

用户手册

[SBC-PH8800]

历史版本

Rev.	Note	Author
20160902	Initial	Sandy

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Release Note

1. 镜像版本

SBC-PH8800_Shipment_Image_SDCard_REV01.img

SBC-PH8800_Shipment_Image_EMMC_Rev01.img

2. 功能列表

SBC-PH8800				
Feature List	Schematic Page#	On-Chip Peripherals	On-Board Peripherals	Detail Functions(existing)
u-boot version	2015.09			Supports kernel boot
kernel version	4.1.6			Supports all below functionality
Filesystem	Debian			Default root file system used by debian
CPU	PH8800-U11	AM437X_ZDN		Null
DDRAM	PH8800-p7-u12/u7	DDR	MT41K256M16HA-125	Can access read write and run code
PMIC	PH8800-p3-u13	I2C0	TPS65218	Null
MicroSD_(TF)	SPH1800-P6-TF1	MMC0	Null	Can access read write and boot
External-RTC	SPH1800-P9-U55	I2C0	RX-8025TUB	can read write and keep time off power
Integrited-RTC	PH8800-u11	RTC	Null	can read write and keep time off power
LEDs	PH8800-p10-D3/D	gpio	Null	System can control LED to light or not
Power-Button	PH1800-P14-S2	I2C0	TPS65218	Can get key value
LCD	SPH1800-P9-J9	RGB	Null	Can show picture on the screen
Backlight	SPH1800-P9-J9	PWM	Null	System can control the LCD backlight
TouchScreen	SPH1800-P9-J9	ADC-TSC	Null	System use touchscreen
eMMC	PH8800-p8-u14	MMC1	MTFC4GACAAAM-4M	Can access read write
EEPROM	PH8800-p8-u6	I2C0	CAT24C256W	Can access read write
SPI-FLASH	PH8800-p8-u3	QSPI	N25Q256A13EF840	1. Boot from SPI-Flash

CAN-1	SPH1800-p8-J61	CAN1	MC33901WEF	System can send and receive data between two board
CAN-2	SPH1800-p8-J61	CAN0	MC33901WEF	System can send and receive data between two board
UART-0	SPH1800-p7-CN4	UART0	NULL	System can send and receive data in loopback mode
UART-1	SPH1800-p7-J4	UART5	MAX3232CUE+	System can send and receive data in loopback mode
UART-2	SPH1800-p13-J58	UART3	Null	System can send and receive data in loopback mode
UART-4	SPH1800-p13-J58	UART1	MAX3232CUE+	System can send and receive data in loopback mode
RS485-2	SPH1800-p8-u5	SPI0	SC16IS752IPW	System can send and receive data between two board
RS485-3	SPH1800-p8-u5	SPI0	SC16IS752IPW	System can send and receive data between two board
USB-Host	SPH1800-p11-p3	USB1	Null	Can recognize U disk by USB host
CAMERA	SPH1800-p9j8	CSI&I2C1	Null	Could preview, take picture and record video
USB-OTG	SPH1800-p11-j13	USB0	Null	Can recognize U disk in host mode, and can work as usb ethernet in device mode
Ethernet-1	PH8800-P9-U9	RGMII1	KSZ9031RNXIA	Can ping the server
Ethernet-2	SPH1800-P12-J17	RGMII2	AR8035	Can ping the server
HDMI	SPH1800-P10-U34	I2C0	TDA19988BHN/C1,551	Can show picture on the screen
Audio	SPH1800-P10-U34	I2C0	TDA19988BHN/C1,551	can play wav

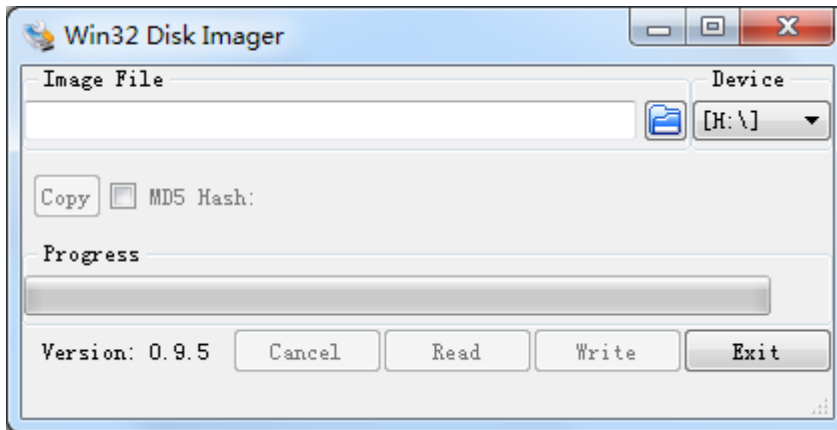
3. 已知问题

Known issue List	Detail
SPI-FLASH	Not Support: SPI-Flash access in kernel
Ethernet-1 & Ethernet-2	Bug: Board to board connect under high or low temperature environment could not working normally
LCD	Bug:4.3 inch Screen turn white for a while in boot
HDMI Audio	Not support Sony HDMI displayer

