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# **BQ25611D I2C Controlled 1-Cell 3.0-A Buck Battery Charger with USB Detection and 1.2-A Boost Operation**

## **1 Features**

- High-efficiency, 1.5-MHz, synchronous switchmode buck charger
	- 92% charge efficiency at 2-A from 5-V input
	- ±0.4% charge voltage regulation with 10-mV step
	- Programmable JEITA thresholds
	- Remote battery sensing to charge faster
- Support USB On-The-Go (OTG) with adjustable output from 4.6 V to 5.15 V
	- Boost converter with up to 1.2-A output
	- 92% boost efficiency at 1-A output
	- Accurate constant current (CC) limit
	- Soft-start up to 500-µF capacitive load
- Single input supporting USB input, high-voltage adapter, or wireless power
	- Support 4-V to 13.5-V input voltage range with 22-V absolute max input rating
	- 130-ns fast turn-off input over voltage protection
	- Programmable input current limit (IINDPM) with I <sup>2</sup>C (100-mA to 3.2-A, 100-mA/step)
	- VINDPM threshold up to 5.4-V automatically tracks battery voltage for maximum power
	- Auto detect USB SDP, CDP, DCP and nonstandard adaptors
- Narrow VDC (NVDC) power path management
	- System instant-on with no battery or deeply discharged battery
- Low R<sub>DSON</sub> 19.5-mΩ BATFET to minimize charging loss and extend battery run time
	- BATFET control for ship mode, and full system reset with and without adapter
- 7-µA low battery leakage current in ship mode
- 9.5-µA low battery leakage current with system standby
- High accuracy battery charging profile
	- ±6% charge current regulation
	- ±7.5% input current regulation
	- ±3% VINDPM voltage regulation
	- Programmable top-off timer for full battery charging
- High integration includes all MOSFETs, current sensing and loop compensation
- Safety-Related Certifications:

### – IEC 62368-1 CB Certification

### **2 Applications**

- [Mobile phone](http://www.ti.com/applications/personal-electronics/mobile-phones/overview.html), [tablet](http://www.ti.com/applications/personal-electronics/tablets/overview.html)
- [Industrial,](http://www.ti.com/applications/industrial/overview.html) [medical,](http://www.ti.com/applications/industrial/medical/overview.html) [portable electronics](http://www.ti.com/applications/personal-electronics/portable-electronics/overview.html)

### **3 Description**

The BQ25611D is a highly integrated 3-A switchmode battery charge management and system power path management device for single cell Li-Ion and Lipolymer batteries. The solution is highly integrated with input reverse-blocking FET (RBFET, Q1), highside switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET, Q4) between system and battery. The low impedance power path optimizes switch-mode operation efficiency, reduces battery charging time and extends battery run time during discharging phase.

The BQ25611D is a highly integrated 3-A switchmode battery charge management and system Power Path management device for Li-ion and Li-polymer batteries. It features fast charging with high input voltage support for a wide range of applications including smart phones and tablets . Its low impedance power path optimizes switch-mode operation efficiency, reduces battery charging time, and extends battery run time during discharging phase. Its input voltage and current regulation and battery remote sensing deliver maximum charging power to the battery.

### **Device Information (1)**



(1) For all available packages, see the orderable addendum at the end of the data sheet.



#### **Simplified Application**

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# **4 Revision History**





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### **5 Description (continued)**

The solution is highly integrated with input reverse-blocking FET (RBFET, Q1), high-side switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET, Q4) between system and battery. It also integrates the bootstrap diode for the high-side gate drive for simplified system design. The  $12C$  serial interface with charging and system settings makes the device a truly flexible solution.

The device supports a wide range of input sources, including standard USB host port, USB charging port, USB compliant high voltage adapter and wireless power. It is compliant with USB 2.0 and USB 3.0 power spec with input current and voltage regulation. The device takes the result from the detection circuit in the system, such as USB PHY device.

The device integrates the buck charger and boost regulator into one solution with single inductor. It meets USB On-The-Go (OTG) operation power rating specification by supplying 5 V (adjustable 4.6V / 4.75 V / 5 V / 5.15 V) with constant current limit up to 1.2 A.

The Power Path management regulates the system slightly above battery voltage but does not drop below 3.5-V minimum system voltage (programmable ) with adapter applied. With this feature, the system maintains operation even when the battery is completely depleted or removed. When the input current limit or voltage limit is reached, the Power Path management automatically reduces the charge current. As the system load continues to increase, the battery starts to discharge the battery until the system power requirement is met. This supplement mode prevents overloading the input source.

The device initiates and completes a charging cycle without software control. It senses the battery voltage and charges the battery in three phases: pre-conditioning, constant current and constant voltage. At the end of the charging cycle, the charger automatically terminates when the charge current is below a preset limit and the battery voltage is higher than the recharge threshold. If the fully charged battery falls below the recharge threshold, the charger automatically starts another charging cycle.

The charger provides various safety features for battery charging and system operations, including battery negative temperature coefficient thermistor monitoring, charging safety timer and overvoltage and over-current protections. Thermal regulation reduces charge current when the junction temperature exceeds 110°C. The status register reports the charging status and any fault conditions. With  $I^2C$ , the VBUS GD bit indicates if a good power source is present, and the  $\overline{\text{INT}}$  output immediately notifies host when a fault occurs.

The device also provides the QON pin for BATFET enable and reset control to exit low power ship mode or full system reset function.

The BQ25611D device is available in 24-pin, 4 mm × 4 mm x 0.75 mm thin WQFN package.



## <span id="page-3-0"></span>**6 Device Comparison Table**



# **7 Pin Configuration and Functions**





### **Pin Functions**



<span id="page-4-0"></span>

#### **[BQ25611D](http://www.ti.com/product/BQ25611D)** SLUSDF6B – JANUARY 2020 – REVISED SEPTEMBER 2020



(1) AI = Analog Input, AO = Analog Output, AIO = Analog Input Output, DI = Digital input, DO = Digital Output, DIO = Digital Input Output, P = Power

(2) All capacitors are ceramic unless otherwise specified



### <span id="page-5-0"></span>**8 Specifications**

### **8.1 Absolute Maximum Ratings**



over operating free-air temperature range (unless otherwise noted) $(1)$ 

(1) Stresses beyond those listed under *Absolute Maximum Rating* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Condition*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### **8.2 ESD Ratings**



(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### **8.3 Recommended Operating Conditions**

over operating free-air temperature range (unless otherwise noted)



#### **8.4 Thermal Information**



<span id="page-6-0"></span>

### **8.4 Thermal Information (continued)**



(1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC Package Thermal Metrics](http://www.ti.com/lit/SPRA953) application report.

