is above the N-MOS current limit threshold, the N-channel MOSFET remains on until the current drops below its current limit. The two DC/DC converters operate synchronized to each other. A 180° phase shift between converter 1 and converter 2 decreases the input RMS current.

8.1.1 Converter 1

In the adjustable output voltage version TPS62420 the converter 1 output voltage can be set through an external resistor network on pin DEF_1, which operates as an analog input. In this case, the output voltage can be set in the range of 0.6 V to V_{IN}. The FB1 pin must be directly connected to the converter 1 output voltage V_{OUT1}. It feeds back the output voltage directly to the regulation loop.

The output voltage of converter 1 can also be changed by the EasyScale™ serial interface. This makes the device very flexible for output voltage adjustment. In this case, the device uses an internal resistor network.

In the fixed default output voltage version like TPS62421, the DEF_1 pin is configured as a digital input. The converter 1 defaults to 1.2 V or 1.8 V depending on the level of DEF_1 pin. If DEF_1 is low the default is 1.2 V; if high, the default is 1.8 V. With the EasyScale™ interface, the output voltage for each DEF_1 pin condition (high or low) can be changed.

8.1.2 Converter 2

In the adjustable output voltage version TPS62420, the converter 2 output voltage is set by an external resistor divider connected to ADJ2 pin and uses an external feed-forward capacitor of 33 pF.

In fixed output voltage version TPS62421, the default output voltage is fixed to 1.8 V. In this case, the ADJ2 pin must be connected directly to the converter 2 output voltage V_{OUT2} . It is also possible to change the output voltage of converter 2 through the EasyScale™ interface. In this case, the ADJ2 pin must be directly connected to converter 2 output voltage V_{OUT2} and no external resistors may be connected.

8.2 Functional Block Diagram

- A. In fixed output voltage version, the pin DEF_1 is connected to an internal digital input and disconnected from the error amplifier
- B. To set the output voltage of converter 2 through EasyScale™ interface, ADJ2 pin must be directly connected to V_{OUT2}

8.3 Feature Description

8.3.1 Dynamic Voltage Positioning

This feature reduces the voltage undershoots and overshoots at load steps from light to heavy load and vice versa. It is activated in power-save mode operation. It provides more headroom for both the voltage drop at a load step, and the voltage increase at a load throw-off. This improves load transient behavior.

At light loads, in which the converter operate in PFM mode, the output voltage is regulated typically 1% higher than the nominal value. In case of a load transient from light load to heavy load, the output voltage drops until it reaches the skip comparator low threshold set to –2% below the nominal value and enters PWM mode. During a load throw off from heavy load to light load, the voltage overshoot is also minimized due to active regulation turning on the N-channel switch.

Figure 6. Dynamic Voltage Positioning

8.3.2 Undervoltage Lockout

The undervoltage lockout circuit prevents the device from malfunctioning at low input voltages and from excessive discharge of the battery and disables the converters. The under-voltage lockout threshold is typically 1.5 V, maximum is 2.35 V. In case the default register values are overwritten by the interface, the new values in the registers REG_DEF_1_Low and REG_DEF_2 remain valid as long the supply voltage does not fall under the undervoltage lockout threshold, independent of whether the converters are disabled.

8.3.3 Mode Selection

The MODE/DATA pin allows mode selection between forced PWM mode and power-save mode for both converters. Furthermore, this pin is a multi-purpose pin and provides (besides mode selection) a one-pin interface to receive serial data from a host to set the output voltage. This is described in the section EasyScale™ interface.

Connecting this pin to GND enables the automatic PWM and power-save mode operation. The converters operate in fixed-frequency PWM mode at moderate to heavy loads and in the PFM mode during light loads, maintaining high efficiency over a wide load current range.

Pulling the MODE/DATA pin high forces both converters to operate constantly in the PWM mode even at light load currents. The advantage is the converters operate with a fixed frequency that allows simple filtering of the switching frequency for noise sensitive applications. In this mode, the efficiency is lower compared to the powersave mode during light loads. For additional flexibility it is possible to switch from power-save mode to forced PWM mode during operation. This allows efficient power management by adjusting the operation of the converter to the specific system requirements.

