2ch.Step-Down DC/DC Controller ICs

☆GreenOperation Compatible

■ GENERAL DESCRIPTION

XC9503 series are PWM controlled, PWM/PFM automatic switching controlled, multi-functional, 2 channel step-down DC/DC controller ICs. Since the series has a built-in 0.9V reference voltage (accuracy ±2%), 0.9V to 6.0V can be set using external components.

With a 300kHz frequency, the size of the external components can be reduced. Switching frequencies of 180kHz & 500kHz are also available as custom-designed products.

The control of the XC9503 series can be switched between PWM control and PWM/PFM automatic switching control using external signals. Control switches from PWM to PFM during light loads when automatic switching is selected and the series is highly efficient from light loads through to large output currents. Noise is easily reduced with PWM control since the frequency is fixed. The series gives freedom to select control suited to the application.

Soft-start time is internally set to 10msec and offers protection against in-rush currents when the power is switched on and also protects against voltage overshoot.

■APPLICATIONS

- ●PDAs
- ●Palmtop computers
- ●Digital cameras
- ●Various multi function power supplies

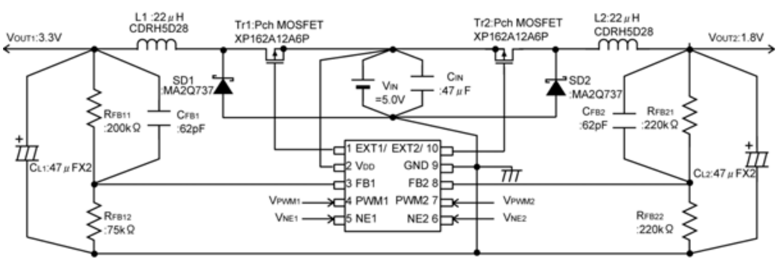
■FEATURES

2 ch DC/DC Controller (Step-Down & Down)

Input Voltage Range	: 2.0V ~ 10V
Power Supply Voltage Range	: 2.0V ~ 10V
Output Voltage Range	: 0.9V ~ 6.0V (set by FB pins)
Oscillation Frequency	: 300kHz (±15%) (180kHz, 500kHz custom)
Maximum Duty Cycle	: 100%
Control Method	: PWM or PWM/PFM Selectable
Output Current	: More than 1000mA (V_{IN}=5.0V, V_{OUT}=3.3V)
High Efficiency	: 92% (TPY.)
Stand-By Function	: 3.0 μA (MAX.)
Soft-Start Time	: 10 ms (internally set)
Packages	: MSOP-10, USP-10
Environmentally Friendly	: EU RoHS Compliant, Pb Free

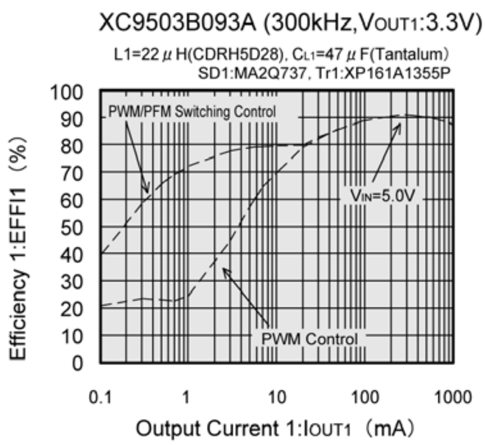
■TYPICAL APPLICATION CIRCUIT

<XC9503B093A V_{OUT}①: 3.3V, V_{OUT}②: 1.8V >

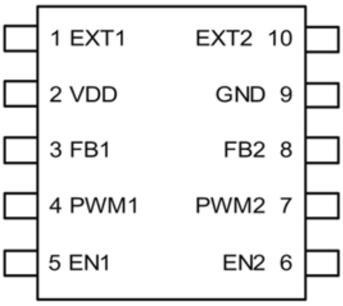


■TYPICAL PERFORMANCE CHARACTERISTICS

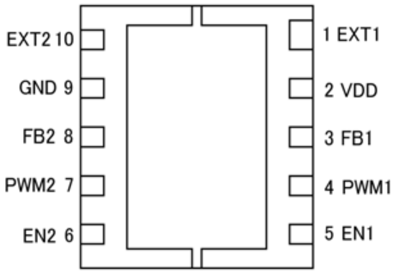
●Efficiency vs. Output Current



PIN CONFIGURATION



MSOP-10
(TOP VIEW)



USP-10
(BOTTOM VIEW)

PIN ASSIGNMENT

PIN NUMBER	PIN NAME	FUNCTIONS
1	EXT 1	Channel 1: External Transistor Drive Pin <Connected to P-ch Power MOSFET Gate>
2	V_{DD}	Supply Voltage
3	FB1	Channel 1: Output Voltage Monitor Feedback Pin <Threshold value: 0.9V. Output voltage can be set freely by connecting split resistors between V_{OUT1} and Ground.>
4	PWM1	Channel 1: PWM/PFM Switching Pin <Control Output 1. PWM control when connected to V_{DD}, PWM / PFM auto switching when connected to Ground. >
5	EN1	Channel 1: Enable Pin <Connected to Ground when Output 1 is in stand-by mode. Connected to V_{DD} when Output 1 is active. EXT1 is high when in stand-by mode.>
6	EN2	Channel 2: Enable Pin <Connected to Ground when Output 2 is in stand-by mode. Connected to V_{DD} when Output 2 is active. EXT2/ is high when in stand-by mode.>
7	PWM2	Channel 2: PWM/PFM Switching Pin <Control Output 2. PWM control when connected to V_{DD}, PWM / PFM auto switching when connected to Ground.>
8	FB2	Channel 2: Output Voltage Monitor Feedback Pin <Threshold value: 0.9V. Output voltage can be set freely by connecting split resistors between V_{OUT2} and Ground.>
9	GND	Ground
10	EXT2	Channel 2: External Transistor Drive Pin <Connected to P-ch Power MOSFET Gate>

PRODUCT CLASSIFICATION

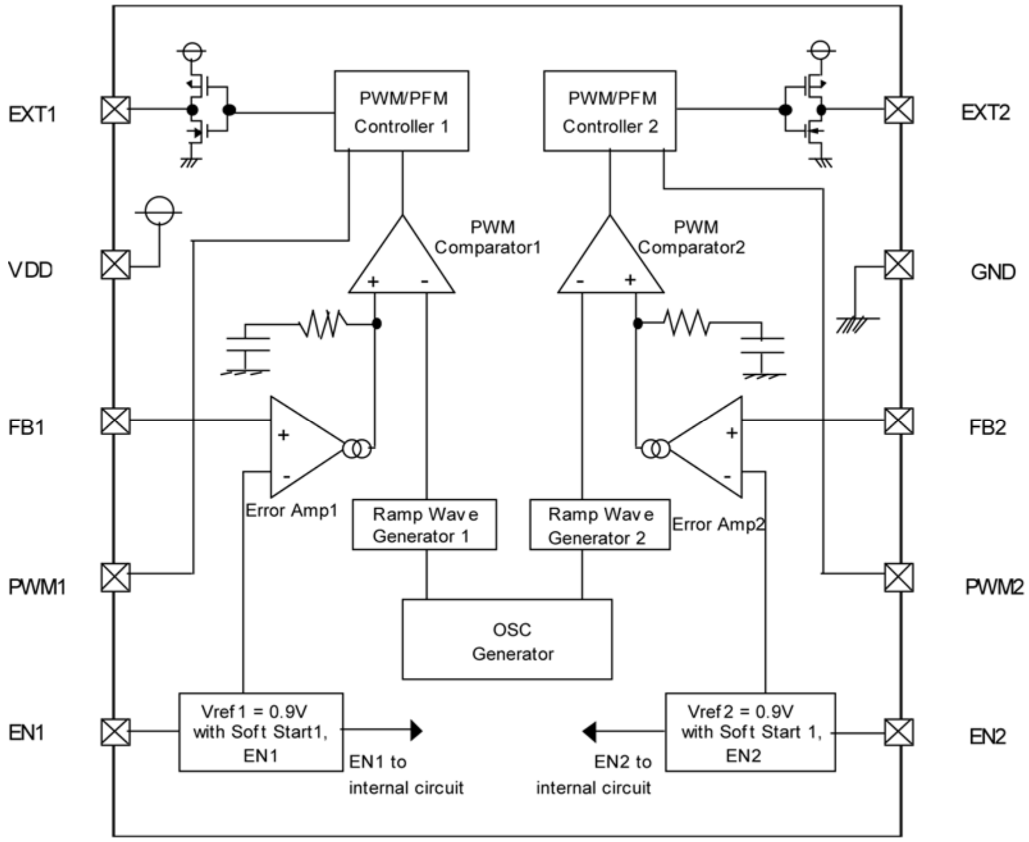
● Ordering Information

<u>XC9503①②③④⑤⑥-⑦</u> (*1)

DESIGNATOR	ITEM	SYMBOL	DESCRIPTION
①	Type of DC/DC Controller	B	Standard type (10 Pin)
②③	Output Voltage	09	FB products→②=0, ③=9 fixed
④	Oscillation Frequency	2	180kHz (custom)
		3	300kHz
		5	500kHz (custom)
⑤⑥-⑦ (*1)	Packages (Order Unit)	AR	MSOP-10 (1,000/Reel)
		AR-G	MSOP-10 (1,000/Reel)
		DR	USP-10 (3,000/Reel)
		DR-G	USP-10 (3,000/Reel)

(*1) The "-G" suffix indicates that the products are Halogen and Antimony free as well as being fully RoHS compliant.

■BLOCK DIAGRAM



■ABSOLUTE MAXIMUM RATINGS

Ta=25℃

PARAMETER		SYMBOL	RATINGS	UNITS
VDD Pin Voltage		VDD	- 0.3 ~ 12	V
FB1, 2 Pin Voltage		VFB	- 0.3 ~ 12	V
EN1, 2 Pin Voltage		VEN	- 0.3 ~ 12	V
PWM1, 2 Pin Voltage		VPWM	- 0.3 ~ 12	V
EXT1, 2 Pin Voltage		VEXT	- 0.3 ~ VDD + 0.3	V
EXT1, 2 Pin Current		IEXT	± 100	mA
Power Dissipation	MSOP-10	Pd	150	mW
	USP-10		150	
Operating Temperature Range		Topr	- 40 ~ + 85	℃
Storage Temperature Range		Tstg	- 55 ~ + 125	℃

Note: Voltage is all ground standardized.

■ELECTRICAL CHARACTERISTICS

XC9503B092A

Common Characteristics Ta=25℃

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage	V_{DD}		2.0	-	10.0	V	①
Maximum Input Voltage	V_{IN}		10.0	-	-	V	①
Output Voltage Range (* 1)	V_{OUTSET}	V_{IN}≧2.0V, $I_{OUT1,\ 2}$=1mA, V_{OUT1}	0.9	-	10.0	V	①
		V_{IN}≧2.0V, $I_{OUT1,\ 2}$=1mA, V_{OUT2}	0.9	-	10.0	V	
Supply Current 1	I_{DD1}	FB1, 2=0V	-	60	120	μA	②
Supply Current 1-1	I_{DD1-1}	EN1=3.0V, EN2=0V, FB1=0V EN2=3.0V, EN1=0V, FB2=0V	-	50	110	μA	②
Supply Current 1-2	I_{DD1-2}	FB1=0V, FB2=1.0V FB1=1.0V, FB2=0V	-	60	130	μA	②
Supply Current 2	I_{DD2}	FB1, 2=1.0V	-	60	140	μA	②
Stand-by Current	ISTB	Same as I_{DD1}, EN1=EN2=0V	-	1.0	3.0	μA	②
Switching Frequency	FOSC	Same as I_{DD1}	153	180	207	kHz	②
EN1, 2 "High" Voltage	V_{ENH}	FB1, 2=0V	0.65	-	-	V	②
EN1, 2 "Low" Voltage	V_{ENL}	FB1, 2=0V	-	-	0.20	V	②
EN1, 2 "High" Current	I_{ENH}	EN1, 2=3.0V	-	-	0.50	μA	②
EN1, 2 "Low" Current	I_{ENL}	EN1, 2=0V, FB1, 2=3.0V	-	-	-0.50	μA	②
PWM1, 2 "High" Current	I_{PWMH}	FB1, 2=3.0V, PWM=3.0V	-	-	0.50	μA	②
PWM1, 2 "Low" Current	I_{PWML}	FB1, 2=3.0V, PWM=0V	-	-	-0.50	μA	②
FB1, 2 "High" Current	I_{FBH}	FB1, 2=3.0V	-	-	0.50	μA	②
FB1, 2 "Low" Current	V_{FBL}	FB1, 2=1.0V	-	-	-0.50	μA	②

Unless otherwise stated, V_{DD}=3.0V, PWM1, 2=3.0V, EN1, 2 =3.0V

Output 1 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB1 Voltage	V_{FB1}	V_{IN}=3.0V, I_{OUT1}=10mA	0.882	0.900	0.918	V	③
Minimum Operation Voltage	V_{INmin1}		-	-	2.0	V	①
Maximum Duty Ratio 1	MAXDTY1	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio1	MINDTY1	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 1	PFMDTY1	No Load, VPWM1=0V	22	30	38	%	④
Efficiency1 (* 4)	EFFI1	I_{OUT1}=250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	④
Soft-Start Time1	T_{SS1}	V_{OUT1}×0.95V, EN1=0V→0.65V	5.0	10.0	20.0	ms	④
EXT1 "High" ON Resistance	R_{EXTBH1}	EN1=0, EXT1=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL1}	FB2=0V, EXT1=0.4V	-	22	30	Ω	⑤
PWM1 "High" Voltage	V_{PWMH1}	No Load	0.65	-	-	V	④
PWM1 "Low" Voltage	V_{PWML1}	No Load	-	-	0.20	V	④

Unless otherwise stated, V_{DD}=EN1=PWM1=3.0V, PWM2=EN2=GND, EXT2=OPEN, FB2=OPEN, V_{IN}=5.0V

Output 2 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB2 Voltage	V_{FB2}	V_{IN}=3.0V, I_{OUT2}=10mA	0.882	0.900	0.918	V	⑥
Minimum Operating Voltage	V_{INmin2}		-	-	2.0	V	①
Maximum Duty Ratio 2	MAXDTY2	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio 2	MINDTY2	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 2	PFMDTY2	No Load, V_{PWM2}=0V	22	30	38	%	⑦
Efficiency 1 (* 2)	EFFI2	I_{OUT2}=250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	⑦
Soft-Start Time 1	T_{SS2}	V_{OUT2}×0.95V, EN2=0V→0.65V	5.0	10.0	20.0	ms	⑦
EXT1 "High" ON Resistance	R_{EXTBH2}	EN2=0, EXT2=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL2}	FB2=0V, EXT2=0.4V	-	22	30	Ω	⑤
PWM 2 "High" Voltage	V_{PWMH2}	No Load	0.65	-	-	V	⑦
PWM 2 "Low" Voltage	V_{PWML2}	No Load	-	-	0.20	V	⑦

Unless otherwise stated, V_{DD}=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, V_{IN}=5.0V

NOTE:
*1: Please be careful not to exceed the breakdown voltage level of the peripheral parts.