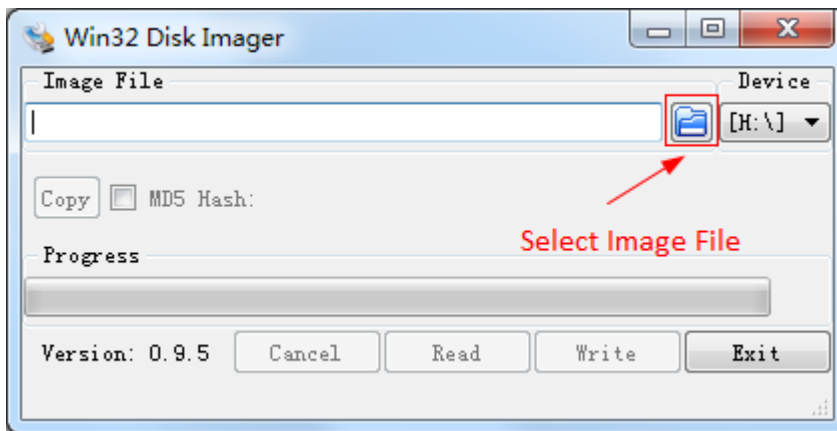
第1章 快速启动

1.1 烧写镜像到 SD 卡

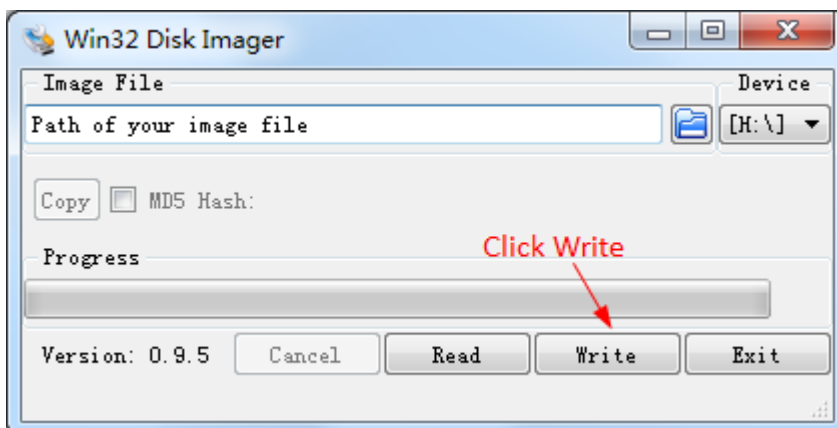
- 首先，你需要准备一张不小于 2G 的 SD 卡
- 然后，你需要从 <https://sourceforge.net/projects/win32diskimager/> 下载并安装 Win32 Disk Imager



- 选择需要烧写的镜像，SBC-PH8800_Shipment_Image_SDCard_Rev01.img:



- 点击 Write 烧写镜像:



1.2 从 SD 卡启动系统

- 在 PC 上安装串口软件（例如 SecureCRT），选择正确的端口号，波特率 115200，8 位数据位，1 位停止位，无奇偶校验
- 用 USB 转 TTL 模块把板子上的 DEBUG 接口(CN4)和 PC 相连
- 把 Micro SD 卡插入板上的插槽 TF1
- 按下按键 S3，用 5V,2A 的电源，给板子供电(J1)，上电复位后松开 S3
- 系统启动完毕之后，串口显示如下

```
[ 7.409917] systemd[1]: starting Journal Service...
[ 7.426561] systemd[1]: Started Journal Service.
[ 7.599897] systemd-udevd[163]: starting version 215
[ 8.102171] systemd-journald[162]: Received request to flush runtime journal from PID 1
[ 8.201122] remoteproc0: failed to load am335x-pm-firmware.elf
[ 8.237170] remoteproc0: powering up wkup_m3
[ 8.262756] remoteproc0: Direct firmware load for am335x-pm-firmware.elf failed with error -2
[ 8.344518] remoteproc0: Falling back to user helper
[ 9.573464] remoteproc0: request_firmware failed: -11
[ 9.580114] remoteproc0: rproc_boot failed
[10.134627] net eth0: initializing cpsw version 1.15 (0)
[10.222955] net eth0: phy found : id is : 0x221622
[10.754600] net eth1: initializing cpsw version 1.15 (0)
[10.842988] net eth1: phy found : id is : 0x4dd072
[11.409176] net can0: c_can_hw_raminit_wait_syscon: time out
[11.491746] c_can_platform 481cc000.can can0: bit-timing not yet defined
[11.553953] c_can_platform 481cc000.can can0: failed to open can device
[11.616721] net can1: c_can_hw_raminit_wait_syscon: time out
[11.710230] c_can_platform 481d0000.can can1: bit-timing not yet defined
[11.745757] c_can_platform 481d0000.can can1: failed to open can device
[12.276336] FAT-fs (mmcblk0p1): volume was not properly unmounted. some data may be corrupt. Please run fsck.
```

```
Debian GNU/Linux 8 embest ttyS0
```

```
www.embest-tech.com
```

```
default username:password is [root:root]
```

```
embest login:
```