In case the operation mode will be changed from forced PWM mode (MODE/DATA = High) to power-save mode Enable (MODE/DATA = 0) the power-save mode will be enabled after a delay time of typically t_{timeout} , which is a maximum of 520 μs.

The forced PWM mode operation is enabled immediately with pin MODE/DATA set to 1.

Feature Description (continued)

8.3.4 Enable

The device has for each converter a separate EN pin to start up each converter independently. If EN1 and EN2 are set to high, the corresponding converter starts up with soft-start.

Pulling EN1 and EN2 pin low forces the device into shutdown, with a shutdown quiescent current of typically 1.2 μA. In this mode, the P- and N-channel MOSFETs are turned-off and the entire internal control circuitry is switched off. For proper operation the EN1 and EN2 pins must be terminated and must not be left floating.

8.3.5 DEF_1 Pin Function

The DEF 1 pin is dedicated to converter 1 and makes the output voltage selection very flexible to support dynamic voltage management. Depending on the device version, this pin works either as:

1. Analog input for adjustable output voltage setting (TPS62420): Connecting an external resistor network to this pin adjusts the default output voltage to any value starting from 0.6 V to V_{IN} .

2. Digital input for fixed default output voltage selection (TPS62421): In case this pin is tied to low level, the output voltage is set according to the value in register REG_DEF_1_Low. The default voltage will be 1.2 V. If tied to high level, the output voltage is set according to the value in register REG_DEF_1_High. The default value in this case is 1.8 V. Depending on the level of pin DEF_1, it selects between the two registers REG_DEF_1_Low and REG_DEF_1_High for output voltage setting. Each register content (and therefore output voltage) can be changed individually through the EasyScale™ interface. This makes the device very flexible in terms of output voltage setting; see [Table](#page-17-0) 4.

8.3.6 180° Out-of-Phase Operation

In PWM mode the converters operate with a 180° turnon phase shift of the PMOS (high side) transistors. It prevents the high-side switches of both converters to be turned on simultaneously, and therefore smooths the input current. This feature reduces the surge current drawn from the supply.

8.3.7 Thermal Shutdown

As soon as the junction temperature, ${\sf T}_{\sf J}$, exceeds typically 150°C the device goes into thermal shutdown. In this mode, the P- and N-channel MOSFETs are turned off. The device continues its operation when the junction temperature falls below the thermal shutdown hysteresis again.

8.3.8 Short Circuit Protection

Both outputs are short circuit protected with maximum output current = I_{LIMF} (P-MOS and N-MOS). Once the PMOS switch reaches its current limit, it will be turned off and the NMOS turned on. The PMOS only turns on again, once the current in the NMOS decreases below the NMOS current limit.

8.4 Device Functional Modes

8.4.1 Soft-Start

The two converters have an internal soft-start circuit that limits the inrush current during start-up. During softstart, the output voltage ramp up is controlled as shown in [Figure](#page-11-0) 7.

NSTRUMENTS

Device Functional Modes (continued)

8.4.2 100% Duty Cycle Low Dropout Operation

The converters offer a low input to output voltage difference while still maintaining operation with the use of the 100% duty cycle mode. In this mode the P-channel switch is constantly turned on. This is particularly useful in battery-powered applications to achieve longest operation time by taking full advantage of the whole battery voltage range; that is, the minimum input voltage to maintain regulation depends on the load current and output voltage, and can be calculated as:

$$
Win_{min} = Vout_{max} + Iout_{max} \times (RDSon_{max} + R_L)
$$

where

- I_{out} = maximum output current plus inductor ripple current
- $RDSon_{max}$ = maximum P-channel switch RDSon
- R_1 = DC resistance of the inductor
- V out_{max} = nominal output voltage plus maximum output voltage tolerance (1) (1)

With decreasing load current, the device automatically switches into pulse-skipping operation in which the power stage operates intermittently based on load demand. By running cycles periodically the switching losses are minimized and the device runs with a minimum quiescent current maintaining high efficiency.