*2: EFFI={ [(output voltage) × (output current)] / [(input voltage) × (input current)] } × 100

■ELECTRICAL CHARACTERISTICS (Continued)

XC9503B093A

Common Characteristics Ta=25℃

PARAMETER	SYMBOL	CONDITIONS		MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage	V_{DD}			2.0	-	10.0	V	①
Maximum Input Voltage	V_{IN}			10.0	-	-	V	①
Output Voltage Range (* 1)	V_{OUTSET}	V_{IN}≧2.0V, $I_{OUT1, 2}$=1mA	V_{OUT1}	0.9	-	10.0	V	①
			V_{OUT2}	0.9	-	10.0	V	
Supply Current 1	I_{DD1}	FB1, 2=0V		-	70	140	μA	②
Supply Current 1-1	I_{DD1-1}	EN1=3.0V, EN2=0V, FB1=0V EN2=3.0V, EN1=0V, FB2=0V		-	60	120	μA	②
Supply Current 1-2	I_{DD1-2}	FB1=0V, FB2=1.0V FB1=1.0V, FB2=0V		-	70	150	μA	②
Supply Current 2	I_{DD2}	FB1, 2=1.0V		-	80	150	μA	②
Stand-by Current	I_{STB}	Same as I_{DD1}, EN1=EN2=0V		-	1.0	3.0	μA	②
Switching Frequency	FOSC	Same as I_{DD1}		255	300	345	kHz	②
EN1, 2 "High" Voltage	V_{ENH}	FB1, 2=0V		0.65	-	-	V	②
EN1, 2 "Low" Voltage	V_{ENL}	FB1, 2=0V		-	-	0.20	V	②
EN1, 2 "High" Current	I_{ENH}	EN1, 2=3.0V		-	-	0.50	μA	②
EN1, 2 "Low" Current	I_{ENL}	EN1, 2=0V, FB1, 2=3.0V		-	-	-0.50	μA	②
PWM1, 2 "High" Current	I_{PWMH}	FB1, 2=3.0V, PWM=3.0V		-	-	0.50	μA	②
PWM1, 2 "Low" Current	I_{PWML}	FB1, 2=3.0V, PWM=0V		-	-	-0.50	μA	②
FB1, 2 "High" Current	I_{FBH}	FB1, 2=3.0V		-	-	0.50	μA	②
FB1, 2 "Low" Current	V_{FBL}	FB1, 2=1.0V		-	-	-0.50	μA	②

Unless otherwise stated, V_{DD}=3.0V, PWM1, 2=3.0V, EN1, 2 =3.0V

Output 1 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 1 Voltage	V_{FB1}	V_{IN}=3.0V I_{OUT1}=10mA	0.882	0.900	0.918	V	③
Minimum Operating Voltage	V_{INmin1}		-	-	2.0	V	①
Maximum Duty Ratio 1	MAXDTY1	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio 1	MINDTY1	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 1	PFMDTY1	No Load, V_{PWM1}=0V	22	30	38	%	④
Efficiency1 (* 4)	EFFI1	I_{OUT1}=250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	④
Soft-Start Time 1	T_{SS1}	V_{OUT1}×0.95V, EN1=0V→0.65V	5.0	10.0	20.0	ms	④
EXT1 "High" ON Resistance	R_{EXTBH1}	EN1=0, EXT1=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL1}	FB2=0V, EXT1=0.4V	-	22	30	Ω	⑤
PWM1 "High" Voltage	V_{PWMH1}	No Load	0.65	-	-	V	④
PWM1 "Low" Voltage	V_{PWML1}	No Load	-	-	0.20	V	④

Unless otherwise stated, V_{DD}=EN1=PWM1=3.0V, PWM2=EN2=GND, EXT2=OPEN, FB2=OPEN, V_{IN}=5.0V

Output 2 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 2 Voltage	V_{FB2}	V_{IN}=3.0V, I_{OUT2}=10mA	0.882	0.900	0.918	V	⑥
Minimum Operating Voltage	V_{INmin2}		-	-	2.0	V	①
Maximum Duty Ratio 2	MAXDTY2	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio 2	MINDTY2	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 2	PFMDTY2	No Load, VPWM2=0V	22	30	38	%	⑦
Efficiency 1 (* 2)	EFFI2	I_{OUT2}=250mA P-ch MOSFET: XP162A12A6P	-	92	-	%	⑦
Soft-Start Time 1	T_{SS2}	V_{OUT2}×0.95V, EN2=0V→0.65V	5.0	10.0	20.0	ms	⑦
EXT1 "High" ON Resistance	R_{EXTBH2}	EN2=0, EXT2=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL2}	FB2=0V, EXT2=0.4V	-	22	30	Ω	⑤
PWM2 "High" Voltage	V_{PWMH2}	No Load	0.65	-	-	V	⑦
PWM2 "Low" Voltage	V_{PWML2}	No Load	-	-	0.20	V	⑦

Unless otherwise stated, V_{DD}=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, V_{IN}=5.0V

NOTE:

*1: Please be careful not to exceed the breakdown voltage level of the peripheral parts.

*2: EFFI={ [(output voltage) × (output current)] / [(input voltage) × (input current)] } × 100

■ELECTRICAL CHARACTERISTICS (Continued)

XC9503B095A Common Characteristics Ta=25℃

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
Supply Voltage	V_{DD}		2.0	-	10.0	V	①
Maximum Input Voltage	V_{IN}		10.0	-	-	V	①
Output Voltage Range (* 1)	V_{OUTSET}	V_{IN}≧2.0V, $I_{OUT1,2}$=1mA, V_{OUT1}	0.9	-	10.0	V	①
		V_{OUT2}	0.9	-	10.0	V	
Supply Current 1	I_{DD1}	FB1, 2=0V	-	90	170	μA	②
Supply Current 1-1	I_{DD1-1}	EN1=3.0V, EN2=0V, FB1=0V EN2=3.0V, EN1=0V, FB2=0V	-	80	150	μA	②
Supply Current 1-2	I_{DD1-2}	FB1=0V, FB2=1.0V FB1=1.0V, FB2=0V	-	100	180	μA	②
Supply Current 2	I_{DD2}	FB1, 2=1.0V	-	100	190	μA	②
Stand-by Current	I_{STB}	Same as I_{DD1}, EN1=EN2=0V	-	1.0	3.0	μA	②
Switching Frequency	FOSC	Same as I_{DD1}	425	500	575	kHz	②
EN1, 2 "High" Voltage	V_{ENH}	FB1, 2=0V	0.65	-	-	V	②
EN1, 2 "Low" Voltage	V_{ENL}	FB1, 2=0V	-	-	0.20	V	②
EN1, 2 "High" Current	I_{ENH}	EN1, 2=3.0V	-	-	0.50	μA	②
EN1, 2 "Low" Current	I_{ENL}	EN1, 2=0V, FB1, 2=3.0V	-	-	-0.50	μA	②
PWM1, 2 "High" Current	I_{PWMH}	FB1, 2=3.0V, PWM=3.0V	-	-	0.50	μA	②
PWM1, 2 "Low" Current	I_{PWML}	FB1, 2=3.0V, PWM=0V	-	-	-0.50	μA	②
FB1, 2 "High" Current	I_{FBH}	FB1, 2=3.0V	-	-	0.50	μA	②
FB1, 2 "Low" Current	V_{FBL}	FB1, 2=1.0V	-	-	-0.50	μA	②

Unless otherwise stated. V_{DD}=3.0V. PWM1. 2=3.0V. EN1. 2 =3.0V

Output 1 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 1 Voltage	V_{FB1}	V_{IN}=3.0V, I_{OUT1}=10mA	0.882	0.900	0.918	V	③
Minimum Operation Voltage	V_{INmin1}		-	-	2.0	V	①
Maximum Duty Ratio 1	MAXDTY1	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio 1	MINDTY1	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 1	PFMDTY1	No Load, V_{PWM1}=0V	22	30	38	%	④
Efficiency1 (* 4)	EFFI1	I_{OUT1}=250mA P-ch MOSFET: XP162A12A6P	-	91	-	%	④
Soft-Start Time 1	T_{SS1}	V_{OUT1}×0.95V, EN1=0V→0.65V	5.0	10.0	20.0	ms	④
EXT1 "High" ON Resistance	R_{EXTBH1}	EN1=0, EXT1=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL1}	FB2=0V, EXT1=0.4V	-	22	30	Ω	⑤
PWM1 "High" Voltage	V_{PWMH1}	No Load	0.65	-	-	V	④
PWM1 "Low" Voltage	V_{PWML1}	No Load	-	-	0.20	V	④

Unless otherwise stated, V_{DD}=EN1=PWM1=3.0V, PWM2=EN2=GND, EXT2=OPEN, FB2=OPEN, V_{IN}=5.0V

Output 2 Characteristics Step-Down Controller

PARAMETER	SYMBOL	CONDITIONS	MIN.	TYP.	MAX.	UNITS	CIRCUIT
FB 2 Voltage	V_{FB2}	V_{IN}=3.0V, I_{OUT2}=10mA	0.882	0.900	0.918	V	⑥
Minimum Operation Voltage	VINmin2		-	-	2.0	V	①
Maximum Duty Ratio 2	MAXDTY2	Same as I_{DD1}	100	-	-	%	②
Minimum Duty Ratio 2	MINDTY2	Same as I_{DD2}	-	-	0	%	②
PFM Duty Ratio 2	PFMDTY2	No Load, V_{PWM2}=0V	22	30	38	%	⑦
Efficiency 1 (* 2)	EFFI2	I_{OUT2}=250mA P-ch MOSFET: XP162A12A6P	-	91	-	%	⑦
Soft-Start Time 1	T_{SS2}	V_{OUT2}×0.95V, EN2=0V→0.65V	5.0	10.0	20.0	ms	⑦
EXT1 "High" ON Resistance	R_{EXTBH2}	EN2=0, EXT2=V_{DD}-0.4V	-	28	47	Ω	⑤
EXT1 "Low" ON Resistance	R_{EXTBL2}	FB2=0V, EXT2=0.4V	-	22	30	Ω	⑤
PWM2 "High" Voltage	V_{PWMH2}	No Load	0.65	-	-	V	⑦
PWM2 "Low" Voltage	V_{PWML2}	No Load	-	-	0.20	V	⑦

Unless otherwise stated, V_{DD}=EN2=PWM2=3.0V, PWM1=EN1=GND, EXT1=OPEN, FB1=OPEN, V_{IN}=5.0V

NOTE:

*1 : Please be careful not to exceed the breakdown voltage level of the peripheral parts.

*2 : EFFI={ [(output voltage) × (output current)] / [input voltage] × (input current)] } × 100

■OPERATIONAL EXPLANATION

The XC9503 series are multi-functional, 2 channel step-down DC/DC converter controller ICs with built-in high speed, low ON resistance drivers.

<Error Amp. 1, 2>
The Error Amplifier is designed to monitor the output voltage and it compares the feedback voltage (FB) with the reference voltage. In response to feedback of a voltage lower than the reference voltage, the output voltage of the error amp. decreases.

<OSC Generator>
This circuit generates the switching frequency, which in turn generates the reference clock.

<Ramp Wave Generator 1, 2>
The ramp wave generator generates a saw-tooth waveform based on outputs from the phase shift generator.

<PWM Comparator 1, 2>
The PWM comparator compares outputs from the error amp. and saw-tooth waveform. When the voltage from the error amp's output is low, the external switch will be set to ON.

<PWM/PFM Controller 1, 2>
This circuit generates PFM pulses.
Control can be switched between PWM control and PWM/PFM automatic switching control using external signals.
The PWM/PFM automatic switching mode is selected when the voltage of the PWM1 (2) pin is less than 0.2V, and the control switches between PWM and PFM automatically depending on the load. As the PFM circuit generates pulses based on outputs from the PWM comparator, shifting between modes occurs smoothly. PWM control mode is selected when the voltage of the PWM1 (2) pin is more than 0.65V. Noise is easily reduced with PWM control since the switching frequency is fixed.
Control suited to the application can easily be selected which is useful in audio applications, for example, where traditionally, efficiencies have been sacrificed during stand-by as a result of using PWM control (due to the noise problems associated with the PFM mode in stand-by).

<Vref with Soft Start 1, 2>
The reference voltage, Vref (FB pin voltage)=0.9V, is adjusted and fixed by laser trimming (for output voltage settings, please refer to next page). To protect against inrush current, when the power is switched on, and also to protect against voltage overshoot, soft-start time is set internally to 10ms. It should be noted, however, that this circuit does not protect the load capacitor (C_L) from inrush current. With the Vref voltage limited and depending upon the input to the error amps, the operation maintains a balance between the two inputs of the error amps and controls the EXT pin's ON time so that it doesn't increase more than is necessary.

<Chip Enable Function>
This function controls the operation and shutdown of the IC. When the voltage of the EN1 or EN2 pins is 0.2V or less, the mode will be chip disable, the channel's operations will stop and the EXT pins will be kept at a high level (the external P-ch MOSFET will be OFF). When both EN1 and EN2 are in a state of chip disable, current consumption will be no more than 3.0 μA. When the EN1 or EN2 pin's voltage is 0.65V or more, the mode will be chip enable and operations will recommence. With soft-start, 95% of the set output voltage will be reached within 10mS (TYP.) from the moment of chip enable.