输入用户名和密码 root 登录;

```
Debian GNU/Linux 8 embest ttyS0
```

```
www.embest-tech.com
```

```
default username:password is [root:root]
```

```
embest login: root
```

```
Password:
```

```
Linux embest 4.1.6 #1 PREEMPT Tue Sep 27 12:00:43 CST 2016 armv7l
```

```
The programs included with the Debian GNU/Linux system are free software;
the exact distribution terms for each program are described in the
individual files in /usr/share/doc/*/copyright.
```

```
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent
permitted by applicable law.
```

```
root@embest:~#
```


1.3 从 SPI Flash 启动

参考 [1.2](#)，先从 SD 卡启动，终端中打印如下信息时，按“回车键”进入 uboot:

```
U-Boot SPL 2015.07 (Sep 27 2016 - 11:42:48)
```

```
SPL: Please implement spl_start_uboot() for your board
```

```
SPL: Direct Linux boot not active!
```

```
reading u-boot.img
```

```
reading u-boot.img
```

```
U-Boot 2015.07 (Sep 27 2016 - 11:42:48 +0800)
```

```
I2C: ready
```

```
DRAM: 1 GiB
```

```
PMIC: TPS65218
```

```
MMC: OMAP SD/MMC: 0, OMAP SD/MMC: 1
```

```
reading uboot.env
```

```
** Unable to read "uboot.env" from mmc0:1 **
```

```
Using default environment
```

```
Net: <ethaddr> not set. Validating first E-fuse MAC
```

```
cpsw, usb_ether
```

```
Hit any key to stop autoboot: 0
```

```
U-Boot#
```

（按下 Enter 键）

在终端中执行以下命令:

```
U-Boot# run update_qspi_flash
```

```
switch to partitions #0, OK
```

```
mmc0 is current device
```

```
SD/MMC found on device
```

```
reading u-boot-spl.bin
```

```
56904 bytes read in 6 ms (9 MiB/s)
```

```
SF: Detected N25Q256 with page size 256 Bytes, erase size 4 KiB, total 32 MiB, mapped at 30000000
```

```
SF: 589824 bytes @ 0x0 Erased: OK
```

```
device 0 offset 0x0, size 0xde48
```

```
SF: 56904 bytes @ 0x0 Written: OK
```

```
reading u-boot.bin
```

```
288632 bytes read in 17 ms (16.2 MiB/s)
```

```
device 0 offset 0x20000, size 0x46778
```

```
SF: 288632 bytes @ 0x20000 Written: OK
```

```
U-Boot#
```

输入下列命令从 SD 卡启动系统:

```
U-Boot# boot
```

将 SBC-PH8800_Shipment_Image_EMMC_Rev01.img 拷贝到 U 盘, 将 U 盘插入 USB 接口 (P3):

```
root@embest:~# ls /dev/sd*
```

```
/dev/sda /dev/sda1
```

```
root@embest:~# mount /dev/sda1 /mnt/
```

```
root@embest:~# dd if=/mnt/SBC-PH8800_Shipment_Image_EMMC_Rev01.img of=/dev/mmcblk1
```

注意: 烧写时间较长, 请耐心等待...

烧写结束后, 上电复位并启动系统 (不用按 S3)

第2章 功能测试

首先, 请参考[第一章 1.1](#), 把系统启动起来. 然后跟随下面的指引测试各项功能.