8.4.3 Power-Save Mode

The power-save mode is enabled with MODE/DATA pin set to 0 for both converters. If the load current of a converter decreases, this converter will enter power-save mode operation automatically. The transition to powersave mode of a converter is independent from the operating condition of the other converter. During power-save mode the converter operates with reduced switching frequency in PFM mode and with a minimum quiescent current to maintain high efficiency. The converter will position the output voltage in PFM mode to typically 1.01 \times V_{OUT} . This voltage positioning feature minimizes voltage drops caused by a sudden load step.

To optimize the converter efficiency at light load the average inductor current is monitored. The device changes from PWM mode to power-save mode, if in PWM mode the inductor current falls below a certain threshold. The typical output current threshold depends on V_{IN} and can be calculated according to [Equation](#page-11-1) 2 for each converter.

[Equation](#page-11-1) 2: Average output current threshold to enter PFM mode

$$
I_{\text{OUT_PFM_enter}} = \frac{VIN_{\text{DCDC}}}{32 \Omega}
$$

[Equation](#page-11-2) 3: Average output current threshold to leave PFM mode

$$
I_{\text{OUT_PFM_leave}} = \frac{VIN_{\text{DCDC}}}{24 \Omega}
$$

(2)

(3)

Device Functional Modes (continued)

To keep the output voltage ripple in power-save mode low, the output voltage is monitored with a single threshold comparator (skip comparator). As the output voltage falls below the skip comparator threshold (skip comp) of 1.01 \times V_{OUTnominal}, the corresponding converter starts switching for a minimum time period of typically 1 μs and provides current to the load and the output capacitor. Therefore the output voltage increases and the device maintains switching until the output voltage trips the skip comparator threshold (skip comp) again. At this moment all switching activity is stopped and the quiescent current is reduced to minimum. The load is supplied by the output capacitor until the output voltage has dropped below the threshold again. Hereupon the device starts switching again. The power-save mode is exited and PWM mode entered in case the output current exceeds the current IOUT_PFM_leave, or if the output voltage falls below a second comparator threshold, called skip comparator low (skip comp Low) threshold. This skip comparator low threshold is set to –2% below nominal V_{out}, and enables a fast transition from power-save mode to PWM mode during a load step. In power-save mode the quiescent current is reduced typically to 19 μA for one converter and 32 μA for both converters active. This single skip comparator threshold method in power-save mode results in a very low output voltage ripple. The ripple depends on the comparator delay and the size of the output capacitor. Increasing output capacitor values minimizes the output ripple. The power-save mode can be disabled through the MODE/DATA pin set to high. Both converters then operate in fixed PWM mode. Power-save mode enable/disable applies to both converters.

8.5 Programming

8.5.1 EasyScale™ Interface: One-Pin Serial Interface for Dynamic Output Voltage Adjustment

8.5.1.1 General

The EasyScale™ interface is a simple but very flexible one-pin interface to configure the output voltage of both DC–DC converters. The interface is based on a master-slave structure, where the master is typically a microcontroller or application processor. [Figure](#page-13-0) 8 and [Table](#page-13-1) 1 give an overview of the protocol. The protocol consists of a device specific address byte and a data byte. The device specific address byte is fixed to 4E hex. The data byte consists of five bit for information, two address bits and the RFA bit. RFA bit set to high indicates the **R**equest **F**or **A**cknowledge condition, but the acknowledge condition is only applied if the protocol was received correctly.

The advantage of EasyScale™ interface compared to other one-pin interfaces is that its bit detection is, to a large extent, independent from the bit transmission rate. It can automatically detect bit rates from 1.7 kbps to 160 kbps. Furthermore, the interface is shared with the MODE/DATA pin and requires therefore no additional pin.

8.5.1.2 Protocol

All bits are transmitted MSB first and LSB last. [Figure](#page-14-0) 9 shows the protocol without acknowledge request (bit $RFA = 0$, [Figure](#page-14-1) 10 with acknowledge (bit $RFA = 1$) request.