OPERATIONAL EXPLANATION (Continued)

<Setting of Output Voltage>

Output voltage can be set by adding external split resistors. Output voltage is determined by the following equation, based on the values of R_{FB11} (R_{FB21}) and R_{FB12} (R_{FB22}). The sum of R_{FB11} (R_{FB21}) and R_{FB12} (R_{FB22}) should normally be 1MΩ or less.

$$V_{OUT}=0.9 \times (R_{FB11}+R_{FB12}) / R_{FB12}$$

The value of C_{FB1} (C_{FB2}), speed-up capacitor for phase compensation, should be $fzfb = 1 / (2 \times \pi \times C_{FB1} \times R_{FB11})$ which is equal to 12kHz. Adjustments are required from 1kHz to 50kHz depending on the application, value of inductance (L), and value of load capacity (C_L).

[Example of Calculation]

When $R_{FB11}=200k\Omega$ *and* $R_{FB12}=75k\Omega$, $V_{OUT1}=0.9 \times (200k+75k) / 75k=3.3V$.

[Typical Example]

VOUT (V)	RFB11 (kΩ)	RFB12 (kΩ)	CFB1 (pF)	VOUT (V)	RFB11 (kΩ)	RFB12 (kΩ)	CFB1 (pF)
1.0	30	270	430	2.5	390	220	33
1.5	220	330	62	2.7	360	180	33
1.8	220	220	62	3.0	560	240	24
2.0	330	270	39	3.3	200	75	62
2.2	390	270	33	5.0	82	18	160

The same method can be adopted for channel two also.

[External Components]

Tr : * MOSFET
XP162A12A6P (P-ch Power MOSFET, TOREX)
Note: V_{GS} breakdown voltage of this Tr. is 12V so please be careful with the power supply voltage.

SD : MA2Q737 (Schottky, MATSUSHITA)
CMS02 (Schottky, TOSHIBA)

L : 10μH (CDRH5D28, SUMIDA, FOSC = 500kHz)
22μH (CDRH5D28, SUMIDA, FOSC = 300kHz)
22μH (CDRH5D28, SUMIDA, FOSC = 180kHz)

C_{L1} : 16V, 47μF (Tantalum)
Increase capacity according to the equation below when the step-up voltage ratio is large and output current is high.

$$C=(C_L \text{ standard value}) \times (I_{OUT} (mA) / 500mA \times V_{OUT} / V_{IN}$$

Tr : * PNP MOSFET
2SA1213 (SANYO)

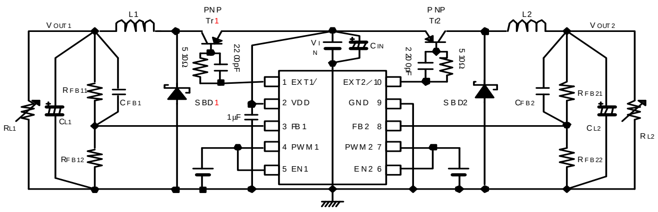
R_B : 500Ω (Adjust in accordance with load & Tr.'s HFE.)
Set according to the equation below.
$R_B \leqq (V_{IN}-0.7) \times hFE / IC-R_{EXTBH}$

C_B : 2200pF (Ceramic)
Set according to the equation below.
$C_{B1} \leqq (2\pi \times R_B \times FOSC \times 0.7)$

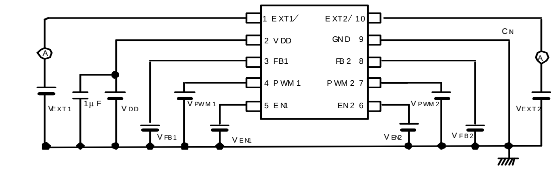
The same components can be adopted for both channel 1 and channel 2.

■TEST CIRCUITS

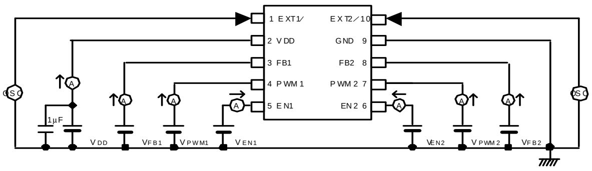
Circuit ①



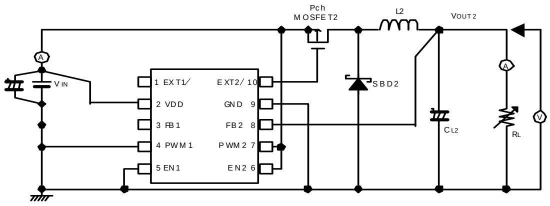
Circuit ⑤



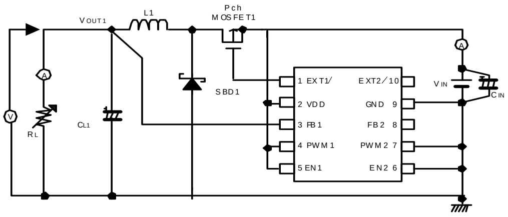
Circuit ②



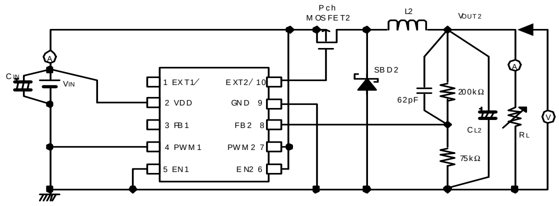
Circuit ⑥



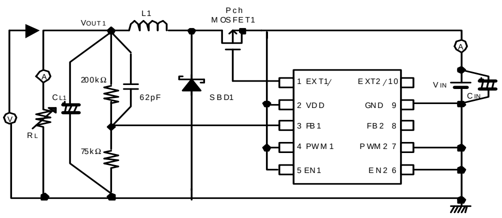
Circuit ③



Circuit ⑦



Circuit ④



■EXTERNAL COMPONENTS USED FOR TEST CIRCUITS

Circuit ①	L1, L2:	22μH (CDRH5D28, SUMIDA)	: XC9503B092A
		15μH (CDRH5D28, SUMIDA)	: XC9503B093A
		10μH (CDRH5D28, SUMIDA)	: XC9503B095A
	SD1, SD2:	CRS02 (Schottky diode, TOSHIBA)	
		EC10QS06 (Schottky diode, NIHON INTER)	
	C_{L1}, C_{L2}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	C_{IN}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	PNP Tr1:	2SA1213 (TOSHIBA)	
	R_{FB}:	Please use by the conditions as below:	
		$R_{FB11} + R_{FB12} \leq 1M\Omega$	
		$R_{FB21} + R_{FB22} \leq 1M\Omega$	
		R_{FB11} / R_{FB12} = (Setting output voltage / 0.9) - 1	
		$V_{OUT2} = (0.9 - V_{OUT1}) \times (R_{FB21}/R_{FB22}) + 0.9V$	
	C_{FB}:	Please adjust as below:	
		$fxfb = 1/(2 \times \pi \times C_{FB1} \times R_{FB11})$ = 1kHz ~ 50kHz (12kHz usual)	
		$fxfb = 1/(2 \times \pi \times C_{FB2} \times R_{FB21})$ = 1kHz ~ 50kHz (12kHz usual)	
Circuit ③	L1:	22μH (CDRH5D28, SUMIDA)	
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	C_{L1}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	C_{IN}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET1:	XP162A12A6P (TOREX)	
Circuit ④	L1:	22μH (CDRH5D28, SUMIDA)	: XC9503B092A
		15μH (CDRH5D28, SUMIDA)	: XC9503B093A
		10μH (CDRH5D28, SUMIDA)	: XC9503B095A
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	C_{L1}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	C_{IN}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET1:	XP162A12A6P (TOREX)	
Circuit ⑥	L1:	22μH (CDRH5D28, SUMIDA)	
	SD1:	MA2Q737 (Schottky diode, MATSUSHITA)	
	C_{L1}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	C_{IN}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET2:	XP162A12A6P (TOREX)	
Circuit ⑦	L2:	22μH (CDRH5D28, SUMIDA)	: XC9503B092A
		15μH (CDRH5D28, SUMIDA)	: XC9503B093A
		10μH (CDRH5D28, SUMIDA)	: XC9503B095A
	SD2:	MA2Q737 (Schottky diode, MATSUSHITA)	
	C_{L2}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	C_{IN}:	16MCE476MD2 (Tantalum, NIHON CHEMICON)	
	P-ch MOSFET2:	XP162A12A6P (TOREX)	

NOTES ON USE

1. Checking for Intermittent Oscillation

The XC9503 series is subject to intermittent oscillation in the proximity of the maximum duty if the step-down ratio is low (e.g., from 4.2 V to 3.3 V) or a heavy load is applied where the duty ratio becomes high. Check waveforms at EXT under your operating conditions. A remedy for this problem is to raise the inductance of coil L or increase the load capacitance C_L.

2. PWM/PFM Automatic Switching

If PWM/PFM automatic switching control is selected and the step-down ratio is low (e.g, from 4.5V to 5.0V) or high (e.g., from 10 V to 1.0 V), the control mode remains in PFM setting over the whole load range, since the duty ratio under continuous-duty condition is smaller than the PFM duty ratio of the XC9503 series. The output voltage's ripple voltage becomes substantially high under heavy load conditions, with the XC9503 series appearing to be producing an abnormal oscillation. If this operation becomes a concern, set pins PWM1 and PWM2 to High to set the control mode to PWM setting. For use under the above-mentioned condition, measured data of PWM/PFM automatic switching control shown on the data sheets are available up to I_{OUT} = 100 mA.

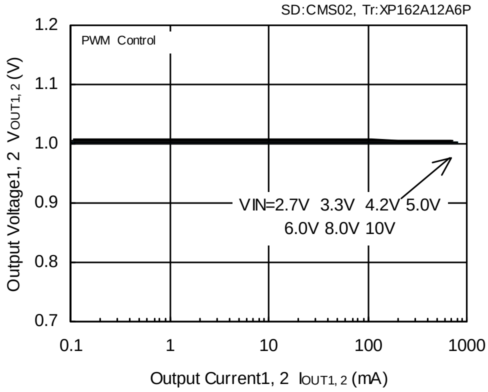
3. Ratings

Use the XC9503 series and external components within the limits of their ratings.

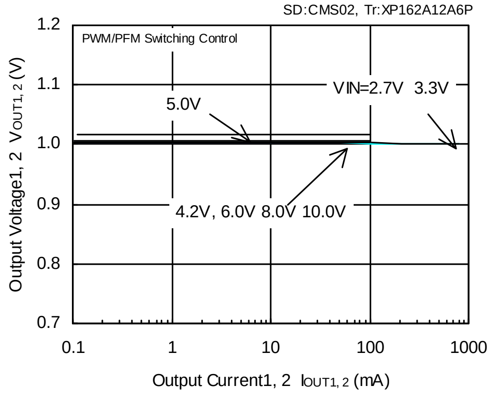
■TYPICAL PERFORMANCE CHARACTERISTICS

(1) Output Voltage vs. Output Current

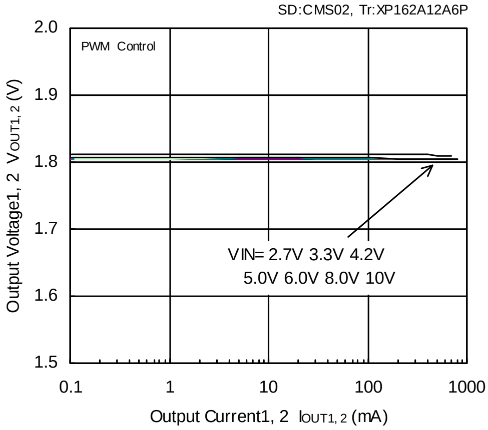
FOSC=300kHz, VOUT1, 2=1.0V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



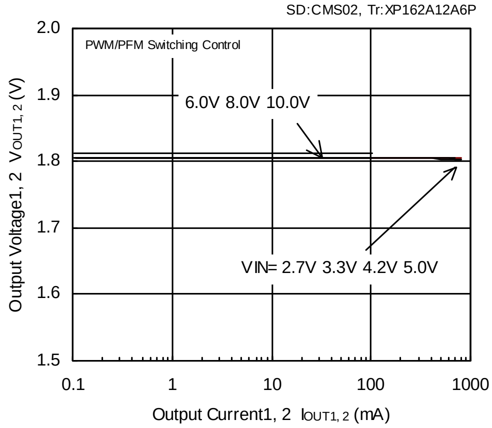
FOCS=300kHz, VOUT1, 2=1.0V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



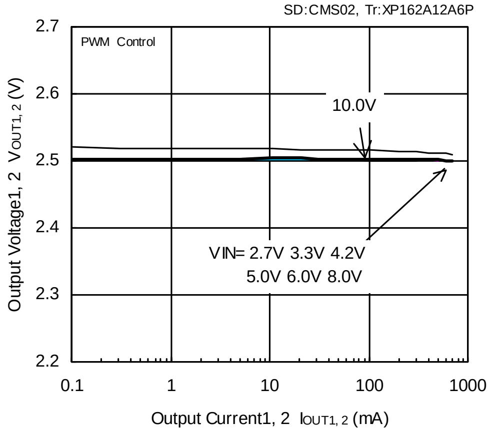
FOSC=300kHz, VOUT1, 2=1.8V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



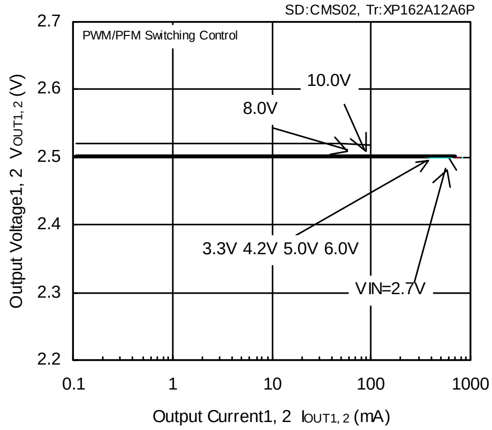
FOSC=300kHz, VOUT1, 2=1.8V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=300kHz, VOUT1, 2=2.5V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=300kHz, VOUT1, 2=2.5V
L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



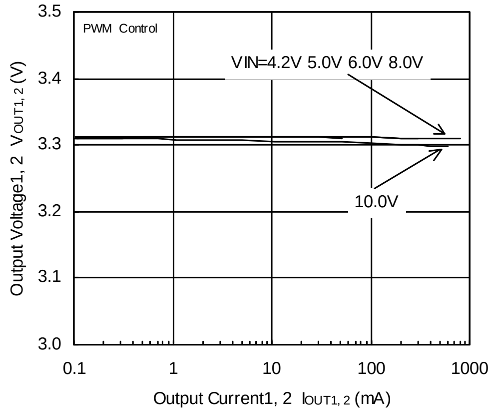
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(1) Output Voltage vs. Output Current (Continued)

