

# 采用小型封装、具有 ±8kV IEC ESD 保护功能的 THVD1400、THVD1420 3.3V 至 5V RS-485 收发器

## 1 特性

- 符合或超出 TIA/EIA-485A 标准要求
- 3V 至 5.5V 电源电压
- 半双工 RS-422/RS-485
- 数据速率
  - THVD1400 : 500kbps
  - THVD1420 : 12Mbps
- 总线 I/O 保护
  - ±16kV HBM ESD
  - ±8kV IEC 61000-4-2 接触放电
  - ±15kV IEC 61000-4-2 空气间隙放电
  - ±4kV IEC 61000-4-4 快速瞬变脉冲
  - ±16V 总线故障保护 ( 总线引脚上的绝对最大电压 )
- 小型、节省空间的 8 引脚 SOT 封装选项 (2.1mm x 1.2mm)
  - 请参阅 [布局示例](#)，了解采用标准 SOIC-8 封装的共同布局
- 工业级工作温度范围：-40°C 至 125°C
- 用于噪声抑制的较大接收器滞后
- 低功耗
  - 低待机电源电流：< 1μA
  - 运行期间静态电流：1.5mA ( 典型值 )
- 适用于热插拔功能的无干扰上电/断电
- 开路、短路和空闲总线失效防护
- 1/8 单位负载 ( 多达 256 个总线节点 )

## 2 应用

- [工厂自动化和控制](#)
- [楼宇自动化](#)
- [电网基础设施](#)
- [电机驱动器](#)
- [电力输送](#)
- [工业运输](#)
- [HVAC 系统](#)
- [视频监控](#)
- [智能仪表](#)

## 说明

THVD1400 和 THVD1420 是强大的半双工 RS-485 收发器，适用于工业应用。这些总线引脚可耐受高级别的 IEC 接触放电 ESD 事件，因此无需使用其他系统级保护元件。

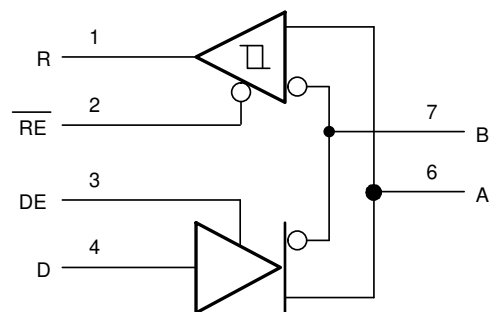
这些器件由 3 至 5.5V 单电源供电。总线引脚具备宽共模电压范围和低输入泄漏，从而使这些器件适用于长线缆上的多点应用。

THVD1400 和 THVD1420 可采用便于插接的业界通用 8 引脚 SOIC 封装，以及业界先进的小型 SOT 封装。这些器件的额定温度范围为 -40°C 至 125°C。

### 器件信息

器件型号	封装 <sup>(1)</sup>	封装尺寸 ( 标称值 )
THVD1400	SOT (8)	2.1mm x 1.2mm
THVD1420	SOIC (8)	4.90mm x 3.91mm

(1) 如需了解所有可用封装，请参阅数据表末尾的可订购产品附录。



简化版原理图



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### 3 Revision History

注：以前版本的页码可能与当前版本的页码不同

Changes from Revision * (December 2020) to Revision A (April 2021)	Page
• 向特性添加了：请参阅布局示例.....	1
• 删除了器件信息表中的 THVD1420 “预告信息” 说明.....	1
• Changed the Electrical and Switching Characteristics tables to remove empty columns.....	6
• Changed the test condition description for the last row of $I_{CC}$ (3.6V) from 'Both driver and receiver enabled' to 'Both driver and receiver disabled'.....	6
• Added 图 5-7, 图 5-8 and 图 5-9.....	9
• Added test conditions for 图 5-1, 图 5-2, 图 5-4 and 图 5-5.....	9
• Added 图 10-2 .....	21

## 4 Pin Configuration and Functions

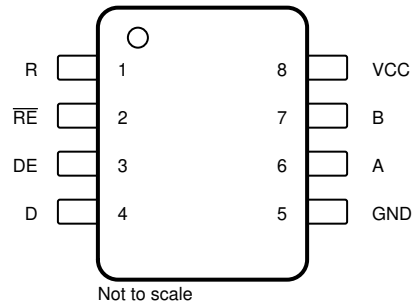


图 4-1. SOIC-8 (D), SOT-8 (DRL) Package, Top View

表 4-1. Pin Functions

PIN		I/O	DESCRIPTION
NAME	NO.		
R	1	Digital output	Receive data output
RE	2	Digital input	Receiver enable, active low (internal 2-M $\Omega$ pull-up)
DE	3	Digital input	Driver enable, active high (internal 2-M $\Omega$ pull-down)
D	4	Digital input	Driver data input
GND	5	Ground	Device ground
A	6	Bus input/output	Bus I/O port, A (complementary to B)
B	7	Bus input/output	Bus I/O port, B (complementary to A)
V <sub>CC</sub>	8	Power	3.3-V to 5-V supply

## 5 Specifications

### 5.1 Absolute Maximum Ratings

over operating free-air temperature range, unless otherwise noted (see <sup>(1)</sup>)

		MIN	MAX	UNIT
V <sub>CC</sub>	Supply voltage	- 0.5	7	V
V <sub>L</sub>	Input voltage at any logic pin (D, DE or RE)	- 0.3	5.7	V
V <sub>A</sub> , V <sub>B</sub>	Voltage at A or B inputs	- 16	16	V
I <sub>O</sub>	Receiver output current	- 24	24	mA
T <sub>J</sub>	Junction temperature		170	°C
T <sub>STG</sub>	Storage temperature	- 65	150	°C

- (1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under [# 5.4](#) is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

### 5.2 ESD Ratings

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±16,000	V
V <sub>(ESD)</sub>	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup>	±1,000	V
		Charged-device model (CDM), per JEDEC specification JESD22-C101 <sup>(2)</sup>	±1,500	

- (1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.  
 (2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

### 5.3 ESD Ratings [IEC]

			VALUE	UNIT
V <sub>(ESD)</sub>	Electrostatic discharge	IEC 61000-4-2 ESD (Contact Discharge), bus terminals and GND	±8,000	V
	Electrostatic discharge	IEC 61000-4-2 ESD (Air-Gap Discharge), bus terminals and GND	±15,000	
	Electrostatic discharge	IEC 61000-4-4 EFT (Fast transient or burst), bus terminals and GND	±4,000	

## 5.4 Recommended Operating Conditions

		MIN	NOM	MAX	UNIT
V <sub>CC</sub>	Supply voltage	3	5	5.5	V
V <sub>ID</sub>	Differential input voltage	-12		12	V
V <sub>I</sub>	Input voltage at any bus terminal <sup>(1)</sup>	-7		12	V
V <sub>IH</sub>	High-level input voltage (driver, driver-enable, and receiver-enable inputs)	2		V <sub>CC</sub>	V
V <sub>IL</sub>	Low-level input voltage (driver, driver-enable, and receiver-enable inputs)	0		0.8	V
I <sub>O</sub>	Output current	Driver		60	mA
		Receiver		8	
R <sub>L</sub>	Differential load resistance	54	60		Ω
1/t <sub>UI</sub>	Signaling rate: THVD1400			500	kbps
1/t <sub>UI</sub>	Signaling rate: THVD1420			12	Mbps
T <sub>J</sub>	Junction temperature	-40		150	°C
T <sub>A</sub> <sup>(2)</sup>	Operating ambient temperature	-40		125	°C
T <sub>SHDN</sub>	Thermal shutdown threshold (temperature rising)	150	170		°C
T <sub>HYS</sub>	Thermal shutdown hysteresis		15		°C

- (1) The algebraic convention in which the least positive (mostnegative) limit is designated as minimum is used in this data sheet.  
(2) Operation is specified for internal (junction) temperatures upto 150°C. Self-heating due to internal power dissipation should be considered for each application. Maximum junction temperature is internally limited by the thermal shut-down (TSD) circuit which disables the driver outputs when the junction temperature reaches 170°C.