2.1 LED 测试

用户能够控制 SOM-PH8800 上的 LED (D3,D4) 指示灯。在终端中执行以下命令来进行测试; (其中 D3 对应 user_leds_d3, D4 对应 user_leds_d4)

熄灭 LED:

```
root@embest:~# echo 0 > /sys/class/leds/user_leds_d3/brightness
```

```
root@embest:~# echo 0 > /sys/class/leds/user_leds_d4/brightness
```

点亮 LED:

```
root@embest:~# echo 1 > /sys/class/leds/user_leds_d3/brightness
```

```
root@embest:~# echo 1 > /sys/class/leds/user_leds_d4/brightness
```

2.2 RTC 测试

在串口终端输入:

查看当前时间:

```
root@embest:~# date
```

```
Sat Jan 1 00:02:07 UTC 2000
```

设置时间 2016 年 3 月 9 日 10 时 46 分:

```
root@embest:~# date 030910462016
```

```
Wed Mar 9 10:46:00 UTC 2016
```

把系统时钟写入 RTC:

```
root@embest:~# hwclock -w
```

读取 RTC:

```
root@embest:~# hwclock
```

```
Wed 09 Mar 2016 10:46:23 AM UTC -0.432561 seconds
```

可以看到, 硬件时钟 RTC 被设置成 2016 年 3 月 9 日, 系统时钟被保存到硬件时钟里。

重启系统并查看时间:

```
root@embest:~# date
```

```
Wed Mar 9 10:46:45 UTC 2016
```

2.3 EEPROM 测试

在串口终端输入以下命令：

```
root@embest:~# ./eeprom_test
```

```
data will write to EEPROM at 0x400
```

```
00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f  
10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f  
20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f  
30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f  
40 41 42 43 44 45 46 47 48 49 4a 4b 4c 4d 4e 4f  
50 51 52 53 54 55 56 57 58 59 5a 5b 5c 5d 5e 5f  
60 61 62 63 64 65 66 67 68 69 6a 6b 6c 6d 6e 6f  
70 71 72 73 74 75 76 77 78 79 7a 7b 7c 7d 7e 7f  
80 81 82 83 84 85 86 87 88 89 8a 8b 8c 8d 8e 8f  
90 91 92 93 94 95 96 97 98 99 9a 9b 9c 9d 9e 9f  
a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 aa ab ac ad ae af  
b0 b1 b2 b3 b4 b5 b6 b7 b8 b9 ba bb bc bd be bf  
c0 c1 c2 c3 c4 c5 c6 c7 c8 c9 ca cb cc cd ce cf  
d0 d1 d2 d3 d4 d5 d6 d7 d8 d9 da db dc dd de df  
e0 e1 e2 e3 e4 e5 e6 e7 e8 e9 ea eb ec ed ee ef  
f0 f1 f2 f3 f4 f5 f6 f7 f8 f9 fa fb fc fd fe ff
```

```
data read from EEPROM at 0x400
```

```
00 01 02 03 04 05 06 07 08 09 0a 0b 0c 0d 0e 0f  
10 11 12 13 14 15 16 17 18 19 1a 1b 1c 1d 1e 1f  
20 21 22 23 24 25 26 27 28 29 2a 2b 2c 2d 2e 2f  
30 31 32 33 34 35 36 37 38 39 3a 3b 3c 3d 3e 3f  
40 41 42 43 44 45 46 47 48 49 4a 4b 4c 4d 4e 4f  
50 51 52 53 54 55 56 57 58 59 5a 5b 5c 5d 5e 5f  
60 61 62 63 64 65 66 67 68 69 6a 6b 6c 6d 6e 6f  
70 71 72 73 74 75 76 77 78 79 7a 7b 7c 7d 7e 7f  
80 81 82 83 84 85 86 87 88 89 8a 8b 8c 8d 8e 8f  
90 91 92 93 94 95 96 97 98 99 9a 9b 9c 9d 9e 9f  
a0 a1 a2 a3 a4 a5 a6 a7 a8 a9 aa ab ac ad ae af  
b0 b1 b2 b3 b4 b5 b6 b7 b8 b9 ba bb bc bd be bf  
c0 c1 c2 c3 c4 c5 c6 c7 c8 c9 ca cb cc cd ce cf  
d0 d1 d2 d3 d4 d5 d6 d7 d8 d9 da db dc dd de df
```

```
e0 e1 e2 e3 e4 e5 e6 e7 e8 e9 ea eb ec ed ee ef
f0 f1 f2 f3 f4 f5 f6 f7 f8 f9 fa fb fc fd fe ff
```

写数据与读到的数据相同，测试通过；

2.4 EMMC 测试

在串口终端执行：

```
root@embest:~# touch emmc_read emmc_write
```

编辑 emmc_write:

```
root@embest:~# vi emmc_write
```

例如写入 “emmc write test”

写 emmc 命令：

```
root@embest:~# dd if=emmc_write of=/dev/mmcblk1
```

```
[ 929.393325] mmcblk1: p1 p2
```

```
0+1 records in
```

```
0+1 records out
```

```
17 bytes (17 B) copied, 0.135215 s, 0.1 kB/s
```