#### **8.5 Electrical Characteristics**





















<span id="page-11-0"></span> $\rm V_{VBUS\_UVLOZ}$  <  $\rm V_{VBUS}$  <  $\rm V_{VBUS\_OV}$  and  $\rm V_{VBUS}$  >  $\rm V_{BAT}$  +  $\rm V_{SLEEP}$ , T $_{\rm J}$  = -40°C to +125°C, and T $_{\rm J}$  = 25°C for typical values (unless otherwise noted)



### **8.6 Timing Requirements**



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### **8.7 Typical Characteristics**



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### **9 Detailed Description**

### **9.1 Overview**

The BQ25611D device is a highly integrated 3.0-A switch-mode battery charger for single cell Li-Ion and Lipolymer battery. It includes the input reverse-blocking FET (RBFET, Q1), high-side switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET, Q4), and bootstrap diode for the high-side gate drive.

### **9.2 Functional Block Diagram**





### <span id="page-15-0"></span>**9.3 Feature Description**

### **9.3.1 Power-On-Reset (POR)**

The device powers internal bias circuits from the higher voltage of VBUS and BAT. When  $V_{VBUS}$  rises above V<sub>VBUS UVLOZ</sub> or V<sub>BAT</sub> rises above V<sub>BAT UVLOZ</sub>, the sleep comparator, battery depletion comparator and BATFET driver are active. I<sup>2</sup>C interface is ready for communication and all the registers are reset to default value. The host can access all the registers after POR.

### **9.3.2 Device Power Up from Battery without Input Source**

If only the battery is present and the voltage is above depletion threshold ( $V_{BAT}$   $_{DPLZ}$ ), the BATFET turns on and connects the battery to the system. The REGN stays off to minimize the quiescent current. The low R<sub>DSON</sub> of BATFET and the low quiescent current on BAT minimize the conduction loss and maximize the battery run time.

The device always monitors the discharge current through BATFET. When the system is overloaded or shorted  $(I<sub>BAT</sub> > I<sub>SYS OCP Q4</sub>)$ , the device turns off BATFET immediately until the input source plugs in again.

With I<sup>2</sup>C, when the BATFET turns off due to over-current, the device sets the BATFET\_DIS bit to indicate the BATFET is disabled until the input source plugs in again or one of the methods described in the [Section 9.3.7.2](#page-23-0) section is applied to re-enable BATFET.

#### **9.3.3 Power Up from Input Source**

When an input source is plugged in, the device checks the input source voltage to turn on the REGN LDO and all the bias circuits. It detects and sets the input current limit before the buck converter is started. The power up sequence from input source is as listed:

- 1. Power Up REGN LDO, see Power Up REGN LDOsection
- 2. Poor Source Qualification, see Poor Source Qualification section
- 3. Input Source Type Detection is based on D+/D– to set default input current limit (IINDPM threshold), see [Input Source Type Detection \(IINDPPM Threshold\)](#page-16-0) section
- 4. Input Voltage Limit Threshold Setting (VINDPM threshold), see [Input Voltage Limit Thresholding Setting](#page-16-0) [\(VINDPM Threshold\)](#page-16-0) section
- 5. Power Up Converter, see [Power Up Converter in Buck Mode](#page-17-0) section

### *9.3.3.1 Power Up REGN LDO*

The REGN LDO supplies internal bias circuits as well as the HSFET and LSFET gate drive. It also provides the bias rail to TS external resistors. The pull-up rail of STAT can be connected to REGN as well. The REGN LDO is enabled when all the below conditions are valid:

- V<sub>VBUS</sub> > V<sub>VBUS</sub> UVLOZ
- In buck mode,  $V_{VBUS} > V_{BAT} + V_{SLEEPZ}$
- In boost mode,  $V_{VBUS}$  <  $V_{BAT}$  +  $V_{SLEEPZ}$
- After 220-ms delay is completed

During high impedance mode when EN\_HIZ bit is 1, REGN LDO turns off. The battery powers up the system.

### *9.3.3.2 Poor Source Qualification*

After the REGN LDO powers up, the device starts to check current capability of the input source. The first step is poor source detection.

• VBUS voltage above  $V_{POORSRC}$  when pulling  $I_{BADSRC}$  (typical 30 mA)

With I<sup>2</sup>C, once the input source passes poor source detection, the status register bit VBUS\_GD is set to 1 and the  $\overline{\text{INT}}$  pin is pulsed to signal to the host.

If the device fails the poor source detection, it repeats poor source qualification every 2 seconds.

<span id="page-16-0"></span>

#### *9.3.3.3 Input Source Type Detection (IINDPM Threshold)*

After poor source detection, the device runs input source detection through D+/D– lines . The D+/D– detection follows the USB Battery Charging Specification 1.2 (BC1.2) to detect standard (SDP/CDP/DCP) and nonstandard adapters through USB D+/D– lines.

With I<sup>2</sup>C, after input source type detection is completed, an INT pulse is asserted to the host, in addition, the following register bits are updated:

The host can over-write the IINDPM register to change the input current limit if needed.

#### **9.3.3.3.1 D+/D– Detection Sets Input Current Limit**

The device contains a D+/D– based input source detection to set the input current limit when a 5-V adapter is plugged-in. The D+/D– detection includes standard USB BC1.2 and non-standard adapters. When an input source is plugged in, the device starts standard USB BC1.2 detection. The USB BC1.2 is capable of identifying Standard Downstream Port (SDP), Charging Downstream Port (CDP) and Dedicated Charging Port (DCP). The non-standard detection is used to distinguish vendor specific adapters (Apple and Samsung) based on their unique dividers on the D+/D– pins. If an adapter is detected as DCP, the input current limit is set at 2.4-A. If an adapter is detected as unknown, the input current limit is set at 0.5 A by ILIM pin.

The secondary detection is used to distinguish two types of charging ports (CDP and DCP). The protocol for secondary detection is as follows:

Most of the time, a CDP requires the portable device (such as smart phone, tablet) to send back an enumeration within 2.5 seconds of CDP plug-in. Otherwise, the port will power cycle back to SDP even the D+/D– detection indicates CDP.



#### **Table 9-1. Non-Standard Adapter Detection**



#### **Table 9-2. Input Current Limit Setting from D+/D– Detection**

#### *9.3.3.4 Input Voltage Limit Threshold Setting (VINDPM Threshold)*

The device has two modes to set the VINDPM threshold.

- Fixed VINDPM threshold. The VINDPM is in default set at 4.5 V (programmable from 3.9 V to 5.4 V) .
- VINDPM threshold tracks the battery voltage to optimize the converter headroom between input and output. When it is enabled in REG07[1:0], the actual input voltage limit is the higher of the VINDPM setting in register and  $V_{BAT}$  + offset voltage in VINDPM\_BAT\_TRACK[1:0].



#### <span id="page-17-0"></span>*9.3.3.5 Power Up Converter in Buck Mode*

After the input current limit is set, the converter is enabled and the HSFET and LSFET start switching. The system voltage is powered from the converter instead of the battery. If battery charging is disabled, the BATFET turns off. Otherwise, the BATFET stays on to charge the battery.