## 5.5 Thermal Information

THERMAL METRIC <sup>(1)</sup>		THVD1400, THVD1420		UNIT
		DRL (SOT)	D (SOIC)	
		8 PINS	8 PINS	
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	112.2	126.0	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	28.4	66.2	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	22.1	69.4	°C/W
ψ <sub>JT</sub>	Junction-to-top characterization parameter	1.2	18.7	°C/W
ψ <sub>JB</sub>	Junction-to-board characterization parameter	22.0	68.7	°C/W

- (1) For more information about traditional and new thermalmetrics, see the [Semiconductor and IC Package Thermal Metrics](#) application report.

## 5.6 Power Dissipation Characteristics

PARAMETER		TEST CONDITIONS		VALUE	UNIT
P <sub>D</sub>	Power dissipation, driver and receiver enabled, V <sub>CC</sub> = 5.5 V, T <sub>A</sub> = 125°C, 50% duty cycle square-wave signal at maximum signaling rate (THVD1400)	Unterminated	R <sub>L</sub> = 300 Ω, C <sub>L</sub> = 50 pF	145	mW
		RS-422 load	R <sub>L</sub> = 100 Ω, C <sub>L</sub> = 50 pF	175	
		RS-485 load	R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF	235	
	Power dissipation, driver and receiver enabled, V <sub>CC</sub> = 5.5 V, T <sub>A</sub> = 125°C, 50% duty cycle square-wave signal at maximum signaling rate (THVD1420)	Unterminated	R <sub>L</sub> = 300 Ω, C <sub>L</sub> = 50 pF	175	mW
		RS-422 load	R <sub>L</sub> = 100 Ω, C <sub>L</sub> = 50 pF	200	
		RS-485 load	R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF	250	

## 5.7 Electrical Characteristics

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
<b>Driver</b>							
V <sub>OD</sub>	Driver differential-output voltage magnitude	R <sub>L</sub> = 60 Ω, -7 V ≤ V <sub>test</sub> ≤ 12 V	See 图 6-1	1.5	2	V	
		R <sub>L</sub> = 60 Ω, -7 V ≤ V <sub>test</sub> ≤ 12 V, 4.5 V ≤ V <sub>CC</sub> ≤ 5.5 V		2.1	3		
		R <sub>L</sub> = 100 Ω, C <sub>L</sub> = 50 pF	See 图 6-2	2	2.5		
		R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF		1.5	2		
		R <sub>L</sub> = 54 Ω, 4.5 V ≤ V <sub>CC</sub> ≤ 5.5 V		2.1	3		
Δ V <sub>OD</sub>	Change in magnitude of driver differential-output voltage	R <sub>L</sub> = 54 Ω or 100 Ω, C <sub>L</sub> = 50 pF	See 图 6-2	-50		50	mV
V <sub>OC(SS)</sub>	Steady-state common-mode output voltage			1	V <sub>CC</sub> / 2	3	V
ΔV <sub>OC</sub>	Change in differential driver common-mode output voltage			-50		50	mV
V <sub>OC(PP)</sub>	Peak-to-peak driver common-mode output voltage	R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF, V <sub>CC</sub> = 5 V	See 图 6-2		520		mV
V <sub>OC(PP)</sub>	Peak-to-peak driver common-mode output voltage	R <sub>L</sub> = 54 Ω, C <sub>L</sub> = 50 pF, V <sub>CC</sub> = 3.3 V	See 图 6-2		250		mV
I <sub>OS</sub>	Driver short-circuit output current	DE = V <sub>CC</sub> , -7 V ≤ [V <sub>A</sub> or V <sub>B</sub> ] ≤ 12 V, or A pin shorted to B pin		-250		250	mA
<b>Receiver</b>							
I <sub>I</sub>	Bus input current (driver disabled)	DE = 0 V, V <sub>CC</sub> = 0 V or 5.5 V		V <sub>I</sub> = 12 V	75	100	μA
				V <sub>I</sub> = -7 V	-97	-70	
V <sub>IT+</sub>	Positive-going receiver differential-input voltage threshold	-7 V ≤ V <sub>CM</sub> ≤ 12 V			-70	-45	mV
V <sub>IT-</sub>	Negative-going receiver differential-input voltage threshold			-200	-150	mV	
V <sub>HYS</sub> <sup>(1)</sup>	Receiver differential-input voltage threshold hysteresis (V <sub>IT+</sub> - V <sub>IT-</sub> )			30	50	mV	
V <sub>OH</sub>	Receiver high-level output voltage	I <sub>OH</sub> = -4 mA		V <sub>CC</sub> - 0.4	V <sub>CC</sub> - 0.2		V
V <sub>OL</sub>	Receiver low-level output voltage	I <sub>OL</sub> = 4 mA			0.2	0.4	V
I <sub>OZ</sub>	Receiver high-impedance output current	V <sub>O</sub> = 0 V or V <sub>CC</sub> , RE = V <sub>CC</sub>		-1		1	μA
<b>Logic</b>							
I <sub>IN</sub>	Input current (D, DE, RE)			-5		5	μA

## 5.7 Electrical Characteristics (continued)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
<b>Supply</b>							
$I_{CC}$	Supply current (quiescent)	$V_{CC} = 3.6$ V	Both driver and receiver enabled	$DE = V_{CC}, \overline{RE} = 0$ , no load	1500	1800	$\mu A$
			Driver enabled and receiver disabled	$DE = V_{CC}, \overline{RE} = V_{CC}$ , no load	1000	1500	
			Driver disabled and receiver enabled	$DE = 0, \overline{RE} = 0$ , no load	700	900	
			Both driver and receiver disabled	$DE = 0, \overline{RE} = V_{CC}$ , no load	0.1	1	
		$V_{CC} = 5.5$ V	Driver and receiver enabled	$DE = V_{CC}, \overline{RE} = 0$ , no load	1700	3000	$\mu A$
			Driver enabled, receiver disabled	$DE = V_{CC}, \overline{RE} = V_{CC}$ , no load	1300	2500	
			Driver disabled, receiver enabled	$DE = 0, \overline{RE} = 0$ , no load	800	1000	
			Driver and receiver disabled	$DE = 0, \overline{RE} = V_{CC}$ , no load	0.1	1	

(1) Under any specific conditions,  $V_{IT+}$  is specified to be at least  $V_{HYS}$  higher than  $V_{IT-}$ .

## 5.8 Switching Characteristics (THVD1400)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
<b>Driver</b>							
$t_r, t_f$	Driver differential output rise and fall times			200	400	600	ns
$t_{PHL}, t_{PLH}$	Driver propagation delay	See <a href="#">图 6-3</a>			250	500	ns
$t_{SK(P)}$	Driver pulse skew, $ t_{PHL} - t_{PLH} $					15	ns
$t_{PHZ}, t_{PLZ}$	Driver disable time				80	200	ns
$t_{PZH}, t_{PZL}$	Driver enable time	Receiver enabled	See <a href="#">图 6-4</a> and <a href="#">图 6-5</a>		200	650	ns
		Receiver disabled			4	10	$\mu s$
<b>Receiver</b>							
$t_r, t_f$	Receiver output rise and fall times				13	20	ns
$t_{PHL}, t_{PLH}$	Receiver propagation delay time	See <a href="#">图 6-6</a>			60	110	ns
$t_{SK(P)}$	Receiver pulse skew, $ t_{PHL} - t_{PLH} $					7	ns
$t_{PHZ}, t_{PLZ}$	Receiver disable time	See <a href="#">图 6-7</a>			30	60	ns
$t_{PZL(1)}, t_{PZH(1)}, t_{PZL(2)}, t_{PZH(2)}$	Receiver enable time	Driver enabled	See <a href="#">图 6-8</a>		60	150	ns
		Driver disabled			4	10	$\mu s$

## 5.9 Switching Characteristics (THVD1420)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
<b>Driver</b>							
$t_r, t_f$	Driver differential output rise and fall times				15	25	ns
$t_{PHL}, t_{PLH}$	Driver propagation delay	See <a href="#">图 6-3</a>			20	38	ns
$t_{SK(P)}$	Driver pulse skew, $ t_{PHL} - t_{PLH} $					3.5	ns
$t_{PHZ}, t_{PLZ}$	Driver disable time				15	38	ns
$t_{PZH}, t_{PZL}$	Driver enable time	Receiver enabled	See <a href="#">图 6-4</a> and <a href="#">图 6-5</a>		15	70	ns
		Receiver disabled			4	10	$\mu s$
<b>Receiver</b>							