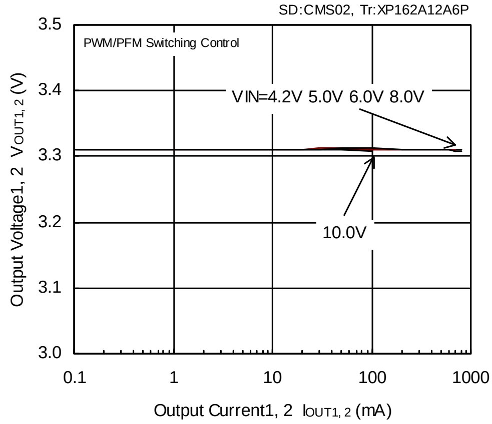
FOSC=300kHz, VOUT1, 2=3.3V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



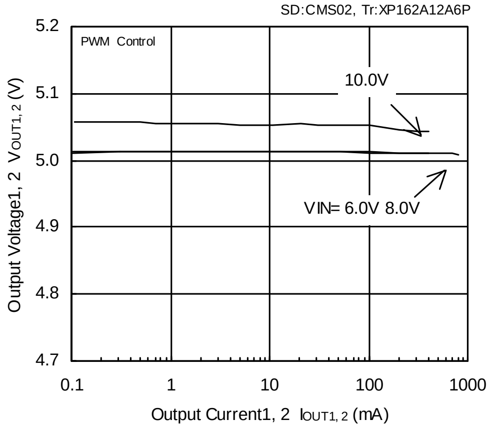
FOSC=300kHz, VOUT1, 2=3.3V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



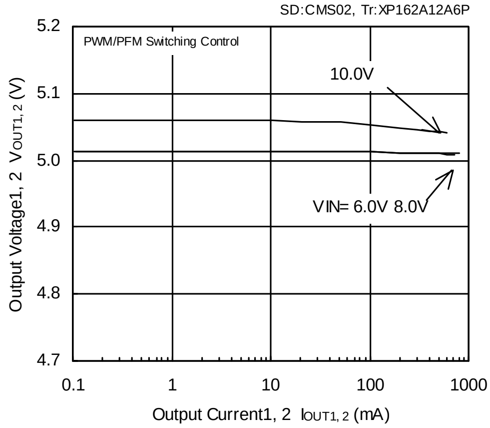
FOSC=300kHz, VOUT1, 2=5.0V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



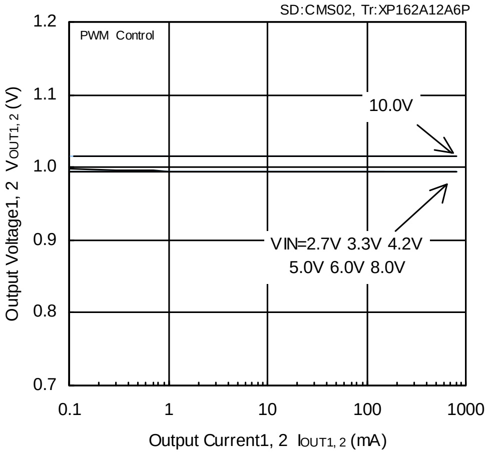
FOSC=300kHz, VOUT1, 2=5.0V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



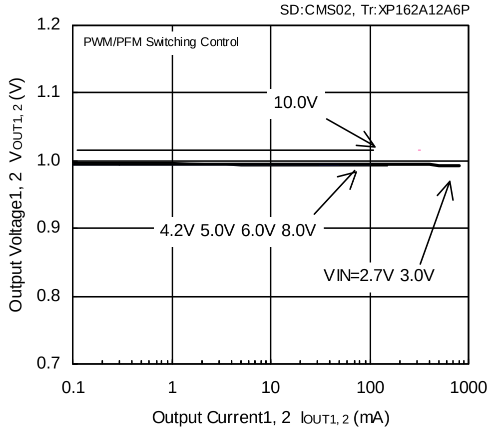
FOSC=180kHz, VOUT1, 2=1.0V

L=47μH(CDRH6D38), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=180kHz, VOUT1, 2=1.0V

L=47μH(CDRH6D38), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



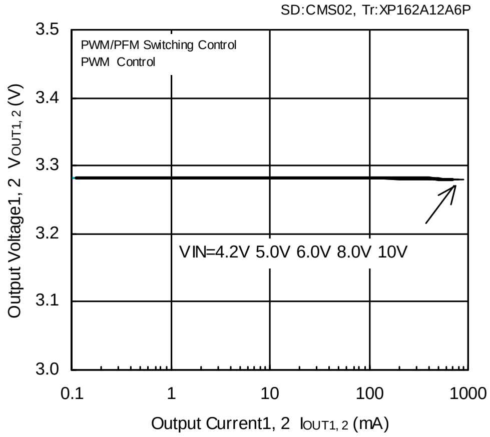
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(1) Output Voltage vs. Output Current (Continued)

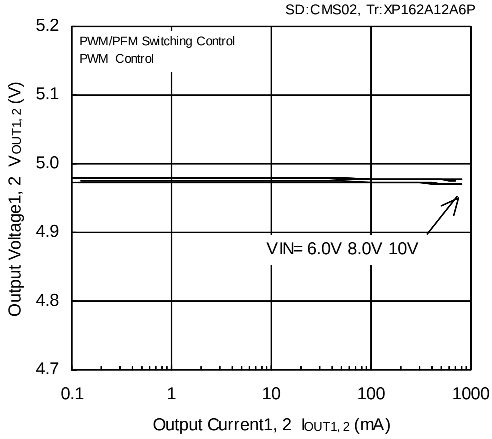
FOSC=180kHz, VOUT1, 2=3.3V

L=47μH(CDRH6D38), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



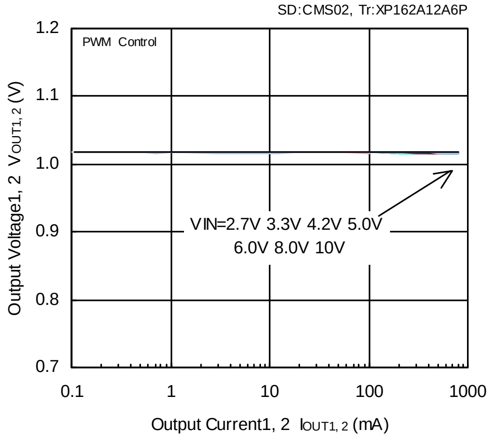
FOSC=180kHz, VOUT1, 2=5.0V

L=47μH(CDRH6D38), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



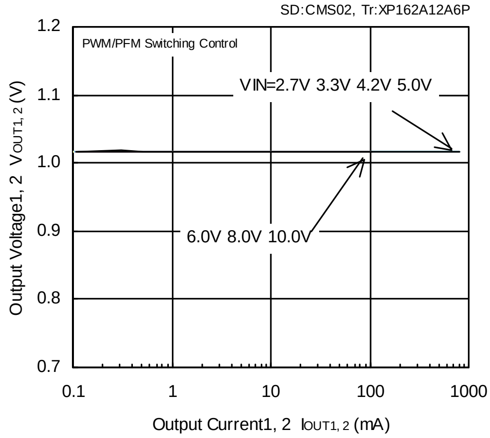
FOSC=500kHz, VOUT1, 2=1.0V

L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



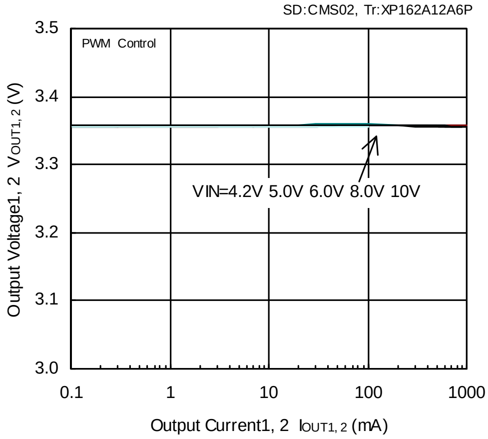
FOSC=500kHz, VOUT1, 2=1.0V

L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



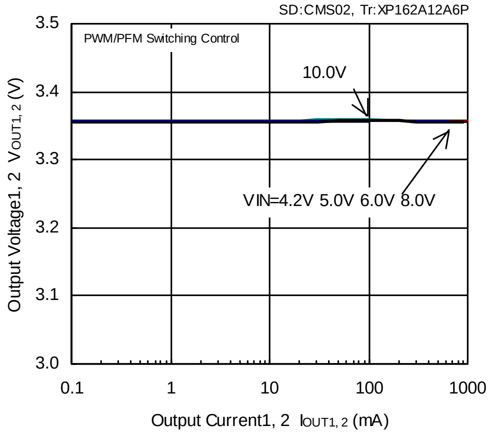
FOSC=500kHz, VOUT1, 2=3.3V

L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=500kHz, VOUT1, 2=3.3V

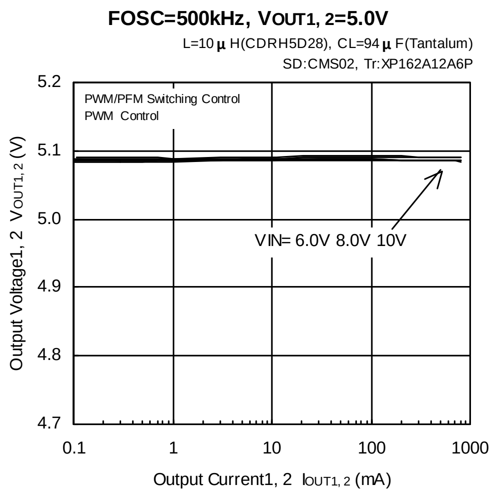
L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(1) Output Voltage vs. Output Current (Continued)

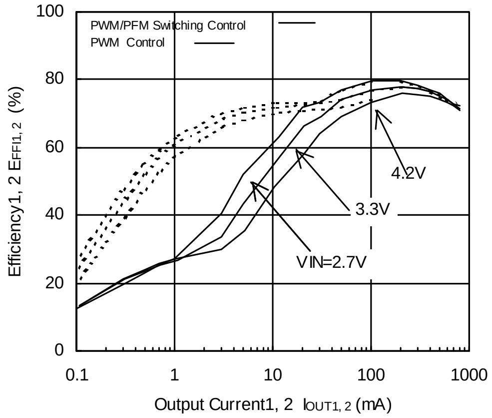


■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(2) Efficiency vs. Output Current

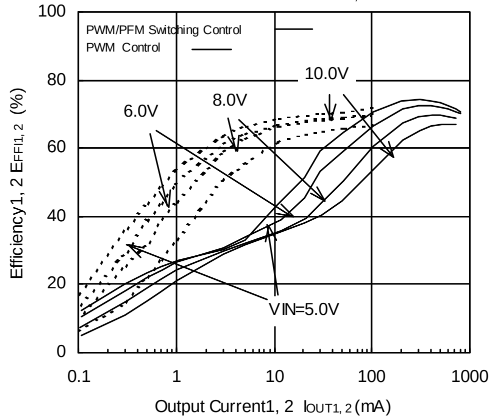
FOSC=300kHz, VOUT1, 2=1.0V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



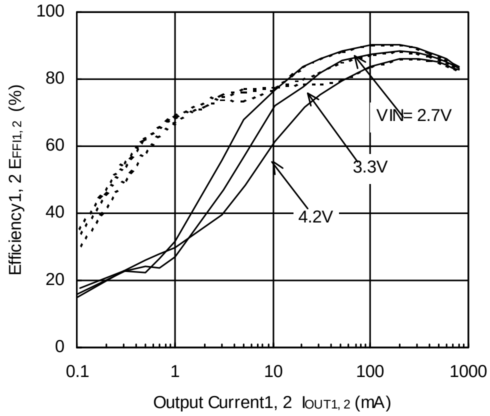
FOSC=300kHz, VOUT1, 2=1.0V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



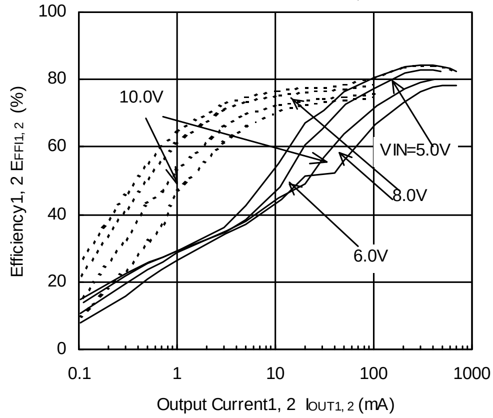
FOSC=300kHz, VOUT1, 2=1.8V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



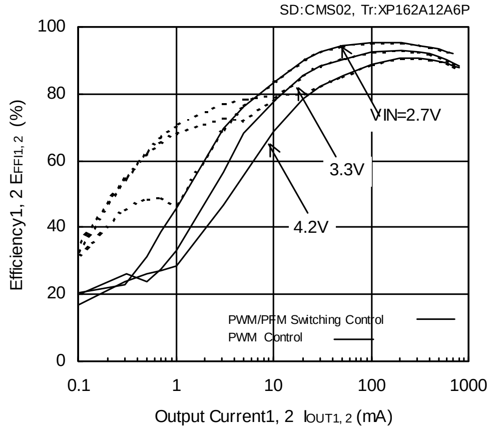
FOSC=300kHz, VOUT1, 2=1.8V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



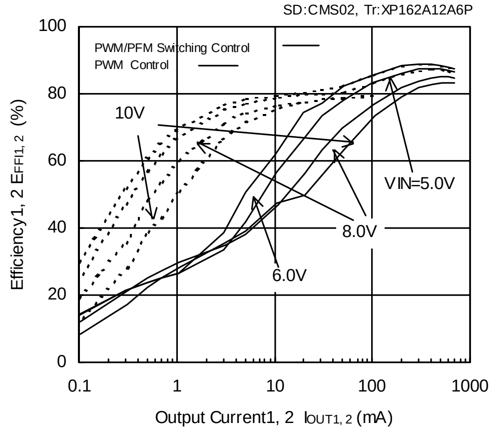
FOSC=300kHz, VOUT1, 2=2.5V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=300kHz, VOUT1, 2=2.5V