The device provides soft-start when system rail is ramping up. When the system rail is below  $V_{BAT; SHORT}$ , the input current is limited to the lower of 200-mA or IINDPM register setting. The system load shall be appropriately planned not to exceed the 200-mA IINDPM limit. After the system rises above  $V_{BAT}$  SHORTZ, the device input current limit is the value set by the IINDPM register .

As a battery charger, the device deploys a highly efficient 1.5-MHz step-down switching regulator. The fixed frequency oscillator keeps tight control of the switching frequency under all conditions of input voltage, battery voltage, charge current and temperature simplifying output filter design.

The converter supports PFM operation by default for fast transient response during system voltage regulation and better light load efficiency. The PFM\_DIS bit disables PFM operation if system voltage is not in regulation.

#### *9.3.3.6 HIZ Mode with Adapter Present*

By setting EN\_HIZ bit to 1 with adapter, the device enters high impedance state (HIZ). In HIZ mode, the system is powered from battery even with good adapter present. The device is in the low input quiescent current state with Q1 RBFET, REGN LDO and the bias circuits off.

#### **9.3.4 Boost Mode Operation From Battery**

The device supports boost converter operation to deliver power from the battery to other portable devices through a USB port. The output voltage is regulated at 5-V (programmable 4.6/4.75/5.0/5.15 V) and output current is up to 1.2 A (programmable 0.5 A/1.2 A ) with constant current regulation. The user needs to have at least 350 mV between V<sub>BAT</sub> and boost mode regulation voltage (V<sub>BST</sub>) to power up boost mode reliably. For example, BOOSTV[1:0] setting is recommended to be 4.75 V or higher if the battery voltage is 4.4 V.

The boost operation is enabled if the conditions below are valid:

- 1. Register setting: BATFET\_DIS = 0, CHG\_COFNIG = 0 and BST\_CONFIG = 1
- 2. BAT above  $V_{BST,BAT}$  set by MIN\_VBAT\_SEL bit,
- 3. VBUS less than  $V_{BAT} + V_{SLEEP}$  (in sleep mode) before converter starts.
- 4. Voltage at TS (thermistor) pin, as a percentage of  $V_{REGN}$ , is within acceptable range ( $V_{BHOT-RISFS}$  <  $V_{TS\%}$  < V<sub>BCOLD</sub> FALL%)
- 5. After 30-ms delay from boost mode enable .

During boost mode, the status register VBUS\_STAT bits is set to 111.

The converter supports PFM operation at light load in boost mode. The PFM\_DIS bit can be used to disable PFM operation in boost configuration.

#### **9.3.5 Power Path Management**

The device accommodates a wide range of input sources such as USB, wall adapter, or car charger. The device provides automatic power path selection to supply the system (SYS) from the input source (VBUS), battery (BAT), or both.

#### *9.3.5.1 Narrow VDC Architecture*

The device deploys Narrow VDC architecture (NVDC) with BATFET separating system from battery. The minimum system voltage is set by SYS Min bits. Even with a fully depleted battery, the system is regulated above the minimum system voltage.

When the battery is below the minimum system voltage setting, the BATFET operates in linear mode (LDO mode), and the system is typically 180 mV above the minimum system voltage setting. As the battery voltage rises above the minimum system voltage, the BATFET is fully on and the voltage difference between the system and battery is the  $V_{DS}$  of the BATFET.



When battery charging is disabled and above the minimum system voltage setting or charging is terminated, the system is always regulated at typically 50 mV above the battery voltage. The status register VSYS STAT bit goes to 1 when the system is in minimum system voltage regulation.



**Figure 9-1. System Voltage vs Battery Voltage**

#### *9.3.5.2 Dynamic Power Management*

To meet the maximum current limit in the USB specification and avoid overloading the adapter, the device features Dynamic Power Management (DPM), which continuously monitors the input current and input voltage. When input source is overloaded, either the current exceeds the input current limit (IINDPM) or the voltage falls below the input voltage limit (VINDPM). The device then reduces the charge current until the input current falls below the input current limit or the input voltage rises above the input voltage limit.

When the charge current is reduced to zero, but the input source is still overloaded, the system voltage starts to drop. Once the system voltage falls below the battery voltage, the device automatically enters the supplement mode where the BATFET turns on and the battery starts discharging so that the system is supported from both the input source and battery.

During DPM mode, the status register bits VINDPM\_STAT or IINDPM\_STAT go to 1.

Figure 9-2 shows the DPM response with 9-V/1.2-A adapter, 3.2-V battery, 2.8-A charge current and 3.5-V minimum system voltage setting.



**Figure 9-2. DPM Response**



#### <span id="page-19-0"></span>*9.3.5.3 Supplement Mode*

When the system voltage falls below the battery voltage, the BATFET turns on and the BATFET gate is regulated so that the minimum BATFET  $V_{DS}$  stays at 30 mV when the current is low. This prevents oscillation from entering and exiting the supplement mode.

As the discharge current increases, the BATFET gate is regulated with a higher voltage to reduce  $R_{DSON}$  until the BATFET is in full conduction. At this point onwards, the BATFET  $V_{DS}$  linearly increases with discharge current. Figure 9-3 shows the V-I curve of the BATFET gate regulation operation. The BATFET turns off to exit supplement mode when the battery is below battery depletion threshold.



**Figure 9-3. BAFET V-I Curve**

#### **9.3.6 Battery Charging Management**

The device charges 1-cell Li-Ion battery with up to 3.0-A charge current for high capacity tablet battery. The 19.5 mΩ BATFET improves charging efficiency and minimizes the voltage drop during discharging.

### *9.3.6.1 Autonomous Charging Cycle*

When battery charging is enabled (CHG\_CONFIG bit = 1 and  $\overline{\text{CE}}$  pin is LOW), the device autonomously completes a charging cycle without host involvement. The device default charging parameters are listed in Table 9-3. The host configures the power path and charging parameters by writing to the corresponding registers through  $1<sup>2</sup>C$ .



### **Table 9-3. Charging Parameter Default Setting**

A new charge cycle starts when the following conditions are valid:

- Converter starts
- Battery charging is enabled (CHG\_CONFIG bit = 1 and  $I_{CHG}$  register is not 0 mA and  $\overline{CE}$  is low)
- No thermistor fault on TS. (TS pin can be ignored by setting TS\_IGNORE bit to 1)
- No safety timer fault
- BATFET is not forced to turn off (BATFET\_DIS bit = 0)



The device automatically terminates the charging cycle when the charging current is below the termination threshold, the battery voltage is above the recharge threshold, and the device is not in DPM mode or thermal regulation. When a fully charged battery is discharged below recharge threshold (selectable through VRECHG bit), the device automatically starts a new charging cycle. After the charge is done, toggle  $\overline{CE}$  pin or CHG CONFIG bit will initiate a new charging cycle. Adapter removal and replug will also restart a charging cycle.

The STAT output indicates the charging status: charging (LOW), charging complete or charge disable (HIGH) or charging fault (blinking). The status register (CHRG\_STAT) indicates the different charging phases: 00-charging disable, 01-pre-charge, 10-fast charge (CC) and constant voltage (CV), 11-charging done. Once a charging cycle is completed, an  $\overline{\text{INT}}$  pulse is asserted to notify the host.