读 emmc 命令：

```
root@embest:~# dd if=/dev/mmcblk1 of=emmc_read bs=1K count=10
```

```
10+0 records in
```

```
10+0 records out
```

```
10240 bytes (10 kB) copied, 0.00446492 s, 2.3 MB/s
```

查看 emmc_read:

```
root@embest:~# cat emmc_read
```

```
emmc write test
```

测试成功；

2.5 ADC 测试

在串口终端输入以下命令，采样值返回：

```
root@embest:~# cat /sys/bus/platform/devices/TI-am335x-adc/iio\:device0/in_voltage4_raw
603
```

```
root@embest:~# cat /sys/bus/platform/devices/TI-am335x-adc/iio\:device0/in_voltage5_raw
599
```

```
root@embest:~# cat /sys/bus/platform/devices/TI-am335x-adc/iio\:device0/in_voltage6_raw
767
```

```
root@embest:~# cat /sys/bus/platform/devices/TI-am335x-adc/iio\:device0/in_voltage7_raw
847
```

2.6 HDMI 测试

打开 SD 卡中 uEnv.txt 文件，修改 fdtfile=embest-SOM_PH8800-BB_SPH1800-HDMI.dtb
用 HDMI 数据线相连接显示设备并重新启动系统；

2.7 HDMI AUDIO 测试

连接 HDMI 设备，执行以下命令播放默认音频文件

```
root@embest:~# aplay /boot/firmware/audio_sample.wav
```

```
Playing WAVE '/boot/firmware/audio_sample.wav' : Signed 16 bit Little Endian, Rate 22050 Hz, Stereo
```

2.8 LCD 测试

4.3 寸屏：

打开 SD 卡中 uEnv.txt 文件，修改 fdtfile= embest-SOM_PH8800-BB_SPH1800-4.3inch_LCD.dtb
连接显示屏到 J9，重新启动系统

7 寸屏：

打开 SD 卡中 uEnv.txt 文件，修改 fdtfile= embest-SOM_PH8800-BB_SPH1800-7inch_LCD.dtb
连接显示屏到 J9，重新启动系统

2.9 背光测试

背光的亮度设置范围为（1—8），1 表示亮度最低，8 表示亮度最高，在串口终端下输入如下命令进行背光测试：

最暗：

```
root@embest:~# echo 1 > /sys/class/backlight/backlight/brightness
```

最亮：

```
root@embest:~# echo 8 > /sys/class/backlight/backlight/brightness
```

2.10 触摸屏测试

连接显示屏到 J9,在串口终端输入以下命令执行触摸屏校准程序：

```
root@embest:~# ts_calibrate
```

按照屏幕上提示，点击 “+” 图标 5 次完成校准。

2.11 串口测试

开发板上有 4 个串口，其中 UART0(CN4)为 debug 接口

2.11.1 UART1

短接 J4 第 2, 3 号接口:

```
root@embest:~# ./uart_test -d /dev/ttyS5 -b 115200
```

```
/dev/ttyS5 SEND: 1234567890
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 1
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 2
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 3
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 4
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 5
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 6
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 7
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 8
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 9
```

```
/dev/ttyS5 RECV 1 total
```

```
/dev/ttyS5 RECV: 0
```

注意: Ctrl+C 中断串口测试

2.11.2 UART2

短接 J58 第 16, 17 号接口:

```
root@embest:~# ./uart_test -d /dev/ttyS3 -b 9600
```

```
/dev/ttyS3 SEND: 1234567890
```

```
/dev/ttyS3 RECV 1 total
```

```
/dev/ttyS3 RECV: 1
```

```
/dev/ttyS3 RECV 1 total
```

```
/dev/ttyS3 RECV: 2
```

```
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 3
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 4
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 5
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 6
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 7
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 8
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 9
/dev/ttyS3 RECV 1 total
/dev/ttyS3 RECV: 0
```

注意：Ctrl+C 中断串口测试

2.11.3 UART4

短接 J58 第 14, 15 号接口:

```
root@embest:~# ./uart_test -d /dev/ttyS1 -b 9600
/dev/ttyS1 SEND: 1234567890
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 1
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 2
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 3
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 4
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 5
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 6
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 7
/dev/ttyS1 RECV 1 total
/dev/ttyS1 RECV: 8
```



```
/dev/ttyS1 RECV 1 total
```

```
/dev/ttyS1 RECV: 9
```

```
/dev/ttyS1 RECV 1 total
```

```
/dev/ttyS1 RECV: 0
```

注意: Ctrl+C 中断串口测试

2.12 RS485 测试

2.12.1 RS485-2 和 RS485-3

分别短接 J62 的 7, 9 号引脚; 8, 10 号引脚(即 RS485-A3 TO RS485-A2, RS485-B3 to RS485-B2):
串口终端输入如下命令 (在后台运行):

```
root@embest:~# ./uart_test -d /dev/ttySC1 -b 9600 -s "a" &
```