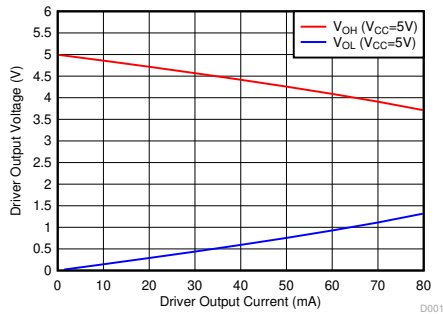
### 5.9 Switching Characteristics (THVD1420) (continued)

over operating free-air temperature range (unless otherwise noted)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
$t_r, t_f$	Receiver output rise and fall times	See <a href="#">图 6-6</a>			10	16	ns
$t_{PHL}, t_{PLH}$	Receiver propagation delay time				40	75	ns
$t_{SK(P)}$	Receiver pulse skew, $ t_{PHL} - t_{PLH} $					5	ns
$t_{PHZ}, t_{PLZ}$	Receiver disable time		See <a href="#">图 6-7</a>		15	25	ns
$t_{PZL(1)}, t_{PZH(1)}$	Receiver enable time	Driver enabled			25	170	ns
$t_{PZL(2)}, t_{PZH(2)}$		Driver disabled	See <a href="#">图 6-8</a>		4	10	$\mu$ s

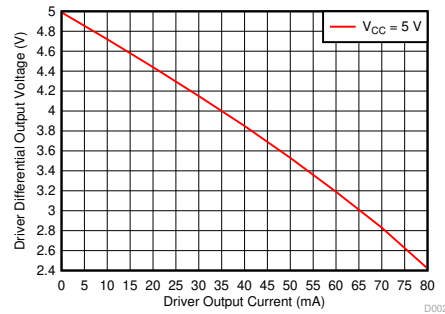


### 5.10 Typical Characteristics



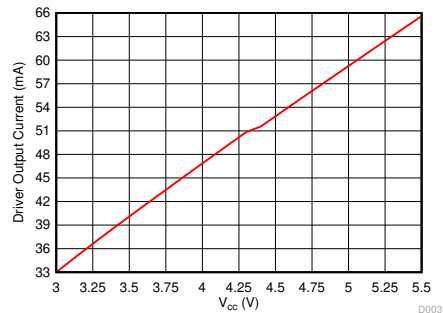
DE = V<sub>CC</sub> T<sub>A</sub> = 25°C

图 5-1. Driver Output voltage vs Driver Output Current



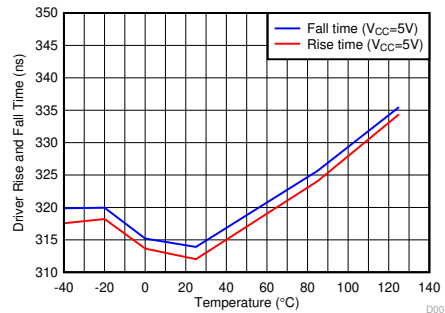
DE = V<sub>CC</sub> D = 0 V T<sub>A</sub> = 25°C

图 5-2. Driver Differential Output voltage vs Driver Output Current



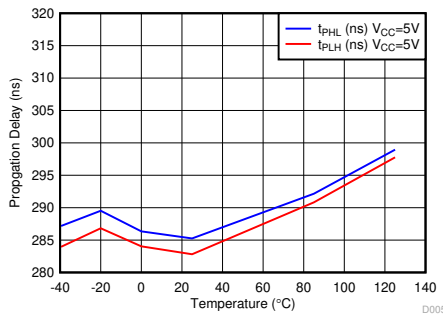
R<sub>L</sub> = 54 Ω DE = V<sub>CC</sub> D = V<sub>CC</sub>  
T<sub>A</sub> = 25°C

图 5-3. Driver Output Current vs Supply Voltage



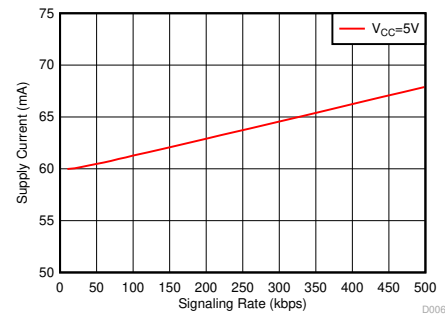
R<sub>L</sub> = 54 Ω C<sub>L</sub> = 50 pF

图 5-4. Driver Rise or Fall Time vs Temperature (THVD1400)



R<sub>L</sub> = 54 Ω C<sub>L</sub> = 50 pF

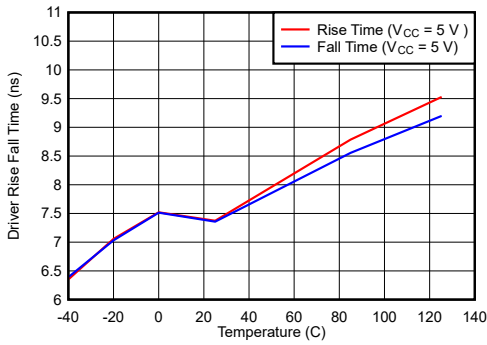
图 5-5. Driver Propagation Delay vs Temperature (THVD1400)



R<sub>L</sub> = 54 Ω T<sub>A</sub> = 25°C

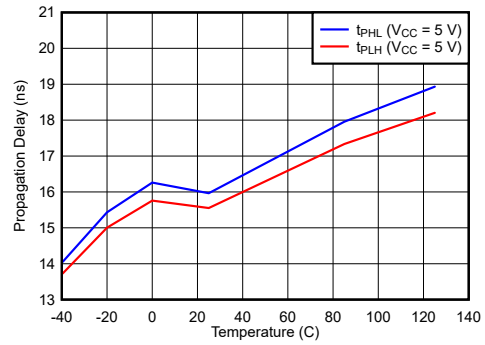
图 5-6. Supply Current vs Signal Rate (THVD1400)

### 5.10 Typical Characteristics (continued)



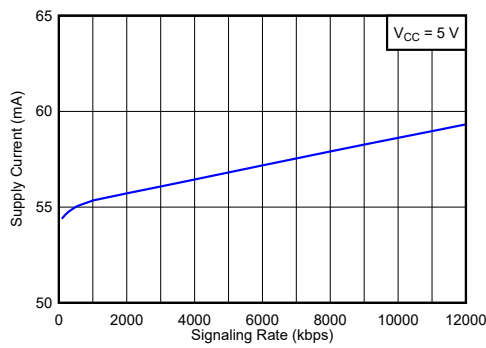
$R_L = 54 \Omega$        $C_L = 50 \text{ pF}$

图 5-7. Driver Rise and Fall Time vs Temperature (THVD1420)



$R_L = 54 \Omega$        $C_L = 50 \text{ pF}$

图 5-8. Driver Propagation Delay vs Temperature (THVD1420)



$R_L = 54 \Omega$      $T_A = 25 \text{ }^\circ\text{C}$

图 5-9. Supply Current vs Signal Rate (THVD1420)

## 6 Parameter Measurement Information

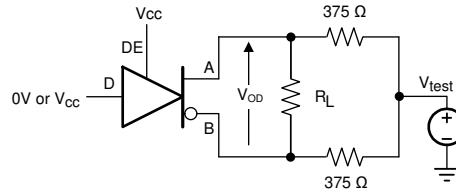


图 6-1. Measurement of Driver Differential Output Voltage With Common-Mode Load

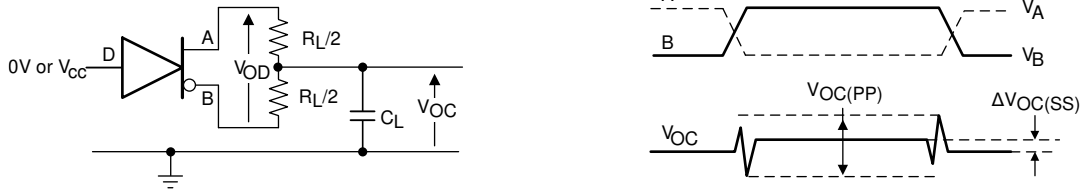


图 6-2. Measurement of Driver Differential and Common-Mode Output With RS-485 Load