Prior to both bytes, device address byte and data byte, a start condition needs to be applied. For this, the MODE/DATA pin needs to be pulled high for at least t_{Start} before the bit transmission starts with the falling edge. In case the MODE/DATA line was already at high level (forced PWM mode selection) no start condition need be applied prior the device address byte.

The transmission of each byte needs to be closed with an end-of-stream condition for at least T_{EOS} .

8.5.1.3 Bit Decoding

The bit detection is based on a PWM scheme, where the criterion is the relation between t_{LOW} and t_{HIGH} . It can be simplified to:

High Bit: $t_{High} > t_{Low}$, but with t_{High} at least 2 x t_{Low} , see [Figure](#page-15-0) 11

Low Bit: $t_{Low} > t_{High}$, but with t_{Low} at least 2 x t_{High} , see [Figure](#page-15-0) 11

The bit detection starts with a falling edge on the MODE/DATA pin and ends with the next falling edge. Depending on the relation between t_{Low} and t_{High} a 0 or 1 is detected.

Programming (continued)

8.5.1.4 Acknowledge

The acknowledge condition is only applied if:

- acknowledge is requested by a set RFA bit
- the transmitted device address matches with the device address of the device
- 16 bits were received correctly

In this case, the device turns on the internal ACKN-MOSFET and pulls the MODE/DATA pin low for the time t_{ACKN} , which is maximum. 520 µs. The acknowledge condition is valid after an internal delay time t_{valACK} . This means the internal ACKN-MOSFET is turned on after t_{valACK}, when the last falling edge of the protocol was detected. The master controller keeps the line low during this time.

The master device can detect the acknowledge condition with its input by releasing the MODE/DATA pin after t_{valACK} and read back a 0.

In case of an invalid device address or not correctly received protocol, no acknowledge condition will be applied, thus the internal MOSFET will not be turned on and the external pullup resistor pulls MODE/DATA pin high after t_{valACK} . The MODE/DATA pin can be used again after the acknowledge condition ends.

NOTE

The acknowledge condition may only be requested in case the master device has an open-drain output.

In case of a push-pull output stage TI recommends to use a series resistor in the MODE/DATA line to limit the current to 500 μA in case of an accidentally requested acknowledge to protect the internal ACKN-MOSFET.

8.5.1.5 MODE Selection

Because of the MODE/DATA pin is used for two functions, interface and a mode selection, the device needs to determine when it has to decode the bit stream or to change the operation mode.

The device enters forced PWM mode operation immediately whenever the MODE/DATA pin turns to high level. The device stays also in forced PWM mode during the whole time of a protocol reception.

With a falling edge on the MODE/DATA pin the device starts bit decoding. If the MODE/DATA pin stays low for at least t_{timeout} , the device gets an internal time-out and power-save mode operation is enabled.

A protocol which is sent within this time will be ignored, because the falling edge for the mode change will be first interpreted as start of the first bit. In this case, TI recommends to send first the protocol and change at the end of the protocol to power-save mode.

DATA OUT | ACK

Figure 8. EasyScale™ Interface Protocol Overview

Table 1. EasyScale™ Interface Bit Description

Product Folder Links: *[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420) [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)*

Programming (continued)

Table 1. EasyScale™ Interface Bit Description (continued)

Figure 9. EasyScale™ Interface Protocol Without Acknowledge

Figure 11. EasyScale™ Interface – Bit Coding

Figure 12. MODE/DATA Pin: Mode Selection

Figure 13. MODE/DATA Pin: Power-Save Mode/Interface Communication

8.6 Register Maps

Three registers with a data content of 5 bits can be addressed. With 5 bit data content, 32 different values for each register are available. [Table](#page-16-1) 2 shows the addressable registers to set the output voltage when DEF_1 pin works as digital input. In this case, converter 1 has a related register for each DEF_1 pin condition, and one register for converter 2. With a high or low condition on pin DEF_1 (TPS62421) either the content of register REG_DEF_1_High/REG_DEF1_Low is selected. The output voltage of converter 1 is set according to the values in [Table](#page-16-2) 4. Table 3 shows the addressable registers if DEF_1 pin acts as analog input with external resistors connected. In this case one register is available for each converter. The output voltage of converter 1 is set according to the values in [Table](#page-18-0) 5. For converter 2, the available voltages are shown in [Table](#page-19-0) 6. To generate these output voltages a precise internal resistor divider network is used, making external resistors unnecessary (less board space), and provides higher output voltage accuracy. The Interface is activated if at least one of the converters is enabled (EN1 or EN2 is high). After the start-up time t_{Start} (170 µs) the interface is ready for data reception.