L=22μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



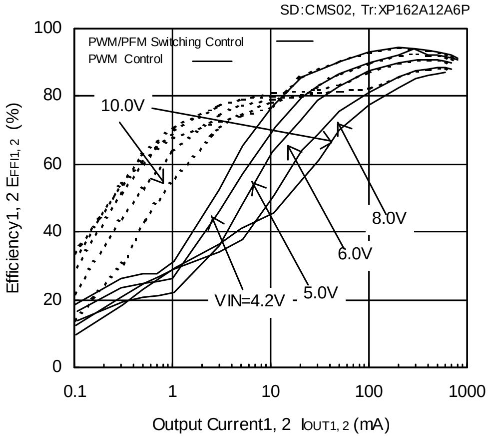
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(2) Efficiency vs. Output Current (Continued)

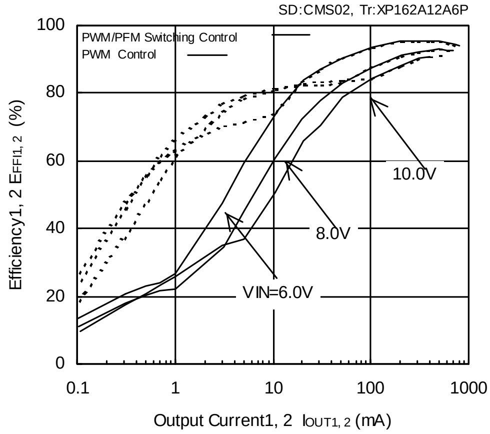
FOSC=300kHz, VOUT1, 2=3.3V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



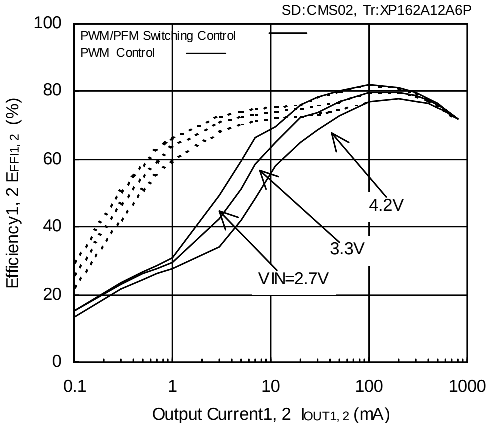
FOSC=300kHz, VOUT1, 2=5.0V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



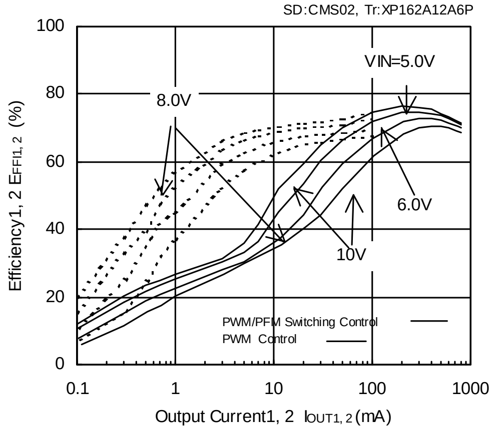
FOSC=180kHz, VOUT1, 2=1.0V

L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



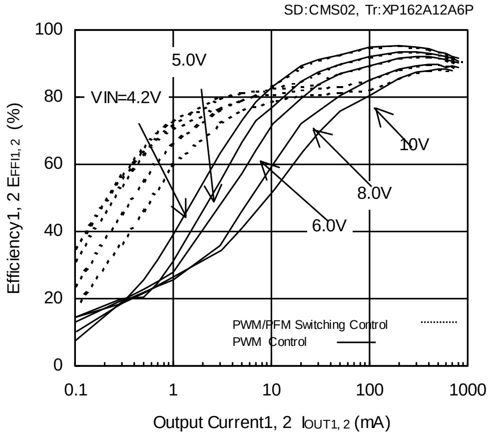
FOSC=180kHz, VOUT1, 2=1.0V

L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



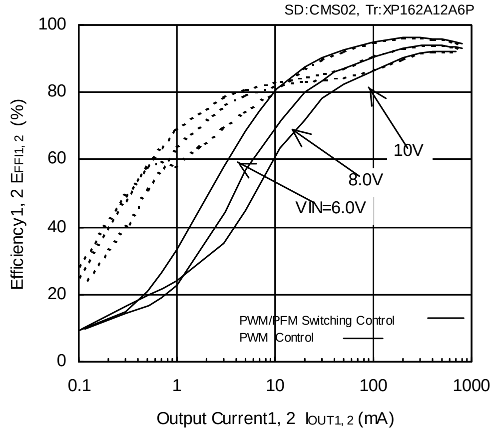
FOSC=180kHz, VOUT1, 2=3.3V

L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=180kHz, VOUT1, 2=5.0V

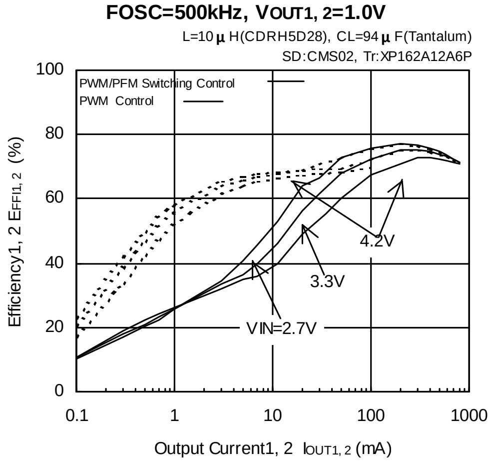
L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P

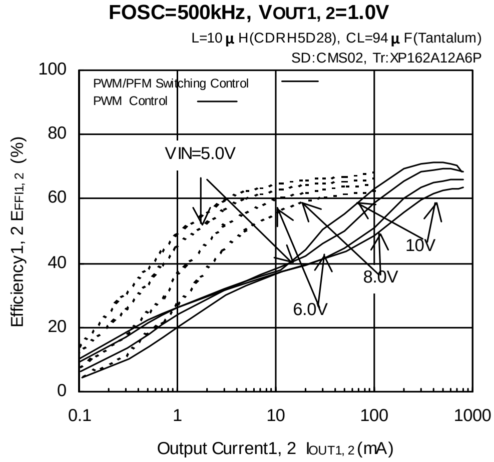


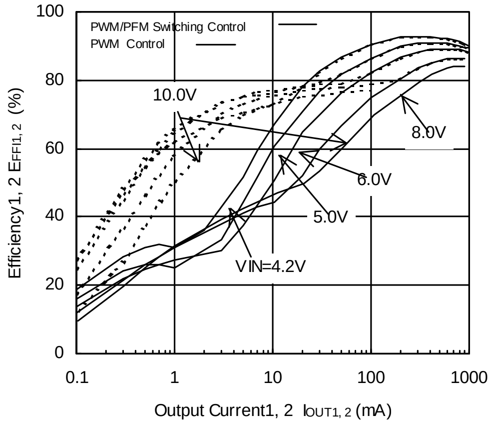
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94µF (Tantalum) + 100µF (OS-COM)

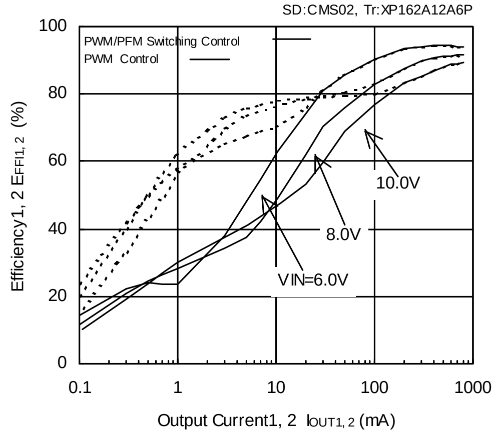
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(2) Efficiency vs. Output Current (Continued)





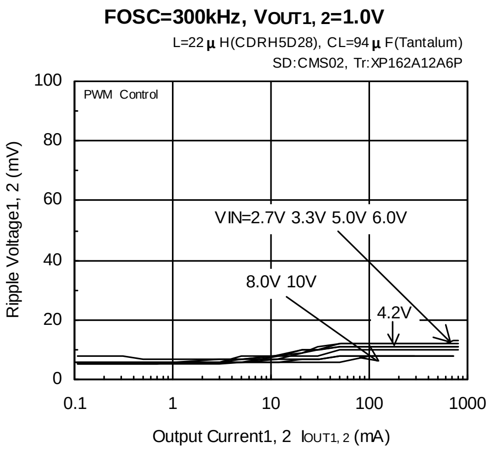


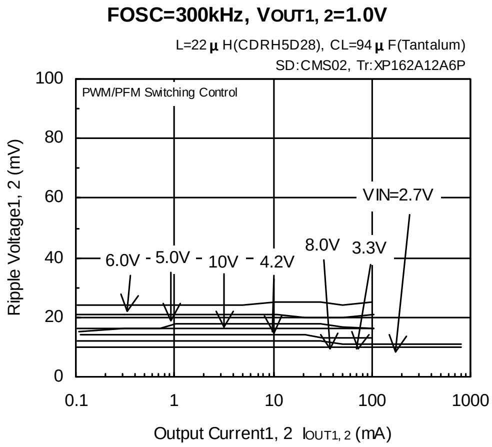


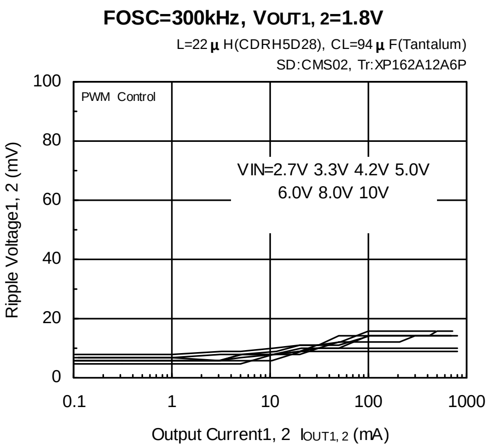
* When setting $V_{OUT1, 2}$ =1.0V, V_{IN}=8.0V, 10.0V,
C_L should be 94μF (Tantalum) + 100μF (OS-COM)

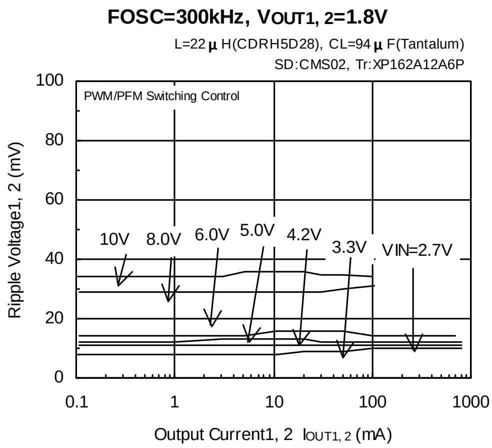
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

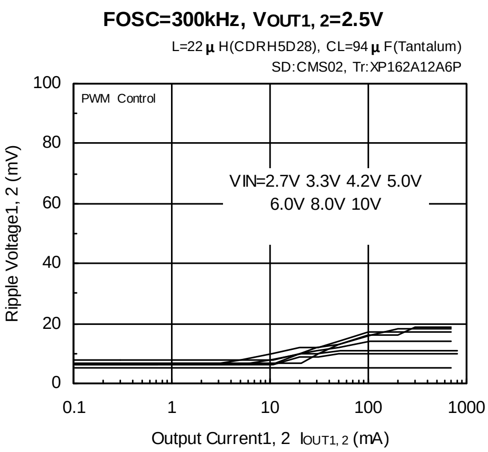
(3) Ripple Voltage vs. Output Current

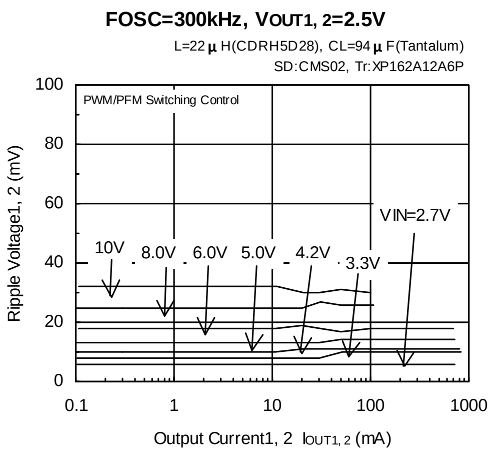












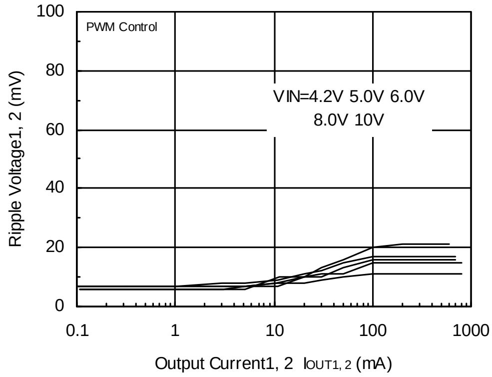
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(3) Ripple Voltage vs. Output Current (Continued)

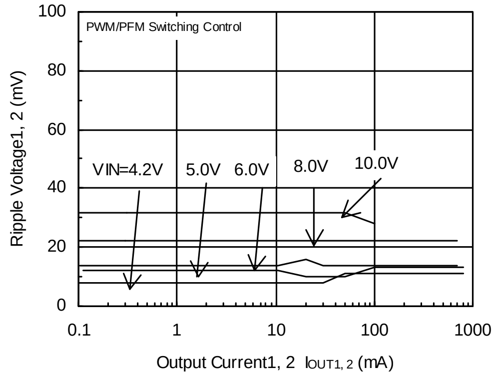
FOSC=300kHz, VOUT1, 2=3.3V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



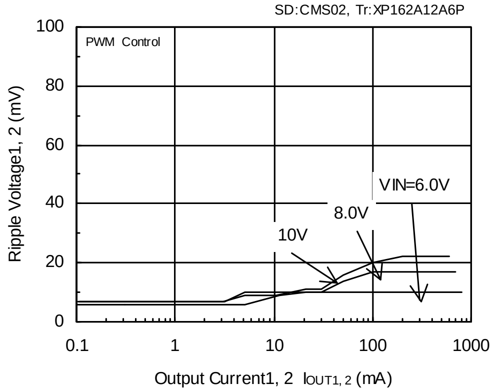
FOSC=300kHz, VOUT1, 2=3.3V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