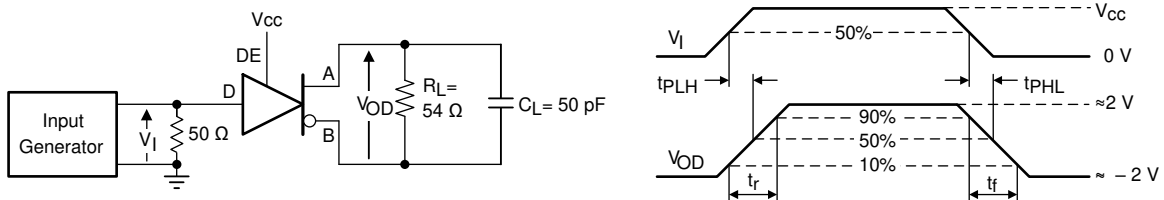


图 6-3. Measurement of Driver Differential Output Rise and Fall Times and Propagation Delays

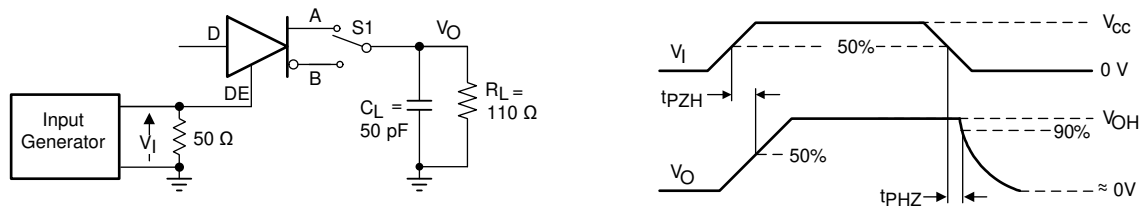


图 6-4. Measurement of Driver Enable and Disable Times With Active High Output and Pull-Down Load

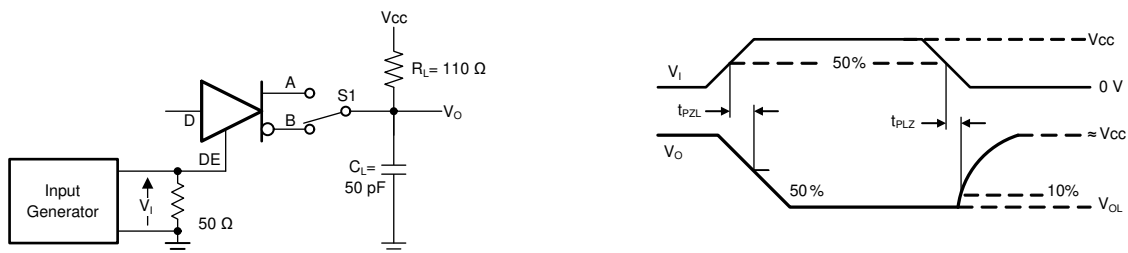
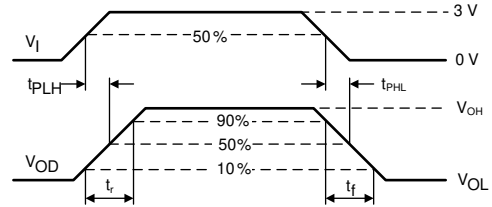
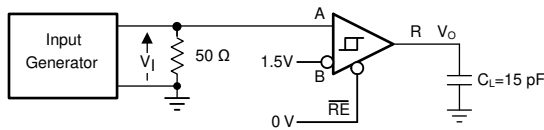
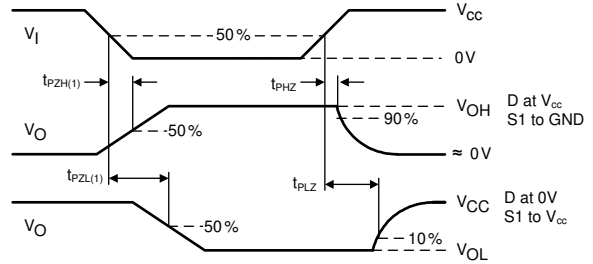
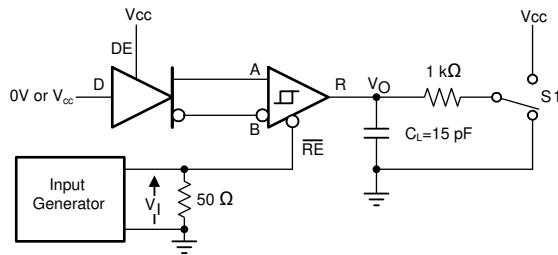


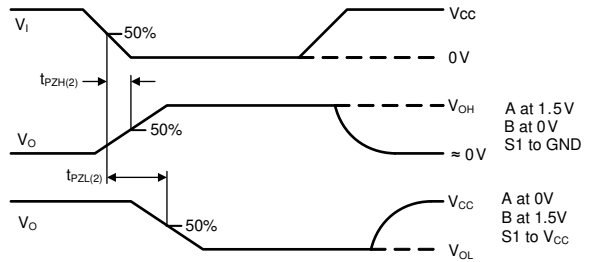
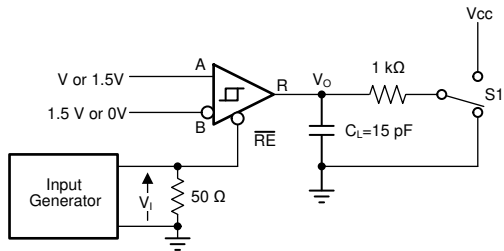
图 6-5. Measurement of Driver Enable and Disable Times With Active Low Output and Pull-up Load



**图 6-6. Measurement of Receiver Output Rise and Fall Times and Propagation Delays**



**图 6-7. Measurement of Receiver Enable/Disable Times With Driver Enabled**



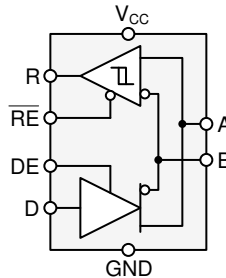
**图 6-8. Measurement of Receiver Enable Times With Driver Disabled**

## 7 Detailed Description

### 7.1 Overview

The THVD1400 is a low-power, half-duplex RS-485 transceiver suitable for data transmission up to 500 kbps. The THVD1420 is a low-power, half-duplex RS-485 transceiver suitable for data transmission up to 12 Mbps.

### 7.2 Functional Block Diagrams



### 7.3 Feature Description

Internal ESD protection circuits protect the transceiver against Electrostatic Discharges (ESD) according to IEC 61000-4-2 of up to  $\pm 8$  kV (Contact Discharge),  $\pm 15$  kV (Air Gap Discharge) and against electrical fast transients (EFT) according to IEC 61000-4-4 of up to  $\pm 4$  kV.

### 7.4 Device Functional Modes

When the driver enable pin, DE, is logic high, the differential outputs A and B follow the logic states at data input D. A logic high at D causes A to turn high and B to turn low. In this case, the differential output voltage defined as  $V_{OD} = V_A - V_B$  is positive. When D is low, the output states reverse, B turns high, A becomes low, and  $V_{OD}$  is negative.

When DE is low, both outputs turn high-impedance. In this condition, the logic state at D is irrelevant. The DE pin has an internal pull-down resistor to ground; thus, when left open, the driver is disabled (high-impedance) by default. The D pin has an internal pull-up resistor to  $V_{CC}$ , thus, when left open while the driver is enabled, output A turns high and B turns low.

表 7-1. Driver Function Table

INPUT	ENABLE	OUTPUTS		FUNCTION
		A	B	
H	H	H	L	Actively drive bus high
L	H	L	H	Actively drive bus low
X	L	Z	Z	Driver disabled
X	OPEN	Z	Z	Driver disabled by default
OPEN	H	H	L	Actively drive bus high by default

When the receiver enable pin,  $\overline{RE}$ , is logic low, the receiver is enabled. When the differential input voltage defined as  $V_{ID} = V_A - V_B$  is positive and higher than the positive input threshold,  $V_{IT+}$ , the receiver output, R, turns high. When  $V_{ID}$  is negative and lower than the negative input threshold,  $V_{IT-}$ , the receiver output, R, turns low. If  $V_{ID}$  is between  $V_{IT+}$  and  $V_{IT-}$ , the output is indeterminate.

When  $\overline{RE}$  is logic high or left open, the receiver output is high-impedance and the magnitude and polarity of  $V_{ID}$  are irrelevant. Internal biasing of the receiver inputs causes the output to go failsafe-high when the transceiver is disconnected from the bus (open-circuit), the bus lines are shorted (short-circuit), or the bus is not actively driven (idle bus).