Table 2. Addressable Registers for Fixed Output Voltage Options (Pin DEF_1 = digital input)

Table 3. Addressable Registers for Adjustable Output Voltage Devices

[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420), [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421) SLVS676D –JUNE 2006–REVISED JULY 2015 **www.ti.com**

Table 4. Selectable Output Voltages for Converter 1, With Pin DEF_1 as Digital Input (TPS62421)

Table 5. Selectable Output Voltages for Converter 1, With DEF1 Pin as Analog Input (TPS62420)

Table 6. Selectable Output Voltages for Converter 2, (ADJ2 Connected to VOUT)

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

9.1.1 Output Voltage Setting

9.1.1.1 Converter 1 Adjustable Default Output Voltage Setting

The output voltage can be calculated to:

$$
V_{\text{OUT}} = V_{\text{REF}} \times \left(1 + \frac{R_{11}}{R_{12}}\right)
$$
 with an internal reference voltage V_{REF} typical 0.6V

(4)

 $V_{\text{OUT}} = V_{\text{REF}} \times \left(1 + \frac{R_{11}}{R_{12}}\right)$ with an internal reference voltage V_{REF} typical 0.6V
eep the operating current to a minimum, TI recommends selecting R_{12} within a rar
sum of R_{12} and R_{11} should no To keep the operating current to a minimum, TI recommends selecting R₁₂ within a range of 180 kΩ to 360 kΩ. The sum of R₁₂ and R₁₁ should not exceed ~1 MΩ. For higher output voltages than 3.3 V, TI recommends choosing lower values than 180 kΩ for R12. Route the DEF_1 line away from noise sources, such as the inductor or the SW1 line. The FB1 line needs to be directly connected to the output capacitor. An internal feedforward capacitor is connected to this pin, therefore there is no need for an external feed-forward capacitor for converter 1.

9.1.1.2 Converter 2

The default output voltage of converter 2 can be set by an external resistor network. For converter 2 the same recommendations apply as for converter 1. In addition to that, a 33-pF external feed-forward capacitor C_{ff2} for good load transient response must be used.

The output voltage can be calculated to:

$$
V_{OUT} = V_{REF} \times \left(1 + \frac{R_{21}}{R_{22}}\right)
$$
 with an internal reference voltage V_{REF} typical 0.6V (5)

Route the ADJ2 line away from noise sources, such as the inductor or the SW2 line. In case the interface is used for converter 2, connect ADJ2 pin directly to V_{OUT2}

9.2 Typical Applications

9.2.1 Typical Application Circuit 1.5-V and 2.85-V Adjustable Outputs

9.2.1.1 Design Requirements

The step-down converter design can be adapted to different output voltage and load current needs by choosing external components appropriate. The following design procedure is adequate for whole V_{IN} , V_{OUT} and load current range of TPS62420.

9.2.1.2 Detailed Design Procedure

9.2.1.2.1 Output Filter Design (Inductor and Output Capacitor)

The device is optimized to operate with inductors of 2.2 μH to 4.7 μH and output capacitors of 10 μF to 22 μF.

For operation with a 2.2-μH inductor, a 22-μF capacitor is suggested.

9.2.1.2.1.1 Inductor Selection

The selected inductor has to be rated for its DC resistance and saturation current. The DC resistance of the inductance will influence directly the efficiency of the converter. Therefore an inductor with lowest DC resistance should be selected for highest efficiency.