#### *9.3.6.2 Battery Charging Profile*

The device charges the battery in five phases: battery short, preconditioning, constant current, constant voltage and top-off trickle charging (optional). At the beginning of a charging cycle, the device checks the battery voltage and regulates current and voltage accordingly.

Resistance between charger output and battery cell terminal such as board routing, connector, MOSFETs and sense resistor can force the charging process to move from constant current to constant voltage too early and increase charge time. To speed up the charging cycle, the device provides BATSNS pin to extend the constant current charge time to delivery maximum power to battery. BATSNS pin is connected directly to battery cell terminal to remotely sense battery cell voltage. BATSNS is by default enabled, and can be disabled through BATSNS DIS bit. If BATSNS is connected to GND or left floating, the charger regulates BAT pin instead.



**Table 9-4. Charging Current Setting**



### **Figure 9-4. Battery Charging Profile**



### *9.3.6.3 Charging Termination*

The device terminates a charge cycle when the battery voltage is above the recharge threshold, and the current is below termination current. After the charging cycle is completed, the BATFET turns off. The STAT is asserted HIGH to indicate charging done. The converter keeps running to power the system, and BATFET can turn on again to engage [Supplement Mode](#page-19-0).

If the device is in IINDPM/VINDPM regulation, or thermal regulation, the actual charging current will be less than the termination value. In this case, termination is temporarily disabled.

When termination occurs, STAT pin goes HIGH. The status register CHRG STAT is set to 11, and an INT pulse is asserted to the host. Termination can be disabled by writing 0 to EN\_TERM bit prior to charge termination.

The termination current is set in REG03[3:0]. Due to the termination current accuracy, the actual termination current may be higher than the termination target. In order to compensate for termination accuracy, a programmable top-off timer can be applied after termination is detected . The top-off timer will follow safety timer constraints, such that if safety timer is suspended, so will the top-off timer. Similarly, if safety timer is doubled, so will the termination top-off timer. TOPOFF\_ACTIVE bit reports whether the top off timer is active or not. The host can read CHRG\_STAT and TOPOFF\_ACTIVE to find out the termination status. STAT pin stays HIGH during top-off timer counting cycle.

Top-off timer gets reset at one of the following conditions:

- 1. Charge disable to enable
- 2. Charger enters termination
- 3. REG\_RST register bit is set

The top-off timer settings are read in once termination is detected by the charger. Programming a top-off timer value (01, 10, 11) after termination will have no effect unless a recharge cycle is initiated. The top-off timer will immediately stop if it is disabled (00). An  $\overline{\text{INT}}$  is asserted to the host when entering top-off timer segment as well as when top-off timer expires.

#### *9.3.6.4 Thermistor Qualification*

The device provides a single thermistor input for battery temperature monitoring.

#### **9.3.6.4.1 JEITA Guideline Compliance During Charging Mode**

To improve the safety of charging Li-ion batteries, the JEITA guideline was released on April 20, 2007. The guideline emphasized the importance of avoiding a high charge current and high charge voltage at certain low and high temperature ranges.

To initiate a charge cycle, the voltage on TS pin, as a percentage of  $V_{REGN}$ , must be within the  $V_{T1|FAI|M}$  to  $V_{\text{TS-RISE}}$  thresholds. If the TS voltage percentage exceeds the T1-T5 range, the controller suspends charging, a TS fault is reported and waits until the battery temperature is within the T1 to T5 range.

At cool temperature (T1-T2), the charge current is reduced to a programmable fast charge current (0%, 20% default, 50%, 100% of I<sub>CHG</sub>, by JEITA\_ISET). At warm temperature (T3-T5), the charge voltage is reduced to 4.1 V or kept at  $V_{RFG}$  (JEITA VSET). and the charge current can be reduced to a programmable level (0%, 20%, 50%, 100% default). Battery termination is disabled in T3-T5. The charger provides more flexible settings on T2 and T3 threshold as well to program the temperature profile beyond JEITA. When the T1 is set to 0°C and T5 is set to 60°C, T2 can be programmed to 5.5°C/10°C(default)/15°C/20°C, and T3 can be programmed to 40°C/ 45.5°C(default)/50.5°C/54.5°C.

When charger does not need to monitor the NTC, host sets TS\_IGNORE bit to 1 to ignore the TS pin condition during charging and boost mode. If TS\_IGNORE bit is set to 1, TS pin is ignored and the charger ignore TS pin input. In this case, NTC\_FAULT bits are 000 to report normal TS status.





**Figure 9-5. JEITA Profile**

Equation 1 through Equation 2 describe how to calculate resistor divider values on Ts pin.



**Figure 9-6. TS Pin Resistor Network**

$$
RT1 = \frac{\frac{1}{V_{T1}\%} - 1}{\frac{1}{R_{T2}} + \frac{1}{R_{NTC,T1}}}
$$
\n
$$
RT2 = \frac{R_{NTC,T1} \times R_{NTC,T5} \times \left(\frac{1}{V_{T5}\%} - \frac{1}{V_{T1}\%}\right)}{R_{NTC,T1} \times \left(\frac{1}{V_{T1}\%} - 1\right) - R_{NTC,T5} \times \left(\frac{1}{V_{T5}\%} - 1\right)}
$$
\n(1)

In the equations above,  $R_{NTC, T1}$  is NTC thermistor resistance value at temperature T1 and  $R_{NTC, T5}$  is NTC thermistor resistance values at temperature T5. Select 0°C to 60°C range for Li-ion or Li-polymer battery then

- $R_{NTC,T1}$  = 27.28 KΩ (0°C)
- $R_{NTC,T5}$  = 3.02 KΩ (60°C)
- RT1 =  $5.3$  K $\Omega$
- RT2 = 31.14 KΩ

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(2)



#### <span id="page-23-0"></span>**9.3.6.4.2 Boost Mode Thermistor Monitor During Battery Discharge Mode**

For battery protection during boost mode, the device monitors the battery temperature to be within the  $V_{BCOLD}$ and V<sub>BHOT</sub> thresholds. When RT1 is 5.3 KΩ and RT2 is 31.14 KΩ, T<sub>BCOLD</sub> default is -19.5°C and T<sub>BHOT</sub> default is 64°C. When temperature is outside of the temperature thresholds, the boost mode is suspended. In addition, VBUS\_STAT bits are set to 000 and NTC\_FAULT is reported. Once temperature returns within thresholds, boost mode is recovered and NTC\_FAULT is cleared.

#### *9.3.6.5 Charging Safety Timer*

The device has a built-in safety timer to prevent extended charging cycle due to abnormal battery conditions. The safety timer is 2 hours when the battery is below  $V_{BATLOWV}$  threshold and 10 hours (10/20 hours in REG05[2] ) when the battery is higher than  $V_{BATLOW}$  threshold. When the safety timer expires, STAT pin is blinking at 1 Hz to report a safety timer expiration fault.