表 7-2. Receiver Function Table

DIFFERENTIAL INPUT	ENABLE	OUTPUT	FUNCTION
$V_{ID} = V_A - V_B$	RE	R	
$V_{IT+} < V_{ID}$	L	H	Receive valid bus high
$V_{IT-} < V_{ID} < V_{IT+}$	L	?	Indeterminate bus state
$V_{ID} < V_{IT-}$	L	L	Receive valid bus low
X	H	Z	Receiver disabled
X	OPEN	Z	Receiver disabled by default
Open-circuit bus	L	H	Fail-safe high output
Short-circuit bus	L	H	Fail-safe high output
Idle (terminated) bus	L	H	Fail-safe high output

## 8 Application Information Disclaimer

### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 8.1 Application Information

The THVD1400 is a half-duplex RS-485 transceiver commonly used for asynchronous data transmissions. The driver and receiver enable pins allow for the configuration of different operating modes.

### 8.2 Typical Application

An RS-485 bus consists of multiple transceivers connecting in parallel to a bus cable. To eliminate line reflections, each cable end is terminated with a termination resistor,  $R_T$ , whose value matches the characteristic impedance,  $Z_0$ , of the cable. This method, known as parallel termination, allows for higher data rates over longer cable length.

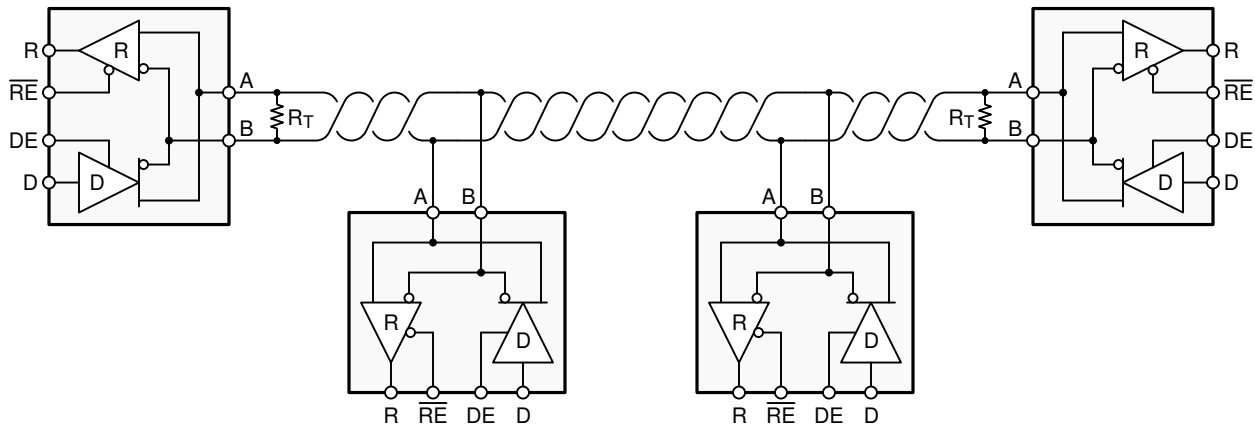


图 8-1. Typical RS-485 Network With Half-Duplex Transceivers

#### 8.2.1 Design Requirements

RS-485 is a robust electrical standard suitable for long-distance networking that may be used in a wide range of applications with varying requirements, such as distance, data rate, and number of nodes.

##### 8.2.1.1 Data Rate and Bus Length

There is an inverse relationship between data rate and cable length, which means the higher the data rate, the shorter the cable length; and conversely, the lower the data rate, the longer the cable length. While most RS-485 systems use data rates between 10 kbps and 100 kbps, some applications require data rates up to 300 kbps at distances of 4000 feet and longer. Longer distances are possible by allowing for small signal jitter of up to 5 or 10%.

### 8.2.1.2 Stub Length

When connecting a node to the bus, the distance between the transceiver inputs and the cable trunk, known as the stub, should be as short as possible. Stubs present a non-terminated piece of bus line which can introduce reflections as the length of the stub increases. As a general guideline, the electrical length, or round-trip delay, of a stub should be less than one-tenth of the rise time of the driver, thus giving a maximum physical stub length as shown in [方程式 1](#).

$$L_{(\text{STUB})} \leq 0.1 \times t_r \times v \times c \quad (1)$$

where

- $t_r$  is the 10/90 rise time of the driver
- $c$  is the speed of light ( $3 \times 10^8$  m/s)
- $v$  is the signal velocity of the cable or trace as a factor of  $c$

### 8.2.1.3 Bus Loading

The RS-485 standard specifies that a compliant driver must be able to driver 32 unit loads (UL), where 1 unit load represents a load impedance of approximately 12 k $\Omega$ . Because the THVD1400 consists of 1/8 UL transceivers, connecting up to 256 receivers to the bus is possible.

#### 8.2.1.4 Receiver Failsafe

The differential receivers of the THVD1400 are *failsafe* to invalid bus states caused by the following:

- Open bus conditions, such as a disconnected connector
- Shorted bus conditions, such as cable damage shorting the twisted-pair together
- Idle bus conditions that occur when no driver on the bus is actively driving

In any of these cases, the differential receiver outputs a failsafe logic high state so that the output of the receiver is not indeterminate.

Receiver failsafe is accomplished by offsetting the receiver thresholds such that the *input indeterminate* range does not include zero volts differential. To comply with the RS-422 and RS-485 standards, the receiver output must output a high when the differential input  $V_{ID}$  is more positive than 200 mV, and must output a low when  $V_{ID}$  is more negative than  $-200$  mV. The receiver parameters which determine the failsafe performance are  $V_{IT+}$ ,  $V_{IT-}$ , and  $V_{HYS}$  (the separation between  $V_{IT+}$  and  $V_{IT-}$ ). As shown in the [Receiver Function Table](#), differential signals more negative than  $-200$  mV always causes a low receiver output, and differential signals more positive than 200 mV always causes a high receiver output.

When the differential input signal is close to zero, it is still above the  $V_{IT+}$  threshold, and the receiver output is high. Only when the differential input is more than  $V_{HYS}$  below  $V_{IT+}$  does the receiver output transition to a low state. Therefore, the noise immunity of the receiver inputs during a bus fault conditions includes the receiver hysteresis value,  $V_{HYS}$ , as well as the value of  $V_{IT+}$ .



### 8.2.1.5 Transient Protection

The bus pins of the THVD1400 transceiver family include on-chip ESD protection against  $\pm 16$ -kV HBM and  $\pm 8$ -kV IEC 61000-4-2 contact discharge. The International Electrotechnical Commission (IEC) ESD test is far more severe than the HBM ESD test. The 50% higher charge capacitance,  $C_{(S)}$ , and 78% lower discharge resistance,  $R_{(D)}$ , of the IEC model produce significantly higher discharge currents than the HBM model.

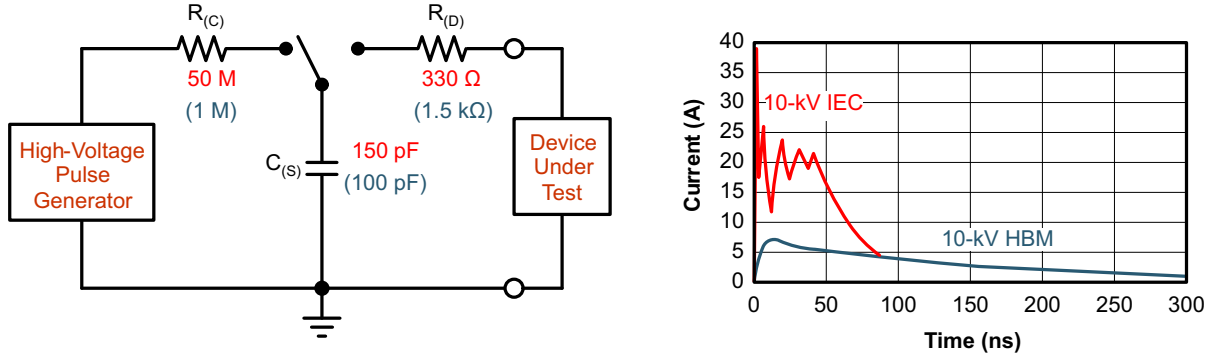


图 8-2. HBM and IEC ESD Models and Currents in Comparison (HBM Values in Parenthesis)

The on-chip implementation of IEC ESD protection significantly increases the robustness of equipment. Common discharge events occur because of human contact with connectors and cables. Designers may choose to implement protection against longer duration transients, typically referred to as surge transients.