接着输入:

```
root@embest:~# ./uart_test -d /dev/ttySC0 -b 9600 -s "c"
```

```
/dev/ttySC0 SEND: c
```

```
/dev/ttySC1 RECV 1 total
```

```
/dev/ttySC1 RECV: c
```

```
/dev/ttySC1 SEND: a
```

```
/dev/ttySC0 RECV 1 total
```

```
/dev/ttySC0 RECV: a
```

ttySC0, ttySC1 分别发送数据, 并能接收数据;

2.13 CAN 测试

SBC-PH8800 上有两个 CAN, 可以用自身的 CAN0 和 CAN1 进行测试。连接 J62 的 1,3 引脚, 2, 4 引脚测试方法如下:

1. 打开 can0 can1

```
root@embest:~# ip link set can0 type can bitrate 50000 triple-sampling on
```

```
root@embest:~# ip link set can1 type can bitrate 50000 triple-sampling on
```

```
root@embest:~# ip link set can0 up
```

```
[ 116.797032] c_can_platform 481cc000.can can0: setting BTR=1c1d BRPE=0000
```

```
root@embest:~# ip link set can1 up
```

```
[ 116.860898] c_can_platform 481d0000.can can1: setting BTR=1c1d BRPE=0000
```

2. 收发数据

can1 接收, can0 往 can1 发数据

```
root@embest:~# candump can1&
```

```
root@embest:~# cansend can0 123#01020304050607
```

```
root@embest:~# can1 123 [7] 01 02 03 04 05 06 07
```

用 ps 和 kill 命令关闭 candump, 换成 can0 接收, can1 往 can0 发数据

```
root@embest:~# candump can0&
```

```
root@embest:~# cansend can1 123#11121314151617
```

```
root@embest:~# can0 123 [7] 11 12 13 14 15 16 17
```

3. 测试完毕关闭设备

```
root@embest:~# ip link set can0 down
```

```
read: Network is down
```

```
root@embest:~# [ 409.786888] c_can_platform 481cc000.can can0: setting BTR=1c1d BRPE=0000
```

```
root@embest:~# ip link set can1 down
```

```
[ 415.503272] c_can_platform 481d0000.can can1: setting BTR=1c1d BRPE=0000
```

```
[2]+ Exit 1 candump can0
```

用户可以根据以上命令进行相互收发测试, 还可以设置不同的波特率进行通信, 在设置不同波特率之前必须先关闭设备, 可设置的波特率有:

25KBPS (250000)

50KBPS (50000)

125KBPS (125000)

500KBPS (500000)

650KBPS (650000)

1MKBPS (1000000)

以上的波特率均能正常通信, 还有其它波特率可以设置, 用户可以自己尝试, 看能否通信。另外也可以外接其他板的 can 接口测试。

2.14 网络测试

连接网线到 J17, 在串口终端中输入以下命令来设置 IP 地址:

```
root@embest:~# ifconfig eth0 192.168.2.64
```

网络测试:

```
root@embest:~# ping 192.168.2.1
```

eth1 测试时, 断开 J17 网线, 连接外接网卡, 执行同样的命令 (eth0 改成 eth1)。

2.15 USB 测试

2.15.1 Host 测试

将 U 盘插入 USB host 接口 (J15), 串口显示磁盘信息:

```
[ 937.902749] usb 1-1.2: new high-speed USB device number 4 using xhci-hcd
[ 938.023750] usb 1-1.2: New USB device found, idVendor=058f, idProduct=6366
[ 938.030999] usb 1-1.2: New USB device strings: Mfr=1, Product=2, SerialNumber=3
[ 938.039779] usb 1-1.2: Product: Flash Card Reader/Writer
[ 938.046076] usb 1-1.2: Manufacturer: Generic
[ 938.050558] usb 1-1.2: SerialNumber: 058F63666438
[ 938.059201] usb-storage 1-1.2:1.0: USB Mass Storage device detected
[ 938.069433] scsi host3: usb-storage 1-1.2:1.0
[ 939.073423] scsi 3:0:0:0: Direct-Access Multiple Card Reader 1.00 PQ: 0 ANSI: 0
[ 939.551759] sd 3:0:0:0: [sda] 15515648 512-byte logical blocks: (7.94 GB/7.39 GiB)
[ 939.560184] sd 3:0:0:0: [sda] Write Protect is off
[ 939.568026] sd 3:0:0:0: [sda] No Caching mode page found
[ 939.575739] sd 3:0:0:0: [sda] Assuming drive cache: write through
[ 939.589938] sda: sda1
[ 939.600578] sd 3:0:0:0: [sda] Attached SCSI removable disk
```