The user can program the fast charge safety timer through I<sup>2</sup>C (CHG TIMER bit REG05[2]). When safety timer expires, the fault register CHRG\_FAULT bits (REG09[5:4]) are set to 11 and an INTis asserted to the host. The safety timer (both fast charge and pre-charge) can be disabled through I<sup>2</sup>C by setting EN\_TIMER bit.

During IINDPM/VINDPM regulation, thermal regulation, or JEITA cool/warm when fast charge current is reduced,the safety timer counts at a half clock rate, because the actual charge current is likely below the setting. For example, if the charger is in input current regulation (IINDPM STAT  $= 1$ ) throughout the whole charging cycle, and the safety time is set to 10 hours, the safety timer will expire in 20 hours. This half clock rate feature can be disabled by writing 0 to the TMR2X\_EN bit.

During faults of BAT\_FAULT, NTC\_FAULT that lead to charging suspend, safety timer is suspended as well. Once the fault goes away, timer resumes. If user stops the current charging cycle, and start again, timer gets reset (toggle CE pin or CHG\_CONFIG bit).

#### **9.3.7 Ship Mode and QON Pin**

#### *9.3.7.1 BATFET Disable (Enter Ship Mode)*

To extend battery life and minimize power when the system is powered off during system idle, shipping, or storage, the device turns off BATFET so that the system voltage is floating to minimize the battery leakage current. When the host sets the BATFET DIS bit, the charger can turn off the BATFET immediately or delay by  $t_{\text{BATER}}$   $_{\text{DIY}}$  as configured by the BATFET DLY bit. To set the device into ship mode with the adapter present, the host has to first set BATFET\_RST\_VBUS to 1 and then BATFET\_DIS to 1. The charger will turn off the BATFET (no charging, no supplement) while the adapter is still attached. When the adapter is removed, the charger will enter ship mode.

#### *9.3.7.2 BATFET Enable (Exit Ship Mode)*

When the BATFET is disabled (in ship mode) as indicated by setting BATFET DIS, one of the following events can enable the BATFET to restore system power:

- 1. Plug in adapter
- 2. Clear BATFET DIS bit
- 3. Set REG\_RST bit to reset all registers including BATFET\_DIS bit to default (0)
- 4. A logic high to low transition on  $\overline{QON}$  pin with t<sub>SHIPMODE</sub> deglitch time to enable BATFET to exit ship mode. EN\_HIZ bit is set to 1 (regardless of adapter present or not). Host has to set EN\_HIZ bit to 0 before boost mode enable. Once adapter plugs in, EN\_HIZ will be cleared.

#### *9.3.7.3 BATFET Full System Reset*

The BATFET functions as a load switch between battery and system when input source is not plugged–in. When BATFET\_RST\_EN=1 and BATFET\_DIS=0, BATFET full system reset function is enabled. By changing the state of BATFET from on to off, systems connected to SYS can be effectively forced to have a power-on-reset. The QON pin supports push-button interface to reset system power without host by changing the state of BATFET. Internally, it is pulled up to the V<sub>OON</sub> voltage through a 200-kΩ resistor.



When the  $\overline{QON}$  pin is driven to logic low for t<sub>QON RST</sub>, BATFET reset process starts. The BATFET is turned off for  $t_{\text{BATET RST}}$  and then it is re-enabled to reset system power. This function can be disabled by setting BATFET RST\_EN bit to 0.

BATFET full system reset functions either with or without adapter present. If BATFET RST WVBUS=1, the system reset function starts after t<sub>QON, RST</sub> when  $\overline{QON}$  pin is pushed to LOW. Once the reset process starts, the device first goes into HIZ mode to turn off the converter, and then power cycles BATFET. If BATFET\_RST\_WVBUS=0, the system reset function doesn't start till t<sub>OON\_RST</sub> after  $\overline{QON}$  pin is pushed to LOW and adapter is removed.

After BATFET full system reset is complete, the device will power up again if EN\_HIZ is not set to 1 before the system reset.



**Figure 9-7. QON Timing**

### **9.3.8 Status Outputs ( STAT, INT )** *9.3.8.1 Charging Status Indicator (STAT)*

The device indicates charging state on the open drain STAT pin. The STAT pin can drive LED.

### **Table 9-5. STAT Pin State**



### *9.3.8.2 Interrupt to Host ( INT)*

In some applications, the host does not always monitor the charger operation. The  $\overline{\text{INT}}$  pulse notifies the host on the device operation. The following events will generate a 256-μs INT pulse.

- Good input source detected
	- $-$  V<sub>VBUS</sub> above battery (not in sleep)
	- $-$  V<sub>VBUS</sub> below V<sub>ACOV</sub> threshold



- $-$  V<sub>VBUS</sub> above V<sub>POORSRC</sub> (typical 3.8 V) when  $I_{BADSRC}$  (typical 30 mA) current is applied (not a poor source)
- Input adapter removed
- USB/adapter source identified during [Input Source Type Detection \(IINDPM Threshold\).](#page-16-0)
- Charge complete
- Any FAULT event in REG09
- VINDPM / IINDPM event detected (REG0A[1:0], maskable)
- Top off timer starts and expires

REG09[7:0] and REG0A[6:4] report charger operation faults and status change to the host. When a fault/status change occurs, the charger sends out an INT pulse and keeps the state in REG09[7:0]/REG0A[6:4] until the host reads the registers. Before the host reads REG09[7:0]/REG0A[6:4] and all the ones are cleared, the charger would not send any INT upon new fault/status change. To read the current status, the host has to read REG09/ REG0A two times consecutively. The first read reports the pre-existing register status and the second read reports the current register status.

### **9.3.9 Protections**

### *9.3.9.1 Voltage and Current Monitoring in Buck Mode*

### **9.3.9.1.1 Input Over-Voltage Protection (ACOV)**

The input voltage is sensed via the VAC pin. The default OVP threshold is 14.2-V, and can be programmed at 5.7 V/6.4 V/11 V/14.2 V via OVP[1:0] register bits . ACOV event will immediately stop converter switching whether in buck or boost mode. The device will automatically resume normal operation once the input voltage drops back below the OVP threshold. During ACOV, REGN LDO is on, and the device doesn't enter HIZ mode.

During ACOV, the fault register CHRG\_FAULT bits are set to 01. An INT pulse is asserted to the host.

### **9.3.9.1.2 System Over-Voltage Protection (SYSOVP)**

The charger device clamps the system voltage during a load transient so that the components connected to the system are not damaged due to high voltage.  $V_{SYS~OVP}$  threshold is about 300-mV above battery regulation voltage when battery charging is terminated. Upon SYSOVP, converter stops switching immediately to clamp the overshoot. The charger pulls 30-mA  $I_{SYS\text{ }LOAD}$  discharge current to bring down the system voltage.