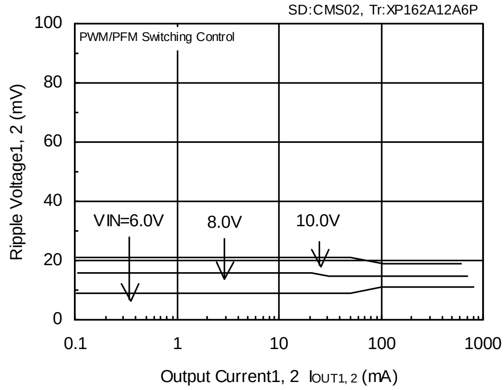
FOSC=300kHz, VOUT1, 2=5.0V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



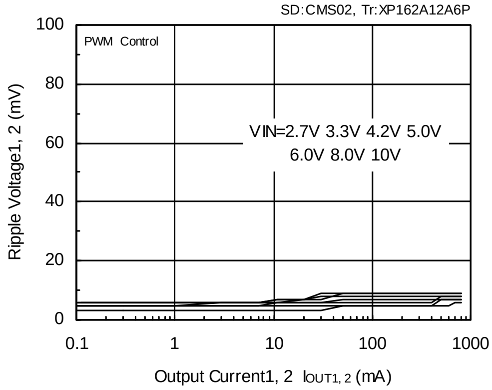
FOSC=300kHz, VOUT1, 2=5.0V

L=22µH(CDRH5D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



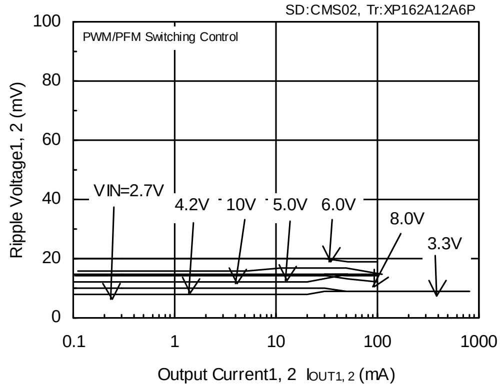
FOSC=180kHz, VOUT1, 2=1.0V

L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



FOSC=180kHz, VOUT1, 2=1.0V

L=47µH(CDRH6D28), CL=94µF(Tantalum)
SD:CMS02, Tr:XP162A12A6P

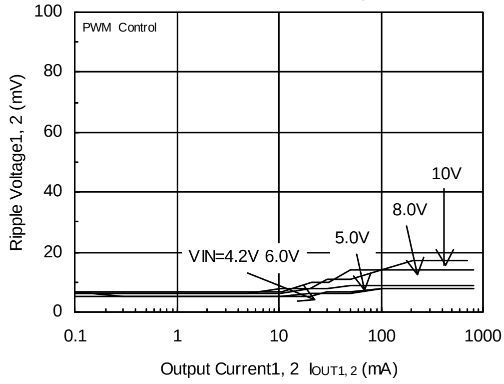


* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94µF (Tantalum) + 100µF (OS-COM)

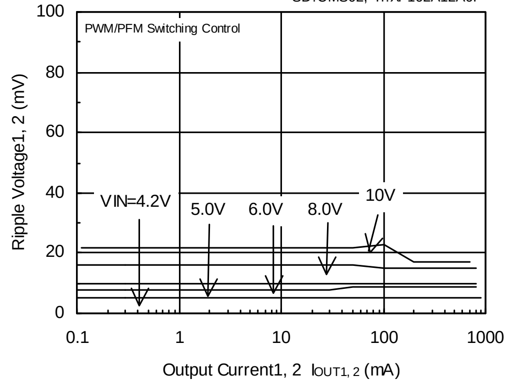
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(3) Ripple Voltage vs. Output Current (Continued)

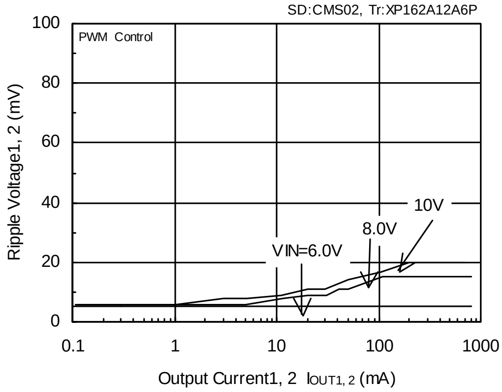
FOSC=180kHz, VOUT1, 2=3.3V
L=47μH(CDRH6D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



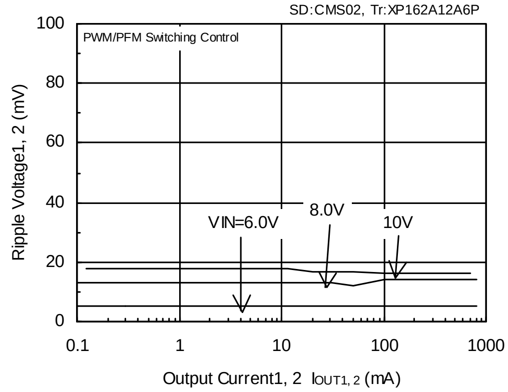
FOSC=180kHz, VOUT1, 2=3.3V
L=47μH(CDRH6D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



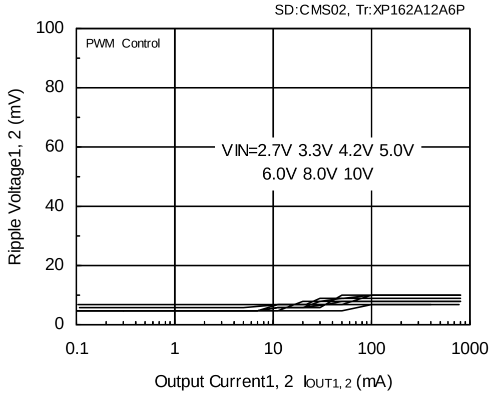
FOSC=180kHz, VOUT1, 2=5.0V
L=47μH(CDRH6D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



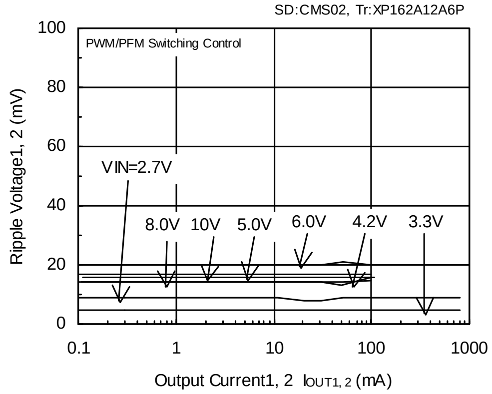
FOSC=180kHz, VOUT1, 2=5.0V
L=47μH(CDRH6D28), CL=94μF(Tantaium)
SD:CMS02, Tr:XP162A12A6P



FOSC=500kHz, VOUT1, 2=1.0V
L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P



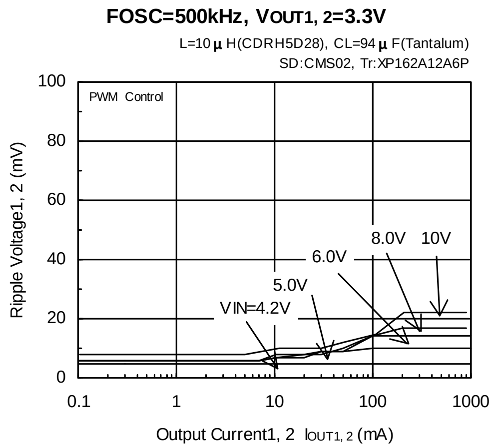
FOSC=500kHz, VOUT1, 2=1.0V
L=10μH(CDRH5D28), CL=94μF(Tantalum)
SD:CMS02, Tr:XP162A12A6P

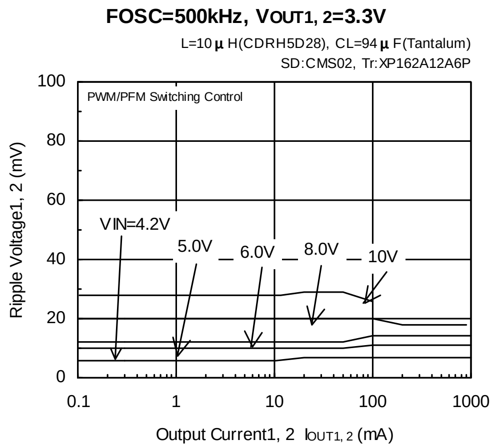


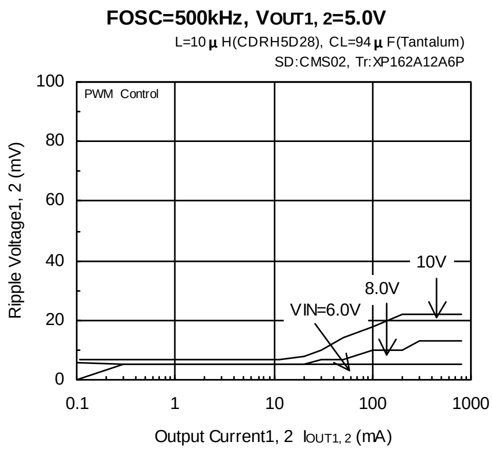
* When setting VOUT1, 2 =1.0V, VIN=8.0V, 10.0V,
CL should be 94μF (Tantalum) + 100μF (OS-COM)

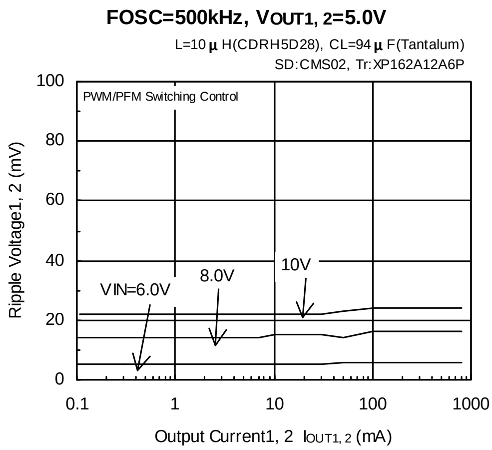
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(3) Ripple Voltage vs. Output Current (Continued)



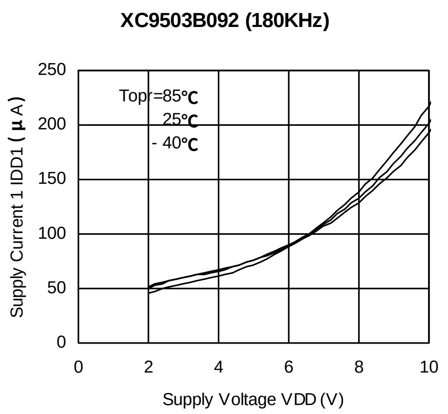




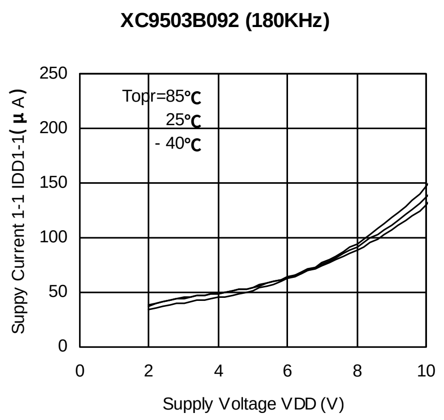


■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

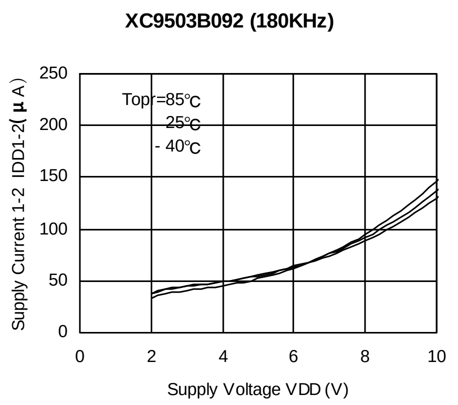
(4) Supply Current 1 vs. Supply Voltage



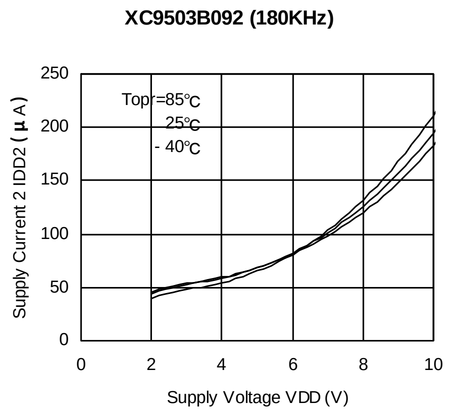
(5) Supply Current 1_1 vs. Supply Voltage



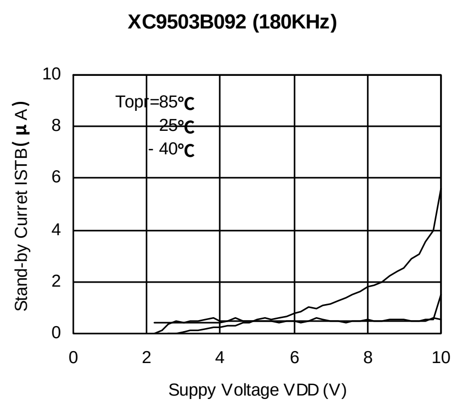
(6) Supply Current 1_2 vs. Supply Voltage