串口终端输入如下命令:

```
root@embest:~# ls /dev/sd*
```

```
/dev/sda /dev/sda1
```

/dev 下存在设备节点;

2.15.2 OTG 测试

2.15.2.1 1 主设备

通过转接线连接 U 盘到 J13:

```
[ 880.127626] xhci-hcd xhci-hcd.0.auto: xHCI Host Controller
[ 880.134829] xhci-hcd xhci-hcd.0.auto: new USB bus registered, assigned bus number 3
[ 880.148726] xhci-hcd xhci-hcd.0.auto: hcc params 0x0238f06d hci version 0x100 quirks 0x00010010
[ 880.159328] xhci-hcd xhci-hcd.0.auto: irq 194, io mem 0x48390000
[ 880.167206] usb usb3: New USB device found, idVendor=1d6b, idProduct=0002
[ 880.175323] usb usb3: New USB device strings: Mfr=3, Product=2, SerialNumber=1
[ 880.183769] usb usb3: Product: xHCI Host Controller
[ 880.188905] usb usb3: Manufacturer: Linux 4.1.6+ xhci-hcd
[ 880.195618] usb usb3: SerialNumber: xhci-hcd.0.auto
[ 880.207218] hub 3-0:1.0: USB hub found
```

```
[ 880.218080] hub 3-0:1.0: 1 port detected
[ 880.222687] xhci-hcd xhci-hcd.0.auto: xHCI Host Controller
[ 880.233442] xhci-hcd xhci-hcd.0.auto: new USB bus registered, assigned bus number 4
[ 880.241707] usb usb4: We don't know the algorithms for LPM for this host, disabling LPM.
[ 880.252038] usb usb4: New USB device found, idVendor=1d6b, idProduct=0003
[ 880.260133] usb usb4: New USB device strings: Mfr=3, Product=2, SerialNumber=1
[ 880.268622] usb usb4: Product: xHCI Host Controller
[ 880.274473] usb usb4: Manufacturer: Linux 4.1.6+ xhci-hcd
[ 880.280171] usb usb4: SerialNumber: xhci-hcd.0.auto
[ 880.292998] hub 4-0:1.0: USB hub found
[ 880.299620] hub 4-0:1.0: 1 port detected
[ 880.532745] usb 3-1: new high-speed USB device number 2 using xhci-hcd
[ 880.673750] usb 3-1: New USB device found, idVendor=058f, idProduct=6366
[ 880.680830] usb 3-1: New USB device strings: Mfr=1, Product=2, SerialNumber=3
[ 880.689456] usb 3-1: Product: Flash Card Reader/Writer
[ 880.695612] usb 3-1: Manufacturer: Generic
[ 880.699948] usb 3-1: SerialNumber: 058F63666438
[ 880.713047] usb-storage 3-1:1.0: USB Mass Storage device detected
[ 880.724837] scsi host2: usb-storage 3-1:1.0
[ 881.733406] scsi 2:0:0:0: Direct-Access Multiple Card Reader 1.00 PQ: 0 ANSI: 0
[ 882.211615] sd 2:0:0:0: [sda] 15515648 512-byte logical blocks: (7.94 GB/7.39 GiB)
[ 882.220103] sd 2:0:0:0: [sda] Write Protect is off
[ 882.227790] sd 2:0:0:0: [sda] No Caching mode page found
[ 882.235398] sd 2:0:0:0: [sda] Assuming drive cache: write through
[ 882.249459] sda: sda1
[ 882.260011] sd 2:0:0:0: [sda] Attached SCSI removable disk.
```

串口终端输入如下命令:

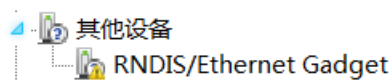
```
root@embest:~# ls /dev/sd*
```

```
/dev/sda /dev/sda1
```

/dev 下存在设备节点;

2.15.2.2 2. 从设备

连接 J13 到 PC 端, 打开设备管理器, 识别到如下设备:



2.16 Camera 测试

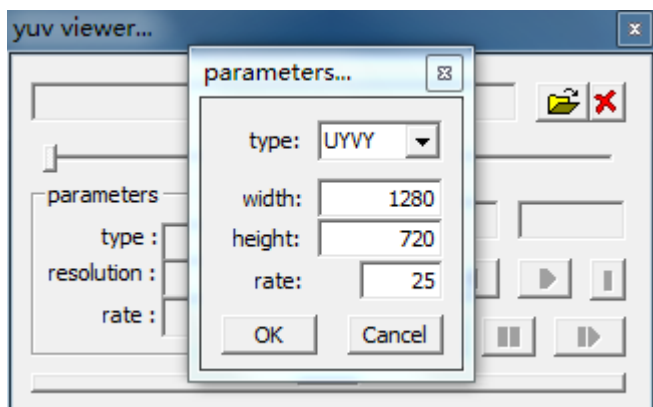
2.16.1 摄像模式

```
root@embest:~# ./mxc_v4l2_capture -iw1280 -ih 720 -ow 1280 -oh 720 -c 25 -f UYVY /boot/firmware/test.yuv  
root@embest:~# sync
```