### *9.3.9.2 Voltage and Current Monitoring in Boost Mode*

### **9.3.9.2.1 Boost Mode Over-Voltage Protection**

When the PMID voltage rises above regulation the target and exceeds  $V_{\text{BST OVP}}$ , the device stops switching immediately and the device exits boost mode and PMID\_GOOD is pulled low as well after the boost mode OVP lasts for 12 ms. Meanwhile, if VAC (and VBUS when shorted to VAC) voltage exceed  $V_{ACOV}$ , the device will exit boost mode as well. BST\_CONFIG bit is set to 0. During boost mode over-voltage, the fault register bit BOOST\_FAULT is set tot 1 to indicate fault in boost operation. An INT is asserted to the host.

### *9.3.9.3 Thermal Regulation and Thermal Shutdown*

### **9.3.9.3.1 Thermal Protection in Buck Mode**

Besides the battery temperature monitor on TS pin, the device monitors the internal junction temperature T $_{\textrm{\scriptsize{J}}}$  to avoid overheating the chip and limits the IC junction temperature in buck mode. When the internal junction temperature exceeds thermal regulation limit (110°C), the device lowers down the charge current. During thermal regulation, the actual charging current is usually below the programmed battery charging current. Therefore, termination is disabled, the safety timer runs at half the clock rate, and the status register THERM\_STAT bit goes high.

Additionally, the device has thermal shutdown to turn off the converter and BATFET when IC surface temperature exceeds  $T_{\text{SHUT}}$  150°C. The BATFET and converter is enabled to recover when IC temperature is 130°C. The fault register CHRG\_FAULT is set to 10 during thermal shutdown and an INT is asserted to the host.

#### **9.3.9.3.2 Thermal Protection in Boost Mode**

Besides the battery temperature monitor on TS pin, The device monitors the internal junction temperature to provide thermal shutdown during boost mode. When IC junction temperature exceeds  $T<sub>SHUT</sub>$  150°C, the boost



mode is disabled by setting BST\_CONFIG bit low . When IC junction temperature is below 145°C, the host can re-enable boost mode.

#### *9.3.9.4 Battery Protection*

#### **9.3.9.4.1 Battery Over-Voltage Protection (BATOVP)**

The battery over-voltage limit is clamped at 4% above the battery regulation voltage. When battery over-voltage occurs, the charger device immediately stops switching. The fault register BAT\_FAULT bit goes high and an INT is asserted to the host.

#### **9.3.9.4.2 Battery Over-Discharge Protection**

When battery is discharged below  $V_{BAT}$  <sub>DPL FALL</sub>, the BATFET will latch off to protect battery from over discharge. To recover from over-discharge latch-off, an input source plug-in is required at VAC/VBUS.

#### **9.3.9.4.3 System Over-Current Protection**

I<sub>SYS</sub> <sub>OCP</sub> Q<sub>4</sub> sets battery discharge current limit. Once I<sub>BAT</sub> > I<sub>SYS</sub> <sub>OCP</sub> Q<sub>4</sub>, charger will latch off Q4 and put the device into ship mode. All methods to exit ship mode are valid to bring the part out of Q4 latch off.

#### **9.3.10 Serial Interface**

The device uses I<sup>2</sup>C compatible interface for flexible charging parameter programming and instantaneous device status reporting. I<sup>2</sup>C<sup>TM</sup> is a bi-directional 2-wire serial interface developed by Philips Semiconductor (now NXP Semiconductors). Only two bus lines are required: a serial data line (SDA) and a serial clock line (SCL). Devices can be considered as masters or slaves when performing data transfers. A master is the device which initiates a data transfer on the bus and generates the clock signals to permit that transfer. At that time, any device addressed is considered a slave.

The device operates as a slave device with address 6BH , receiving control inputs from the master device like micro controller or a digital signal processor through REG00-REG0C. Register read beyond REG0C returns 0xFF. The I<sup>2</sup>C interface supports both standard mode (up to 100 kbits), and fast mode (up to 400 kbits). connecting to the positive supply voltage via a current source or pull-up resistor. When the bus is free, both lines are HIGH. The SDA and SCL pins are open drain.

#### *9.3.10.1 Data Validity*

The data on the SDA line must be stable during the HIGH period of the clock. The HIGH or LOW state of the data line can only change when the clock signal on the SCL line is LOW. One clock pulse is generated for each data bit transferred.



**Figure 9-8. Bit Transfer on the I2C Bus**

### *9.3.10.2 START and STOP Conditions*

All transactions begin with a START (S) and can be terminated by a STOP (P). A HIGH to LOW transition on the SDA line while SCL is HIGH defines a START condition. A LOW to HIGH transition on the SDA line when the SCL is HIGH defines a STOP condition. START and STOP conditions are always generated by the master. The bus is considered busy after the START condition, and free after the STOP condition.





**Figure 9-9. TS START and STOP conditions**

#### *9.3.10.3 Byte Format*

Every byte on the SDA line must be 8 bits long. The number of bytes to be transmitted per transfer is unrestricted. Each byte has to be followed by an Acknowledge bit. Data is transferred with the Most Significant Bit (MSB) first. If a slave cannot receive or transmit another complete byte of data until it has performed some other function, it can hold the clock line SCL low to force the master into a wait state (clock stretching). Data transfer then continues when the slave is ready for another byte of data and release the clock line SCL.



**Figure 9-10. Data Transfer on the I2C Bus**

### *9.3.10.4 Acknowledge (ACK) and Not Acknowledge (NACK)*

The acknowledge takes place after every byte. The acknowledge bit allows the receiver to signal the transmitter that the byte was successfully received and another byte may be sent. All clock pulses, including the acknowledge ninth clock pulse, are generated by the master. The transmitter releases the SDA line during the acknowledge clock pulse so the receiver can pull the SDA line LOW and it remains stable LOW during the HIGH period of this clock pulse.

When SDA remains HIGH during the ninth clock pulse, this is the Not Acknowledge signal. The master can then generate either a STOP to abort the transfer or a repeated START to start a new transfer.

### *9.3.10.5 Slave Address and Data Direction Bit*

After the START, a slave address is sent. This address is 7 bits long followed by the eighth bit as a data direction bit (bit R/W). A zero indicates a transmission (WRITE) and a one indicates a request for data (READ).



**Figure 9-11. Complete Data Transfer**

### *9.3.10.6 Single Read and Write*

If the register address is not defined, the charger IC send back NACK and go back to the idle state.



### **Figure 9-12. Single Write**

<span id="page-28-0"></span>



**Figure 9-13. Single Read**

#### *9.3.10.7 Multi-Read and Multi-Write*

The charger device supports multi-read and multi-write on REG00 through REG0C.



**Figure 9-15. Multi-Read**

REG09[7:0]/REG0A[6:4] are fault/status change register. They keep all the fault/status information from last read until the host issues a new read. For example, if Charge Safety Timer Expiration fault occurs but recovers later, the fault register REG09 reports the fault when it is read the first time, but returns to normal when it is read the second time. In order to get the fault information at present, the host has to read REG09/REG0A for the second time.