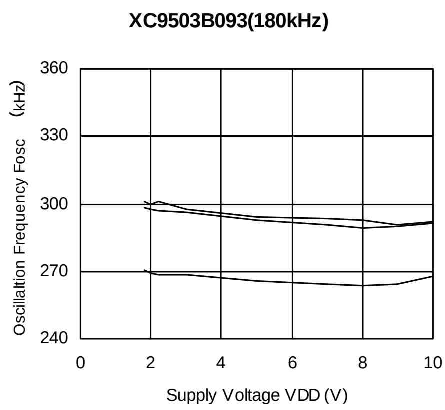
(7) Supply Current 2 vs. Supply Voltage



(8) Stand-by Current vs. Supply Voltage

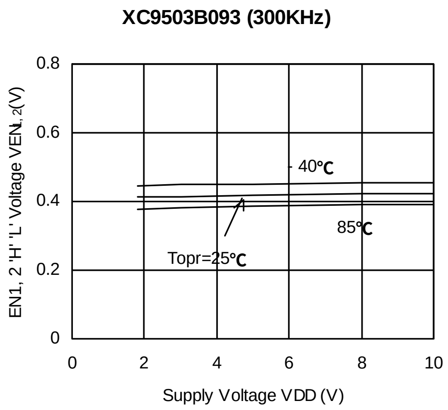


(9) Oscillation Frequency vs. Supply Voltage

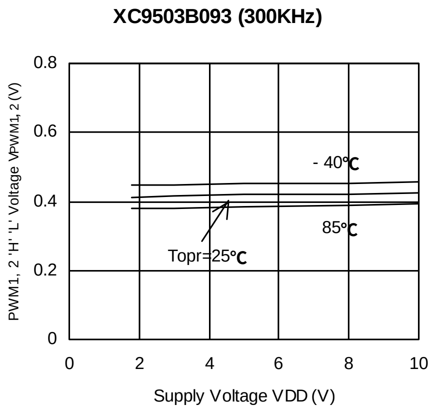


TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

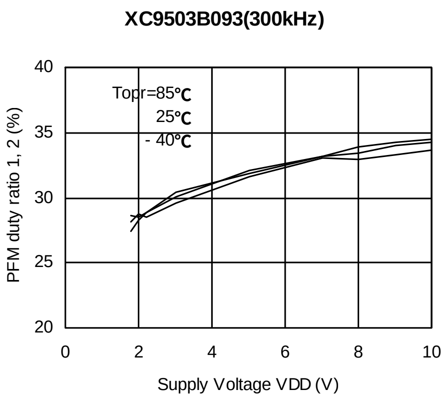
(10) EN1, 2 'High' 'Low' Voltage vs. Supply Voltage



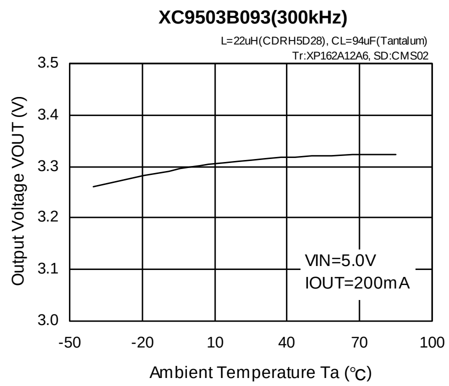
(11) PWM1, 2 'High' 'Low' Voltage vs. Supply Voltage



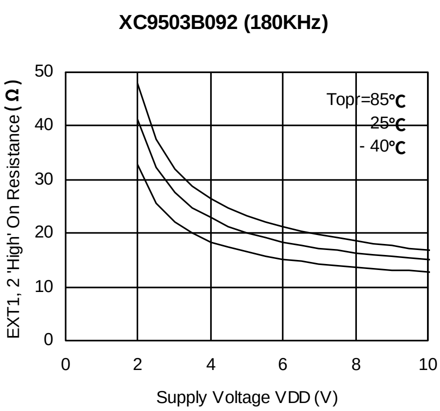
(12) PFM Duty Ratio 1, 2 vs. Supply Voltage



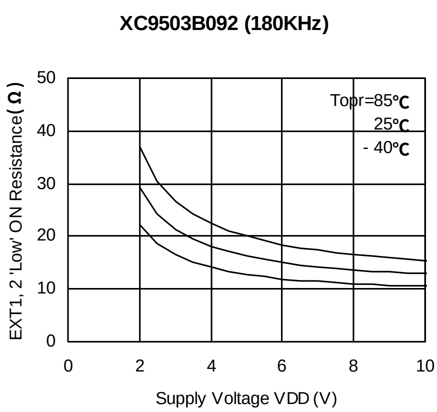
(13) Output Voltage vs. Ambient Temperature



(14) EXT1, 2 'High' On Resistance vs. Supply Voltage

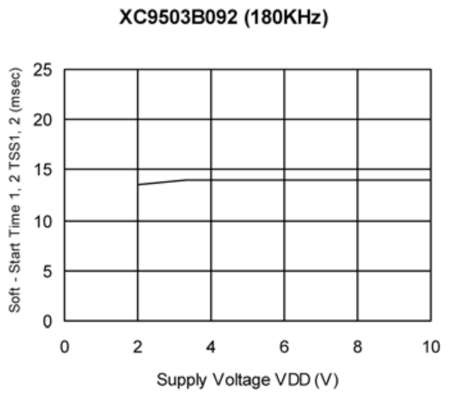


(15) EXT1, 2 'Low' On Resistance vs. Supply Voltage



■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(16) Soft-Start Time 1, 2 vs. Supply Voltage



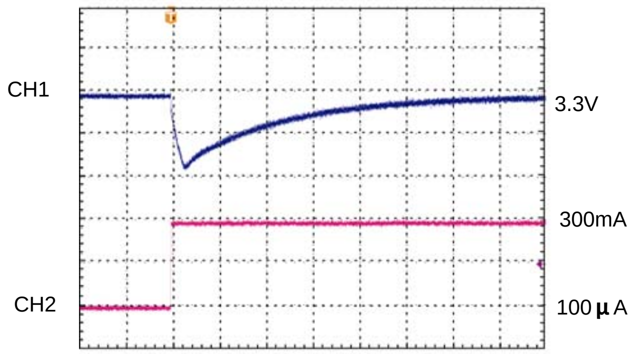
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(17) Load Transient Response

< $V_{OUT1,2}$ = 3.3 V, V_{IN} = 5.0V, $I_{OUT1,2}$ = 100 μA ⇔ 300mA >

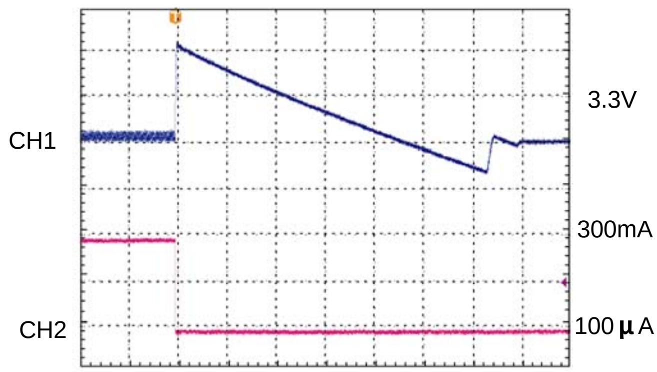
● PWM Control

FOSC = 300kHz, $V_{OUT1,2}$ = 3.3V
V_{IN} = 5.0V, $I_{OUT1,2}$ = 100 μA → 300mA



200 μsec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 100mV/div
CH2: $I_{OUT1,2}$, 150mA/div

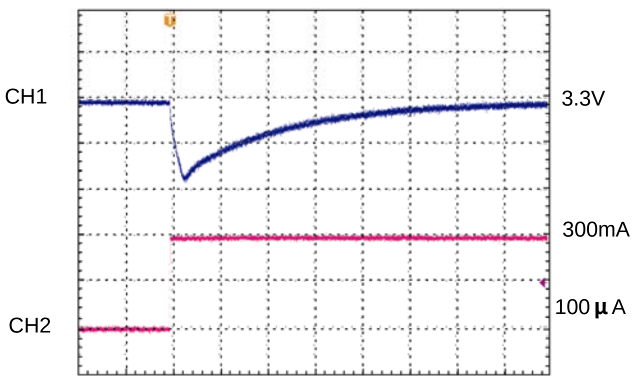
FOSC = 300kHz, $V_{OUT1,2}$ = 3.3V
V_{IN} = 5.0V, $I_{OUT1,2}$ = 300mA → 100 μA



10msec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 50mV/div
CH2: $I_{OUT1,2}$, 150mA/div

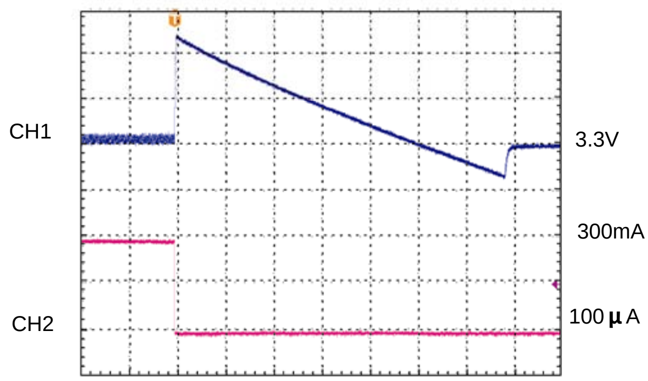
● PWM/PFM Switching Control

FOSC=300kHz, $V_{OUT1,2}$=3.3V
V_{IN}=5.0V, $I_{OUT1,2}$=100 μA→300mA



200 μsec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 100mV/div
CH2: $I_{OUT1,2}$, 1 50mA/div

FOSC=300kHz, $V_{OUT1,2}$=3.3V
V_{IN}=5.0V, $I_{OUT1,2}$=300mA→100 μA



10msec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 100mV/div
CH2: $I_{OUT1,2}$, 150mA/div

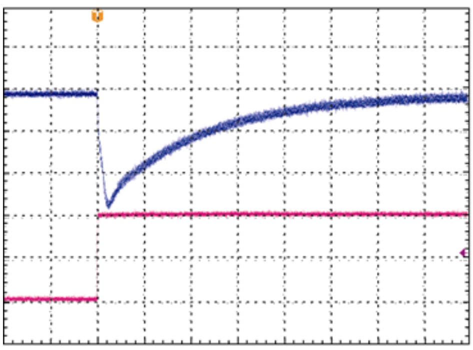
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(17) Load Transient Response (Continued)

< $V_{OUT1,\,2}$ = 3.3V, V_{IN} = 5.0V, $I_{OUT1,\,2}$ =10mA ⇔ 300mA >

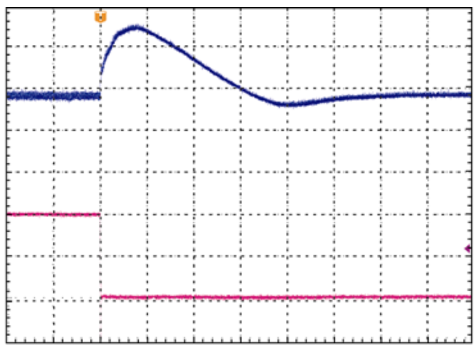
● PWM Control

FOSC=300kHz, $V_{OUT1,\,2}$ =3.3V
V_{IN}=5.0V, $I_{OUT1,\,2}$ =10mA→300mA



200µsec/div
CH1: $V_{OUT1,\,2}$, AC-COUPLED, 50mV/div
CH2: $I_{OUT1,\,2}$, 150mA/div

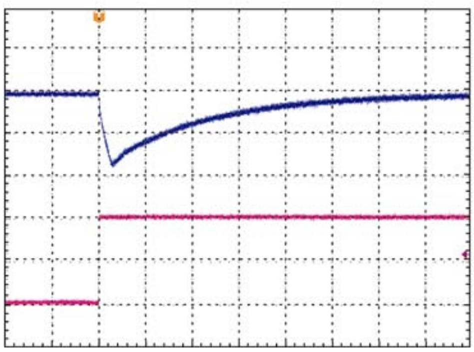
FOSC=300kHz, $V_{OUT1,\,2}$=3.3V
V_{IN}=5.0V, $I_{OUT1,\,2}$ =300mA→10mA



400µsec/div
CH1: $V_{OUT1,\,2}$, AC-COUPLED, 50mV/div
CH2: $I_{OUT1,\,2}$, 150mA/div

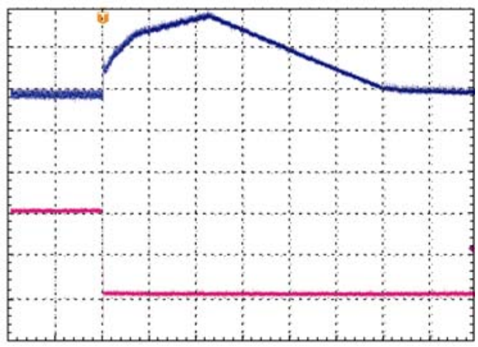
● PWM/PFM Switching Control

FOSC=300kHz, $V_{OUT1,\,2}$ =3.3V
V_{IN}=5.0V, $I_{OUT1,\,2}$ =10mA→300mA



200µsec/div
CH1: $V_{OUT1,\,2}$, AC-COUPLED, 100mV/div
CH2: $I_{OUT1,\,2}$, 150mA/div

FOSC=180kHz, V_{OUT1}=3.3V
V_{IN}=5.0V, $I_{OUT1,\,2}$ =300mA→10mA



200µsec/div
CH1: $V_{OUT1,\,2}$, AC-COUPLED, 50mV/div
CH2: $I_{OUT1,\,2}$, 150mA/div

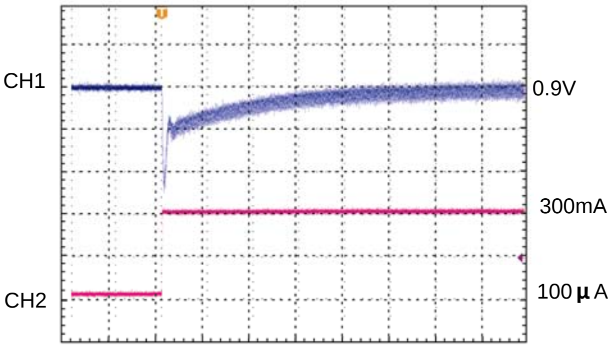
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(17) Load Transient Response (Continued)

< $V_{OUT1,2}$ = 0.9V, V_{IN} = 3.3V, $I_{OUT1,2}$ =100 μA ⇔ 300mA >

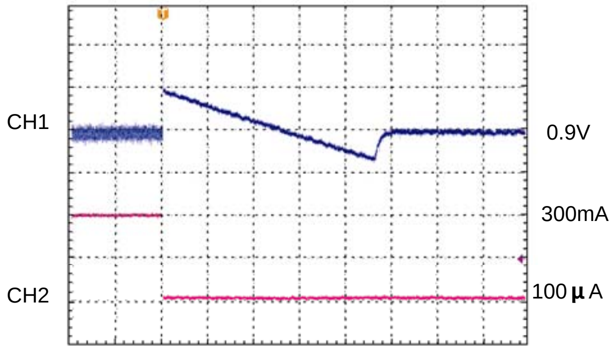
● PWM Control

FOSC=300kHz, $V_{OUT1,2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1,2}$ =100 μA→300mA