EFTs are generally caused by relay-contact bounce or the interruption of inductive loads. Surge transients often result from lightning strikes (direct strike or an indirect strike which induce voltages and currents), or the switching of power systems, including load changes and short circuit switching. These transients are often encountered in industrial environments, such as factory automation and power-grid systems.

图 8-3 compares the pulse-power of the EFT and surge transients with the power caused by an IEC ESD transient. The left hand diagram shows the relative pulse-power for a 0.5-kV surge transient and 4-kV EFT transient, both of which dwarf the 10-kV ESD transient visible in the lower-left corner. 500-V surge transients are representative of events that may occur in factory environments in industrial and process automation.

The right hand diagram shows the pulse-power of a 6-kV surge transient, relative to the same 0.5-kV surge transient. 6-kV surge transients are most likely to occur in power generation and power-grid systems.

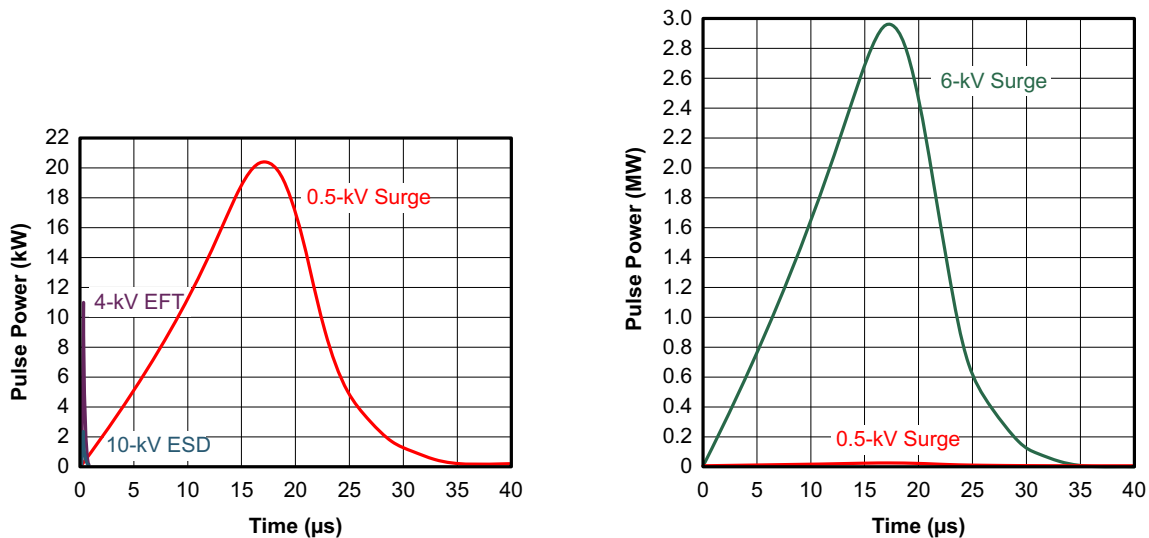


图 8-3. Power Comparison of ESD, EFT, and Surge Transients

In the event of surge transients, high-energy content is characterized by long pulse duration and slow decaying pulse power. The electrical energy of a transient that is dumped into the internal protection cells of a transceiver is converted into thermal energy, which heats and destroys the protection cells, thus destroying the transceiver.

Figure 8-4 shows the large differences in transient energies for single ESD, EFT, surge transients, and an EFT pulse train that is commonly applied during compliance testing.

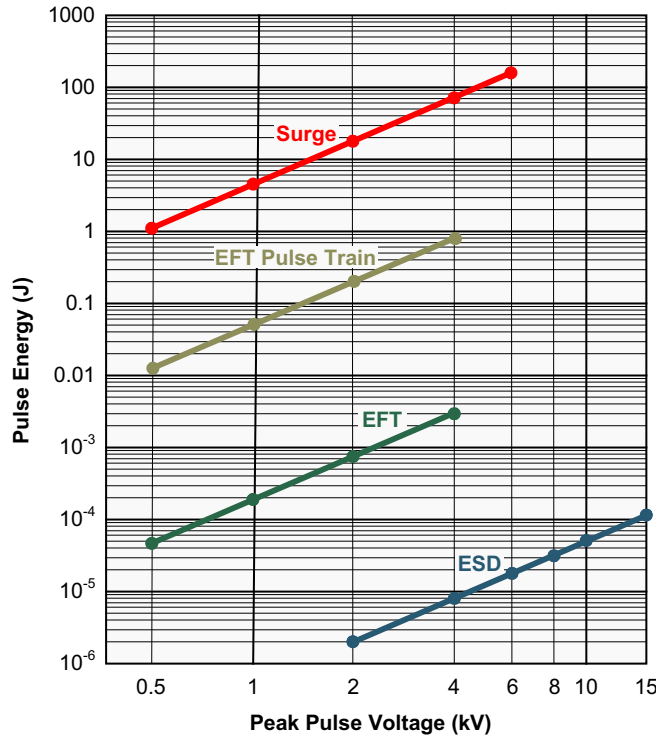


Figure 8-4. Comparison of Transient Energies

### 8.2.2 Detailed Design Procedure

In order to protect bus nodes against high-energy transients, the implementation of external transient protection devices is necessary. 图 8-5 suggests a protection circuit against 1 kV surge (IEC 61000-4-5) transients. 表 8-1 shows the associated bill of materials.

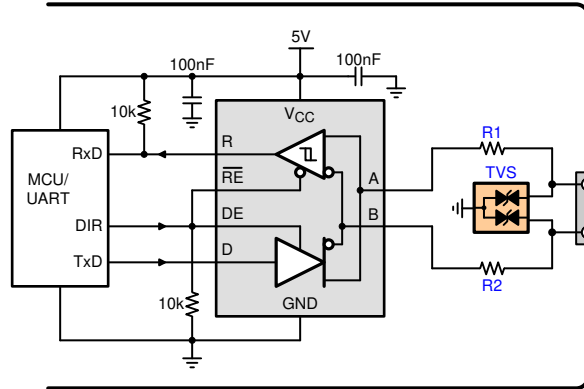


图 8-5. Transient Protection Against Surge Transients for Half-Duplex Devices

表 8-1. Bill of Materials

DEVICE	FUNCTION	ORDER NUMBER	MANUFACTURER
XCVR	RS-485 transceiver	THVD1400	TI
R1	10-Ω, pulse-proof thick-film resistor	CRCW0603010RJNEAHP	Vishay
R2			
TVS	Bidirectional 400-W transient suppressor	CDSOT23-SM712	Bourns