[Equation](#page-21-1) 6 calculates the maximum inductor current under static load conditions. The saturation current of the inductor should be rated higher than the maximum inductor current as calculated with [Equation](#page-21-2) 7. This is recommended because during heavy load transient the inductor current will rise above the calculated value.

$$
\Delta I_{L} = \text{Vout} \times \frac{1 - \frac{\text{Vout}}{\text{Vin}}}{L \times f}
$$

$$
I_{Lmax} = I_{\text{outmax}} + \frac{\Delta I_{L}}{2}
$$

where

- $f =$ Switching frequency (2.25 MHz typical)
- $L =$ Inductor value
- ΔI_{L} = Peak-to-peak inductor ripple current
- I_{Lmax} = Maximum inductor current (7) I_{Lmax}

 $V = 1$

(6)

Typical Applications (continued)

The highest inductor current will occur at maximum V_{IN} .

Open core inductors have a soft saturation characteristic and they can usually handle higher inductor currents versus a comparable shielded inductor.

A more conservative approach is to select the inductor current rating just for the maximum switch current of the corresponding converter. It must be considered, that the core material from inductor to inductor differs and will have an impact on the efficiency especially at high switching frequencies.

Refer to [Table](#page-22-0) 7 and the typical applications for possible inductors.

DIMENSIONS [mm ³]	INDUCTOR TYPE	SUPPLIER
$3.2 \times 2.6 \times 1.0$	MIPW3226	FDK
$3 \times 3 \times 0.9$	LPS3010	Coilcraft
$2.8 \times 2.6 \times 1.0$	VLF3010	TDK
$2.8 \times 2.6 \times 1.4$	VLF3014	TDK
$3 \times 3 \times 1.4$	LPS3015	Coilcraft
$3.9 \times 3.9 \times 1.7$	LPS4018	Coilcraft

Table 7. List of Inductors

9.2.1.2.1.2 Output Capacitor Selection

The advanced fast response voltage mode control scheme of the two converters allows the use of small ceramic capacitors with a typical value of 10 μF, without having large output voltage undershoots and overshoots during heavy load transients. Ceramic X7R/X5R capacitors having low ESR values result in lowest output voltage ripple and are therefore recommended.

If ceramic output capacitors are used, the capacitor RMS ripple current rating will always meet the application requirements. The RMS ripple current is calculated as:

$$
I_{\text{RMSCout}} = \text{Vout} \times \frac{1 - \frac{\text{Vout}}{\text{Vin}}}{L \times f} \times \frac{1}{2 \times \sqrt{3}}
$$
(8)

At nominal load current the inductive converters operate in PWM mode and the overall output voltage ripple is the sum of the voltage spike caused by the output capacitor ESR plus the voltage ripple caused by charging and discharging the output capacitor:

$$
\Delta \text{Vout} = \text{Vout} \times \frac{1 - \frac{\text{Vout}}{\text{Vin}}}{L \times f} \times \left(\frac{1}{8 \times \text{Cout} \times f} + \text{ESR} \right)
$$
\n(9)

Where the highest output voltage ripple occurs at the highest input voltage V_{IN} .

At light load currents the converters operate in power-save mode and the output voltage ripple is dependent on the output capacitor value. The output voltage ripple is set by the internal comparator delay and the external capacitor. Higher output capacitors like 22-μF values minimize the voltage ripple in PFM mode and tighten DC output accuracy in PFM mode.

9.2.1.2.1.3 Input Capacitor Selection

Because of the nature of the buck converter having a pulsating input current, a low-ESR input capacitor is required for best input voltage filtering and minimizing the interference with other circuits caused by high input voltage spikes. The converters need a ceramic input capacitor of 10 μF. The input capacitor can be increased without any limit for better input voltage filtering.

[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420), [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)

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9.2.1.3 Application Curves

Product Folder Links: *[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420) [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)*

[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420), [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)

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[TPS62420](http://www.ti.com/product/tps62420?qgpn=tps62420), [TPS62421](http://www.ti.com/product/tps62421?qgpn=tps62421)

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9.2.2 Typical Application Circuit TPS62421

In fixed output voltage version TPS62421, the default output voltage of converter 1 is fixed to 1.2 V or 1.8 V depending on the DEF_1 pin level. The default output voltage of converter 2 is fixed to 1.8 V. The ADJ2 pin must be connected directly to the converter 2 output voltage.