### **9.4 Device Functional Modes**

### **9.4.1 Host Mode and Default Mode**

The device is a host controlled charger, but it can operate in default mode without host management. In default mode, the device can be used an autonomous charger with no host or while host is in sleep mode. When the charger is in default mode, WATCHDOG\_FAULT bit is HIGH. When the charger is in host mode, WATCHDOG FAULT bit is LOW.

After power-on-reset, the device starts in default mode with watchdog timer expired, or default mode. All the registers are in the default settings.

All the device parameters can be programmed by the host. To keep the device in host mode, the host has to reset the watchdog timer by writing 1 to WD\_RST bit before the watchdog timer expires (WATCHDOG\_FAULT bit is set), or disable watchdog timer by setting WATCHDOG bits = 00.



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**Figure 9-16. Watchdog Timer Flow Chart**

<span id="page-30-0"></span>

### **9.5 Register Maps**

I <sup>2</sup>C Slave Address: 6BH

Default I<sup>2</sup>C Slave Address: 0x6B (1101 011B + R/ $\overline{W}$ )



Complex bit access types are encoded to fit into small table cells. Table 9-7 shows the codes that are used for access types in this section.



### **Table 9-7. I2C Access Type Codes**

#### <span id="page-31-0"></span>**9.5.1 Input Current Limit Register (Address = 00h) [reset = 17h] Figure 9-17. REG00 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset



<span id="page-32-0"></span>

### **9.5.2 Charger Control 0 Register (Address = 01h) [reset = 1Ah] Figure 9-18. REG01 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset







#### <span id="page-33-0"></span>**9.5.3 Charge Current Limit Register (Address = 02h) [reset = 91h] Figure 9-19. REG02 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset



### **Table 9-10. REG02 Field Descriptions**

<span id="page-34-0"></span>

#### **9.5.4 Pre-charge and Termination Current Limit Register (Address = 03h) [reset = 12h] Figure 9-20. REG03 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### **Table 9-11. REG03 Field Descriptions**





#### <span id="page-35-0"></span>**9.5.5 Battery Voltage Limit Register (Address = 04h) [reset = 40h] Figure 9-21. REG04 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset





<span id="page-36-0"></span>

#### **9.5.6 Charger Control 1 Register (Address = 05h) [reset = 9Eh] Figure 9-22. REG05 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset







#### <span id="page-37-0"></span>**9.5.7 Charger Control 2 Register (Address = 06h) [reset = E6h] Figure 9-23. REG06 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### **Table 9-14. REG06 Field Descriptions**



<span id="page-38-0"></span>

#### **9.5.8 Charger Control 3 Register (Address = 07h) [reset = 4Ch] Figure 9-24. REG07 Register**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset





#### <span id="page-39-0"></span>**[BQ25611D](http://www.ti.com/product/BQ25611D)** SLUSDF6B – JANUARY 2020 – REVISED SEPTEMBER 2020 **[www.ti.com](http://www.ti.com)**



### **9.5.9 Charger Status 0 Register (Address = 08h)**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset





<span id="page-40-0"></span>

m.

# **9.5.10 Charger Status 1 Register (Address = 09h)**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset







### <span id="page-41-0"></span>**9.5.11 Charger Status 2 Register (Address = 0Ah)**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset



### **Table 9-18. REG0A Field Descriptions**

<span id="page-42-0"></span>

### **9.5.12 Part Information Register (Address = 0Bh)**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset

#### **Table 9-19. REG0B Field Descriptions**



<span id="page-43-0"></span>



#### **9.5.13 Charger Control 4 Register (Address = 0Ch) [reset = 75h] Figure 9-29. REG0C**



LEGEND: R/W = Read/Write; R = Read only; -n = value after reset





<span id="page-44-0"></span>

### **10 Application and Implementation**

#### **Note**

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

### **10.1 Application Information**

A typical application consists of the device configured as an I<sup>2</sup>C controlled Power Path management device and a single cell battery charger for Li-Ion and Li-polymer batteries used in a wide range of smart phones and other portable devices. It integrates an input reverse-block FET (RBFET, Q1), high-side switching FET (HSFET, Q2), low-side switching FET (LSFET, Q3), and battery FET (BATFET Q4) between the system and battery. The device also integrates a bootstrap diode for the high-side gate drive.

### **10.2 Typical Application**



**Figure 10-1. BQ25611D Application Diagram**

For this design example, use the parameters shown in the table below.



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#### **10.2.2 Detailed Design Procedure**

#### *10.2.2.1 Inductor Selection*

The 1.5-MHz switching frequency allows the use of small inductor and capacitor values to maintain an inductor saturation current higher than the charging current ( $I_{CHG}$ ) plus half the ripple current ( $I_{RIPPIE}$ ):

$$
I_{\text{SAT}} \ge I_{\text{CHG}} + (1/2) I_{\text{RIPPLE}} \tag{3}
$$

The inductor ripple current depends on the input voltage (V<sub>VBUS</sub>), the duty cycle (D = V<sub>BAT</sub>/V<sub>VBUS</sub>), the switching frequency  $(f_S)$  and the inductance (L).

$$
I_{RIPPLE} = \frac{V_{IN} \times D \times (1 - D)}{fs \times L}
$$
 (4)

The maximum inductor ripple current occurs when the duty cycle (D) is 0.5 or approximately 0.5. Usually inductor ripple is designed in the range between 20% and 40% maximum charging current as a trade-off between inductor size and efficiency for a practical design.

#### *10.2.2.2 Input Capacitor and Resistor*

Design input capacitance to provide enough ripple current rating to absorb input switching ripple current. The worst case RMS ripple current is half of the charging current when duty cycle is 0.5. If the converter does not operate at 50% duty cycle, then the worst case capacitor RMS current  $I_{\text{C}IN}$  occurs where the duty cycle is closest to 50% and can be estimated using Equation 5.

$$
I_{\text{CIN}} = I_{\text{CHG}} \times \sqrt{D \times (1 - D)}
$$
\n<sup>(5)</sup>

Low ESR ceramic capacitor such as X7R or X5R is preferred for input decoupling capacitor and should be placed to the drain of the high-side MOSFET and source of the low-side MOSFET as close as possible. Voltage rating of the capacitor must be higher than normal input voltage level. A rating of 25-V or higher capacitor is preferred for 12-V input voltage. Capacitance of minimum 10 μF is suggested for typical of 3-A charging current.

During high current output over 700 mA in boost mode, a 10-kΩ pull-down resistor on VBUS is recommended to keep VBUS low in case Q1 RBFET leakage gets high.

#### *10.2.2.3 Output Capacitor*

Ensure that the output capacitance has enough ripple current rating to absorb the output switching ripple current. Equation 6 shows the output capacitor RMS current  $I_{\text{COUT}}$  calculation.

$$
I_{\text{COUT}} = \frac{I_{\text{RIPPLE}}}{2 \times \sqrt{3}} \approx 0.29 \times I_{\text{RIPPLE}}
$$
 (6)

The output capacitor voltage ripple can be calculated as follows:



$$
\Delta V_{\rm O} = \frac{V_{\rm OUT}}{8L C \text{fs}^2} \left( 1 - \frac{V_{\rm OUT}}{V_{\rm IN}} \right) \tag{7}
$$

At certain input and output voltage and switching frequency, the voltage ripple can be reduced by increasing the output filter LC.