### 8.2.3 Application Curves

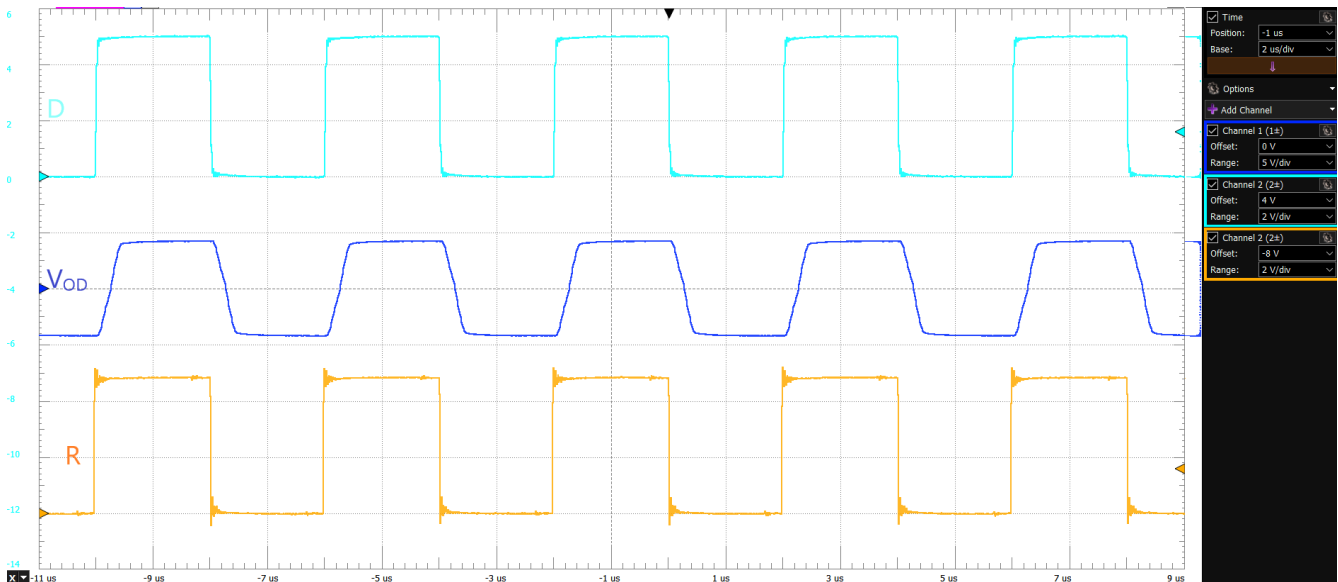


图 8-6. THVD1400 waveforms at 500 kbps, V<sub>CC</sub> = 5V

## 9 Power Supply Recommendations

To ensure reliable operation at all data rates and supply voltages, each supply should be decoupled with a 100 nF ceramic capacitor located as close to the supply pins as possible. This helps to reduce supply voltage ripple

present on the outputs of switched-mode power supplies and also helps to compensate for the resistance and inductance of the PCB power planes.

## 10 Layout

### 10.1 Layout Guidelines

Robust and reliable bus node design often requires the use of external transient protection devices in order to protect against surge transients that may occur in industrial environments. Since these transients have a wide frequency bandwidth (from approximately 3 MHz to 300 MHz), high-frequency layout techniques should be applied during PCB design.

1. Place the protection circuitry close to the bus connector to prevent noise transients from propagating across the board.
2. Use  $V_{CC}$  and ground planes to provide low inductance. Note that high-frequency currents tend to follow the path of least impedance and not the path of least resistance.
3. Design the protection components into the direction of the signal path. Do not force the transient currents to divert from the signal path to reach the protection device.
4. Apply 100-nF to 220-nF decoupling capacitors as close as possible to the  $V_{CC}$  pins of transceiver, UART and/or controller ICs on the board.
5. Use at least two vias for  $V_{CC}$  and ground connections of decoupling capacitors and protection devices to minimize effective via inductance.
6. Use 1-k $\Omega$  to 10-k $\Omega$  pull-up and pull-down resistors for enable lines to limit noise currents in these lines during transient events.
7. Insert pulse-proof resistors into the A and B bus lines if the TVS clamping voltage is higher than the specified maximum voltage of the transceiver bus pins. These resistors limit the residual clamping current into the transceiver and prevent it from latching up.
8. While pure TVS protection is sufficient for surge transients up to 1 kV, higher transients require metal-oxide varistors (MOVs) which reduce the transients to a few hundred volts of clamping voltage, and transient blocking units (TBUs) that limit transient current to less than 1 mA.

### 10.2 Layout Example

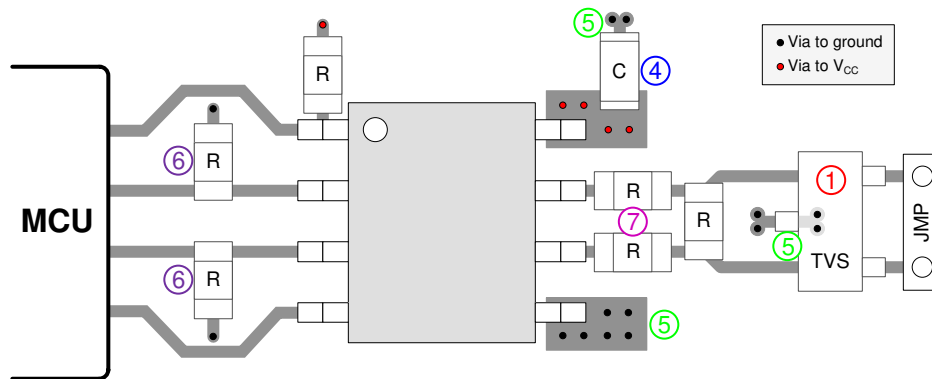


图 10-1. Layout Example for SOIC package

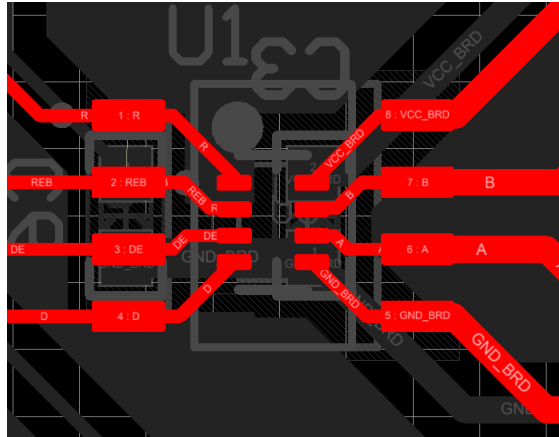


图 10-2. Layout Example for Co-layout of SOIC (D) and SOT (DRL)

## 11 Device and Documentation Support

### 11.1 Device Support

### 11.2 接收文档更新通知

要接收文档更新通知，请导航至 [ti.com](http://ti.com) 上的器件产品文件夹。点击 [订阅更新](#) 进行注册，即可每周接收产品信息更改摘要。有关更改的详细信息，请查看任何已修订文档中包含的修订历史记录。

### 11.3 支持资源

[TI E2E™ 支持论坛](#) 是工程师的重要参考资料，可直接从专家获得快速、经过验证的解答和设计帮助。搜索现有解答或提出自己的问题可获得所需的快速设计帮助。

链接的内容由各个贡献者“按原样”提供。这些内容并不构成 TI 技术规范，并且不一定反映 TI 的观点；请参阅 TI 的《[使用条款](#)》。

### 11.4 Trademarks

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ESD 的损坏小至导致微小的性能降级，大至整个器件故障。精密的集成电路可能更容易受到损坏，这是因为非常细微的参数更改都可能会导致器件与其发布的规格不相符。

### 11.6 术语表

[TI 术语表](#) 本术语表列出并解释了术语、首字母缩略词和定义。

## 12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

**PACKAGING INFORMATION**

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
PTHVD1400DRLR	ACTIVE	SOT-5X3	DRL	8	4000	TBD	Call TI	Call TI	-40 to 125		<a href="#">Samples</a>
THVD1400DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	1400	<a href="#">Samples</a>
THVD1420DR	ACTIVE	SOIC	D	8	2500	RoHS & Green	NIPDAU	Level-1-260C-UNLIM	-40 to 125	1420	<a href="#">Samples</a>
THVD1420DRLR	PREVIEW	SOT-5X3	DRL	8	4000	RoHS & Green	SN	Level-1-260C-UNLIM	-40 to 125	T420	

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.



D0008A

# PACKAGE OUTLINE

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



4214825/C 02/2019

### NOTES:

1. Linear dimensions are in inches [millimeters]. Dimensions in parenthesis are for reference only. Controlling dimensions are in inches. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed  $.006$  [0.15] per side.
4. This dimension does not include interlead flash.
5. Reference JEDEC registration MS-012, variation AA.