摄像头会录制一段分辨率 1280*720，帧率 25 的视频。

用 Ctrl+C 结束录制。此时在 sd 卡下会生成 test.yuv 文件。

连接 SD 卡到电脑，用 Pyuv.exe 打开。参数设置如下：



注意：Tool 目录下提供了 Pyuv.exe。

目前摄像头支持的最大分辨率是 720P(1280*720)。

2.16.2 拍照模式

```
root@embest:~# ./capture_jpeg_to_display 1.jpg
```

摄像头拍摄 640*480 格式的图片，并将图片全部图像显示到 LCD 屏

第3章 系统编译

3.1 配置编译环境

将 release 文件夹的所有内容拷贝到 Linux 环境下的\$HOME 目录下（可能需要先解压 rar 文件），编译工具 gcc-linaro-4.9-2015.05-x86_64_arm-linux-gnueabihf 在\$HOME/S5_tool 目录下，用如下命令解压：

```
$xz -d gcc-linaro-4.9-2015.05-x86_64_arm-linux-gnueabihf.tar.xz
```

```
$tar -xvf gcc-linaro-4.9-2015.05-x86_64_arm-linux-gnueabihf.tar
```

导入环境变量：

```
$export
```

```
CROSS_COMPILE=$HOME/tool/gcc-linaro-4.9-2015.05-x86_64_arm-linux-gnueabihf/bin/arm-linux-gnueabihf-
```

```
$export ARCH=arm
```

3.2 编译 UBOOT

3.2.1 获取 uboot 源码

Uboot 源码在\$HOME/S4_Sourcecode/目录下，解压 u-boot*.tar.gz：

```
$ cd $HOME/S4_Sourcecode/
```

```
$ tar -zxvf u-boot*.tar.gz
```

3.2.2 编译并烧写镜像到 SD 卡

```
$ cd $HOME/S4_Sourcecode/u-boot
```

```
$ make distclean
```

```
$make som_ph8800_defconfig
```

```
$make
```

编译完成后在\$HOME/S4_Sourcecode/u-boot 目录下生成 MLO, u-boot.img，将两个文件拷贝到 SD 卡中；

3.2.3 编译并烧写镜像 SPI Flash

```
$ cd $HOME/S4_Sourcecode/u-boot
```

```
$ make distclean
```

```
$make som_ph8800_qspiboot_defconfig
```

```
$make
```

编译完成后在\$HOME/S4_Sourcecode/u-boot 目录下生成 u-boot.bin，\$HOME/S4_Sourcecode/u-boot*/spl 目录下生成 u-boot-spl.bin,将两个文件拷贝到 SD 卡中；

从 SD 卡启动，在 uboot 阶段执行：

```
U-Boot# run update_qspi_flash
```

等待执行结束，这两个文件就烧写到 SPI flash 中。

(参考 [1.3 从 SPI Flash 启动系统](#))

3.3 Kernel

3.3.1 获取内核源码

内核源码存在\$HOME/S4_Sourcecode/目录下,解压 linux*.tar.gz

```
$ tar -zxvf linux*.tar.gz
```

3.3.2 编译并烧写镜像到 SD 卡

```
$ cd $HOME/ release/S4_Sourcecode/linux*
```

```
$ make distclean
```

```
$ make embest_ti_8800_defconfig
```

```
$ make
```

编译完成后在

- 目录\$HOME/release/S4_Sourcecode/linux*/arch/arm/boot 下生成 zImage 文件。
- 目录 \$HOME/ release/S4_Sourcecode/linux*/arch/arm/boot/dts 中生成下列 3 个文件:
 1. embest-SOM_PH8700-BB_SPH1800-4.3inch_LCD.dtb
 2. embest-SOM_PH8700-BB_SPH1800-7inch_LCD.dtb
 3. embest-SOM_PH8700_BB_SPH1800-HDMI.dtb

dtb 文件分别对应 4.3 寸屏，7 寸屏，（配置方法参考 [LCD 测试](#)， [HDMI 测试](#)）

将文件拷贝到 SD 卡中。

单击下面可查看定价，库存，交付和生命周期等信息

[>>Avnet manufacturing service\(英蓓特\)](#)