The charger device has internal loop compensation optimized for > 10-μF ceramic output capacitance. The preferred ceramic capacitor is 10-V rating, X7R or X5R.



### <span id="page-47-0"></span>**10.3 Application Curves**



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### <span id="page-49-0"></span>**11 Power Supply Recommendations**

In order to provide an output voltage on SYS, the battery charger requires a power supply between 4-V and 13.5-V input with at least 100-mA current rating connected to VBUS and a single-cell Li-Ion battery with battery voltage greater than V<sub>BAT UVLOZ</sub> connected to BAT. The source current rating needs to be at least 3-A in order for the buck converter of the charger to provide maximum output power to SYS.

### **12 Layout**

### **12.1 Layout Guidelines**

The switching node rise and fall times should be minimized for minimum switching loss. Proper layout of the components to minimize high frequency current path loop (see Figure 12-1) is important to prevent electrical and magnetic field radiation and high frequency resonant problems. Follow this specific order carefully to achieve the proper layout.

- 1. Place input capacitor as close as possible to PMID pin and GND pin connections and use shortest copper trace connection or GND plane. Add 1 nF small size (such as 0402 or 0201) decoupling cap for high frequency noise filter and EMI improvement.
- 2. Place inductor input pin to SW pin as close as possible. Minimize the copper area of this trace to lower electrical and magnetic field radiation but make the trace wide enough to carry the charging current. Do not use multiple layers in parallel for this connection. Minimize parasitic capacitance from this area to any other trace or plane.
- 3. Put output capacitor near to the inductor and the device. Ground connections need to be tied to the IC ground with a short copper trace connection or GND plane.
- 4. Route analog ground separately from power ground. Connect analog ground and connect power ground separately. Connect analog ground and power ground together using thermal pad as the single ground connection point. Or using a 0-Ω resistor to tie analog ground to power ground.
- 5. Use single ground connection to tie charger power ground to charger analog ground. Just beneath the device. Use ground copper pour but avoid power pins to reduce inductive and capacitive noise coupling.
- 6. Place decoupling capacitors next to the IC pins and make trace connection as short as possible.
- 7. It is critical that the exposed thermal pad on the backside of the device package be soldered to the PCB ground. Ensure that there are sufficient thermal vias directly under the IC, connecting to the ground plane on the other layers.
- 8. Ensure that the number and sizes of vias allow enough copper for a given current path.

See the *[BQ25619 BMS025 Evaluation Module EVM User's Guide](http://www.ti.com/lit/pdf/SLUUC27)* for the recommended component placement with trace and via locations. For the VQFN information, refer to *[Quad Flatpack No-Lead Logic Packages](http://www.ti.com/lit/pdf/SCBA017) [Application Report](http://www.ti.com/lit/pdf/SCBA017)* and *[QFN and SON PCB Attachment Application Report](http://www.ti.com/lit/pdf/SLUA271)*.

### **12.2 Layout Example**



**Figure 12-1. High Frequency Current Path**



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**Figure 12-2. Layout Example**



### <span id="page-51-0"></span>**13 Device and Documentation Support**

### **13.1 Device Support**

### **13.2 Documentation Support**

#### **13.2.1 Related Documentation**

For related documentation see the following:

• *[BQ25619 BMS025 Evaluation Module User's Guide](http://www.ti.com/lit/pdf/SLUUC27)*

#### **13.3 Receiving Notification of Documentation Updates**

To receive notification of documentation updates, navigate to the device product folder on [ti.com.](https://www.ti.com) Click on *Subscribe to updates* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### **13.4 Support Resources**

TI E2E™ [support forums](https://e2e.ti.com) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

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#### **13.5 Trademarks**

TI E2E™ is a trademark of Texas Instruments.

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#### **13.6 Electrostatic Discharge Caution**



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### **13.7 Glossary**

**[TI Glossary](https://www.ti.com/lit/pdf/SLYZ022)** This glossary lists and explains terms, acronyms, and definitions.

<span id="page-52-0"></span>

### **14 Mechanical, Packaging, and Orderable Information**

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



### **PACKAGING INFORMATION**



**(1)** The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

**(6)** Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE OPTION ADDENDUM**

www.ti.com 17-Aug-2021

# **PACKAGE MATERIALS INFORMATION**

Texas<br>Instruments

### **TAPE AND REEL INFORMATION**





### **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





Pack Materials-Page 1

**TEXAS**<br>INSTRUMENTS

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 1-Jun-2020



\*All dimensions are nominal



Pack Materials-Page 2

# **MECHANICAL DATA**



All linear dimensions are in millimeters. Dimensioning and tolerancing per ASME Y14.5M-1994. А.

- This drawing is subject to change without notice. Β.
- Quad Flatpack, No-Leads (QFN) package configuration. C.
- D. The package thermal pad must be soldered to the board for thermal and mechanical performance.
- E. See the additional figure in the Product Data Sheet for details regarding the exposed thermal pad features and dimensions. F. Falls within JEDEC MO-220.



# RTW (S-PWQFN-N24)

# PLASTIC QUAD FLATPACK NO-LEAD

### THERMAL INFORMATION

This package incorporates an exposed thermal pad that is designed to be attached directly to an external heatsink. The thermal pad must be soldered directly to the printed circuit board (PCB). After soldering, the PCB can be used as a heatsink. In addition, through the use of thermal vias, the thermal pad can be attached directly to the appropriate copper plane shown in the electrical schematic for the device, or alternatively, can be attached to a special heatsink structure designed into the PCB. This design optimizes the heat transfer from the integrated circuit (IC).

For information on the Quad Flatpack No-Lead (QFN) package and its advantages, refer to Application Report, QFN/SON PCB Attachment, Texas Instruments Literature No. SLUA271. This document is available at www.ti.com.

The exposed thermal pad dimensions for this package are shown in the following illustration.







RTW (S-PWQFN-N24)

PLASTIC QUAD FLATPACK NO-LEAD



**NOTES:** 

- A. All linear dimensions are in millimeters.
	- B. This drawing is subject to change without notice.
	- Publication IPC-7351 is recommended for alternate designs. C.
	- D. This package is designed to be soldered to a thermal pad on the board. Refer to Application Note, Quad Flat-Pack Packages, Texas Instruments Literature No. SLUA271, and also the Product Data Sheets for specific thermal information, via requirements, and recommended board layout. These documents are available at www.ti.com <http://www.ti.com>.
	- E. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC 7525 for stencil design considerations.
	- F. Customers should contact their board fabrication site for recommended solder mask tolerances and via tenting recommendations for vias placed in the thermal pad.



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