# EXAMPLE BOARD LAYOUT

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:8X



SOLDER MASK DETAILS

4214825/C 02/2019

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

D0008A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT

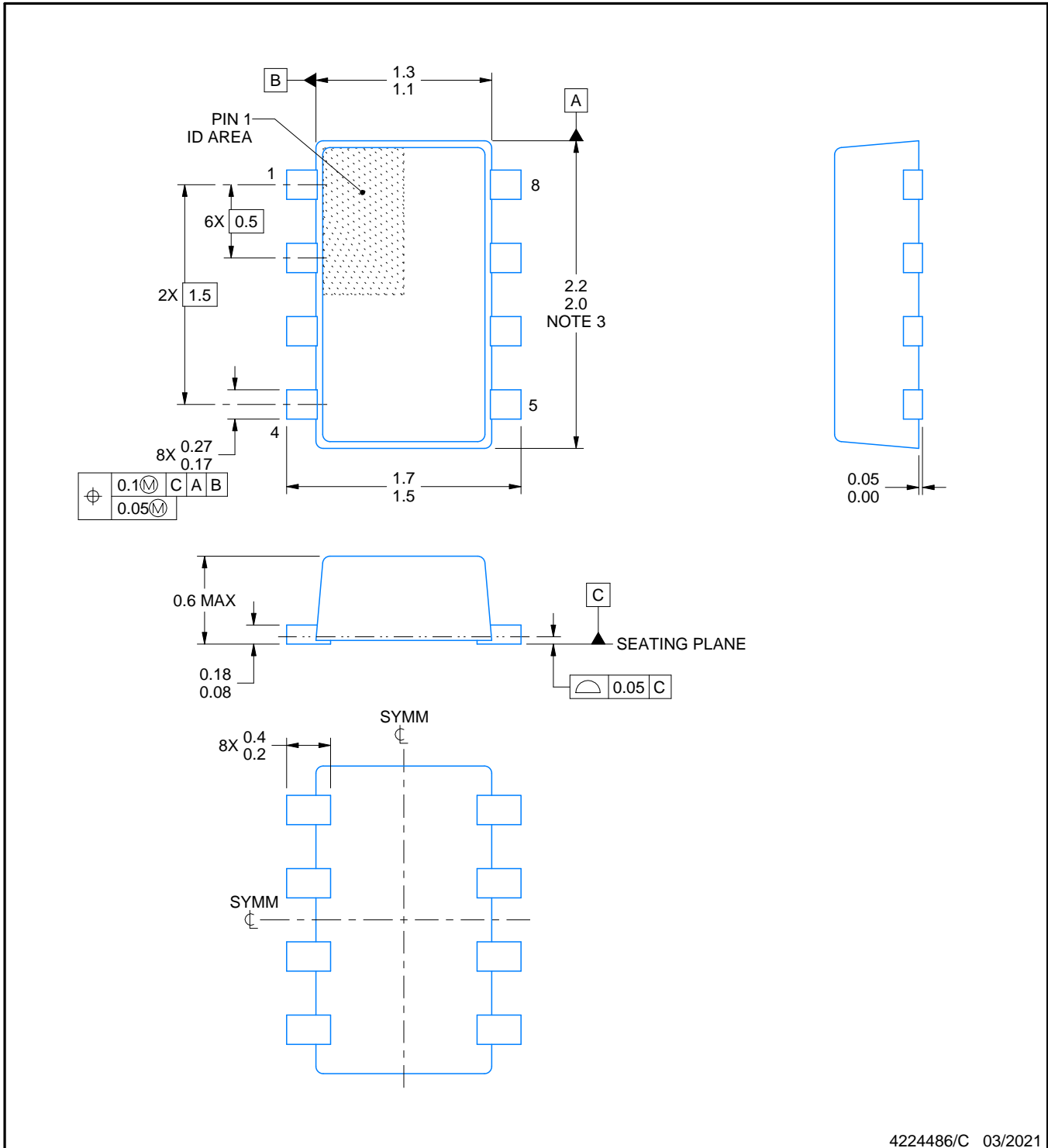


SOLDER PASTE EXAMPLE  
BASED ON .005 INCH [0.125 MM] THICK STENCIL  
SCALE:8X

4214825/C 02/2019

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.



4224486/C 03/2021

NOTES:

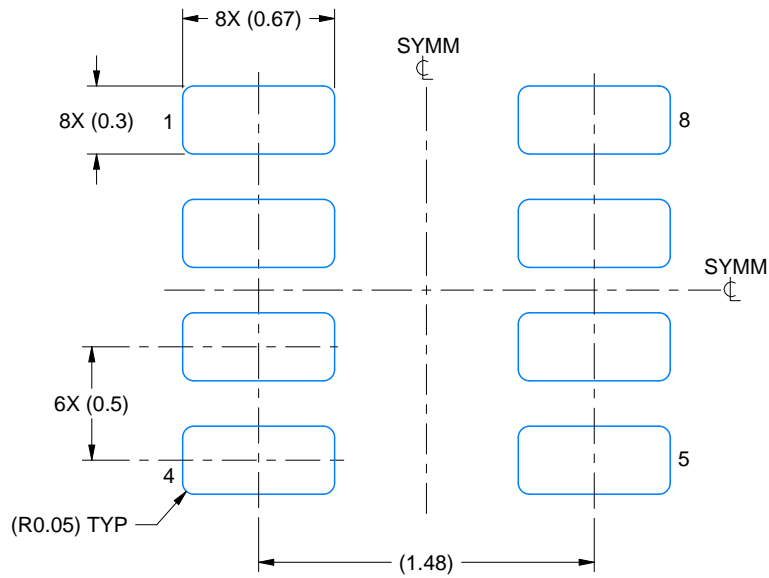
1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, interlead flash, protrusions, or gate burrs shall not exceed 0.15 mm per side.

# EXAMPLE BOARD LAYOUT

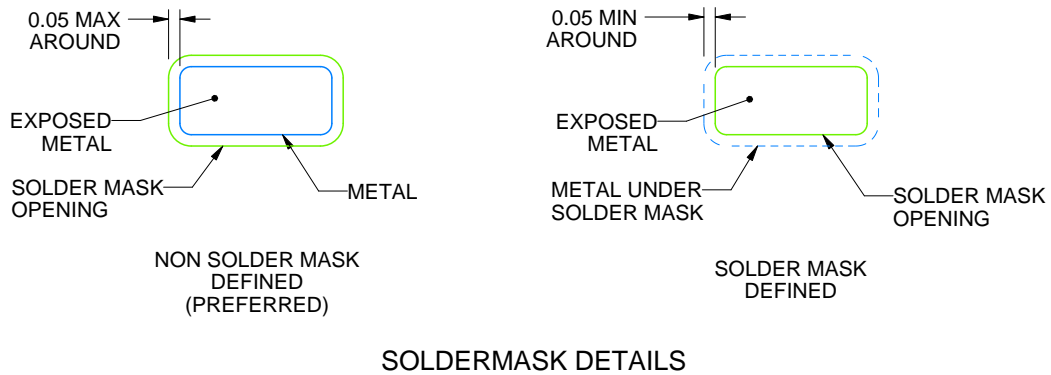
DRL0008A

SOT-5X3 - 0.6 mm max height

PLASTIC SMALL OUTLINE



LAND PATTERN EXAMPLE  
EXPOSED METAL SHOWN  
SCALE:30X



SOLDERMASK DETAILS

4224486/C 03/2021

NOTES: (continued)

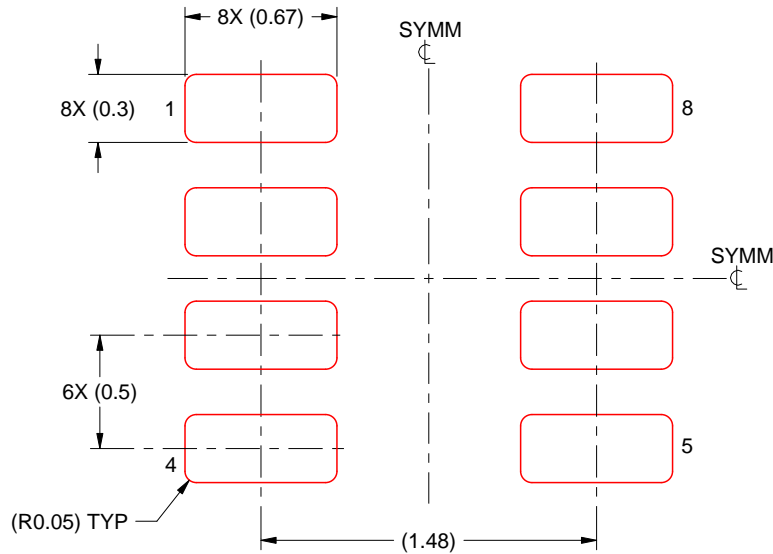
- 4. Publication IPC-7351 may have alternate designs.
- 5. Solder mask tolerances between and around signal pads can vary based on board fabrication site.

# EXAMPLE STENCIL DESIGN

DRL0008A

SOT-5X3 - 0.6 mm max height

PLASTIC SMALL OUTLINE



SOLDER PASTE EXAMPLE  
BASED ON 0.1 mm THICK STENCIL  
SCALE:30X

4224486/C 03/2021

NOTES: (continued)

6. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
7. Board assembly site may have different recommendations for stencil design.

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