Figure 35. Typical Application Circuit TPS62421

10 Power Supply Recommendations

The TPS6242x device has no special requirements for its input power supply. The input power supply's output current needs to be rated according to the supply voltage, output voltage and output current of the TPS6242x.

11 Layout

11.1 Layout Guidelines

As for all switching power supplies, the layout is an important step in the design. Proper function of the device demands careful attention to PCB layout. Take care in board layout to get the specified performance. If the layout is not carefully done, the regulator could show poor line and/or load regulation, stability issues as well as EMI problems. It is critical to provide a low inductance, impedance ground path. Therefore, use wide and short traces for the main current paths as indicated in bold in [Figure](#page-27-4) 36.

The input capacitor should be placed as close as possible to the IC pins as well as the inductor and output capacitor.

Connect the GND pin of the device to the PowerPAD of the PCB and use this pad as a star point. For each converter use a common power GND node and a different node for the signal GND to minimize the effects of ground noise. Connect these ground nodes together to the PowerPAD (star point) underneath the IC. Keep the common path to the GND pin, which returns the small signal components and the high current of the output capacitors as short as possible to avoid ground noise. The output voltage sense lines (FB1, ADJ2, DEF_1) should be connected right to the output capacitor and routed away from noisy components and traces (that is, SW line). If the EasyScale™ interface is operated with high transmission rates, the MODE/DATA trace must be routed away from the ADJ2 line to avoid capacitive coupling into the ADJ2 pin. A GND guard ring between the MODE/DATA pin and ADJ2 pin avoids potential noise coupling.

11.2 Layout Example

Figure 36. Layout Diagram

Layout Example (continued)

Figure 37. PCB Layout

12 Device and Documentation Support

12.1 Device Support

12.1.1 Third-Party Products Disclaimer

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12.2 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

Table 8. Related Links

12.3 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms](http://www.ti.com/corp/docs/legal/termsofuse.shtml) of [Use.](http://www.ti.com/corp/docs/legal/termsofuse.shtml)

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12.4 Trademarks

EasyScale, OMAP, PowerPAD, E2E are trademarks of Texas Instruments. All other trademarks are the property of their respective owners.

12.5 Electrostatic Discharge Caution

These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

12.6 Glossary

[SLYZ022](http://www.ti.com/lit/pdf/SLYZ022) — *TI Glossary*.

This glossary lists and explains terms, acronyms, and definitions.

13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGING INFORMATION

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

www.ti.com 10-Dec-2020

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OTHER QUALIFIED VERSIONS OF TPS62420 :

• Automotive: [TPS62420-Q1](http://focus.ti.com/docs/prod/folders/print/tps62420-q1.html)

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

TEXAS

TAPE AND REEL INFORMATION

STRUMENTS

*All dimensions are nominal

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE

Pack Materials-Page 1

PACKAGE MATERIALS INFORMATION

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*All dimensions are nominal

Pack Materials-Page 2

GENERIC PACKAGE VIEW

DRC 10 VSON - 1 mm max height

3 x 3, 0.5 mm pitch PLASTIC SMALL OUTLINE - NO LEAD

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.

PACKAGE OUTLINE

DRC0010J VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

NOTES:

- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
- 2. This drawing is subject to change without notice.

3. The package thermal pad must be soldered to the printed circuit board for optimal thermal and mechanical performance.

EXAMPLE BOARD LAYOUT

DRC0010J VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

NOTES: (continued)

4. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature number SLUA271 (www.ti.com/lit/slua271).

5. Vias are optional depending on application, refer to device data sheet. If any vias are implemented, refer to their locations shown on this view. It is recommended that vias under paste be filled, plugged or tented.

EXAMPLE STENCIL DESIGN

DRC0010J VSON - 1 mm max height

PLASTIC SMALL OUTLINE - NO LEAD

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.

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