200 μsec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1,2}$, 150mA/div

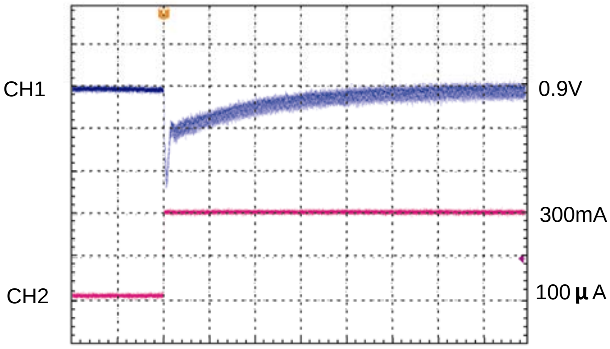
FOSC=300kHz, $V_{OUT1,2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1,2}$ =300mA→100 μA



4msec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1,2}$, 150mA/div

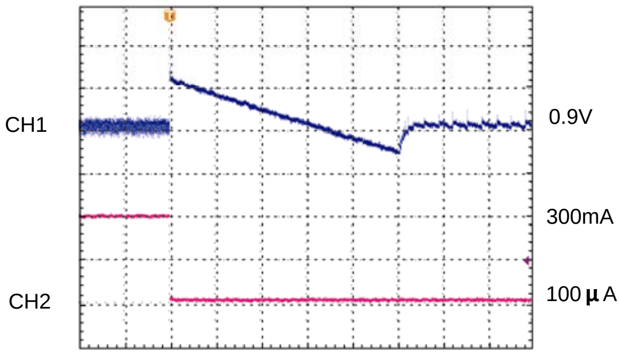
● PWM/PFM Switching Control

FOSC=300kHz, $V_{OUT1,2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1,2}$ =100 μA→300mA



200 μsec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1,2}$, 150mA/div

FOSC=300kHz, $V_{OUT1,2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1,2}$ =300mA→100 μA



200 μsec/div
CH1: $V_{OUT1,2}$, AC-COUPLED, 50mV/div
CH2: $I_{OUT1,2}$, 150mA/div

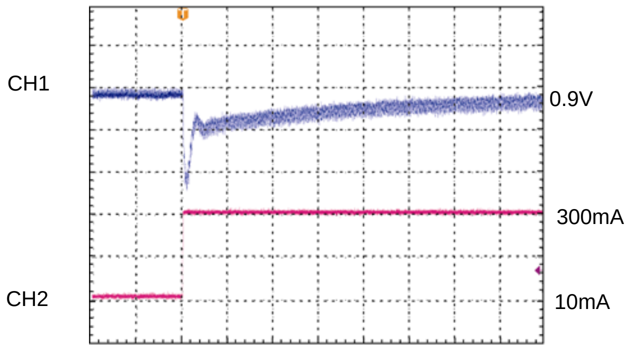
■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(17) Load Transient Response (Continued)

< $V_{OUT1, 2}$ = 0.9V, V_{IN} = 3.3V, $I_{OUT1, 2}$ =10mA ⇔ 300mA >

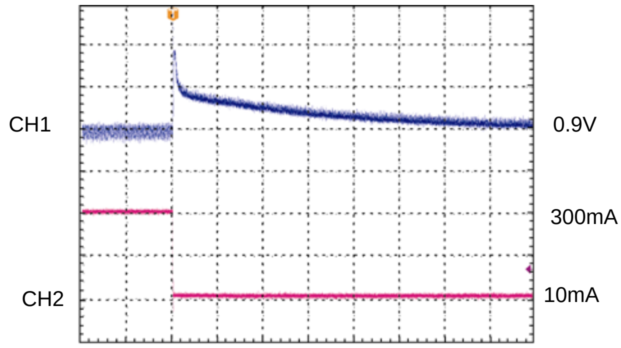
● PWM Control

FOSC=300kHz, $V_{OUT1, 2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1, 2}$ =10mA→300mA



100 µ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1, 2}$, 150mA/div

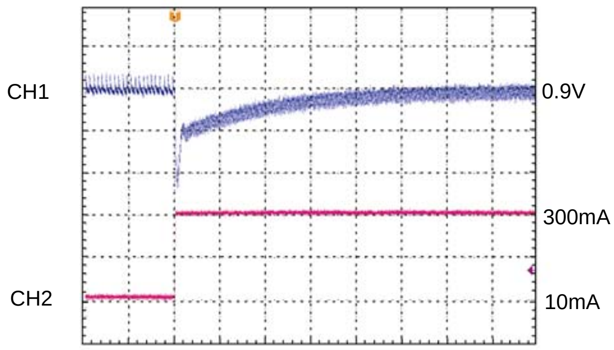
FOSC=300kHz, $V_{OUT1, 2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1, 2}$ =300mA→10mA



100 µ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1, 2}$, 150mA/div

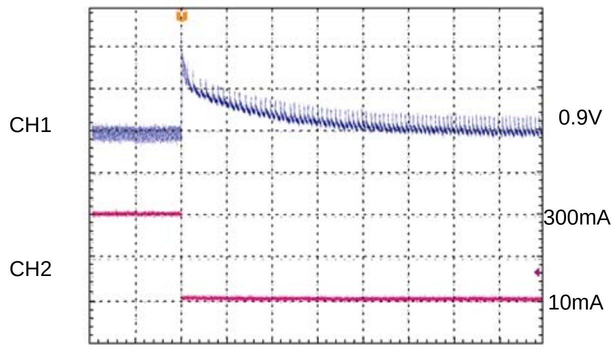
● PWM/PFM Switching Control

FOSC=300kHz, $V_{OUT1, 2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1, 2}$ =10mA→300mA



200 µ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1, 2}$, 150mA/div

FOSC=300kHz, $V_{OUT1, 2}$ =0.9V
V_{IN}=3.3V, $I_{OUT1, 2}$ =300mA→10mA



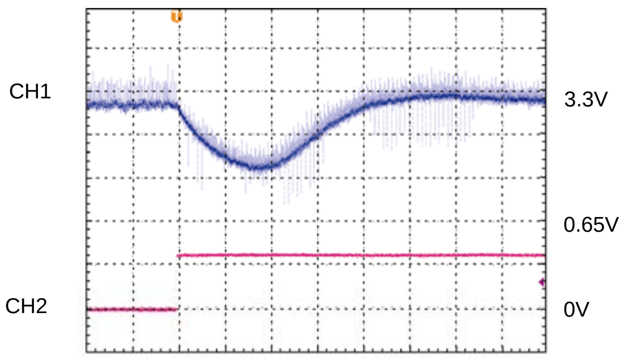
200 µ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1, 2}$, 150mA/div

■TYPICAL PERFORMANCE CHARACTERISTICS (Continued)

(17) Load Transient Response (Continued)

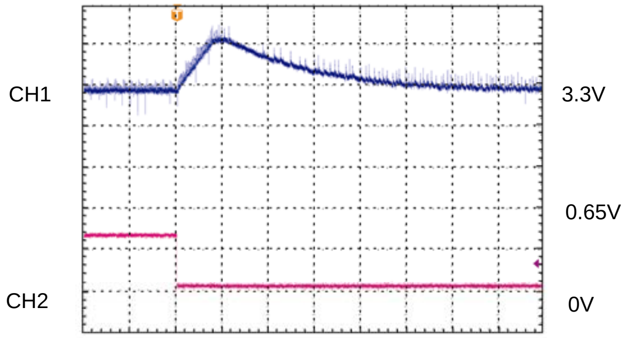
< PWM Control ⇔ PWM / PFM Switching Control >

FOSC=300kHz, $V_{OUT1, 2}$ =3.3V
V_{IN}=5.0V, $I_{OUT1, 2}$ =5mA, PWM1, 2 'Low'→'High'



400 μ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 10mV/div
CH2: $I_{OUT1, 2}$, 0.5V/div

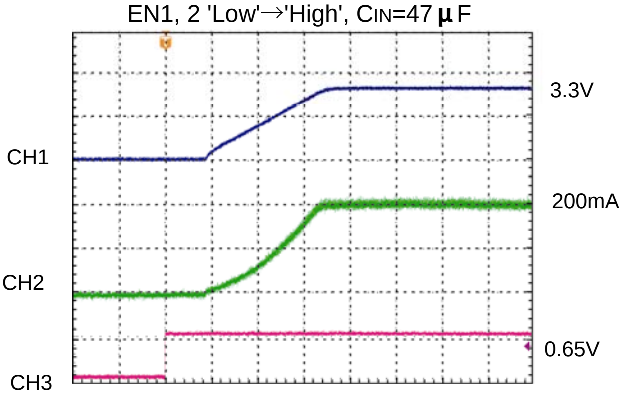
FOSC=300kHz, $V_{OUT1, 2}$ =3.3V
V_{IN}=5.0V, $I_{OUT1, 2}$ =5mA, PWM1, 2 'High'→'Low'



200 μ sec/div
CH1: $V_{OUT1, 2}$, AC-COUPLED, 20mV/div
CH2: $I_{OUT1, 2}$, 0.5V/div

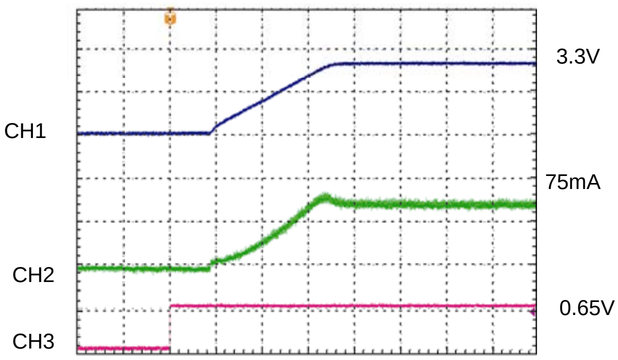
< Soft-Start Wave Form >

FOSC=300kHz, $V_{OUT1, 2}$ =3.3V
V_{IN} = 5.0V, I_{OUT}1, 2 = 300mA,
EN1, 2 'Low'→'High', C_{IN}=47 μ F



4msec/div
CH1: $V_{OUT1, 2}$, 2.0V/div
CH2: $I_{IN1, 2}$, 100mA/div
CH3: EN1, 2, 0.5V/div

FOSC=300kHz, $V_{OUT1, 2}$ =3.3V
V_{IN} = 5.0V, $I_{OUT1, 2}$ = 100mA,
EN1, 2 'Low'→'High', C_{IN}=47 μ F

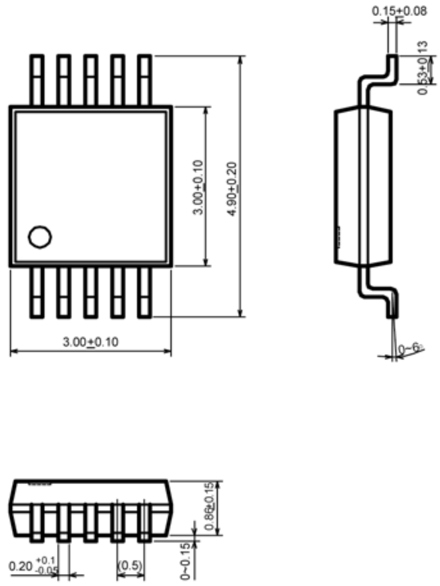


4msec/div
CH1: $V_{OUT1, 2}$, 2.0V/div
CH2: $I_{IN1, 2}$, 50mA/div
CH3: EN1, 2, 0.5V/div

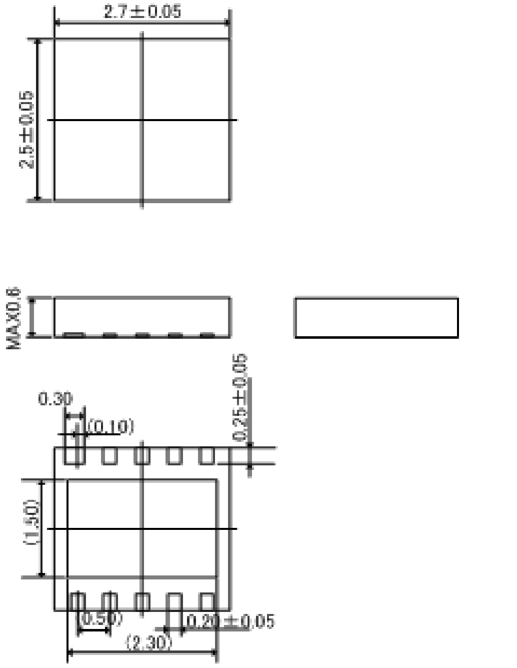
* CH1: EN2=GND when measurement
CH2: EN1=GND when measurement

PACKAGING INFORMATION

●MSOP-10 Unit : mm

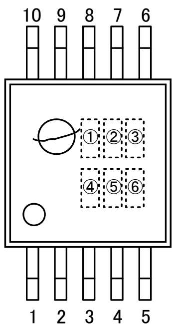


●USP-10 Unit : mm

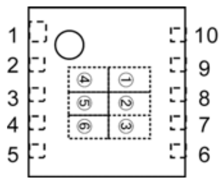


MARKING RULE

●MSOP-10, USP-10



MSOP-10
(TOP VIEW)



USP-10
(TOP VIEW)

① represents product series

MARK	PRODUCT SERIES
4	XC9503B09xxx

② represents type of DC/DC controller

MARK	PRODUCT SERIES
B	XC9503B09xxx

③, ④ represents FB voltage

MARK		VOLTAGE (V)	PRODUCT SERIES
③	④		
0	9	0.9	XC9503B09xxx

⑤ represents oscillation frequency

MARK	OSCILLATION FREQUENCY (kHz)	PRODUCT SERIES
2	180	XC9503B092xx
3	300	XC9503B093xx
5	500	XC9503B095xx

⑥ represents production lot number
0 to 9, A to Z repeated (G, I, J, O, Q, W excluded)
Note: No character inversion used.

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